

2) Orthogonality of Subspaces.

↳ Every vector in one subspace is orthogonal to every vector in the other subspace

- ↳ $\{\vec{0}\}$ and every other vs ✓
- ↳ a line & another line ✓
- ↳ a line & an orthogonal plane ✓
- ↳ Two planes ✗

We have already seen $A: m \times n$

$C(A^T), d = A^T w$ $\dim = r, \mathbb{R}^n$	$C(A), c = Ax, \dim = r$ \mathbb{R}^m
$N(A), Ax = 0$ $\dim n-r, \mathbb{R}^n$	$N(A^T), A^T y = 0, \dim = m-r$ \mathbb{R}^m
$d^T x = w^T \underbrace{Ax}_{=0} = 0$	$c^T y = x^T \underbrace{A^T y}_{=0} = 0$

Every vector is covered
 — orthogonal subspaces.

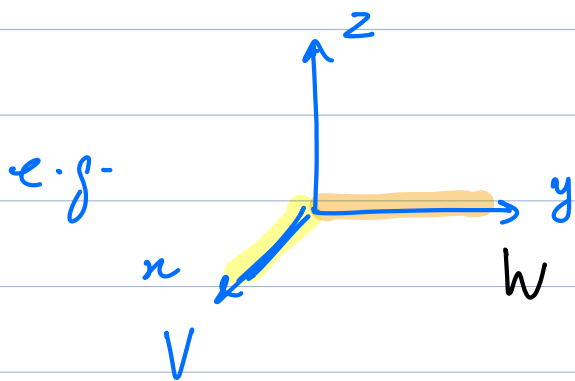
Formally: Given a subspace V , the space of all vectors orthogonal to V is called the orthogonal complement of V :

$$C(A) = N(A^T)^\perp$$

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("v perp" V^\perp)

Q: Can 2 v.s. be orthogonal without being complements? ✓



V & W are orthogonal.

e.g. z axis

∴ these are not complements.

■ If V is a v.s. of \mathbb{R}^m with $\dim r$, then the complement must be of $\dim m-r$

↳ prove? Basis for V : $\{v_1, \dots, v_r\}$

↳ Put in a matrix

$$\begin{bmatrix} v_1 & v_2 & \dots & v_r \end{bmatrix}$$

↑ ↑ ↑

$$\text{Colspace} = \text{left N.S.}^\perp$$

dim r

$m-r$

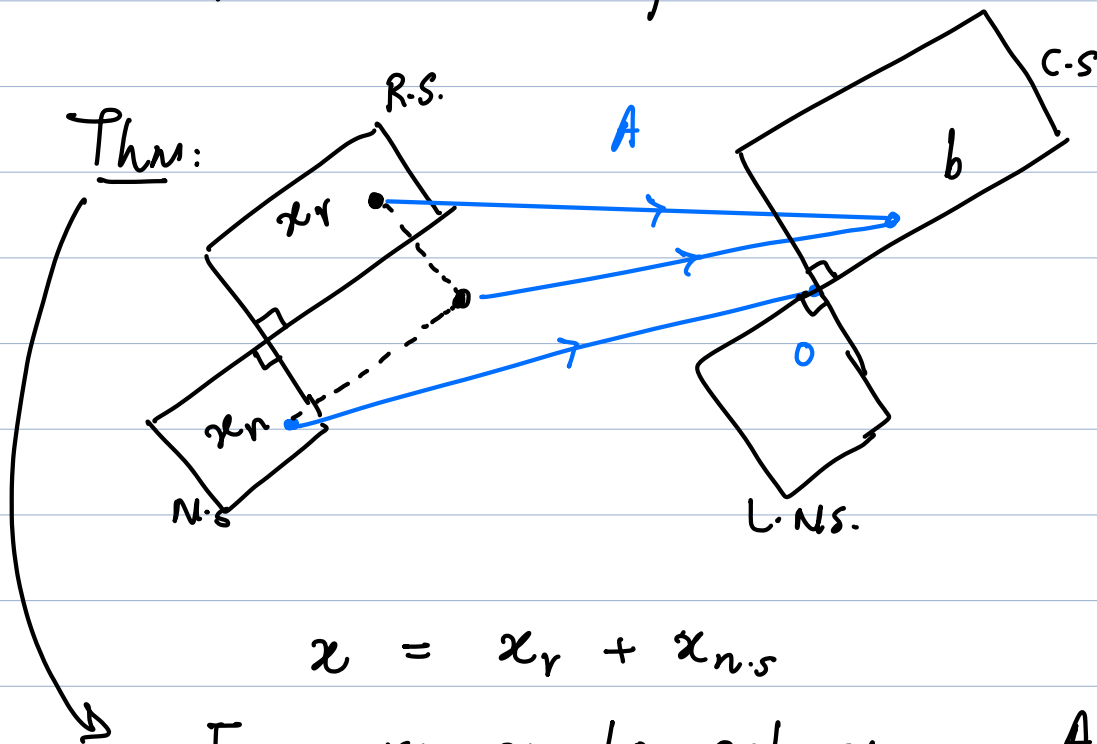
✓

(proof by construction).

Bottom line: Any space \mathbb{R}^n can be broken up into a subspace V & its orthogonal complement.

$$\rightarrow \mathbb{R}^n = \text{Row space} + \text{Null space.}$$

$$\mathbb{R}^m = \text{Col space} + \text{L. Null space.}$$



$$x = x_r + x_{n.s.}$$

From row sp to col space, A is invertible.

\Rightarrow for every b in $C(A)$, there is exactly one x_r in $C(A^T)$.

