

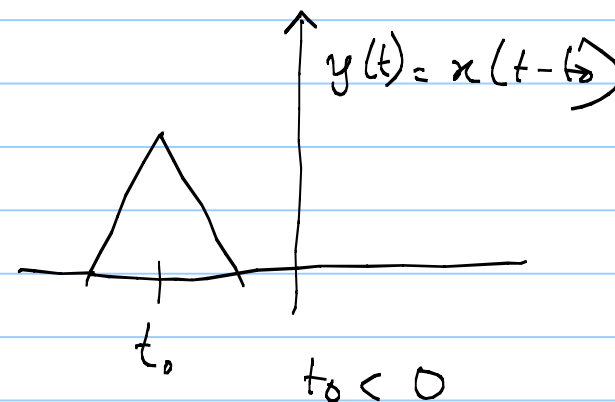
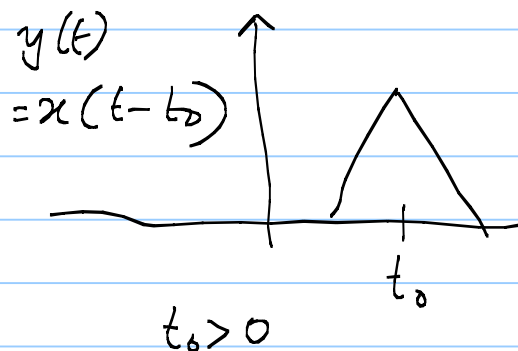
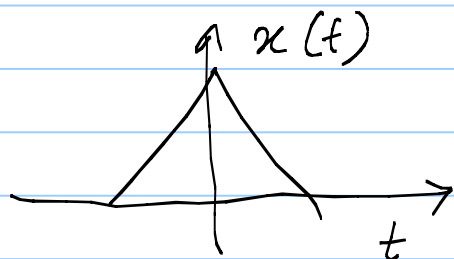
Basic operations on signals

Operation on the independent variable.

Shift:

$$y(t) = x(t - t_0)$$

$$y(t_0) = x(t_0 - t_0) = x(0)$$



Scaling

$$y(t) = x(at)$$

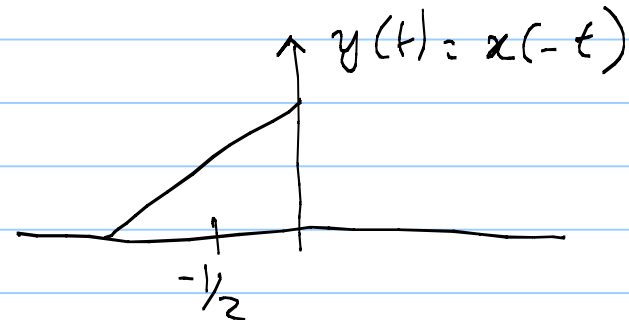
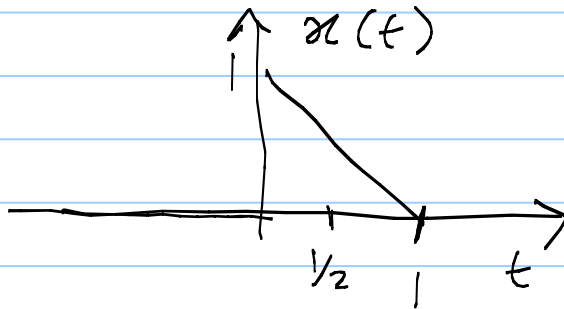
$$a \in \mathbb{R}$$

Eg:

$$y(t) = x(-t)$$

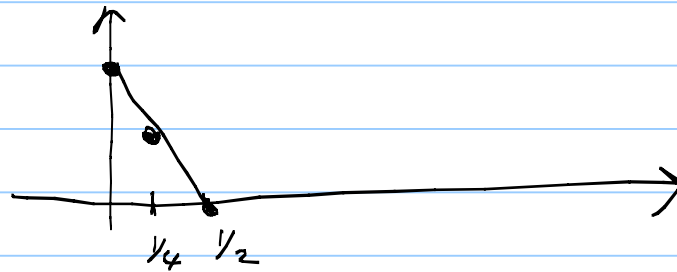
$$a = -1$$

Reflection about the y -axis

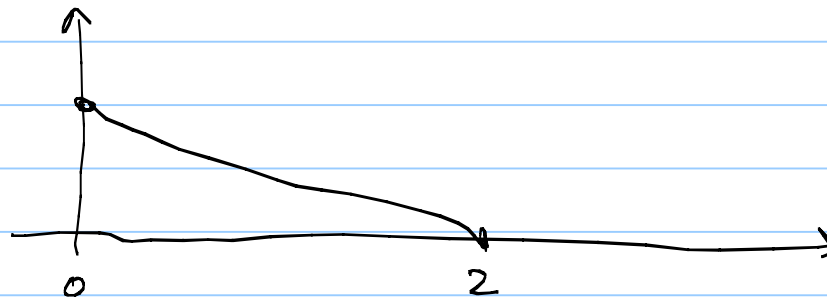


For $|a| \neq 1$:

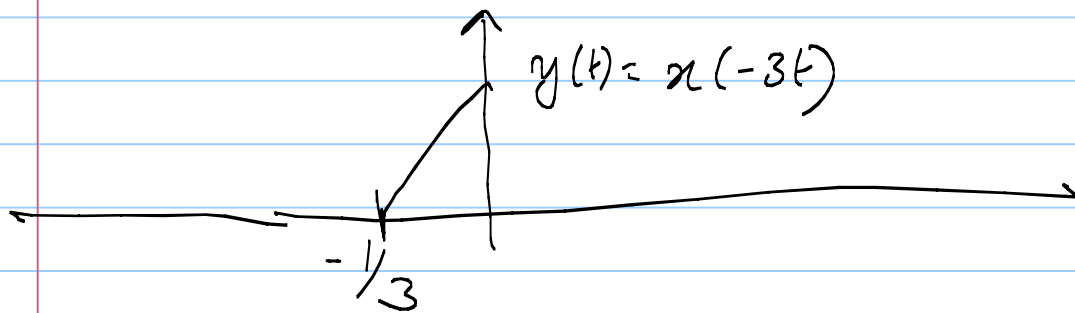
Eg: say $a = 2$, $y(t) = x(2t)$



Eg: $a = 1/2$ $y(t) = x(1/2 t)$



Ex: $a = -3$ $y(t) = x(-3t)$



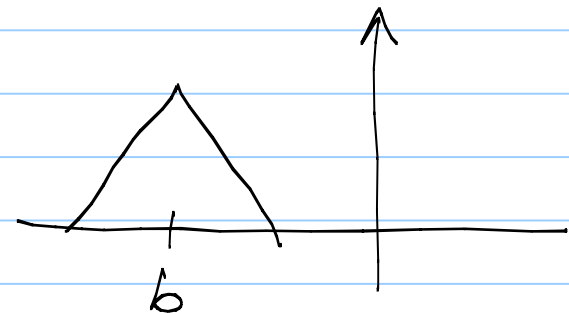
Affine transformation. $at + b$

$$y(t) = x(at + b)$$

Shift first, then scale

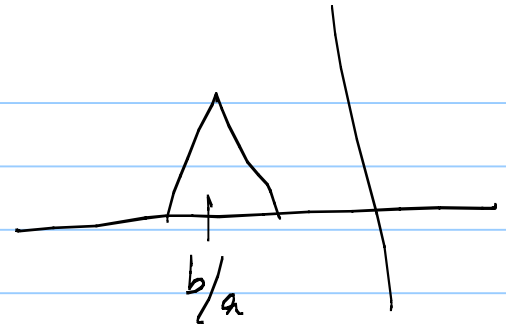
$$w(t) = x(t + b)$$

$\uparrow$ $\uparrow$
 (An arrow points from the t in the argument to the t in the function name $w(t)$.)



$$w(at) = x(at + b)$$

not $x(at + ab)$



Scale first, then shift

$$w(t) = x(at)$$

$$\begin{aligned} w\left(t + \frac{b}{a}\right) &= x\left[a\left(t + \frac{b}{a}\right)\right] \\ &= x(at + b) \end{aligned}$$

Non linear transform:

$$\begin{aligned} X_M(s) &= \int_0^{\infty} x(t) t^{s-1} dt && \text{Mellin transform} \\ &= \int_{-\infty}^{\infty} x(e^{-t}) e^{-st} dt \\ &= \text{Laplace transform of } x(e^{-t}) \end{aligned}$$

Energy & Power of a Signal

Given $x(t)$, energy is defined as

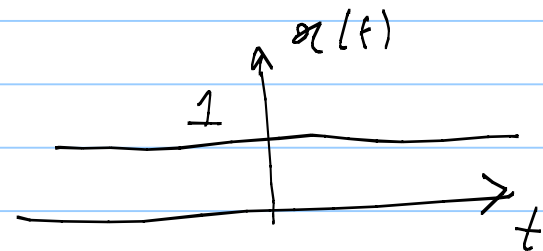
$$E = \int_{-\infty}^{\infty} |x(t)|^2 dt = \|x\|_2^2 \quad (2\text{-norm squared})$$

Power is defined as,

$$P = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt$$

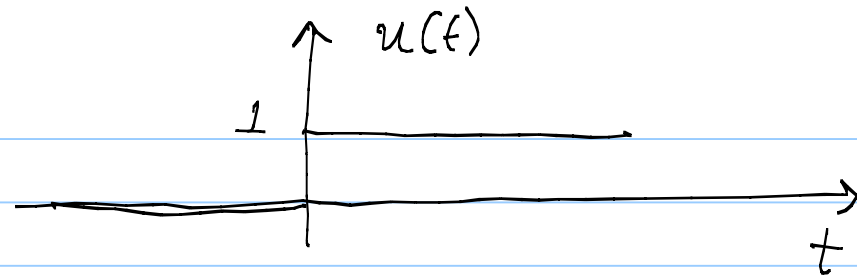
Elementary Signals:

$$x(t) = 1 \quad \forall t \quad \text{"DC signal"}$$



Unit Step Function

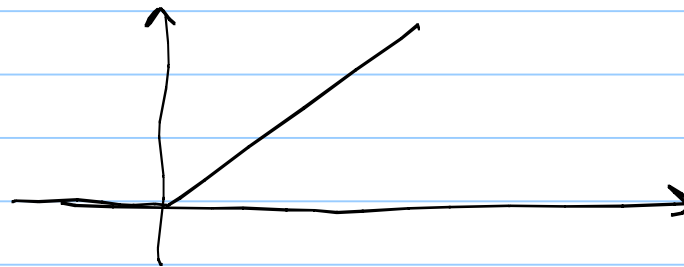
$$u(t) = \begin{cases} 1 & t > 0 \\ 0 & t < 0 \end{cases}$$

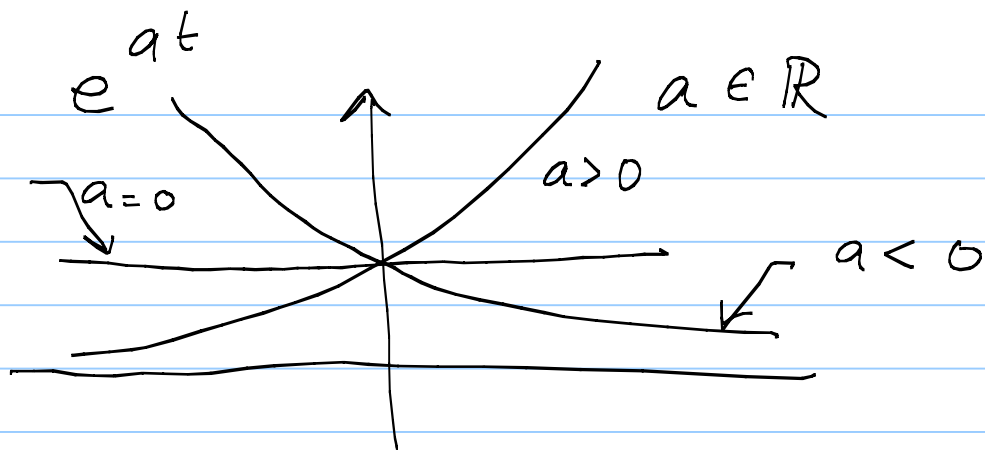


Variants:

For $t = 0$, $u(t)$ can be defined to be 0, 1, $\frac{1}{2}$, any value, or undefined.

Unit ramp





$$e^{j\Omega_0 t} \quad \Omega_0 \in \mathbb{R}$$

$$= \cos \Omega_0 t + j \sin \Omega_0 t$$

$$e^{j\Omega_0(t+T_0)} = e^{j\Omega_0 t + j\Omega_0 T_0} = e^{j\Omega_0 t} \cdot \underbrace{e^{j\Omega_0 T_0}}_1$$

$$\Omega_0 T_0 = k 2\pi$$

$$T_0 = \frac{k 2\pi}{\Omega_0}$$

If T_0 is the period (fundamental period)

$$T_0 = \frac{2\pi}{\Omega_0}$$

$$\text{For } e^{-j\Omega_0 t}, \quad T_0 = \frac{2\pi}{\Omega_0}$$

$$e^{j\Omega_0 t}, \quad T_0 = \frac{2\pi}{|\Omega_0|} \Rightarrow \begin{matrix} \text{As } \Omega_0 \rightarrow \infty \\ T_0 \rightarrow 0 \end{matrix}$$

Signal is periodic $\forall \Omega_0$
with period $\frac{2\pi}{|\Omega_0|} = T_0$

Most general exponential:

$$e^{st} = e^{(\sigma + j\Omega)t}$$

$\sigma + j\Omega$: complex frequency

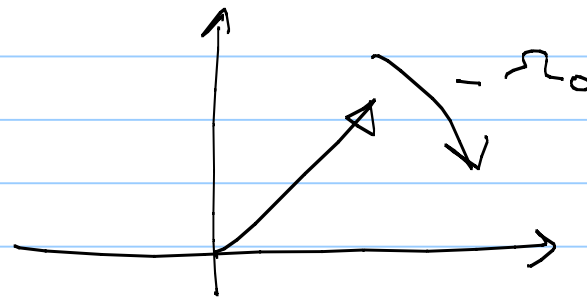
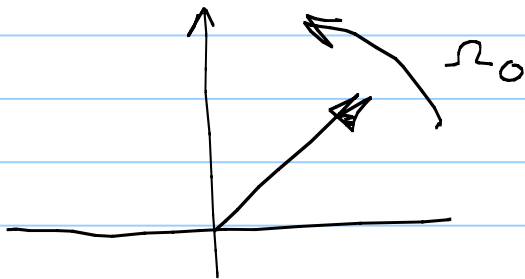
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Note Title

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$e^{j\Omega_0 t}$ is periodic with period $\frac{2\pi}{|\Omega_0|}$

- 1) Always periodic for any Ω_0 w/ period $\frac{2\pi}{|\Omega_0|}$
- 2) Oscillates more & more rapidly as $\Omega_0 \uparrow$



$$e^{st} = e^{(\sigma + j\Omega)t} = e^{\sigma t} \cdot e^{j\Omega t}$$

$\sigma + j\Omega$: complex frequency

Continuous-Time Impulse

Dirac delta function

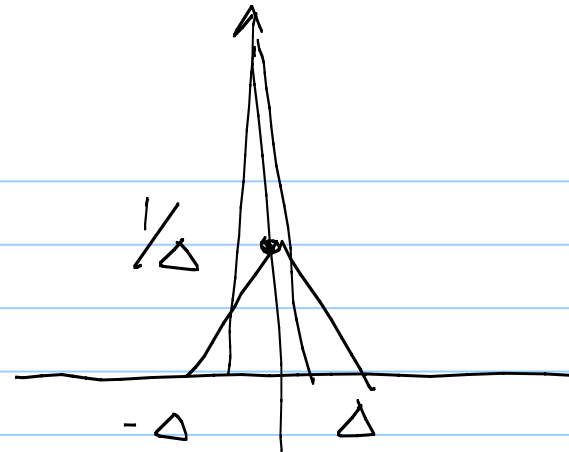
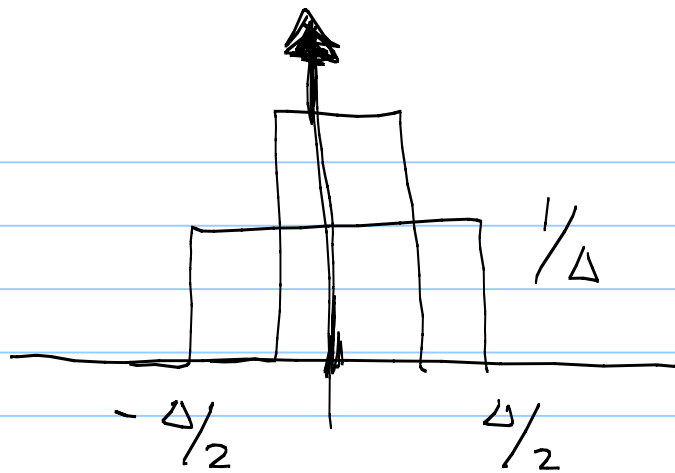
$$\delta(t) = 0 \quad t \neq 0$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

Not a function in the usual sense.

Called functional or generalized function

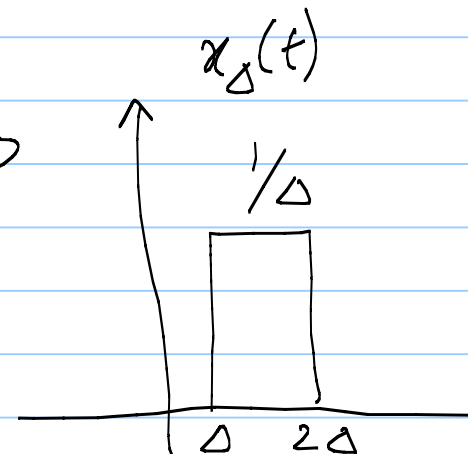
Also called distribution



$$x_{\delta}(t) = \frac{1}{\sqrt{2\pi} \delta} e^{-t^2/2\delta^2}$$

$$x_{\delta}(t) \rightarrow \delta(t) \text{ as } \delta \rightarrow 0$$

$$\delta(0) = \infty \quad \text{wrong}$$

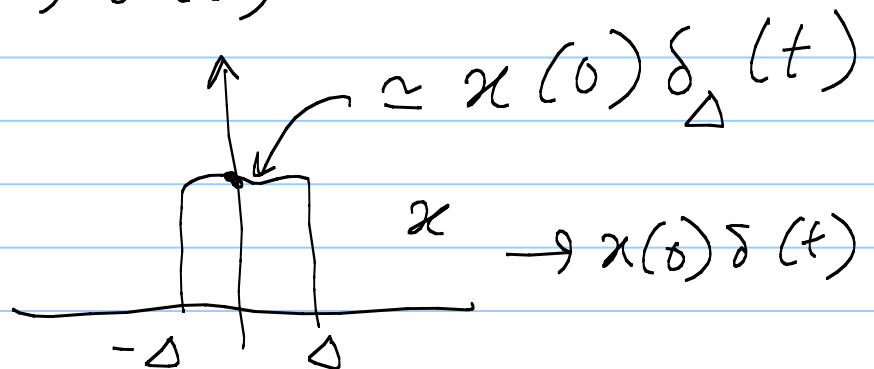
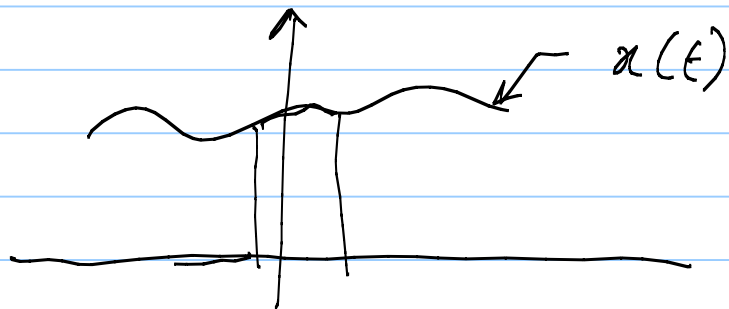


$$x_{\Delta}(t) \rightarrow \delta(t) \text{ as } \Delta \rightarrow 0$$

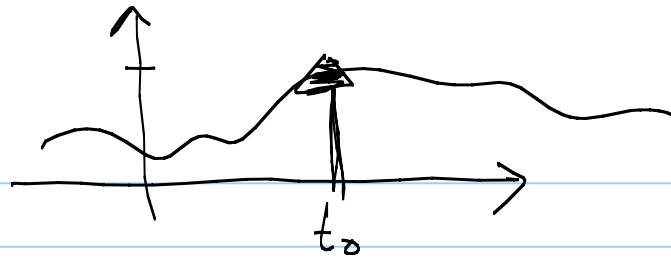
Sifting property

If $x(t)$ is continuous at $t=0$, then

$$x(t) \delta(t) = x(0) \delta(t)$$



$$\delta(t - t_0)$$

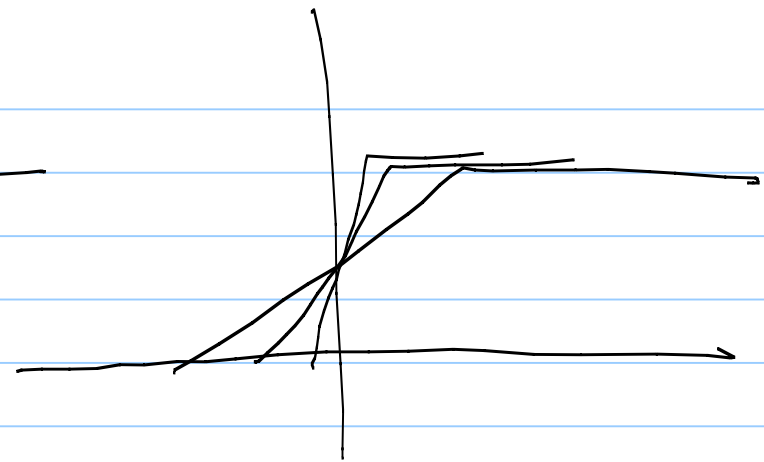
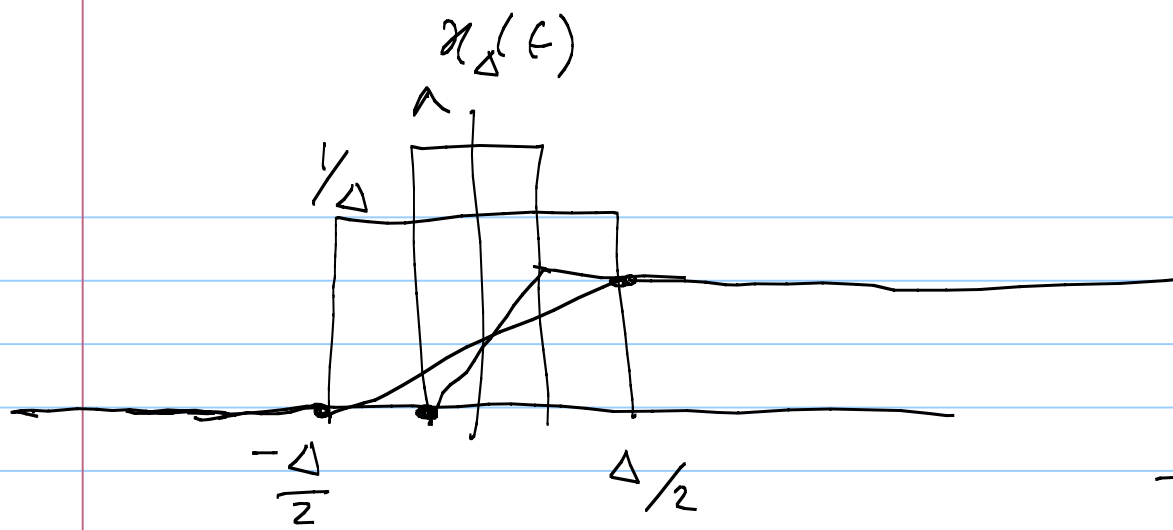


$$x(t) \delta(t - t_0) = x(t_0) \delta(t - t_0)$$

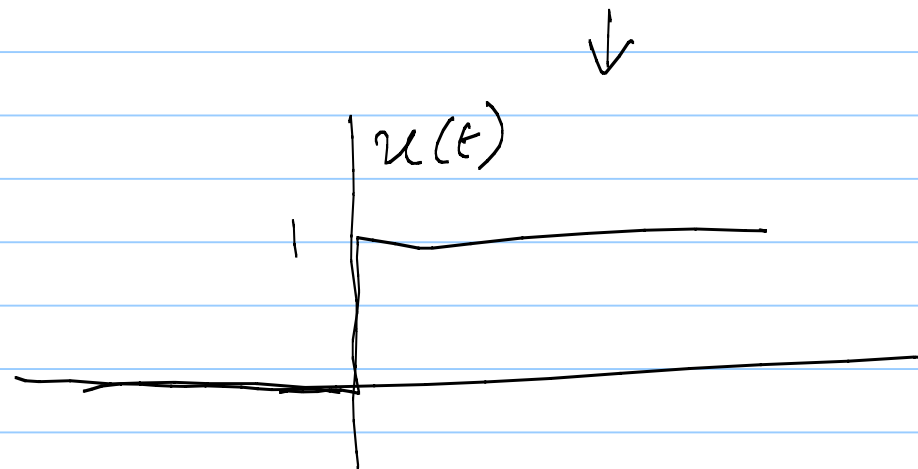
$$\delta(at) = \frac{1}{|a|} \delta(t) \quad (\text{verify!})$$

$$\delta(-t) = \delta(t) \quad \text{even function}$$

$$\delta(at + b) = \frac{1}{|a|} \delta(t + b/a) \quad (\text{verify})$$



$$-\int_{-\infty}^{\infty} x_\Delta(\tau) d\tau$$



$$\int_{-\infty}^t \delta(\tau) d\tau = u(t)$$

$$\frac{d}{dt} \int_{-\infty}^t \delta(\tau) d\tau = \delta(t) = \frac{d}{dt} u(t)$$

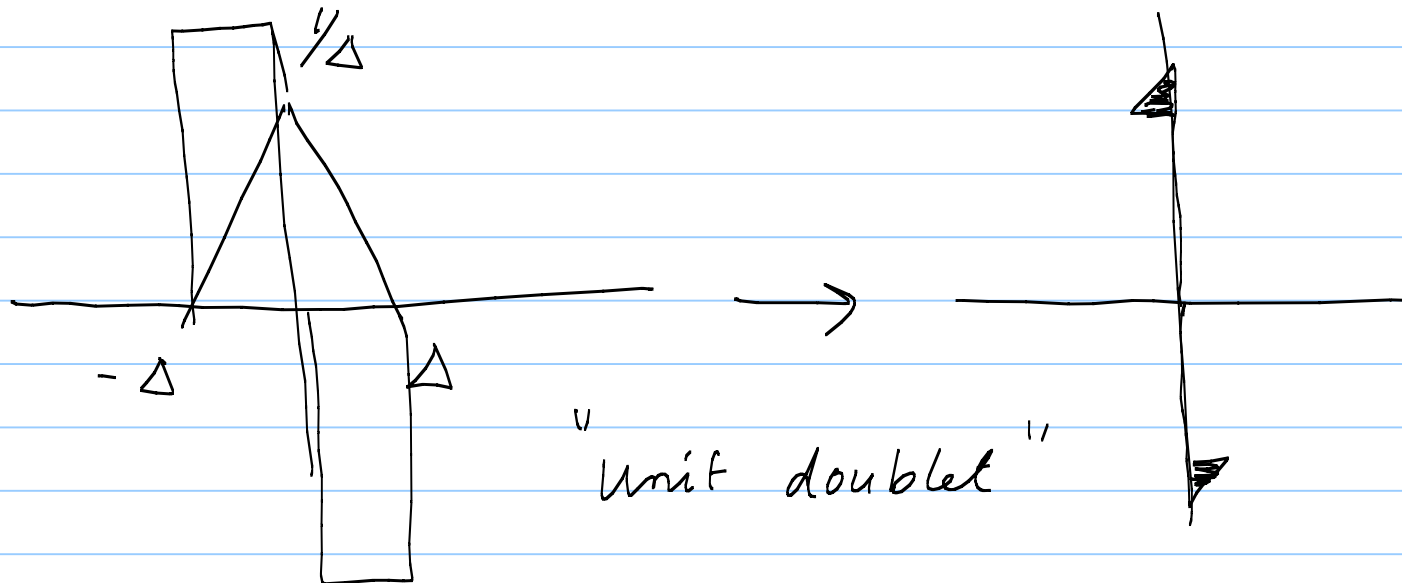
$$\delta(t) = \frac{d}{dt} u(t)$$

$$\begin{aligned} \frac{d}{dt} [f(t) u(t)] &= u(t) f'(t) + f(t) u'(t) \\ &= u(t) f'(t) + f(t) \delta(t) \end{aligned}$$

$$= u(t) f'(t) + f(0) \delta(t)$$

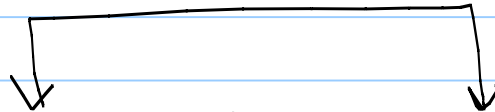
$f(t) u(t) =$ "right sided signal"

$f(t) u(-t) =$ "left sided signal"



$$\int_{-\infty}^{\infty} \delta'(t) dt = 0$$

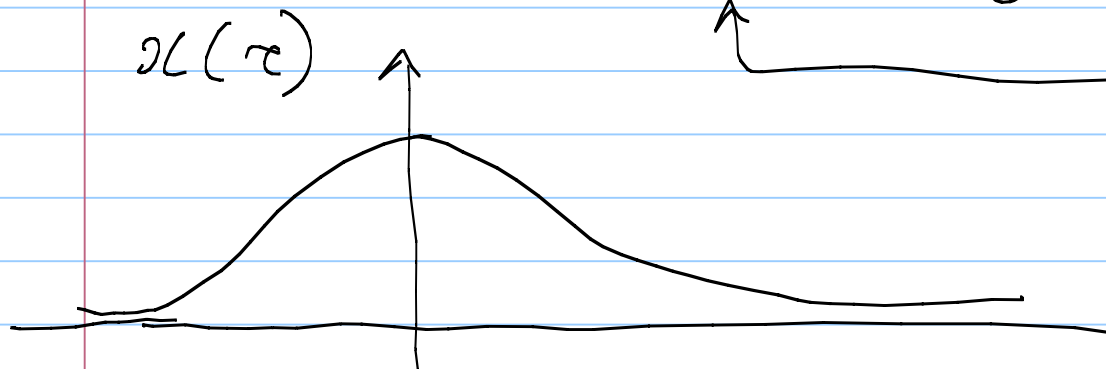
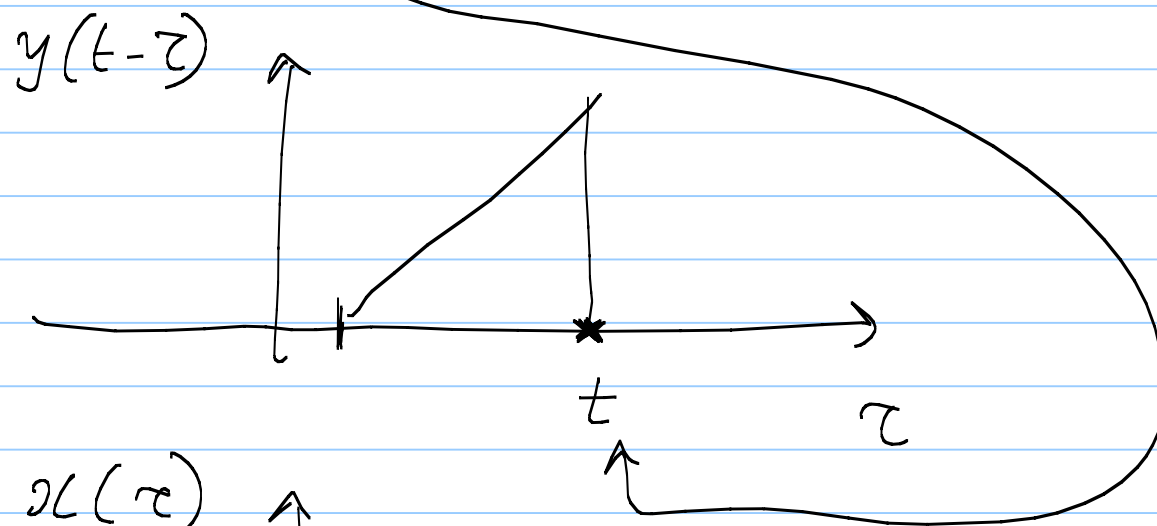
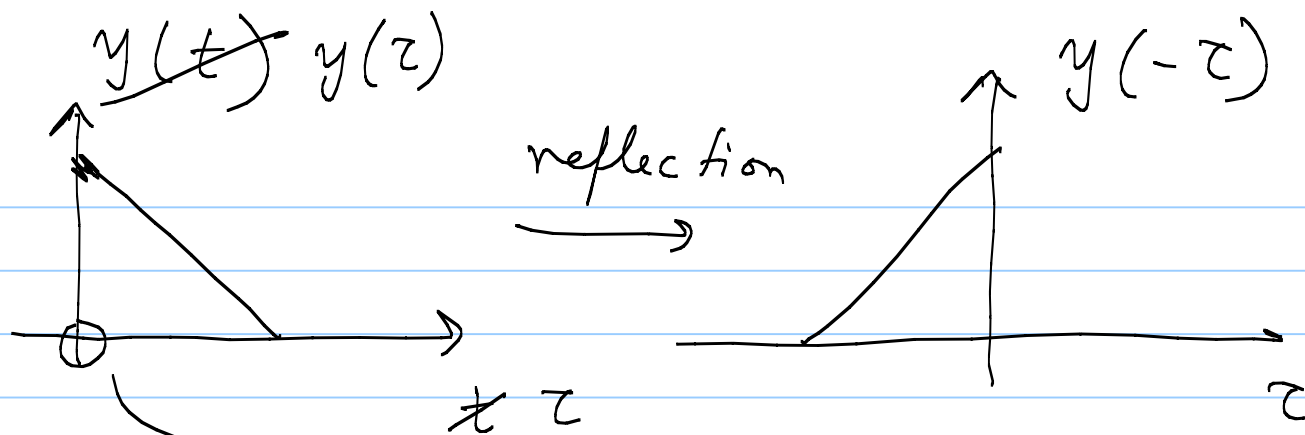
Convolution

$$x(t) * y(t) \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} x(\tau) y(t-\tau) d\tau = z(t)$$


$$y(t) \longrightarrow y(\tau)$$

$$w(\tau) = y(-\tau) \quad \text{reflection}$$

$$w(\tau - t) = y(-(\tau - t)) = y(t - \tau) \quad \text{translation}$$



$$\int_{-\infty}^{\infty} x(\tau) y(t-\tau) d\tau = z(t)$$

<http://www.jhu.edu/~signals/>

$$\int_{-\infty}^{\infty} x(\tau) y(t-\tau) d\tau$$

$$t - \tau = \lambda$$

$$\int_{-\infty}^{\infty} y(\lambda) x(t-\lambda) d\lambda \quad \text{Commutative}$$

Under certain conditions,

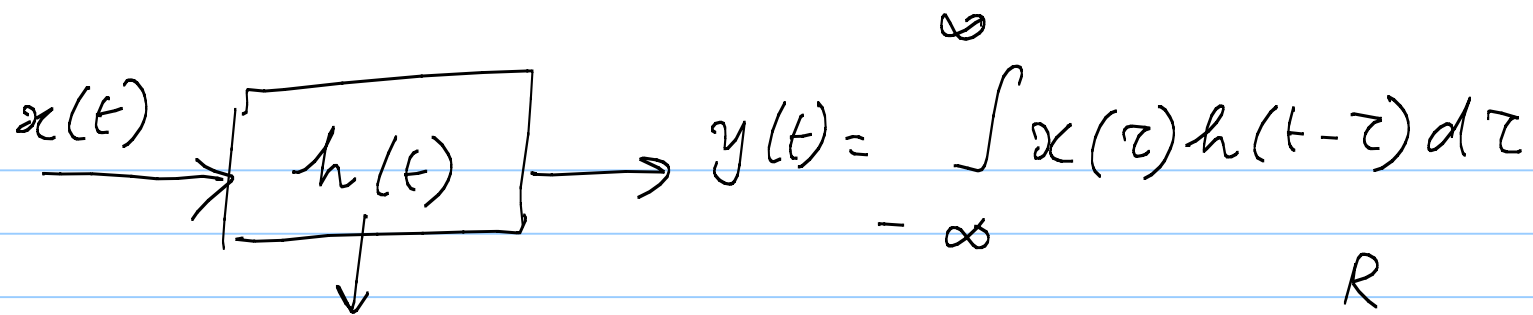
$$x * (y * z) = (x * y) * z \quad \text{associative}$$

$$x(t) * \delta(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t - \tau) d\tau$$

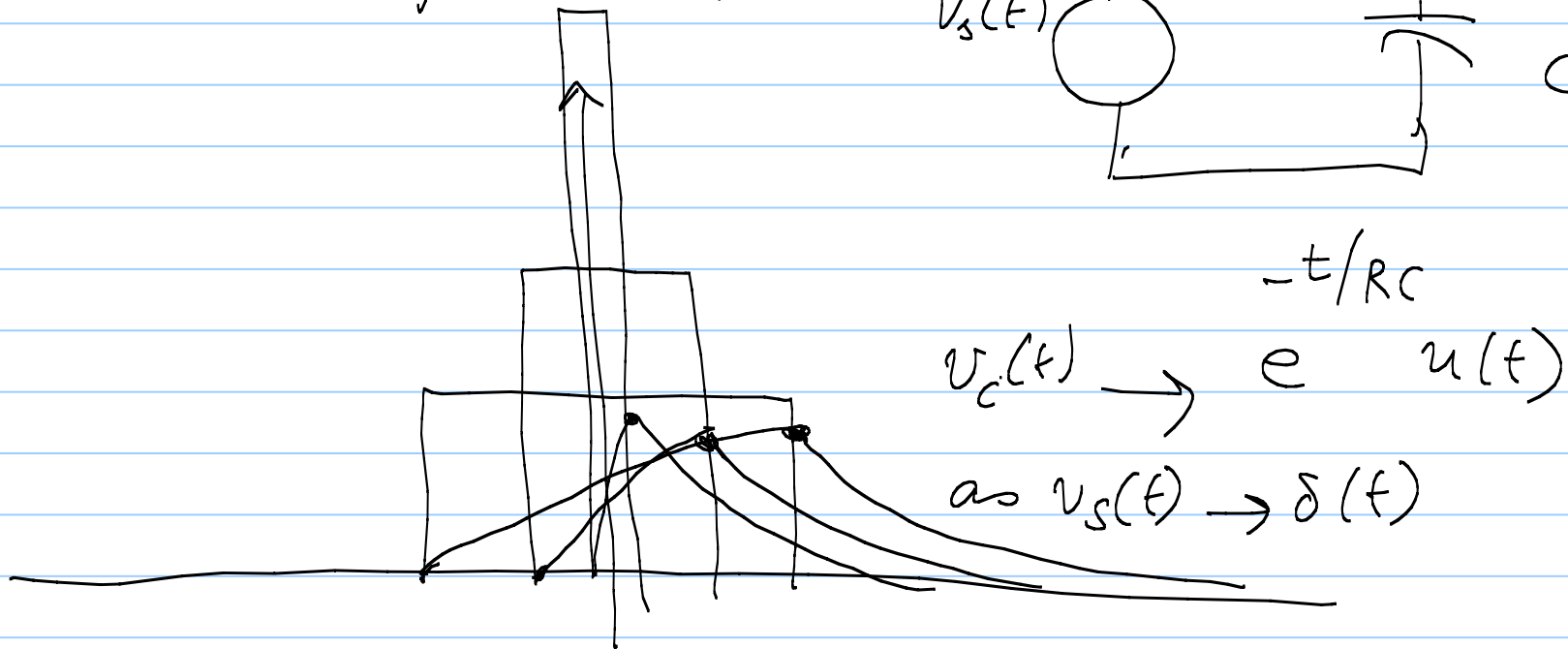
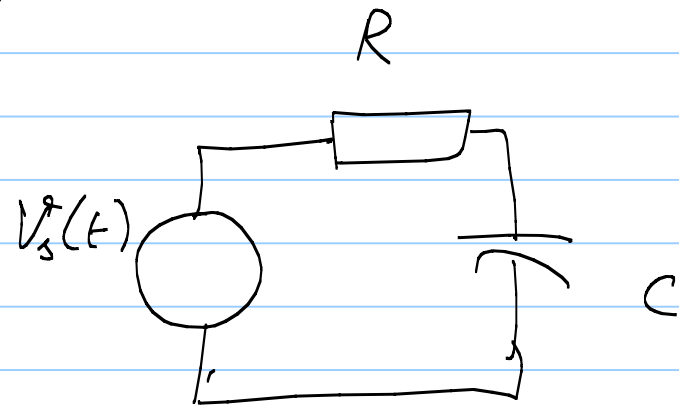
$$= x(t)$$

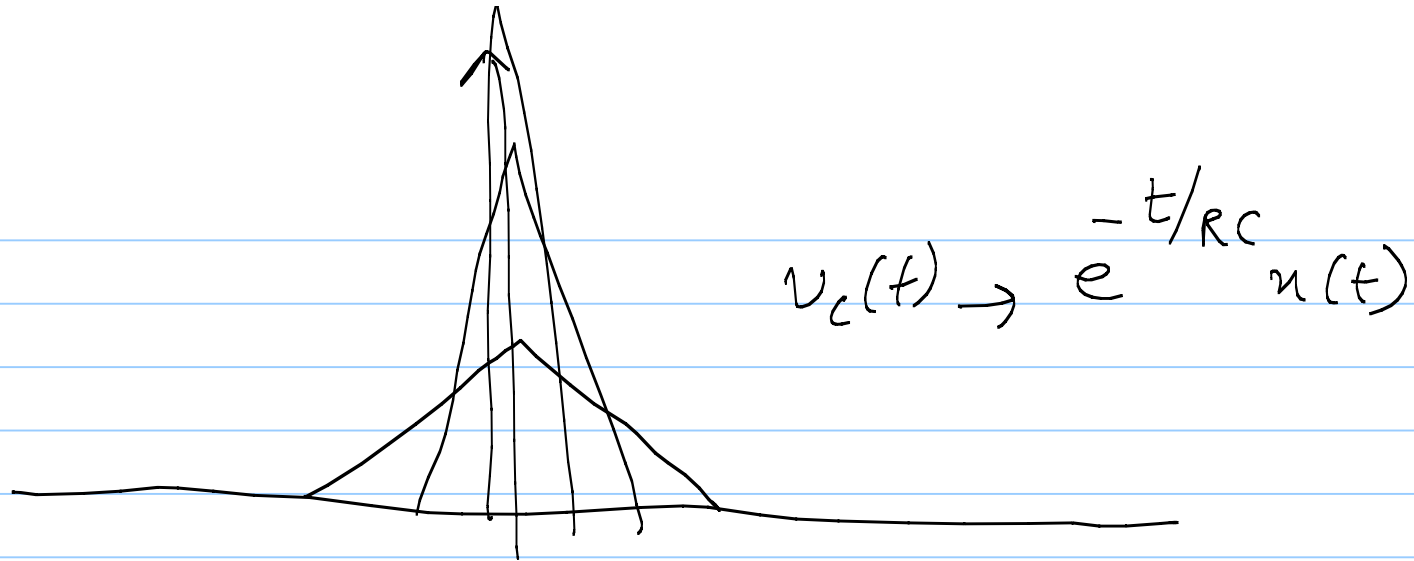
$$x(t) * \delta(t - t_0) = x(t - t_0) \quad (\text{verify})$$

$$\text{If } x(t) = \delta(t), \quad x(t) * \delta(t) = x(t) \Rightarrow \delta(t) * \delta(t) = \delta(t)$$



system's impulse response





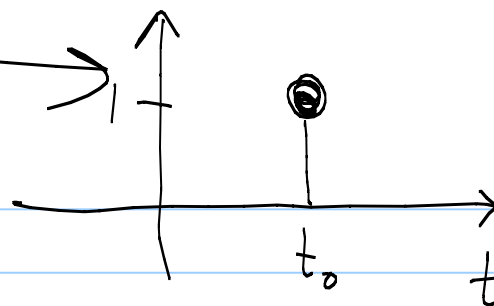
$\delta^2(t) = \text{not defined}$

$$\delta(t) = 0 \quad t \neq 0$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

WRONG!

$$\delta(t) = \begin{cases} 1 & t = 0 \\ 0 & t \neq 0 \end{cases}$$



Consider $x(t) * h(t)$

Suppose $h(t) = 0 \quad t < 0$

$h(t)$ can be written as $h(t)u(t)$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) u(t-\tau) d\tau$$

For $\tau > t \quad u(t-\tau) = 0$

$$y(t) = \int_{-\infty}^t x(\tau) h(t-\tau) \underbrace{u(t-\tau)}_1 d\tau$$

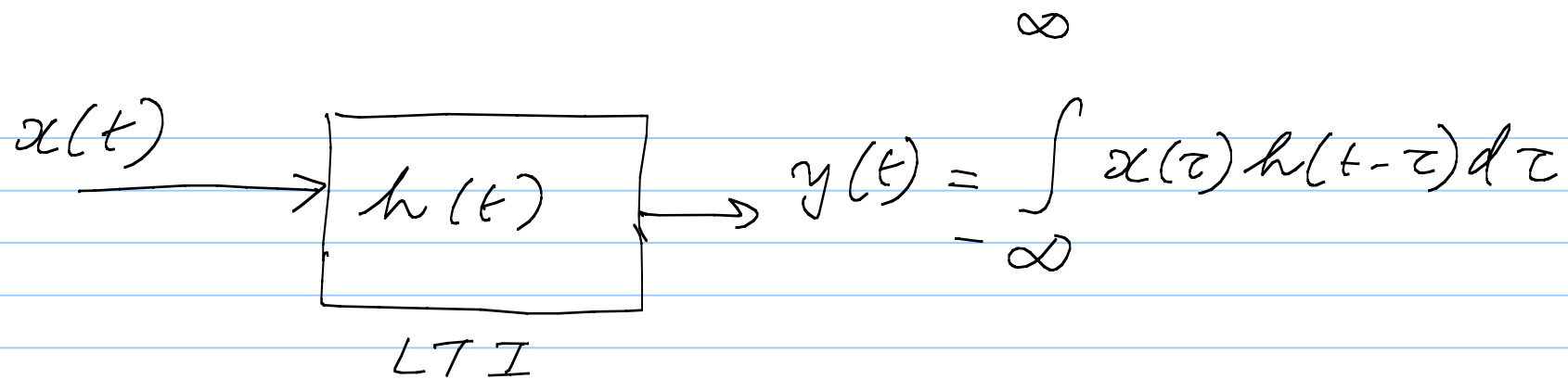
Now suppose $x(t) = 0 \quad t < 0$

i.e. $x(t)$ is written as $x(t)u(t)$

$$y(t) = \int_{-\infty}^t x(\tau) u(\tau) h(t-\tau) u(t-\tau) d\tau$$

$$= \int_0^t x(\tau) \underbrace{u(\tau)}_1 h(t-\tau) \underbrace{u(t-\tau)}_1 d\tau$$

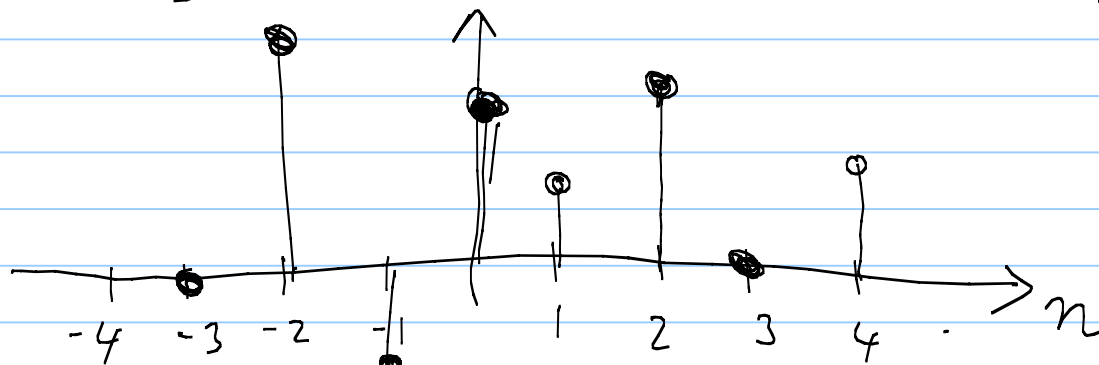
$$= \int_0^t x(\tau) h(t-\tau) d\tau$$



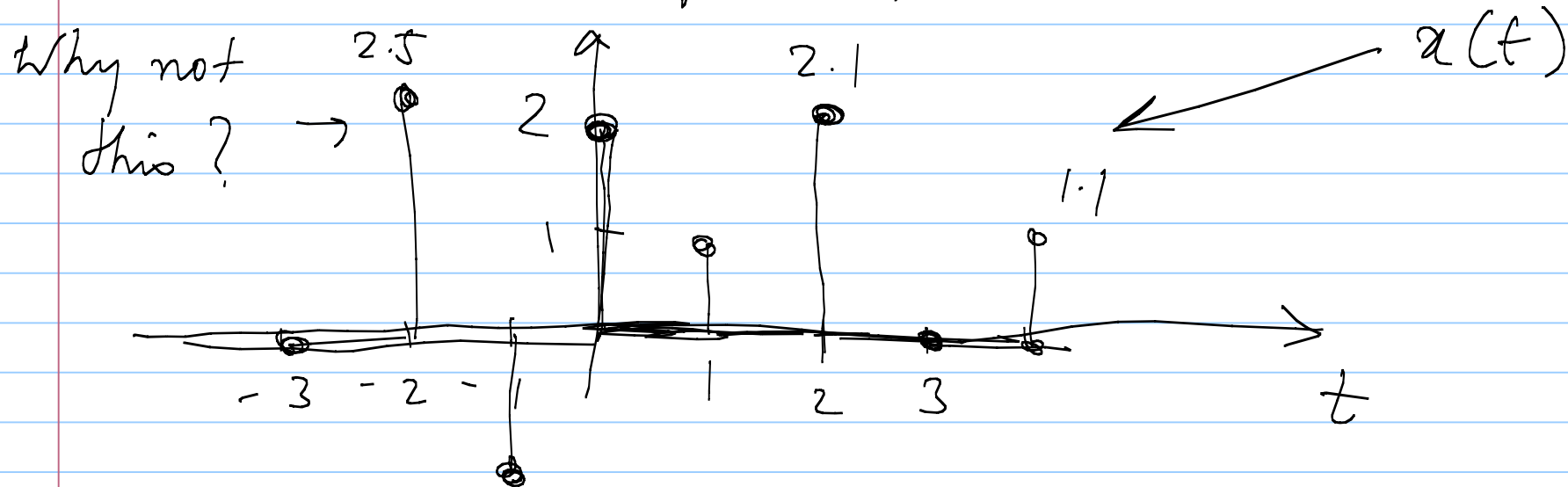
Discrete-time sequence

$$x[n] \in \mathbb{C}$$

$$n \in \mathbb{Z} = \{0, \pm 1, \pm 2, \pm 3, \dots\}$$



$x[1.5] = \text{undefined}$, NOT zero



$x(t)$
 $y(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau = 0$

Unit impulse: $\delta[n] = \begin{cases} 1 & n = 0 \\ 0 & n \neq 0 \end{cases}$

Unit step: $u[n] = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases}$
 $= n \leq -1$

Analogous to complex exponential e^{st} , in discrete time we have

$$x[n] = z^n$$

$$Z = r e^{j\omega}$$

$$r > 0$$

$$x[n] = r^n e^{j\omega n}$$

" " " "

