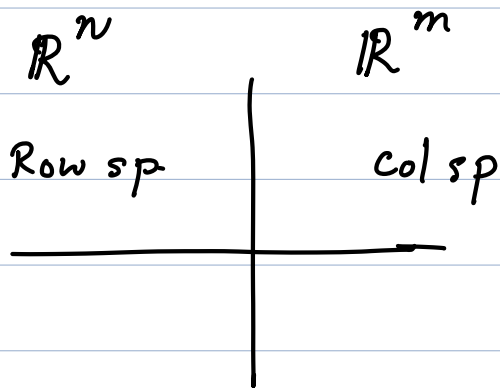


Linear Transformations.

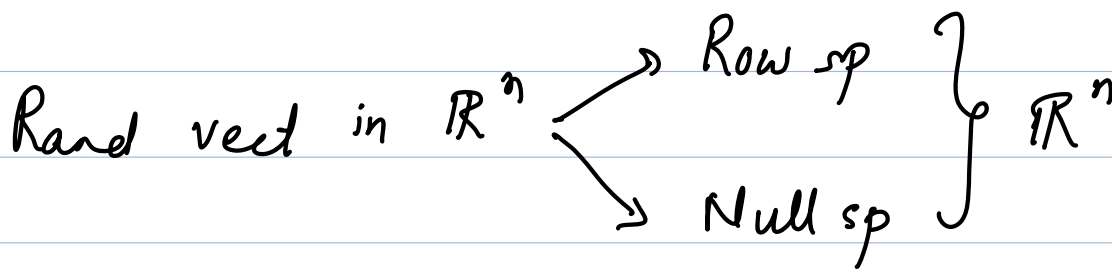
- Next tut (2) \rightarrow 17/2
- tut(1) quiz \rightarrow in class 14 or 15th Feb.



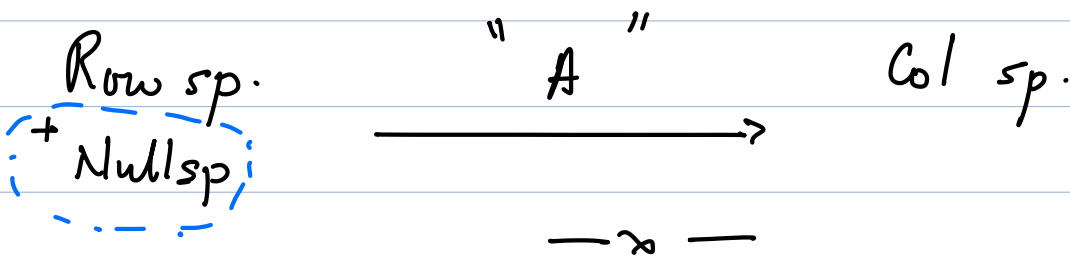
$$Ax = b$$

\downarrow in \mathbb{R}^n \searrow \mathbb{R}^m

The matrix A is "moving" x from \mathbb{R}^n to \mathbb{R}^m



$x \neq 0$, $x \in \text{Row sp.}$, due to A , \rightarrow goes to Col sp.



4 examples.

$$A_1 = \begin{pmatrix} \alpha & 0 \\ 0 & \alpha \end{pmatrix}$$

$$A_2 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

$$A_3 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

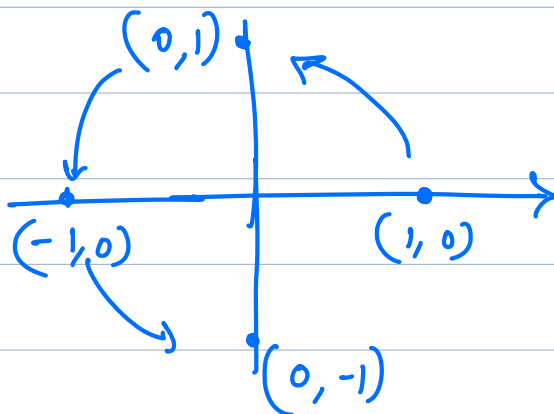
$$A_4 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

input $\begin{pmatrix} x \\ y \end{pmatrix}$

1) scaling, stretching.

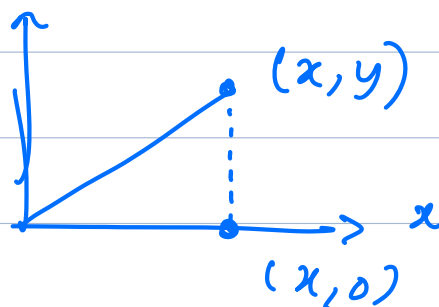
$$2) A_2 \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -y \\ x \end{pmatrix}$$

Rotation



3) Swap/mirror/reflect.

4) Projection on
x axis.



What is common?

↳ working on linear comb of coordinates.

↳ None of them move the origin!

$$\begin{array}{ccc} u & \xrightarrow{A} & v \\ p & \longrightarrow & q \end{array}$$

$$\rightarrow \alpha u + \beta p \xrightarrow{A} \alpha v + \beta q.$$

\Rightarrow Applies to any transf that comes from a matrix.

\rightarrow What is a linear transf. (also linear map).

A mapping T between 2 vector spaces V and W that preserves the operations of addition & scalar multiplication.

