

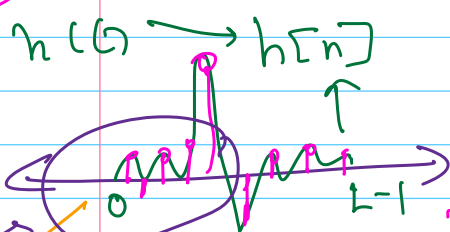
8th Nov 2025

- ① → Linear Equaliser (L-mouse) ↖ FIR
- ② → Decision Feedback Equaliser ↖ non-linear || IIR
- ③ → Fractionally Spaced Equalisation
- ④ → Intro to Block Modulation

①

DFE

← symbol-spaced DFE



$$y[k] = \sum_{i=0}^{L-1} h_i x[k-i] + n[k]$$

$\times \{w_L\}$

$\times \{w_{L1}^{FF}\}$

Pre-cursor ISI

Post-cursor ISI

Δ

$\hat{x}(k)$

$\hat{x}(k-\Delta)$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

DFE → ADC

$y[k]$

$\{w_{L1}^{FF}\}$

$a[k]$

$b[k]$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

$\hat{x}(k)$

Pre-cursor ISI ≈ 0



$\{w_{L2}^{FB}\}$

$L \rightarrow \Delta \approx L/2$

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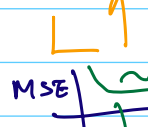
$L \rightarrow \Delta \approx L/2$

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$L_1 \rightarrow FF$
 $L_2 \rightarrow FB$

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$L_1 \rightarrow FF$
 $L_2 \rightarrow FB$

DFE

Wiener-Hopf Filter

$$LE \rightarrow \bar{W}_{LE} = R^{-1} \bar{p}, R = E[\bar{y} \bar{y}^H]$$

$$\bar{y} = \begin{bmatrix} y(k) \\ y(k-1) \\ \vdots \\ y(k-L+1) \end{bmatrix} \uparrow L$$

$$\bar{W}_{LE} = \bar{R}^{-1} \bar{p} \quad \begin{matrix} (L_1+L_2) \times 1 \\ (L_1+L_2) \times (L_1 \times L_2) \end{matrix}$$

$$\begin{matrix} L_1 \\ L_2 \end{matrix} \left\{ \begin{bmatrix} W_1^{FF} \\ \vdots \\ W_{L_1}^{FF} \\ \vdots \\ W_1^{FB} \\ \vdots \\ W_{L_2}^{FB} \end{bmatrix} \right\} \quad (L_1+L_2) \times 1$$

$$\bar{x}(k) = \begin{bmatrix} y(k) \\ y(k-1) \\ \vdots \\ y(k-L_1+1) \\ \hat{I}(k-1) \\ \hat{I}(k-2) \\ \vdots \\ \hat{I}(k-L_2) \end{bmatrix} \quad \begin{matrix} L_1 \\ L_2 \end{matrix}$$

$$R = E[\bar{x}(k) \bar{x}(k)^H]$$

$$\bar{p} = E[\hat{I}^*(k) \bar{x}(k)]$$

$$\hat{I}(k-\Delta-1)$$

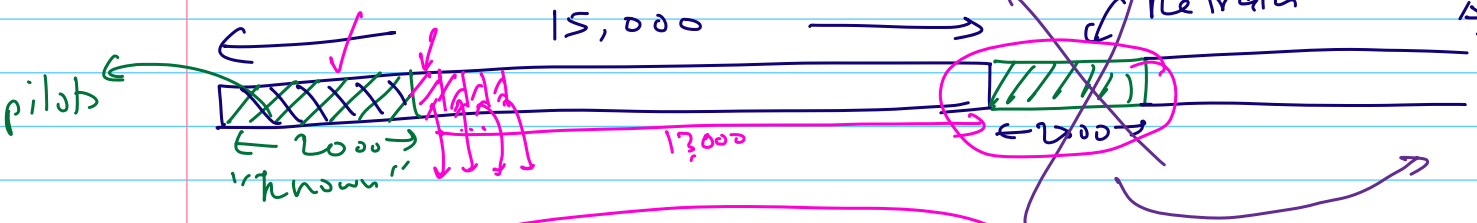
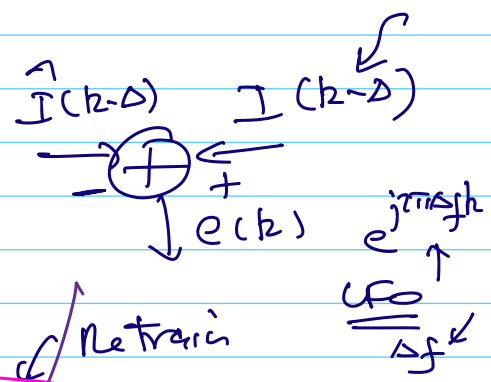
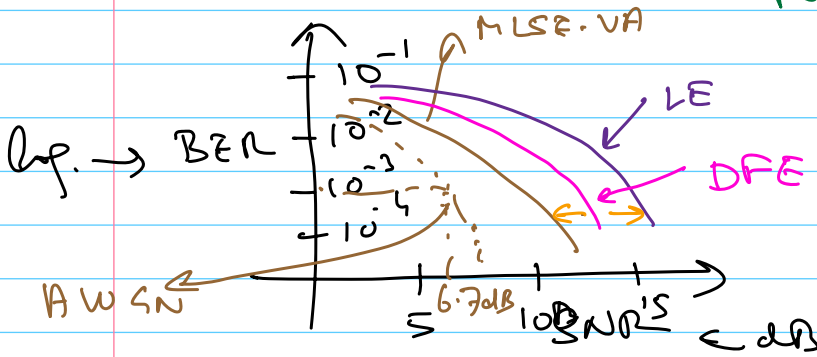
$$\hat{I}(k-\Delta-L_2)$$