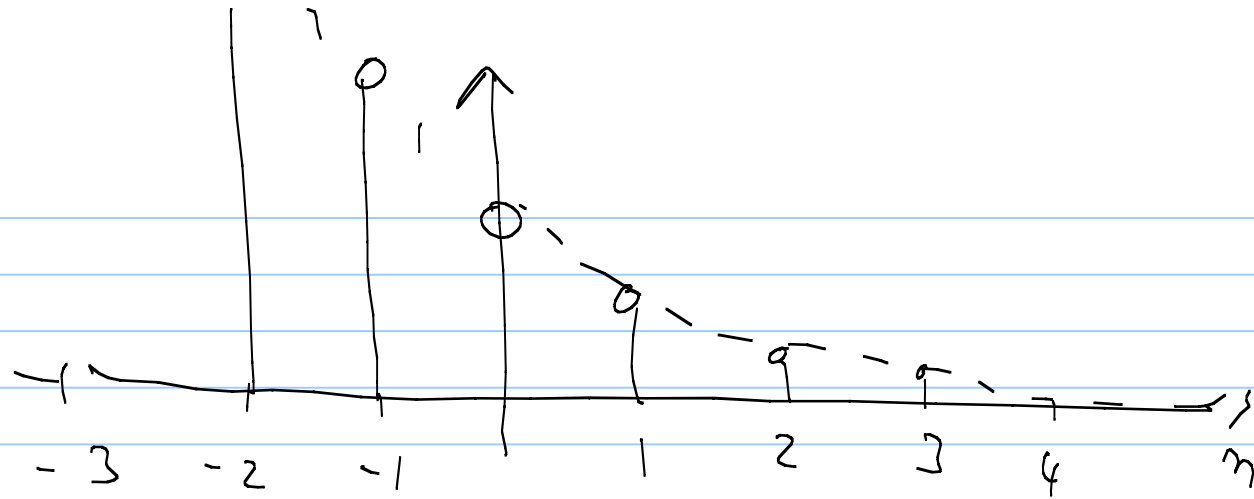
$$\text{DC: } x[n] = 1 \quad \forall n \quad r=1, \omega=0$$

real exponential: $r^n, \omega=0$

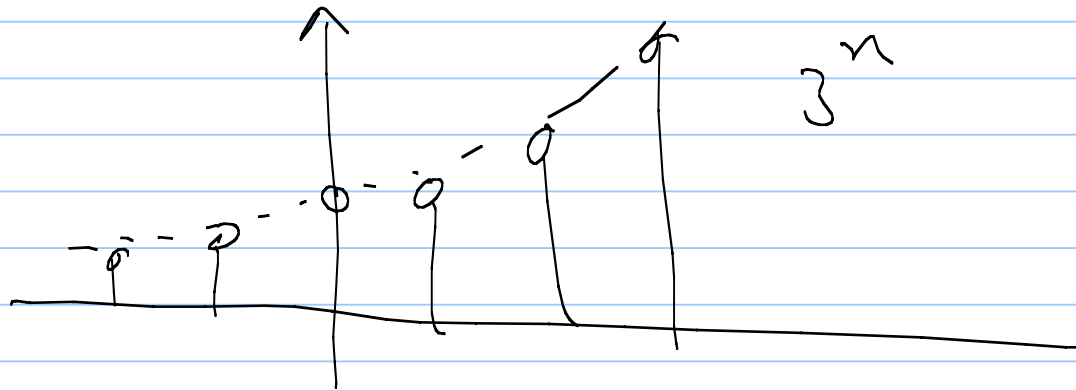
$|r| > 1$ growing exponential to the right

$|r| < 1$ " " to the left

$$x[n] = \left(\frac{1}{2}\right)^n$$



$$x[n] = 3^n$$



If $-1 < r < 0$, then signs alternate

$$x[n] = \left(-\frac{1}{2}\right)^n = (-1)^n \left(\frac{1}{2}\right)^n$$

Let's look at $e^{j\omega_0 n}$ & compare it
with $\underbrace{e^{j\Omega_0 t}}$

↳ 1. always periodic w/ period $T = \frac{2\pi}{|\Omega_0|}$

2. Oscillates more & more rapidly
as $\Omega_0 \uparrow$

$$x[n] = e^{j\omega_0 n}$$

$$\text{If } x[n+N] = x[n], \text{ then } e^{j\omega_0(n+N)} = e^{j\omega_0 n}$$

$$\Rightarrow e^{j\omega_0 N} = 1$$

$$\omega_0 N = 2\pi k$$

$$2\pi f_0 N = 2\pi k$$

$$f_0 = k/N$$

Hence $e^{j\omega_0 n}$ is periodic with period N
if and only if $f_0 = \frac{k}{N}$ i.e. a rational number

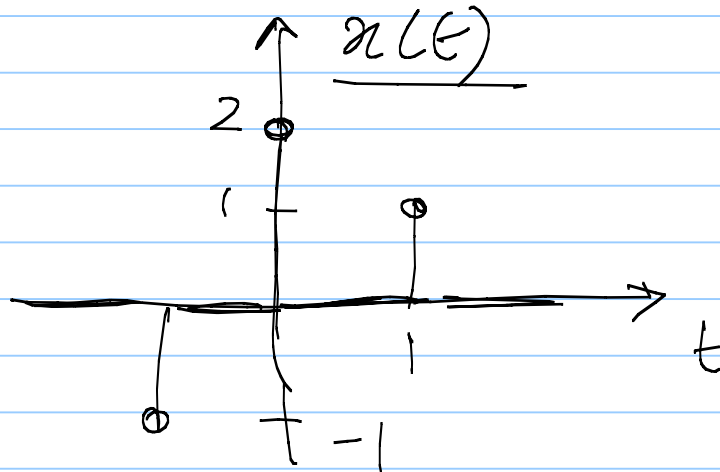
Now if $\omega_1 = \omega_0 + 2\pi$

$$\begin{aligned} e^{j\omega_1 n} &= e^{j(\omega_0 + 2\pi)n} = e^{j\omega_0 n} e^{j2\pi n} \\ &= e^{j\omega_0 n} \end{aligned}$$

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Note Title

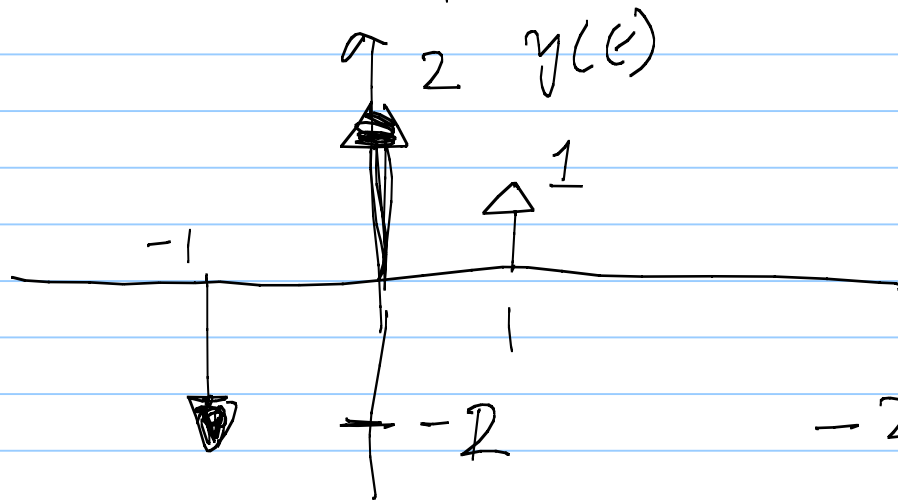
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$$x(1) = 1$$

$$x(0) = 2 \neq 2\delta(t)$$

$$\int_{-\infty}^{\infty} x(t) dt = 0$$



$$\int_{-\infty}^{\infty} y(t) dt =$$

$$-2 + 2 + 1 = 1$$

$$f(x) = \begin{cases} 1 & x \text{ is irrational} \\ 0 & x \text{ is rational} \end{cases}$$

$$e^{j\omega_0 n} = x[n]$$

$$x[n+N] = x[n] \Rightarrow \underbrace{\frac{\omega_0}{2\pi}}_{f_0} = \frac{k}{N}$$

$e^{j\Omega_0 t}$ is always periodic w/ periodic

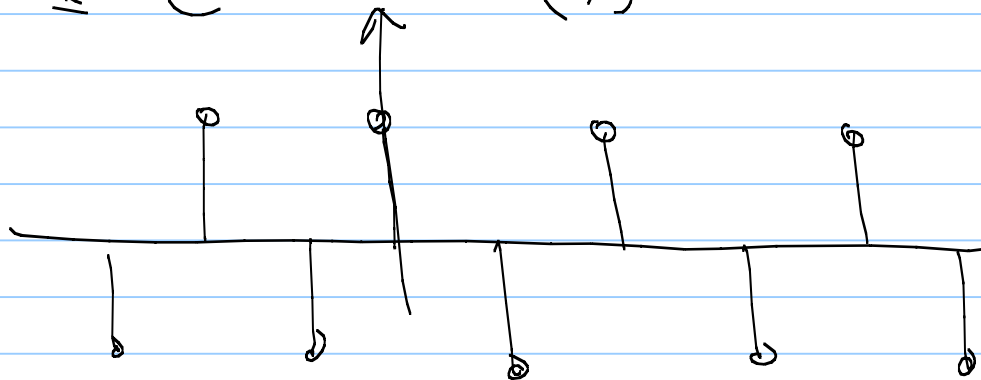
$$T = \frac{2\pi}{|\Omega_0|}$$

$$e^{j(\omega_0 + 2\pi)n} = e^{j\omega_0 n}$$

$$\text{If } \omega_0 = 0 \quad e^{j\omega_0 n} = 1 \quad \forall n$$

$$\text{If } \omega_0 = 2\pi, \quad e^{j2\pi n} = 1 \quad \forall n$$

$$e^{j\pi n} = e^{-j\pi n} = (-1)^n$$



$$e^{j 1.1 \bar{u} n} = \cos(1.1 \bar{u} n) + j \sin(1.1 \bar{u} n)$$

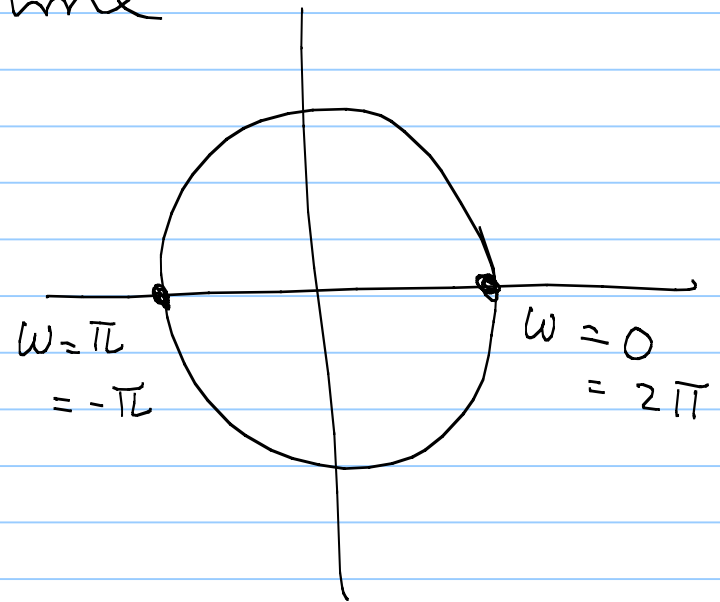
e^{jn} = not periodic in time

$$= e^{j(1+2\pi)n}$$

$$e^{j\omega_0 n}$$

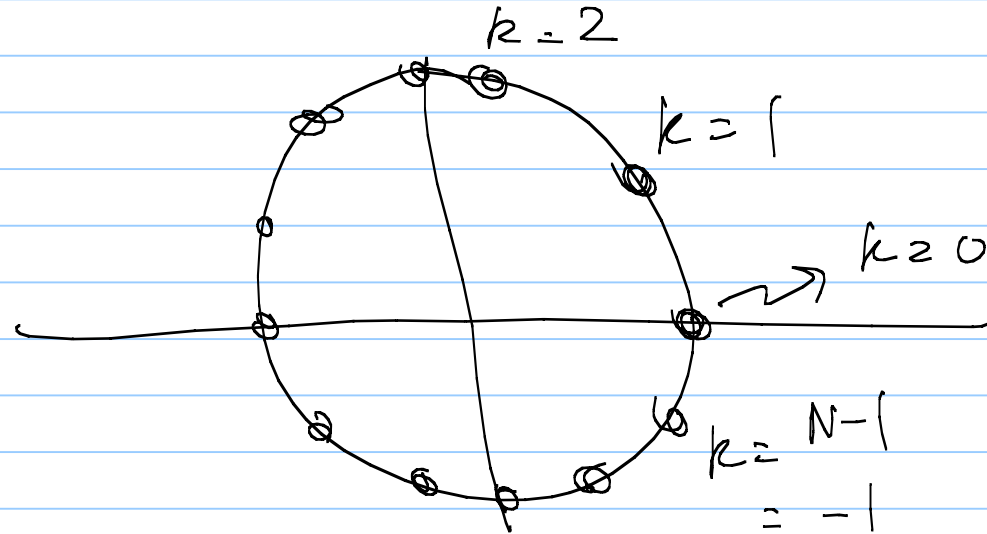
$$\frac{\omega_0}{2\pi} = \frac{K}{N}$$

$$f_0 \rightarrow (0, 1)$$



$$f_0 = \left\{ 0, \frac{1}{N}, \frac{2}{N}, \frac{3}{N}, \dots, \frac{N-1}{N}, N \right\}$$

N distinct complex exponential



$e^{j\omega_0 n}$ & $e^{-j\omega_0 n}$ are two linearly independent signals.

$$x_1[n] = e^{j\omega_0 n} = \cos \omega_0 n + j \sin \omega_0 n$$

$$x_2[n] = e^{-j\omega_0 n} = \cos \omega_0 n - j \sin \omega_0 n$$

$$a_1 x_1[n] + a_2 x_2[n] = 0$$

$$\Rightarrow a_1 = a_2 = 0 \quad a_1, a_2 \in \mathbb{C}$$

$$\cos \omega_0 n = \frac{1}{2} e^{j\omega_0 n} + \frac{1}{2} e^{-j\omega_0 n}$$

$$\cos 2\pi \frac{1}{N} n \quad \xrightarrow{k=1} \quad \cos 2\pi \frac{-1}{N} n \quad \xrightarrow{k=-1 = N-1}$$

$$\underbrace{2\pi f_0}_{\omega_0} n$$

$$\sin 2\pi \frac{1}{N} n$$

$$\sin 2\pi \frac{-1}{N} n$$

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$$x[n] = e^{j\omega_0 n} \quad : \text{We want } x[n+N] = x[n]$$

$$\Rightarrow f_0 = \frac{\omega_0}{2\pi} = \frac{K}{N} \Rightarrow K = 0, 1, \dots, N-1$$

Discrete-Time Convolution:

$$\begin{aligned} y[n] &= \sum_{k=-\infty}^{\infty} x[k] h[n-k] \\ &= x[n] * h[n] \end{aligned}$$

$$y(t) = x(t) \cdot h(t)$$

$$y(ct) = x(ct) \cdot h(ct)$$

$$y(t) = x(t) * h(t)$$

$$y(ct) = x(ct) * h(ct) \quad \text{WRONG} \leftarrow$$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau$$

$$y(ct) = \int_{-\infty}^{\infty} x(\tau) h(ct - \tau) d\tau$$

find the
correct
expression

$$\text{Let } \left. \begin{array}{l} x[n+N] = x[n] \\ h[n+N] = h[n] \end{array} \right\} \text{ same period } N$$

$$\sum_{k=-\infty}^{\infty} \underbrace{x[k] h[n-k]}_{\text{periodic w/ period } N}$$

$$= \quad 0 \quad , \quad \infty \quad , \quad \infty \quad - \infty$$

Suppose,
$$\sum_{k=0}^{N-1} x[k] h[n-k] \stackrel{\text{def}}{=} x[n] \otimes h[n]$$

circular convolution
periodic convolutions

$\xrightarrow{\text{optional suffix } N}$

$$x(t+T) = x(t) \quad ; \quad h(t+T) = h(t)$$

$$x(t) \otimes h(t) = \int_0^T x(\tau) h(t-\tau) d\tau$$

For linear convolution, if $x[n]$ is of length M , & $h[n]$ is of length N , then

$$x[n] * h[n] = y[n] \rightarrow \text{is of length } M+N-1$$

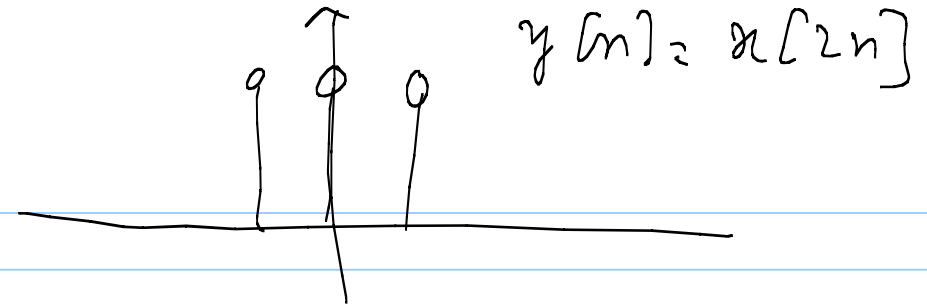
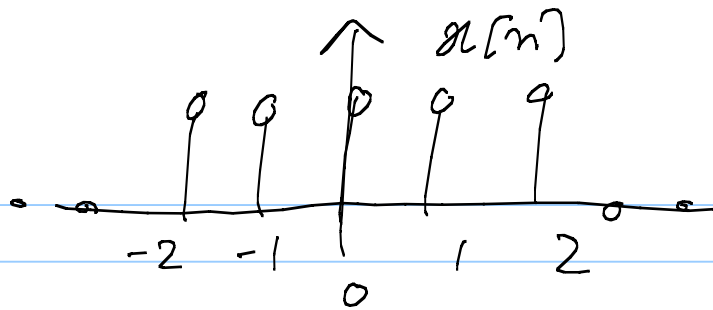
(Verify)

Scaling in Discrete Time

$$x[an] \quad an \in \mathbb{Z}$$

Eg: $y[n] = x[2n]$

$$y[0] = x[0], \quad y[1] = x[2], \quad y[-1] = x[-2], \dots$$



$$y[n] = x[n/2]$$

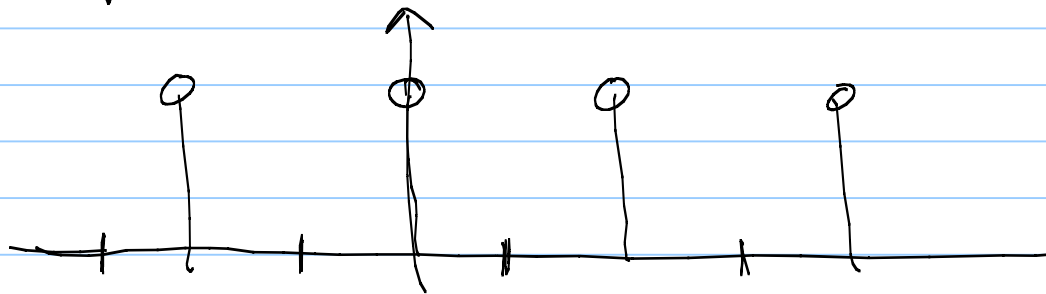
$$y[0] = x[0]$$

$$y[2] = x[1]$$

$$y[-2] = x[-1]$$

$$y[1] = x[1/2] = \underline{\text{undefined}}$$

$$y[-1] = x[-1/2] = \underline{\text{undefined}}$$



It is common to set $y[n] = 0$ when
 $n = 2k + 1$

$$y[n] \propto x[mn + p]$$

$$w[n] \propto x[n + p]$$

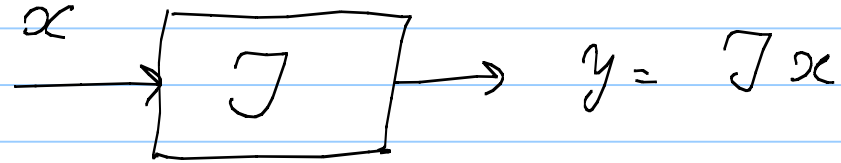
$$w[mn] \propto x[mn + p]$$

Is the other way possible? i.e., scaling
first & then shifting?

Think about this

Systems

Takes an input, processes it, & produces an output.



(1) Linear

(a) additivity: if $x_1 \longrightarrow y_1$
& $x_2 \longrightarrow y_2$

and $x_1 + x_2 \longrightarrow y_1 + y_2$

then additivity holds

(b) Homogeneity:

$$a \in \mathbb{C}$$

$$\text{If } x_1 \rightarrow y_1$$

then homogeneity holds $a \cdot x_1 \rightarrow a \cdot y_1$

If both additivity & homogeneity hold,
the system is linear

$$a_1 x_1 + a_2 x_2 \rightarrow a_1 y_1 + a_2 y_2 \quad (\text{superposition})$$

$$y(t) = \frac{dx(t)}{dt} \quad \text{verify that this is linear}$$

$$y(t) = x^2(t) \quad \text{verify that this is nonlinear}$$

$$y[n] = b_0 x[n] + b_1 x[n-1] + a_1 y[n-1] \quad (\text{linear})$$

One important consequence of linearity is
if $x(t) = 0 \quad \forall t$, $y(t) = 0$ for all t

$$x_1(t) \rightarrow y(t)$$

$$0 \cdot x(t) \rightarrow 0 \cdot y(t)$$

$$0 \longrightarrow 0$$

EC5142 11th Aug. 2011

Note Title

11-08-2011

Classification of Systems.

1) Linearity

Additivity + homogeneity = linearity

$$v(t) = i(t) \cdot R \quad \text{linear system}$$

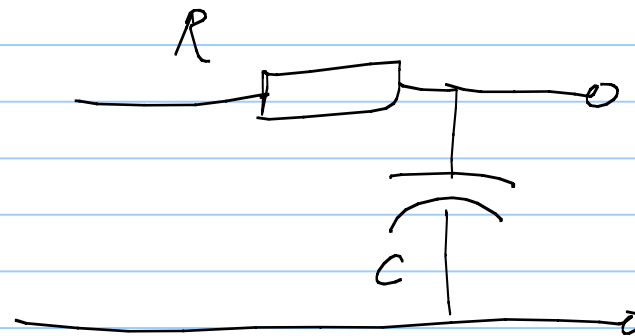
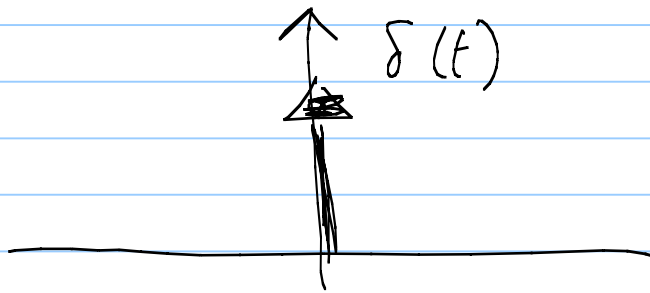
$$\underbrace{a \cdot x} \longrightarrow a \cdot y$$

$$a \in \mathbb{C}$$

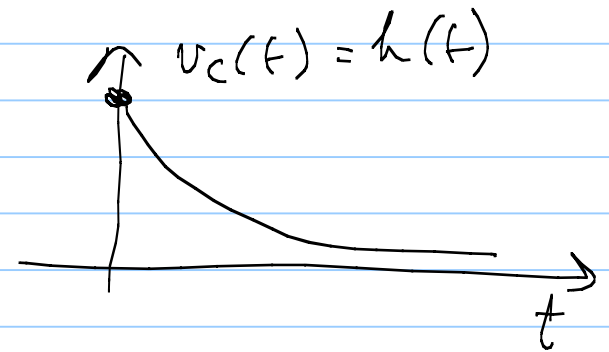
$$0 \cdot x \longrightarrow 0 \cdot y$$

If $x(t) = 0 \quad \forall t$, then $y(t) = 0 \quad \forall t$

If $x(t) = 0$ for $t < t_0$, then $y(t) = 0$ for $t < t_0$



$$h(t) = e^{-t/RC} \quad u(t) = v_c(t)$$
$$v_c(0^-) = 0$$



2) Causality

If the Output $y(t) \big|_{t=t_0}$ depends only on

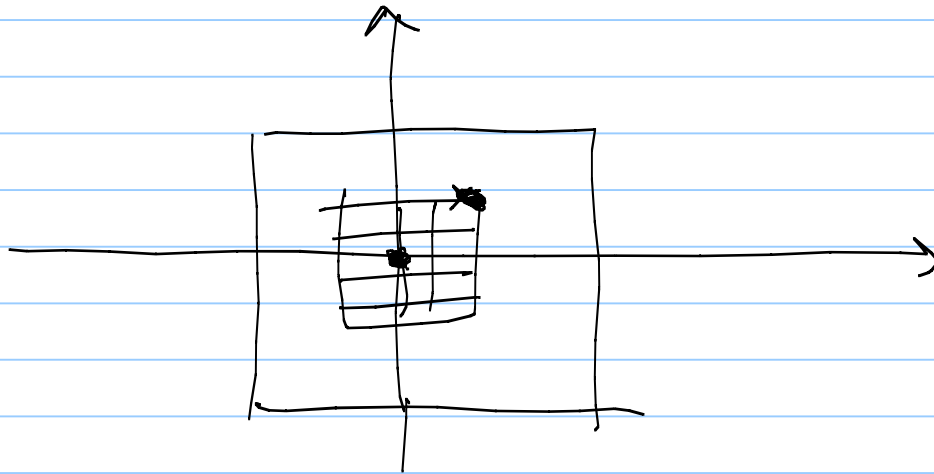
i/p $x(t)$ for $t \leq t_0$ & $y(t)$ for $t < t_0$
then the system is causal

Eg: $y(t) = C x(t)$: causal

Eg: $y(t) = x(-t)$ non causal

since for $t < 0$, the o/p is a fun. of $x(t)$ for $t > 0$.

Eg: $y(t) = x(t) \cos(t+1)$ causal



3) Memory or Memoryless

If o/p at $t=t_0$ depends only i/p only at $t=t_0$
then the system is memoryless.

$$V(t) = i(t) \cdot R \quad \text{memoryless}$$

$$V_c(t) = \int_{-\infty}^t i_c(\tau) d\tau \quad \text{has memory}$$

$$y[n] = x[n] + a y[n-1] \quad \begin{array}{l} \text{has memory} \\ \text{causal, linear} \end{array}$$

$$y[n] = x[n] + b x[n+1] + a y[n-1] \quad \begin{array}{l} \text{has memory} \\ \text{linear} \\ \text{non causal} \end{array}$$

4) Time Invariance

$$\text{If } x(t) \rightarrow y(t)$$

$$\& \quad x(t-t_0) \rightarrow y(t-t_0)$$

then the system is time invariant

$$y(t) = t x(t)$$

$$y(t-t_0) = (t-t_0) x(t-t_0) \quad \text{--- (1)}$$

$$x(t) \longrightarrow x(t-t_0) = w(t) \longrightarrow t \rightarrow w(t) \\ t \rightarrow x(t-t_0) \quad - (2)$$

$\Rightarrow$ Time variant

$$y(t) = x^2(t) \quad \begin{array}{l} \text{nonlinear} \\ \text{time invariant} \end{array}$$

Linearity + time invariance : important
LTI systems Sub class of systems

(5) Stability Bounded i/p Bounded o/p (BIBO)
stability

If $|x(t)| \leq B_x$ produces $y(t)$ o.f.

$|y(t)| \leq B_y$, then the system is BIBO stable

$$y(t) = \int_{-\infty}^t x(\tau) d\tau$$

If $x(t) = u(t)$, $y(t) = t u(t)$

$$e^{j\omega_0 n} : x[n+N] = x[n]$$

$$f_0 = \frac{\omega_0}{2\pi} = \frac{k}{N} \quad k=0, 1, \dots, N-1$$

For some k & N , N need not be the fundamental period.

Even & Odd

If $x(t) = x(-t)$, then $x(t)$ is even

($x(t)$ is real valued)

$\cos(t)$: even

$\sin(t)$: odd

$x(t) = -x(-t)$ then $x(t)$ is odd

For complex signals

If $x(t) = x^*(-t)$, then it is conjugate even
conjugate symmetric

$x(t) = -x^*(-t)$, conjugate antisymmetric

$$e^{j\Omega_0 t} \rightarrow (e^{-j\Omega_0 t})^* = e^{j\Omega_0 t} : \text{conjugate symmetric}$$

Real Valued:

Any signal can be expressed as a sum of even & odd parts.

$$x(t) = \underset{\substack{\uparrow \\ \text{odd part}}}{x_o(t)} + \underset{\substack{\downarrow \\ \text{even part}}}{x_e(t)}$$

$$x_e(t) = \frac{x(t) + x(-t)}{2}$$

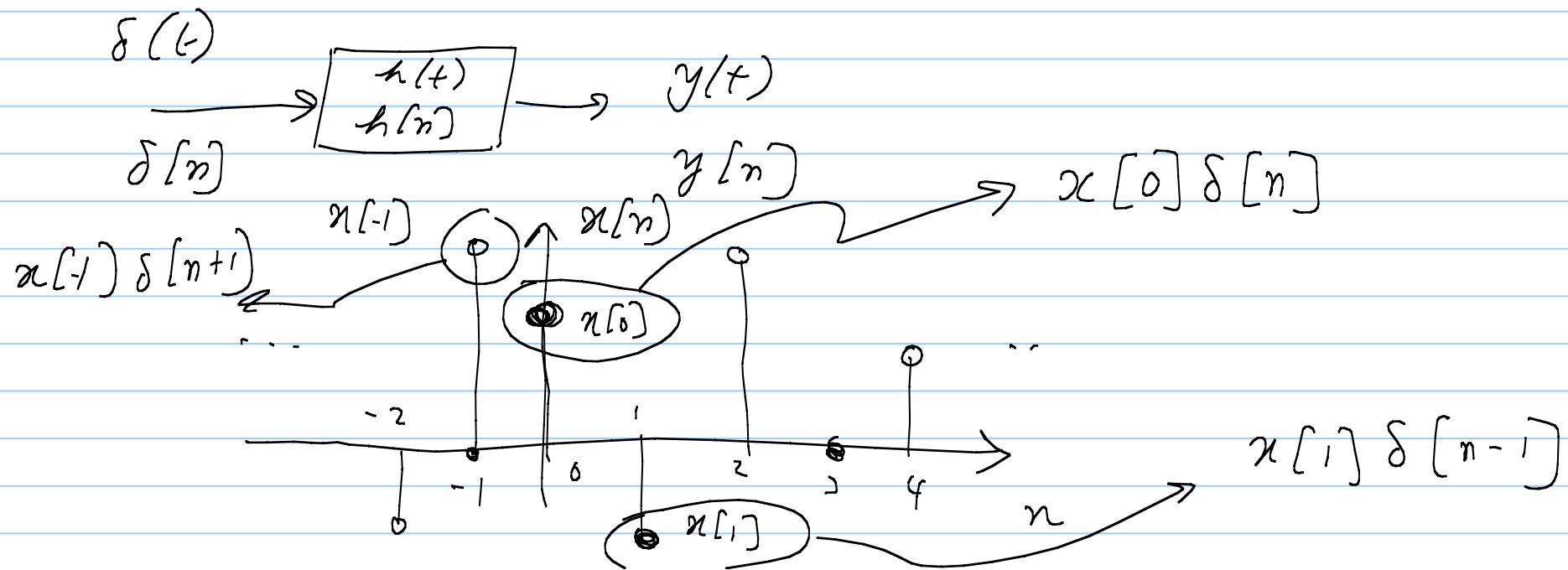
$$x_o(t) = \frac{x(t) - x(-t)}{2}$$

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Note Title

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Systems that are both linear & time invariant form an important class LTI



$$x[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n-k]$$

$$\delta[n] \longrightarrow h[n]$$

$$\delta[n-k] \longrightarrow h[n-k] \quad \text{time invariance}$$

$$x[k] \delta[n-k] \longrightarrow x[k] h[n-k] \quad \text{homogeneity}$$

$$\sum_{k=-\infty}^{\infty} x[k] \delta[n-k] \longrightarrow \sum_{k=-\infty}^{\infty} x[k] h[n-k] \quad \text{additivity}$$

$$\underbrace{\sum_k x[k] \delta[n-k]}$$

$$x[n] \longrightarrow \sum_{k=-\infty}^{\infty} x[k] h[n-k] = y[n]$$

$$x(t) \longrightarrow \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau = y(t)$$

For causal systems, $h(t) = 0 \quad t < 0$
necessary & sufficient

Necessity: $\delta(t)$ is applied at $t = 0$
& hence $h(t)$ cannot be non zero for $t < 0$
for a causal system

Sufficiency: $h(t) = 0 \quad t < 0$

$$y(t) = \int_{-\infty}^{\infty} x(\tau) h(t - \tau) d\tau$$

$$= \int_{-\infty}^{t_0} x(\tau) h(t_0 - \tau) d\tau$$

$\Rightarrow y(t_0)$ depends only on i/p values
 $t \leq t_0$

Stability $|x(t)| \leq B_x$ bounded i/p

$$y(t) = \int_{-\infty}^{\infty} x(t-\tau) h(\tau) d\tau$$

$$|y(t)| = \left| \int_{-\infty}^{\infty} x(t-\tau) h(\tau) d\tau \right|$$

$$\leq \int_{-\infty}^{\infty} \underbrace{|x(t-\tau)|}_{\leq B_x} |h(\tau)| d\tau$$

$$|y(t)| \leq B_x \int_{-\infty}^{\infty} |h(\tau)| d\tau$$

For bounded o/p we require $\int_{-\infty}^{\infty} |h(\tau)| d\tau < \infty$

$$\sum_{k=-\infty}^{\infty} |h[k]| < \infty \quad \text{for DT systems}$$



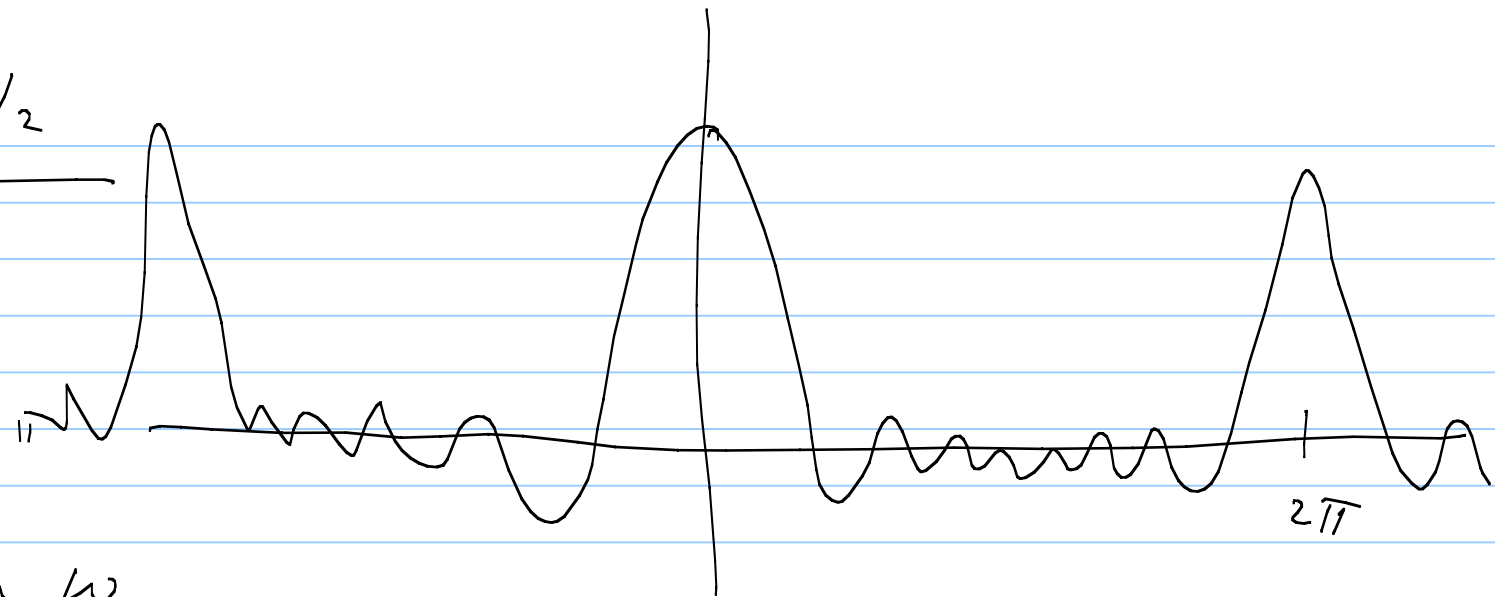
Sometimes also called analog sinc
non periodic

$$\frac{\sin(2N+1)\omega/2}{\sin \omega/2}$$

"digital sinc"

periodic in ω

ω /period 2π



Dirichlet kernel

Matlab: diric

Systems represented by Linear Const. Coeff.

Differential Equations (LCCDE) are a very
Diffuse

important class

EC 5142 22nd Aug. 2011

Note Title

22-08-2011

$$\frac{d^k}{dt^k} a_k e^{st} = a_k s^k e^{st}$$

$$\sum_{k=0}^N a_k \frac{d^k}{dt^k} y(t) = \sum_{l=0}^M b_l \frac{d^l}{dt^l} x(t)$$

Homogeneous soln is obtained by solving

$$\sum_{k=0}^N a_k \frac{d^k}{dt^k} y(t) = 0$$

$$\text{If } y(t) = e^{st}$$

$$e^{st} \left[\sum_{k=0}^N a_k s^k \right] = 0$$

$$\Rightarrow \sum_{k=0}^N a_k s^k = 0$$

If the roots are distinct,

$$y_h(t) = \sum_{k=1}^N c_k e^{s_k t}$$

C_k : are determined by the auxiliary conditions

$e^{s_k t}$: natural modes of the system

Recall.

$$Y_I e^{-at} + \frac{1}{a-b} \left[-e^{-at} + e^{-bt} \right] u(t)$$

For $Y_I = 0$, we get $-\underbrace{\frac{1}{a-b} e^{-at}}_{\text{natural mode}} + \underbrace{\frac{1}{a-b} e^{-bt}}_{\text{forced response}} \quad t \geq 0$

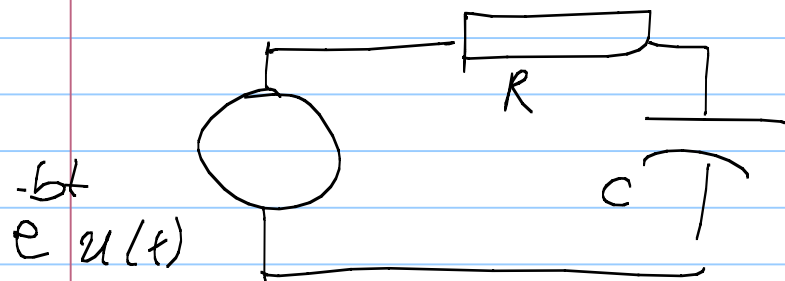
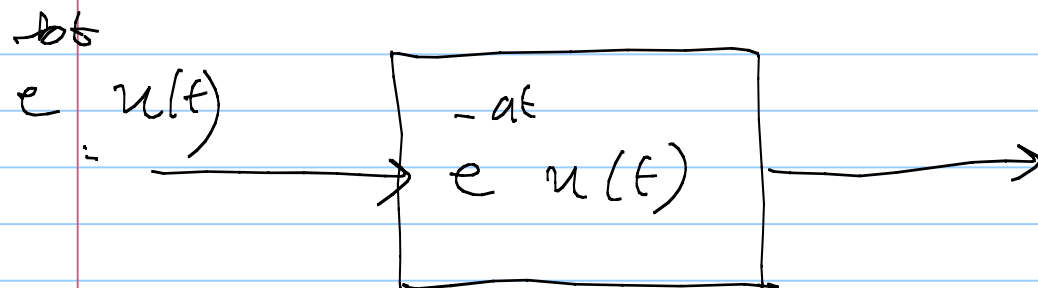
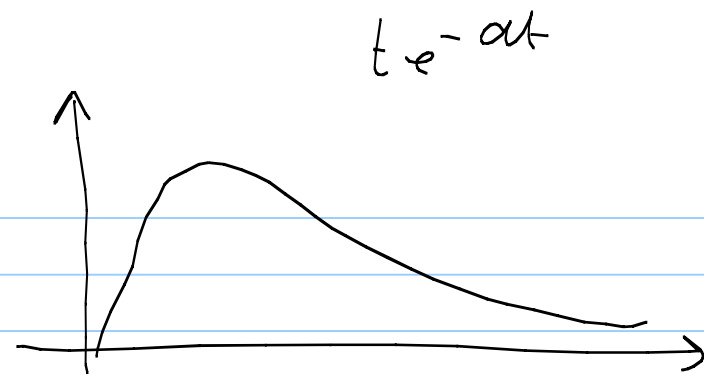
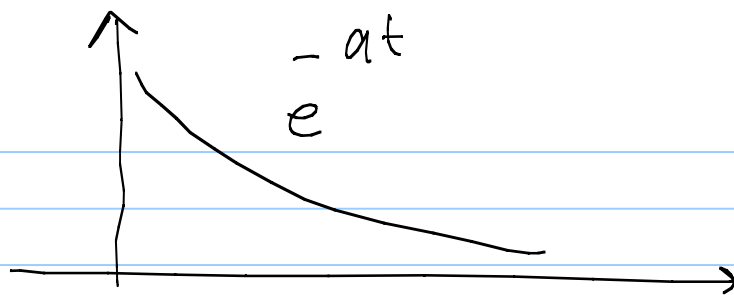
Repeated roots:

$$\text{Eg, } e^{st} (s+a)^2 = 0$$

Modes are: $c_1 e^{-at}$, $c_2 t e^{-at}$

For multiplicity 'r'

$$c_1 e^{-at}, c_2 t e^{-at}, c_3 t^2 e^{-at}, \dots, c_r t^{r-1} e^{-at}$$



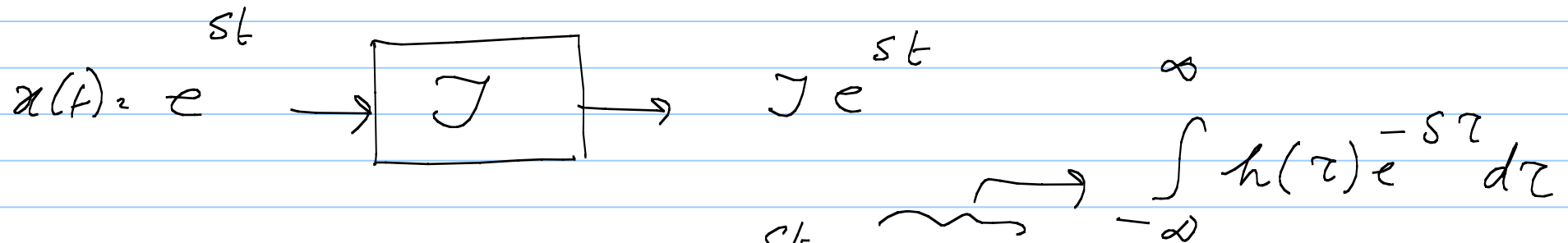
$$\frac{1}{a-b} \left[e^{-bt} - e^{-at} \right] u(t)$$

If $a = b$, soln is of the form $\underbrace{k e^{-at}}_{\text{natural mode}} + C \cdot t e^{-at}$

natural mode

$$\begin{aligned} e^{-at} u(t) * e^{-at} u(t) &= \int_0^t e^{-a\tau} e^{-a(t-\tau)} d\tau \\ &= e^{-at} \int_0^t d\tau \\ &= t e^{-at} u(t) \end{aligned}$$

Look up Lathi for zero-input & zero state responses.



For LTI: $y(t) = e^{st} H(s)$

$$= \lambda \cdot x(t)$$

Represented by $\underline{A} \underline{x} = \lambda \underline{x}$

Diagram showing a system block. The input is $x(t) = e^{j\Omega t}$. The output is $y(t) = e^{j\Omega t} \int_{-\infty}^{\infty} h(\tau) e^{-j\Omega\tau} d\tau$.

$H(j\Omega)$ is also denoted by $H(\Omega)$

↳ just notation

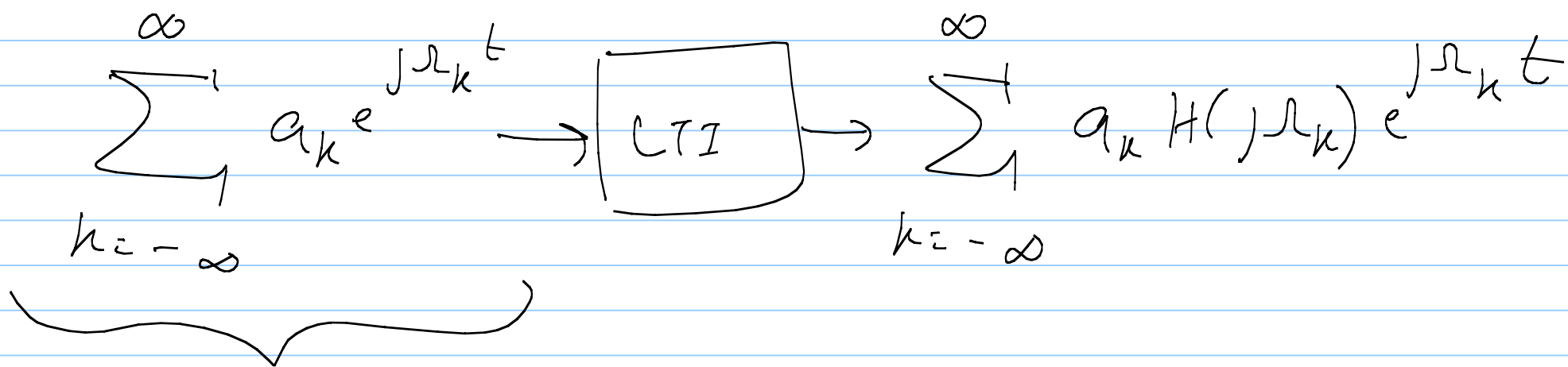
$$\overbrace{H(j\Omega)}$$

$$\sum_{k=1}^N a_k e^{s_k t} \longrightarrow \boxed{\text{LTI}} \longrightarrow \sum_{k=1}^N H(s_k) a_k e^{s_k t}$$

$$\sum_{k=1}^N a_k e^{j\Omega_k t} \longrightarrow \boxed{\text{LTI}} \longrightarrow \sum_{k=1}^N a_k (H(j\Omega_k)) e^{j\Omega_k t}$$

No new frequencies !!

We will assume

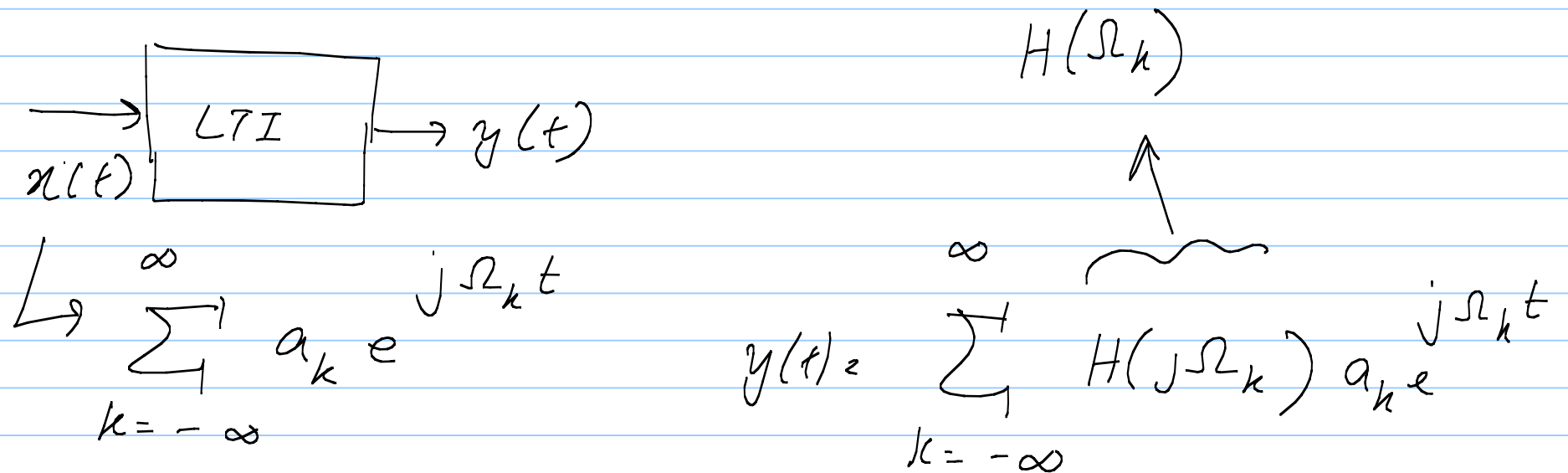
$$\sum_{k=-\infty}^{\infty} a_k e^{j\Omega_k t} \rightarrow \boxed{\text{LTI}} \rightarrow \sum_{k=-\infty}^{\infty} a_k H(j\Omega_k) e^{j\Omega_k t}$$


very powerful way of representing certain types of
 $x(t)$

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Note Title

23-08-2011



No new frequencies are introduced by an LTI system

If $x(t+T) = x(t)$, then

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\Omega_0 t}$$

$$\Omega_0 = \frac{2\pi}{T}$$

Fourier Series representation

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\Omega_0 t}$$

synthesis eqn

Inner product of $x(t)$ & $y(t)$: $\int_R x(t) y^*(t) dt$

$$\int_0^T x(t) \cdot e^{-j l \Omega_0 t} dt = \int_0^T \left[\sum_{k=-\infty}^{\infty} a_k e^{j k \Omega_0 t} \right] e^{-j l \Omega_0 t} dt$$

$$= \sum_{k=-\infty}^{\infty} a_k \int_0^T e^{j(k-l)\Omega_0 t} dt$$

$$= a_k \delta_{kl} T \quad \rightarrow \delta_{kl} = \begin{cases} 1 & k=l \\ 0 & k \neq l \end{cases}$$

$$= a_l T$$

$$a_l = \frac{1}{T} \int_0^T x(t) e^{-j l \Omega_0 t} dt$$

analysis
equation

$$\cos \Omega_0 t = \frac{1}{2} e^{j \Omega_0 t} + \frac{1}{2} e^{-j \Omega_0 t}$$

$$a_1 = \frac{1}{2} = a_{-1}$$

$$\sin \Omega_0 t : \quad a_1 = \frac{1}{2j} \quad a_{-1} = -\frac{1}{2j}$$

$$\cos \Omega_0 t + \sin^2 \Omega_0 t = \cos \Omega_0 t + \frac{1}{2}(1 - \cos 2\Omega_0 t)$$

$$= \cos \Omega_0 t + \underbrace{\frac{1}{2}}_{a_0} - \frac{1}{2} \cos 2\Omega_0 t$$

$$a_0 = \frac{1}{2}$$

$$a_2 = a_{-2} = -\frac{1}{4}$$

$$a_1 = \frac{1}{2} = a_{-1}$$

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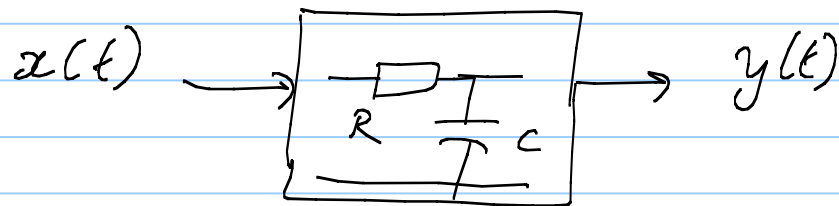
Note Title

24-08-2011

$$x(t) = \cos \Omega_0 t + \sin^2 \Omega_0 t$$

$$= \cos \Omega_0 t + \frac{1}{2} (1 - \cos 2\Omega_0 t)$$

$$a_0 = \frac{1}{2} \quad a_1 = a_{-1} = \frac{1}{2} \quad a_2 = a_{-2} = -\frac{1}{4}$$



$$h(t) = \frac{1}{RC} e^{-t/RC} u(t)$$

$$H(j\Omega) = \int_{-\infty}^{\infty} h(t) e^{-j\Omega t} dt = \frac{1}{1 + j\Omega RC}$$

$$y(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\Omega_0 t}$$

$$c_0 = a_0 H(j\Omega) \Big|_{\Omega=0} = \frac{1}{2}$$

$$c_1 = \frac{1}{2} \frac{1}{1 + j\Omega_0 RC} \quad c_{-1} = \frac{1}{2} \frac{1}{1 - j\Omega_0 RC}$$

$$C_2 = -\frac{1}{4} \frac{1}{1 + j2\Omega_0 RC} \quad C_{-2} = -\frac{1}{4} \frac{1}{1 - 2j\Omega_0 RC}$$

For real-valued $x(t)$, $x(t) = x^*(t)$

$$x^*(t) = \left[\sum_{k=-\infty}^{\infty} a_k e^{jk\Omega_0 t} \right]^*$$

$$= \sum_{k=-\infty}^{\infty} a_k^* e^{-jk\Omega_0 t}$$

$$= \sum_{k=-\infty}^{\infty} a_{-k}^* e^{jk\Omega_0 t}$$

$$= x(t)$$

$$\Rightarrow a_k = a_{-k}^* \Rightarrow |a_k| = |a_{-k}|$$

Again, for real-valued $x(t)$

$$x(t) = a_0 + \sum_{k=1}^{\infty} a_k e^{jk\Omega_0 t} + \sum_{k=1}^{\infty} a_{-k} e^{-jk\Omega_0 t}$$

$$= a_0 + \sum_{k=1}^{\infty} \left[a_k e^{jk\Omega_0 t} + a_k^* e^{-jk\Omega_0 t} \right]$$

$$a_k = A_k e^{j\theta_k}$$

$$= a_0 + \sum_{k=1}^{\infty} \left[A_k e^{j(k\Omega_0 t + \theta_k)} + A_k e^{-j(k\Omega_0 t + \theta_k)} \right]$$

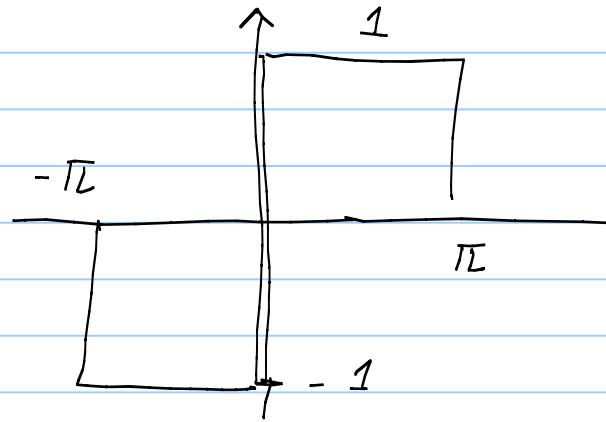
$$= a_0 + \sum_{k=1}^{\infty} 2A_k \cos(k\Omega_0 t + \theta_k)$$

$$A_k \cos(k\Omega_0 t + \theta_k) = \underbrace{A_k \cos \theta_k}_{B_k} \cos k\Omega_0 t - \underbrace{A_k \sin \theta_k}_{C_k} \sin k\Omega_0 t$$

$$x(t) = a_0 + \sum_{k=1}^{\infty} B_k \cos k\Omega_0 t - C_k \sin k\Omega_0 t$$

Eg:

$x(t)$



$$\Omega_0 = \frac{2\pi}{T} = \frac{2\pi}{2\pi} = 1$$

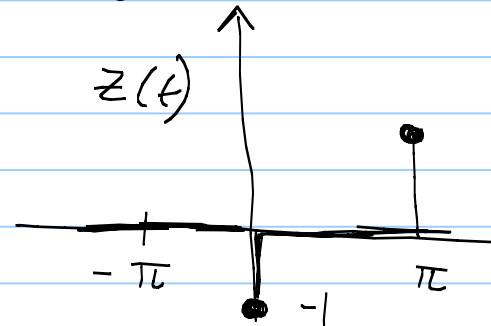
$$a_k = \frac{1}{T} \int_T x(t) e^{-j k \Omega_0 t} dt = \begin{cases} \frac{2}{j\pi k} & k \text{ odd} \\ 0 & k \text{ even} \end{cases}$$

$$x(t) = \frac{4}{\pi} \left[\sin t + \frac{1}{3} \sin 3t + \frac{1}{5} \sin 5t + \dots \right]$$

$$x(t) = \begin{cases} -1 & -\pi < t < 0 \\ 1 & 0 < t < \pi \end{cases}$$

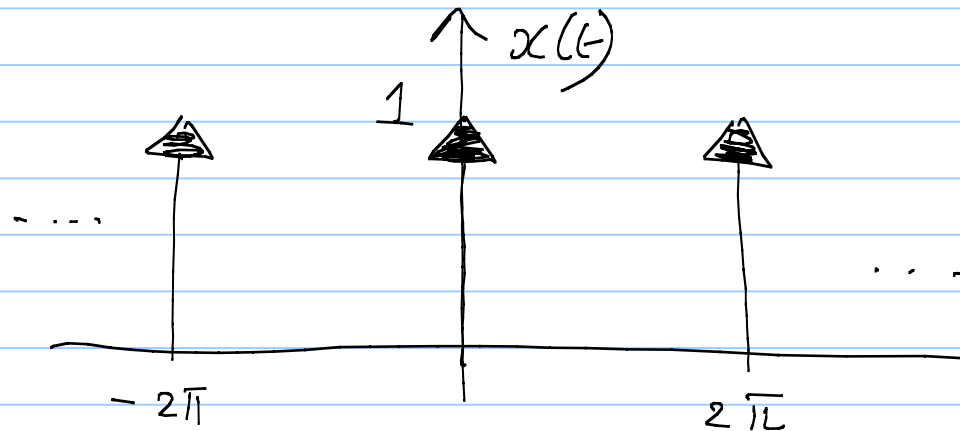
$$y(t) = \begin{cases} -1 & -\pi < t \leq 0 \\ 1 & 0 < t \leq \pi \end{cases}$$

$$y(t) = x(t) +$$



$y(t)$ has the same set of FS coeffs. as $x(t)$
 since $z(t)$'s FS coeffs. are ZERO.

