

ECE 2015

Sinusoidal steady state response of second order systems

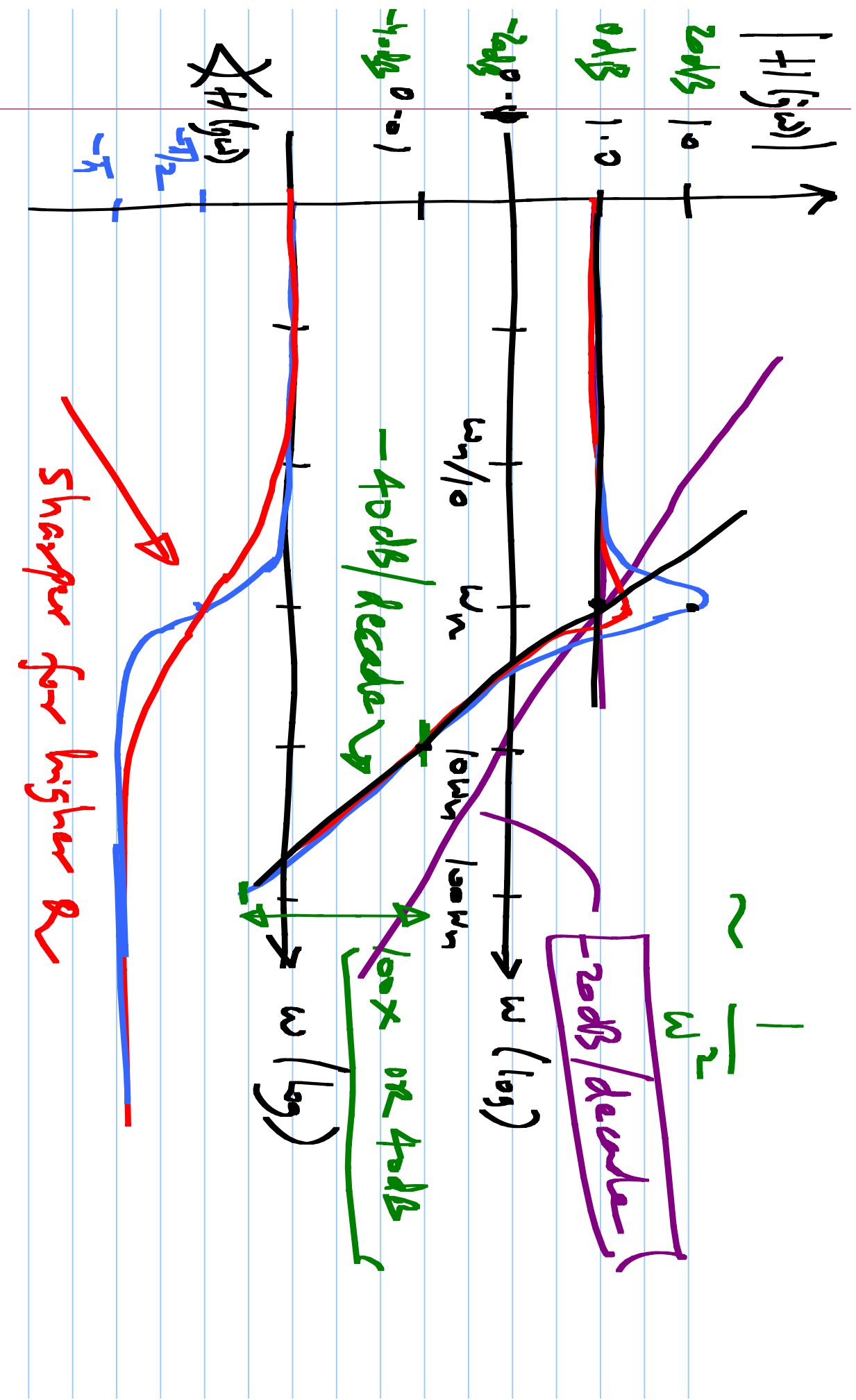
16/10/2017

$$H(j\omega) = \frac{1}{1 - \frac{\omega^2}{\omega_n^2} + j \cdot \frac{\omega}{\omega_n}}$$

