

Computing Solutions to Maxwell's eqns

- Given these eqns + Boundary conditions:

$$\nabla \times \vec{E} = -\vec{M} - j\omega\mu\vec{H}, \quad \nabla \cdot \vec{E} = \rho_{ev}/\epsilon,$$

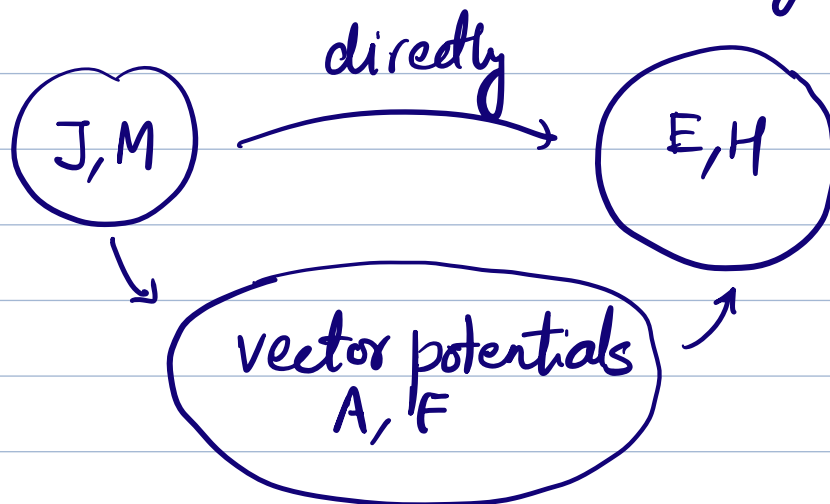
$$\nabla \times \vec{H} = \vec{J} + j\omega\epsilon\vec{E}, \quad \nabla \cdot \vec{H} = \rho_{mv}/\mu,$$

(can be combined into sep eqns for $\vec{E}$ & $\vec{H}$)

① Note: The above is true for homogeneous media, i.e. ϵ, μ not fns of $\vec{r}$. Else $\nabla \cdot \vec{D} = \rho_{ev}$.

② Note: $\vec{J}$ can be split as $\vec{J}_{\text{cond}} + \vec{J}_{\text{imp}}$ where $\vec{J}_{\text{cond}}$ is due to the medium and $\vec{J}_{\text{imp}}$ is an external/impressed current due to a source.

→ There are two routes to solving them:



We are familiar with the direct route, so now explore the vector potential route. Assume no charges for now.

① First $\vec{A}$.. when $\rho_m = 0$, $\nabla \cdot \vec{B} = 0$ (no M)

Vector calculus identity is $\nabla \cdot (\nabla \times \vec{A}) = 0$ for any $\vec{A}$.

Goal? Get an eqn for $\vec{A}$ in terms of $\vec{J}$

Since $\vec{\nabla} \cdot \vec{B} = 0$, $\vec{B}$ must be of the form:
 $\vec{B}_A = \vec{\nabla} \times \vec{A} = \mu \vec{H}_A$

$$\text{So } \vec{H}_A = \frac{1}{\mu} \vec{\nabla} \times \vec{A} \quad - (1)$$

$$\hookrightarrow \text{Then } \vec{\nabla} \times \vec{E} = -j\omega \vec{B} = -j\omega \vec{\nabla} \times \vec{A} \\ \Rightarrow \vec{\nabla} \times [\vec{E} + j\omega \vec{A}] = 0.$$

Another vector calculus identity states
 $\vec{\nabla} \times \vec{\nabla} \phi = 0$ for any scalar ϕ . (potential)

$\Rightarrow \vec{E} + j\omega \vec{A}$ must be of the form $[-\vec{\nabla} \phi_e]$
Convention electric

$$\therefore \vec{E} = -j\omega \vec{A} - \vec{\nabla} \phi_e. \quad - (2)$$

$\hookrightarrow$ Now let's use the other M.E.: (Ampere)

$$\vec{\nabla} \times \vec{H}_A = j\omega \epsilon \vec{E}_A + \vec{J} = \frac{1}{\mu} \vec{\nabla} \times (\vec{\nabla} \times \vec{A})$$

$$\Rightarrow \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A} = j\omega \mu \epsilon \vec{E}_A + \mu \vec{J} \quad - (3)$$

