

Review of Gaussian random variables and vectors:

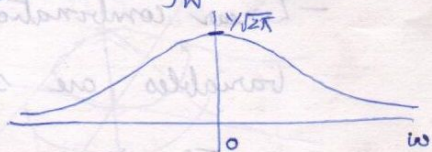
Scalar real Gaussian random variables

Standard Gaussian random variable W takes values over the real line \mathbb{R} and has pdf

$$f_W(w) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{w^2}{2}\right), \quad w \in \mathbb{R}.$$

Mean of $W = E[W] = 0$.

Variance of $W = E[W^2] (= \sigma^2) = 1$.

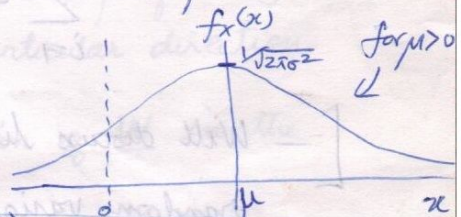


General Gaussian random variable $X = \sigma W + \mu$

Mean of $X = E[X] = \mu$.

Variance of $X = E[(X-\mu)^2] = \sigma^2$

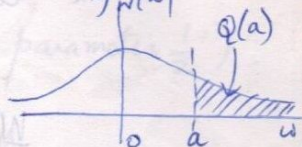
$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right), \quad x \in \mathbb{R}.$$



Notation: $X \sim N(\mu, \sigma^2)$ (Standard Gaussian $W \sim N(0, 1)$)

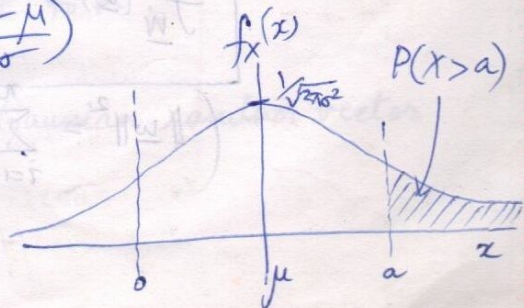
Tail probability of the standard Gaussian r.v.:

$$Q(a) = P(W > a) = \int_a^{\infty} f_W(w) dw = \int_a^{\infty} \frac{1}{\sqrt{2\pi}} e^{-w^2/2} dw$$



Tail probability of a general Gaussian r.v.:

$$\begin{aligned} P(X > a) &= P(\sigma W + \mu > a) \\ &= P\left(W > \frac{a - \mu}{\sigma}\right) \\ &= Q\left(\frac{a - \mu}{\sigma}\right) \end{aligned}$$



Useful bounds on $Q(a)$:

$$\frac{1}{\sqrt{2\pi} a} \left(1 - \frac{1}{a^2}\right) e^{-a^2/2} < Q(a) < e^{-a^2/2} \quad \text{for } a > 1$$

\Rightarrow Tail probability decays exponentially fast (as a increases).

Linear transformations of Gaussian random variables:

- Linear combinations of independent Gaussian random variables are still Gaussian.

If X_1, X_2, \dots, X_n are independent and $X_i \sim N(\mu_i, \sigma_i^2)$,

then

$$\sum_{i=1}^n c_i X_i \sim N\left(\sum_{i=1}^n c_i \mu_i, \sum_{i=1}^n c_i^2 \sigma_i^2\right).$$

[- Will discuss linear combinations of jointly Gaussian random variables after discussing jointly Gaussian random vectors]

- Real Gaussian random vectors:

Standard Gaussian random vector \underline{W} :

* Collection of n i.i.d. standard Gaussian r.v.s
 W_1, W_2, \dots, W_n .

$$\underline{W} = (W_1, W_2, \dots, W_n)^T.$$

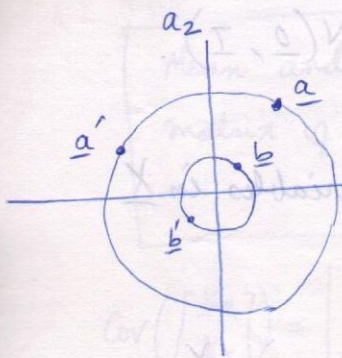
* Takes values in \mathbb{R}^n .

$$f_{\underline{W}}(\underline{w}) = \frac{1}{(\sqrt{2\pi})^n} \exp\left(-\frac{\|\underline{w}\|^2}{2}\right), \quad \underline{w} \in \mathbb{R}^n$$

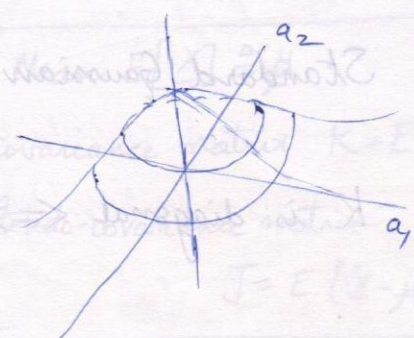
$(\|\underline{w}\|^2 = \sum_{i=1}^n w_i^2)$; Euclidean distance from origin $\underline{0}$ to $\underline{w} = (w_1, w_2, \dots, w_n)^T$

Note that the pdf $f_{\underline{w}}(\underline{w})$ depends only on the magnitude of the argument (i.e. only $\|\underline{w}\|$).

* If $T_{n \times n}$ is an orthonormal transformation; i.e., $T^T T = T T^T = I_n$, then $T \underline{w}$ is also standard Gaussian. ($T_{n \times n}$ preserves the magnitude of a vector. ($\|T \underline{w}\|^2 = \underline{w}^T T^T T \underline{w} = \underline{w}^T \underline{w} = \|\underline{w}\|^2$)
Isotropic property.
(- Rotations and reflections are some such transformations)



$n=2$
 $f(\underline{a}) = f(\underline{a}')$
 $f(\underline{b}) = f(\underline{b}')$



\underline{w} does not prefer any particular direction.

Each element of $T \underline{w}$ is a projection of \underline{w} in the direction defined by a row of T .

\Rightarrow Projections of the standard Gaussian random vector in orthogonal directions are independent.

* $\|\underline{w}\|^2 \Leftrightarrow \sum_{i=1}^n w_i^2 \sim \chi_n^2$ chi-squared random variable with n degrees of freedom.

for $n=2$, $f_{\|\underline{w}\|^2}(a) = \frac{1}{2} e^{-a/2}$, $a \geq 0$.

(exponential distribution for $n=2$ with parameter $\frac{1}{2}$).

(2, 3/1/12)

General Gaussian random vector $\underline{X} = A \underline{w} + \underline{\mu}$

$\underline{\mu} \in \mathbb{R}^n$

A : linear transformation from \mathbb{R}^n to \mathbb{R}^n .

* Any linear transformation of a Gaussian random vector is also Gaussian.

* If A is invertible, then

$$f_{\underline{X}}(\underline{x}) = \frac{1}{(\sqrt{2\pi})^n \sqrt{\det(AA^T)}} \exp\left[-\frac{1}{2} (\underline{x}-\underline{\mu})^T (AA^T)^{-1} (\underline{x}-\underline{\mu})\right]$$

* Mean vector $E[\underline{X}] = \underline{\mu}$.

$$\text{Covariance matrix} = E[(\underline{X}-\underline{\mu})(\underline{X}-\underline{\mu})^T] = AA^T \triangleq K.$$

$\underline{X} \sim N(\underline{\mu}, K)$. [Note that \underline{X} is completely characterized by $\underline{\mu}$ and K].

Standard Gaussian random vector $\underline{W} \sim N(\underline{0}, I)$.

* K is diagonal \Leftrightarrow component random variables in \underline{X} are independent.

$K = I \Leftrightarrow$ component random variables in \underline{X} are independent and have the same unit variance.

(also called white Gaussian random vector).

* If A is not invertible,

$A\underline{W}$ maps \underline{W} into a subspace of dimension less than n .

Density of $A\underline{W}$ equals 0 outside this subspace and impulsive inside. $\delta(\underline{W})$

Some components of $A\underline{W}$ can be expressed as linear combinations of the others.

\Rightarrow We can think of \underline{X} to have some

components $\tilde{\underline{X}}$ that are linearly independent combinations of \underline{W} and other components are linear combinations of elements in $\tilde{\underline{X}}$.

$\tilde{\underline{X}}$ will have an invertible covariance matrix.

We will take K to be invertible in general for simplicity. Otherwise, we can handle using the above separation of \underline{X} into $\tilde{\underline{X}}$ and other components.

Complex Gaussian random vectors:

$$\underline{X} = \underline{X}_R + j \underline{X}_I$$

where $\underline{X}_R, \underline{X}_I$ are real random vectors.

