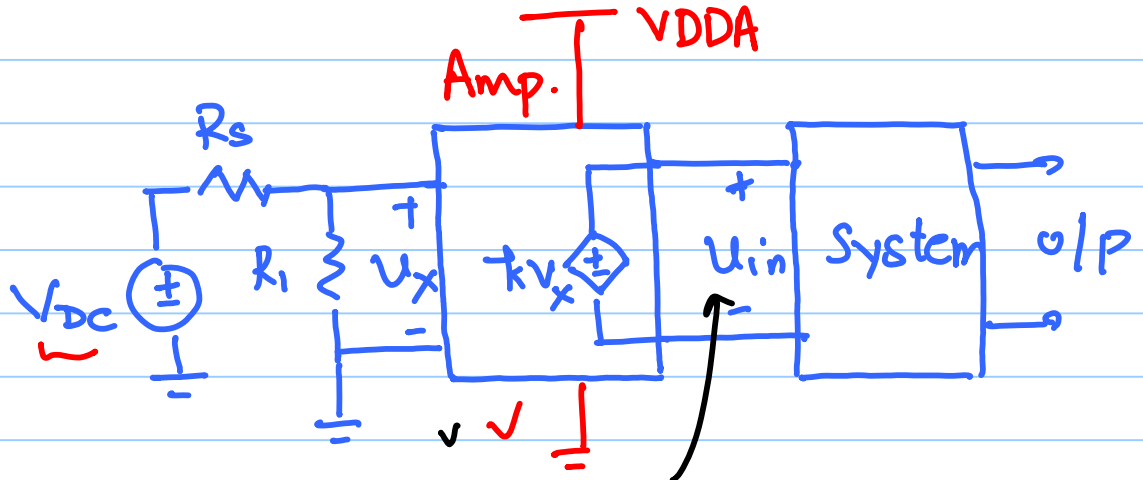
Lecture # 03

Note Title 04-02-2021



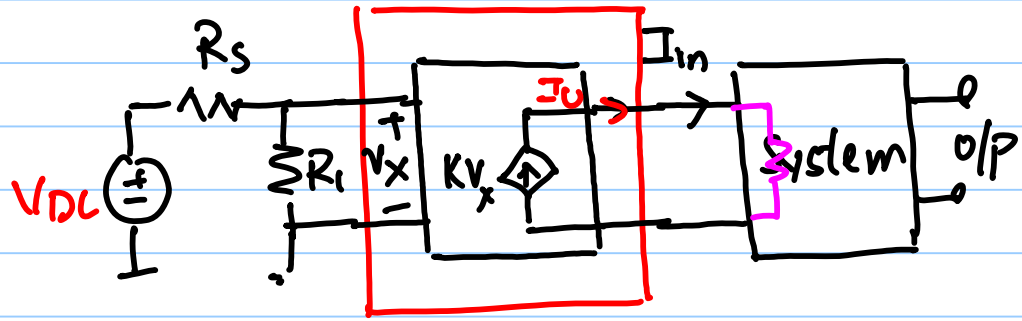
as large as required by sys.

$$V_x = \frac{R_1}{R_1+R_s} V_{DC}$$

$$U_{in} = kV_x \leq V_{DC}$$

$$> V_{DC}$$

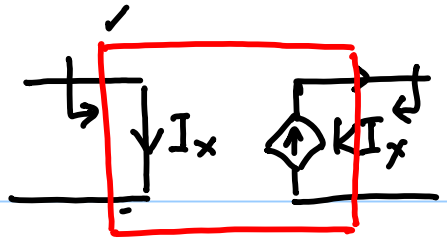
VCVS: Voltage Controlled Voltage Source.



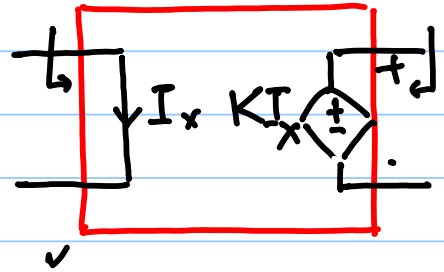
VCCS: Voltage Controlled Current Source

$$I_o = kV_x = k \cdot \frac{R_1}{R_1+R_s} V_{DC}$$

Current Controlled Current Source (CCCS)



Current Controlled Voltage Source (CCVS)