$L+L_2$ channel $\rightarrow \{f_k\} \rightarrow VA$

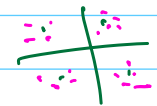
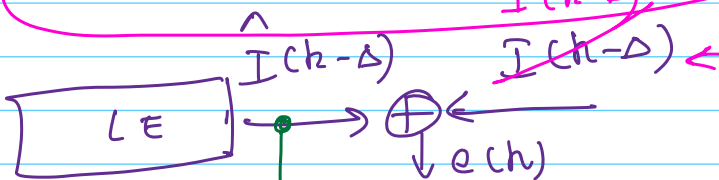
$LE \rightarrow M$ taps

$DFE \rightarrow M$ taps $M = L_1 + L_2$

$$M^3 \uparrow R \propto M^2 \log(M)$$



Decision-Aided Tracking



adaptive theory

$$\bar{P} = E \left[\tilde{I}^*(k-\Delta) \tilde{y}(k) \right]$$

$$\tilde{I}(k-\Delta) = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x_j \\ x_{j-1} \end{bmatrix}$$

"Robust-statistics"

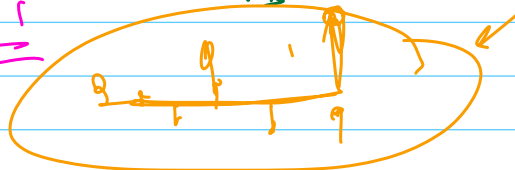
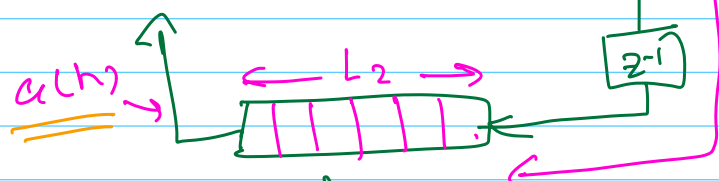
"Downshift"

→ DFE ← ?