→ \underline{X} is complex Gaussian if $\begin{bmatrix} \underline{X}_R \\ \underline{X}_I \end{bmatrix}$ is a real Gaussian random vector.

→ Distribution of \underline{X} is specified completely by

Mean and covariance matrix of $\begin{bmatrix} \underline{X}_R \\ \underline{X}_I \end{bmatrix}$

(or) equivalently

Mean $E[\underline{X}] \triangleq \underline{\mu}$.
Covariance matrix $K = E[(\underline{X} - \underline{\mu})(\underline{X} - \underline{\mu})^H]$
Pseudo-covariance matrix $J = E[(\underline{X} - \underline{\mu})(\underline{X} - \underline{\mu})^T]$

$$\text{Cov} \left(\begin{bmatrix} \underline{X}_R \\ \underline{X}_I \end{bmatrix} \right) = \begin{bmatrix} C_R & C_{RI} \\ C_{IR} & C_I \end{bmatrix}$$

where $C_{IR} = C_{RI}^T$.

$$K = (C_R + C_I) + j(C_{IR} - C_{RI})$$

$$J = (C_R - C_I) + j(C_{IR} + C_{RI})$$

→ \underline{X} is circularly symmetric if $e^{j\theta} \underline{X}$ has the same distribution as \underline{X} for any θ .

$$\Rightarrow (1) E[\underline{X}] = E[e^{j\theta} \underline{X}] \Rightarrow E[\underline{X}] = \underline{0} \text{ (zero-mean)}$$

$$(2) E[\underline{X} \underline{X}^T] = E[e^{j\theta} \underline{X} e^{j\theta} \underline{X}^T] = e^{j2\theta} E[\underline{X} \underline{X}^T]$$

$$\Rightarrow E[\underline{X} \underline{X}^T] = \underline{0}$$

$$\Rightarrow J = \underline{0} \text{ (zero pseudo-covariance)}$$

$$\Rightarrow C_R = C_I, \quad C_{IR} = -C_{RI}$$

If \underline{X} is circularly symmetric, K fully specifies the second-order statistics. Further, if \underline{X} is also Gaussian, K specifies the entire statistics.

Denoted $CN(\underline{0}, K)$.

Special cases:

(1) $n=1$ Complex Gaussian random variable

$$X = X_R + jX_I \rightarrow 5 \text{ parameters in general}$$
$$E[X_R], E[X_I], E[X_R^2], E[X_I^2], E[X_R X_I]$$

X_R, X_I i.i.d

zero-mean Gaussian

\Leftrightarrow circularly symmetric X .

$$\sim CN(0, \sigma^2)$$

$$\sigma^2 = E[X_R^2] = E[X_I^2]$$

Only one parameter σ^2 .

Standard circularly symmetric complex Gaussian $CN(0, 1)$.

(2) Standard circularly symmetric complex Gaussian random vector $\underline{W} \sim CN(\underline{0}, I_n)$

$$f_{\underline{W}}(\underline{w}) = \frac{1}{\pi^n} \exp(-\|\underline{w}\|^2), \quad \underline{w} \in \mathbb{C}^n$$

$U\underline{W}$ has the same distribution as \underline{W} if

U is unitary, i.e., $U^H U = I$. (Isotropic property)

$$\|\underline{W}\|^2 \sim \chi_{2n}^2 \text{ (chi-squared r.v. with } 2n \text{ degrees of freedom)}$$

$\rightarrow \underline{X} = A\underline{W}$ is also circularly symmetric complex Gaussian with covariance matrix $K = AA^H$.

$$\underline{X} \sim CN(\underline{0}, K)$$

Also, any circular symmetric complex Gaussian r. vector can be written as a linearly transformed version of a standard circularly symmetric complex Gaussian r. vector.

If A is invertible, we have

$$f_{\underline{X}}(\underline{x}) = \frac{1}{\pi^n \det(K)} \exp(-\underline{x}^H K^{-1} \underline{x}), \quad \underline{x} \in \mathbb{C}^n$$

Detection in Gaussian noise:

Scalar case

$$y = u + w \quad (\text{real AWGN channel})$$

u is equally likely to be u_A or u_B

$$w \sim N(0, \frac{N_0}{2})$$

Detection problem: Observe Y and decide on U .

$$\hat{U} = g(Y)$$

$g(\cdot)$ specifies detection rule.

Choose $g(\cdot)$ to minimize probability of error.

$$P_e = \Pr(\hat{U} \neq U)$$

Minimize $\Pr(\hat{U} \neq U | Y=y)$ for each y .

$$\Rightarrow \hat{U} = u_A \text{ if } \boxed{\Pr(U = u_A | Y=y) \geq \Pr(U = u_B | Y=y)} \quad (\text{MAP rule})$$

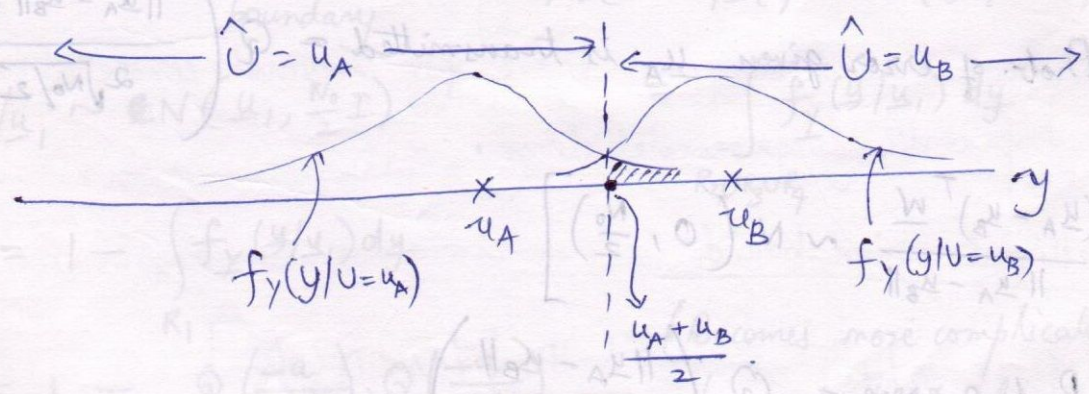
$$\Rightarrow \hat{U} = u_A \text{ if } f_Y(y | U = u_A) P(U = u_A) \geq f_Y(y | U = u_B) P(U = u_B)$$

$$\Rightarrow \hat{U} = u_A \text{ if } \boxed{f_Y(y | U = u_A) \geq f_Y(y | U = u_B)} \quad (\text{ML rule}) \quad (\text{since } P(U = u_A) = P(U = u_B))$$

$$\frac{1}{\sqrt{2\pi(\frac{N_0}{2})}} e^{-\frac{(y-u_A)^2}{2(\frac{N_0}{2})}} \geq \frac{1}{\sqrt{2\pi(\frac{N_0}{2})}} e^{-\frac{(y-u_B)^2}{2(\frac{N_0}{2})}}$$

$$\hat{U} = u_A \text{ if } (y-u_A)^2 \leq (y-u_B)^2 \quad [\text{Nearest neighbour rule}]$$

$$\text{or } |y-u_A| \leq |y-u_B|$$



— Easily extends to M -ary signaling (u_1, u_2, \dots, u_M) instead of binary signaling (u_A, u_B) . [Nearest-neighbour detection]

Vector case:

$$\underline{y}_{n \times 1} = \underline{u}_{n \times 1} + \underline{w}_{n \times 1}$$

$\underline{w} \sim N(0, \frac{N_0}{2} \mathbf{I})$ white Gaussian noise

\underline{u} is either \underline{u}_A or \underline{u}_B with equal probability

ML rule: $\hat{\underline{u}} = \underline{u}_A$ if $f_{\underline{y}}(\underline{y} | \underline{u} = \underline{u}_A) \geq f_{\underline{y}}(\underline{y} | \underline{u} = \underline{u}_B)$

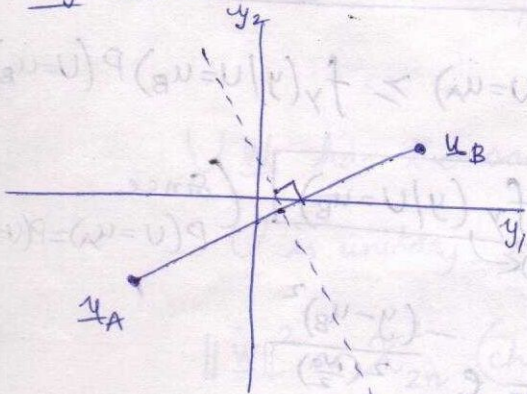
$$(or) \|\underline{y} - \underline{u}_A\|^2 \leq \|\underline{y} - \underline{u}_B\|^2$$

$$\left[\text{Since } f_{\underline{y}}(\underline{y} | \underline{u} = \underline{u}_A) = \frac{1}{(2\pi \frac{N_0}{2})^{N/2}} \cdot \exp\left(-\frac{\|\underline{y} - \underline{u}_A\|^2}{N_0}\right) \right]$$

Nearest neighbour rule:

- Projection of \underline{y} onto $\underline{u}_A - \underline{u}_B$ sufficient

e.g. 2D case



- Projection of noise along $\underline{u}_A - \underline{u}_B$ determines performance

- Noise orthogonal to $\underline{u}_A - \underline{u}_B$ is independent of noise along $\underline{u}_A - \underline{u}_B$ and irrelevant.