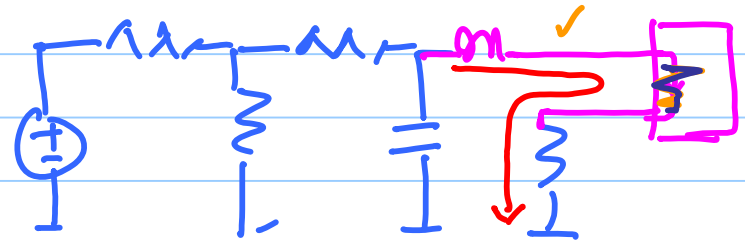


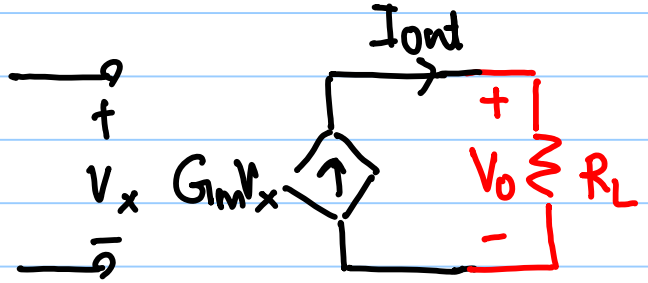
Voltage source @ o/p $\Rightarrow$ $Z_{out} = 0$

Current source @ o/p $\Rightarrow$ $Z_{out} = \infty$

Voltage sensing @ i/p $\Rightarrow$ $Z_{in} = \infty$

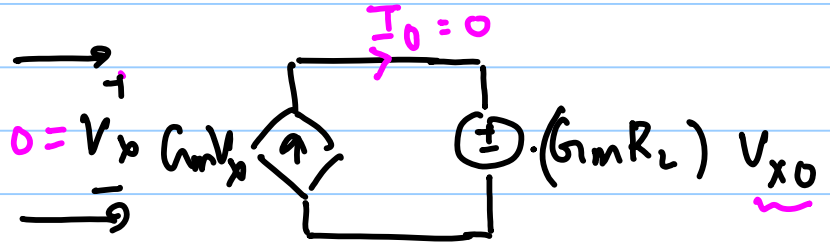
Current sensing @ i/p $\Rightarrow$ $Z_{in} = 0$

