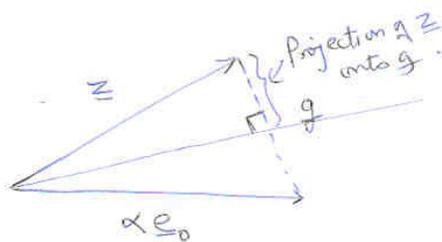


Problem Set 8

① $z = [z(0) \ z(1) \ \dots \ z(n-1)] \quad e_0 = [1 \ 0 \ \dots \ 0]$



$$z \theta = \alpha e_0$$

$$\Rightarrow |\alpha| = \|z\| \quad (\theta \text{ unitary})$$

$\dagger \alpha z^*(0)$ is real (since $z \theta z^H$ is real)

$$\text{If } z(0) = |a| e^{j\phi_a}, \quad \alpha = \pm e^{j\phi_a} \|z\|$$

Let $g = z - \alpha e_0$

g is also equal to 2 (projection of z onto g)

$$\Rightarrow g = 2 \left(\frac{z g^H g}{g g^H g} \right)$$

$$\Rightarrow z - \alpha e_0 = 2 z \frac{g^H g}{g g^H}$$

$$\Rightarrow \alpha e_0 = z \left(I - 2 \frac{g^H g}{g g^H} \right)$$

Required θ

where $g = z \pm \|z\| e^{j\phi_a} e_0$

② $A = \begin{bmatrix} 1 & 0.75 & 0.75 \\ 0.4 & 0.2 & 0.2 \end{bmatrix}$

$$x_1 = [1 \ 0.75 \ 0.75] \quad \theta_1 = I_3 - \frac{2 g_1^T g_1}{g_1 g_1^T}$$

where $g_1 = x_1 \pm \|x_1\| [1 \ 0 \ 0]$

Let $g_1 = [0.75 \ 0.75] + \|x_1\| [1 \ 0 \ 0] = [2.2748 \ 0.1500 \ 1.0000]$

$$x_1 \theta_1 = [-1.2748 \ 0 \ 0]$$

$$x_2 \theta_1 = [-0.4707 \ -0.0871 \ 0.1043]$$

$$\begin{bmatrix} 1 & 0.75 & 0.75 \\ 0.4 & 0.2 & 0.2 \end{bmatrix} \theta_1 = \begin{bmatrix} -1.2748 & 0 & 0 \\ -0.4707 & -0.0871 & 0.1043 \end{bmatrix}$$

If we choose $g_1 = x_1 - \|x_1\| [0 \ 0 \ 0]$, we get

$$\begin{bmatrix} 1 & 0.75 & 0.75 \\ 0.4 & 0.2 & 0.2 \end{bmatrix} \theta_1 = \begin{bmatrix} 1.2748 & 0 & 0 \\ 0.4707 & 0.0871 & -0.1043 \end{bmatrix}$$

To set this 0, we choose θ_2 such that

$$[0.0875 \quad -0.1043] \theta_2 = [\alpha \ 0]$$

$$\alpha = \|[0.0875 \quad -0.1043]\| = 0.1359$$

$$A \theta_1 \cdot \begin{bmatrix} 1 & 0 \\ 0 & \theta_2 \end{bmatrix} = \begin{bmatrix} 1.2748 & 0 & 0 \\ 0.4707 & 0.1359 & 0 \end{bmatrix}$$

③ $H^H H = \begin{bmatrix} 1 & 0 & 1 \\ 1 & \epsilon & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & \epsilon \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 2 \\ 2 & 2+\epsilon^2 \end{bmatrix}$ which in finite precision is

$$\begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix}$$

rank = 2.

rank = 1

④ $\begin{bmatrix} \lambda^{1/2} \phi_{i-1}^{1/2} & b_i \\ \lambda^{1/2} q_{i-1}^H & \bar{X}_i^* \end{bmatrix} \theta = \begin{bmatrix} \phi_i^{1/2} & 0 \\ q_i^H & e_a^+(i) \gamma^{1/2}(i) \end{bmatrix}$

+ve entries.

$$\begin{bmatrix} x & 0 & 0 & x \\ x & x & 0 & x \\ x & x & x & x \\ x & x & x & x \end{bmatrix} \theta = \begin{bmatrix} x & 0 & 0 & 0 \\ x & x & 0 & 0 \\ x & x & x & 0 \\ x & x & x & x \end{bmatrix}$$

For $[a \ b]$ Given's rotation matrix $\frac{1}{\sqrt{1+|e|^2}} \begin{bmatrix} 1 & -P \\ P^* & 1 \end{bmatrix}$ where $P = \frac{b}{a}$, $a \neq 0$.

→ +ve diagonal entries.

$$\Theta = \Theta_1 \Theta_2 \Theta_3$$

$$= \begin{bmatrix} 1 & 0 & 0 & -p_1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ p_1^* & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -p_2 \\ 0 & 0 & 1 & 0 \\ 0 & p_2^* & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -p_3 \\ 0 & 0 & p_3^* & 1 \end{bmatrix} \frac{1}{\sqrt{1+p_1^2} \sqrt{1+p_2^2} \sqrt{1+p_3^2}}$$

$$= \begin{bmatrix} 1 & 0 & 0 & -p_1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ p_1^* & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ -p_2 \\ -p_3 \\ 1 \end{bmatrix} \frac{1}{\sqrt{1+p_1^2} \sqrt{1+p_2^2} \sqrt{1+p_3^2}}$$

$$= \begin{bmatrix} \\ \\ \\ \end{bmatrix} \times$$

$$\rightarrow = [p_1^* \ 0 \ 0 \ 1] \begin{bmatrix} 0 \\ -p_2 \\ -p_3 \\ 1 \end{bmatrix} = 1 > 0.$$

(...)

$$\begin{bmatrix} p_1 & p_2 & p_3 \\ p_1^* & p_2^* & p_3^* \end{bmatrix} = \begin{bmatrix} p_1 & p_2 & p_3 \\ p_1^* & p_2^* & p_3^* \end{bmatrix} \Gamma = \dots$$