↳ Boundary: Hyperplane perpendicular to $\underline{u}_B - \underline{u}_A$.

$$\begin{aligned} (\underline{u}_A - \underline{u}_B)^T \underline{w} &\sim N\left(0, (\underline{u}_A - \underline{u}_B)^T \frac{N_0}{2} (\underline{u}_A - \underline{u}_B)\right) \\ &N\left(0, \|\underline{u}_A - \underline{u}_B\|^2 \cdot \frac{N_0}{2}\right) \end{aligned}$$

$$\text{Prob. of error given } \underline{u}_A \text{ is transmitted} = Q\left(\frac{\|\underline{u}_A - \underline{u}_B\| \sqrt{\frac{N_0}{2}}}{2\sqrt{N_0/2}}\right)$$

$$\left[\frac{(\underline{u}_A - \underline{u}_B)^T \underline{w}}{\|\underline{u}_A - \underline{u}_B\|} \sim N\left(0, \frac{N_0}{2}\right) \right]$$

$$\text{Prob. of error} = Q\left(\frac{\|\underline{u}_A - \underline{u}_B\|}{2\sqrt{N_0/2}}\right)$$

- Minimum distance/nearest neighbour rule for M-ary case as well.

Complex vector case

$$\underline{Y} = \underline{U} + \underline{W}$$

\underline{Y} is $n \times 1$, \underline{U} is $n \times 1$, \underline{W} is $n \times 1$

$\underline{W} \sim \mathcal{CN}(\underline{0}, N_0 \mathbf{I}_{n \times n})$ white Gaussian noise.

\underline{U} is either \underline{u}_A or \underline{u}_B with equal probability

Note: Any $\underline{y} > \underline{0}$ is \underline{u}_A and $\underline{y} < \underline{0}$ is \underline{u}_B

ML rule: $\hat{\underline{U}} = \underline{u}_A$ if $\|\underline{y} - \underline{u}_A\|^2 \leq \|\underline{y} - \underline{u}_B\|^2$.

- Projection of \underline{Y} onto $\underline{u}_A - \underline{u}_B$ sufficient.

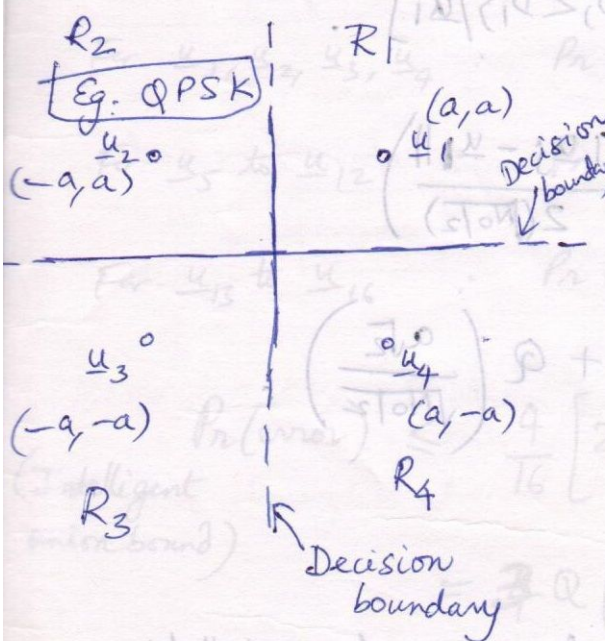
$$\frac{(\underline{u}_A - \underline{u}_B)^H \underline{Y}}{\|\underline{u}_A - \underline{u}_B\|} \rightarrow \text{a complex scalar r.v.}$$

- Only noise along this vector determines performance.
- Can think of this as real vector case with dimension $2n$.

Probability of error and bounds (M-ary case):

\underline{U} can take values $\underline{u}_1, \underline{u}_2, \dots, \underline{u}_M$.

Decision rule: $\hat{\underline{U}} = \arg \min_i \|\underline{y} - \underline{u}_i\|^2 = \arg \min_i D_i^2$



$$Pr(\text{error}) = \sum_{i=1}^M Pr(\text{error} | \underline{u}_i) Pr(\underline{u}_i)$$

Assume $Pr(\underline{u}_i) = \frac{1}{4}$.

By symmetry, $Pr(\text{error} | \underline{u}_i)$ same for all i .

Decision regions denoted R_1, R_2, R_3, R_4

$$Pr(\text{error} | \underline{u}_i) = Pr(\underline{y} \notin R_1 | \underline{u}_1)$$

$$\begin{aligned} \underline{Y} | \underline{u}_1 &\sim \mathcal{CN}(\underline{u}_1, \frac{N_0}{2} \mathbf{I}) \\ &= \int_{R_2 \cup R_3 \cup R_4} f_{\underline{Y}}(\underline{y} | \underline{u}_1) d\underline{y} \\ &= 1 - \int_{R_1} f_{\underline{Y}}(\underline{y} | \underline{u}_1) d\underline{y} \end{aligned}$$

$$\begin{aligned} &= 1 - Q\left(\frac{-a}{N_0/2}\right) \cdot Q\left(\frac{-a}{N_0/2}\right) \\ &= 1 - \left(1 - Q\left(\frac{a}{N_0/2}\right)\right)^2 \end{aligned}$$

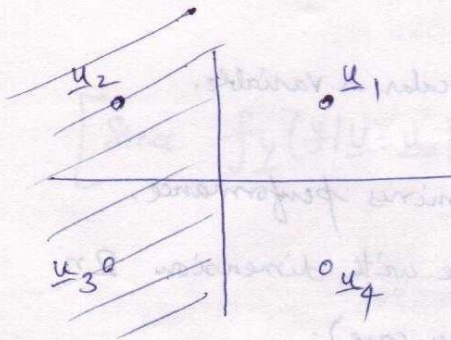
(Becomes more complicated to evaluate for large M and more complicated decision boundaries)

Union bound

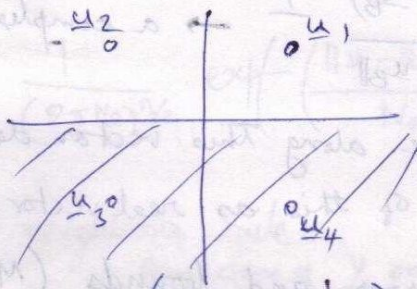
$$Pr(\text{error}/u_i) = Pr \left[\bigcup_{j \neq i} \{D_j < D_i\} / u_i \right]$$

$$\leq \sum_{j \neq i} Pr \left[\{D_j < D_i\} / u_i \right]$$

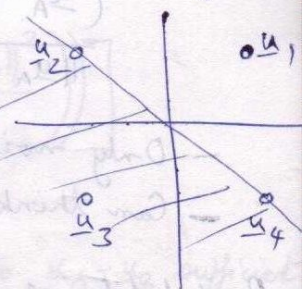
Pairwise error probability
for binary detection
between signals u_i and u_j



$$Pr(D_2 < D_1 / u_1)$$



$$Pr(D_4 < D_1 / u_1)$$



$$Pr(D_3 < D_1 / u_1)$$

$$Pr(\text{error}/u_i) \leq \sum_{j=2}^4 Pr \left[\{D_j < D_1\} / u_1 \right]$$

$$= \sum_{j=2}^4 Q \left(\frac{\|u_j - u_1\|}{2\sqrt{N_0/2}} \right)$$

$$= 2Q \left(\frac{a}{\sqrt{N_0/2}} \right) + Q \left(\frac{a\sqrt{2}}{\sqrt{N_0/2}} \right)$$

Union bound.

→ Union bound can be loose for several constellations, especially large constellations.