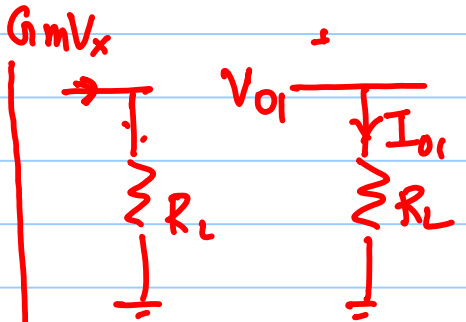




$V_o = G_m V_x \cdot R_L$

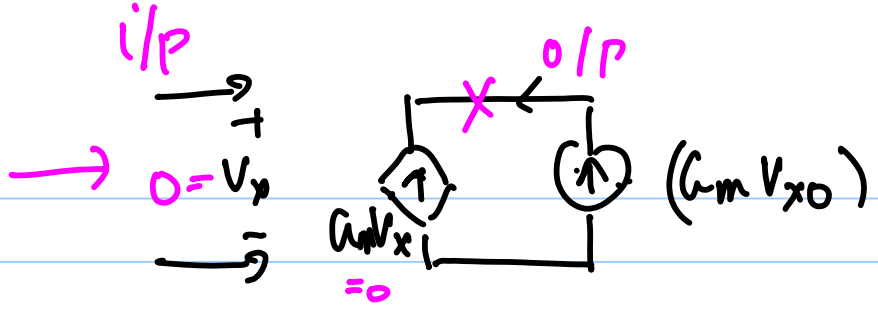
$= (G_m R_L) V_x$

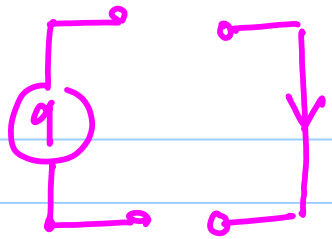


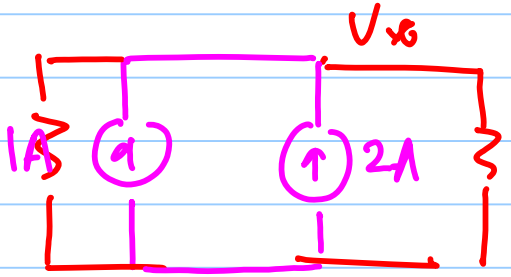


$V_{o1} = (G_m R_L) V_x$

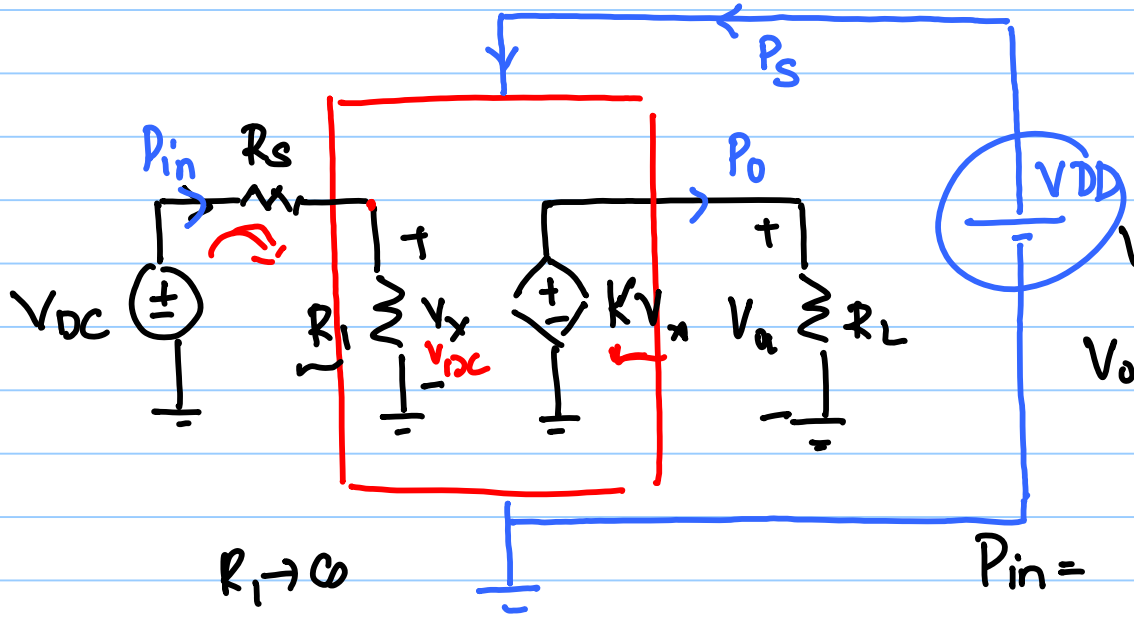
$I_{o1} = G_m V_x$







Unilateral controlled sources.



$V_o = K V_x$

$V_o = K \dfrac{R_1}{R_1 + R_S} V_{DC}$

$P_{in} = \dfrac{V_{DC}^2}{R_1 + R_S}$

$P_{out} = \dfrac{K^2 V_x^2}{R_L} = \dfrac{K^2 V_{DC}^2}{R_L} \dfrac{R_1^2}{(R_1+R_S)^2}$

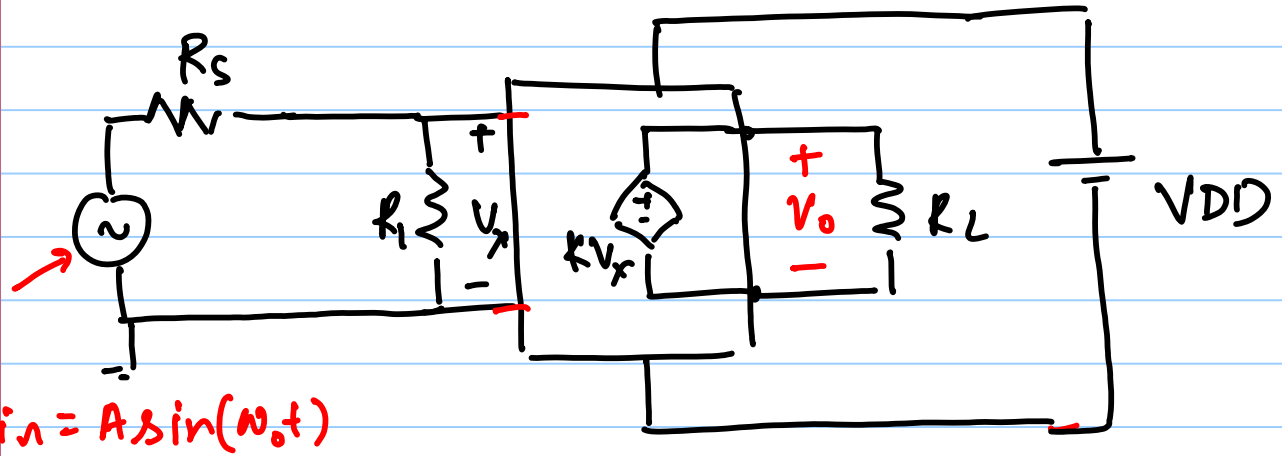
$\dfrac{P_{out}}{P_{in}} = \dfrac{K^2 R_1^2 / R_L (R_1+R_S)^2}{1/(R_1+R_S)} = \dfrac{K^2 R_1^2}{R_L (R_1+R_S)}$

$$\frac{P_{out}}{P_{in}} = \frac{K^2}{\frac{R_L}{R_1}\left(1+\frac{R_S}{R_1}\right)} > 1$$