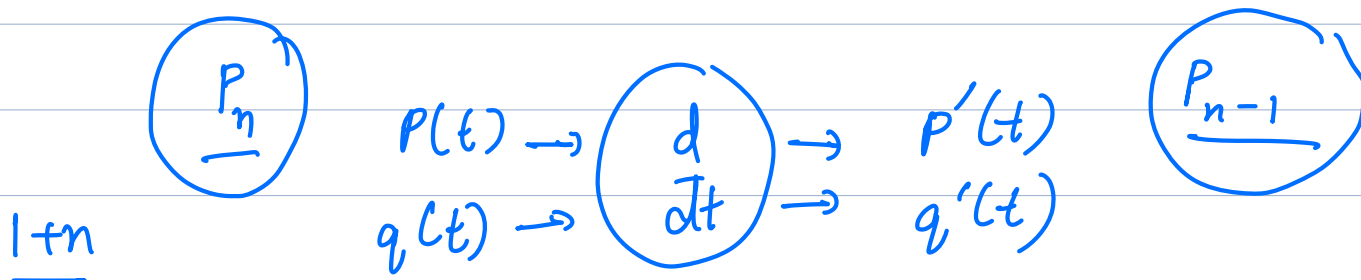
\therefore a matrix is a linear transformation.

e.g. the space of polynomials, $p(t)$, degree n .

e.g. $p(t) = a_0 + a_1 t + a_2 t^2 + \dots + a_n t^n$
 $n+1$ coefs are reqd. P_n

Q1: operation of $\frac{d}{dt}$ is linear?

$$\frac{d}{dt} (a_0 + \dots + a_n t^n) = a_1 + 2a_2 t + \dots + n a_n t^{n-1}$$



\therefore This is a linear transf.

Does this transf have a null space

Yes! any $P(t) = a_0$

$$\left. \begin{array}{l} \text{Nullity} = 1 \\ \text{rank} = n \end{array} \right\}$$

Sum of rank, nullity = dim of orig space P_n

e.g. 2. Integration: \int_0^t

$$\int_0^t p(t) dt = a_0 t + a_1 \frac{t^2}{2} + \dots + a_n \frac{t^{n+1}}{n+1}$$

Is it a linear transf. ✓

No nontrivial null space

Transformations as Matrices

space of P_n (polynomials).

$$p(t) = a_0 + a_1 t + \dots + a_n t^n$$

Coeffs:

$$\begin{pmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{pmatrix}$$

$\hookrightarrow n+1$

Is there a basis to express such a vector?

Yes, canonical basis

$$\begin{pmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

...

$$\begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix}$$

$$p = \sum_{i=1}^{n+1} a_i p_i \quad \begin{matrix} \downarrow & \downarrow & \downarrow \\ p_1 & p_2 & p_{n+1} \end{matrix}$$

$p_i \rightarrow \text{const term.}$

↳ e.g. if differentiation.

$$\frac{dp(t)}{dt} = a_0 \times 0 + a_1 \times 1 + a_2 \times 2t \dots + a_n \times nt^{n-1}$$

basis P_3 of P_3 $\left[p_1 = 1, p_2 = t, p_3 = t^2, p_4 = t^3 \right]$

due to d/dt $\left[A p_1 = 0, A p_2 = p_1, A p_3 = 2 p_2, A p_4 = 3 p_3 \right]$

$$A \left[\begin{array}{c|c|c|c} p_1 & p_2 & p_3 & p_4 \end{array} \right] = A_{\text{diff}} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

↑
input space
basis
vectors

↳ $p = 2 + t - t^2 - t^3$. find $\frac{dp}{dt}$.

$$p = \begin{pmatrix} 2 \\ 1 \\ -1 \\ -1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \\ -1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ -2 \\ -3 \\ 0 \end{pmatrix}$$

$$1 - 2t - 3t^2 \quad \checkmark$$

Recipe .

$$V \xrightarrow{T} W$$

- 1) Need a basis for the input space $V: \{x_1, \dots, x_n\}$
- 2) Need a basis for the o/p space $W: \{y_1, \dots, y_m\}$

$$\text{Col } j \text{ of } A \quad T(x_j) = \left(\alpha_1 y_1 + \dots + \alpha_m y_m \right)$$

eg. 2 integration $V = P_3, W = P_4$

$$[x_1 = 1, x_2 = t, x_3 = t^2, x_4 = t^3]$$

$$[y_1 = 1, y_2 = t, y_3 = t^2, y_4 = t^3, y_5 = t^4]$$

$$\underline{A} \longrightarrow \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & \frac{1}{3} & 0 \\ 0 & 0 & 0 & \frac{1}{4} \end{pmatrix} \quad \leftarrow A_{\text{integ.}}$$

$1^{\text{st}} \rightarrow x_1$

$T(x_1) \rightarrow t$, in $\{y\}$ basis

$$T(x_2) \rightarrow \frac{t^2}{2}$$

$$T(x_3) \rightarrow \frac{t^3}{3}$$

$$T(x_4) \rightarrow \frac{t^4}{4}$$

(we didn't need y_1)

$$p(t) = t + \frac{t^2}{5} \quad \text{i/p.}$$

$$\int_0^1 p(t) dt = \frac{t^2}{2} + \frac{t^3}{15} \text{ o/p.}$$

$$\begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & \frac{1}{3} & 0 \\ 0 & 0 & 0 & \frac{1}{4} \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ \frac{1}{5} \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \frac{1}{2} \\ \frac{1}{15} \\ 0 \end{pmatrix}$$

→ ∞ → .