4/3/12

Intelligent union bound

$$Pr(\text{error}/u_i) \leq \sum_{j \in N_{ML}^{(i)}} Pr \left[\{D_j < D_i\} / u_i \right]$$

Set of neighbours of i that characterize the decision region R_i

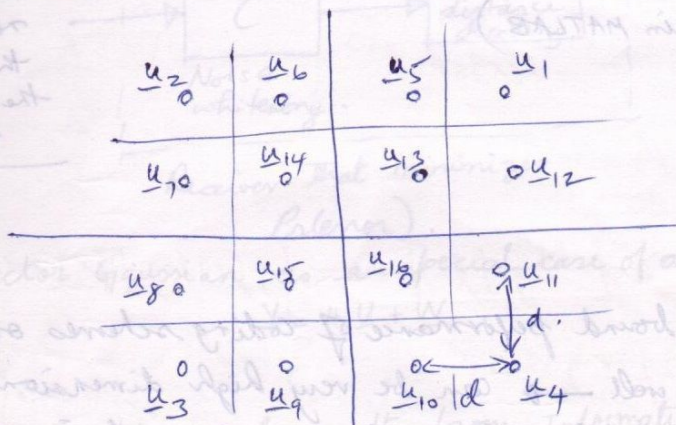
- In the above QPSK example, only u_2 and u_4 define R_1 (6)

R_1 .

$$\Rightarrow \Pr(\text{error}/u_1) \leq 2Q\left(\frac{a}{\sqrt{N_0/2}}\right)$$

Note: Any pairwise error probability $P[D_j < D_i | u_i]$ is a lower bound for $\Pr(\text{error}/u_i)$.

Eg. 16-QAM



For u_1, u_2, u_3, u_4 : $\Pr(\text{error}/u_i) \leq 2Q\left(\frac{d}{2\sigma}\right)$

For u_5 to u_{12} : $\Pr(\text{error}/u_i) \leq 3Q\left(\frac{d}{2\sigma}\right)$

For u_{13} to u_{16} : $\Pr(\text{error}/u_i) \leq 4Q\left(\frac{d}{2\sigma}\right)$

(Intelligent union bound)

$$\Pr(\text{error}) \leq \frac{4}{16} \left[2Q\left(\frac{d}{2\sigma}\right) \right] + \frac{8}{16} \left[3Q\left(\frac{d}{2\sigma}\right) \right] + \frac{4}{16} \left[4Q\left(\frac{d}{2\sigma}\right) \right]$$

$$= 3Q\left(\frac{d}{2\sigma}\right)$$

(Simple union bound will be looser and involve many more terms - 15 terms for each u_i).

Nearest neighbours approximation

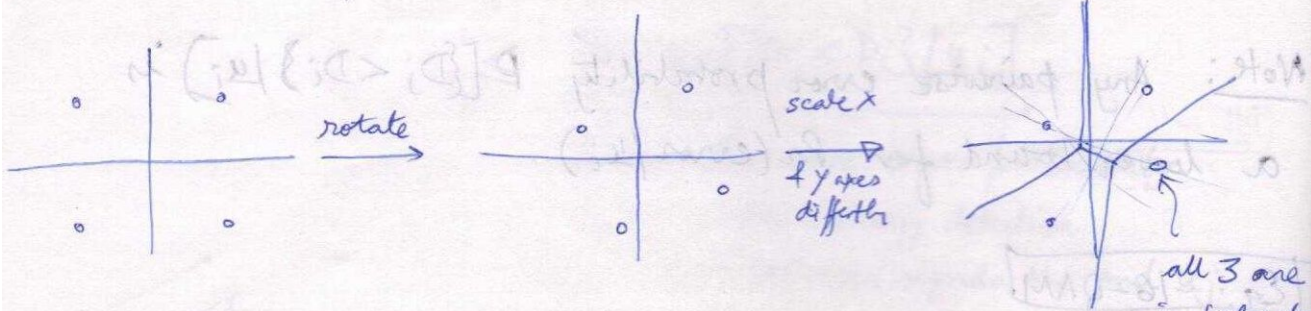
$$\Pr(\text{error}/u_i) \approx \underbrace{N_{d_{\min}}(i)}_{\substack{\text{No. of nearest} \\ \text{neighbours of } u_i}} Q\left(\frac{d_{\min}}{2\sigma}\right)$$

distance at which nearest neighbours are.

- $Q(x)$ decays rapidly with x for large x .
 \Rightarrow terms with smaller x dominate.

- Can easily use these bounds in higher dimensions as well.

- Another example:



(Use voronoi command in MATLAB)

all 3 are important neighbours that define the decision boundary

- Could use this to bound performance of coding schemes over AWGN channels as well \rightarrow can be very high dimension depending on block length of the code, exact analysis very difficult.

- Will use this bound to analyze and design space-time codes.

Summary thus far:

\rightarrow Gaussian random vectors (real and complex)

\rightarrow Vector Gaussian channel

$$\underline{Y} = \underline{U} + \underline{W}$$

For $\underline{U} \in \{u_1, u_2, \dots, u_M\}$, detection rule that minimizes $\Pr(\text{error})$. In the equally likely input case, minimum distance decoding rule. Calculation of $\Pr(\text{error})$ and upper bounds / lower bounds / approximation.

For a given transmission scheme, we discussed $\Pr(\text{error})$. What about rate? Will talk a bit about capacity of vector Gaussian channel next.

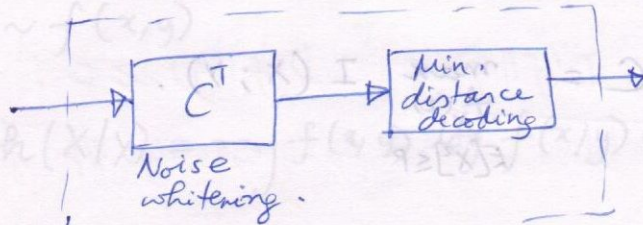
→ Detection rule with correlated noise

$$\underline{y} = \underline{u} + \underline{w}$$

$\underline{w} \sim N(0, K)$

$$\max_i f_Y(y|u_i) \equiv \min_i (y - u_i)^T K^{-1} (y - u_i)$$

$$K^{-1} = CC^T \Rightarrow \min_i \|C^T(y - u_i)\|^2$$



Receiver that minimizes
Pr(error).

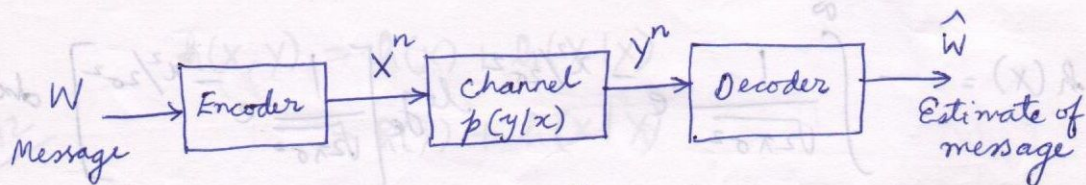
→ Vector Gaussian as a special case of a MIMO channel (diagonal H)

$$\underline{y} = H \underline{u} + \underline{w}$$

15
6/8/12

Some definitions and results from Information Theory:

A communication system model.



Memoryless channel: $p(y^n|x^n) = \prod_{i=1}^n p(y_i|x_i)$

Discrete Memoryless channel (DMC): X, Y take values from discrete alphabets \mathcal{X}, \mathcal{Y} .

→ channel used n times to send message W .

As $n \rightarrow \infty$, what is the highest rate in bits/channel use at which information can be sent with arbitrarily low probability of error?

Shannon's result:

$$C = \max_{p(x)} I(X; Y)$$

where $I(X; Y)$ is the mutual information between X and Y .



$$Z_i \sim N(0, N) \text{ i.i.d.}$$

→ If input is unconstrained, capacity is infinite
(for the above channel with continuous input/output)

→ Usually, there is a transmit power constraint (average).

$$E[X^2] \leq P.$$

In this case, $C = \max_{\substack{f_X(z) \\ E[X^2] \leq P}} I(X; Y).$

Differential entropy:

$$X \sim f_X(x); \quad h(X) = E[-\log f_X(X)] = - \int_{\mathcal{S}} f_X(x) \log f_X(x) dx$$