$P_S + P_{in} \geq P_{out}$

V_{DDA}, (A)V_{DD}, (D)V_{DD}

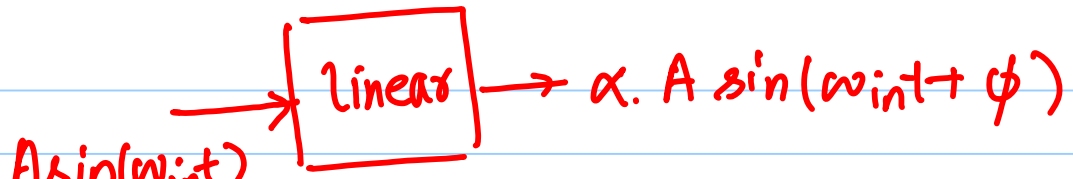
Analog Digital

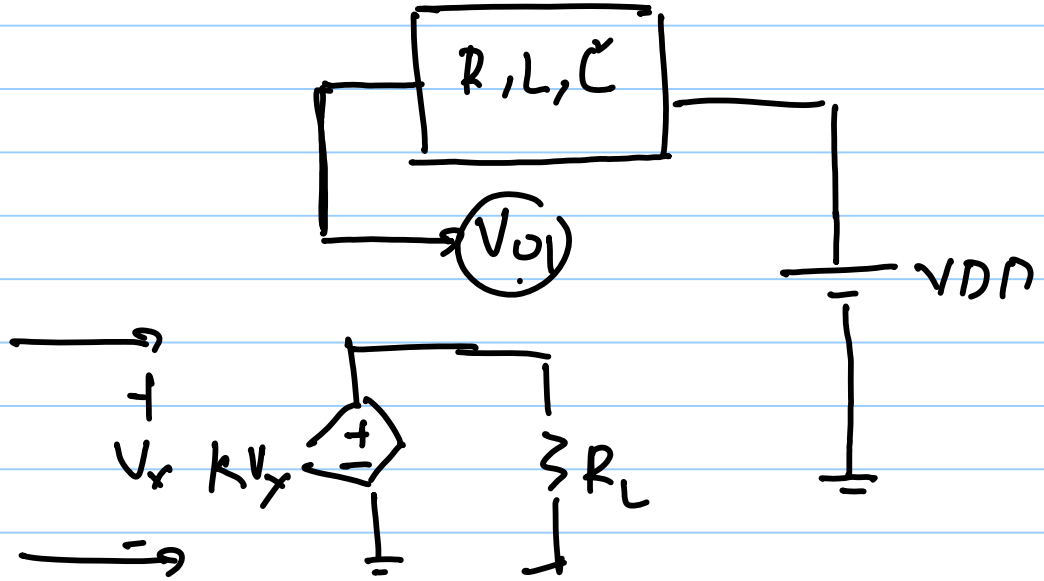


$$V_o = kV_x = k\frac{R_1}{R_1+R_S}(A\sin(\omega_0 t))$$

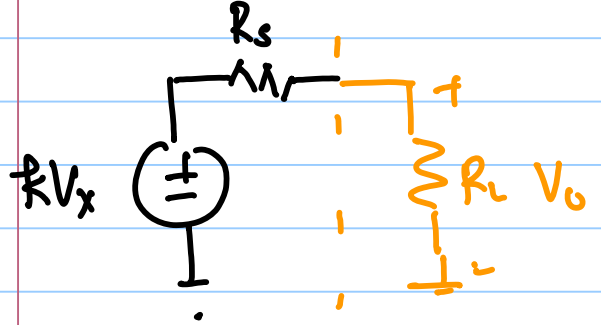
$$V_o = k\frac{R_1}{R_1+R_S}A\sin(\omega_0 t)$$

- Power gain from i/p to o/p irrespective of i/p amp. & frequency
- Power is drawn from supply V_{DD} and delivered to o/p.





⇒ Non-linear system to deliver power at o/p with $\frac{P_{out}}{P_{in}} > 1$



$$V_o = \frac{R_L}{R_L + R_s}(kV_x)$$