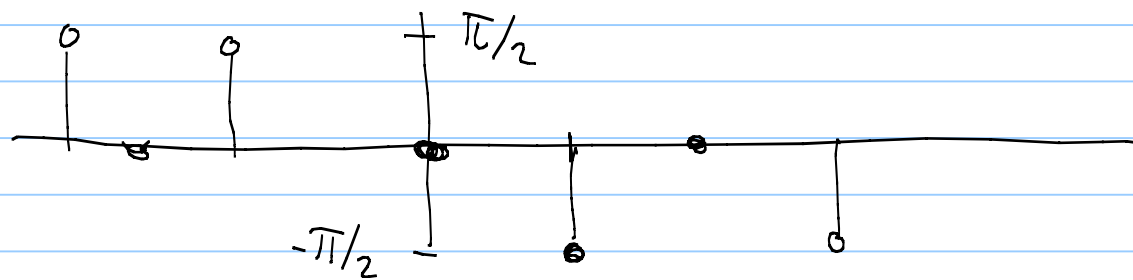
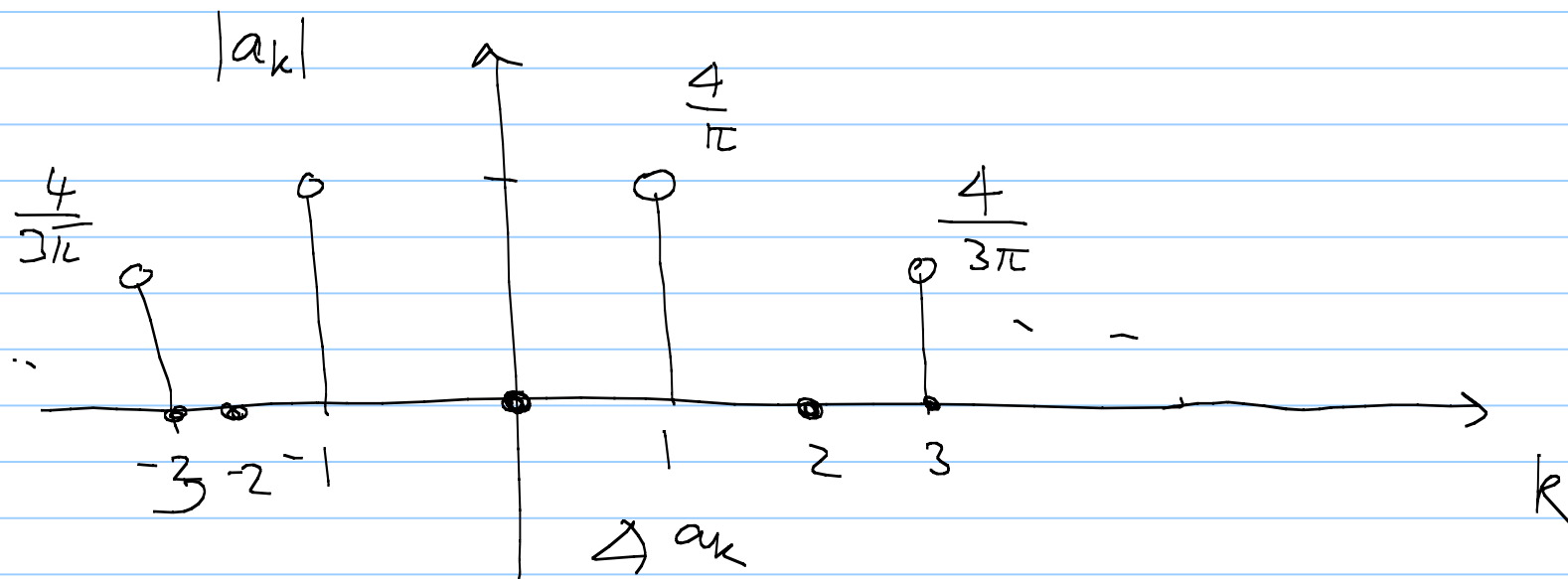
Eg!

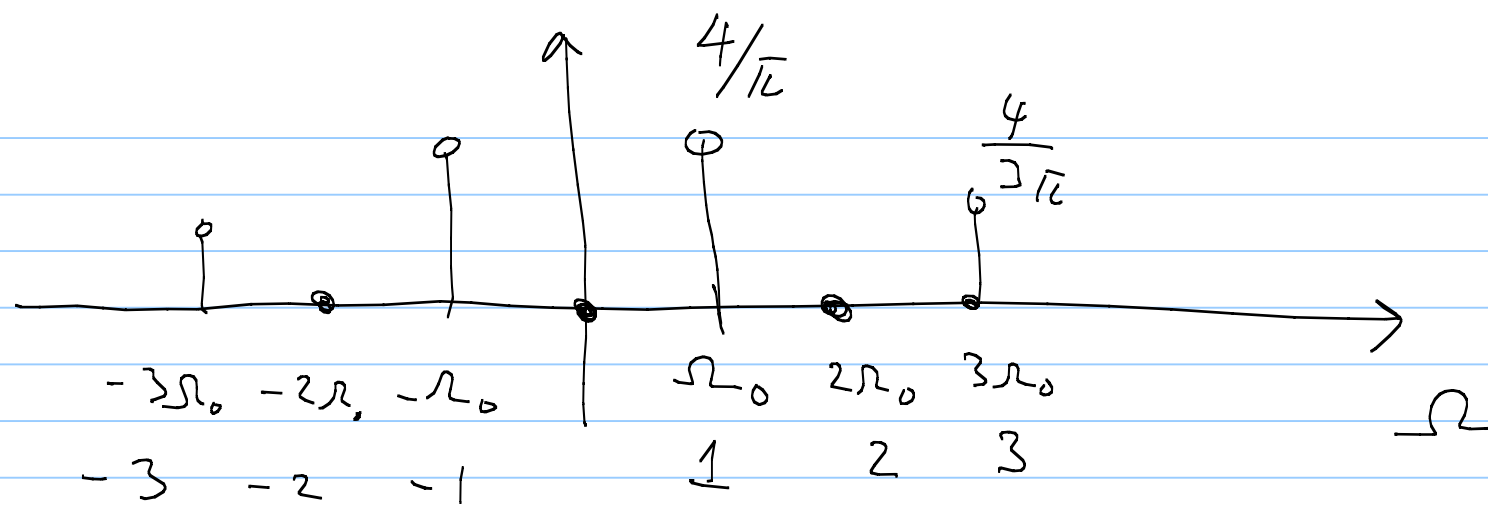


$$x(t) = \sum_{k=-\infty}^{\infty} \delta(t + 2k\pi)$$

$$a_k = \frac{1}{2\pi} \quad \forall k$$

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{j k \Omega_0 t}$$



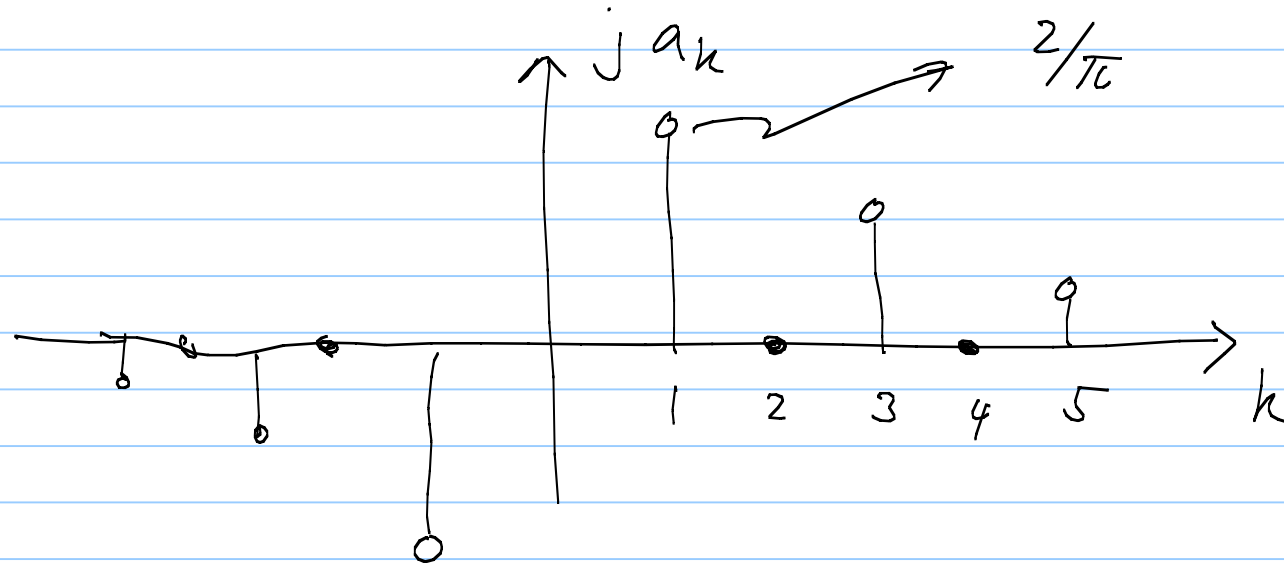


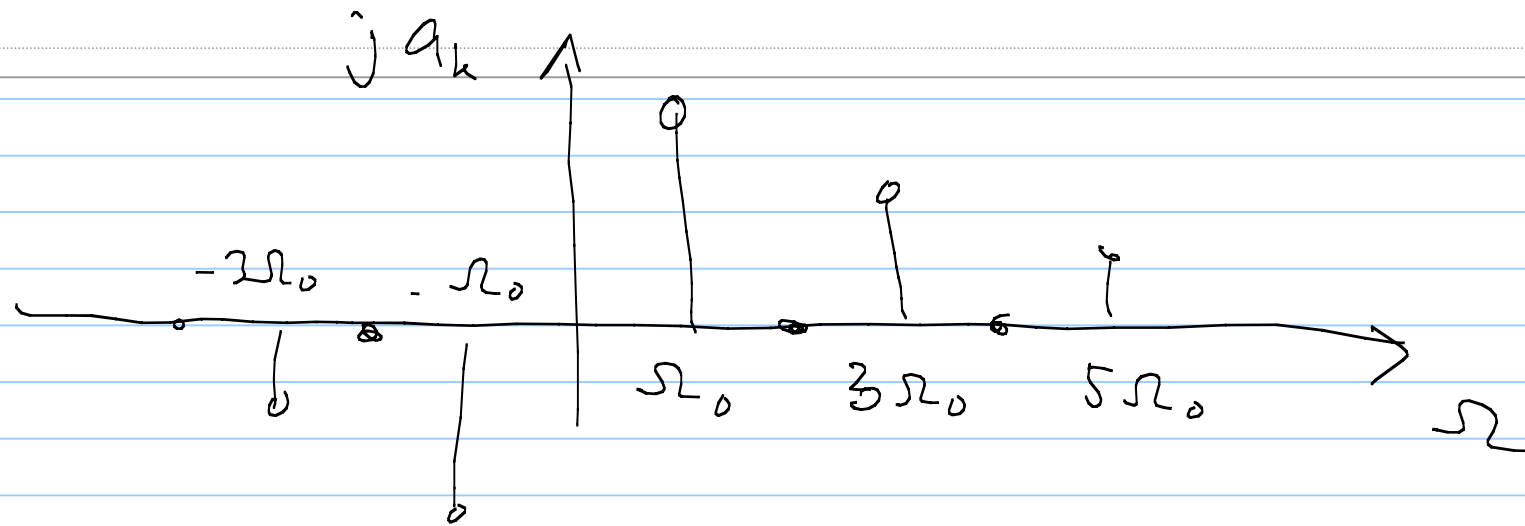
EC 5142 29th Aug. 2011

Note Title

29-08-2011

$$a_k^2 = \begin{cases} \frac{2}{j\pi k} & k \text{ odd} \\ 0 & k \text{ even} \end{cases}$$





Symmetry

$x(t)$ is real-valued

$$x(t) = \sum_{k=0}^{\infty} A_k \cos k\Omega_0 t - \sum_{k=1}^{\infty} B_k \sin k\Omega_0 t$$

Suppose $x(t)$ is even, i.e. $x(t) = x(-t)$

$$x(-t) = \sum_{k=0}^{\infty} A_k \cos k\Omega_0 t + \sum_{k=1}^{\infty} B_k \sin k\Omega_0 t$$

$$= x(t)$$

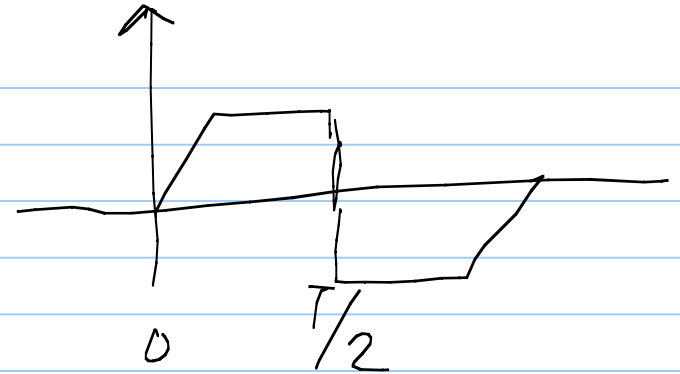
$$\Rightarrow B_k = 0$$

Suppose $x(t) = -x(-t)$ i.e. odd

$$\Rightarrow A_k = 0$$

Half wave (odd) symmetry

$$x(t + T/2) = -x(t)$$



$$\frac{1}{T} \int_0^{T/2} x(t) e^{-j k \Omega_0 t} dt + \underbrace{\frac{1}{T} \int_{T/2}^T x(t) e^{-j k \Omega_0 t} dt}_{t + T/2 = \lambda}$$

$$t + T/2 = \lambda$$

$$a_k = 0 \quad k = \text{even}$$

What about half wave even symmetry?

$$x(t + T/2) = x(t)$$

Properties

(1) Linearity $x_1(t+T) = x_1(t) \iff a_n$

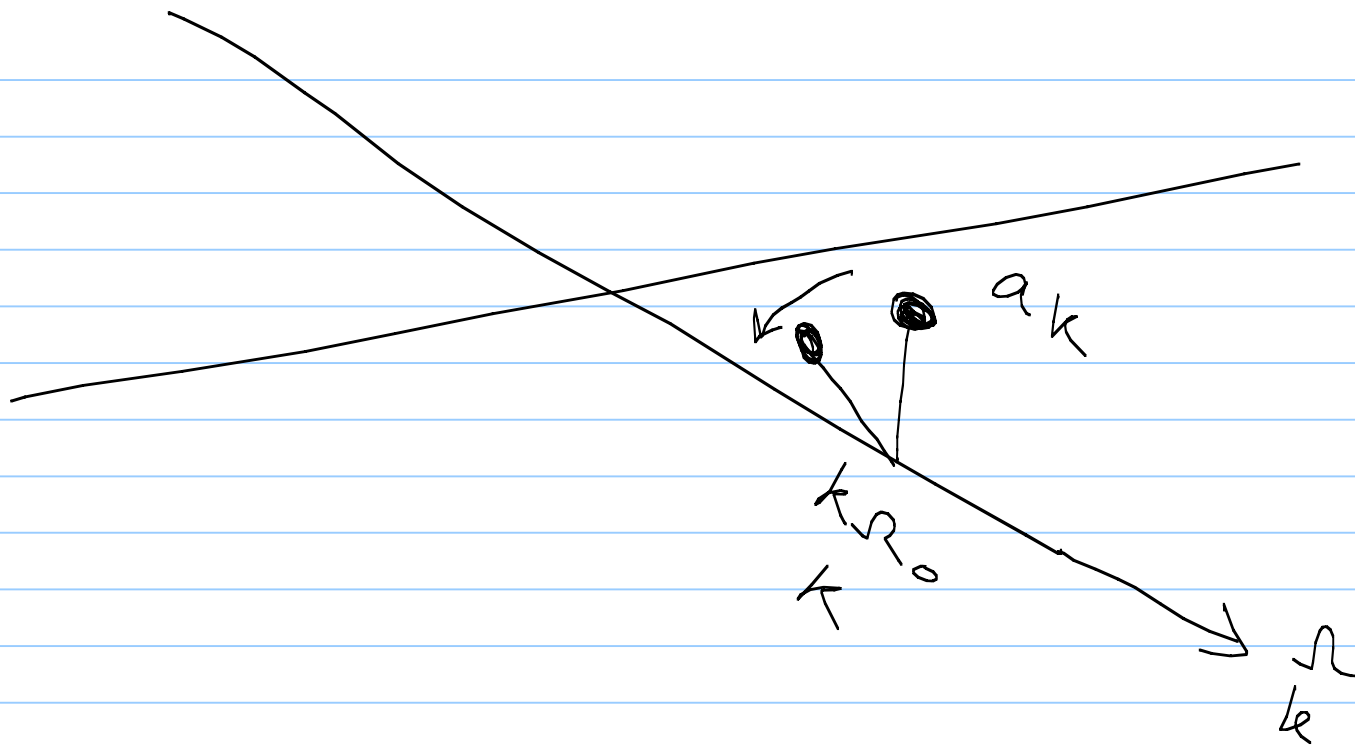
$x_2(t+T) = x_2(t) \iff b_k$

$$c_1 x_1(t) + c_2 x_2(t) \xleftrightarrow{FS} c_1 a_k + c_2 b_k$$

(2) Time Shift

$$y(t) = x(t - t_0) \xleftrightarrow{e^{-jk\Omega_0 t_0}} a_k = b_k$$

$$|b_k| = |a_k|$$



$$\begin{array}{ccc}
 y(t) & \longleftrightarrow & b_k \\
 (3) \quad = x(-t) & \longleftrightarrow & b_k = a_{-k}
 \end{array}$$

$$x(t) \text{ is real valued} \Rightarrow a_{-k} = a_k^*$$

$$x(t) \text{ is even} \Rightarrow a_{-k} = a_k$$

$$a_k = a_k^* = a_{-k} \quad \text{real \& even}$$

$$(4) \quad y(t) = x(ct)$$

$$x(t) = x(t + T_x)$$

$$y(t) = x(ct) = x(ct + T_x)$$

$$\begin{aligned} y\left(t - \frac{T_x}{c}\right) &= x\left(c\left(t - \frac{T_x}{c}\right) + T_x\right) \\ &= x(ct) \end{aligned}$$

$$\Rightarrow T_y = \frac{T_x}{c}$$

$$b_k = \frac{1}{T_y} \int_0^{T_y} y(t) e^{-j k \frac{2\pi}{T_y} t} dt$$

$$= \frac{1}{T_y} \int_0^{T_y} x(ct) e^{-j k \frac{2\pi}{T_y} t} dt$$

Letting $ct = \lambda$, we get

$$b_k = \frac{1}{T_y} \int_0^{T_y} y(t) e^{-j k \frac{2\pi}{T_y} t} dt = a_k$$

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Time Scaling:

$$y(t) = x(ct)$$

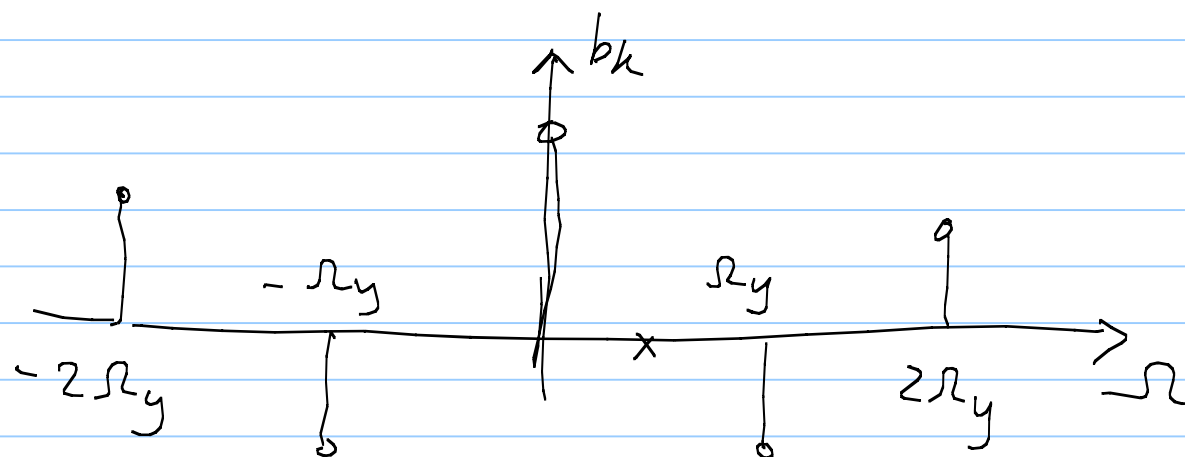
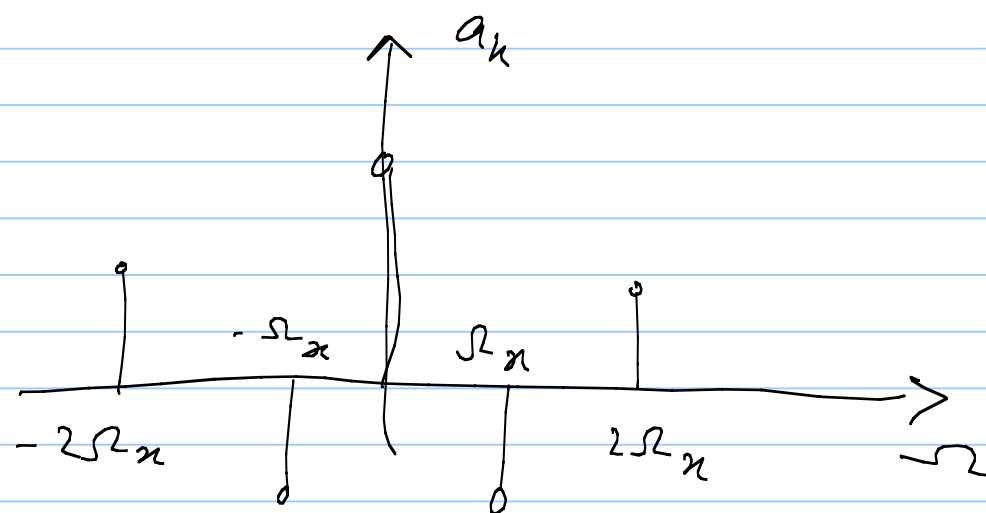
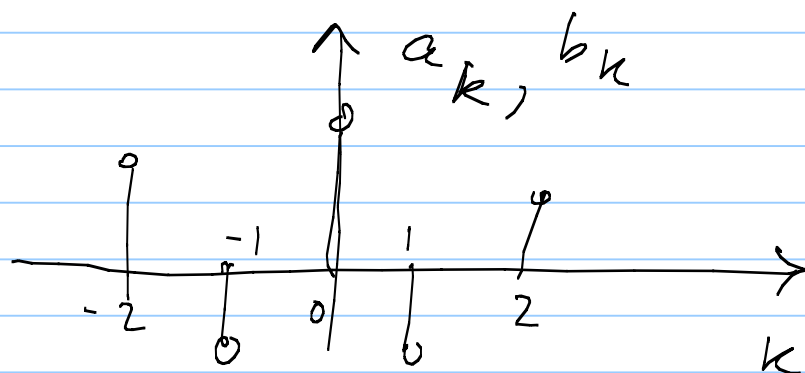
$$y(t) \longleftrightarrow b_k \quad \text{period } T_y$$

$$x(t) \longleftrightarrow a_k \quad \text{period } T_x$$

$$T_y = \frac{T_x}{c}$$

$$\Omega_y = c \Omega_x$$

$$b_k = a_k$$



Multiplication in the time domain

$$x(t) y(t) \longleftrightarrow ?$$

$$\frac{1}{T} \int_T \left[\sum_{k=-\infty}^{\infty} a_k e^{jk\Omega_0 t} \right] \left[\sum_{l=-\infty}^{\infty} b_l e^{jl\Omega_0 t} \right] e^{-jm\Omega_0 t} dt$$

$$= \frac{1}{T} \int_T \left[\sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} a_k b_l e^{j(k+l)\Omega_0 t} \right] e^{-jm\Omega_0 t} dt$$

Let $k + l = r$ & simplify

$$x(t) y(t) \longleftrightarrow a_k * b_k$$

Convolution in the time domain

$$\mathcal{Z}\{x(t) \otimes y(t)\} \longleftrightarrow a_k \cdot b_k$$

$$z(t) = \int_T x(\tau) y(t-\tau) d\tau$$

Differentiation:

$$x(t) \longleftrightarrow a_k$$

$$x'(t) \longleftrightarrow$$

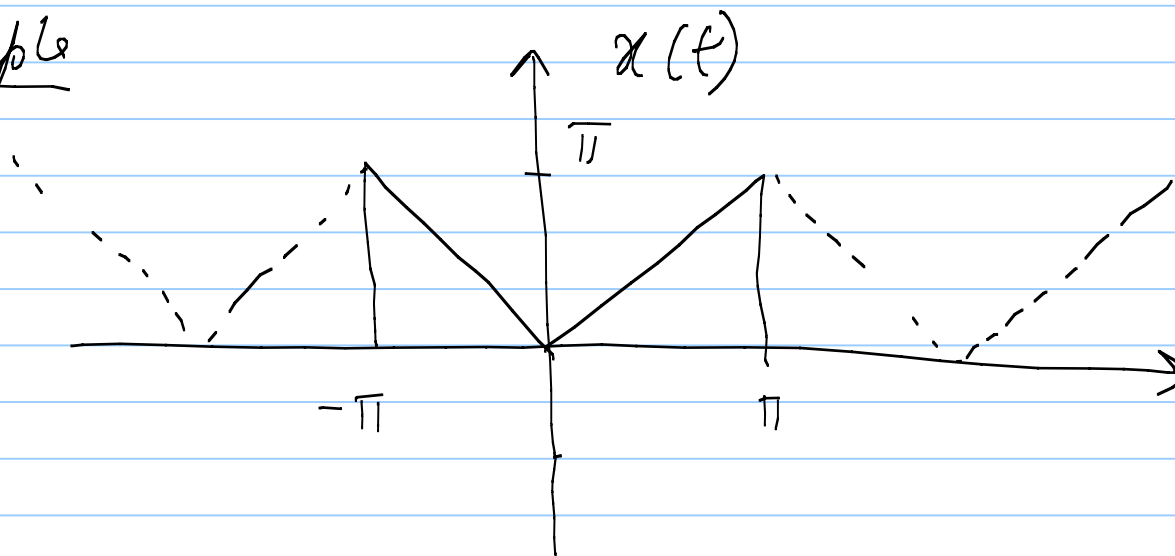
$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\Omega_0 t}$$

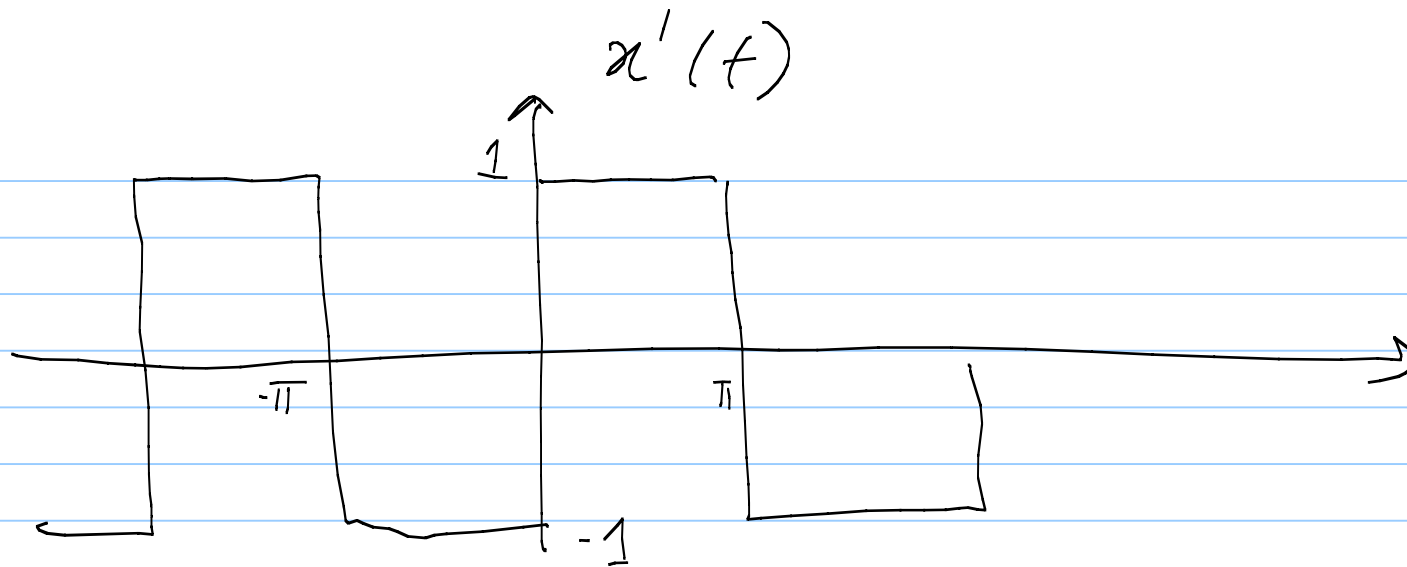
$$\frac{dx}{dt} = \frac{d}{dt} \left[\sum_{k=-\infty}^{\infty} a_k e^{jk\Omega_0 t} \right]$$

$$\stackrel{?}{=} \sum_{k=-\infty}^{\infty} jk\Omega_0 a_k e^{jk\Omega_0 t}$$

$$x'(t) \longleftrightarrow jk\Omega_0 a_k$$

Example





$$x'(t) \longleftrightarrow \begin{cases} \frac{2}{j k \pi} & k \text{ odd} \\ 0 & k \text{ even} \end{cases}$$

$$x(t) \longleftrightarrow a_k$$

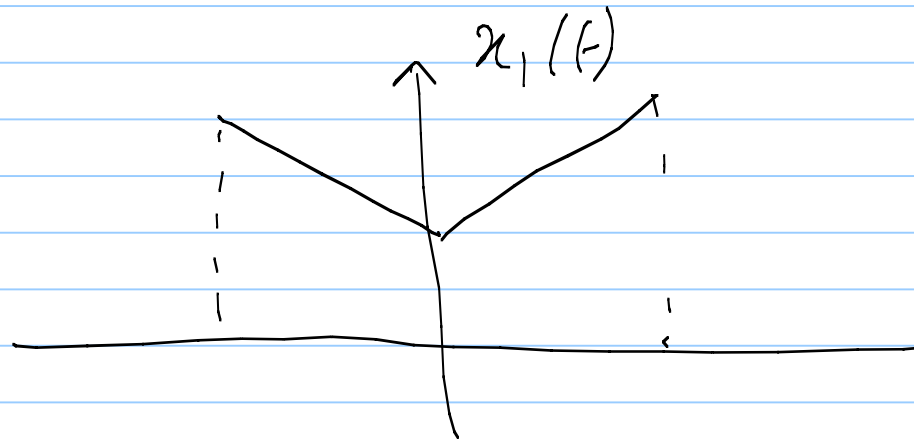
$$x'(t) \longleftrightarrow jk\Omega_0 a_k = b_k$$

$$b_k = \begin{cases} \frac{2}{jk\pi} & k = \text{odd} \\ 0 & k = \text{even} \end{cases}$$

$$a_k = \frac{2}{jk\pi \cdot jk\Omega_0} \quad k \text{ odd}$$

$$= \frac{-2}{\pi \Omega_0 k^2} \quad k \neq 0 \quad \Omega_0 = 1$$

Now consider



$$x_1'(t) = x'(t)$$

Hence a_0 has to be computed separately

If the N^{th} derivative of $x(t)$ becomes
impulsive, then the FS coefficients decay
as $\frac{1}{k^N}$

Integration

$$\int_{-\infty}^t x(\tau) d\tau \longleftrightarrow \begin{array}{ll} \frac{a_k}{jk\Omega_0} & k \neq 0 \\ a_0 & = 0 \end{array}$$

Parseval's Relation

$$\frac{1}{T} \int_T |x(t)|^2 dt = \sum_{k=-\infty}^{\infty} |a_k|^2$$

$$\begin{aligned} & \frac{1}{T} \int_T x(t) x^*(t) dt \\ &= \frac{1}{T} \int_T \left[\sum_{k=-\infty}^{\infty} a_k e^{jk\Omega_0 t} \right] \left[\sum_{l=-\infty}^{\infty} a_l^* e^{-jl\Omega_0 t} \right] dt \end{aligned}$$

$$11. \quad \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} a_k a_l^* \frac{1}{T} \int_T e^{j(k-l)\omega_0 t} dt$$

$$= \sum_{k=-\infty}^{\infty} |a_k|^2$$

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For Fourier series, the basis functions were
 $e^{jk\Omega_0 t}$
 $k = 0, \pm 1, \pm 2, \dots$

Generalized FS expansion:

$$x(t) = \sum_k a_k \phi_k(t)$$

$$\langle x(t), \phi_\ell \rangle = \sum_k a_k \langle \phi_k(t), \phi_\ell(t) \rangle$$

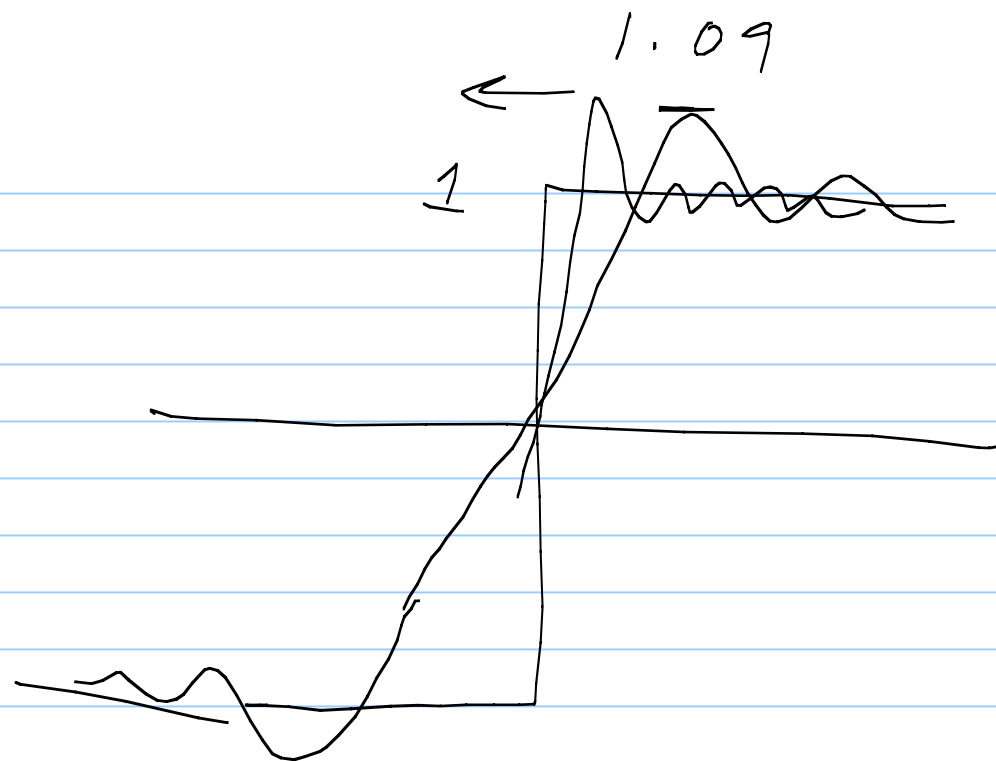
$$\text{if } \langle \phi_k(t), \phi_\ell(t) \rangle = \delta_{k\ell}$$

$$a_\ell = \langle x(t), \phi_\ell(t) \rangle$$

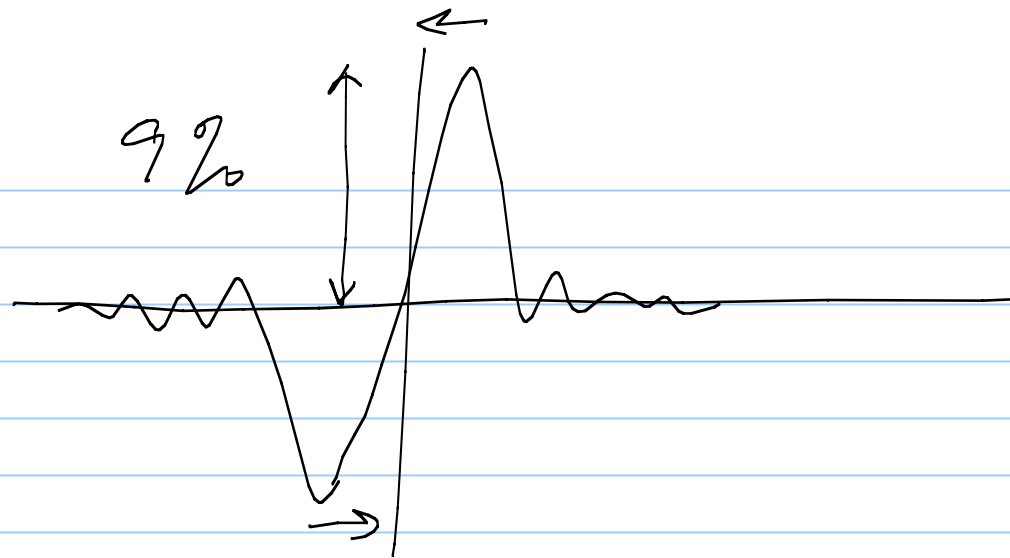
$$\langle p(t), q(t) \rangle = \int_{\mathbb{R}} p(t) q^*(t) dt$$

For the Fourier basis $\langle e^{jk\Omega_0 t}, e^{jl\Omega_0 t} \rangle = T \delta_{kl}$

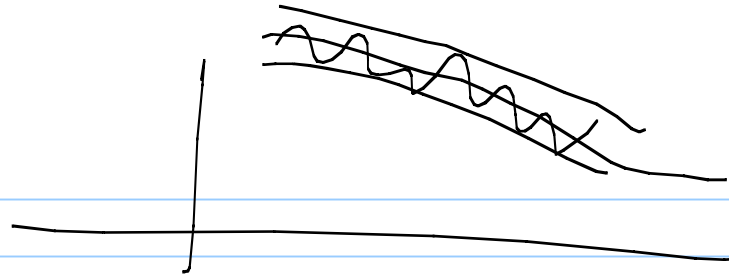
Convergence Does FS expansion converge?
How does it converge?



$$x_N(t) = \sum_{k=-N}^N a_k e^{jk\Omega_0 t}$$



$x_n(t)$ as $n \rightarrow \infty$, will not converge to
 $x(t)$ pointwise



$$e(t) \not\rightarrow 0 \quad \forall t$$

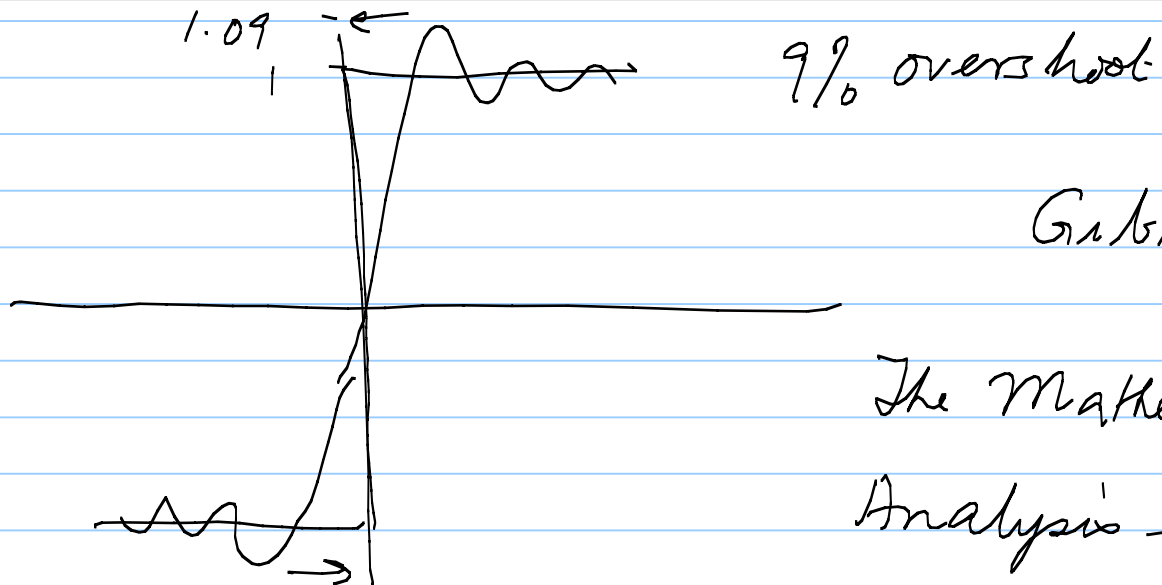
$$\frac{1}{T} \int_T |e(t)|^2 dt \rightarrow 0$$

Mean Square convergence

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Gibbs phenomenon

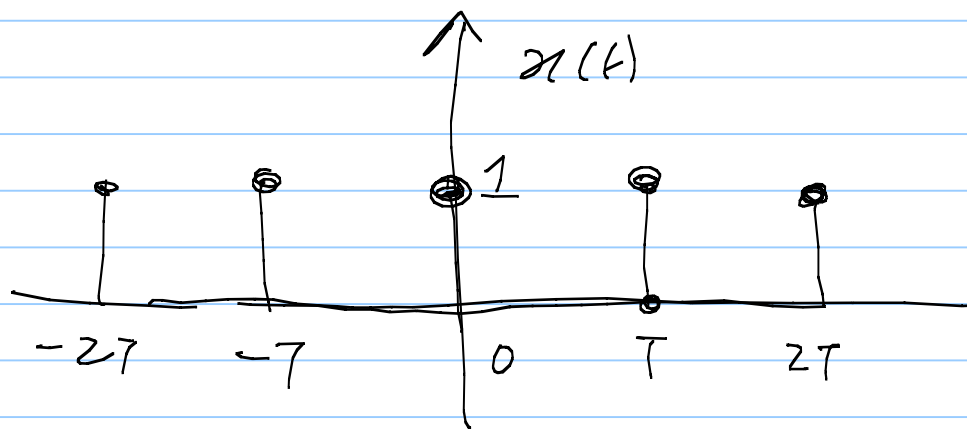
The Mathematics of Circuit
Analysis - E.A. Guillermo
pp. 485 - 496

$$x_N(t) = \sum_{k=-N}^N a_k e^{jk\Omega_0 t}$$

$$x(t) - x_N(t) = e_N(t) \not\rightarrow 0 \text{ as } N \rightarrow \infty$$

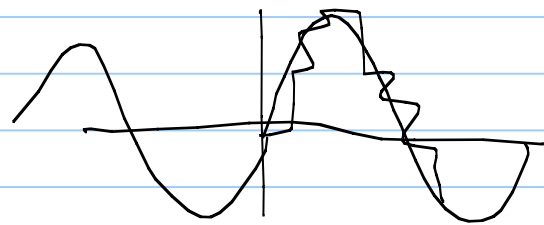
$$\frac{1}{T} \int_T |e_N(t)|^2 dt \rightarrow 0 \text{ as } N \rightarrow \infty$$

$\Rightarrow$ convergence is in the mean-square sense

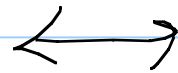
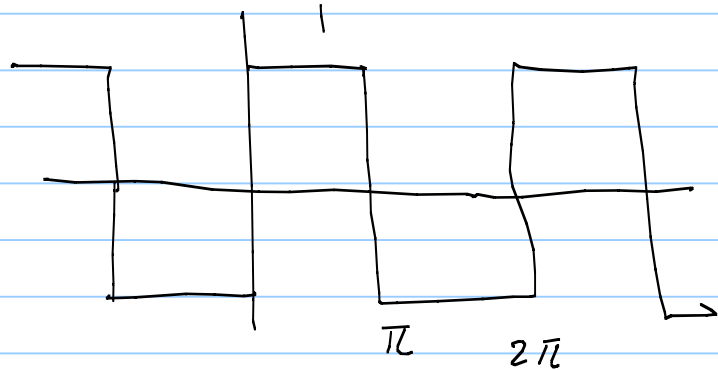


$$a_k = 0$$

Look up Dirichlet's conditions



$$a_1 = \frac{1}{2j}; \quad a_{-1} = a_1^*$$



$$\frac{4}{\pi} \left\{ \sin t + \frac{1}{3} \sin 3t + \frac{1}{5} \sin 5t + \dots \right\}$$

"On Bandwidth" - David Slepian
 Proc. IEEE 1977

$$x[n] = x[n+N]$$

$$e^{j k \Omega_0 n}$$

$$\Omega_0 = \frac{2\pi}{N}$$

$$= e^{j k \frac{2\pi}{N} n}$$

$$e^{j k \frac{2\pi}{N} n}$$

$$\phi_k[n] = e$$

$$= \phi_{k+N}[n]$$

$$x[n] = \sum_{k=0}^{N-1} a_k e^{j k \frac{2\pi}{N} n}$$

$$\langle x[n], \phi_l[n] \rangle = \sum_{k=0}^{N-1} a_k e^{j \frac{k 2\pi}{N} n} \cdot e^{-j \frac{l 2\pi}{N} n}$$

$$\sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi}{N} l k} = N a_l$$

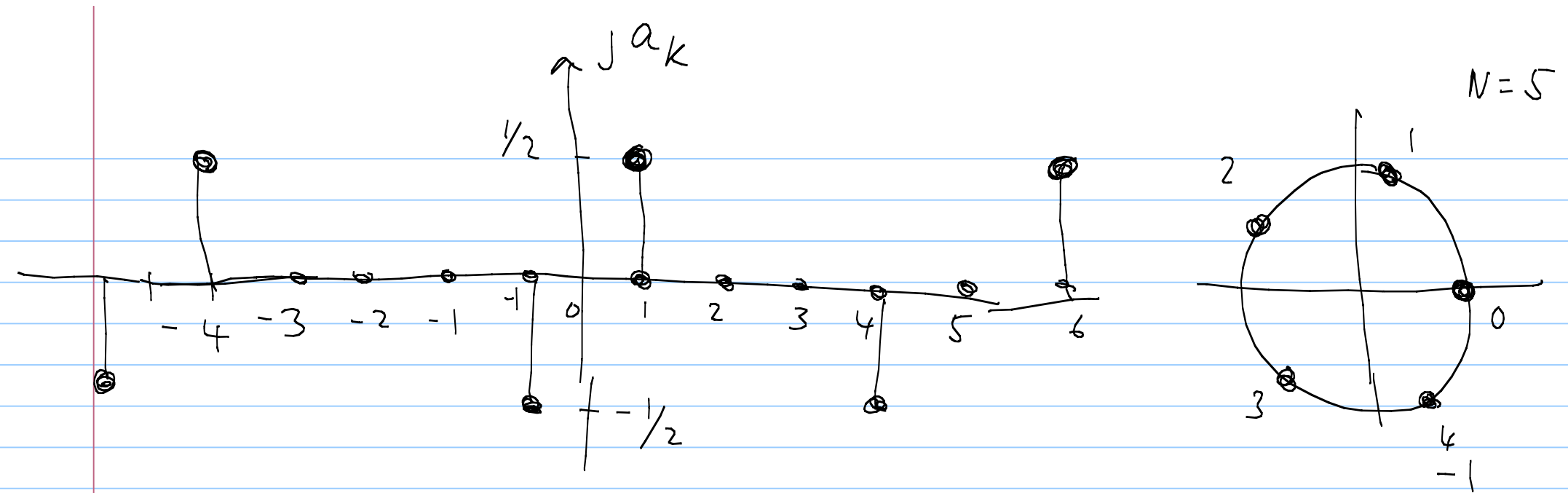
$$a_l = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-j l \frac{2\pi}{N} n}$$

$$= a_{l+N}$$

Eg

$$\text{Sim } \frac{2\pi}{N} n \leftrightarrow a_1 = \frac{1}{2j} = a_{-1}^* \Rightarrow a_{-1} = \frac{-1}{2j}$$