(Depends only on the pdf)

$$\mathcal{S} = \{x : f_X(x) > 0\}$$

Eg: $X \sim \frac{1}{\sqrt{2\pi\sigma^2}} e^{-x^2/2\sigma^2} \quad [\text{i.e. } N(0, \sigma^2)]$

$$h(X) = - \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-x^2/2\sigma^2} \log \left[\frac{1}{\sqrt{2\pi\sigma^2}} e^{-x^2/2\sigma^2} \right] dx$$

$$= - \log \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-x^2/2\sigma^2} dx$$

$$+ \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-x^2/2\sigma^2} \left[\frac{x^2}{2\sigma^2} \right] dx$$

$$= \log_e \sqrt{2\pi\sigma^2} + \frac{1}{2} = \frac{1}{2} \log_e 2\pi\sigma^2 + \frac{1}{2}$$

$$= \frac{1}{2} \log_e (2\pi e \sigma^2) \text{ nats}$$

$$= \frac{1}{2} \log_2 (2\pi e \sigma^2) \text{ bits}$$

Joint and conditional differential entropy:

$$X_1, X_2, \dots, X_n \sim f(x_1, x_2, \dots, x_n)$$

Joint entropy $[h(\underline{X})]$

$$h(X_1, X_2, \dots, X_n) = -E[\log f(X_1, X_2, \dots, X_n)]$$
$$= -\int f(x_1, x_2, \dots, x_n) \log f(x_1, x_2, \dots, x_n) dx_1 dx_2 \dots dx_n$$

$$X, Y \sim f(x, y)$$

Conditional entropy

$$h(X|Y) = -\int f(x, y) \log f(x|y) dx dy$$

$$= -\int f(y) \underbrace{f(x|y) \log f(x|y)}_{h(X|Y=y)} dx dy$$

Similarly $h(X|Y, Z) = -\int f(x, y, z) \log f(x|y, z) dx dy dz$

Chain rule: $h(X_1, X_2, \dots, X_n) = \sum_{i=1}^n h(X_i | X_{i-1}, \dots, X_1)$

$$h(X, Y) = h(X) + h(Y|X)$$

$$= h(Y) + h(X|Y)$$

Relative entropy:

$D(f||g)$ between 2 densities $f(\cdot)$ and $g(\cdot)$ is

$$D(f||g) = \int f(x) \log \frac{f(x)}{g(x)} dx$$

[Finite only if the support set of f is contained in the support set of g .]

Mutual information between 2 r.v.'s X, Y with joint

pdf $f(x, y)$ is

$$I(X, Y) = D(f(x, y) || f(x)f(y))$$

$$= \int f(x, y) \log \frac{f(x, y)}{f(x)f(y)} dx dy$$

$$= \int f(x) f(y|x) \log \frac{f(x) f(y|x)}{f(x) f(y)} dx dy$$

$$= \int f(x,y) \log f(y|x) dx dy - \int f(x,y) \log f(y) dx dy$$

$$= h(y) - h(y|x)$$

$$= h(x) - h(x|y)$$

Important property of $D(f||g)$: $D(f||g) \geq 0$.

with equality iff $f=g$.

$$\Rightarrow (1) I(x; y) \geq 0$$

$$(2) h(x|y) \leq h(x)$$

Entropy of a Gaussian random vector $X \sim N(\mu, K)$

$$h(X) = \frac{1}{2} \log_2 [(2\pi e)^n |K|] \text{ bits.}$$

Proof: $f_X(x) = \frac{1}{(\sqrt{2\pi})^n |K|^{1/2}} e^{-\frac{1}{2}(x-\mu)^T K^{-1}(x-\mu)}$

$$h(X) = - \int f(x) \ln \left[\frac{1}{(\sqrt{2\pi})^n |K|^{1/2}} e^{-\frac{1}{2}(x-\mu)^T K^{-1}(x-\mu)} \right] dx$$

$$= \ln [(\sqrt{2\pi})^n |K|^{1/2}] + \frac{1}{2} E[(x-\mu)^T K^{-1}(x-\mu)]$$

$$= \frac{1}{2} \ln (2\pi^n |K|) + \frac{1}{2} E[(x-\mu)^T K^{-1}(x-\mu)]$$

$$E[(x-\mu)^T K^{-1}(x-\mu)] = \text{Tr} [E[(x-\mu)^T K^{-1}(x-\mu)]]$$

$$= E[\text{Tr}((x-\mu)^T K^{-1}(x-\mu))] = E[\text{Tr}((x-\mu)(x-\mu)^T K^{-1})]$$

$$= E[\text{Tr}((x-\mu)(x-\mu)^T K^{-1})]$$

$$= \text{Tr}(E[(x-\mu)(x-\mu)^T K^{-1}]) = \text{Tr}(I_n) = n$$

$$h(\underline{x}) = \frac{1}{2} \log_e((2\pi)^n |K|) + \frac{1}{2} n \log_e e \geq (\dots) \leftarrow$$

$$= \frac{1}{2} \log_e((2\pi e)^n |K|) \text{ nats}$$

$$= \frac{1}{2} \log_2((2\pi e)^n |K|) \text{ bits.}$$

Then:

Consider $\underline{x} \in \mathbb{R}^n$ which are zero-mean with covariance matrix $K = E[\underline{x}\underline{x}^T]$. Then,

$$h(\underline{x}) \leq \frac{1}{2} \log_2((2\pi e)^n |K|) \text{ bits.}$$

with equality iff $\underline{x} \sim N(\underline{0}, K)$.

Proof:

Let $g(\underline{x})$ be any density satisfying $E[\underline{x}] = \underline{0}$, $E[\underline{x}\underline{x}^T] = K$.

Let $\phi_K(\underline{x})$ be the pdf of a $N(\underline{0}, K)$ vector.

$$D(g \parallel \phi_K) \geq 0.$$

$$\Rightarrow 0 \leq \int g(\underline{x}) \log \frac{g(\underline{x})}{\phi_K(\underline{x})} d\underline{x}$$

$$= -h(g) - \int g(\underline{x}) \log \phi_K(\underline{x}) d\underline{x}$$

$$\text{Since } \phi_K(\underline{x}) = \frac{1}{(2\pi)^n |K|^{1/2}} e^{-\frac{1}{2} \underline{x}^T K^{-1} \underline{x}}.$$

$$\log \phi_K(\underline{x}) = -\log (2\pi)^n |K|^{1/2} - \frac{1}{2} \underline{x}^T K^{-1} \underline{x}.$$

$$E_g[\log \phi_K(\underline{x})] = -\log (2\pi)^n |K|^{1/2} - \frac{1}{2} E_g[\underline{x}^T K^{-1} \underline{x}]$$

$$= -\log (2\pi)^n |K|^{1/2} - \frac{1}{2} E_g[\text{Tr}(\underline{x}\underline{x}^T K^{-1})]$$

$$= -\log (2\pi)^n |K|^{1/2} - \frac{n}{2}$$

$$= E_{\phi_K}[\log \phi_K(\underline{x})]$$

$$\Rightarrow h(\underline{Y}) \leq \frac{1}{2} \log((2\pi e)^n |K|) \text{ bits}$$

①
8/8/12

Capacity of the vector Gaussian channel:

$$\underline{Y} = \underline{X} + \underline{W}_{n \times 1}$$

$\underline{W} \sim N(0, K)$ and independent of \underline{X}

$$C = \max_{f_X(x)} I(\underline{X}; \underline{Y})$$

$$E[\underline{X}^T \underline{X}] \leq P \rightarrow \text{average power constraint}$$

$$[E[\underline{X}^T \underline{X}] \leq P \text{ is also equivalently } \text{Tr}(E[\underline{X} \underline{X}^T]) \leq P \\ \text{Tr}(K_X) \leq P]$$

$$I(\underline{X}; \underline{Y}) = h(\underline{Y}) - h(\underline{Y}|\underline{X})$$

$$= h(\underline{Y}) - h(\underline{X} + \underline{W}|\underline{X})$$

$$= h(\underline{Y}) - h(\underline{W}|\underline{X})$$

$$= h(\underline{Y}) - h(\underline{W})$$

$$= h(\underline{Y}) - \frac{1}{2} \log((2\pi e)^n |K|)$$

$$\text{Covariance of } \underline{Y}, K_Y = E[\underline{Y} \underline{Y}^H] = K_X + K$$

$$(\text{actually } E[(\underline{Y} - \underline{A}_Y)(\underline{Y} - \underline{A}_Y)^H])$$

For a given K_X

$$I(\underline{X}; \underline{Y}) \leq \frac{1}{2} \log((2\pi e)^n |K_X + K|) - \frac{1}{2} \log((2\pi e)^n |K|)$$

We can further optimize over all K_X subject to $\text{tr}(K_X) \leq P$.

$$C = \max_{K_X} \frac{1}{2} \log \frac{|K_X + K|}{|K|} \\ \text{tr}(K_X) \leq P$$

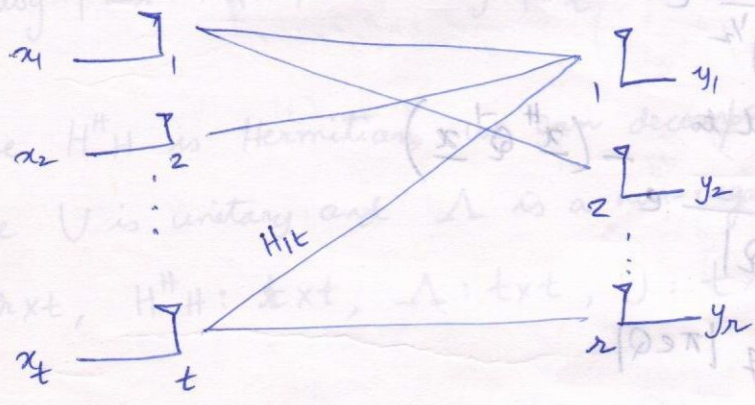
This can be solved. We will do it for the MIMO case

(and the vector Gaussian case will be a special case of this).