$$\omega \ll \omega_n : |H(j\omega)| \approx 1, \quad \angle H(j\omega) = 0$$

$$\omega \gg \omega_n : |H(j\omega)| \approx \frac{\omega_n^2}{\omega^2}, \quad \angle H(j\omega) = -\pi$$

$$\omega = \omega_n : |H(j\omega)| = Q, \quad \angle H(j\omega) = -\pi/2$$



decibel unit

$$20 \log_{10}$$

$$|H(j\omega)|$$

$$20 \log_{10}$$

$$\left| \frac{V_o}{V_s} \right|$$

$$10x \Rightarrow 20 \text{ dB}$$

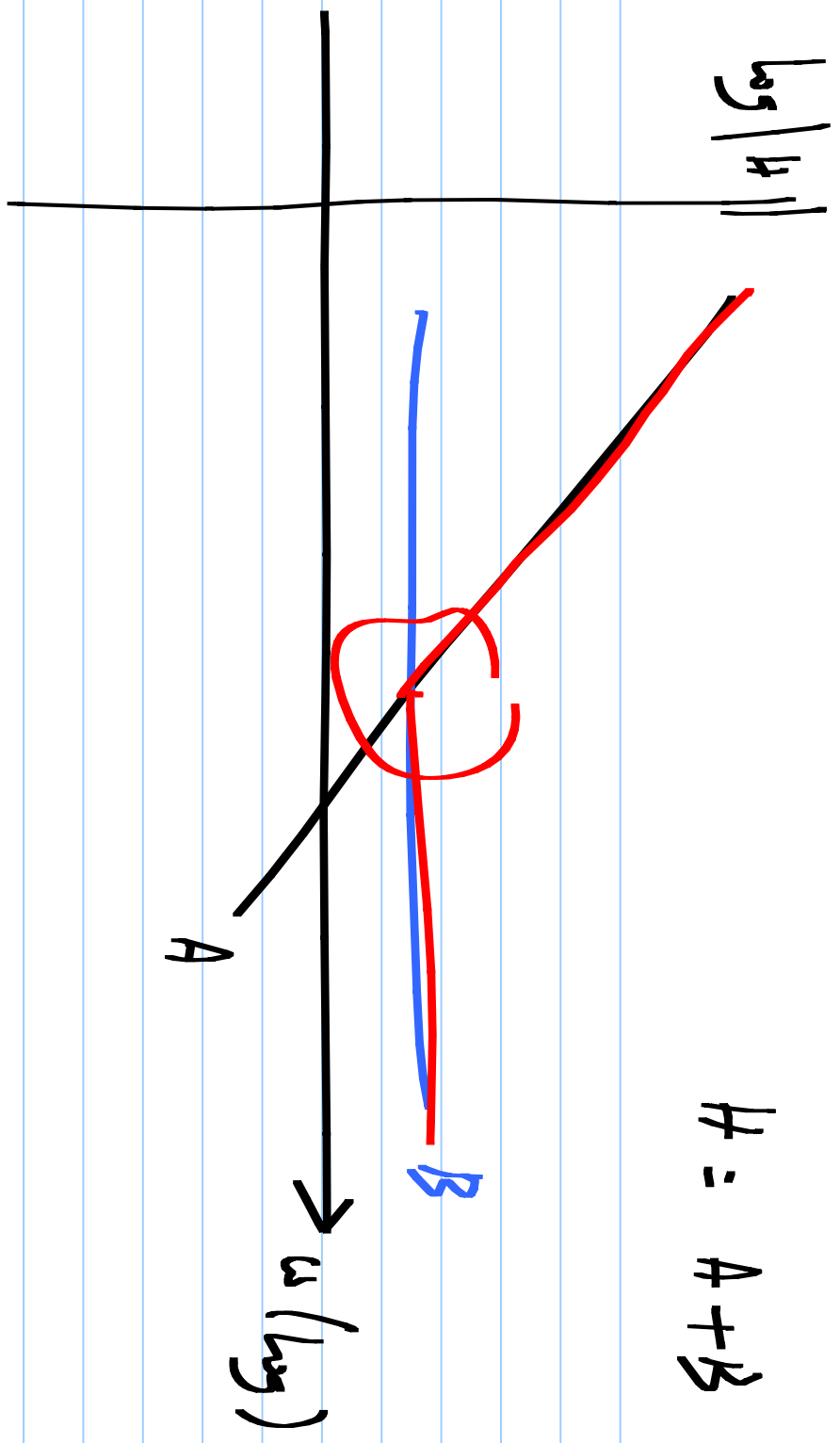
$$V_1 + \sqrt{\frac{P_1}{R}} = \frac{V_1^2}{R}$$