Substitute for $\vec{E}_A$ from (2):

$$\vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A} = \omega^2 \mu \epsilon \vec{A} - j\omega \mu \epsilon \vec{\nabla} \phi_e + \mu \vec{J} \\ \nabla^2 \vec{A} + \omega^2 \mu \epsilon \vec{A} = -\mu \vec{J} + \underbrace{j\omega \mu \epsilon \vec{\nabla} \phi_e + \vec{\nabla}(\vec{\nabla} \cdot \vec{A})}_{\vec{\nabla}(\vec{\nabla} \cdot \vec{A} + j\omega \mu \epsilon \phi_e)}$$

Notice that for $\vec{A}'$, so far we have only specified $\nabla \times \vec{A}' (= \vec{B})$, but not $\nabla \cdot \vec{A}$.

Based on the Helmholtz decomp thm in vector calculus that holds for fields that decay at ∞ , $\vec{A}$ is specified if you specify both its curl & div. $\Rightarrow$ we are free to specify $\nabla \cdot \vec{A}$. We set $\nabla \cdot \vec{A} = -j\omega\mu\epsilon\phi_e$ (Lorentz Gauge condn)

$$\Rightarrow \nabla^2 \vec{A} + \omega^2\mu\epsilon\vec{A} = -\mu\vec{J} \quad (4) \quad (\text{Where have we seen this eqn?})$$

$$\& \vec{E}_A = -\nabla\phi_e - j\omega\vec{A} = -j\omega\vec{A} - \frac{j}{\omega\mu\epsilon} \nabla(\nabla \cdot \vec{A}) \quad (5)$$

$$\text{or } \vec{E}_A = \frac{j}{\omega\mu} \nabla \times \vec{H}_A \quad (6)$$

$\hookrightarrow$ So given $\vec{J} \rightarrow$ find $\vec{A} \rightarrow$ find $\vec{H}_A \rightarrow$ find $\vec{E}_A$.

<Eqn (4) is the critical step>

② The second vector potential, $\vec{F}$. (no $\vec{J}$)
When $\rho_e = 0$, $\nabla \cdot \vec{D} = 0$.

$\Rightarrow \vec{D}$ must bc of curl form.

$$\text{Set } \vec{D}_F = -\nabla \times \vec{F} \quad (7)$$

$\searrow$ Convention.

$$\Rightarrow \vec{E}_F = -\frac{1}{\epsilon} \nabla \times \vec{F} \quad (8)$$

$$\text{Then } \nabla \times \vec{H}_F = j\omega\epsilon\vec{E}_F \Rightarrow [\vec{H}_F + j\omega\vec{F}] = -\nabla\phi_m$$

ϕ_m : scalar magnetic potential.

$$\therefore H_F = -\nabla\phi_m - j\omega\vec{F} \quad \text{--- (9)}$$

Going back to (8), $\nabla \times E_F = -\frac{1}{\epsilon}(\nabla \times (\nabla \times F))$

$$\Rightarrow -M - j\omega\mu H_F = -\frac{1}{\epsilon}(\nabla(\nabla \cdot F) - \nabla^2 F)$$

like before we have the freedom to choose
 $\nabla \cdot F = -j\omega\mu\epsilon\phi_m \quad \text{--- (10)}$

Gives $\nabla^2 \vec{F} + \omega^2\mu\epsilon\vec{F} = -\epsilon\vec{M} \quad \text{--- (11)}$

$$\& \quad H_F = -j\omega F - \frac{j}{\omega\mu\epsilon} \nabla(\nabla \cdot F) \quad \text{--- (12)}$$

$$\text{or } H_F = \frac{-1}{j\omega\mu} \nabla \times E_F \quad \text{--- (13)}$$

So, given $\vec{M} \rightarrow$ solve (11) to get $\vec{F} \rightarrow$ find $\vec{E}_F$ from (8)

↓
find $\vec{H}_F$ from (13).

< Solving eqn (11) is key >

Note: The critical eqns (9), (11) are of the same form, inhomogeneous wave eqn (RHS $\neq 0$).

$\therefore$ Net soln if we have both $\vec{J}$ & $\vec{M}$?

$E = E_A + E_F$, $H = H_A + H_F$ superposition.