$N=5$

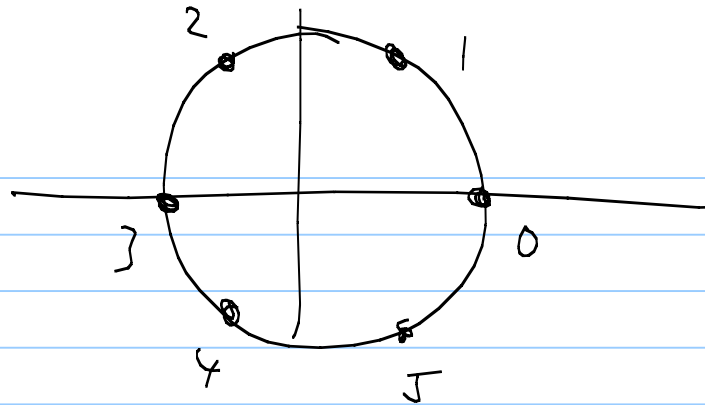


Eq 1

$$\sin 3 \frac{2\pi}{5} n = \sin \left(1 - 2/5\right) \frac{2\pi}{5} n$$

$$= - \sin 2 \frac{2\pi}{5} n$$

$$\underline{N=6}$$



Properties

(1) Linearity

$$(2) \quad x[n - n_0] \xleftrightarrow{\text{DFTS}} a_k e^{-j k \frac{2\pi n_0}{N}}$$

$$(3) \quad x[n] y[n] \longleftrightarrow a_k \otimes_N b_k$$

$$(4) \quad x[n] \otimes_N y[n] \longleftrightarrow N \cdot a_k \cdot b_k$$

$$(5) \quad e^{j l \frac{2\pi}{N} n} x[n] \longleftrightarrow a_{k-l}$$

$$(6) \quad \frac{1}{N} \sum_{n=0}^{N-1} |x[n]|^2 = \sum_{k=0}^{N-1} |a_k|^2$$

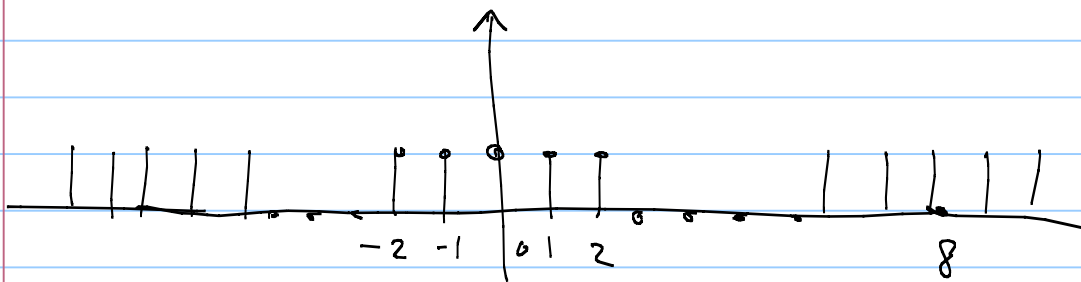
Think about time scaling.

$$x[2n] \text{ \& \ } x[n]$$

Then FS coefficients are not related, in general.

$$y[n] = \begin{cases} x\left[\frac{n}{m}\right] & n = 0, \pm m, \pm 2m, \dots \\ 0 & \text{otherwise} \end{cases}$$

What is the relationship between FS
coeff. z $x[n]$ & $y[n]$?



$$a_k = \frac{1}{8} \sum_{n=-2}^2 1 \cdot e^{-j k \frac{2\pi}{8} n}$$

$$= \frac{1}{8} \frac{\sin \frac{5\pi k}{8}}{\sin \frac{\pi k}{8}}$$

For $N=32$

$$a_k = \frac{1}{32} \frac{\sin 5\pi k/32}{\sin \pi k/32}$$

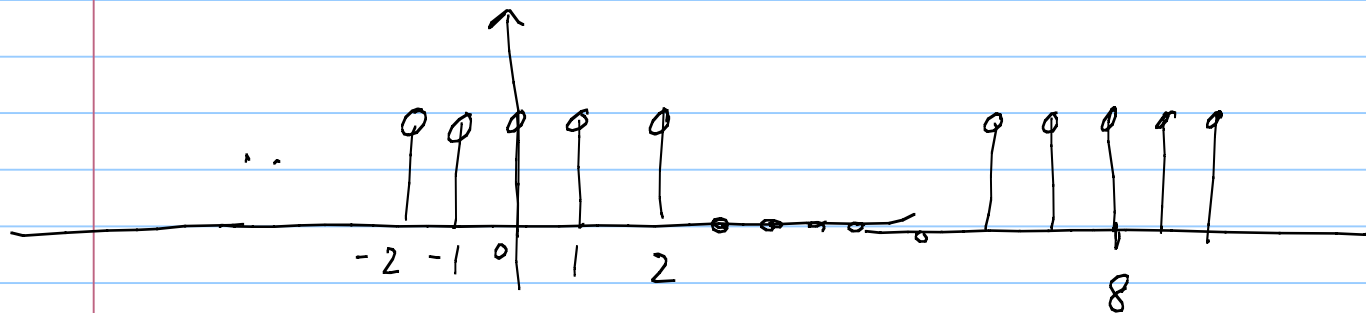
Plot a_k vs k

a_k vs. frequency

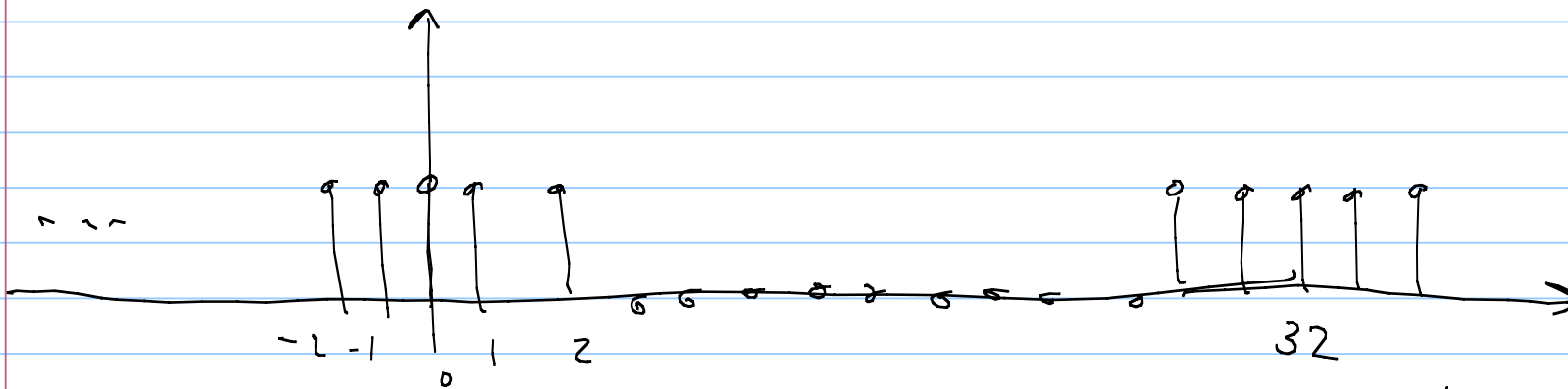
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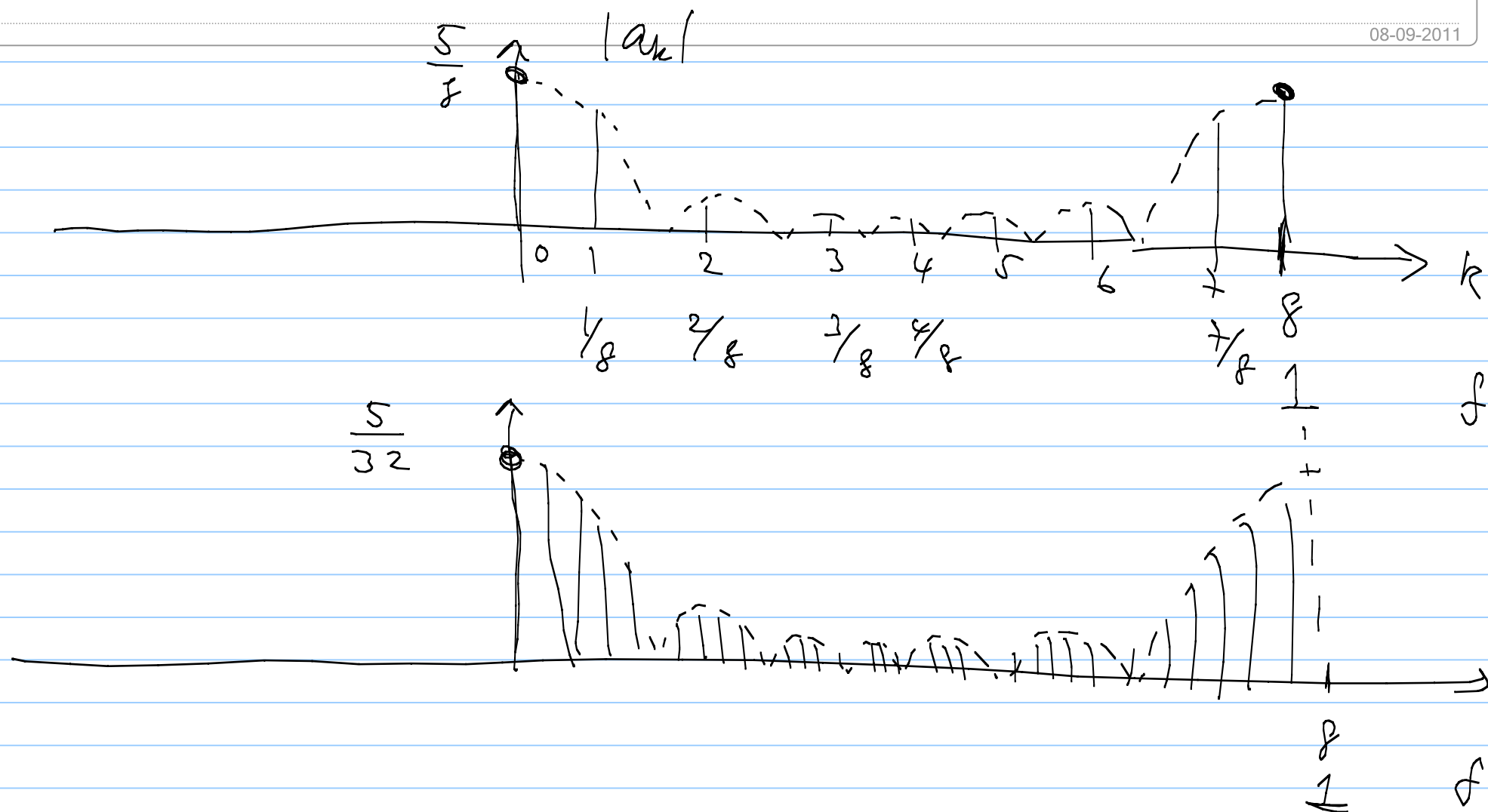
08-09-2011



$$a_k = \frac{1}{8} \frac{\sum_{k=-2}^2 \frac{5\pi k}{8}}{\sum_{k=-2}^2 \frac{\pi k}{8}}$$



$$a_k = \frac{1}{32} \frac{\sum_{k=-2}^2 \frac{5\pi k}{32}}{\sum_{k=-2}^2 \frac{\pi k}{32}}$$



DFT

$x[n]$ given for $n=0, 1, \dots, N-1$

$$X[k] \stackrel{\text{def}}{=} \sum_{n=0}^{N-1} x[n] e^{-j 2\pi k n / N}$$

$\nwarrow$ k^{th} DFT coefficient

DFT

$$X[k+N] = X[k]$$

$X[k]$ need to be considered only for $k=0, 1, \dots, N-1$

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j \frac{2\pi k n}{N}} \quad \text{IDFT}$$

$$x[n+N] = x[n]$$

Recall:

$$x[n] = \sum_{k=0}^{N-1} a_k e^{j \frac{2\pi k n}{N}}$$

Where $x[n+N] = x[n]$

$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi k n}{N}}$$

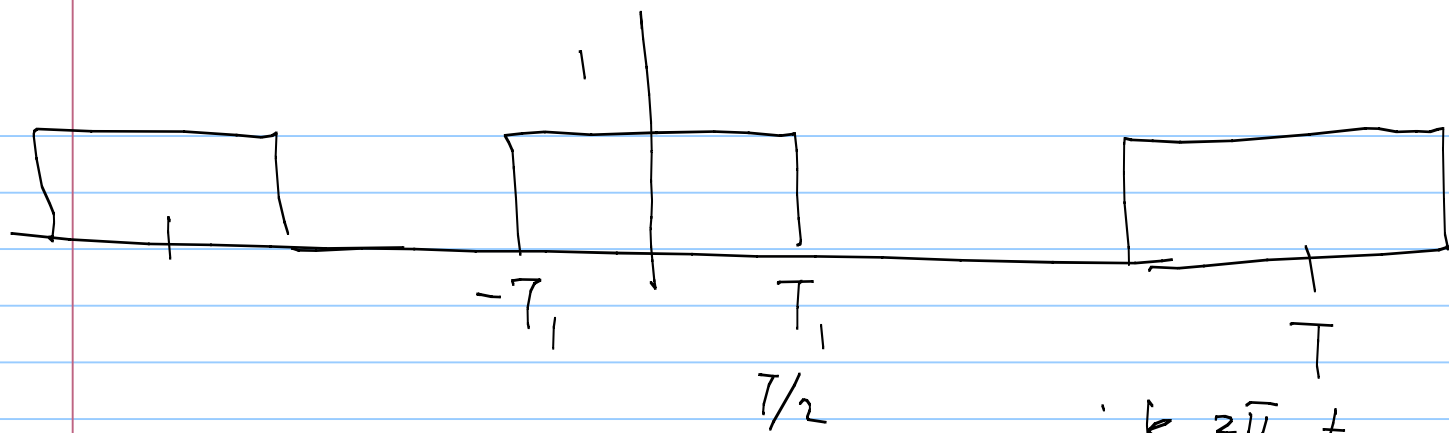
$$N a_k = \sum_{n=0}^{N-1} x[n] e^{-j 2\pi k n / N} = X[k]$$

$$x(t + T) = x(t)$$

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{-j k \Omega_0 t} \quad \Omega_0 = 2\pi / T$$

$$a_k = \frac{1}{T} \int_T x(t) e^{+j k \omega_0 t} dt$$





$$a_k = \frac{1}{T} \int_{-T/2}^{T/2} 1 \cdot e^{-j k \frac{2\pi}{T} t} dt$$

$$= \frac{1}{T} \int_{-T_1}^{T_1} e^{-j k \frac{2\pi}{T} t} dt = \frac{1}{T} \frac{\sin \frac{2\pi k T_1}{T}}{k \pi / T}$$

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DFS & DTFS (Cont'd)

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-jk \frac{2\pi}{N} n} \quad k = 0, 1, \dots, N-1$$

$$x[n] = \frac{1}{N} \sum_{k=0}^{N-1} X[k] e^{j \frac{2\pi}{N} kn}$$

We can also define with $\frac{1}{\sqrt{N}}$ scale factor for

both DFT & IDFT

$$X[k] = \frac{1}{\sqrt{N}} \sum_{n=0}^{N-1} x[n] e^{-j k \frac{2\pi}{N} n}$$

$$x[n] = \frac{1}{\sqrt{N}} \sum_{k=0}^{N-1} X[k] e^{+j k \frac{2\pi}{N} n}$$

DTFS

$$x[n+N] = x[n]$$

$$x[n] = \sum_{k=0}^{N-1} a_k e^{j k \frac{2\pi}{N} n}$$

$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi}{N} nk}$$

$$X[k] = N a_k$$

$$y[n] = x[n]$$

Find FS coeffs of $y[n]$ & relate them to $x[n]$

$\Rightarrow$ Duality property

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j k \frac{2\pi}{N} n} \quad k = 0, 1, \dots, N-1$$

$$\begin{bmatrix}
 1 & 1 & 1 & \dots & 1 \\
 1 & e^{-j \frac{2\pi}{N}} & e^{-j 1 \cdot \frac{2\pi}{N} 2} & \dots & e^{-j 1 \cdot \frac{2\pi}{N} (N-1)} \\
 & \uparrow & & & \\
 & e^{-j k \frac{2\pi}{N} n} & & & \\
 \leftarrow & & \xrightarrow{n: 0 \rightarrow N-1} & & \\
 & \downarrow k = 0 \rightarrow (N-1) & & & \\
 1 & e^{-j (N-1) \frac{2\pi}{N} 1} & \dots & e^{-j (N-1) \frac{2\pi}{N} (N-1)} &
 \end{bmatrix}
 \begin{bmatrix}
 x[0] \\
 x[1] \\
 x[2] \\
 \vdots \\
 x[N-1]
 \end{bmatrix}
 =
 \begin{bmatrix}
 X[0] \\
 X[1] \\
 \\
 \\
 X[N-1]
 \end{bmatrix}$$

$N \times N$

$$\underline{W}_N \underline{x} = \underline{X}$$

$$N \times N \quad N \times 1 \quad N \times 1$$

$$e^{-j k \frac{2\pi}{N} n} = W_N^{nk}$$

$$\underline{x} = \underline{W}_N^{-1} \underline{X} = \frac{1}{N} \underline{W}_N^H \underline{X}$$

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$$\begin{array}{ccccc} \underline{X} & = & \underline{W} & \underline{x} \\ N \times 1 & & N \times N & & N \times 1 \end{array}$$

$$\underline{W} \equiv \frac{W}{N}$$

$$\underline{x} = \underline{W}^{-1} \underline{X}$$

$$\underline{W}^{-1} = \frac{1}{N} \underline{W}^H$$

$$\underline{W} =$$

$$\left[\begin{array}{c} \uparrow \\ -j k \frac{2\pi n}{N} \\ \leftarrow e \rightarrow n \\ \downarrow k \end{array} \right]$$

$$\underline{x}^H \underline{x} = \sum_{n=0}^{N-1} |x[n]|^2$$

$$\underline{X}^H \underline{X} = (\underline{W} \underline{x})^H (\underline{W} \underline{x})$$

$$= \underline{x}^H \underline{W}^H \underline{W} \underline{x}$$

$$= \underline{x}^H N \underline{W}^{-1} \underline{W} \underline{x}$$

$$= N \underline{x}^H \underline{x}$$

$$\underline{x}^H \underline{x} = \frac{1}{N} \underline{X}^H \underline{X}$$

In DTFS, for real-valued $x[n]$

$$a_{-k} = a_k^*$$

$$a_{-k} = a_{N-k}$$

For DFT, $X[-k] = X^*[k]$

$$X[-k] = X[N-k]$$

Notation to show periodicity explicitly:

$$x[n] \equiv x[\langle n \rangle_N]$$

$$\langle n \rangle_N \equiv n \bmod N$$

$$x_k \equiv x[k]$$

$$x[0] = x[N] = x[-N] = x[2N] = x[-2N] = \dots$$

$$x[-1] = x[N-1]$$

$$X[0] = X[N]$$

$$X[-1] = X[N-1]$$

$$x[-n] = x[N-n]$$

$$x[n] \otimes h[n] = \sum_{k=0}^{N-1} x[k] h[n-k] = y[n]$$

$$y_0 = x_0 h_0 + x_1 h_{-1} + x_2 h_{-2} + \dots + x_{N-1} h_{-(N-1)}$$

$\equiv h_{N-1} \qquad \qquad \qquad \equiv h_{N-2} \qquad \qquad \qquad \equiv h_1$

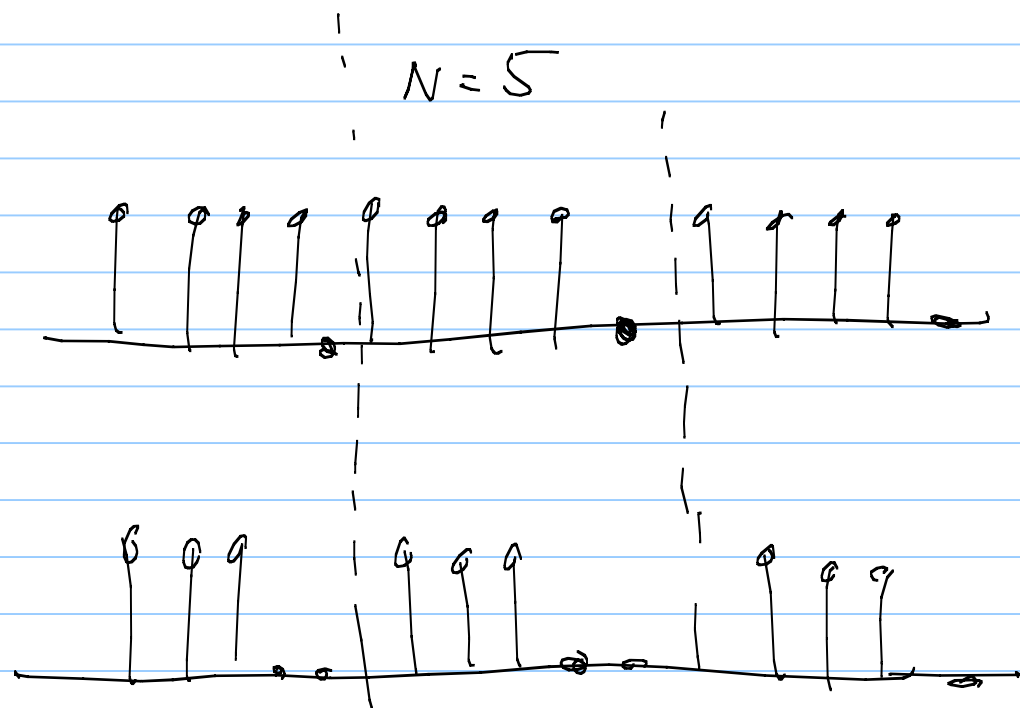
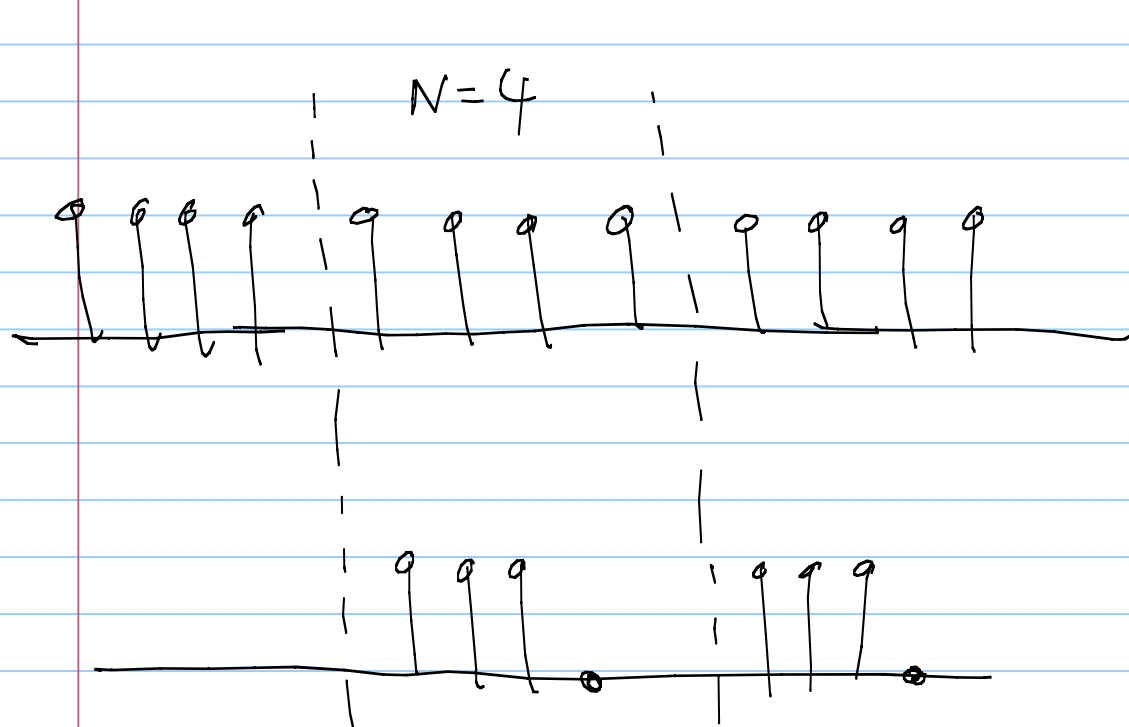
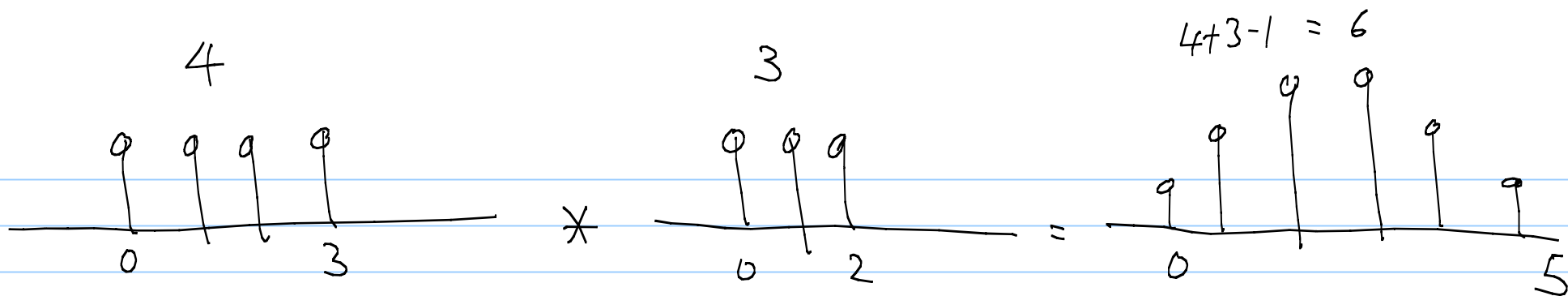
$$\begin{bmatrix} h_0 & h_{N-1} & h_{N-2} & \dots & h_1 \\ h_1 & h_0 & h_{N-1} & \dots & h_2 \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ h_{N-1} & h_{N-2} & & & h_0 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ \vdots \\ x_{N-1} \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ \vdots \\ y_{N-1} \end{bmatrix}$$

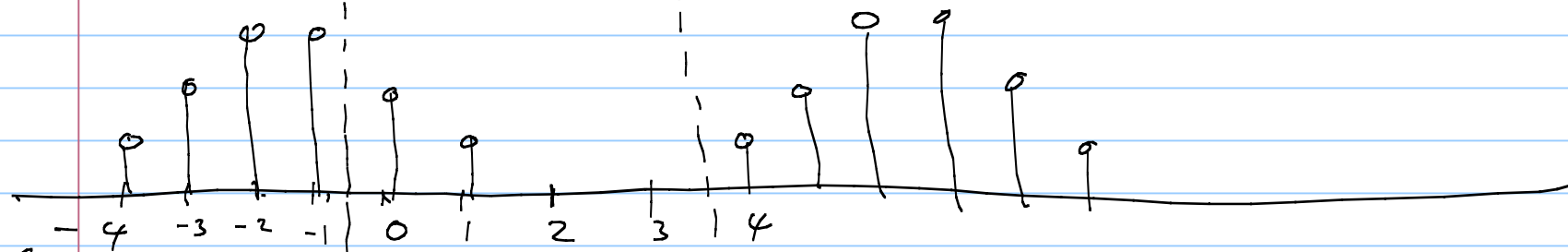
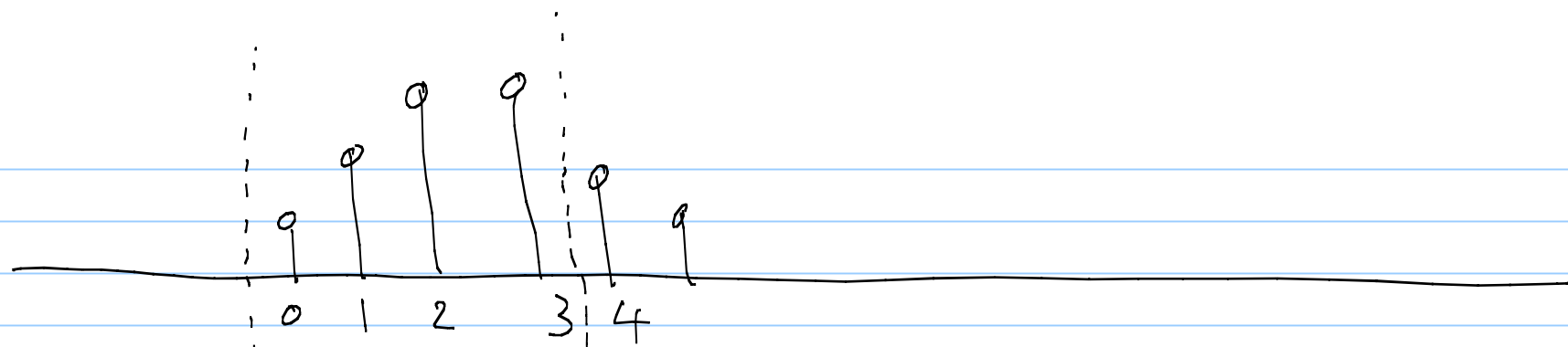
2nd row is a circular shift of first row

To get $x[n] \otimes h[n]$, the indirect approach:

take the DFTs of $x[n]$ & $h[n]$, multiply in the transform domain, & then take inverse transform

$$x[n] \otimes h[n] \longleftrightarrow X[k] H[k]$$

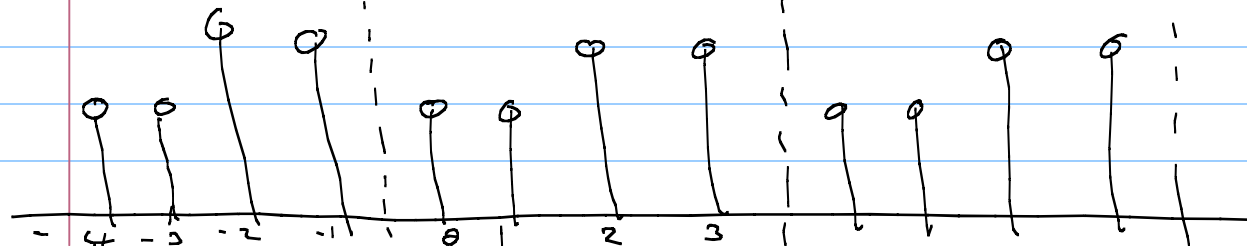




first repetition
to the left.

Tail interferes
with the first
2 samples

first repetition to the right
— does not interfere with
values in $[0, 3]$



result of circular
convolution for $N=4$

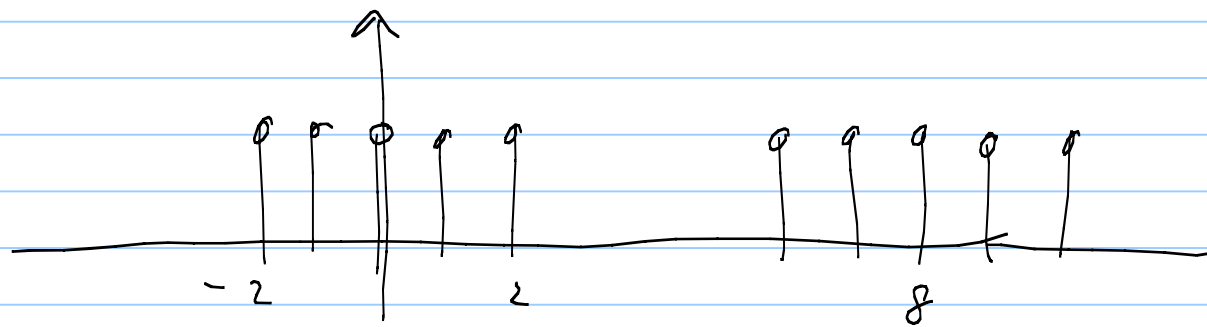
If the repetitions should not overlap then we must choose $N \geq P + Q - 1$. In such a situation, over $[0, N-1]$, the results of linear & circular convolutions are identical.

If $N = P + Q - 1$, the repetitions about each other. If $N > P + Q - 1$, then zeros occur between the repetitions.

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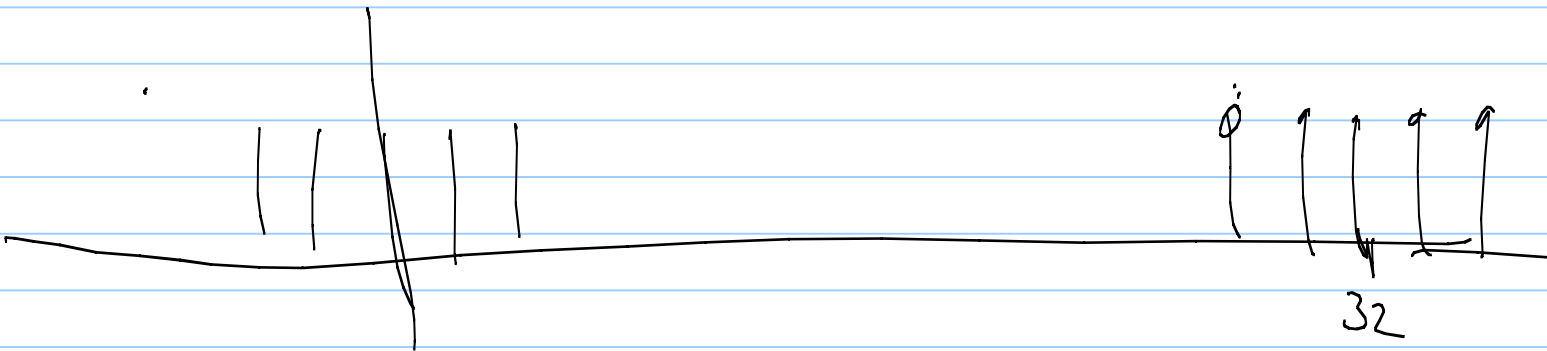
Note Title

16-09-2011



$$a_k = \frac{1}{8} \frac{\sum_{k=0}^7 e^{j\pi k}}{\sum_{k=0}^7 e^{j\pi k/8}}$$

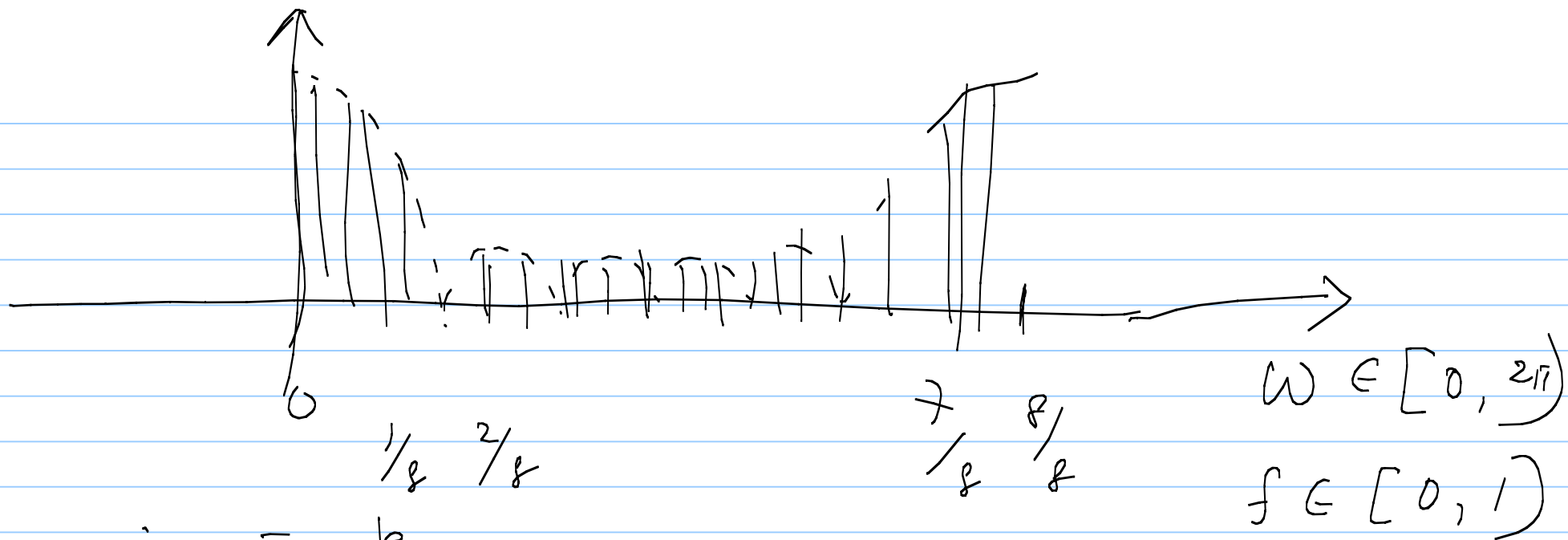
$$k=0, 1, \dots, 7$$



$$k=0, 1, \dots, 31$$

$$a_k = \frac{1}{32} \frac{\sum_{k=0}^{31} e^{j\pi k}}{\sum_{k=0}^{31} e^{j\pi k/32}}$$

$N a_k$



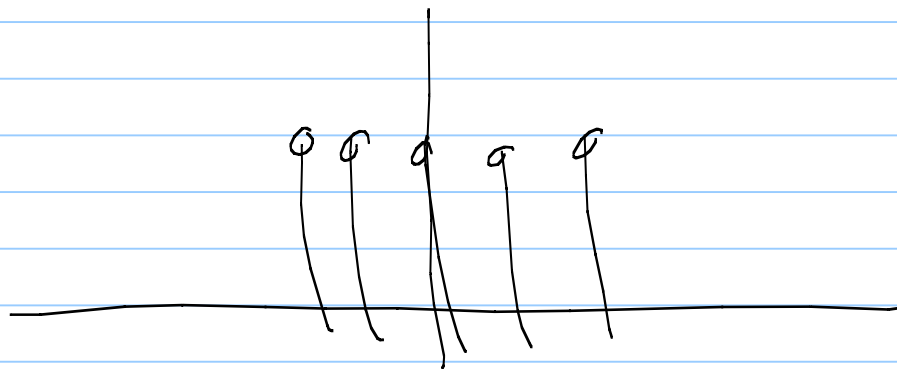
$$e^{j 2\pi \underbrace{\frac{k}{N}}_f n}$$

$$\Omega_0 = \frac{2\pi}{N}$$

$$k\Omega_0 = 2\pi \frac{k}{N} \rightsquigarrow 0 \text{ to } N-1$$

$$N a_k = X[k]$$

8 point DFT



32 point DFT

$$y[n] = \underset{0}{x[n]}$$

$$0 \leq n \leq N-1$$

$$N \leq n \leq L-1$$

L-point DFT of $y[n]$

$$\sum_{n=0}^{L-1} y[n] e^{-j \frac{k 2 \pi}{L} n}$$

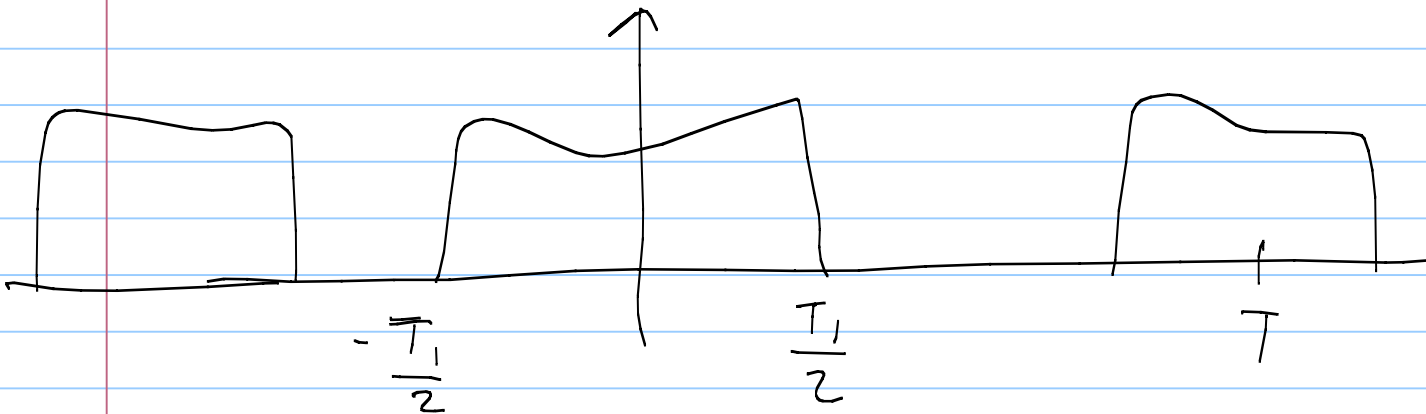
$$Y[k] = \sum_{n=0}^{N-1} x[n] e^{-j \frac{k 2 \pi}{L} n}$$

$$k = 0, 1, \dots, L-1$$

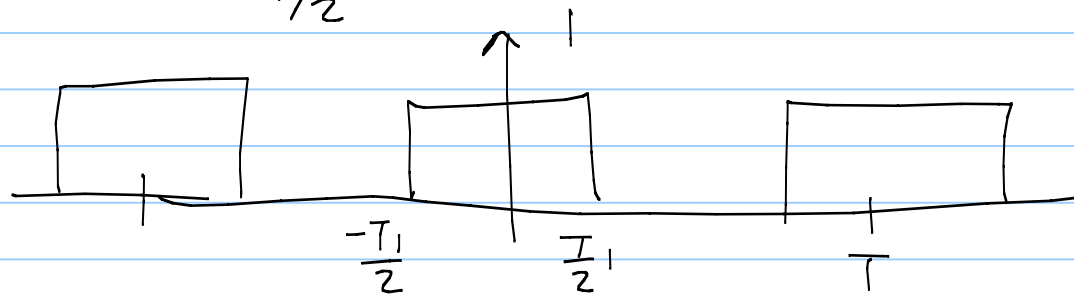
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Note Title

19-09-2011



$$a_k = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-j k \frac{2\pi}{T} t} dt$$



$$x(t) = \begin{cases} 1 & -T_1/2 \leq t \leq T_1/2 \\ 0 & T_1/2 < |t| < T/2 \end{cases}$$

$$a_k = \frac{1}{T} \frac{\sin \pi k T_1 / T}{\pi k / T}$$

$$\frac{1}{T} \frac{\sin \Omega T_1 / 2}{\Omega / 2} \bigg|_{\Omega = k \frac{2\pi}{T}}$$

$$a_k T = \frac{\sum \bar{\pi} k T_1 / T}{\frac{\pi k}{T} T_1} T_1$$

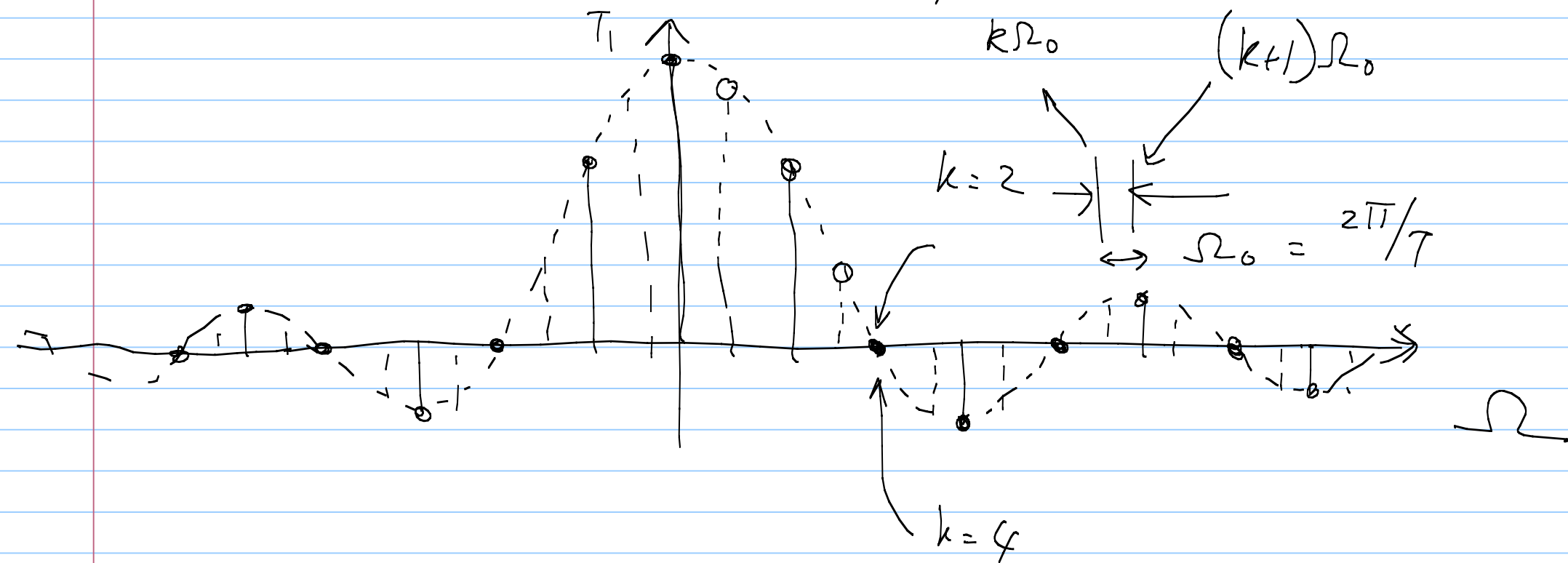
As $T \rightarrow \infty$, $a_k \rightarrow 0$

Let us consider $\frac{T_1}{T} = \frac{1}{2}$

$$\frac{T_1}{T} = \frac{1}{4}$$

Case 1) $a_k T = \frac{\sum \pi k / 2}{k \pi / 2} \cdot T_1$

Case 2) $a_k T = \frac{\sum \pi k / 4}{k \pi / 4}, T_1$

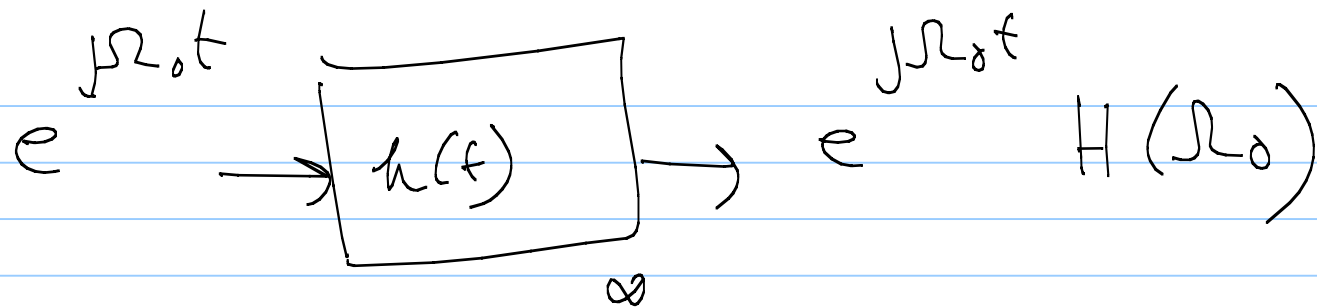


$$a_k = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-j \underbrace{k \frac{2\pi}{T} t}} dt$$

As $T \rightarrow \infty$, $a_k \rightarrow 0$, but $a_k T$ tends to a limit

$$a_k T \rightarrow \int_{-\infty}^{\infty} x(t) e^{-j \underbrace{\omega t}} dt = X(\omega)$$

$$X(\omega) \stackrel{\text{def}}{=} \int_{-\infty}^{\infty} x(t) e^{-j \omega t} dt \quad \text{CTFT}$$



$$H(\Omega) = \int_{-\infty}^{\infty} h(t) e^{-j\Omega t} dt$$

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{j k \Omega_0 t}$$

$$\Omega_0 = \frac{2\pi}{T}$$

$$= \frac{1}{T} \sum_{k=-\infty}^{\infty} (a_k T) e^{j k \Omega_0 t}$$

$$= \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} (a_k T) e^{j k \Omega_0 t} \Omega_0$$

$$\rightarrow \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\Omega) e^{j \Omega t} d\Omega \quad \text{as } \Omega_0 \rightarrow 0$$

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$$\boxed{X(\Omega) = \int_{-\infty}^{\infty} x(t) e^{-j\Omega t} dt} \equiv X(j\Omega)$$

$$\lim_{T \rightarrow \infty} \int_{-T/2}^{T/2} x(t) e^{-j\Omega_k t} dt = \int_{-\infty}^{\infty} x(t) e^{-j\Omega_k t} dt$$

$$x(t+T) = x(t)$$

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{j\Omega_k t}$$

Synthesis eqn.

$$A \quad T \rightarrow \infty$$

$$x(t) = \frac{1}{T} \sum_{k=-\infty}^{\infty} a_k T e^{j k \overbrace{\Omega_k}^{\Omega_0} t}$$

$$\Omega_0 = \frac{2\pi}{T}$$

$$= \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} (a_k T) e^{j \Omega_k t} \quad \Omega_0$$

$$\Omega_0 = (k+1)\Omega_0 - k\Omega_0 \rightarrow \Delta\Omega$$

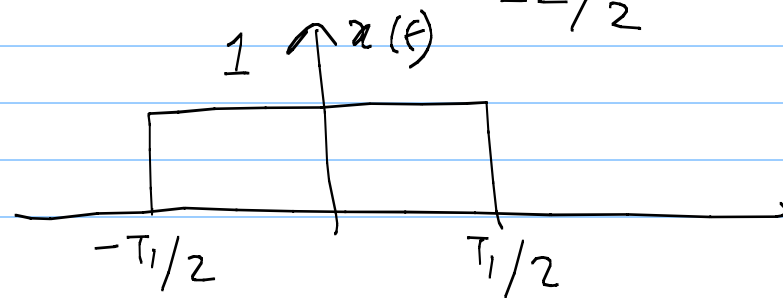
$$x(t) = \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} (a_k T) e^{j \Omega_k t} \quad \Delta\Omega$$

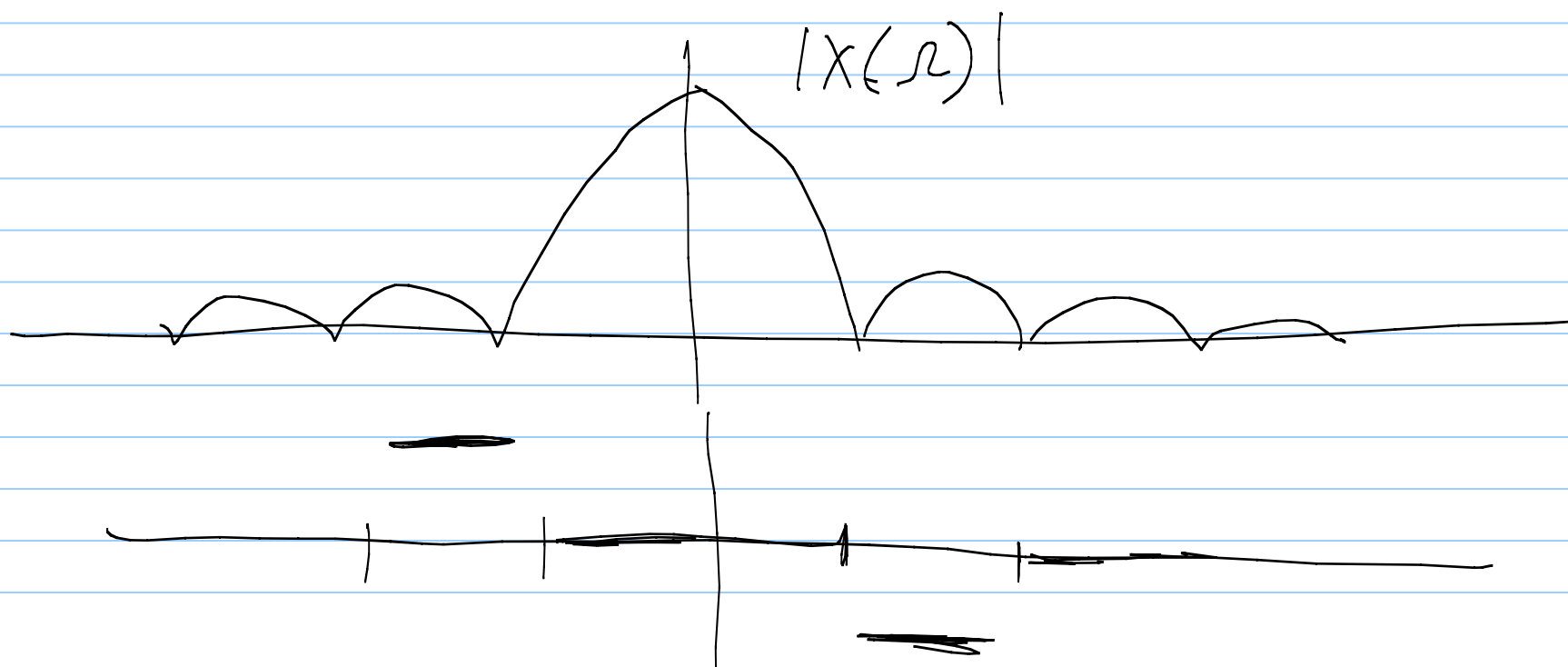
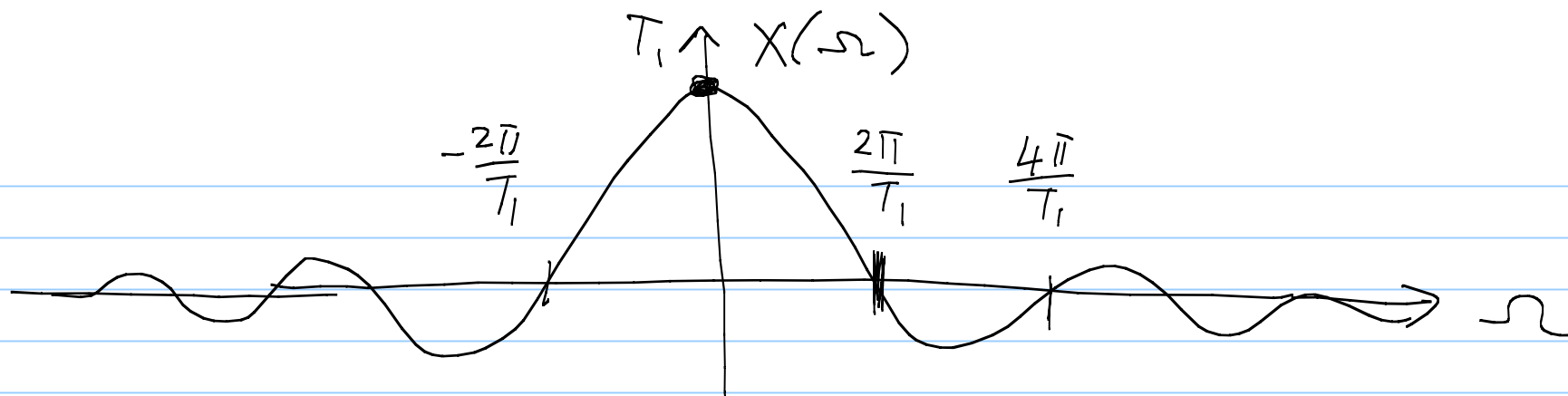
As $T \rightarrow \infty$,