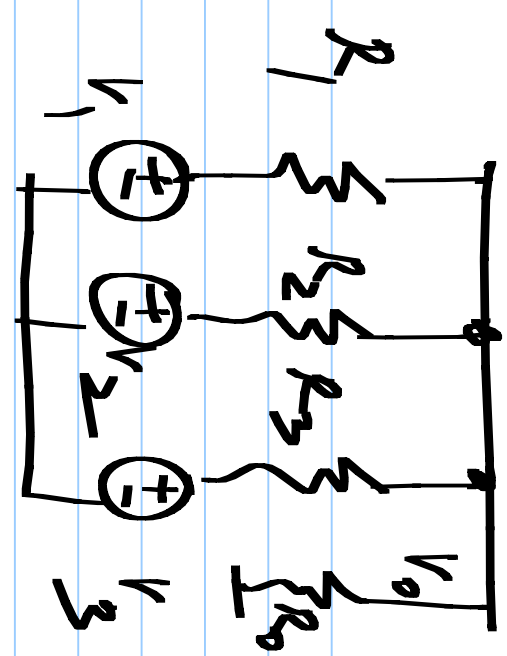
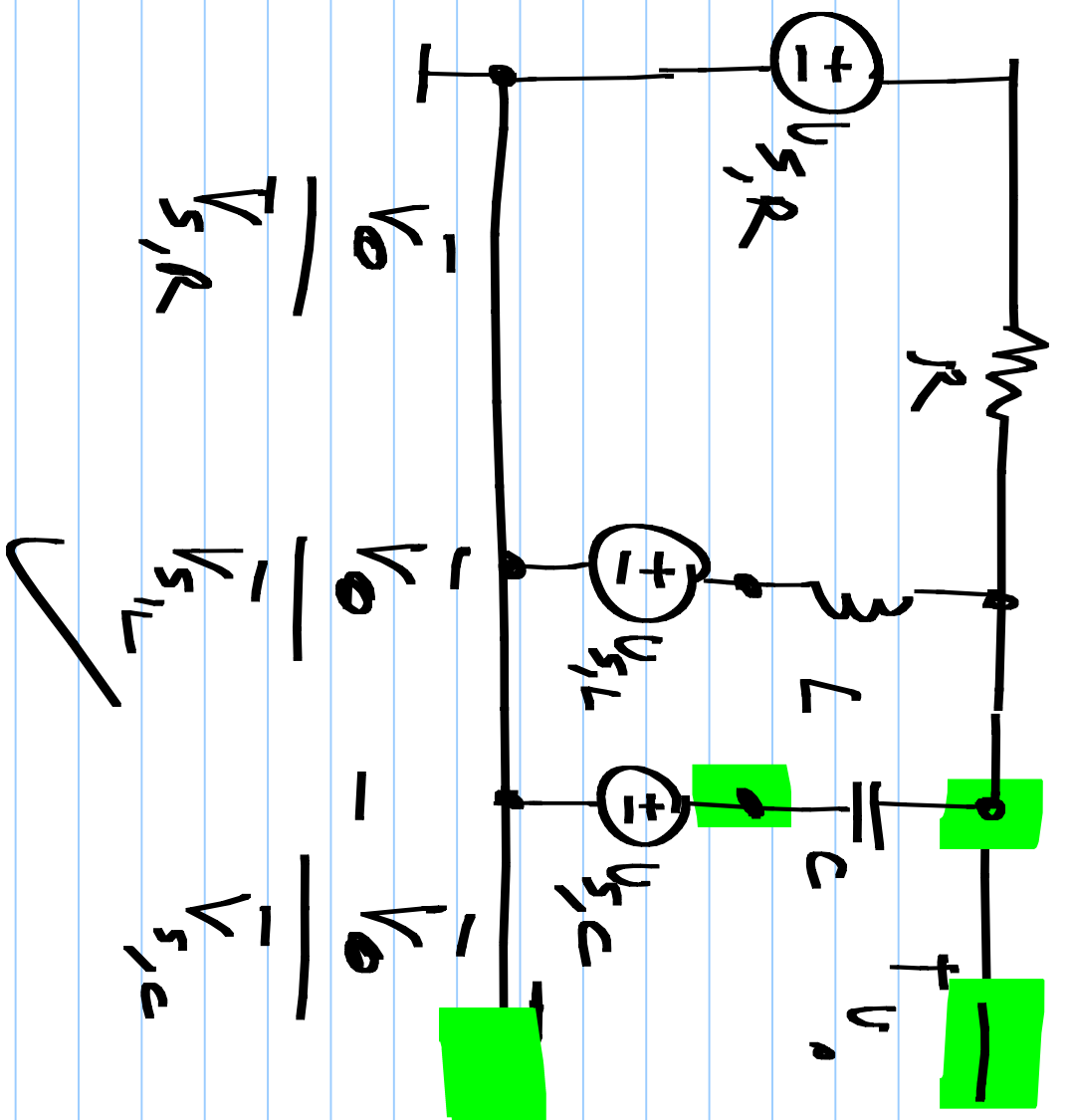
$$V_2 + \sqrt{\frac{P_2}{R}} = \frac{V_2^2}{R}$$