<HW: Read solved example 6.1 of AE>

Using this framework all the examples of wave propagation, waveguide modes etc can be expressed in the A, F language.

Note: even if $J=0, M=0$, we can have both $A \neq 0$ & $F \neq 0$, in that case:

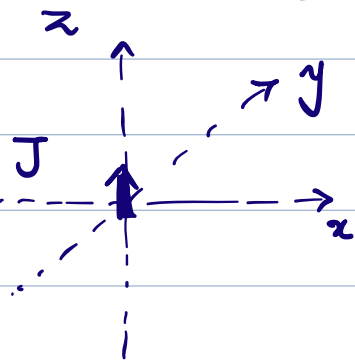
$$\nabla^2 \vec{A} + \omega^2 \mu \epsilon \vec{A} = 0 \quad \& \quad \nabla^2 \vec{F} + \omega^2 \mu \epsilon \vec{F} = 0.$$

This is the standard wave eqn which we know how to solve!

↳ Inhomogeneous wave eqn, e.g. $\vec{J} \neq 0$.

For simplicity assume $\vec{J} = J_z \hat{z}$, so the wave eqn becomes:

$$\begin{aligned} \nabla^2 A_x + k^2 A_x &= 0 \\ \nabla^2 A_y + k^2 A_y &= 0 \\ \nabla^2 A_z + k^2 A_z &= -\mu J_z \end{aligned} \quad \left. \begin{array}{l} \} \text{easy} \\ \} \text{not so easy!} \end{array} \right.$$



This is the standard & most basic antenna problem.

We will come back to it after learning how to solve the z -eqn.



Green's functions / Impulse response

(phy)

(EE)

Recall

$$x(t) \rightarrow \boxed{h(t)} \rightarrow y(t)$$

LTI system.

convolution.

In time domain, $y(t) = \int_{-\infty}^{\infty} h(t-\tau)x(\tau)d\tau$

where $h(t)$ was the impulse response.

How do we get $h(t)$? Recall FT:

$$X(\omega) = \int_{-\infty}^{\infty} x(t) \exp(j\omega t) dt.$$

Then $Y(\omega) = H(\omega) X(\omega).$

Set $x(t) = \delta(t) \Rightarrow X(\omega) = 1$

$\Rightarrow Y(\omega) = H(\omega).$

Only need to do this once. Later any new $x(t) \rightarrow X(\omega)$ and get $Y = HX$.

Keep in mind H was how the system responded to a delta fn. We borrow this idea next.

— x —

Consider a diff eqn, eg. $\nabla^2 \phi = f$ or

$\nabla^2 \phi + \nabla \phi = f$, etc. Here, f : output

and ϕ : input. Write in general as

Operator $\leftarrow \int \phi(r) = f(r) \rightarrow$ o/p

i/p

↳ what we ideally want is $\phi(r) = L^{-1}f(r)$.
But how?

① Define the impulse response, g as follows:

$$L g(r, r') = \delta(r, r')$$

only a fn of r . fn of r & r' Delta input at $r = r'$

How does this help us? Left multiply $f(r')$

$$f(r') L g(r, r') = f(r') \delta(r, r')$$

can take it inside as L depends only on r .

$$\therefore L f(r') g(r, r') = f(r') \delta(r, r').$$

Now integrate over r' coordinates (both sides) and we must make sure $r' = r$ is in the domain of integration Ω .

$$\int_{\Omega} L f(r') g(r, r') \underbrace{dr'}_{\substack{\text{can be } dx', dx'dy', dx'dy'dz' \\ \text{depending on the problem.}}} = \int_{\Omega} f(r') \delta(r, r') dr'$$

$$\Rightarrow L \int_{\Omega} f(r') g(r, r') dr' = \begin{cases} f(r), & \text{if } r = r' \in \Omega \\ 0 & \text{if } r = r' \notin \Omega. \end{cases}$$

Original eqn? $\mathcal{L} \phi(r) = f(r)$. Compare with above eqn to get

$$\phi(r) = \int_{\Omega} f(r') g(r, r') dr'$$

Compare with LTI response $y(t) = \int_{-\infty}^{\infty} x(z) h(t-z) dz$.

This g : Green's fn or impulse response.