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} X(\Omega) e^{j\Omega t} d\Omega = x(t)$$

$$\text{If } x(t) = \begin{cases} 1 & |t| < T_1/2 \\ 0 & \text{otherwise} \end{cases}$$

$$X(\Omega) = \int_{-T_1/2}^{T_1/2} 1 \cdot e^{-j\Omega t} dt = \frac{\sin \Omega T_1/2}{\Omega/2}$$



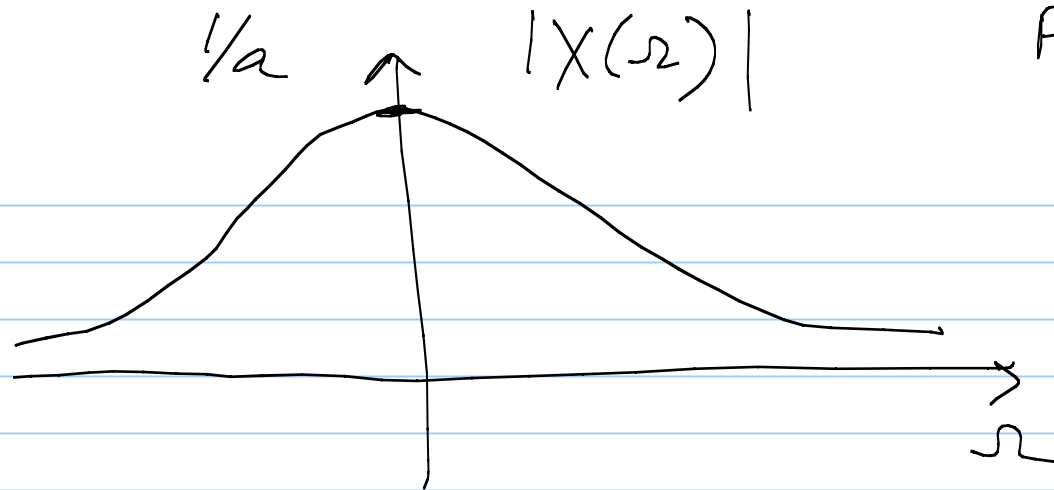


$$x(t) = x^*(t) \quad \text{real-valued}$$

$$X(\Omega) = X^*(-\Omega)$$

$\Rightarrow |X(\Omega)|$: even function of Ω mag. spectrum
 $\Delta X(\Omega)$: odd " " phase spectrum

$$\begin{aligned}
 \mathcal{F}\{e^{-at} u(t)\} &= \int_{-\infty}^{\infty} e^{-at} u(t) e^{-j\Omega t} dt \\
 &= \frac{1}{a + j\Omega} \quad \text{Re}\{a\} > 0
 \end{aligned}$$



For real a ,

$$|X(\Omega)| = \frac{1}{\sqrt{a^2 + \Omega^2}}$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{1}{a + j\Omega} e^{j\Omega t} d\Omega$$

$$X(0) = \int_{-\infty}^{\infty} x(t) dt$$

$$x(0) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\Omega) d\Omega$$

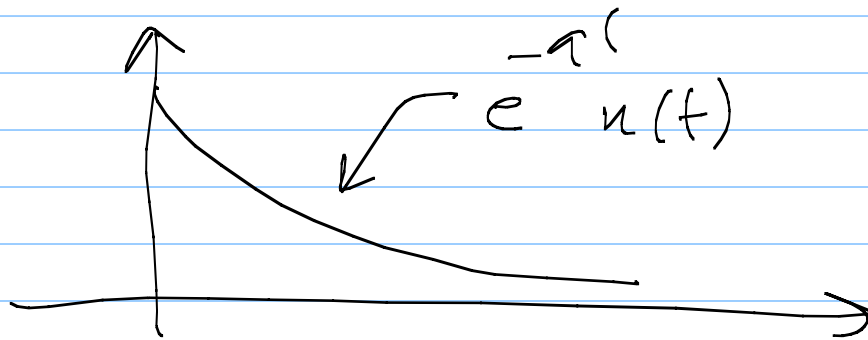
$$x(t) \Big|_{t=0} = \frac{1}{2\pi} \int_{-\infty}^{\infty} \left[\frac{a}{a^2 + \Omega^2} - j \frac{\Omega}{a^2 + \Omega^2} \right] d\Omega$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{a^2}{a^2 + \Omega^2} d\Omega - \underbrace{\frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{\Omega}{a^2 + \Omega^2} d\Omega}_{= 0}$$

$$\lim_{T \rightarrow \infty} \int_{-T}^T \frac{\Omega}{a^2 + \Omega^2} d\Omega = 0$$

Cauchy Principal Value

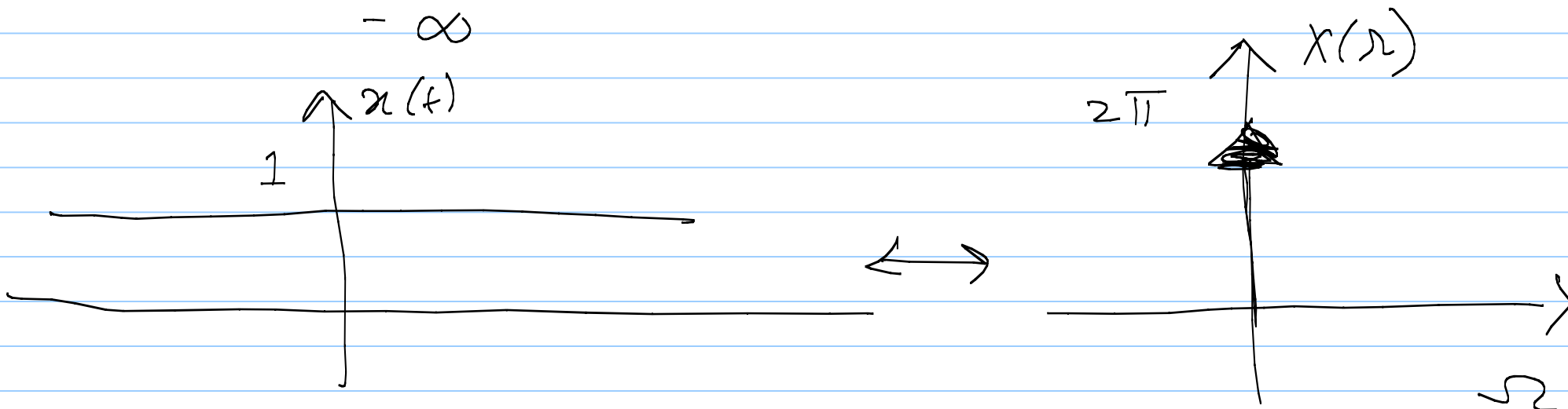
$$\frac{1}{2\pi} \int_{-\infty}^{\infty} \frac{a}{a^2 + \Omega^2} d\Omega = \frac{1}{2\pi} \tan^{-1} \left(\frac{\Omega}{a} \right) \Big|_{-\infty}^{\infty}$$



$$e^{-a|t|} = \frac{1}{2\pi} \pi = \frac{1}{2}$$

$$X(\Omega) = 2\pi \delta(\Omega)$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} 2\pi \delta(\Omega) e^{j\Omega t} d\Omega = 1 \quad \forall t$$



$$X(\Omega) = \int_{-\infty}^{\infty} 1 \cdot e^{-j\Omega t} dt = 2\pi \delta(\Omega)$$

$$1 \longleftrightarrow 2\pi \delta(\Omega)$$

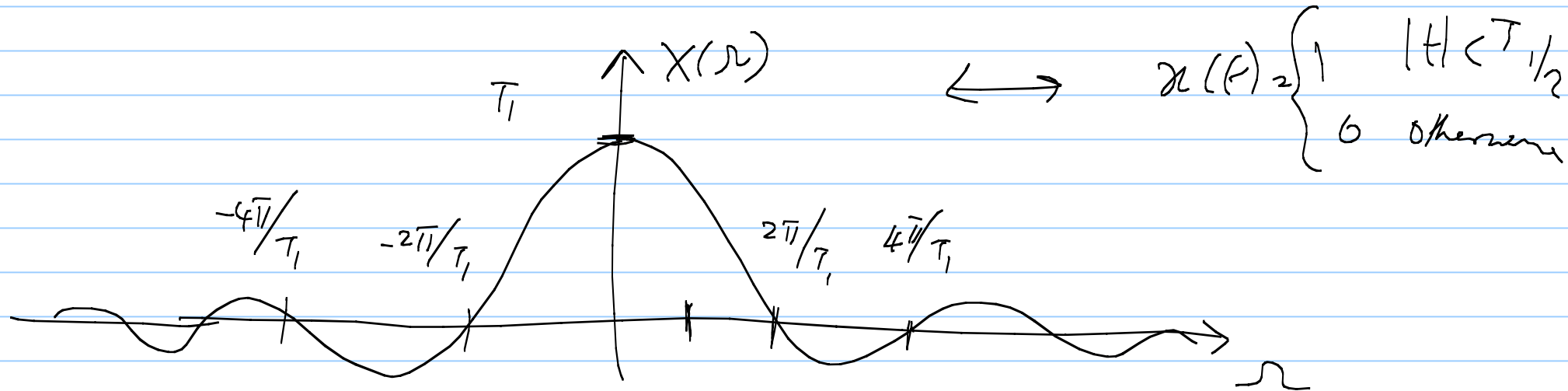
$$x(t - t_0) \longleftrightarrow e^{-j\Omega t_0} X(\Omega)$$

$$e^{j\Omega_0 t} x(t) \longleftrightarrow X(\Omega - \Omega_0)$$



$$e^{j\Omega_0 t} \cdot 1 \longleftrightarrow 2\pi \delta(\Omega - \Omega_0)$$

$$a_1 x_1(t) + a_2 x_2(t) \leftrightarrow a_1 X_1(\Omega) + a_2 X_2(\Omega)$$



What is the DC value of $x(t)$?

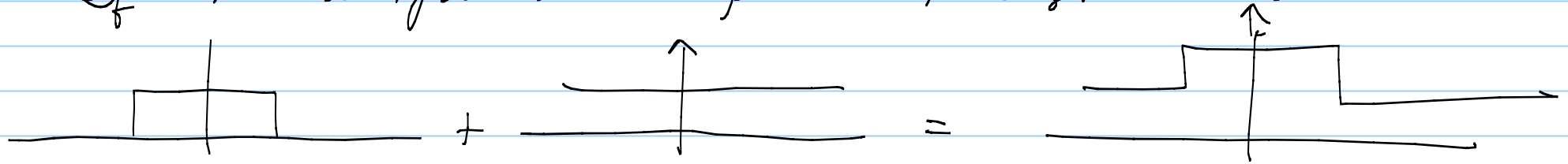
$$\overline{x(t)} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x(t) dt$$

$$= \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T_1/2}^{T_1/2} 1 dt$$

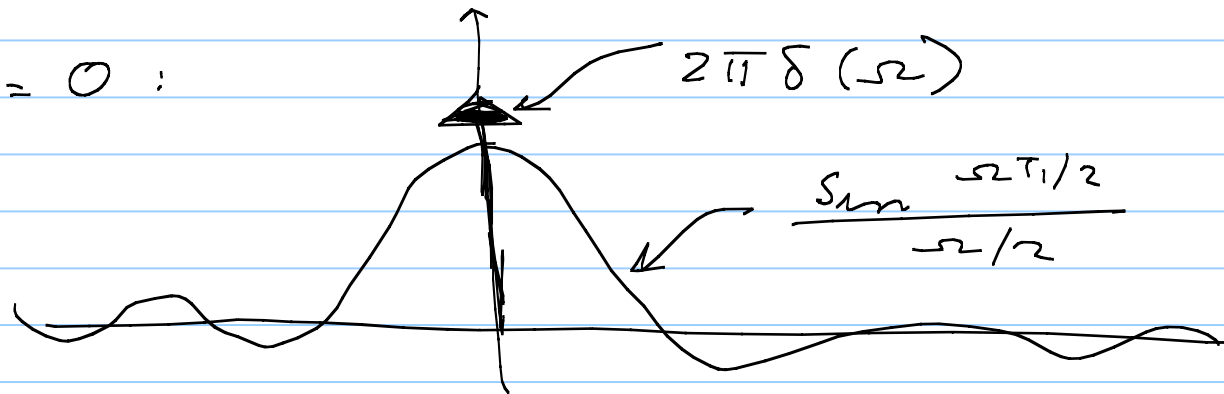
$$= \lim_{T \rightarrow \infty} \frac{T_1}{T} = 0$$

DC value is actually zero. Hence if $X(0)$ is non zero, it doesn't mean a pure tone of that frequency is present.

If DC component is present, signal will be



Spectrum will now contain an extra impulse at $\Omega = 0$:

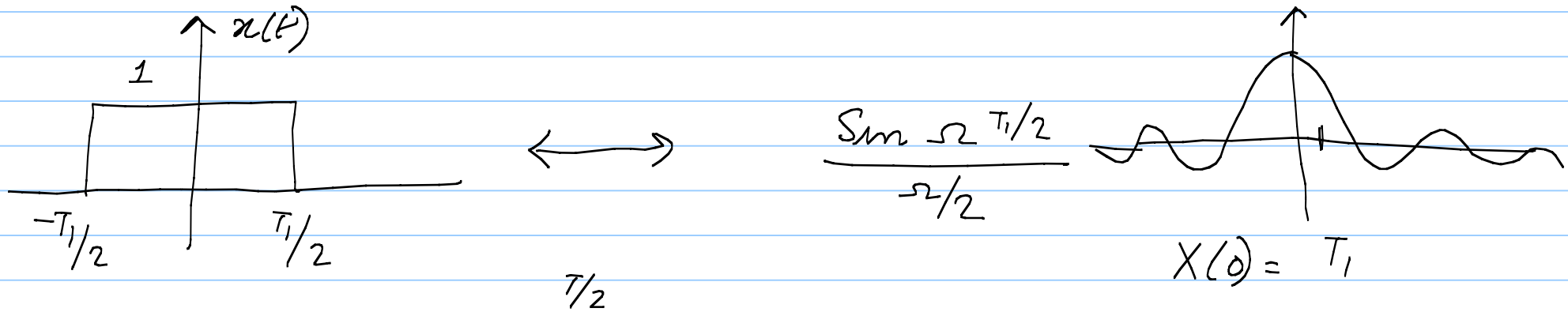


$$X(\Omega) = 2\pi\delta(\Omega) + \frac{\sin \Omega T_1/2}{\Omega/2}$$

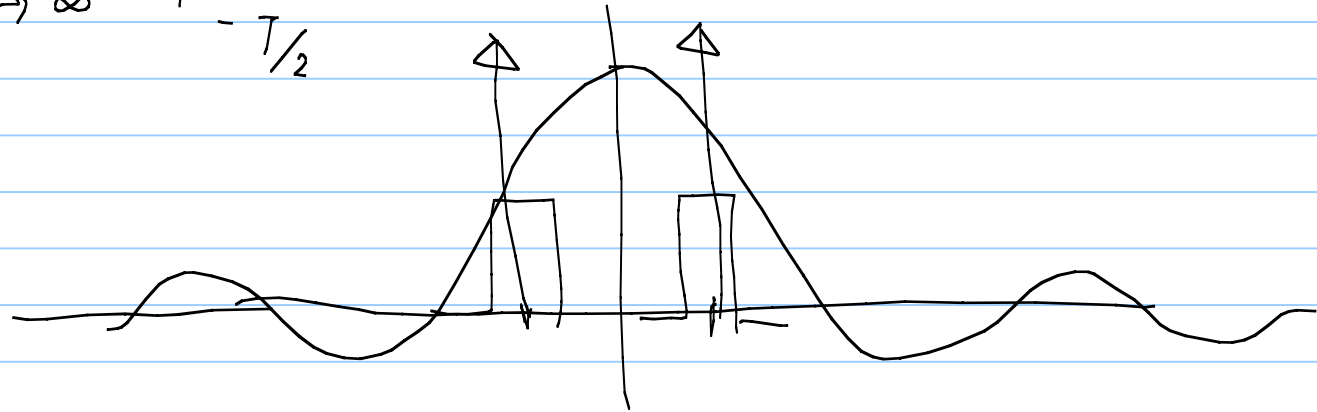
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21-09-2011



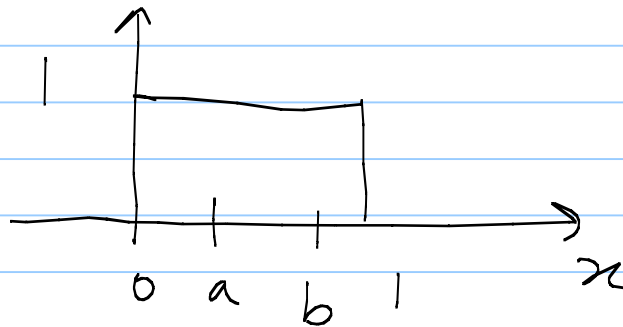
$$\bar{x}(t) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x(t) dt = 0$$



$$e^{j\Omega_0 t} \longleftrightarrow 2\pi \delta(\Omega - \Omega_0)$$

$$\cos \Omega_0 t \longleftrightarrow \pi [\delta(\Omega - \Omega_0) + \delta(\Omega + \Omega_0)]$$

$$\sin \Omega_0 t \longleftrightarrow \frac{\pi}{j} [\delta(\Omega - \Omega_0) - \delta(\Omega + \Omega_0)]$$

 $f_X(x)$


$$0 \leq a < b \leq 1$$

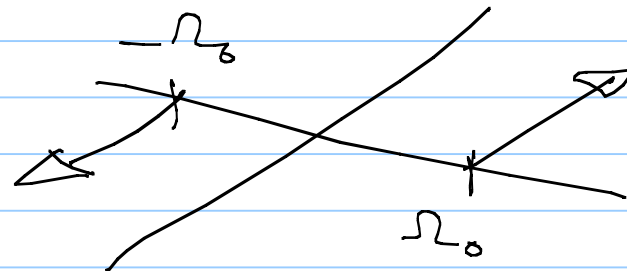
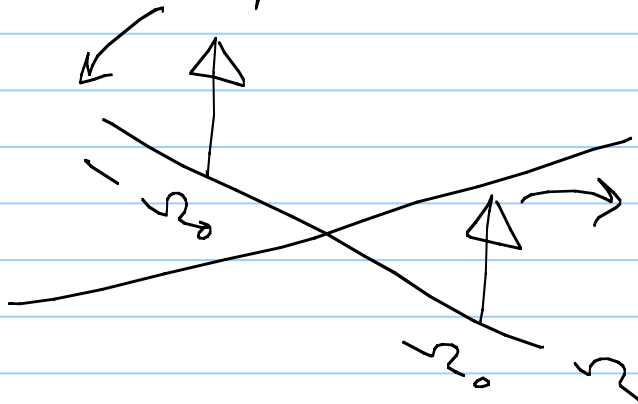
$$P[a \leq X \leq b] = b - a$$

$$P[X = a] = 0$$

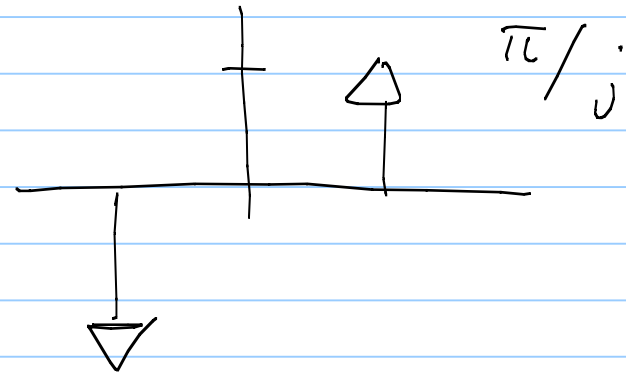
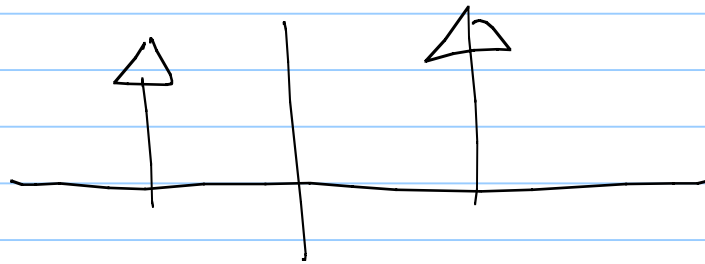
Properties

1) linearly

2) Time Shift : $x(t - t_0) \longleftrightarrow e^{-j\Omega t_0} X(\Omega)$

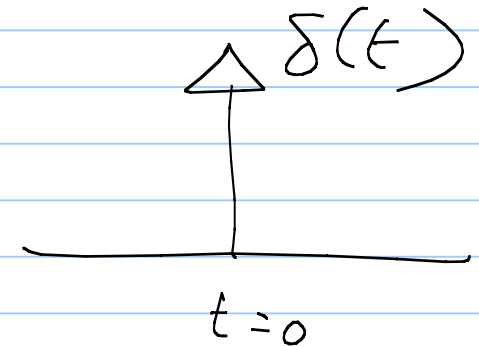
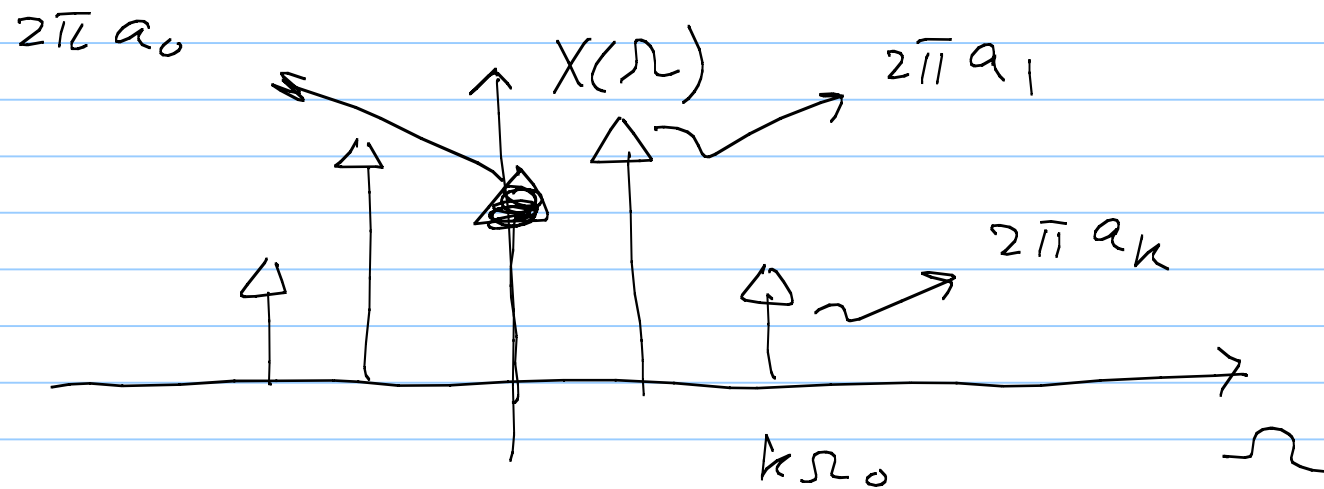
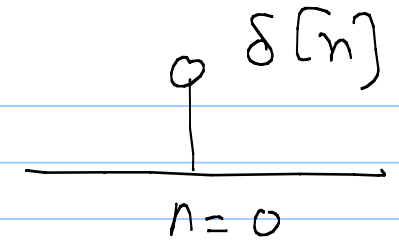
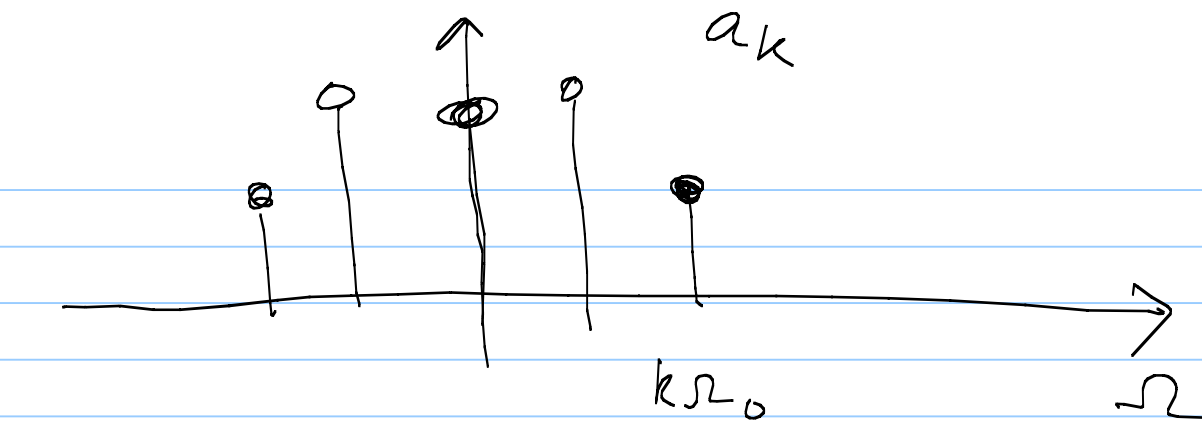


$$\cos \Omega_0 t \longleftrightarrow \pi [\delta(\Omega - \Omega_0) + \delta(\Omega + \Omega_0)]$$



$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{j k \Omega_0 t}$$

$$\longleftrightarrow \sum_{k=-\infty}^{\infty} 2\pi a_k \delta(\Omega - k\Omega_0)$$

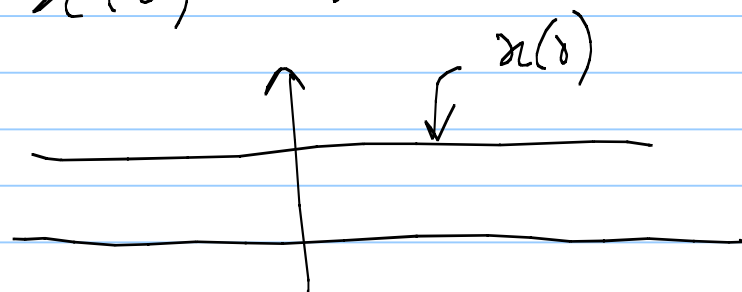


3) Modulation $e^{j\Omega_0 t} x(t) \leftrightarrow X(\Omega - \Omega_0)$

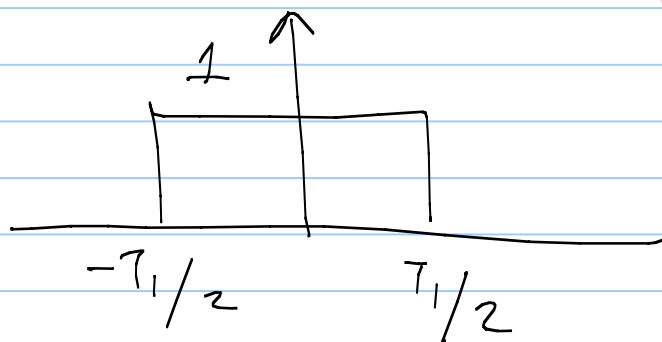
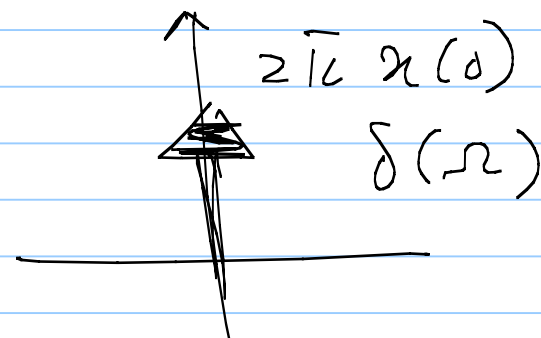
$$4) \quad y(t) = x(at) \quad \longleftrightarrow \quad \frac{1}{|a|} X(\omega/a)$$

For $a = 0$

$$y(t) = x(0) \quad \forall t$$

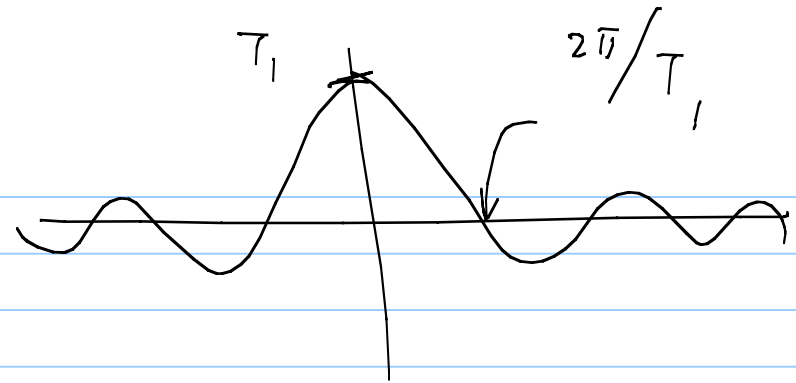


$\longleftrightarrow$



$\longleftrightarrow$

$$\frac{\sin \omega T_1/2}{\omega/2}$$



As $T_1 \rightarrow \infty$, $a(t) \rightarrow 1 \quad \forall t$

$$\frac{\sin \Omega T_1/2}{\Omega/2} \rightarrow 2\pi \delta(\Omega)$$

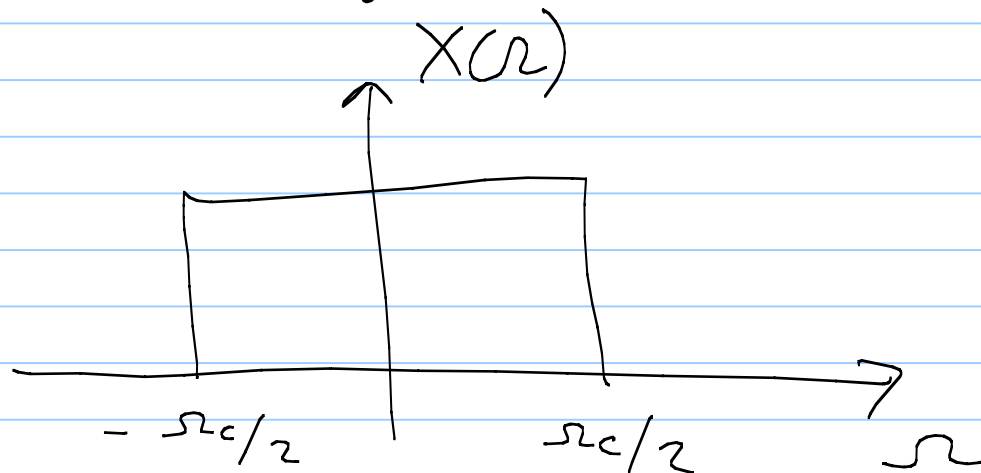
$$\frac{\sin \pi t}{\pi t} \equiv \text{sinc}(t)$$

5) Duality

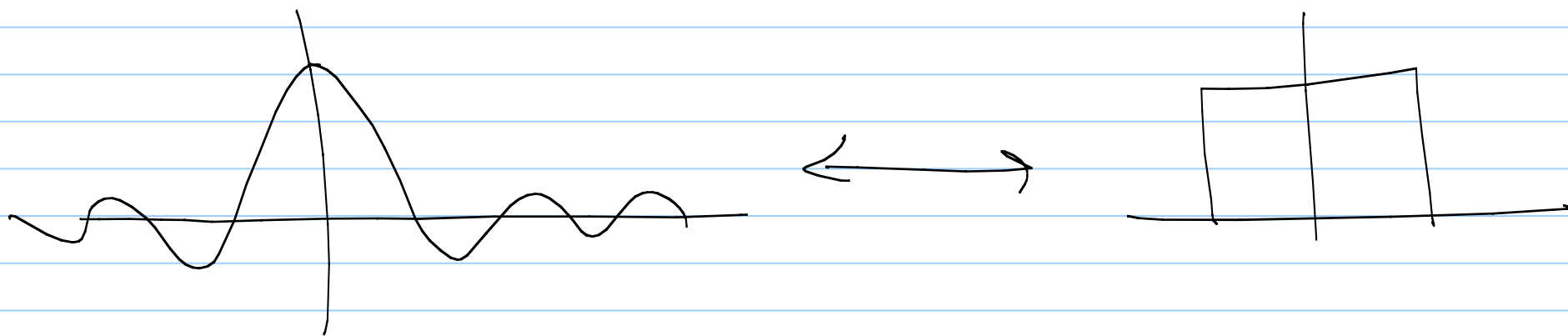
$$X(\Omega) = \int_{-\infty}^{\infty} x(t) e^{-j\Omega t} dt$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\Omega) e^{j\Omega t} d\Omega$$

$X(\Omega)$



$$x(t) = \frac{1}{2\pi} \int_{-\Omega_c/2}^{\Omega_c/2} 1 \cdot e^{j\Omega t} d\Omega = F_c \operatorname{sinc}(F_c t)$$



$$x(t) \longleftrightarrow X(\Omega)$$

$$y(t) = X(t) \longleftrightarrow 2\pi x(-\omega)$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega \leftarrow$$

$$Y(\omega) = \int_{-\infty}^{\infty} \underbrace{y(t)} e^{-j\omega t} dt$$

$$\rightarrow 2\pi x(\lambda) = \int_{-\infty}^{\infty} X(\Omega) e^{j\Omega\lambda} d\Omega$$

$$= \int_{-\infty}^{\infty} X(t) e^{j\lambda t} dt$$

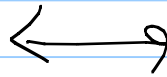
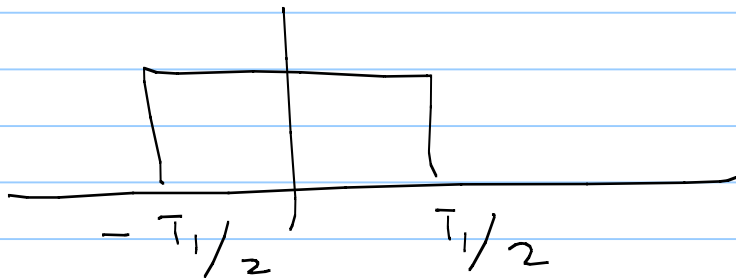
$$2\pi x(-\lambda) = \int_{-\infty}^{\infty} X(t) e^{-j\lambda t} dt$$

$$2\pi x(-\Omega) = \int_{-\infty}^{\infty} X(t) e^{-j\Omega t} dt$$

$$\mathcal{F}\{X(t)\} = 2\pi \mathcal{X}(-\Omega)$$

$$X(t) \longleftrightarrow 2\pi \mathcal{X}(-\Omega)$$

$\mathcal{X}(t)$



$$\frac{\sin \Omega T_1/2}{\Omega/2} = X(\Omega)$$

$$X(t) = \frac{\sin t \tau_1/2}{t/2} \equiv \frac{\sin t \Omega_c/2}{t/2}$$

$$\frac{X(t)}{2\pi} = \frac{\sin t \Omega_c/2}{\pi t}$$

$$= \frac{\sin \pi F_c t}{\pi F_c t} \cdot F_c$$

$$= F_c \operatorname{sinc}(F_c t) \longleftrightarrow x(-\Omega)$$

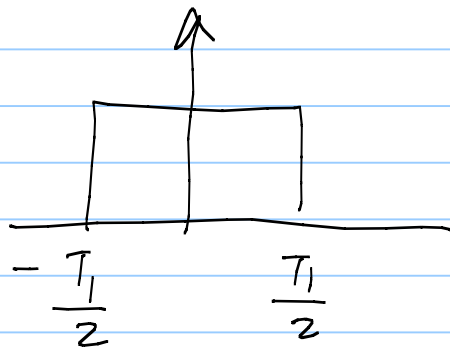


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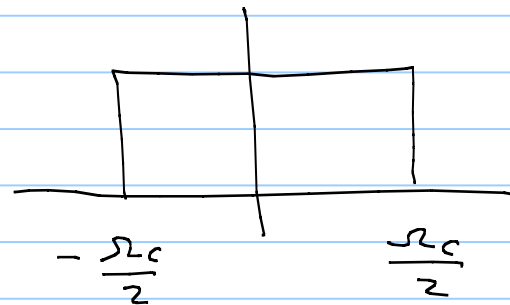
26-09-2011

$$X(t) \longleftrightarrow 2\pi x(-\omega)$$



$$\frac{\sin \omega T_1/2}{\omega/2}$$

$$F_c \operatorname{sinc}(F_c t)$$



For real $x(t)$, $x(t) = x^*(t)$

$$X(\Omega) = X^*(-\Omega)$$

$$X(\Omega) = X_R(\Omega) + j X_I(\Omega)$$

$$X^*(-\Omega) = X_R(-\Omega) - j X_I(-\Omega)$$

$$\Rightarrow X_R(\Omega) = X_R(-\Omega) \quad \text{even}$$

$$X_I(-\Omega) = -X_I(\Omega) \quad \text{odd}$$

$|X(\omega)|$: even

$\angle X(\omega)$: odd

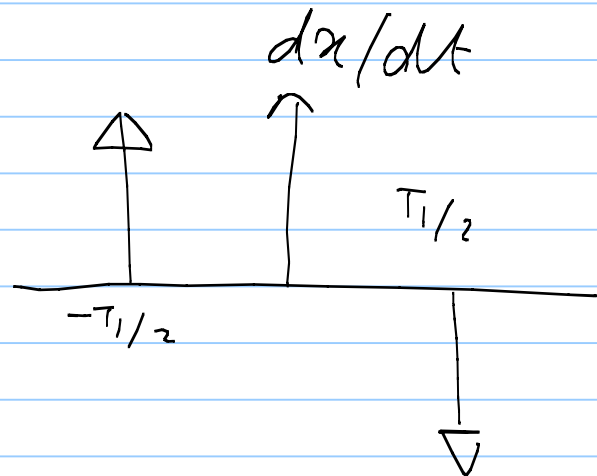
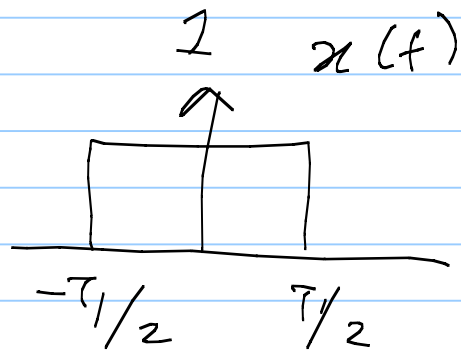
Differentiation:

$$x(t) \leftrightarrow X(\omega)$$

$$x'(t) \leftrightarrow j\omega X(\omega)$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$$

$$\frac{dx}{dt} \stackrel{?}{=} \frac{1}{2\pi} \int_{-\infty}^{\infty} j \omega X(\omega) e^{j\omega t} d\omega$$



$$\delta(t + T/2) - \delta(t - T/2)$$

$$e^{j\Omega T_1/2} - e^{-j\Omega T_1/2} \leftrightarrow 2j \sin \Omega T_1/2$$

$$x(t) \rightarrow \frac{\sin \Omega T_1/2}{\Omega/2}$$

$$x(at) \leftrightarrow \frac{1}{|a|} X(\Omega/a)$$

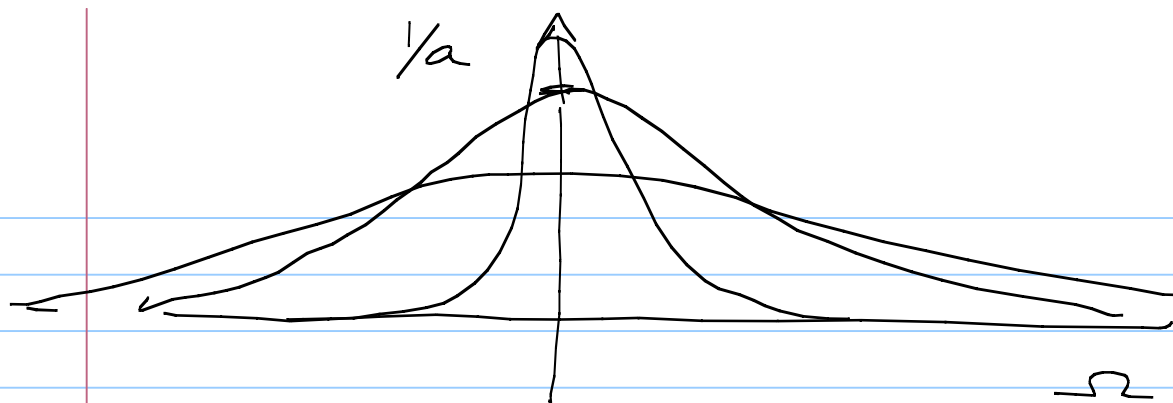
$$x(-t) \leftrightarrow X(-\Omega)$$

$$e^{-at} u(t) \longleftrightarrow \frac{1}{a + j\Omega}$$

$$u(t) \longleftrightarrow ?$$

$$e^{-at} u(t) \longleftrightarrow \frac{a}{a^2 + \Omega^2} - \frac{j\Omega}{a^2 + \Omega^2}$$

$$\mathcal{L}_{a \rightarrow 0} \left(\frac{a}{a^2 + \Omega^2} - \frac{j\Omega}{a^2 + \Omega^2} \right) =$$

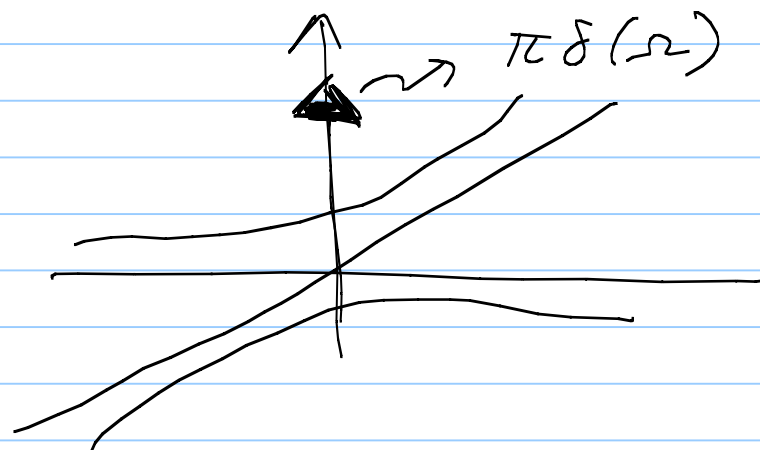
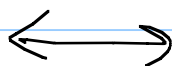
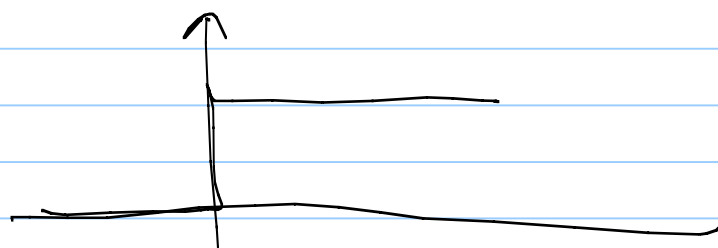


$$\int_{-\infty}^{\infty} \frac{a}{a^2 + \Omega^2} d\Omega = \pi$$

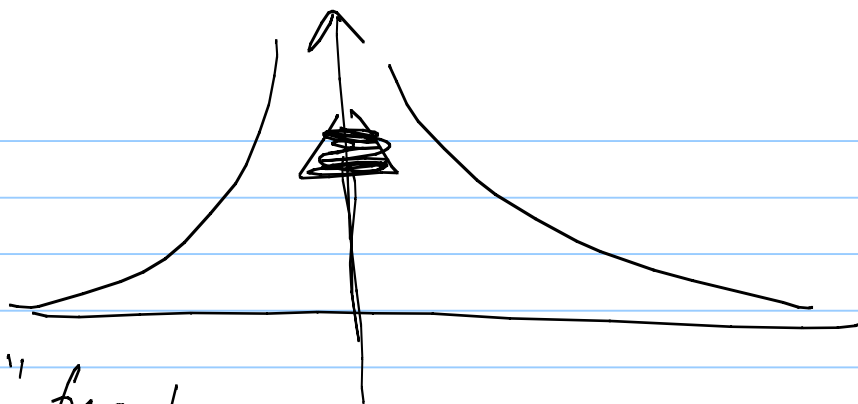
indep. of a !

$$\mathcal{L} \left\{ \frac{a}{a^2 + \Omega^2} - \frac{j\Omega}{a^2 + \Omega^2} \right\} \rightarrow \pi \delta(\Omega) + \frac{1}{j\Omega}$$

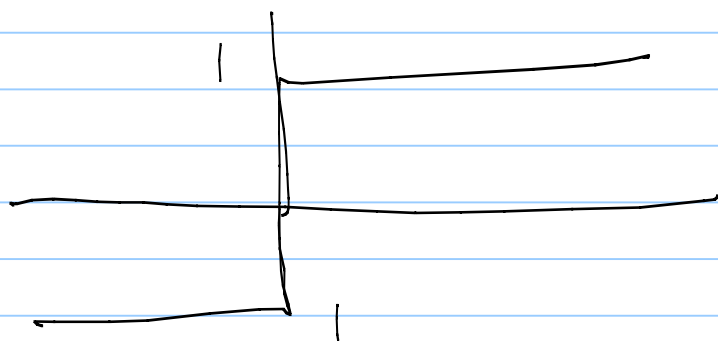
$a \rightarrow 0$



$|X(\omega)|$

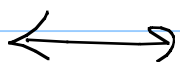


$\text{Sgn}(t) = \text{"signum" function}$



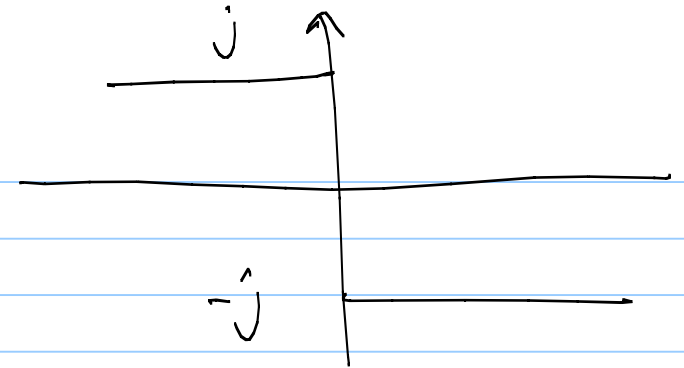
$$= 2 \left[u(t) - \frac{1}{2} \right]$$

$$= 2u(t) - 1$$



$$2\pi \delta(\omega) + \frac{2}{j\omega} - 2\pi \delta(\omega) = \frac{2}{j\omega}$$

$$x(t) = \frac{1}{T_L t}$$



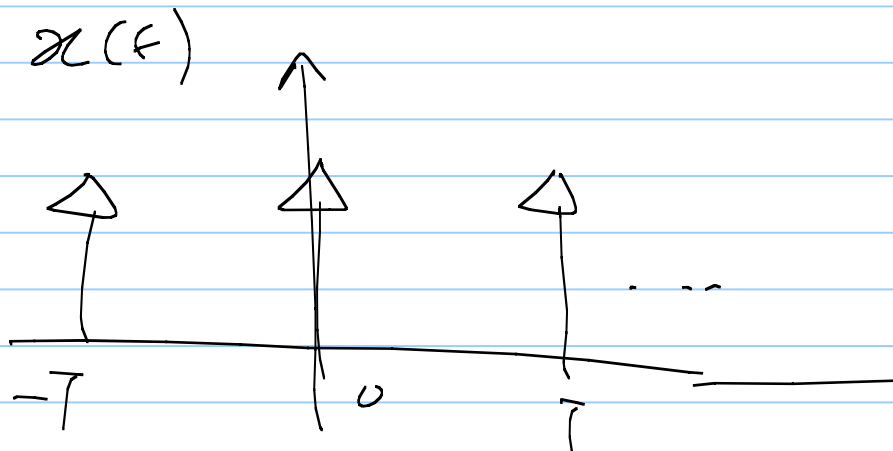
Other forms of $X(\omega)$.

$$X(F) = \int_{-\infty}^{\infty} x(t) e^{-j 2\pi F t} dt$$

$$x(t) = \int_{-\infty}^{\infty} X(F) e^{j 2\pi F t} dF$$

$$\mathcal{F}\{\mathcal{F}\{x(t)\}\} = ?$$

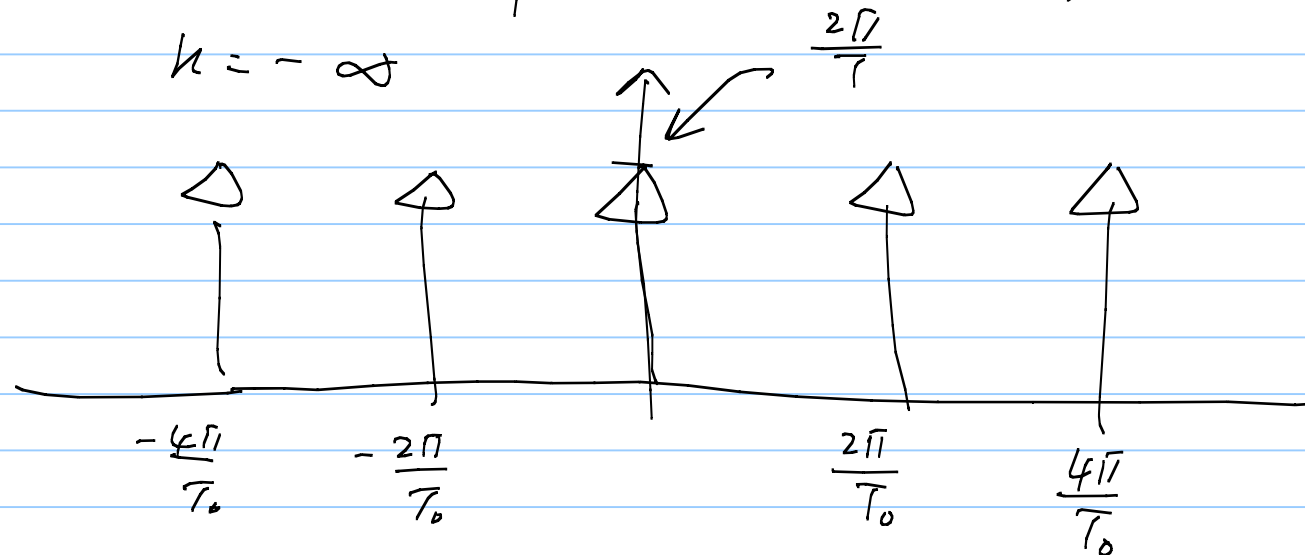
$$\mathcal{F}\mathcal{F}\mathcal{F}\mathcal{F}\{x(t)\} = ?$$



$$a_k = \frac{1}{T}$$

$$x(t) = \sum_{k=-\infty}^{\infty} \frac{1}{T} e^{jk\Omega_0 t}$$

$$\longleftrightarrow \sum_{k=-\infty}^{\infty} \frac{2\pi}{T} \delta(\Omega - k\Omega_0)$$