Emre Telatar, "Capacity of Multi-antenna Gaussian Channels,"
European Transactions on Telecommunications, 1999.

- Formulas for capacity
- Methods to evaluate these formulas
- Potential gains of multi-antenna systems over single-antenna systems
- Deterministic & fading multi-antenna channels.

Model



$$y = Hx + n \rightarrow \sim CN(0, I_r)$$

$\underbrace{H}_{r \times t \text{ matrix}}$

- * Flat fading model between each tx-rx antenna pair
- * Power constraint: $E[x^H x] \leq P$ i.e. $\text{tr}(E[x x^H]) \leq P$.

Three cases considered:

(1) H is deterministic

- channel known at receiver, statistics known at transmitter.
- (2) H is a random matrix and independent for each use of the channel.
 - (3) H is a random matrix but fixed for all channel uses once chosen.

Section 2: (self-study) discusses complex Gaussian random vectors in detail.

Important results:

$$(1) \quad \underline{X}_{n \times 1} \quad \hat{X}_{2n \times 1} = \begin{bmatrix} \text{Re}(X) \\ \text{Im}(X) \end{bmatrix}$$

Complex Gaussian.

Circularly symmetric \underline{X} with cov. Q

$$\rightarrow \text{Cov } \hat{X} \text{ is } \frac{1}{2} \begin{bmatrix} \text{Re}(Q) & -\text{Im}(Q) \\ \text{Im}(Q) & \text{Re}(Q) \end{bmatrix}$$

$$(2) \quad \underline{X} \sim \text{CN}(\underline{0}, Q) \text{ has pdf } \frac{1}{|\pi Q|^{1/2}} e^{-\frac{1}{2} \underline{\hat{x}}^H \hat{Q}^{-1} \underline{\hat{x}}}$$

which is equal to

$$\frac{1}{|\pi Q|} e^{-\frac{1}{2} \underline{x}^H Q^{-1} \underline{x}}$$

$$h(\underline{x}) = \log |\pi e Q|$$

$$(3) \quad \underline{X} : \text{zero-mean, with } E[\underline{X} \underline{X}^H] = Q.$$

$$h(\underline{X}) \leq \log |\pi e Q|$$

with equality iff $\underline{X} \sim \text{CN}(\underline{0}, Q)$

$$(4) \quad \text{If } \underline{X} \sim \text{CN}(\underline{0}, K_x), \text{ then so is } \underline{Y} = A \underline{X}_{n \times 1} \text{ for any } A \in \mathbb{C}^{m \times n}.$$

$$K_y = A K_x A^H.$$

(5) If \underline{X} & \underline{Y} are independent circularly symmetric complex Gaussians, then $\underline{Z} = \underline{X} + \underline{Y}$ is circularly symmetric complex Gaussian.

Now, let us consider the case

$$\underline{Y} = H \underline{X} + \underline{N} \rightarrow \text{CN}(\underline{0}, I_n)$$

where H is deterministic.

Following the same steps as in the vector Gaussian case,

$$C = \max_{\substack{Q \\ \text{tr}(Q) \leq P}} \log |HQH^H + I_n|$$

$$\triangleq \psi(Q, H)$$

$$C = \max_{\substack{Q \\ \text{tr}(Q) \leq P}} \psi(Q, H)$$

18
10/8/12

→ Since $\det(I+AB) = \det(I+BA)$

$$\log |I_n + HQH^H| = \log |I_t + QH^H H|$$

→ Since $H^H H$ is Hermitian, we can decompose $H^H H = U^H \Lambda U$ where U is unitary and Λ is a non-negative diagonal matrix.

$$(H: n \times t, H^H H: t \times t, \Lambda: t \times t, U: t \times t)$$

$$\psi(Q, H) = \log |I_t + Q U^H \Lambda U| = \log |I_t + \underbrace{Q U^H}_{A} \underbrace{\Lambda^{1/2}}_B \underbrace{\Lambda^{1/2} U}_{C}|$$

$$= \log |I_t + \underbrace{\Lambda^{1/2} U Q U^H}_{B} \underbrace{\Lambda^{1/2}}_A|$$

→ Observe $\tilde{Q} = U Q U^H$ is non-negative definite, i.e., $\tilde{Q} \geq 0$ if and only if $Q \geq 0$. Also, $\text{tr}(\tilde{Q}) = \text{tr}(Q)$.

$$(\because \text{tr}(U Q U^H) = \text{tr}(Q U^H U) = \text{tr}(Q))$$

$$\Rightarrow \max_{\substack{Q \geq 0 \\ \text{tr}(Q) \leq P}} \psi(Q, H) = \max_{\substack{\tilde{Q} \geq 0 \\ \text{tr}(\tilde{Q}) \leq P}} \psi(\tilde{Q}, H)$$

$$= \log |I_t + \Lambda^{1/2} \tilde{Q} \Lambda^{1/2}|$$

Maximization of $\psi(Q, H)$ can be done over \tilde{Q} .

→ For any $A \geq 0$, $\det(A) \leq \prod A_{ii}$, with equality when A is diagonal.

$$\tilde{Q} \geq 0 \Rightarrow \Lambda^{1/2} \tilde{Q} \Lambda^{1/2} + I_t \geq 0$$

$$\Rightarrow \det(I_t + \Lambda^{1/2} \tilde{Q} \Lambda^{1/2}) \leq \prod_i (i^{\text{th}} \text{ diagonal entry of } I_t + \Lambda^{1/2} \tilde{Q} \Lambda^{1/2})$$

$$\Lambda = \begin{bmatrix} \lambda_1 & & & 0 \\ & \lambda_2 & & \\ & & \ddots & \\ 0 & & & \lambda_t \end{bmatrix}$$

$$\Rightarrow |I_t + \Lambda^{1/2} \tilde{Q} \Lambda^{1/2}| \leq \prod_i (1 + \tilde{Q}_{ii} \lambda_i)$$

(1) with equality when \tilde{Q} is diagonal.

→ \tilde{Q} is diagonal. What should be the diagonal values?

Solve

$$\begin{aligned} \max & \prod_i (1 + \tilde{Q}_{ii} \lambda_i) \\ \tilde{Q}_{ii} & \geq 0 \\ \sum_i \tilde{Q}_{ii} & \leq P \end{aligned}$$

Solution: $\tilde{Q}_{ii} = \left(\mu - \frac{1}{\lambda_i}\right)^+$ for $i=1, 2, \dots, t$.

where $\sum_i \tilde{Q}_{ii} = P$

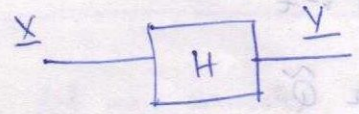
(Waterfilling solution)

→ $C = \log \left(\prod_i (1 + \tilde{Q}_{ii} \lambda_i) \right)$

$$= \sum_i \log (1 + \tilde{Q}_{ii} \lambda_i)$$

$$= \sum_{(\mu \lambda_i - 1 \geq 0)} \log (\mu \lambda_i)$$

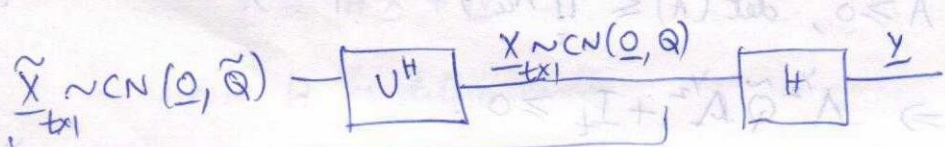
$$\tilde{Q}_{ii} \lambda_i = (\mu \lambda_i - 1)^+$$



$$X \sim \mathcal{CN}(0, Q)$$

$$\tilde{Q} = U Q U^H$$

$$\Rightarrow Q = U^H \tilde{Q} U$$



Optimal input

$$\underline{y} = H \underline{x} + \underline{N}$$

$$= H U^H \tilde{\underline{x}} + \underline{N}$$

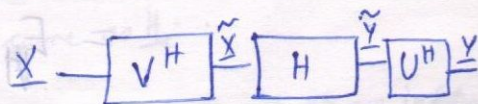
Alternative approach:

$$H_{r \times t} \text{ can be written as } H = U D V^H$$

where $U_{r \times r}$, $V_{t \times t}$ are unitary, $D \geq 0$ diagonal.