Proof: (by contradiction)

Say ~~x_r~~ $Ax_r = b$, & another x_r'
 $Ax_r' = b$, then

$$A(x_r - x_r') = b - b = 0$$

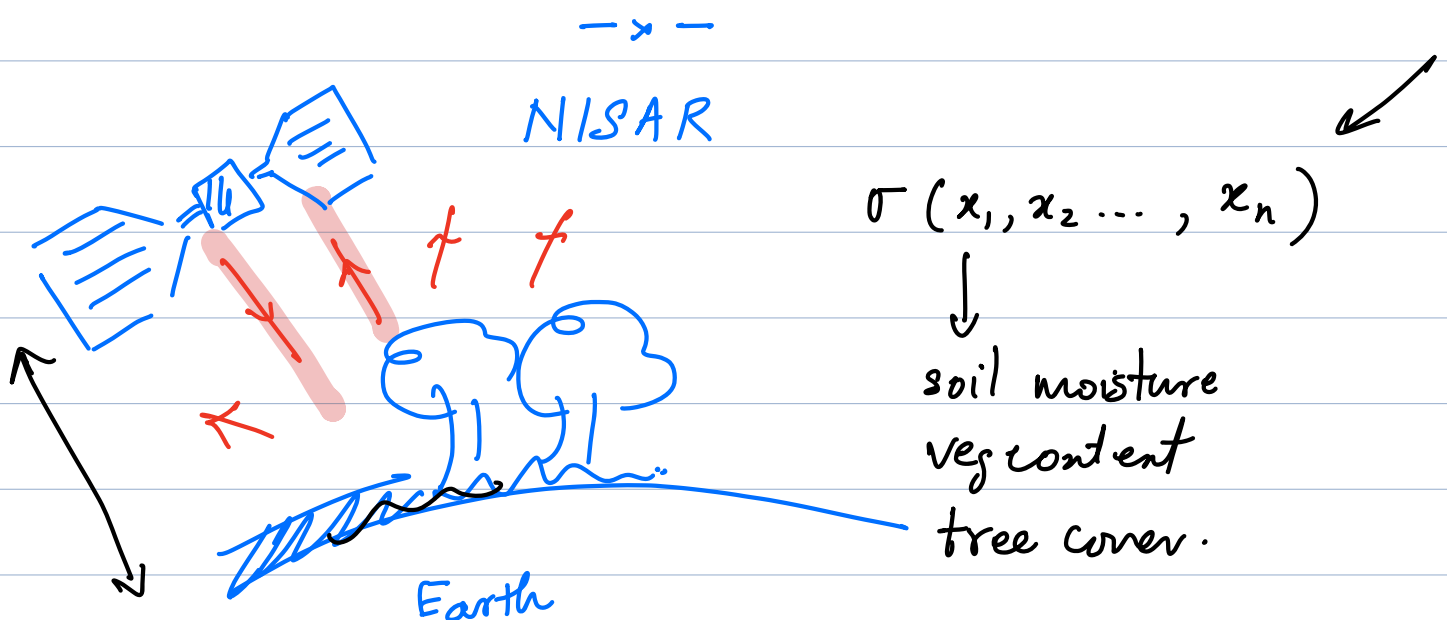
$$\Rightarrow x_r - x_r' \in N(A)$$

This is a contradiction!

$$Ax_r = b$$

If there exists a pseudoinverse $A^{\dagger}(Ax_r) = x_r$

$$A^{\dagger}(Ax_n) = 0$$



To do: Build a linear model for σ
in terms of $\{x_1, \dots, x_n\}$.

What you have: Radar meas & access to ground data.

① The model.

$$\sigma = A x + a_0$$

\downarrow \searrow \rightarrow

$1 \times n$ \mathbb{R}^n $\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$

$$\sigma(x) = \beta_0 + \sum_{i=1}^n \beta_i x_i$$

unknown? β 's.

② Determine coeffs of model.

Ground data $\rightarrow \{x_1, \dots, x_n\}$ set of values.
meas $\rightarrow \sigma_i$.

$$\begin{pmatrix} \sigma_1 \\ \vdots \\ \sigma_{n+1} \end{pmatrix} = \begin{pmatrix} 1 & x_1 & x_2 & x_3 & \dots & x_n \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & x_1^{n+1} & \dots & x_n^{n+1} \end{pmatrix} \begin{pmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_n \end{pmatrix}$$

σ A $n+1 \times n+1$ β

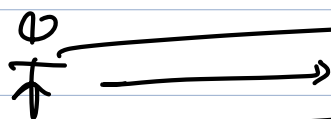
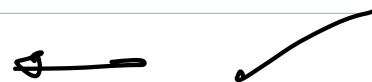
③ Solve: $\beta = A^{-1} \sigma$. if A^{-1} exists.

if doesn't, then a problem.
— x —

Least Squares Problems

Const acc

$$v = u + at$$



At various t , measure v .

Objective: estimate acc., u

$$v = u + at + \text{noise}$$

$$v = (u + at) \times \text{noise}$$

$$\begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} 1 & t_1 \\ 1 & t_2 \\ \vdots & \vdots \\ 1 & t_n \end{bmatrix} \begin{bmatrix} u \\ a \end{bmatrix} \Rightarrow Ax = b$$

v_i : can have noise,
 t_i : can also have noise.

Assume cols
of A are lin
indepn.

$$m > n.$$


more meas than variables.

1) $m > n$ \Rightarrow Either one or zero solns.

$$b \in C(A).$$

due to errors in meas, most likely
• b





2) Say that $b \notin C(A)$, what is the best that we can do?

error vector : $e = b - Ax$.

We want? x s.t. $\|e\|$ is minimized.

$$\cdot \min_x \left[\|b - Ax\| \right]$$

↓
variable of min

— λ — .