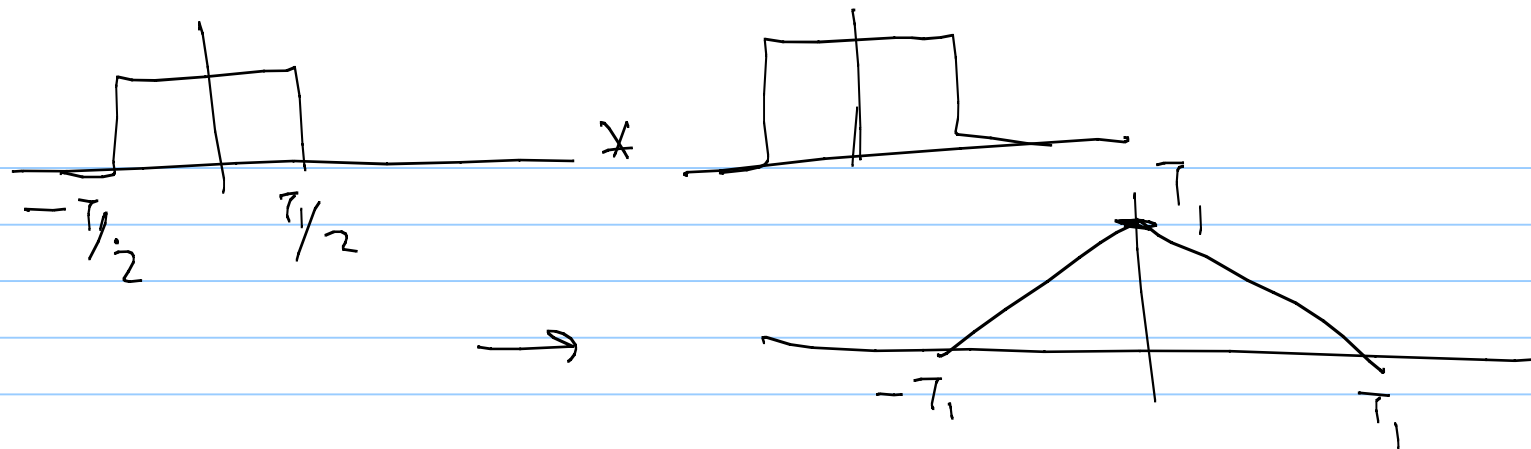
$$x(t) = e^{-t^2/2} \longleftrightarrow ?$$

$$\frac{1}{\sigma} \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{-\frac{t^2}{2\sigma^2}} dt = 1$$

Convolution

$$x(t) * y(t) \longleftrightarrow X(\omega) Y(\omega)$$

$$x(t) \cdot y(t) \longleftrightarrow \frac{1}{2\pi} X(\omega) * Y(\omega)$$



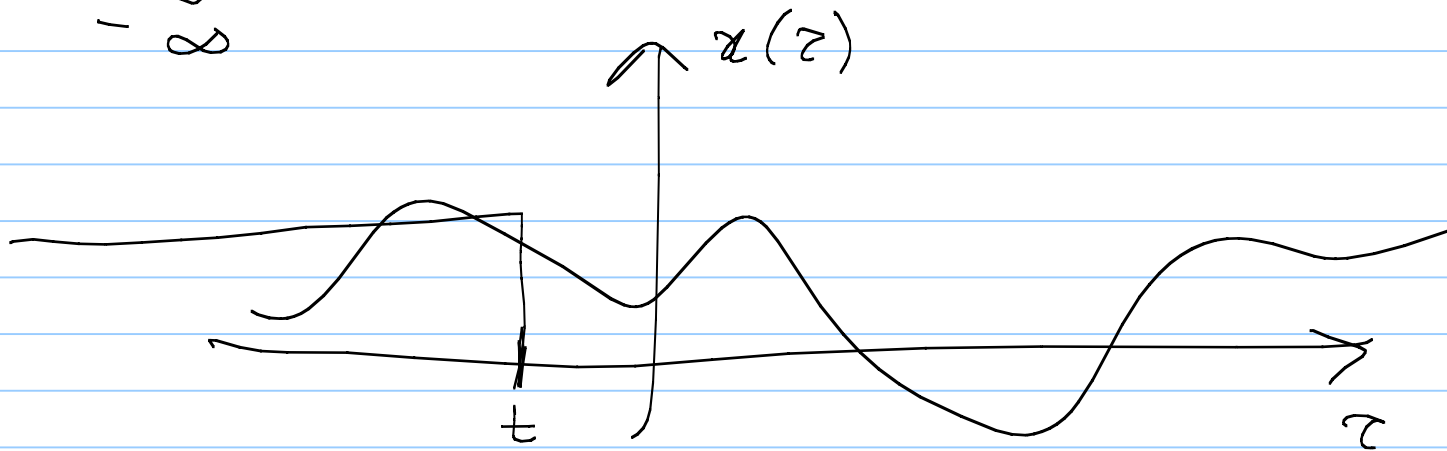
$$\longleftrightarrow \left[\frac{\sin \omega T_1/2}{\omega/2} \right]^2$$

$$\int_{-\infty}^{\infty} x(t) y^*(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) Y^*(\omega) d\omega$$

$$\int_{-\infty}^{\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\omega)|^2 d\omega$$

Integration Property

$$y(t) = \int_{-\infty}^{\infty} x(\tau) d\tau = x(t) * u(t)$$



$$\longleftrightarrow X(\omega) \cup(\omega)$$

$$X(\omega) \left[\pi \delta(\omega) + \frac{1}{j\omega} \right]$$

$$= \pi X(0) \delta(\omega) + \frac{X(\omega)}{j\omega}$$

$$y(t) = \int_{-\infty}^t x(\tau) d\tau \longleftrightarrow \pi X(0) \delta(\omega) + \frac{X(\omega)}{j\omega}$$

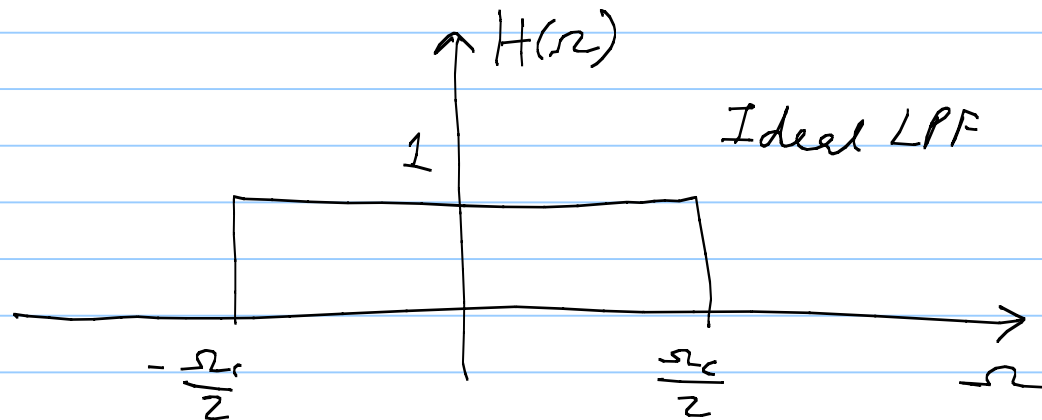
$$\frac{dy}{dt} = x(t)$$

$$j\omega \left[\bar{u} X(0) \delta(\omega) + \frac{X(\omega)}{j\omega} \right]$$

$$= \underbrace{j\omega \delta(\omega)}_0 \bar{u} X(0) + X(\omega)$$

$$= X(\omega) \text{ as expected.}$$

Ideal Filters

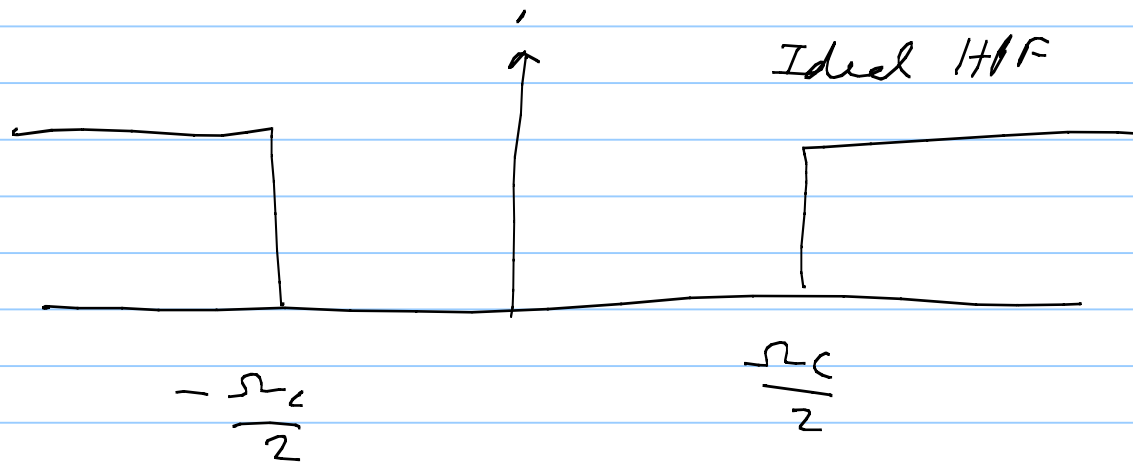


Ideal LPF

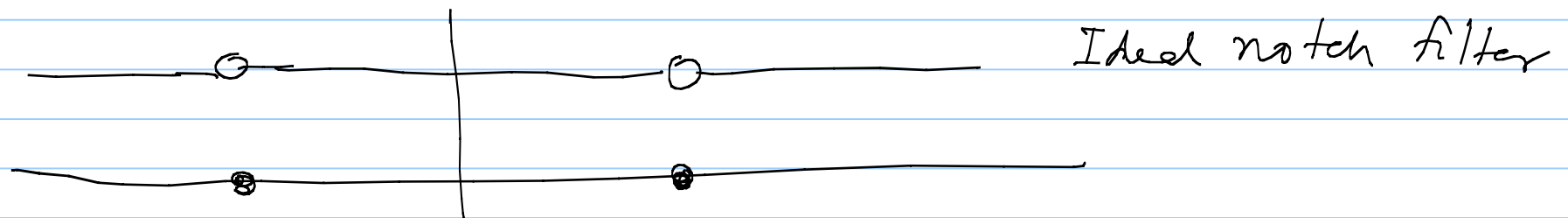
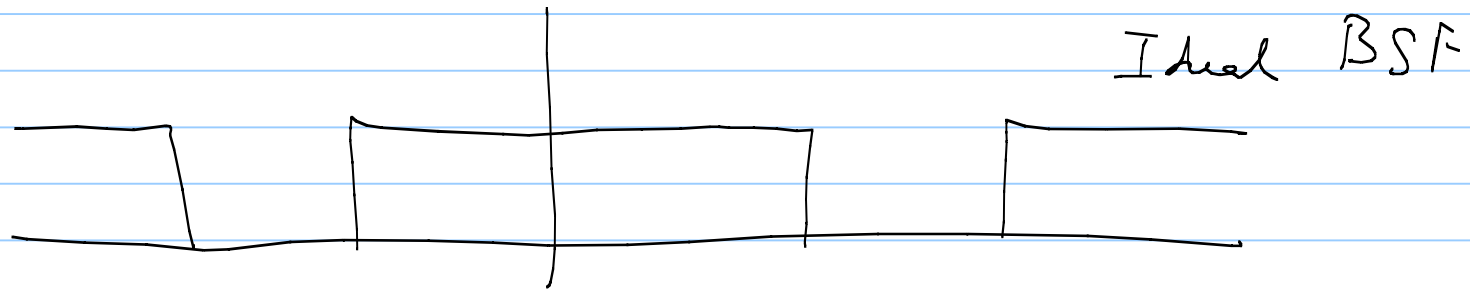
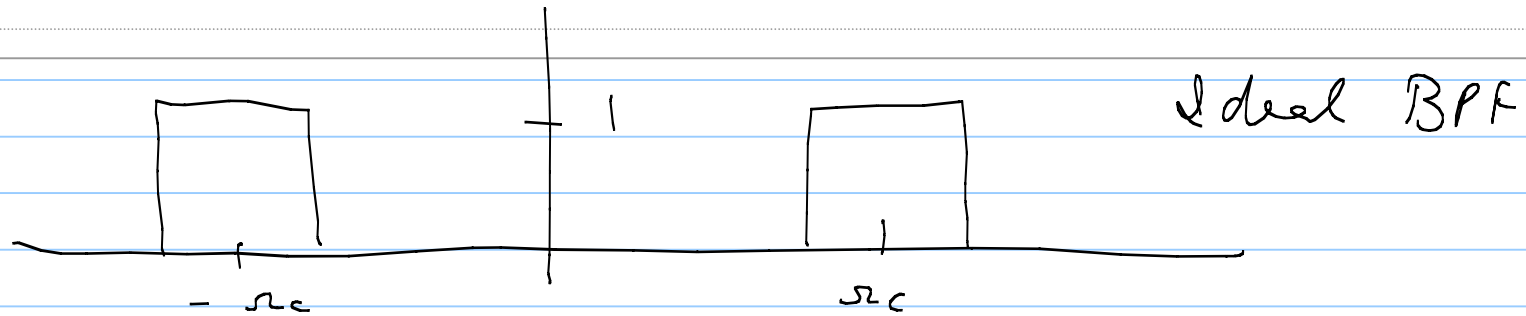
$$\longleftrightarrow F_c \text{sinc}(F_c t)$$

↓

non-causal



Ideal HPF



$$x[n+N] = x[n]$$

$$x[n] = \sum_{k=0}^{N-1} a_k e^{j k \frac{2\pi}{N} n}$$

$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-j k \frac{2\pi}{N} n}$$

$$= \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-j k \frac{2\pi}{N} n}$$

$$N a_k = \sum_{n=-\langle N \rangle}^{\langle N \rangle} x[n] e^{-j \underbrace{k \omega_0}_\omega n} \quad \omega_0 = \frac{2\pi}{N}$$

As $N \rightarrow \infty$

$N a_k \rightarrow$

$$\sum_{n=-\infty}^{\infty} x[n] e^{-j \omega n} \equiv X(e^{j \omega})$$

DTFT

$\hookrightarrow 2\pi$ periodic

$$x[n] = \sum_{k=0}^{N-1} a_k e^{j k \frac{2\pi}{N} n}$$

$$= \frac{1}{N} \sum_{k=0}^{N-1} (N a_k) e^{j k \frac{2\pi}{N} n}$$

$$\omega_0 = \frac{2\pi}{N}$$

$$= \frac{1}{2\pi} \sum_{k=0}^{N-1} (N a_k) e^{j k \omega_0 n} \omega_0$$

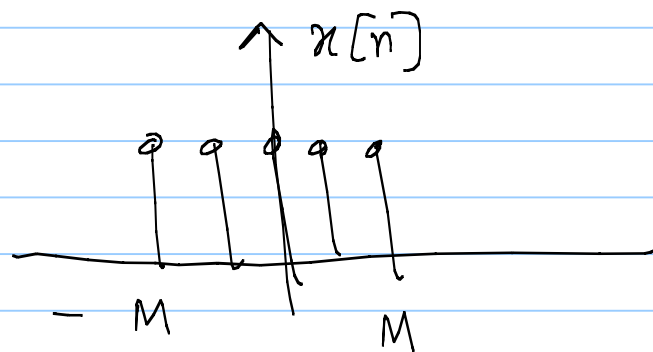
$$\Rightarrow N \rightarrow \infty \quad \omega_0 \rightarrow 0$$

IDTFT

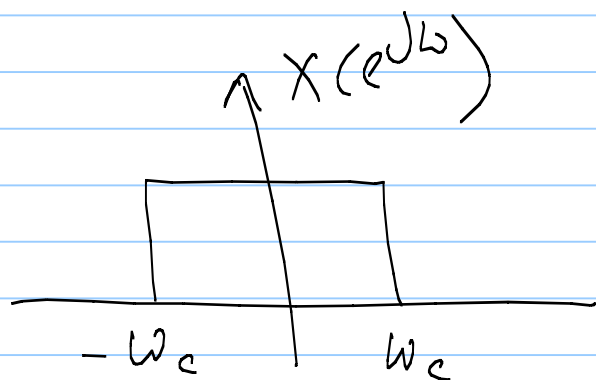
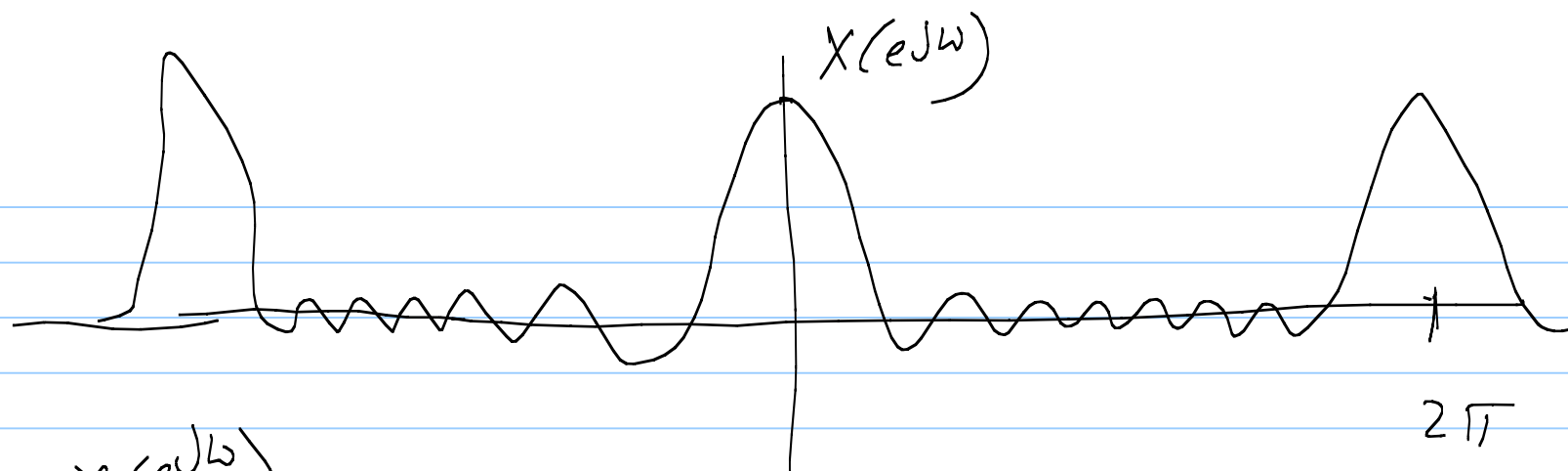
$$\frac{1}{2\pi} \int_0^{2\pi} X(e^{j\omega}) e^{j\omega n} d\omega = x[n]$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$

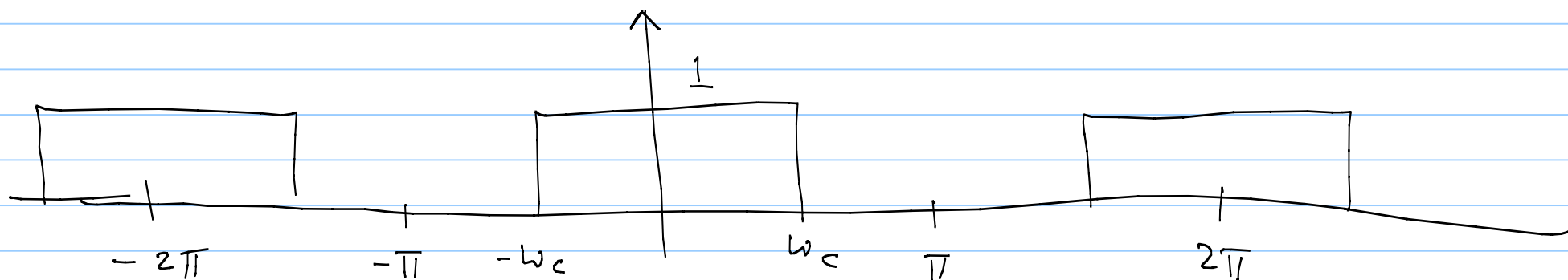
DTFT

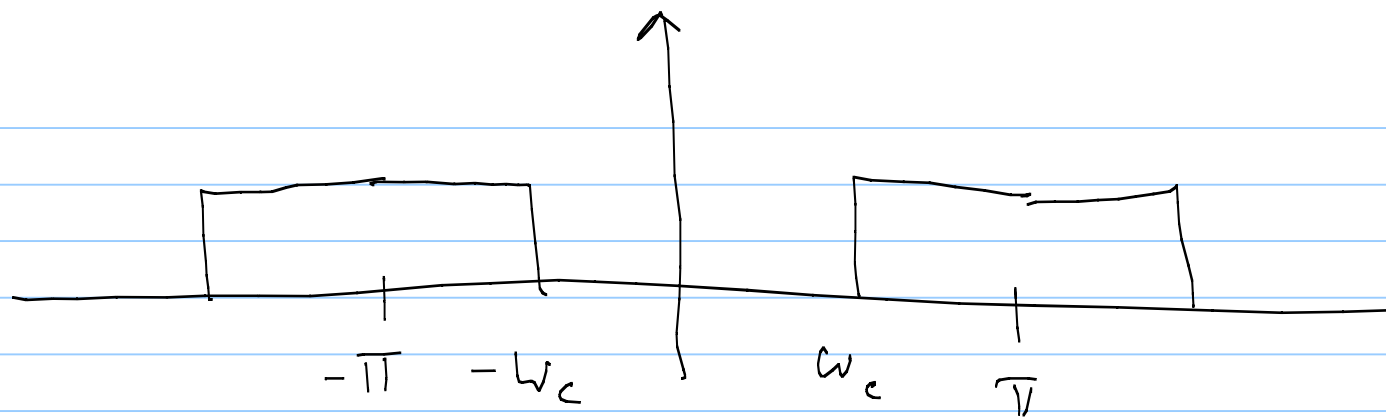


$$X(e^{j\omega}) = \frac{\sin((2M+1)\omega/2)}{\sin \omega/2}$$



$$\longleftrightarrow x[n] = \frac{\sin \omega_c n}{\pi n}$$





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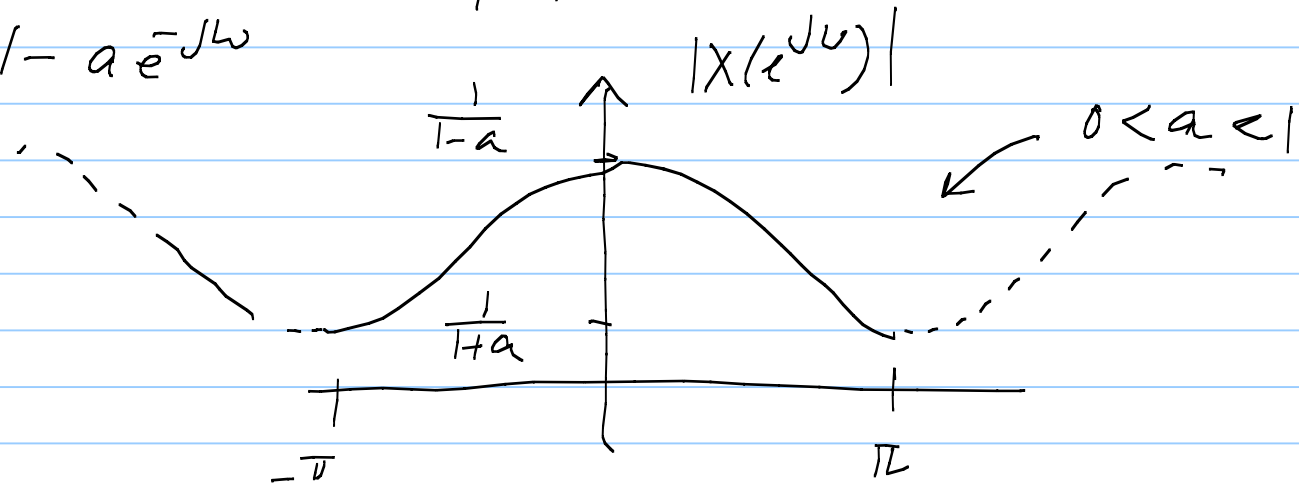
$$a^n u[n] \longleftrightarrow X(e^{j\omega})$$

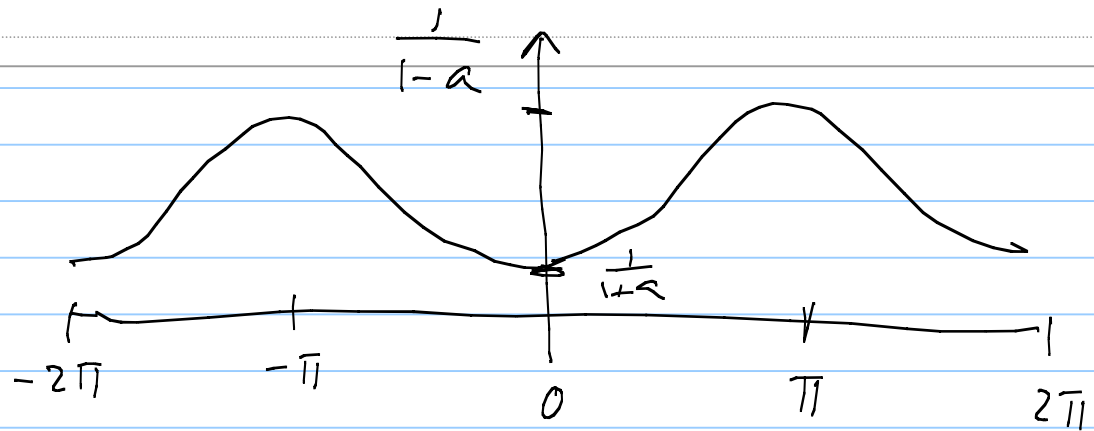
$$\sum_{n=0}^{\infty} a^n e^{-j\omega n} = \frac{1}{1 - a e^{-j\omega}}$$

$$|a| < 1$$

$$(-1)^n a^n u[n]$$

$$\longleftrightarrow \frac{1}{1 + a e^{-j\omega}}$$





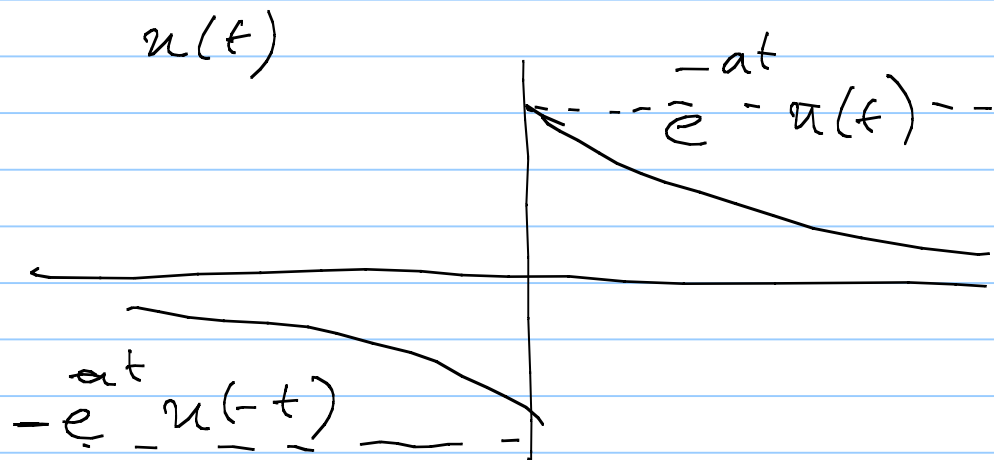
$$u[n] \longleftrightarrow ?$$

Recall:

$$\text{sgn}(t) \longleftrightarrow \frac{2}{j\omega}$$

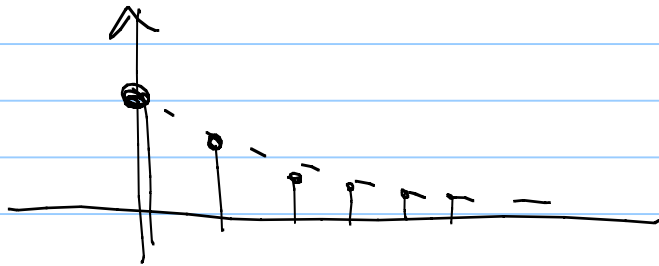
$$\frac{1}{2} \operatorname{sgn}(t) \longleftrightarrow \frac{1}{j\Omega}$$

$$\underbrace{\frac{1}{2} \operatorname{sgn}(t) + \frac{1}{2}} \longleftrightarrow \frac{1}{j\Omega} + \pi \delta(\Omega)$$



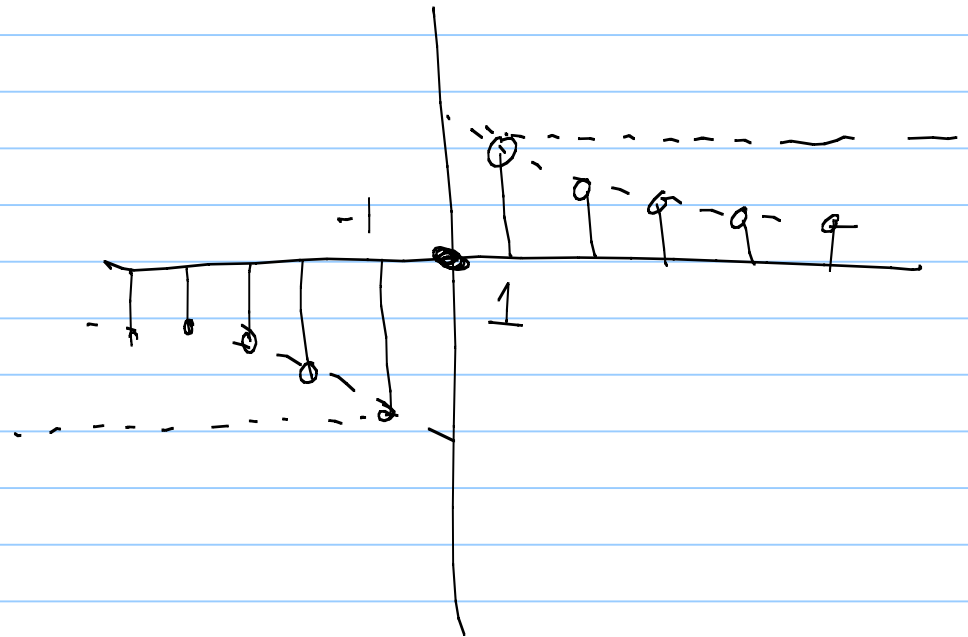
Take limit as $a \rightarrow 0$

$$a^n u[n] \longleftrightarrow \frac{1}{1 - a e^{-j\omega}}$$



$$x[n] \longleftrightarrow X(e^{j\omega})$$

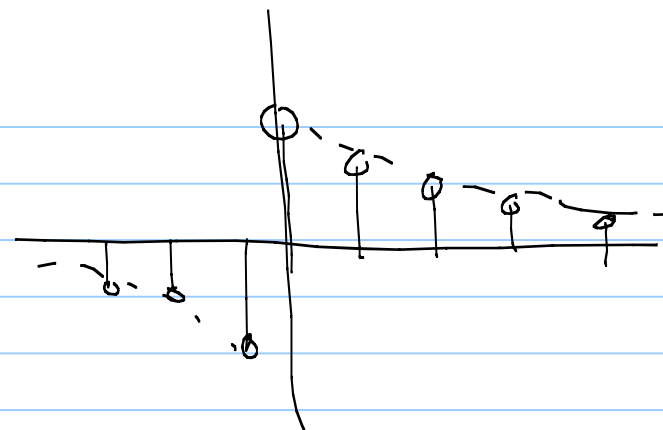
$$x[-n] \longleftrightarrow X(e^{-j\omega})$$



$$a^{-n} u[-n] \longleftrightarrow \frac{1}{1 - a e^{j\omega}}$$

$$a^{-(n+1)} u[-n-1] \longleftrightarrow \frac{e^{j\omega}}{1 - a e^{j\omega}}$$

$$x[-n-n_0] \longleftrightarrow e^{-j\omega n_0} X(e^{j\omega})$$

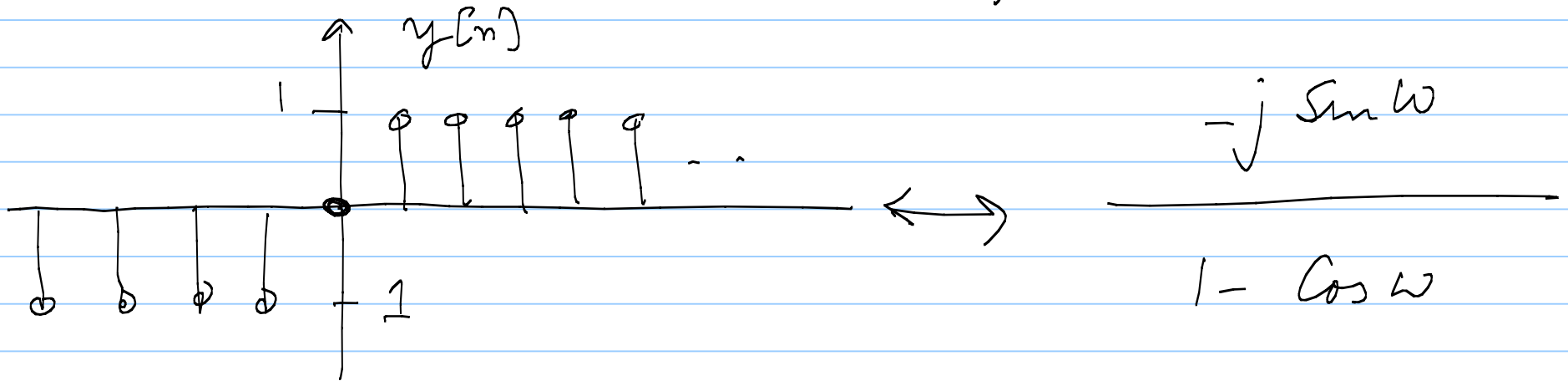


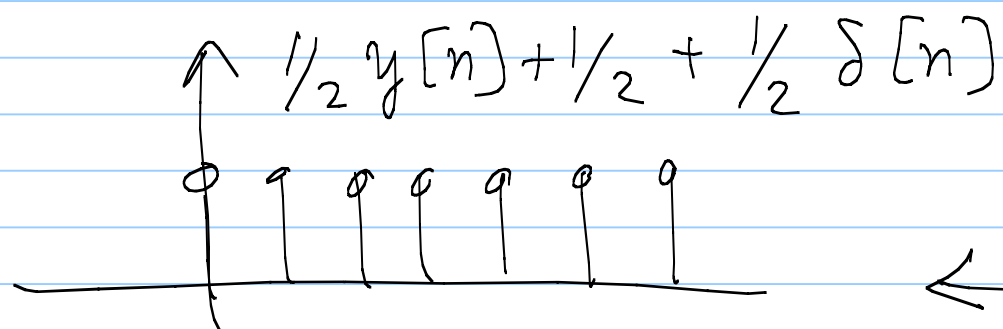
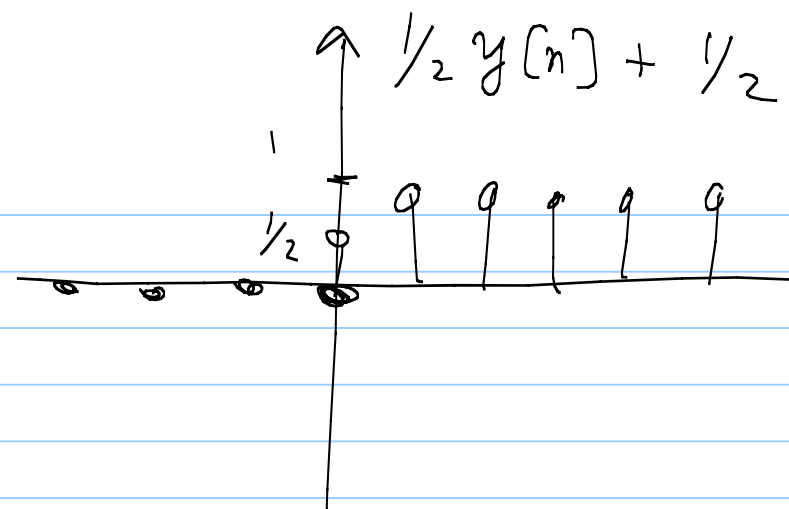
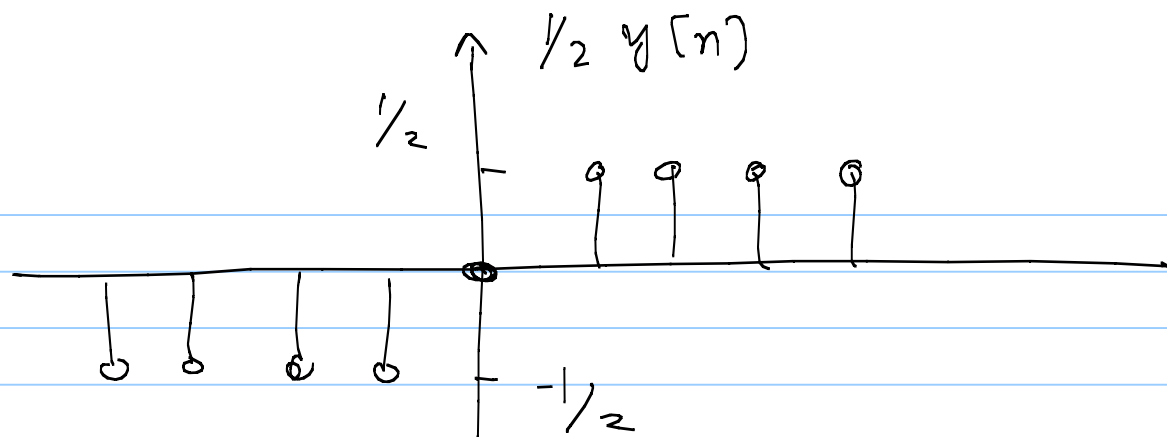
$$a^{-n} u[-n-1] \longleftrightarrow \frac{a e^{j\omega}}{1 - a e^{j\omega}}$$

$$a^n u[n] - a^{-n} u[-n-1] \longleftrightarrow \frac{1}{1 - a e^{-j\omega}} - \frac{a e^{j\omega}}{1 - a e^{j\omega}}$$

$$a^n u[n] - a^{-n} u[-n-1] - \delta[n] \leftrightarrow \frac{1}{1 - a e^{-j\omega}} - \frac{a e^{j\omega}}{1 - a e^{j\omega}} - 1$$

Take Limit as $a \rightarrow 1$ & simplify





$$\longleftrightarrow \frac{1}{1 - e^{-j\omega}} + \pi \delta(\omega)$$

$$-\pi \leq \omega < \pi$$

$$\longleftrightarrow \frac{1}{1 - e^{j\omega}} + \sum_{k=-\infty}^{\infty} \pi \delta(\omega - 2\pi k)$$

$$X(e^{j\omega}) \equiv X(\omega)$$

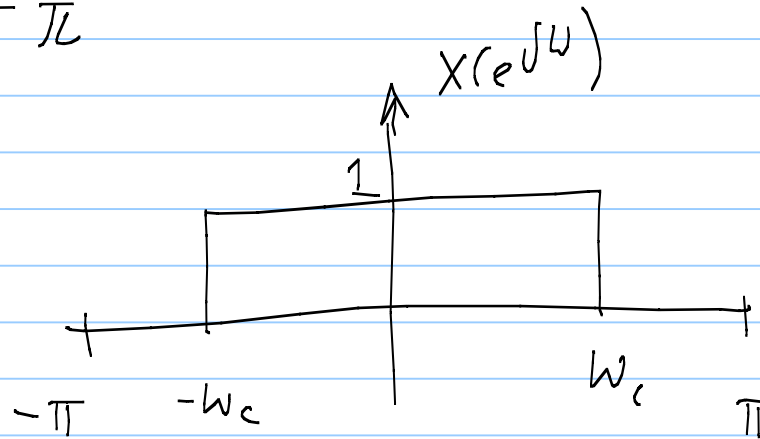
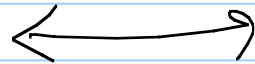
Properties (cont'd)

$$x[n] * y[n] \longleftrightarrow X(e^{j\omega}) Y(e^{j\omega})$$

$$x[n] y[n] \longleftrightarrow \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\theta) Y(\omega - \theta) d\theta$$

$$\sum_{n=-\infty}^{\infty} |x[n]|^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} |X(e^{j\omega})|^2 d\omega$$

$$\frac{\sin \omega_c n}{\pi n}$$



$$\sum_{n=-\infty}^{\infty} x[n] = X(e^{j\omega}) \Big|_{\omega=0}$$

$$\sum_{n=-\infty}^{\infty} \frac{\sin \omega_c n}{\pi n} = 1$$

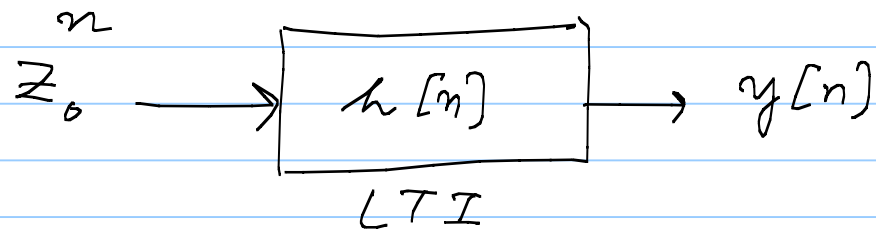
$$\sum_{n=-\infty}^{\infty} \frac{\sin^2 \omega_c n}{\pi^2 n^2} = \frac{\omega_c}{\pi}$$

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$$y[n] = \sum_{m=-\infty}^{\infty} z_0^{n-m} h[m]$$
$$= z_0^n \underbrace{\sum_{m=-\infty}^{\infty} h[m] z_0^{-m}}_{H(z_0)}$$

$$H(z) \equiv \sum_{n=-\infty}^{\infty} h[n] z^{-n} \quad \text{Z-transform of } h[n]$$

$$h[n] \xleftrightarrow{Z} H(z)$$

Eg: $x[n] = a^n u[n]$

$$X(z) = \sum_{n=0}^{\infty} a^n z^{-n} = \sum_{n=0}^{\infty} (a z^{-1})^n$$

$$= \frac{1}{1 - a z^{-1}} \quad |a z^{-1}| < 1$$

$$|a\bar{z}| < 1 = |a| < |z| = \underbrace{|z| > |a|}$$

Region of convergence (ROC)

Eg: $x[n] = -a^n u[-n-1]$

$$X(z) = - \sum_{n=-\infty}^{-1} a^n z^{-n} = \frac{1}{1 - a\bar{z}} \quad |z| < |a|$$

Recall: $X(s) = \int_{-\infty}^{\infty} x(t) e^{-st} dt$ $s = \sigma + j\Omega$

$$e^{+at} u(t) \longleftrightarrow \frac{1}{s-a} \quad \operatorname{Re}\{s\} > \operatorname{Re}\{a\}$$

$$-e^{+at} u(-t) \longleftrightarrow \frac{1}{s-a} \quad \operatorname{Re}\{s\} < \operatorname{Re}\{-a\}$$

$$a^n u[n] \xleftrightarrow{\text{DTFT}} \frac{1}{1 - a e^{-j\omega}} \quad |a| < 1$$

$2^n u[n]$ does NOT possess DTFT

$$2^n u[n] \xleftrightarrow{z} \frac{1}{1 - 2z^{-1}} \quad |z| > 2$$

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n} = X(\omega)$$

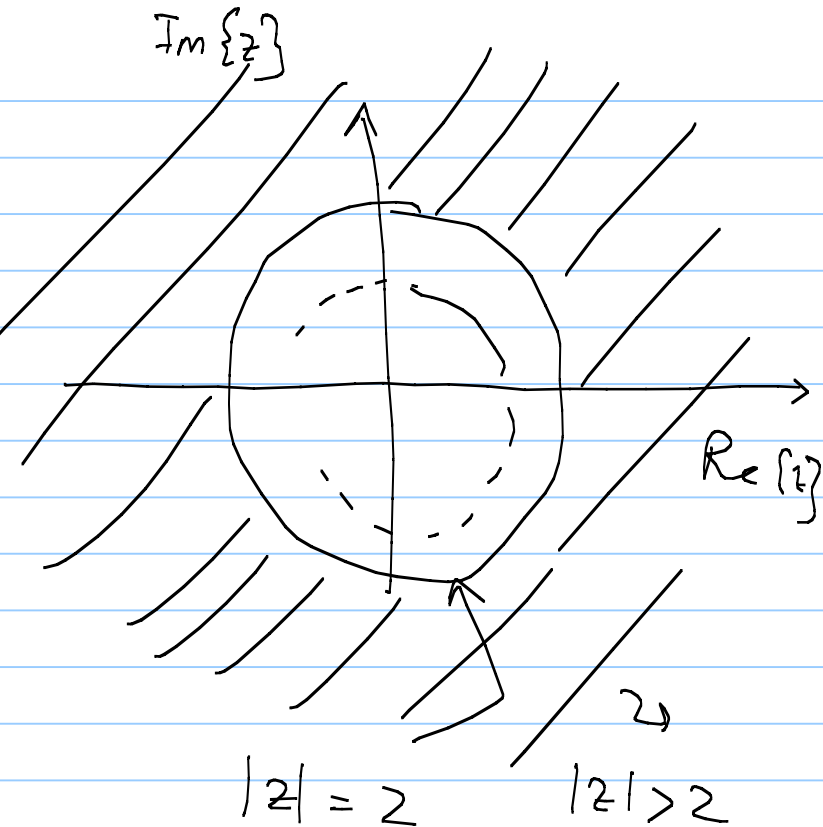
$$X(e^{j\omega}) = X(z) \Big|_{z=e^{j\omega}}$$

$$\frac{1}{2} u[n] \longleftrightarrow \frac{1}{1 - 2z^{-1}} \quad |z| > 2$$

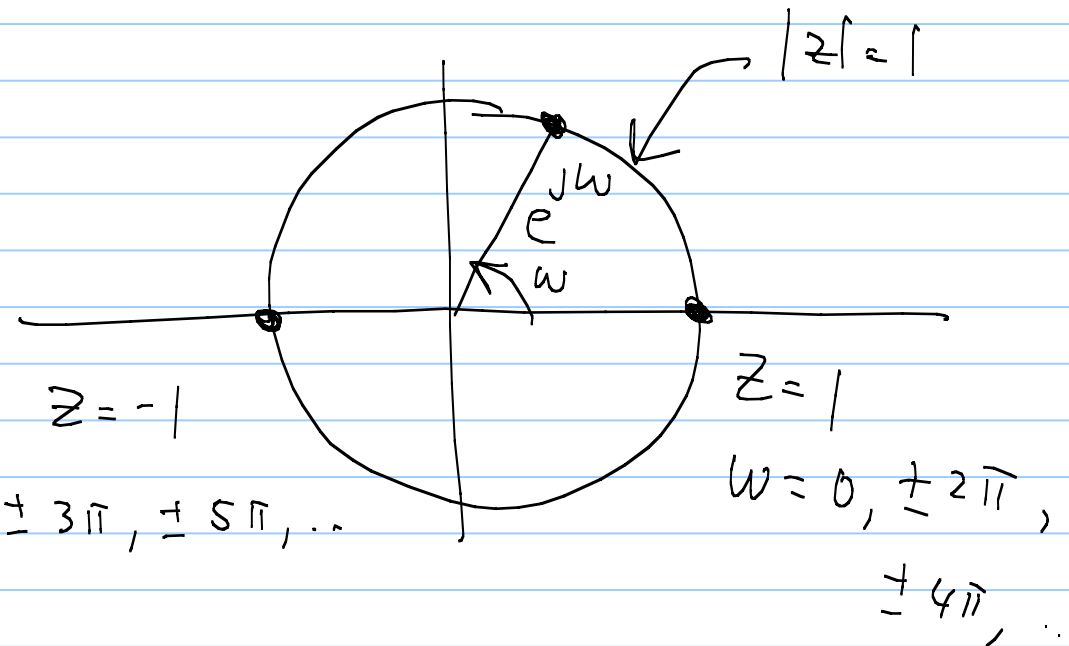
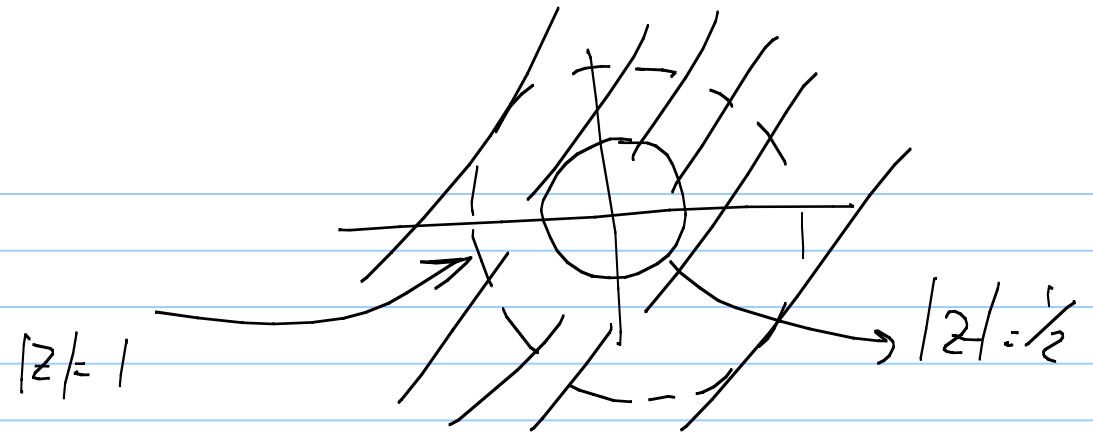
DTFT does not exist since

$$z = e^{j\omega} \notin \text{ROC}$$

$$\left(\frac{1}{2}\right)^n u[n] \longleftrightarrow \frac{1}{1 - \frac{1}{2}z^{-1}} \quad |z| > \frac{1}{2}$$



$$\frac{1}{2}^n u[n] \longleftrightarrow \frac{1}{1 - \frac{1}{2} e^{-j\omega}}$$



$$\sum_{n=-\infty}^{\infty} x[n] r^{-n} e^{-j\omega n}$$

$$z = r e^{j\omega}$$

$$2^n x[n] \rightarrow \sum_{n=0}^{\infty} \left(\frac{2}{r}\right)^n e^{-j\omega n} \quad \text{exists for } r > 2$$

In general,

$$\sum_{n=-\infty}^{\infty} x[n] z^{-n} = \sum_{n=-\infty}^{\infty} x[n] r^{-n} e^{-j\omega n} = X(z)$$

$$|X(z)| = \left| \sum_{n=-\infty}^{\infty} x[n] r^{-n} e^{-j\omega n} \right|$$

$$\leq \sum_{n=-\infty}^{\infty} |x[n]| r^{-n} < \infty \Rightarrow \text{transform exists}$$

$$= \underbrace{\sum_{n=0}^{\infty} \frac{|x[n]|}{r^n}}_{\text{causal part}} + \underbrace{\sum_{n=1}^{\infty} \frac{|x[-n]|}{r^n}}_{\text{anticausal part}}$$

(A)

(B)

Suppose (A) exist for $r = r_1$
then (A) surely exist for all $r > r_1$

Suppose (B) exist for $r = r_2$
then (B) surely exists for all $r < r_2$

$\therefore$ The ROC is, in general of the form

$$r_1 < |z| < r_2$$

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The RoC for a general $x[n]$ is of the form

$$r_1 < |z| < r_2$$

r_1 can be as small as zero

r_2 can be as large as ∞

For finite duration sequences, $X(z)$ is

$$x[-M]z^M + x[-M+1]z^{M-1} + \dots + x[-1]z + x[0] \\ + x[1]z^{-1} + x[2]z^{-2} + \dots + x[N]z^{-N}$$

$$z = 0 \notin \text{ROC} \quad z = \infty \notin \text{ROC}$$

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ROC = entire z -plane except 0 and/or ∞