$$10 \log_{10} = \frac{P_1}{P_2}$$

$$= 20 \log_{10} \frac{V_1}{V_2}$$

$$H = A + B$$





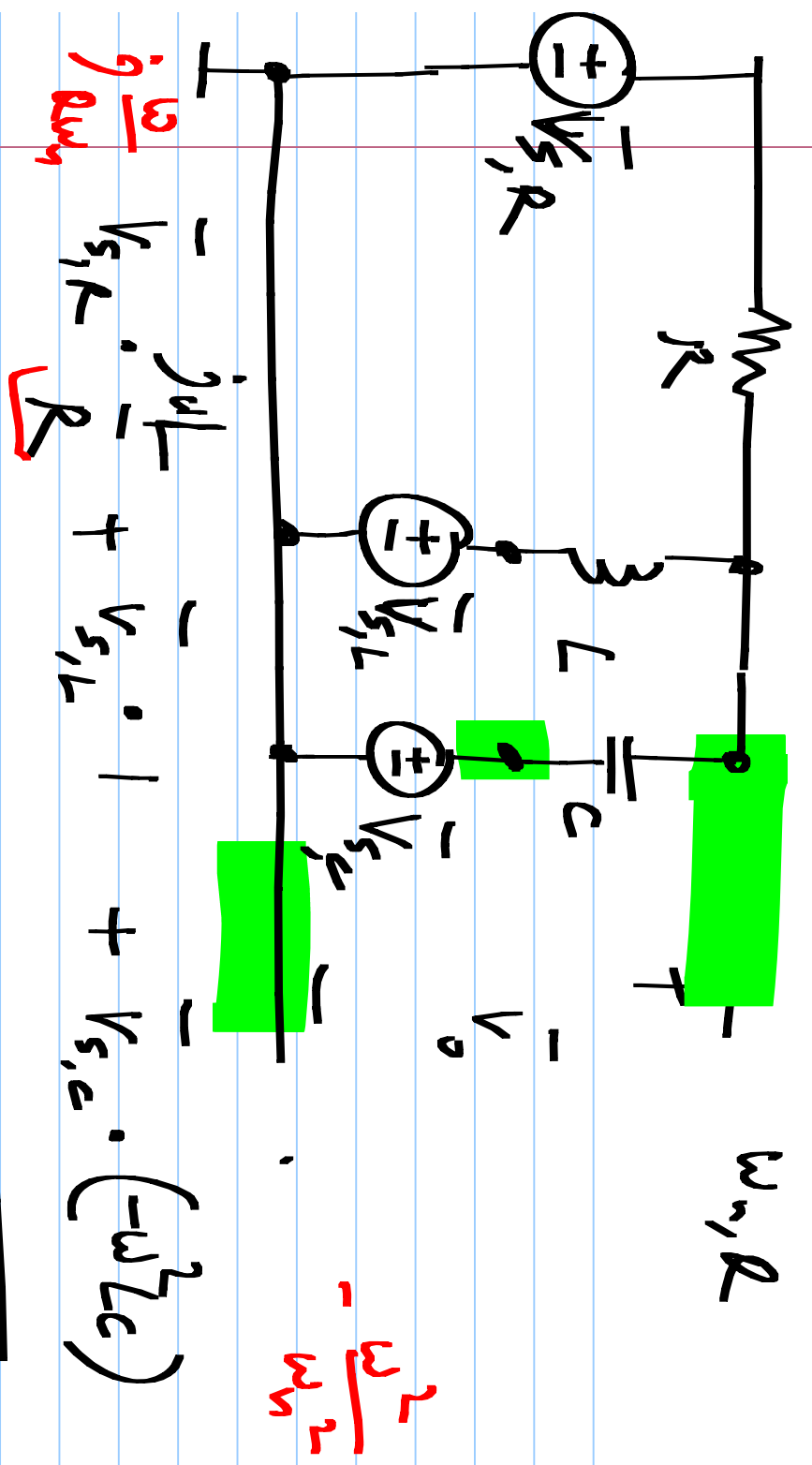
$$U_0 = \frac{U_1 \cdot G_1 + U_2 \cdot G_2 + U_3 \cdot G_3}{G_1 + G_2 + G_3 + G_0}$$

$$\underline{U_0} = \underline{U_{s,R}}$$

$$\underline{U_0} = \underline{U_{s,L}}$$

$$\underline{U_0} = \underline{U_{s,C}}$$





$$\left(\frac{j\omega L}{R} + 1 - \omega^2 LC \right) \left[\left(1 - \frac{\omega^2}{\omega_n^2} \right) + j\frac{\omega}{Q\omega_n} \right]$$

$$\frac{1}{1}$$

$$\frac{1}{V_{s,L}} = \frac{1}{1 - \omega^2 L C + j \omega L R}$$

$$j \omega L R$$

$$j \frac{\omega}{R \omega_n}$$

$$\frac{1}{V_o} = \frac{1}{1 - \omega^2 L C + j \omega L R} = \frac{1}{1 - \frac{\omega^2}{\omega_n^2} + j \frac{\omega}{R \omega_n}}$$

$$- \omega^2 L C$$

$$- \omega^2 / \omega_n^2$$

$$\frac{1}{V_{s,C}} = \frac{1}{1 - \omega^2 L C + j \omega L R} = \frac{1}{1 - \frac{\omega^2}{\omega_n^2} + j \frac{\omega}{R \omega_n}}$$