- Entries of D are the non-negative square roots of the eigenvalues of $H H^H$,
- Columns of V are the eigenvectors of $H H^H$
- Columns of U are the eigenvectors of $H^H H$.

$$\underline{y} = H \underline{x} + \underline{N}$$



$$\Rightarrow \underline{y} = U D V^H \underline{x} + \underline{N} \sim \text{CN}(\underline{0}, \underline{I})$$

$$\Rightarrow U^H \underline{y} = D V^H \underline{x} + \tilde{\underline{N}}$$

$$\tilde{\underline{N}} \sim \text{CN}(\underline{0}, \underline{I})$$

U, V are invertible and $\tilde{\underline{N}}$ has the same distribution as \underline{N}

$$\Rightarrow \underline{y} = H \underline{x} + \underline{N}$$

equivalent to

$$\tilde{\underline{y}} = D \tilde{\underline{x}} + \tilde{\underline{N}} \text{ where } \tilde{\underline{y}} = U^H \underline{y}, \tilde{\underline{x}} = V^H \underline{x}$$

Since H is a $r \times t$ matrix, its rank is at most $\min\{r, t\}$.

Only $\min\{r, t\}$ of the diag. entries of D are non-zero.

For these channels,

$$\tilde{y}_i = \lambda_i \tilde{x}_i + n_i \quad i = 1, 2, \dots, \min(r, t)$$

[The noise in channels where λ_i is zero does not have any effect.]

Only the channels with $\lambda_i > 0$ need to be considered.

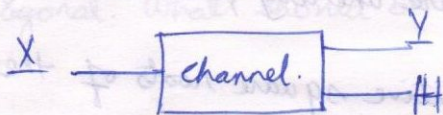
$$\tilde{\underline{x}} \sim \text{CN}(\underline{0}, \tilde{\underline{Q}}) \text{ where } \tilde{\underline{Q}} \text{ is determined by waterfilling}$$

Multi-antenna Gaussian channel with Rayleigh Fading: \underline{Y}

$$\underline{Y} = \underline{H} \underline{X} + \underline{N}$$

each entry is independent and
 $\underline{H} \sim \text{CN}(\underline{0}, \underline{1})$

Assume \underline{H} is known at the receiver.



$$\begin{aligned} I(\underline{X}; \underline{Y}, \underline{H}) &= I(\underline{X}; \underline{H}) + I(\underline{X}; \underline{Y} | \underline{H}) \\ &= 0 + I(\underline{X}; \underline{Y} | \underline{H}) \end{aligned}$$

$$= E_{\underline{H}} [I(\underline{X}; \underline{Y} | \underline{H} = \underline{H})]$$

(L9)

12/8/12

Now

$$C = \max_{f_{\underline{X}}(\underline{x})} E_{\underline{H}} [I(\underline{X}; \underline{Y} | \underline{H} = \underline{H})] \quad \text{tr}(K_{\underline{X}}) \leq P$$

$$\leq \max_{\substack{\underline{Q} \sim \text{CN}(\underline{0}, \underline{Q}) \\ \text{tr}(\underline{Q}) \leq P \\ \underline{Q} \succeq 0}} E_{\underline{H}} [\log \det (\underline{I}_2 + \underline{H} \underline{Q} \underline{H}^{\text{H}})]$$

(Since $I(\underline{X}; \underline{Y} | \underline{H} = \underline{H}) \leq \log \det (\underline{I}_2 + \underline{H} \underline{Q} \underline{H}^{\text{H}})$ for any

\underline{X} with $K_{\underline{X}} = \underline{Q}$), $E_{\underline{H}} [I(\underline{X}; \underline{Y} | \underline{H} = \underline{H})] \leq E_{\underline{H}} [\log \det (\underline{I}_2 + \underline{H} \underline{Q} \underline{H}^{\text{H}})]$

$$C = \max_{\substack{\text{tr}(\underline{Q}) \leq P \\ \underline{Q} \succeq 0}} E_{\underline{H}} [\log \det (\underline{I}_2 + \underline{H} \underline{Q} \underline{H}^{\text{H}})] \triangleq \psi(\underline{Q})$$

$\rightarrow \underline{Q} \succeq 0 \Rightarrow \underline{Q} = \underline{U} \underline{D} \underline{U}^{\text{H}}$ where \underline{U} is unitary, $\underline{D} \succeq 0$ is diagonal.

$$\psi(\underline{Q}) = E_{\underline{H}} [\log \det (\underline{I}_2 + \underline{H} \underline{U} \underline{D} \underline{U}^{\text{H}} \underline{H}^{\text{H}})]$$

$$= E_{\mathbb{H}} \left[\log \det (I_n + (\mathbb{H}U)D(\mathbb{H}U)^H) \right]$$

(Lemma 5: $\mathbb{H}_{n \times t}$ i.i.d. entries each $CN(0, 1)$.)

Then for any unitary $U_{n \times n}$, $V_{t \times t}$,

$U\mathbb{H}V^H$ has the same distribution as \mathbb{H} .

Pf:

Suffices to show $G_{\mathbb{H}} = U\mathbb{H}$ has the same distribution as \mathbb{H} .
(Then, apply the result to $G_{\mathbb{H}}^H$.)

$$G_{\mathbb{H}} = \begin{bmatrix} G_1 & G_2 & \dots & G_t \end{bmatrix} = U \begin{bmatrix} H_1 & H_2 & \dots & H_t \end{bmatrix}$$

$$\Rightarrow G_i = UH_i \sim CN(0, I) \text{ same as } H_i.$$

Also, columns of $G_{\mathbb{H}}$ are independent since columns of \mathbb{H} are independent. (1)

→ Since the distribution of $\mathbb{H}U$ is the same as \mathbb{H} ,

$$\psi(Q) = \psi(D) = E_{\mathbb{H}} \left[\log \det (I_n + \mathbb{H}D\mathbb{H}^H) \right]$$

Therefore, we can restrict to diagonal $Q \geq 0$.

→ Let Π be any permutation matrix.

$$\text{Define } Q^{\Pi} = \Pi Q \Pi^H.$$

Q^{Π} has diagonal entries that are a permutation of diagonal entries of Q .

$$\psi(Q^{\Pi}) = E_{\mathbb{H}} \left[\log \det (I_n + \mathbb{H}\Pi Q \Pi^H \mathbb{H}^H) \right]$$

Since $\mathbb{H}\Pi$ has the same distribution as \mathbb{H} ,

$$\psi(Q^{\Pi}) = \psi(Q).$$

→ (1) For any \mathbb{H} , $Q \rightarrow I_n + \mathbb{H}Q\mathbb{H}^H$ is linear and preserves positive definiteness.

(2) Since $\log \det$ is concave on the set of positive definite matrices,

$$Q \rightarrow \psi(Q, H) = \log \det (I_n + HQH^T) \text{ is concave.}$$

(1) & (2) $\Rightarrow Q \rightarrow \psi(Q)$ is concave.

$$\rightarrow \tilde{Q} = \frac{1}{t} \sum_{\pi} Q^{\pi} \text{ satisfies } \psi(\tilde{Q}) \geq \psi(Q)$$

$$\text{and } \text{tr}(\tilde{Q}) = \text{tr}(Q).$$

$$\Rightarrow \tilde{Q} = \alpha I \text{ is the optimal } Q.$$

$$\text{and } \alpha = \frac{P}{t}.$$

$$C = E_H \left[\log \det \left(I_n + \frac{P}{t} HH^T \right) \right].$$

Remarks:

$$(1) H = \begin{bmatrix} H_{11} & H_{12} & \dots & H_{1t} \\ \vdots & \vdots & \ddots & \vdots \\ H_{21} & H_{22} & \dots & H_{2t} \end{bmatrix}$$

$$HH^T = \begin{bmatrix} \sum_{i=1}^t |H_{1i}|^2 & & \\ & \sum_{i=1}^t |H_{2i}|^2 & \\ & & \ddots \\ & & & \sum_{i=1}^t |H_{ti}|^2 \end{bmatrix}$$