In general if $z = r e^{j\omega} \in \text{ROC}$, then
 $r e^{j\omega} \in \text{ROC} \quad \forall \omega \in [-\pi, \pi)$

$$X(z) = \frac{P(z)}{Q(z)} \quad P(z) \text{ \& } Q(z) \text{ are polynomials in } z$$

then $X(z)$ is said to be rational

roots of $P(z)$ are called ZEROS of $X(z)$

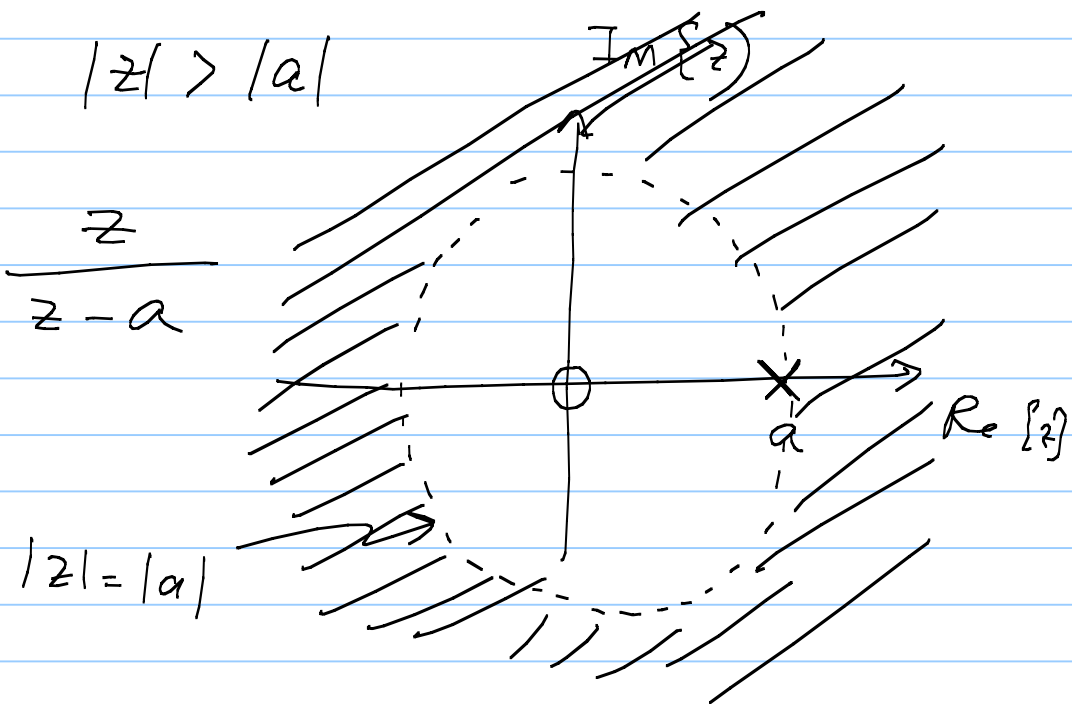
roots of $Q(z)$ are called POLES of $X(z)$

$$a^n u[n] \longleftrightarrow \frac{1}{1 - a z^{-1}}$$

$$= \frac{z}{z - a}$$

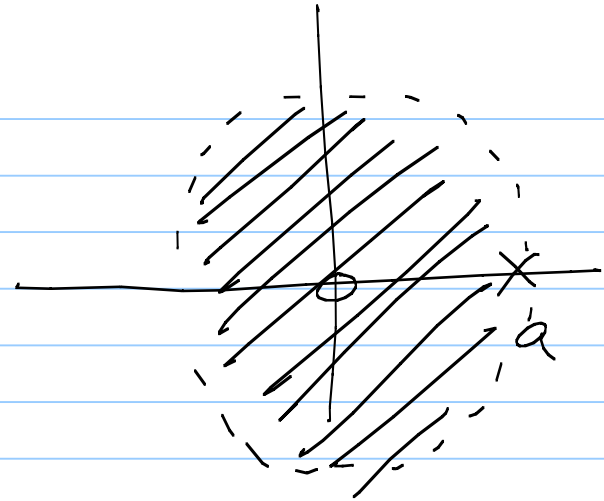
pole: $z = a$

zero: $z = 0$



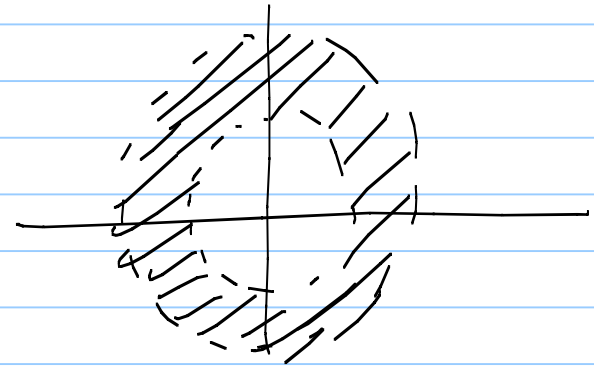
$$-a^n u[-n-1] \leftrightarrow \frac{1}{1-a\bar{z}'} \quad |z| < |a|$$

ROC cannot contain poles



For rational $X(z)$:

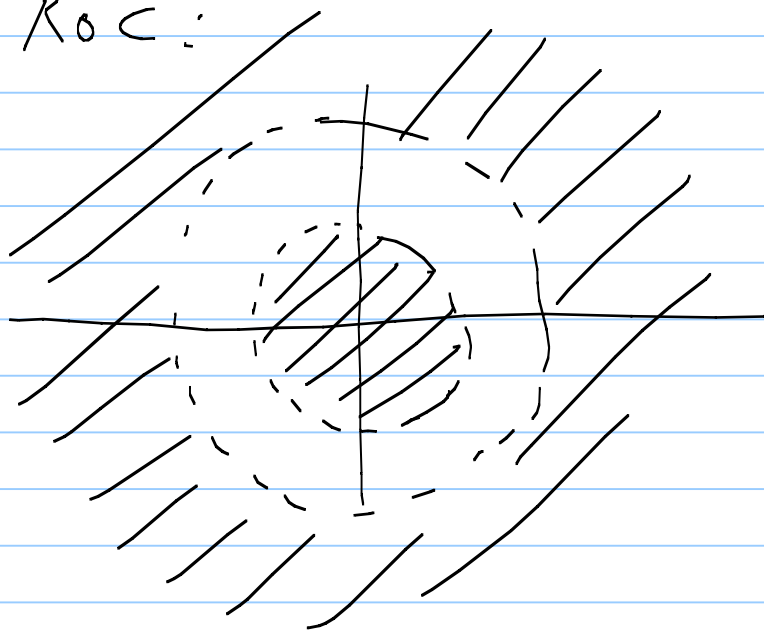
(a) ROC is an annular region



(b) ROC cannot contain poles

(c) R_oC must be a connected region on

Invalid R_oC :



(d) For finite duration sequences, R_oC is the entire z -plane except possibly for 0 and/or ∞

(e) For right sided sequences, the ROC is a circle with radius R_1 s.t. ROC is of the form $R_1 < |z| \leq \infty$

(f) For left sided sequences, the ROC is bounded by a circle of radius R_2 s.t. the ROC is of the form $0 \leq |z| < R_2$

$X(z)$ is an analytic function in the ROC

$$z = x + j y$$

$$X(z) = U(x, y) + j V(x, y)$$

$$\left. \begin{array}{l} U_x = V_y \\ U_y = -V_x \end{array} \right\} \text{Cauchy-Riemann Equations}$$

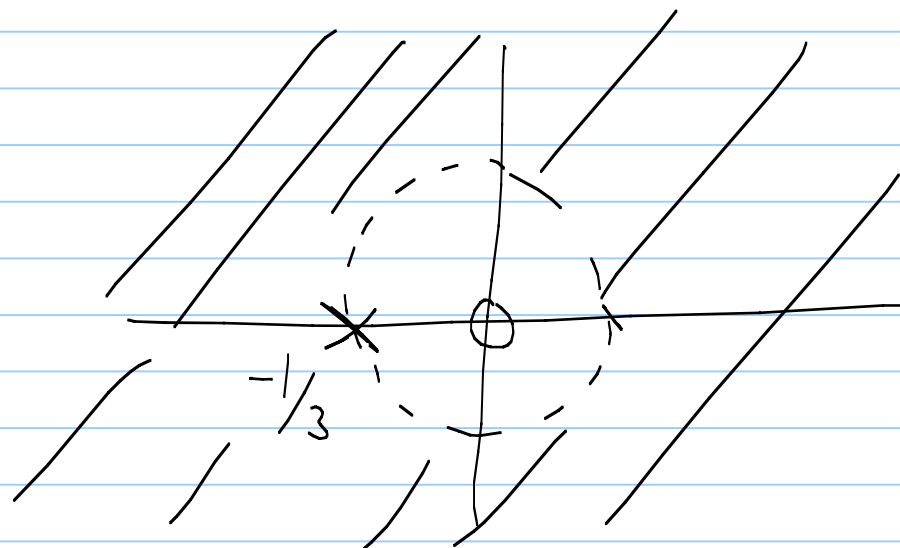
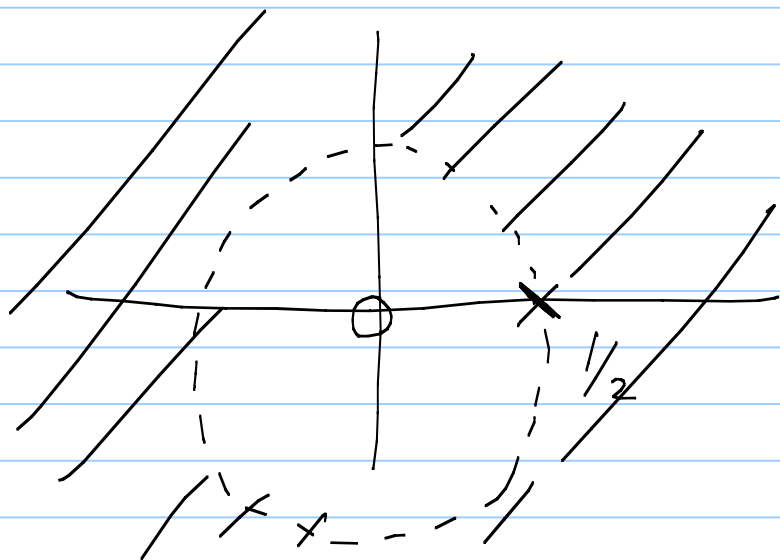
Properties

$$a_1 x_1[n] + a_2 x_2[n] \longleftrightarrow a_1 X_1(z) + a_2 X_2(z)$$

$$ROC \supseteq ROC_{x_1} \cap ROC_{x_2}$$

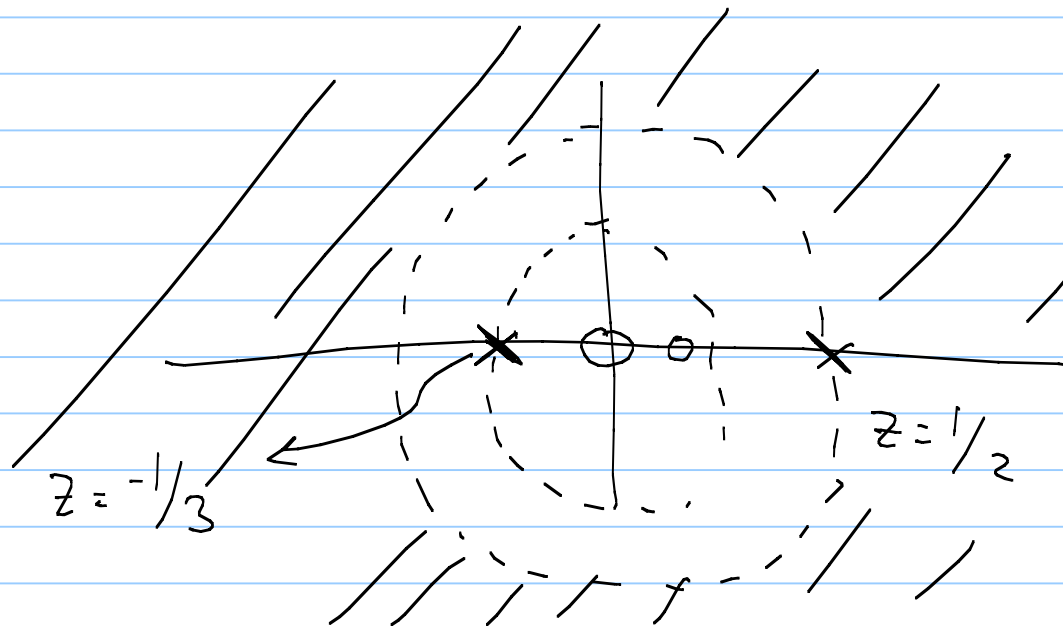
$$\left(\frac{1}{2}\right)^n u[n] \longleftrightarrow \frac{1}{1 - \frac{1}{2} \bar{z}^{-1}} \quad |z| > \frac{1}{2}$$

$$\left(-\frac{1}{3}\right)^n u[n] \longleftrightarrow \frac{1}{1 + \frac{1}{3} \bar{z}^{-1}} \quad |z| > \frac{1}{3}$$



$$X(z) = \frac{1}{1 - \frac{1}{2} \bar{z}'} + \frac{1}{1 + \frac{1}{3} \bar{z}'} = \frac{2(1 - \frac{1}{2} \bar{z}')}{(1 - \frac{1}{2} \bar{z}')(1 + \frac{1}{3} \bar{z}')}$$

$$|z| > \frac{1}{2} \cap |z| > \frac{1}{3} \quad |z| > \frac{1}{2}$$



$$\frac{2z(z - \frac{1}{2})}{(z - \frac{1}{2})(z - \frac{1}{3})}$$

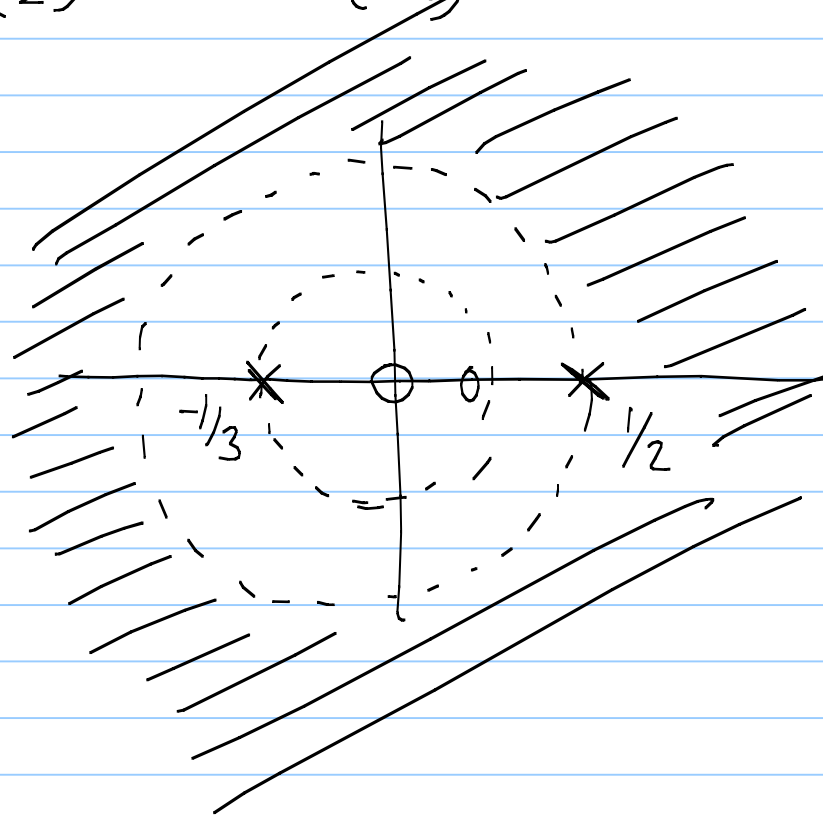
EC5142 Oct. 11, 2011

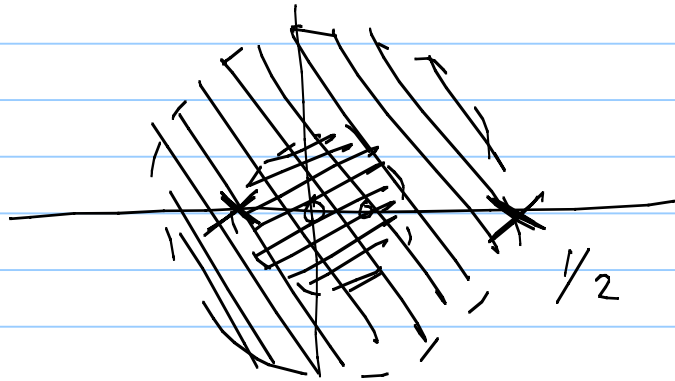
Note Title

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$$\left(\frac{1}{2}\right)^n u[n] + \left(-\frac{1}{3}\right)^n u[n] \longleftrightarrow$$

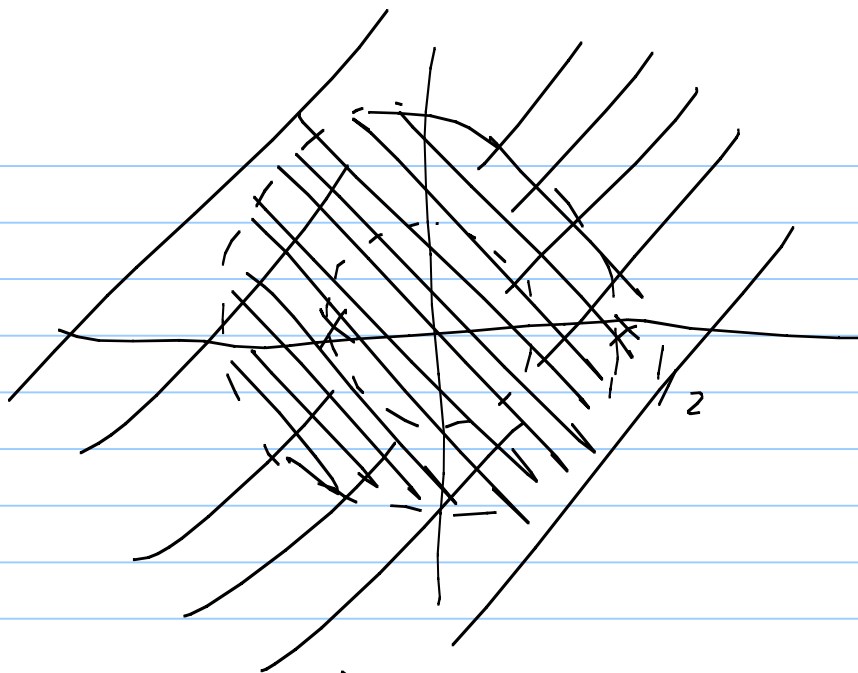
$$\frac{2(1 - \frac{1}{12}\bar{z}')}{(1 - \frac{1}{2}\bar{z}')(1 + \frac{1}{3}\bar{z}')} \quad |z| > \frac{1}{2}$$





$$|z| < 1/3 \cap |z| < 1/2 = |z| < 1/3$$

$$= \left(-\frac{1}{3}\right)^n u[-n-1] - \left(\frac{1}{2}\right)^n u[-n-1]$$



$$|z| > 1/3 \cap |z| < 1/2$$

$$= 1/3 < |z| < 1/2$$

$$\left(-\frac{1}{3}\right)^n u[n]$$

$$- \left(\frac{1}{2}\right)^n u[-n-1]$$

Time Delay

$$x[n-n_0] \longleftrightarrow z^{-n_0} X(z)$$

ROC is identical except possibly for addition or deletion of 0 and/or ∞

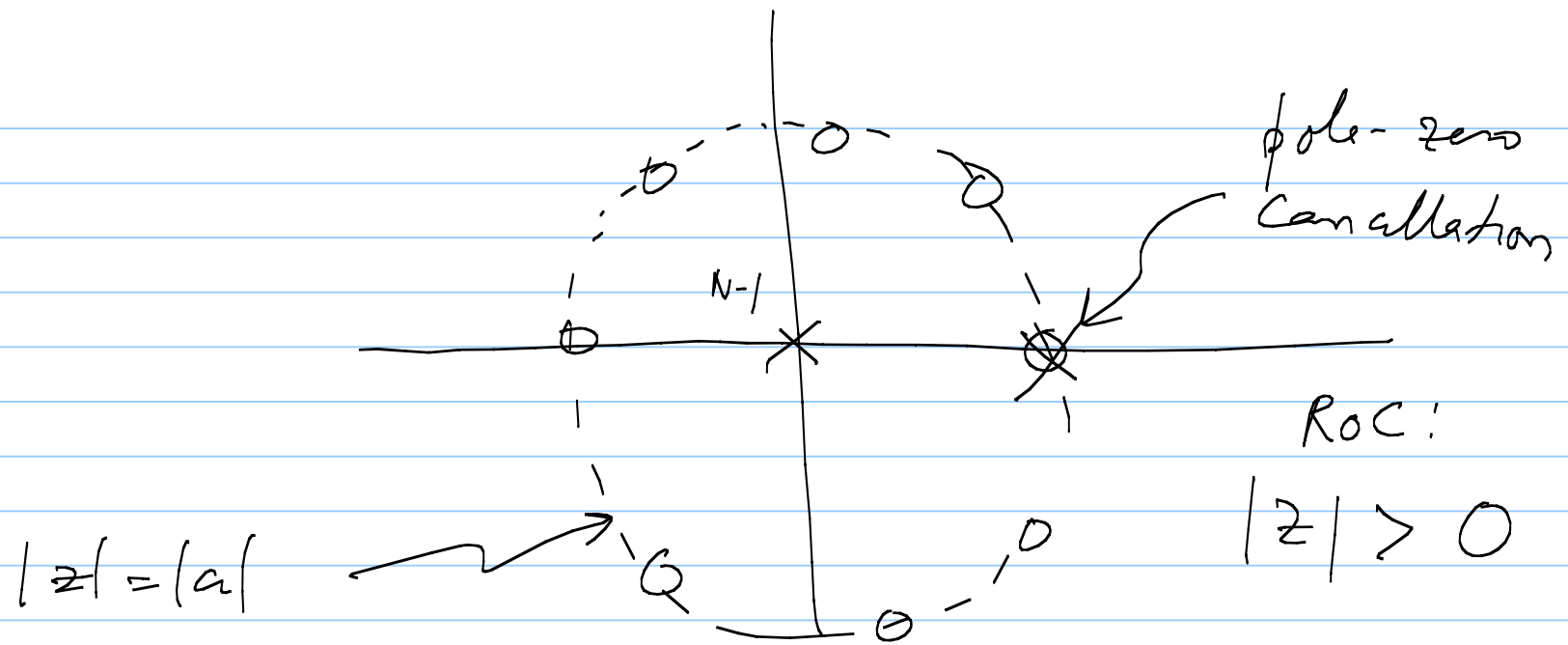
$$a^n u[n] \longleftrightarrow \frac{1}{1 - a\bar{z}} \quad |z| > |a|$$

$$a^{n-N} u[n-N] \longleftrightarrow \frac{z^{-N}}{1 - a\bar{z}}$$

$$a^n u[n-N] \longleftrightarrow \frac{a^{N-N} z^N}{1 - a z^{-1}} \quad |z| > |a|$$

$$a^n [u[n] - u[n-N]] \longleftrightarrow \frac{1 - a^{N-N} z^N}{1 - a z^{-1}}$$

$$1, a, a^2, \dots, a^{N-1} = \frac{z^N - a^N}{z^{N-1} (z - a)}$$



pole or zero at the origin: "trivial" pole / zero

Un cancelled nontrivial pole: $\frac{1}{1 - a\bar{z}^{-1}}$

gives rise to either $a^n u[n]$ or $-a^n u[-n-1]$

(depends on RoC) $\Rightarrow \infty$ -duration sequence.

If there are only trivial poles, then

the sequence is finite duration

$$1, a, a^2, \dots, a^{N-1} \longleftrightarrow 1 + a z^{-1} + a^2 z^{-2} + \dots + a^{N-1} z^{-(N-1)}$$

"All zero filter"

$$\frac{z^{N-1} + a z^{N-2} + \dots + a^{N-1}}{z^{N-1}}$$

$N-1$ zeros

$N-1$ trivial poles

$$X(z) = \frac{1}{1 + a_1 z^{-1} + \dots + a_{N-1} z^{-(N-1)}}$$

"All pole filter"

$$X(z) = \frac{P(z)}{Q(z)} \quad \text{"pole zero filter"}$$

$$\frac{1}{(1 - a z^{-1})(1 - b z^{-1})} = \frac{z^2}{(z - a)(z - b)}$$

$$\frac{z}{(z-a)(z-b)} \Rightarrow \begin{array}{l} \text{poles: } z = a, b \\ \text{zero: } z = 0, \infty \end{array}$$

$$\frac{(z-a)(z-b)}{z} \begin{array}{l} \text{zero: } z = a, b \\ \text{poles: } z = 0, \infty \end{array}$$

Exponential Multiplication

$$x[n] \leftrightarrow X(z) \quad r_1 < |z| < r_2$$

$$a^n x[n] \leftrightarrow \sum_{n=-\infty}^{\infty} x[n] \left(\frac{z}{a}\right)^{-n} \leftrightarrow X\left(\frac{z}{a}\right)$$

$$r_1 < \left|\frac{z}{a}\right| < r_2$$

$$|a| r_1 < |z| < |a| r_2$$

Suppose z_0 is a zero of $X(z)$, i.e. $X(z_0) = 0$

$$y[n] = a^n x[n] \iff Y(z) = X(z/a)$$

$$Y(az_0) = X(az_0/a) = X(z_0) = 0$$

$\Rightarrow az_0$ is a root of $Y(z)$

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$$r^n x[n] \longleftrightarrow X(z/r) \quad |r| r_1 < |z| < |r| r_2$$

$$\sum_{n=-\infty}^{\infty} x[n] z^{-n} = \frac{1}{1 - z^{-1}} = X(z) \quad |z| > 1$$

$$a^n x[n] \longleftrightarrow X(z/a) \quad |z/a| > 1$$

$$\frac{1}{1 - (z/a)^{-1}} = \frac{1}{1 - a z^{-1}} \quad |z| > |a|$$

$$e^{j\omega_0 n} x[n] \longleftrightarrow X\left(\frac{z}{e^{j\omega_0}}\right) \quad \text{ROC is same}$$

$$\text{DTFT} : X(z) \Big|_{z=e^{j\omega}}$$

$$e^{j\omega_0 n} x[n] \xleftrightarrow{\text{DTFT}} X\left(\frac{e^{j\omega}}{e^{j\omega_0}}\right) = X(e^{j(\omega-\omega_0)})$$

Differentiation in the Z-Domain

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

$$\frac{dX}{dz} = \sum_{n=-\infty}^{\infty} x[n] (-n z^{-n-1})$$

$$-z \frac{dX}{dz} = \sum_{n=-\infty}^{\infty} n x[n] z^{-n}$$

$$n x[n] \longleftrightarrow -z \frac{dx}{dz}$$

ROC is same
except possibly for the
boundary circle

Eg

$$x[n] = \begin{cases} \frac{1}{n^2} & n > 1 \\ 0 & n \leq 0 \end{cases}$$

$X(z)$ — dilogarithm function $|z| \geq 1$

$$n x[n] = \begin{cases} \frac{1}{n} & n \geq 1 \\ 0 & n \leq 0 \end{cases}$$

$$X(z) : \text{Roc } |z| > 1$$

$$a^n x[n] \longleftrightarrow \frac{1}{1 - a\bar{z}^{-1}} \quad |z| > |a|$$

$$n a^n x[n] \longleftrightarrow -z \frac{d}{dz} \frac{1}{1 - a\bar{z}^{-1}} \quad |z| > |a|$$

$$= (z) \frac{-(-a)(-\bar{z}^2)}{(1 - a\bar{z}^{-1})^2}$$

$$= \frac{a\bar{z}^{-1}}{(1 - a\bar{z}^{-1})^2} \quad |z| > |a|$$

$$(n+1) a^{n+1} u[n+1] \longleftrightarrow \frac{a}{(1 - a\bar{z}^{-1})^2} \quad |z| > |a|$$

$$(n+1) a^n u[n+1] \longleftrightarrow \frac{1}{(1 - a\bar{z}^{-1})^2} \quad |z| > |a|$$

$$(n+1) a^n u[n] \longleftrightarrow \frac{1}{(1 - a\bar{z}^{-1})^2} \quad |z| > |a|$$

$$\} \longleftrightarrow \frac{1}{(1 - a\bar{z}^{-1})^m} \quad |z| > |a|$$

Exponential mult.

$$\frac{1}{2} r^n e^{j\omega_0 n} u[n] \longleftrightarrow \frac{1/2}{1 - \left(\frac{z}{r e^{j\omega_0}} \right)^{-1}} \quad |z| > r$$

$$= \frac{1/2}{1 - r e^{j\omega_0} z^{-1}}$$

$$\frac{1}{2} r^n e^{-j\omega_0 n} u[n] \longleftrightarrow \frac{1/2}{1 - r e^{-j\omega_0} z^{-1}} \quad |z| > r$$

$$r^n \cos \omega_0 n u[n] \longleftrightarrow \frac{1 - r \cos \omega_0 z^{-1}}{1 - 2r \cos \omega_0 z^{-1} + r^2 z^{-2}}$$

$$(1 - r e^{j\omega_0} z^{-1})(1 - r e^{-j\omega_0} z^{-1})$$

Suppose $x[n]$ is real-valued. $x[n] = x^*[n]$

$$X(z) = \sum_{n=-\infty}^{\infty} x^*[n] z^{-n}$$
$$= \left[\sum_{n=-\infty}^{\infty} x[n] (z^*)^{-n} \right]^*$$

$$= X^*(z^*)$$

$$X^*(z) = X(z^*)$$

Suppose z_0 is a root of $X(z)$.

$$X(z_0) = 0$$

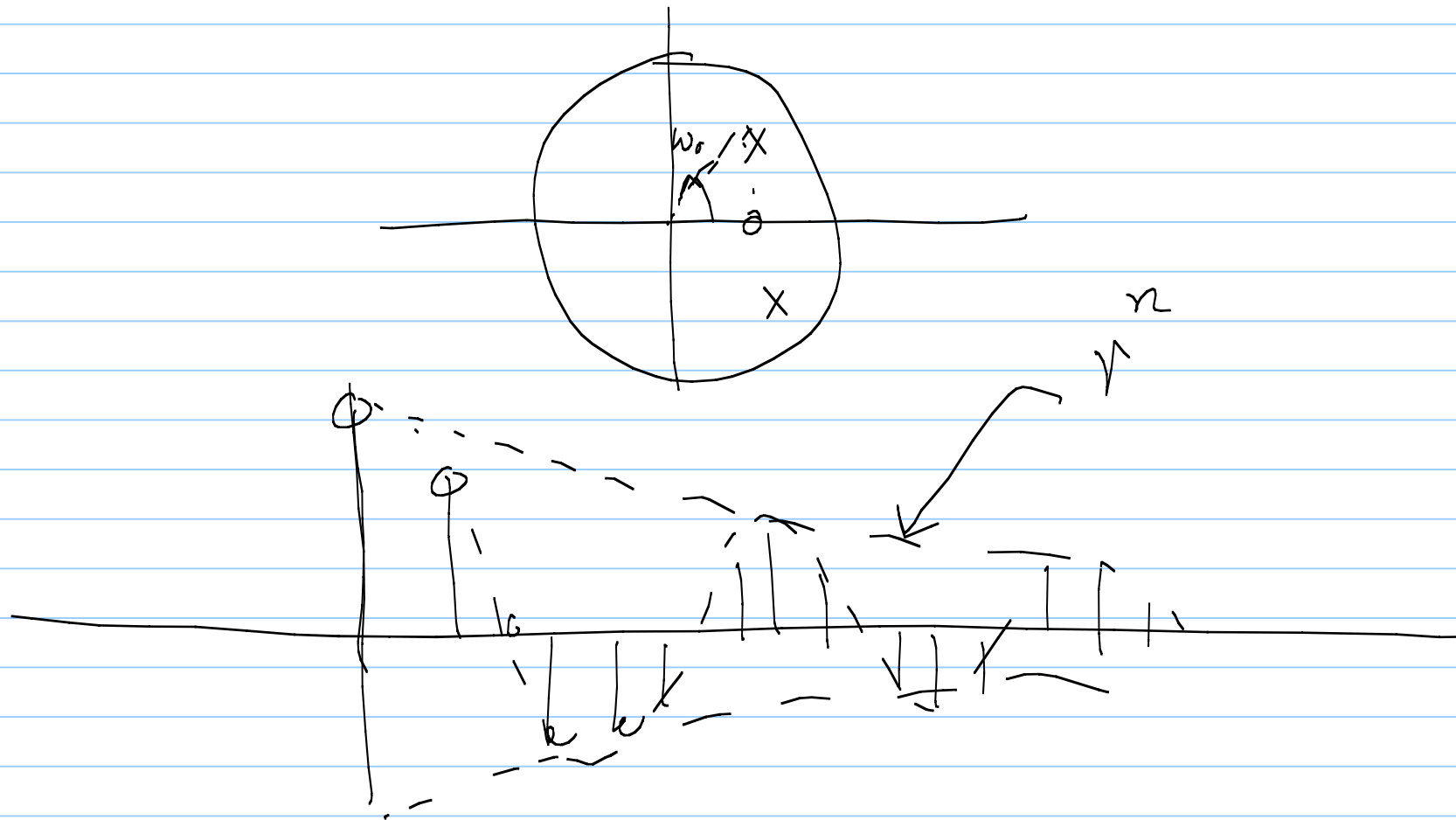
$$X^*(z_0) = 0$$

$$X(z_0^*) = 0$$

$\Rightarrow z_0^*$ is also a root

$$X(z) = \frac{B(z)}{A(z)} = \frac{b_0 + b_1 \bar{z}^1 + \dots + b_M \bar{z}^M}{1 + a_1 \bar{z}^1 + \dots + a_N \bar{z}^N}$$

$$b_k, a_k \in \mathbb{R}$$



Time Reversal

$$x[n] \longleftrightarrow X(z) \quad r_1 < |z| < r_2$$

$$x[-n] \longleftrightarrow X(\bar{z}^{-1}) \quad 1/r_2 < |z| < 1/r_1$$

$$a^n x[n] \longleftrightarrow \frac{1}{1 - a\bar{z}^{-1}} \quad |z| > |a|$$

$$a^{-n} x[-n] \longleftrightarrow \frac{1}{1 - az} \quad |z| < 1/|a|$$

$$= \frac{-\bar{a}^{-1} \bar{z}^{-1}}{1 - \bar{a}^{-1} \bar{z}^{-1}}$$

$$a^{-n-1} u[-n-1] \longleftrightarrow \frac{-\bar{a}^{-1}}{1 - \bar{a}^{-1} \bar{z}^{-1}} \quad |z| < |\bar{a}^{-1}|$$

$$-(\bar{a}^{-1})^n u[-n-1] \longleftrightarrow \frac{1}{1 - \bar{a}^{-1} \bar{z}^{-1}} \quad |z| < |\bar{a}^{-1}|$$

$$x[-n] \longleftrightarrow X(\bar{z}^{-1}) \quad \frac{1}{r_2} < |z| < \frac{1}{r_1}$$

$$(-1)^n x[n] \longleftrightarrow X(-z) \quad \text{ROC is same}$$

Convolution in the Time Domain

$$y[n] = \sum_{m=-\infty}^{\infty} x[m] h[n-m]$$

$$= x[n] * h[n]$$

$$Y(z) = X(z)H(z)$$

$$Roc \supseteq Roc_x \cap Roc_h$$

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Convolution in the time domain:

$$y[n] = x[n] * h[n]$$

$$Y(z) = \sum_{n=-\infty}^{\infty} y[n] z^{-n}$$

$$= \sum_{n=-\infty}^{\infty} \left[\sum_{m=-\infty}^{\infty} x[m] h[n-m] \right] z^{-n}$$

$$= \sum_{m=-\infty}^{\infty} x[m] \left[\sum_{n=-\infty}^{\infty} h[n-m] z^{-n} \right]$$

$$= \sum_{m=-\infty}^{\infty} x[m] H(z) z^{-m}$$

$$= H(z) X(z)$$

$$Roc \supseteq Roc_x \cap Roc_h$$

$$a^n u[n] * (-b^n u[-n-1]) \longleftrightarrow \frac{1}{(1-a\bar{z}')(1-b\bar{z}')}$$

$$\downarrow$$

$$\frac{1}{1-a\bar{z}'}$$

$$\downarrow$$

$$\frac{1}{1-b\bar{z}'}$$

$$|a| < |z| < |b|$$

$$|z| > |a|$$

$$|z| < |b|$$

Multiplication in the time Domain

$$X(\theta) \equiv X(e^{j\theta})$$

$$x[n] h[n] \xleftrightarrow{\text{DTFT}} \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\theta) H(\omega - \theta) d\theta$$

$$\sum_{n=-\infty}^{\infty} x[n] h[n] e^{-j\omega n}$$

$$= \sum_{n=-\infty}^{\infty} \left[\frac{1}{2\pi} \int_{-\pi}^{\pi} X(\theta) e^{j\theta n} d\theta \right] h[n] e^{-j\omega n}$$

$$? = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\theta) \left[\sum_{n=-\infty}^{\infty} h[n] e^{-j(\omega-\theta)n} \right] d\theta$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\theta) H(\omega-\theta) d\theta \quad \text{circular convolution}$$

What about corresponding z-transform property?

$$x[n] h[n] \xleftrightarrow{z} ?$$

Will turn out to be complex convolution

[Complex Variables & Laplace Transform for Engineers
— Wilbur LePage, Dover]

Initial Value Theorem $x[n] = 0 \quad n < 0$

$$X(z) = x[0] + x[1]z^{-1} + x[2]z^{-2} + \dots$$

$$\lim_{z \rightarrow \infty} X(z) = x[0]$$

Final Value Theorem

Let $v[n]$ be right sided,

$$\text{i.e. } v[n] = 0 \quad n < M$$

$$\text{Let } x[n] = v[n] - v[n-1]$$

$$X(z) = (1 - z^{-1})V(z)$$

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

$$= \sum_{n=M}^{\infty} (v[n] - v[n-1]) z^{-n}$$

$$\lim_{z \rightarrow 1} X(z) = \sum_{n=M}^{\infty} (v[n] - v[n-1])$$

$$= \lim_{N \rightarrow \infty} \sum_{n=M}^N (v[n] - v[n-1])$$

$$= \lim_{N \rightarrow \infty} \left[\begin{aligned} &v[M] - v[M-1] \\ &+ v[M+1] - v[M] \\ &+ \dots \\ &+ v[N-1] - v[N-2] + v[N] \end{aligned} \right]$$

$$= \lim_{N \rightarrow \infty} \left[\underset{\downarrow}{v[N-1]} + v[N] \right]$$

$$= v[\infty]$$

$$= \lim_{z \rightarrow 1} X(z)$$

$$= \lim_{z \rightarrow 1} (1 - \bar{z}^{-1}) V(z)$$

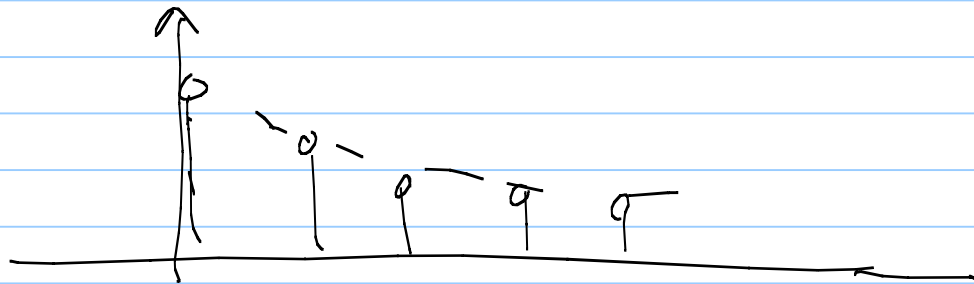
$$v[\infty] = \lim_{z \rightarrow 1} (1 - \bar{z}^{-1}) V(z)$$

Eg: $x[n] = \left(\frac{1}{3}\right)^n u[n] + 2u[n] + \left(-\frac{1}{2}\right)^n u[n]$

$$x[\infty] = 2$$

Verify Final Value Theorem for above Example

$$a^n u[n] \longleftrightarrow \frac{1}{1 - a z^{-1}} \quad |z| > |a|$$



$a^n \xleftrightarrow{z}$ does not exist

$1 \xleftrightarrow{z}$ - do -

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$$x[n] * h[n] \longleftrightarrow X(z) H(z) \quad \text{Roc} \supseteq \text{Roc}_x \cap \text{Roc}_h$$

$$x[n] h[n] \longleftrightarrow \text{complex convolution}$$

$$a^n u[n] = x[n] \xleftrightarrow{z} \frac{1}{1 - a\bar{z}^{-1}} \quad |z| > |a|$$

$$h[n] = a^n u[n]$$

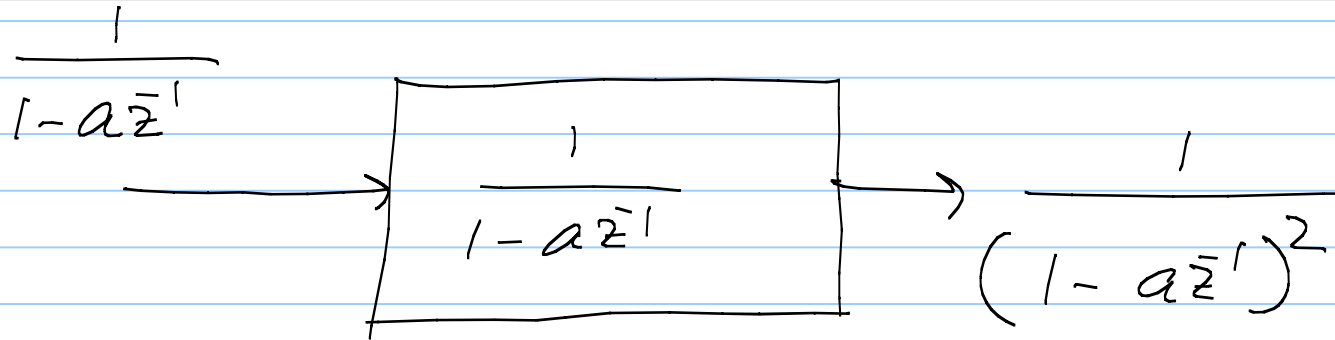
$$y[n] - a y[n-1] = x[n]$$

$$x[n] = b^n u[n]$$

$$x[n] = a^n x[n]$$

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Methods of Inversion

If $X(z)$ is rational, i.e.

$$X(z) = \frac{B(z)}{A(z)}$$

$\nwarrow M^{\text{th}} \text{ order}$
 $\swarrow N^{\text{th}} \text{ order}$

$$\begin{aligned}
 &= \frac{b_0 + b_1 \bar{z}^{-1} + \dots + b_m \bar{z}^{-m}}{1 \cancel{a_0} + a_1 \bar{z}^{-1} + \dots + a_N \bar{z}^{-N}} \\
 &= \frac{b_0 \prod_{l=1}^m (1 - z_l \bar{z}^{-1})}{\prod_{k=1}^N (1 - p_k \bar{z}^{-1})}
 \end{aligned}$$

Suppose $b_0 = b_1 = b_2 = \dots = b_{k-1} = 0$

$$X(z) = \frac{z^{-k} B_1(z)}{A(z)}$$

1.2. We can find the inverse transform of $\frac{B_1(z)}{A(z)}$

& shift the inverse transform appropriately.

Similarly for $A(z)$

Assume $M < N$, simple roots.

$$X(z) = \frac{B(z)}{\prod_{k=1}^N (1 - p_k z^{-1})} \rightarrow \text{partial fractions}$$

$$= \sum_{k=1}^N \frac{A_k \rightarrow \text{residues}}{1 - p_k \bar{z}^{-1}}$$

$$A_k = \frac{B(z)}{\prod_{\substack{l=1 \\ l \neq k}}^N (1 - p_l \bar{z}^{-1})} \Bigg|_{z = z_k}$$

Matlab:

residue(b,a)

$$\frac{A_k}{1 - p_k \bar{z}^{-1}} \rightarrow \begin{matrix} A_k (p_k)^n u[n] \\ \text{or} \\ -A_k (p_k)^n u[-n-1] \end{matrix}$$

dependency on ROC

$$X(z) = \frac{1}{1 - \frac{3}{2}z^{-1} + \frac{1}{2}z^{-2}} = \frac{1}{(1 - \frac{1}{2}z^{-1})(1 - z^{-1})}$$

$$= \frac{2}{1 - z^{-1}} + \frac{-1}{1 - \frac{1}{2}z^{-1}}$$

$$(a) |z| < \frac{1}{2} \quad (b) \frac{1}{2} < |z| < 1 \quad (c) |z| > 1$$

$$\underline{M \geq N}$$

$$X(z) = \frac{B(z)}{A(z)} = \sum_{r=1}^{M-N} C_r z^{-r} + \left. \frac{B_1(z)}{A(z)} \right\} \begin{array}{l} \text{proper form} \\ \text{rational} \end{array}$$

$$X(z) = \frac{1 + 2z^{-1} + z^{-2}}{1 - \frac{3}{2}z^{-1} + \frac{1}{2}z^{-2}} = 2 + \frac{B_1(z)}{A(z)}$$

proceed as before

Repeated Roots:

$$X(z) = \frac{G \prod_{i=1}^M (1 - a_i z^{-1})}{\prod_{q=1}^Q (1 - b_q z^{-1}) \prod_{l=1}^R (1 - \gamma_l z^{-1})^{\sigma_l}} \quad M < N$$

$$N = Q + \sum_{l=1}^R \sigma_l$$

$$X(z) = \sum_{q=1}^Q \frac{A_q}{1 - b_q \bar{z}^{-1}} + \sum_{l=1}^R \sum_{k=1}^{\sigma_l} \frac{c_{lk}}{(1 - \gamma_l \bar{z}^{-1})^k}$$

γ_l : root, σ_l = multiplicity

$$A_q = \left. X(z) (1 - b_q \bar{z}^{-1}) \right|_{z = b_q}$$

fixed $\searrow$

$$c_{lk} = \frac{1}{(-\gamma_l)^{\sigma_l - k} (\sigma_l - k)!} \frac{d^{\sigma_l - k}}{d\bar{z}^{\sigma_l - k}} \left[X(\bar{z}^{-1}) (1 - \gamma_l \bar{z})^{\sigma_l} \right] \bigg|_{\bar{z} = \frac{1}{\gamma_l}}$$

Σg

$$X(z) = \frac{12 - 22z^{-1} + 16z^{-2}}{(1 - 2z^{-1})^3}$$

$$R = 1$$

$$l = 1$$

$$\sigma_l = \sigma_1 = 3$$

$$c_{1,3} = \frac{1}{(-2)^0 0!} \frac{d^0}{dz^0} \left[\frac{12 - 22z + 16z^2}{(1 - 2z)^3} \right] \bigg|_{z=1/2} = 5$$

$$c_{1,2} = \frac{1}{(-2)^1 1!} \frac{d^1}{dz^1} \left[\frac{12 - 22z + 16z^2}{(1 - 2z)^3} \right] \bigg|_{z=1/2} = 3$$

$$C_{11} = \frac{1}{(-2)^2 2!} \frac{d^2}{d\zeta^2} \left[\frac{12 - 22\zeta + 16\zeta^2}{(1-2\zeta)^3} \right] \bigg|_{\zeta=1/2} = 4$$

$$X(z) = \frac{4}{1-2z^{-1}} + \frac{3}{(1-2z^{-1})^2} + \frac{5}{(1-2z^{-1})^3}$$

$$a^n u[n] \longleftrightarrow \frac{1}{1-az^{-1}} \quad |z| > |a|$$

$$(n+1)a^n u[n] \longleftrightarrow \frac{1}{(1-az^{-1})^2} \quad |z| > |a|$$

$$? \longleftrightarrow \frac{1}{(1 - a\bar{z}^{-1})^3} \quad |z| > |a|$$

Power Series Expansion

$$X(z) = \frac{1}{1 - a\bar{z}^{-1}} \quad |z| > |a|$$

$$= 1 + a\bar{z}^{-1} + a^2\bar{z}^{-2} + a^3\bar{z}^{-3} + \dots$$

$$\longleftrightarrow \left\{ \dots, 0, 0, \underset{\substack{\downarrow n=0}}{1}, a, a^2, a^3, \dots \right\} = a^n u[n]$$

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$$X(z) = \frac{1}{1 - a\bar{z}^{-1}}$$

$$= 1 + a\bar{z}^{-1} + a^2\bar{z}^{-2} + \dots$$

$$\longleftrightarrow \{ 0, 0, 0, \underset{\substack{\uparrow \\ n=0}}{1}, a, a^2, \dots \} = a^n u[n]$$

$$|a\bar{z}^{-1}| < 1 \Rightarrow |a| < |z| \\ = |z| > |a|$$

For anti causal resp., i.e. $|z| < |a|$, we need powers of z , rather than $\bar{z}^{-1}$

$$X(z) = \frac{-\bar{a}^{-1}z}{1 - \bar{a}^{-1}z}$$

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$$= -\bar{a}^{-1}z \left[1 + \bar{a}^{-1}z + \bar{a}^{-2}z^2 + \dots \right] \quad |\bar{a}^{-1}z| < 1$$

$$= |z| < |a|$$

$$= -\bar{a}^{-1}z - \bar{a}^{-2}z^2 - \bar{a}^{-3}z^3 - \dots$$

$\uparrow$ $\uparrow$ $\uparrow$
 $n = -1$ $n = -2$ $n = 0$

$$\longleftrightarrow \{ \dots, -\bar{a}^{-3}, -\bar{a}^{-2}, -\bar{a}^{-1}, 0, 0, 0 \}$$

$$-a^n u[-n-1]$$

Long Division $1 + a\bar{z}^{-1} + \dots$

$$1 - a\bar{z}^{-1} \overline{) \begin{array}{r} 1 \\ 1 - a\bar{z}^{-1} \end{array}}$$

$$\begin{array}{r} a\bar{z}^{-1} \\ a\bar{z}^{-1} - a^2\bar{z}^{-2} \\ \hline \end{array}$$

$$a^2\bar{z}^{-2}$$

Causal response

Anticausal response: $-a^{-1}z^{-1} - a^{-2}z^{-2} -$

$$\begin{array}{r}
 -a^{-1}z^{-1} + 1 \quad \Bigg) \quad 1 \\
 \underline{1 - a^{-1}z^{-1}} \\
 a^{-1}z^{-1} \\
 \underline{a^{-1}z^{-1} - a^{-2}z^{-2}} \\
 a^{-2}z^{-2} \\
 \vdots
 \end{array}$$

$$a^{-|n|} = x[n] = \begin{array}{c} n \\ a u[n] + \\ -n \\ a u[-n-1] \end{array}$$

$$a^n u[n] \longleftrightarrow \frac{1}{1 - a\bar{z}^{-1}} \quad |z| > |a|$$

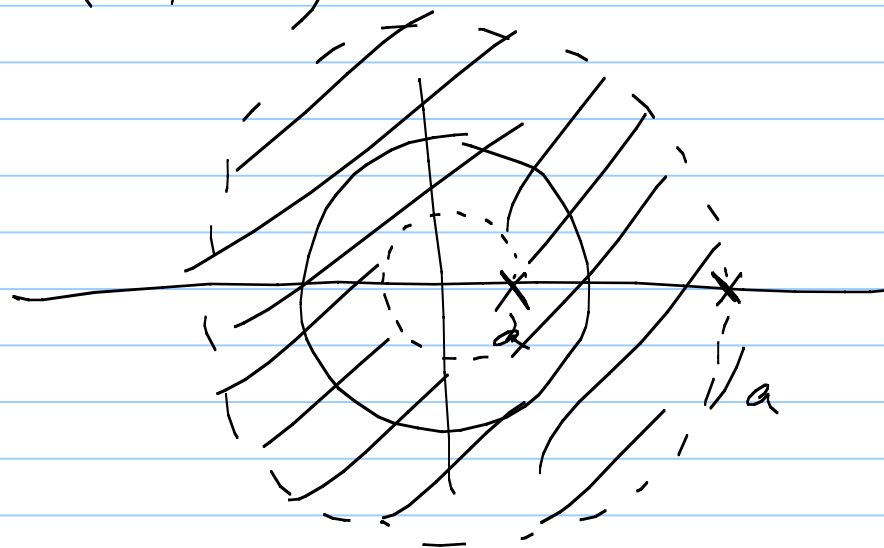
$$a^{-n} u[-n] \longleftrightarrow \frac{1}{1 - az} \quad |z| < |1/a|$$

$$a^{-n-1} u[-n-1] \longleftrightarrow \frac{z}{1 - az} \quad |z| < |1/a|$$

$$-a^{-n} u[-n-1] \longleftrightarrow \frac{az}{1 - az} \quad |z| < |1/a|$$

$$\frac{\ln |a|}{a} \longleftrightarrow \frac{1}{1 - a\bar{z}'} + \frac{az}{1 - az} \quad |a| < |z| < \frac{1}{|a|}$$

$$= \frac{1 - a^2}{1 + a^2 - a(z + \bar{z}')}$$



$$X(z) = b_{-q} z^q + b_{-(q-1)} z^{q-1} + \dots + b_{-1} z + b_0 + b_1 z^{-1} + b_2 z^{-2} + \dots + b_p z^{-p}$$

$$\longleftrightarrow \{0, 0, \underset{\substack{\uparrow \\ n=-q}}{b_{-q}}, b_{-(q-1)}, \dots, b_{-1}, \underset{\substack{\uparrow \\ n=0}}{b_0}, b_1, \dots, b_p, 0\}$$

$$X(z) = z^2 (1 - \frac{1}{2} z^{-1}) (1 + z^{-1}) (1 - z^{-1})$$

$$x[n] =$$

$$X(z) = e^z = 1 + \frac{z}{1!} + \frac{z^2}{2!} + \frac{z^3}{3!} + \dots \quad |z| < \infty$$

$$\longleftrightarrow \left\{ \dots, \frac{1}{3!}, \frac{1}{2!}, \frac{1}{1!}, \frac{1}{0!}, 0, 0, \dots \right\} = x[n]$$

$n = -3 \qquad n = -2 \qquad n = -1 \qquad n = 0$

$$X(z) = e^{-z} \longleftrightarrow x[-n]$$

$$X(z) = \ln(1 + az^{-1})$$

$$|z| > |a|$$

$$= \sum_{n=1}^{\infty} (-1)^{n+1} \frac{a^n z^{-n}}{n}$$



Can also get same answer using differentiation in the z-domain property

Contour Integral Method

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

$$\frac{1}{2\pi j} \oint X(z) z^{k-1} dz = \frac{1}{2\pi j} \oint \left[\sum_{n=-\infty}^{\infty} x[n] z^{-n} \right] z^{k-1} dz$$

$$= \sum_{n=-\infty}^{\infty} x[n] \frac{1}{2\pi j} \oint z^{k-n-1} dz$$

$$\frac{1}{2\pi j} \oint z^n dz = \begin{cases} 1 & n = -1 \\ 0 & n \neq -1 \end{cases}$$