$L_2 = ?$

$L_2 \uparrow \rightarrow L_2 T$



order of L

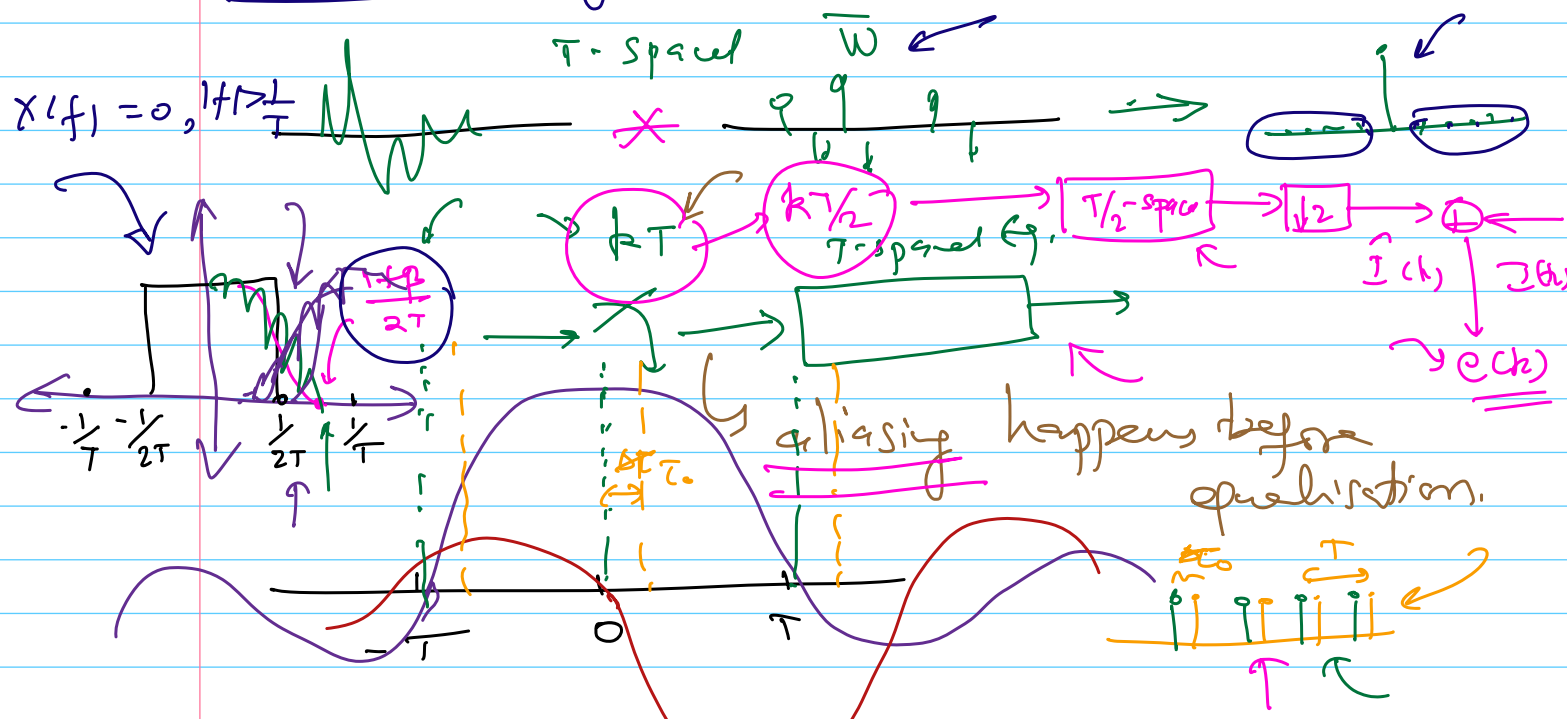
$\{f_l\} \quad l=0 \dots L-1$

Memory of $(L-1)$

DFE $\rightarrow L_2 \approx L-1$
 $M = L_1 + L_2$
 $\hookrightarrow 2L \text{ to } 3L$

$M \approx 3L \text{ to } 4L$

Fractionally Spaced Equalization



$$Y_T(f) = \frac{1}{T} \sum_n x(f - \frac{n}{T}) e^{j2\pi(f - \frac{n}{T})T_0}$$

"f-hat"

$$Y_T(f) = \frac{1}{T} \sum_n x(f - \frac{n}{T}) e^{j2\pi(f - \frac{n}{T})T_0}$$

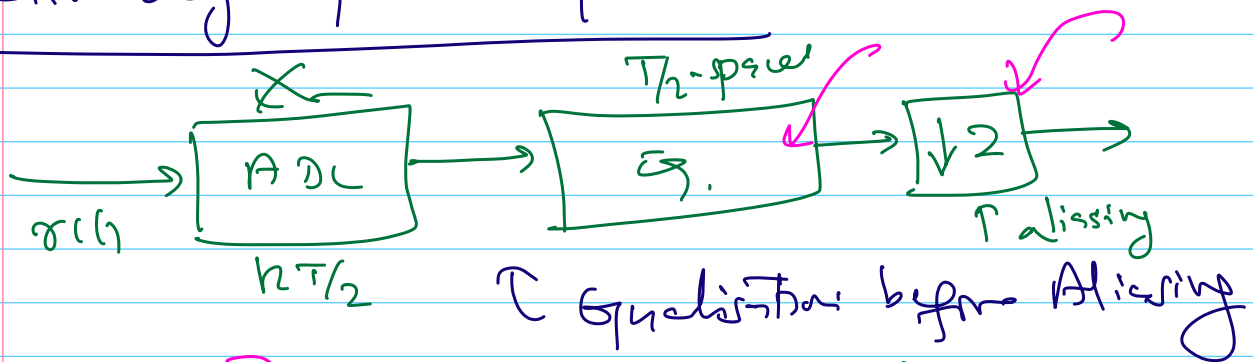
$2\pi f T_0$
↑

$$C_T(f) = \sum c_k e^{-j2\pi f k T}$$

Qualification after aliasing

$$C_T(f) \cdot Y_T(f)$$

Fractionally - spaced Equalizer (FSE) FS-LE
FS-DFE



$$C_{T/2}(f) Y_{T/2}(f) = C_{T/2}(f) \sum_n x(f - \frac{n}{T/2}) e^{j2\pi(f - \frac{n}{T/2})T_0}$$

$$= C_{T/2}(f) \cdot x(f) e^{j2\pi f T_0} \quad |f| < \frac{1}{T}$$

- (1+p)/2T (1+p)/2T

↓ Downsampling

↑ upshift

$$\sum_n C_{T/2}(f - \frac{k}{T}) x(f - \frac{k}{T}) e^{j2\pi(f - \frac{k}{T})T_0}$$

within the summation

$X_{DC}(f - \frac{k}{T})$