((i,j) element)

$$\sum_{k=1}^t H_{ik} H_{jk}^*$$

For a fixed r , as $t \rightarrow \infty$

$$\frac{1}{t} H H^H \rightarrow I_r \text{ almost surely (by law of large numbers)}$$

$$\Rightarrow C \rightarrow r \log(1+P)$$

14/8/12

(2) For $r=1$, $H = [H_{11} \ H_{12} \ \dots \ H_{1t}]$

$$H H^H = \sum_{i=1}^t |H_{1i}|^2$$

For $t=1$, $H = \begin{bmatrix} H_{11} \\ H_{21} \\ \vdots \\ H_{r1} \end{bmatrix}$

$$[I_r + \frac{P}{t} H H^H] = [1 + \frac{P}{t} H^H H]$$

$$H^H H = \sum_{i=1}^r |H_{i1}|^2$$

$$C = E \left[\log \left(1 + \frac{P}{t} \sum_{i=1}^t |H_{1i}|^2 \right) \right] \text{ (or) } E \left[\log \left(1 + \frac{P}{t} \sum_{i=1}^r |H_{i1}|^2 \right) \right]$$

(3) Evaluation of the capacity

$$\det \left(I_r + \frac{P}{t} H H^H \right) = \det \left(I_t + \frac{P}{t} H^H H \right)$$

(Use this when $r < t$)

(Use this when $r \geq t$)

$$\text{Let } W = \begin{cases} H H^H & r < t \\ H^H H & r \geq t \end{cases}$$

Let $n = \max(r, t)$

$m = \min(r, t)$

W : $m \times m$ random non-negative definite matrix

follows the Wishart distribution with parameters m, n

$\lambda_1, \lambda_2, \dots, \lambda_m$: Eigenvalues of W (random variables)

$$C = E_{\lambda} \left[\sum_{i=1}^m \log \left(1 + \frac{P}{t} \lambda_i \right) \right]$$

Joint density of the unordered eigenvalues:

$$f_{\lambda}(\lambda_1, \lambda_2, \dots, \lambda_m) = \frac{1}{m! K_{m,n}} e^{-\sum_i \lambda_i} \prod_i \lambda_i^{n-m} \prod_{i < j} (\lambda_i - \lambda_j)^2$$

Joint density of ordered eigenvalues:

$$f_{\lambda, \text{ordered}}(\lambda_1, \dots, \lambda_m) = \frac{1}{K_{m,n}} e^{-\sum_i \lambda_i} \prod_i \lambda_i^{n-m} \prod_{i < j} (\lambda_i - \lambda_j)^2$$

for $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_m \geq 0$

($K_{m,n}$ is a normalizing factor)

Density of one of the unordered eigenvalues:

$$f_{\lambda_1}(\lambda_1) = \frac{1}{m} \sum_{i=1}^m \varphi_i(\lambda_1)^2 \lambda_1^{n-m} e^{-\lambda_1} \quad \text{--- (1)}$$

where $\varphi_{k+1}(\lambda) = \left[\frac{k!}{(k+n-m)!} \right]^{1/2} L_k^{n-m}(\lambda)$ $k=0, \dots, m-1$

where $L_k^{n-m}(x) = \frac{1}{k!} e^x x^{m-n} \frac{d^k}{dx^k} (e^{-x} x^{n-m+k})$ is the Laguerre

polynomial of order k .

$$C = E \left[\sum_{i=1}^m \log \left(1 + \frac{p}{t} \lambda_i \right) \right] = m E \left[\log \left(1 + \frac{p}{t} \lambda \right) \right]$$

where λ is distributed as in (1).

$$\Rightarrow C = \int_0^{\infty} \log \left(1 + \frac{p}{t} \lambda \right) \sum_{k=0}^{m-1} \frac{k!}{(k+n-m)!} \left[L_k^{n-m}(\lambda) \right]^2 \lambda^{n-m} e^{-\lambda} d\lambda$$

where $m = \min\{\lambda, t\}$, $n = \max\{\lambda, t\}$

L_j^i are the associated Laguerre polynomials.

Special cases

(a) $\boxed{r=1}$

Note $L_0^{n-m}(\lambda) = 1$.

$$\Rightarrow C = \frac{1}{\Gamma(r)} \int_0^\infty \log(1+P\lambda) \lambda^{r-1} e^{-\lambda} d\lambda \quad (\text{See Figure 2})$$

As $r \rightarrow \infty$, $C \rightarrow \log(1+Pr)$.

(b) $\boxed{r=1}$

$$C = \frac{1}{\Gamma(t)} \int_0^\infty \log\left(1 + \frac{P}{t}\lambda\right) \lambda^{t-1} e^{-\lambda} d\lambda \quad (\text{See Figure 3})$$

As $t \rightarrow \infty$, $C \rightarrow \log(1+P)$.

(c) $\boxed{r=t}$

$$C = \int_0^\infty \log\left(1 + \frac{P\lambda}{r}\right) \sum_{k=0}^{r-1} L_k(\lambda)^2 e^{-\lambda} d\lambda$$

where $L_k = L_k^0$ is the Laguerre polynomial of order k .

Using results from the theory of random matrices, we get

$$C \sim r \int_0^4 \log(1+Pv) \frac{1}{\pi} \sqrt{\frac{1}{v} - \frac{1}{4}} dv$$

which is linear in r . (See Fig. 4).

(4)

$C(r, t, P)$: Capacity of channel with r receivers
 t transmitters
 P total transmit power.

$$\boxed{C(a, b, Pb) = C(b, a, Pa)}$$

e.g. $C(1, t, Pt) = C(t, 1, P)$

$t \times 1$ with power Pt (\equiv) $1 \times t$ with power P .

(5)

Above, capacity is also ergodic capacity : when H is ergodic (not only when H is i.i.d.) memoryless

where $\gamma(a, x)$ is the incomplete gamma function

$$= \int_0^x u^{a-1} e^{-u} du$$

let $\psi(P, \epsilon)$ be the rate R at which $P(\psi(P, H) \leq R) = \epsilon$.

i.e. $\psi(P, \epsilon)$ is the ϵ -outage capacity.

→ HU has the same distribution as H for unitary U .

$$\Rightarrow \psi(UQU^H, H) = \psi(Q, H)$$

⇒ Q can be chosen to be diagonal without affecting the outage prob.

$$P_{out}(R, P) = \inf_{\substack{Q: Q \geq 0 \\ Q \text{ diag} \\ \sum_i Q_{ii} \leq P}} P_{\mathcal{R}}(\psi(Q, H) < R)$$

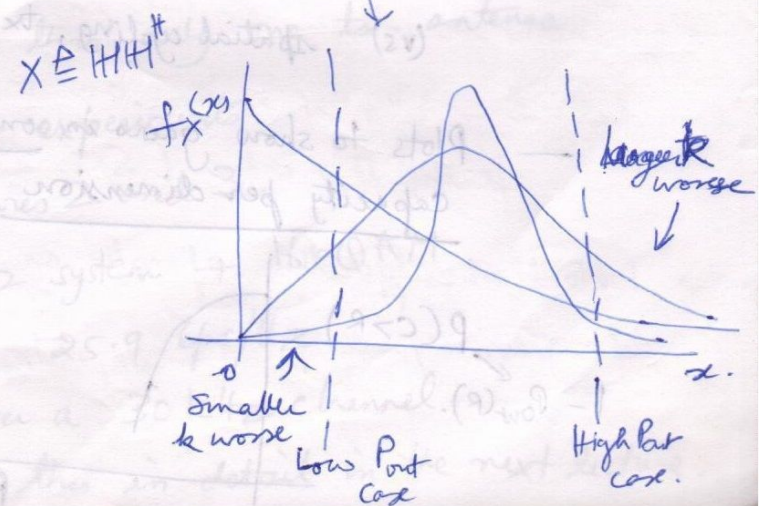
→ Only a conjecture for optimal Q .

$$Q = \frac{P}{k} \text{diag} \{ \underbrace{1, \dots, 1}_k, \underbrace{0, \dots, 0}_{t-k} \}$$

for some $1 \leq k \leq t$ integer

→ Example: $\gamma_2 = 1$ case.

See Fig. 6 & 7.



So far: Telatar (1999)

→ deterministic H
- SVD + waterfilling

→ Random H (fast fading)

- Ergodic capacity
- $C \propto \min(r, t)$

→ Random H (slow fading) - non-ergodic

- Outage probability
- Outage capacity
- Some evaluation/plots for $r=1$ case.

Today: Summary of some other parallel work
(also from Bell labs)

Foschini and Gans (1998)

"On limits of Wireless Communications in a Fading Environment
when Using Multiple Antennas"

- Focus on outage capacity: How does it increase
with no. of antennas? Linear (analysis based on
a lower bound, numerical evaluation).

- Combined transmit-receive diversity
(vs) spatial cycling, tx diversity, rx diversity

- Plots to show gains in outage capacity and
capacity per dimension