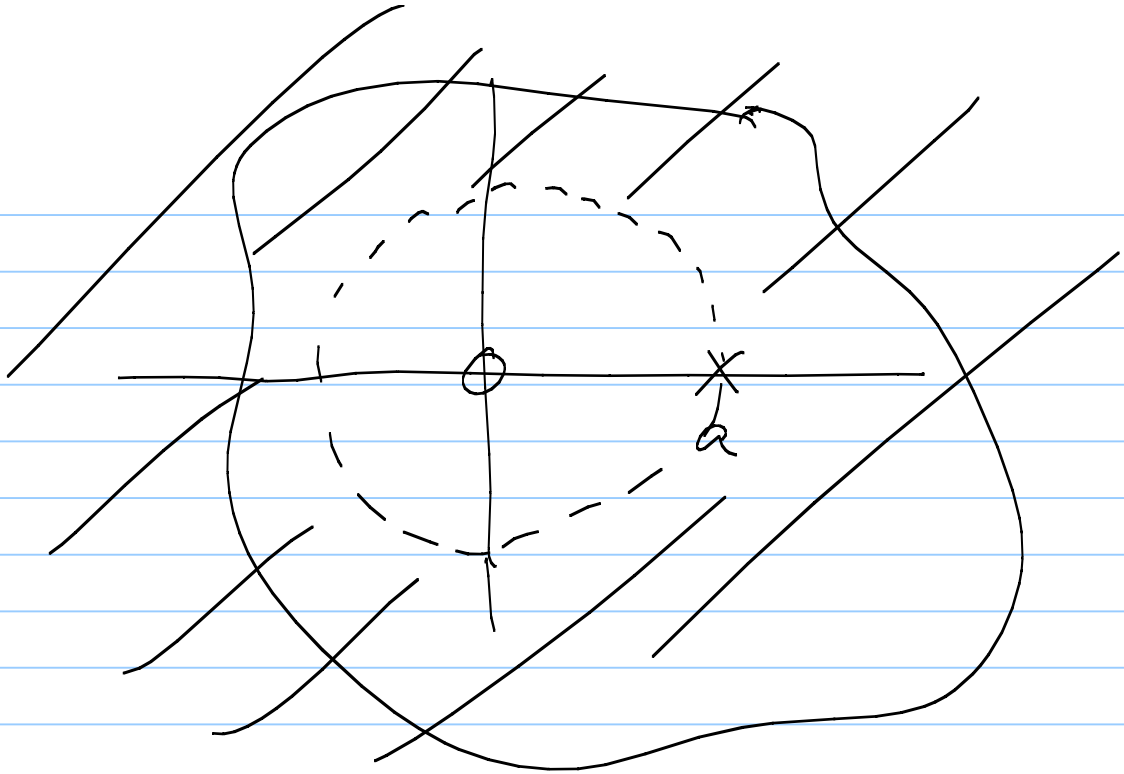
$$\frac{1}{2\pi j} \oint z^{k-n-1} dz = \begin{cases} 1 & k = n \\ 0 & k \neq n \end{cases}$$

$$\frac{1}{2\pi j} \oint X(z) z^{k-1} dz = x[k]$$

$$X(z) = \frac{1}{1 - az^{-1}}$$

$$= \frac{z}{z - a}$$

$$|z| > |a|$$



$$\frac{1}{2\pi j} \oint \frac{z^{n-1}}{z-a} dz$$

$$= \frac{1}{2\pi j} \oint \frac{z^n}{z-a} dz$$

Using Residue theorem:

$$\text{Res} \left[\frac{X(z)}{z-a} \right]_{z=a} = X(z) \Big|_{z=a} = a^n \quad n \geq 0$$

$$x[n] = a^n \quad n \geq 0$$

[Can also see Markusharich]

$$\sum_{k=0}^N a_k y[n-k] = \sum_{l=0}^M b_l x[n-l]$$

$$a_0 = 1$$

$$y[n] = - \sum_{k=1}^N a_k y[n-k] + \sum_{l=0}^M b_l x[n-l]$$

Applying z -transform,

$$Y(z) = - \sum_{k=1}^N a_k z^{-k} Y(z) + \sum_{l=0}^M b_l z^{-l} X(z)$$

$$\underbrace{Y(z)}_{A(z)} \left[1 + \sum_{k=1}^N a_k z^{-k} \right] = X(z) \underbrace{\sum_{l=0}^M b_l z^{-l}}_{B(z)}$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{l=0}^M b_l z^{-l}}{1 + \sum_{k=1}^N a_k z^{-k}} = \frac{B(z)}{A(z)}$$

$H(z)$: system transfer function

rational transfer function

$$\frac{Y(z)}{X(z)} = \frac{B(z)}{A(z)}$$

$$A(z)Y(z) = B(z)X(z)$$

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$$\sum_{k=0}^N a_k y[n-k] = \sum_{l=0}^M b_l x[n-l]$$

$$\underbrace{Y(z) \left[1 + \sum_{k=1}^N a_k z^{-k} \right]}_{A(z)} = X(z) \underbrace{\left[\sum_{l=0}^M b_l z^{-l} \right]}_{B(z)} \quad a_0 = 1$$

$$\frac{Y(z)}{X(z)} = \frac{B(z)}{A(z)} = H(z) \leftarrow \text{Transfer function}$$

$\updownarrow$

$$h[n] \leftarrow \text{impulse response}$$

$$H(e^{j\omega}) = H(z) \Big|_{z=e^{j\omega}} \leftarrow \text{Frequency response}$$

Roots of $B(z)$ are zeros of the system

" " $A(z)$ " poles "

BIBO stable: $\sum_{n=-\infty}^{\infty} |h[n]| < \infty$

Recall $|H(z_0)| < \infty \Rightarrow \sum_{n=-\infty}^{\infty} |h[n]| |z_0|^{-n} < \infty$

$$\Rightarrow z_0 \in \text{ROC}$$

Consider a BIBO stable system:

$$\sum_{n=-\infty}^{\infty} |h[n]| < \infty$$

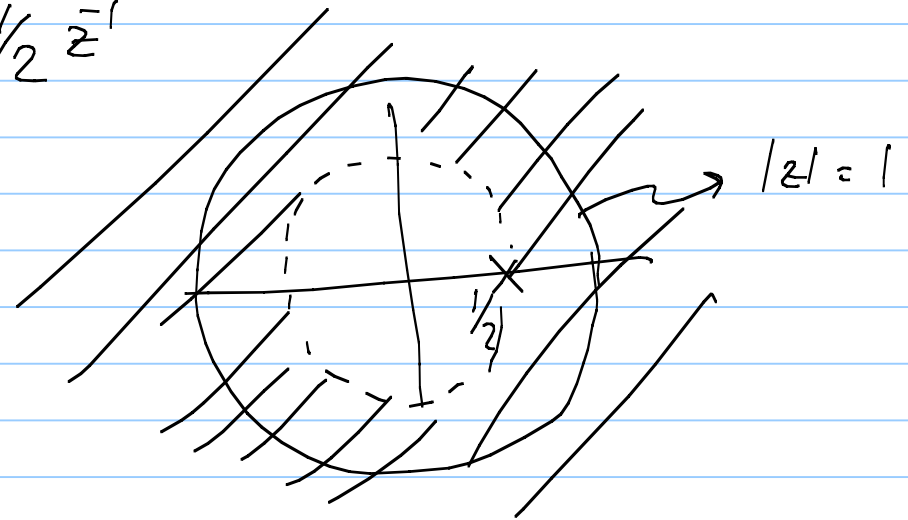
$$\sum_{n=-\infty}^{\infty} |h[n]| |1|^{-n} < \infty$$

$$\sum_{n=-\infty}^{\infty} |h[n]| |e^{j\omega}|^{-n} < \infty$$

$$\Rightarrow e^{j\omega} \in \text{ROC}$$

$$\text{Eg } h(n) = \left(\frac{1}{2}\right)^n u(n) \leftrightarrow \frac{1}{1 - \frac{1}{2}z^{-1}} \quad |z| > \frac{1}{2}$$

$$\Rightarrow \sum_{n=-\infty}^{\infty} |h(n)| < \infty$$



$$2^n u(n) \leftrightarrow \frac{1}{1 - 2z^{-1}} \quad |z| > 2$$

not stable

$$-2^n u[-n-1] \longleftrightarrow \frac{1}{1-2\bar{z}^{-1}} \quad |z| < 2$$

$e^{j\omega} \in \text{ROC} \Rightarrow \text{stable}$

$$-(1/2)^n u[-n-1] \longleftrightarrow \frac{1}{1-1/2 \bar{z}^{-1}} \quad |z| < 1/2$$

not stable

$$\frac{a^{|n|}}{a} \longleftrightarrow \frac{1-a^2}{1+a^2-a(z+\bar{z}^{-1})} \quad |a| < |z| < 1/|a|$$

Causality implies that ROC is a region outside a certain circle

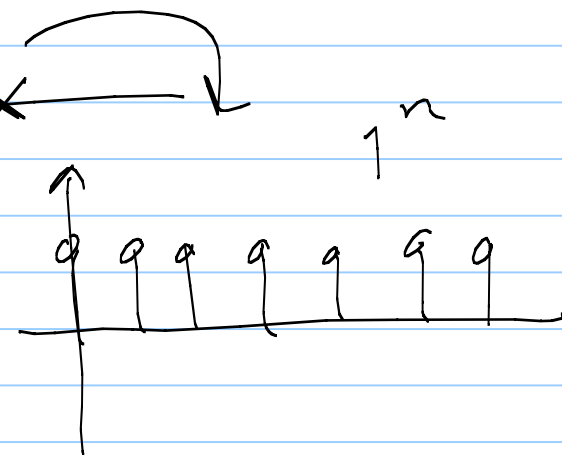
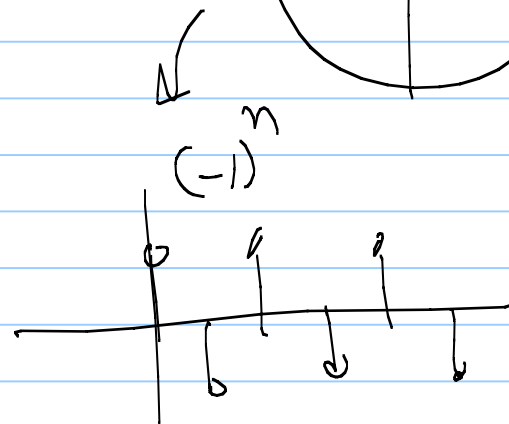
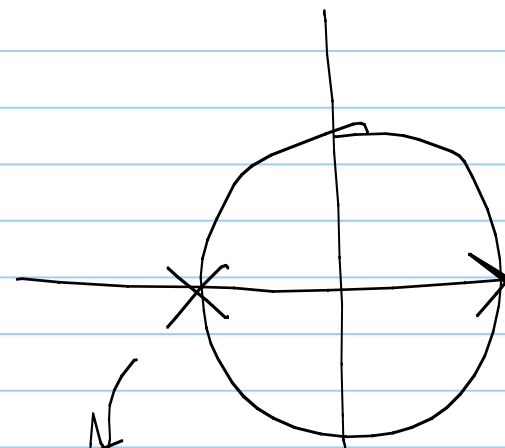
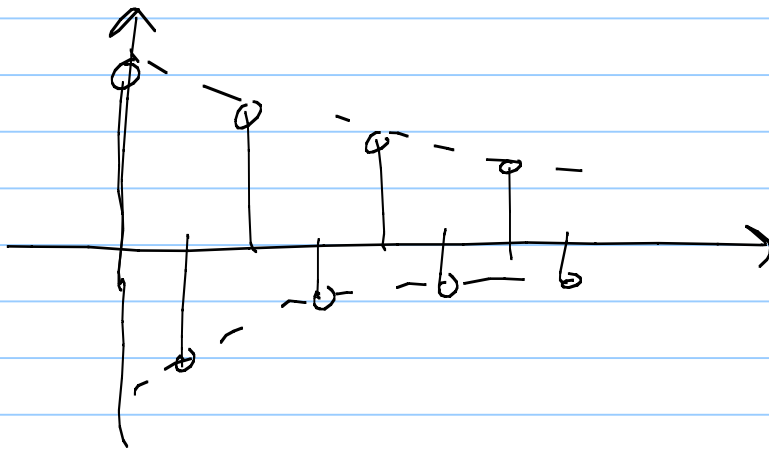
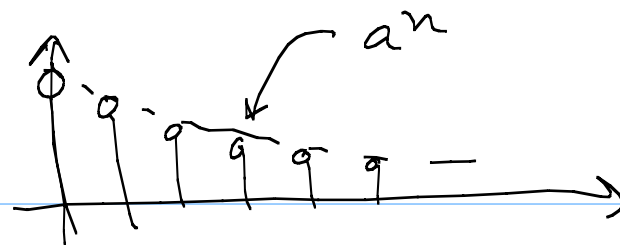
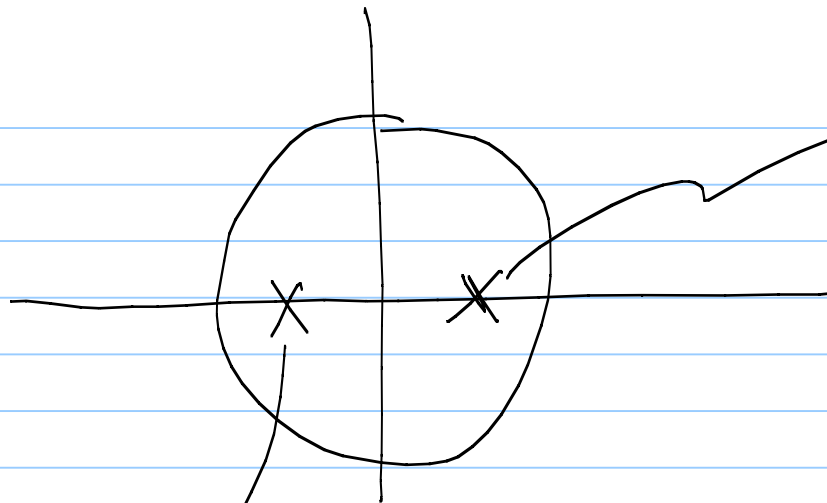
For rational TF, ROC is outside the circle corresponding to largest radius pole

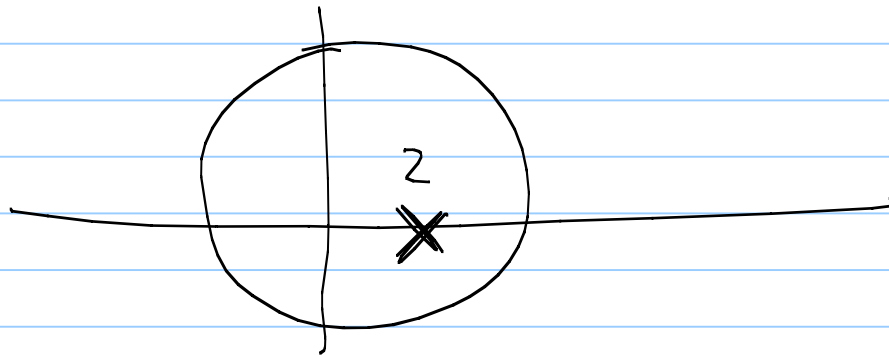
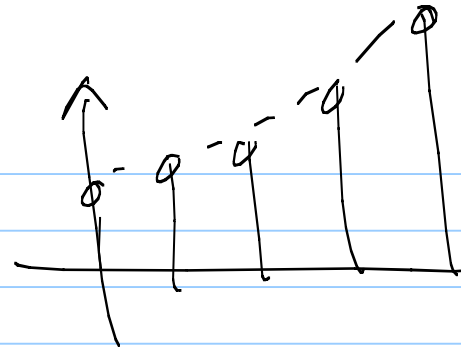
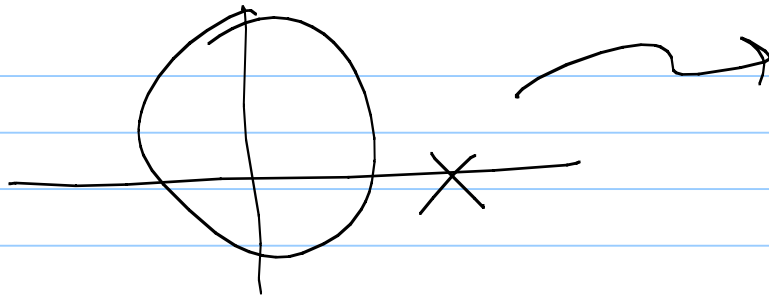
For stability, $e^{j\omega} \in \text{ROC}$.

$\Rightarrow$ all poles must be strictly

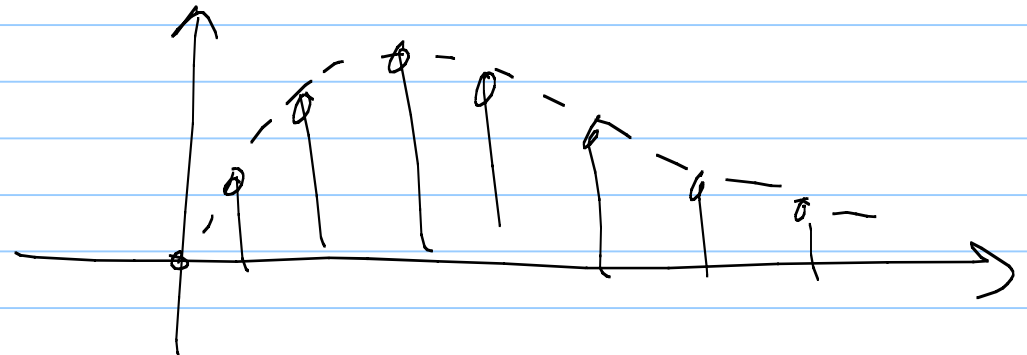
inside the unit circle

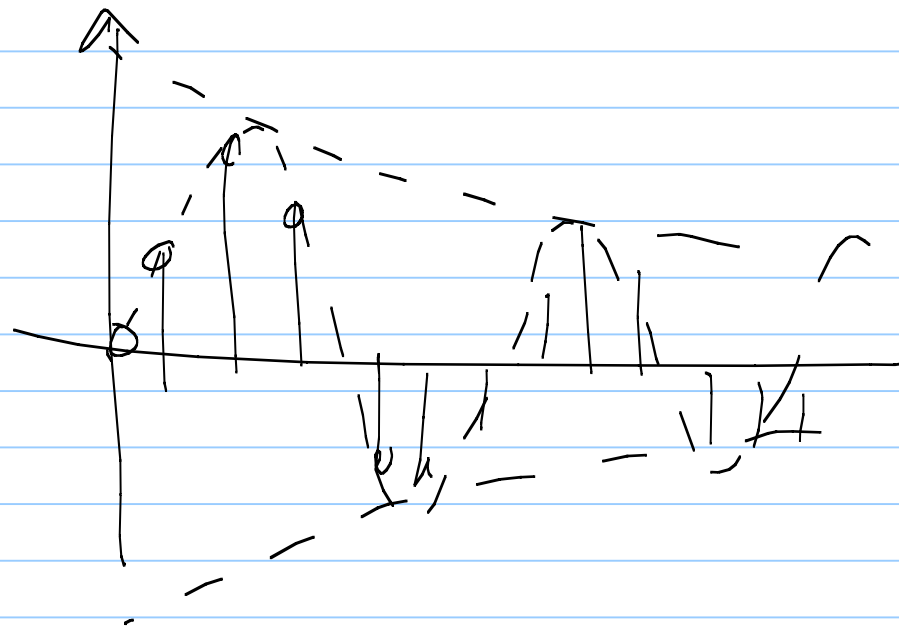
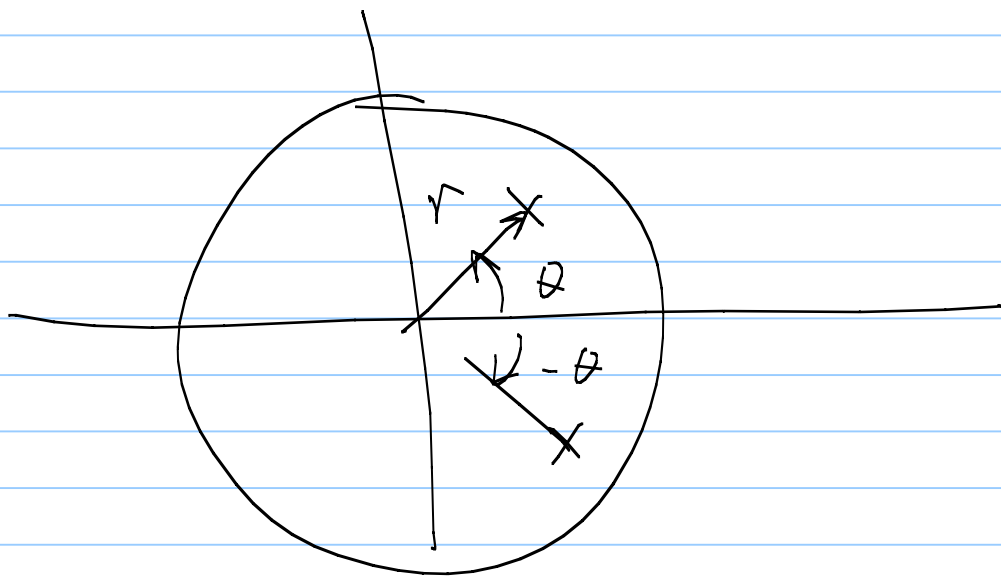
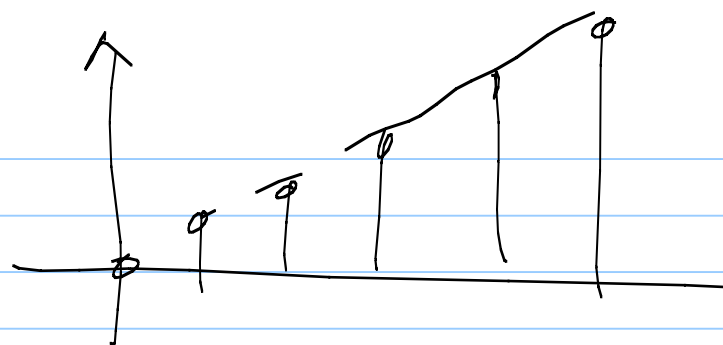
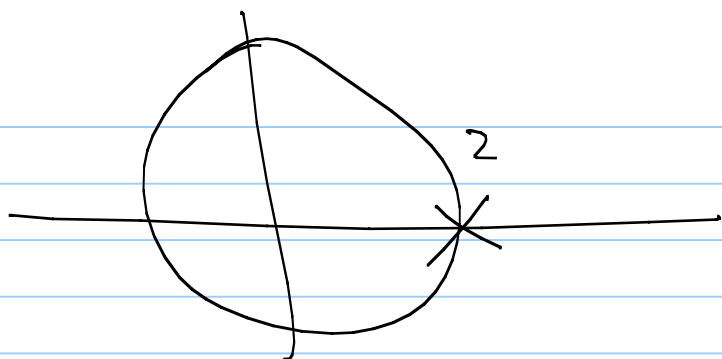
$h[n]$ is finite $\leftrightarrow H(z)$ except for 0 and/or ∞





n
 $n a_n(n)$





If uncancelled nontrivial poles exist,

then $h(n)$ will contain terms like $a^n u(n)$
or $n a^n u(n)$, etc., which last (theoretically)
for ∞ duration $\Rightarrow$ IIR systems
(infinite impulse response)

Otherwise, $h(n)$ is finite: FIR

finite impulse response

$$H(z) \Big|_{z=e^{j\omega}} = H(e^{j\omega})$$

$$H(z) = \frac{B(z)}{A(z)} = K \frac{\prod_{l=1}^M (1 - z_l \bar{z}')}{\prod_{k=1}^N (1 - p_k \bar{z}')}$$

$$= K \frac{z^{N-M} \prod_{l=1}^M (z - z_l)}{\prod_{k=1}^N (z - p_k)}$$

trivial
poles/zeros

$$H(e^{j\omega}) = K e^{j\omega(N-M)} \frac{\prod_{l=1}^M (e^{j\omega} - z_l)}{\prod_{k=1}^N (e^{j\omega} - p_k)}$$

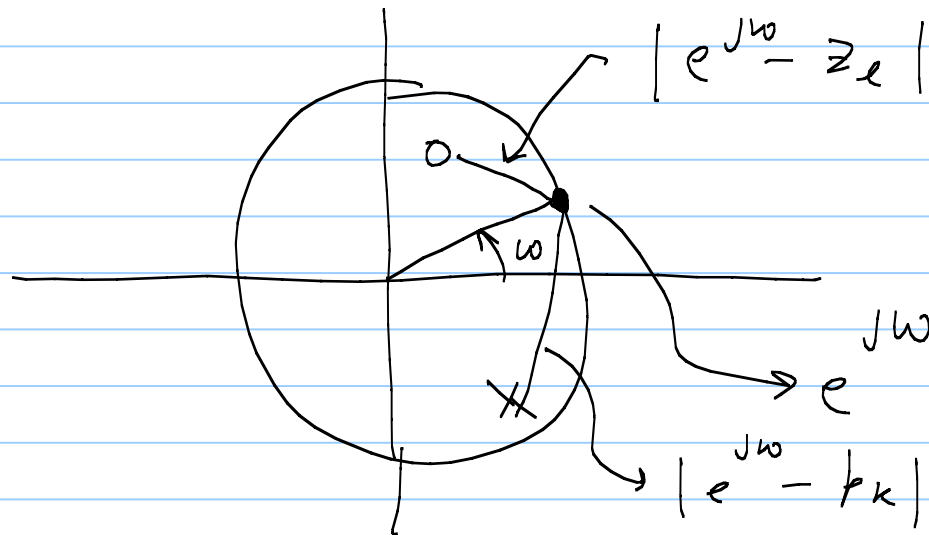
$$|H(e^{j\omega})| = |K| \frac{\prod_{l=1}^M |e^{j\omega} - z_l|}{\prod_{k=1}^N |e^{j\omega} - p_k|}$$

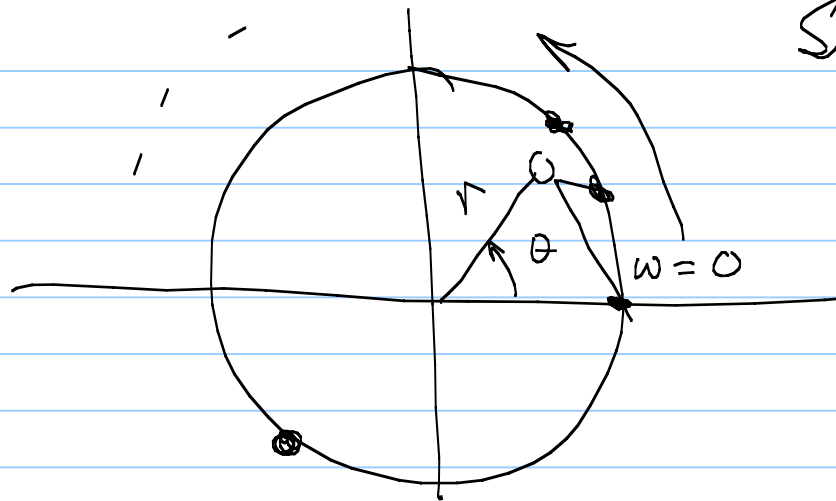
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$$|H(e^{j\omega})| = |k| \underbrace{|e^{j\omega(N-m)}|}_{1} \frac{\prod_{l=1}^M |e^{j\omega} - z_l|}{\prod_{k=1}^N |e^{j\omega} - p_k|}$$





Single complex zero

$$re^{j\theta}$$

$$H(z) = 1 - re^{j\theta} z^{-1}$$

$$|H(e^{j\omega})|^2 = |1 - re^{j\theta} e^{-j\omega}|^2$$

$$= 1 + r^2 - 2r \cos(\omega - \theta)$$

$$10 \log_{10} (1+r)^2$$

$$10 \log_{10} (1-r)^2$$

$$|H(e^{j\omega})|^2$$

min

$$= (1-r)^2$$

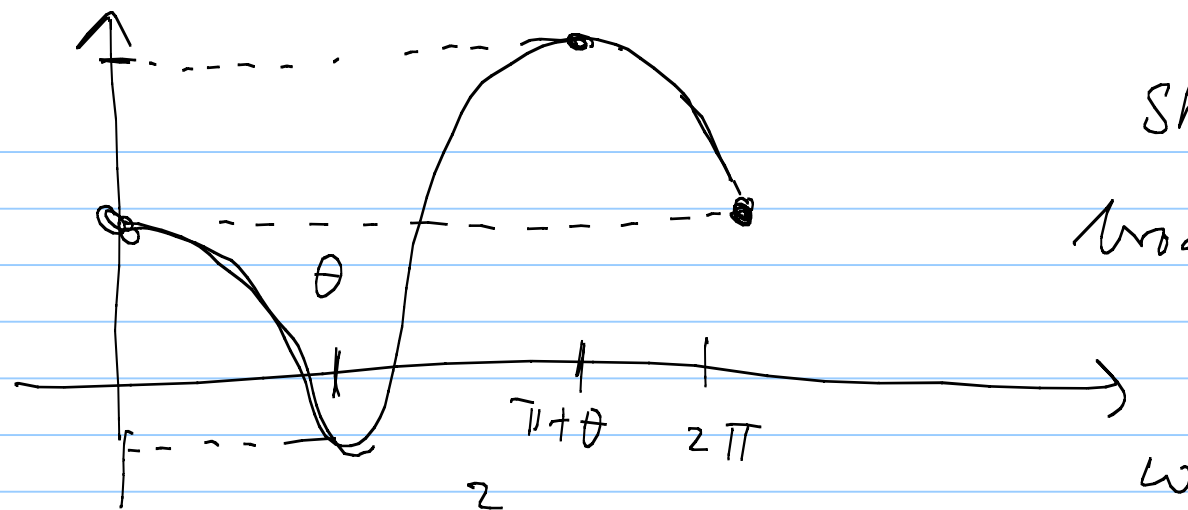
$$\text{for } \omega = \theta$$

$$|H(e^{j\omega})|^2$$

max

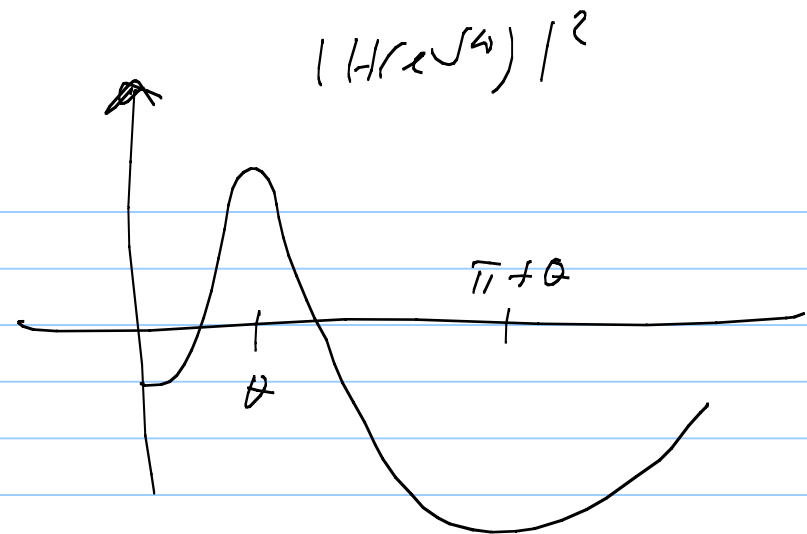
$$= (1+r)^2$$

$$\text{for } \omega = \pi + \theta$$



Sharper valley
broader peak

$$H(z) = \frac{1}{1 - re^{j\theta} z^{-1}}$$



sharper
peak

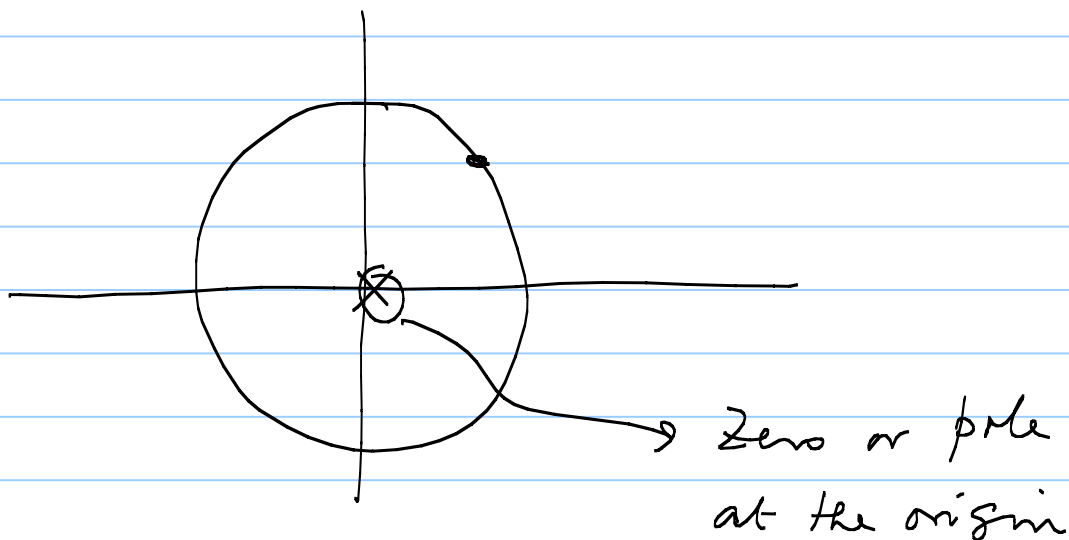
broader
valley

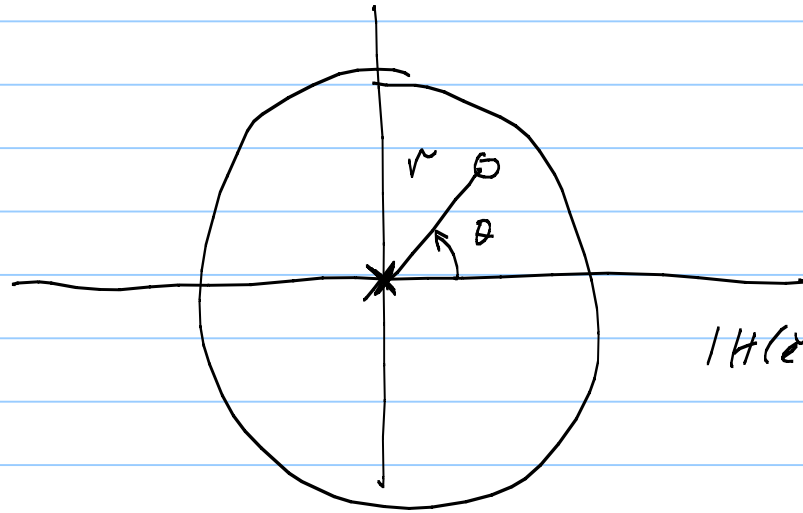
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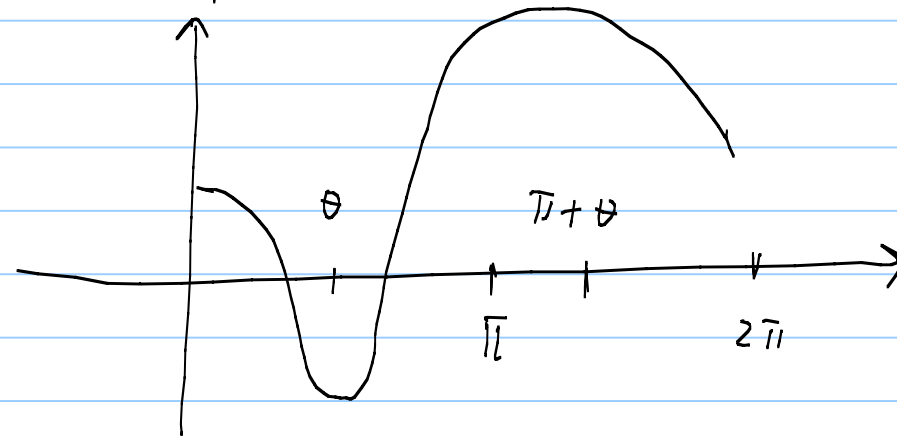
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$$|H(e^{j\omega})| = |K| \underbrace{|e^{j\omega(N-M)}|}_{\substack{\text{trivial poles} \\ \& \text{zeros}}} \frac{\prod_{l=1}^M |e^{j\omega} - z_l|}{\prod_{k=1}^N |e^{j\omega} - p_k|}$$





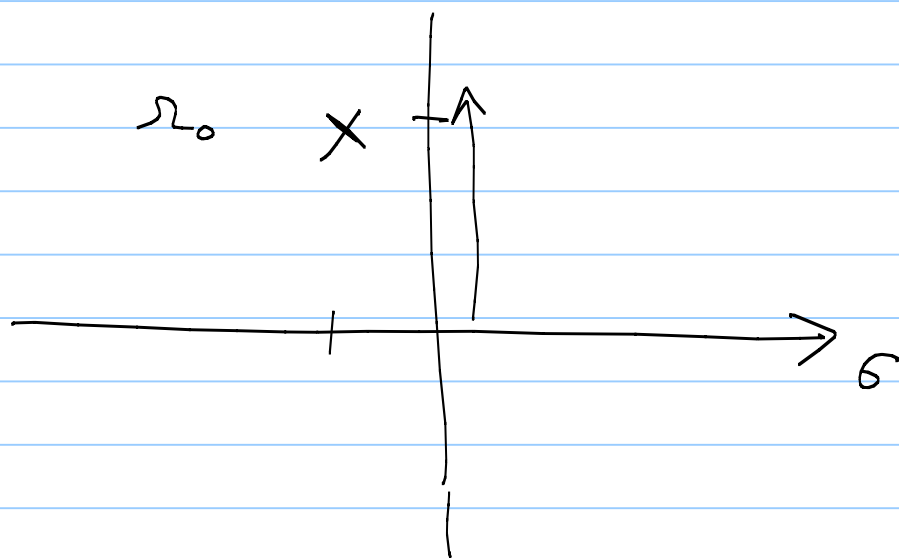
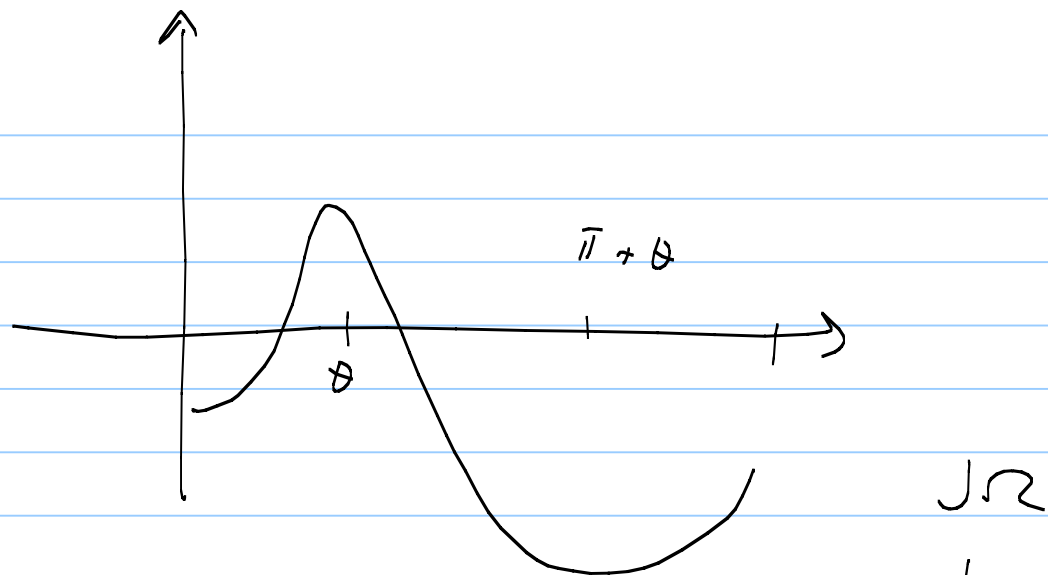
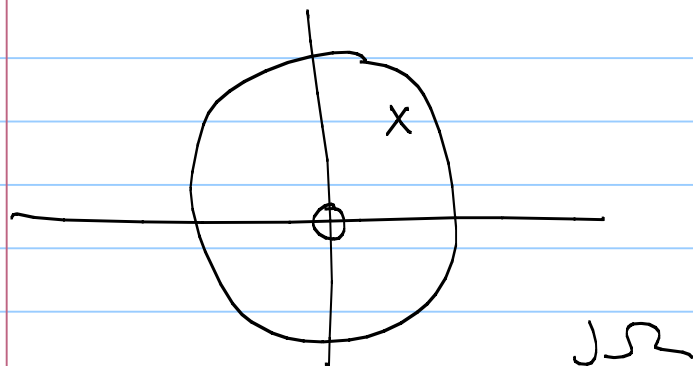
$$1 + r^2 - 2r \cos(\omega - \theta)$$



$$H(z) = \frac{1 - r e^{j\theta} z^{-1}}{z - r e^{j\theta}}$$

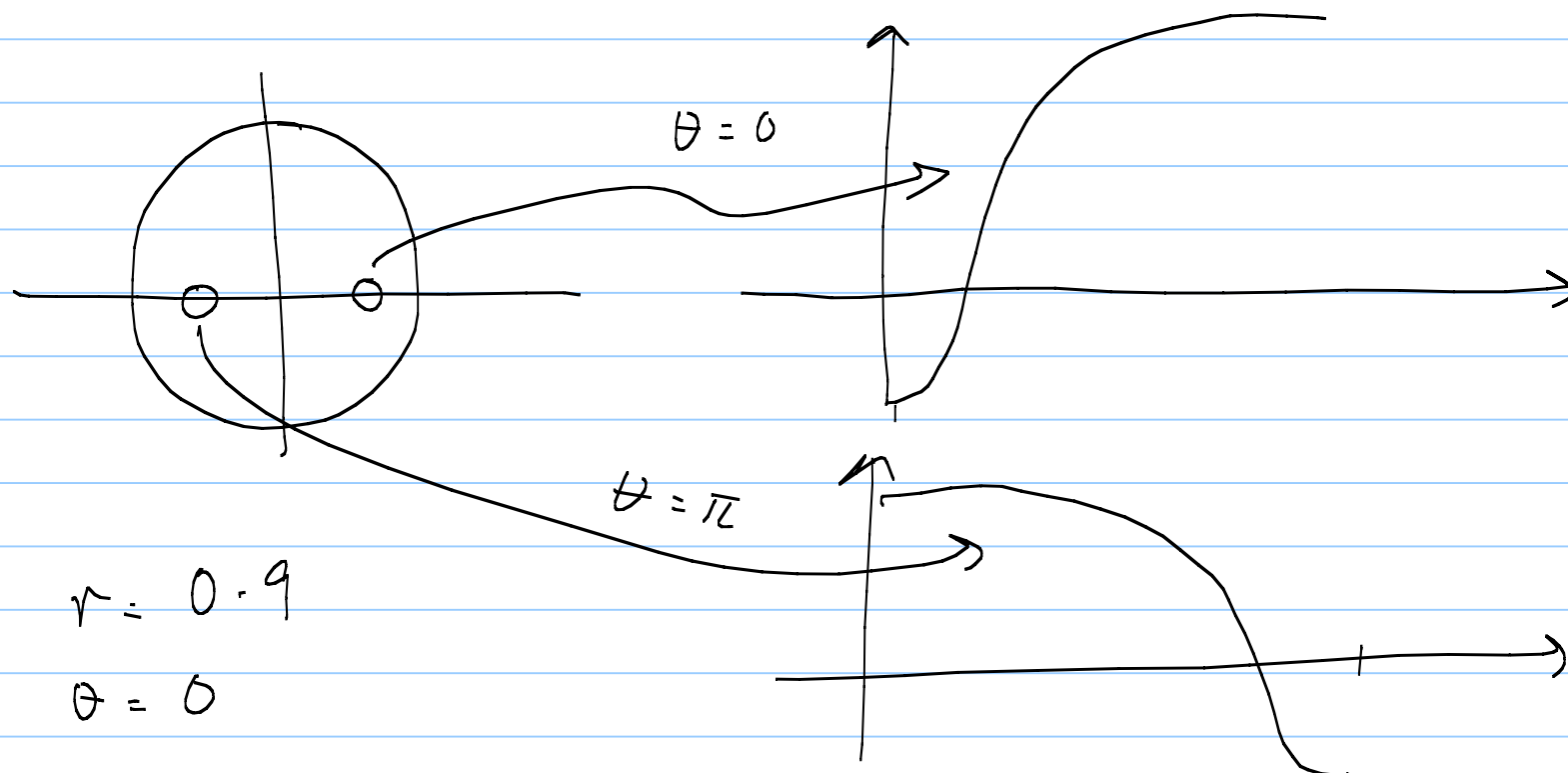
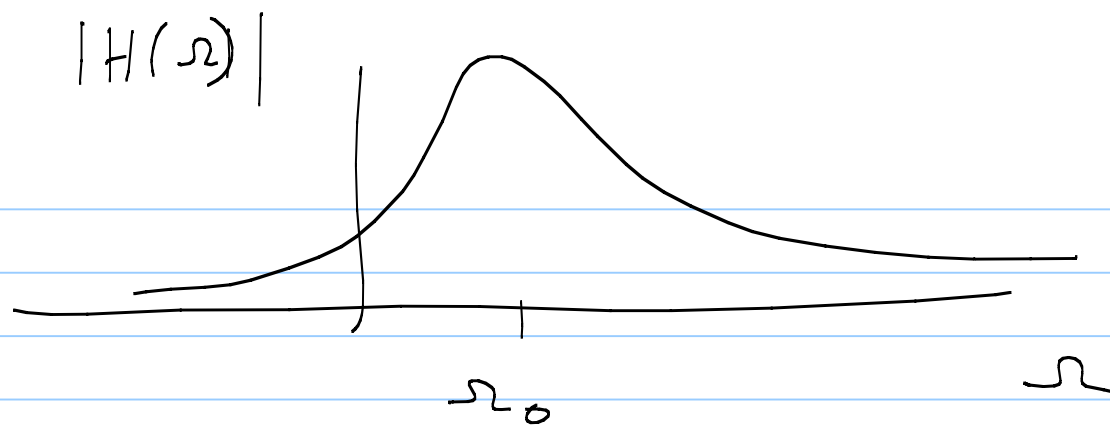
Plot $20 \log_{10} |H(e^{j\omega})|$ or $10 \log_{10} |H(e^{j\omega})|^2$

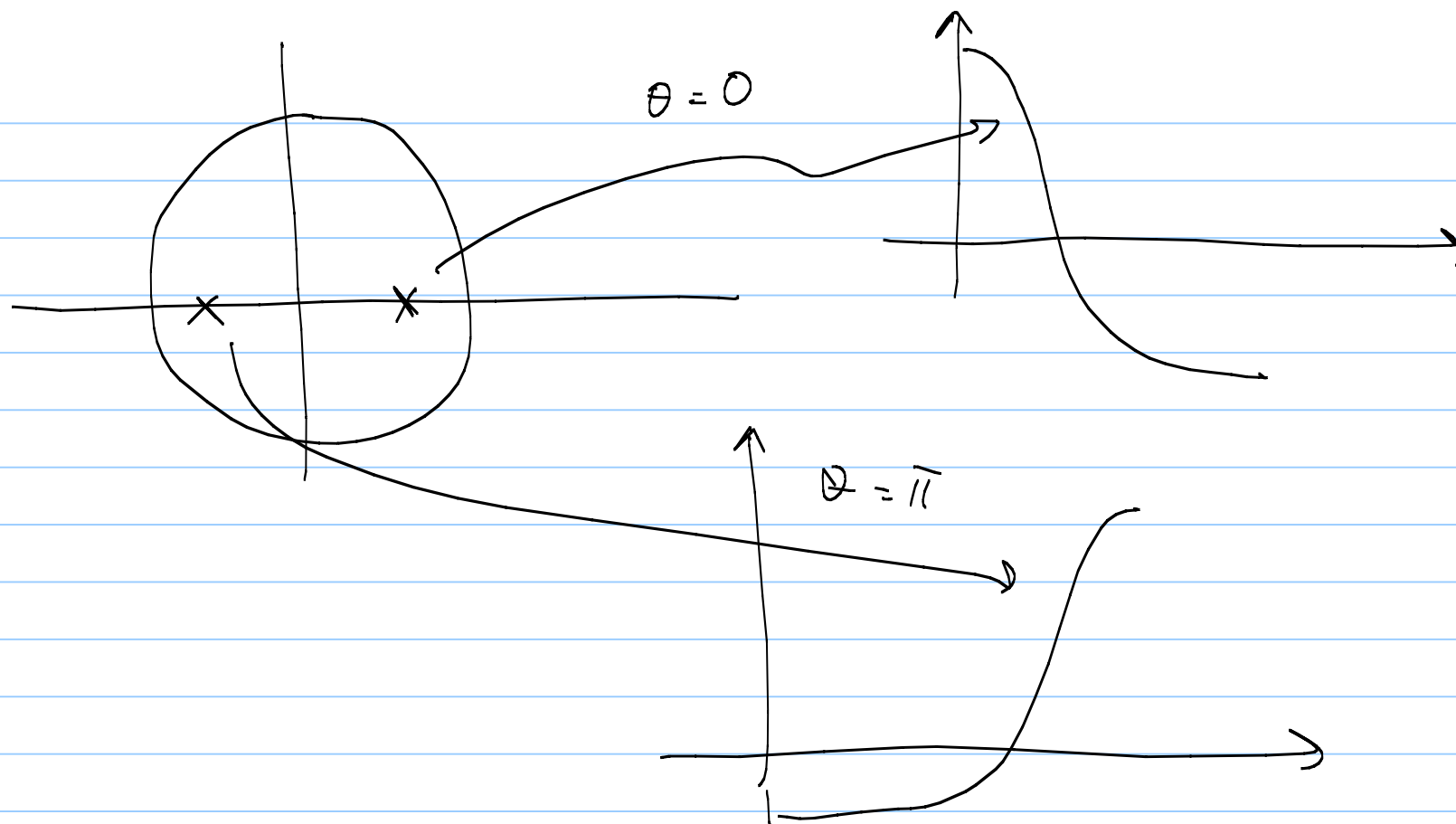
$$H(z) = \frac{1}{1 - r e^{j\theta} z^{-1}}$$



$$H(s) \Big|_{s=j\Omega} = \frac{|k| \prod_{l=1}^M |s - p_l|}{\prod_{k=1}^N |s - p_k|}$$

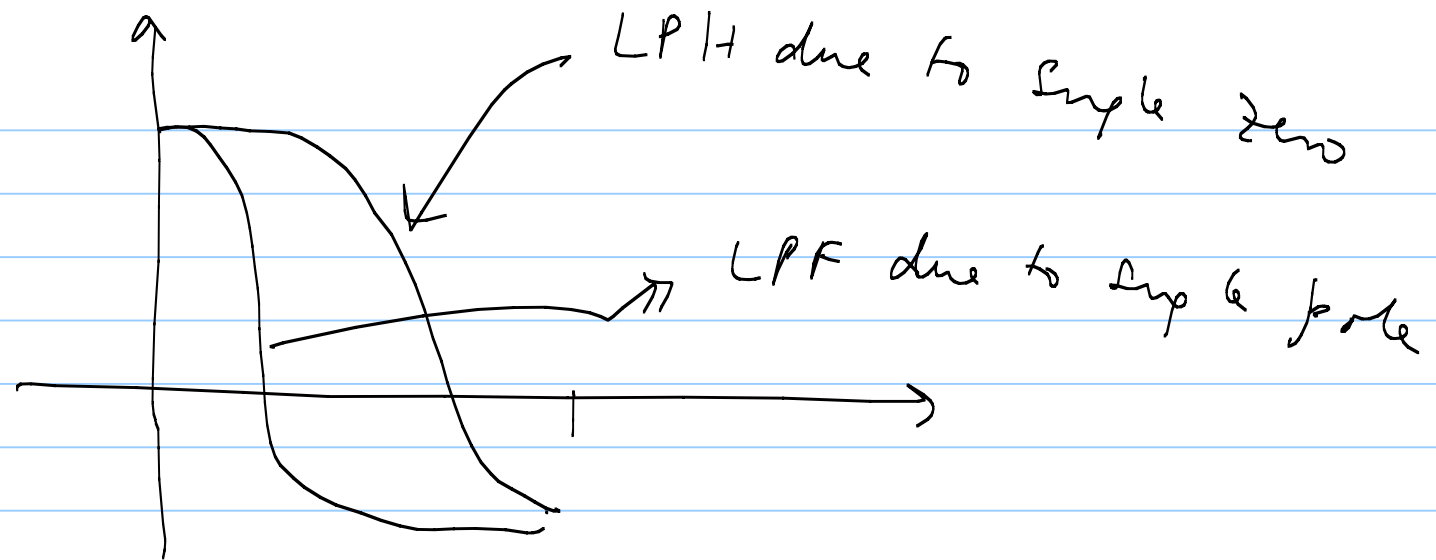
$\downarrow$ $\uparrow$
 M $j\Omega$





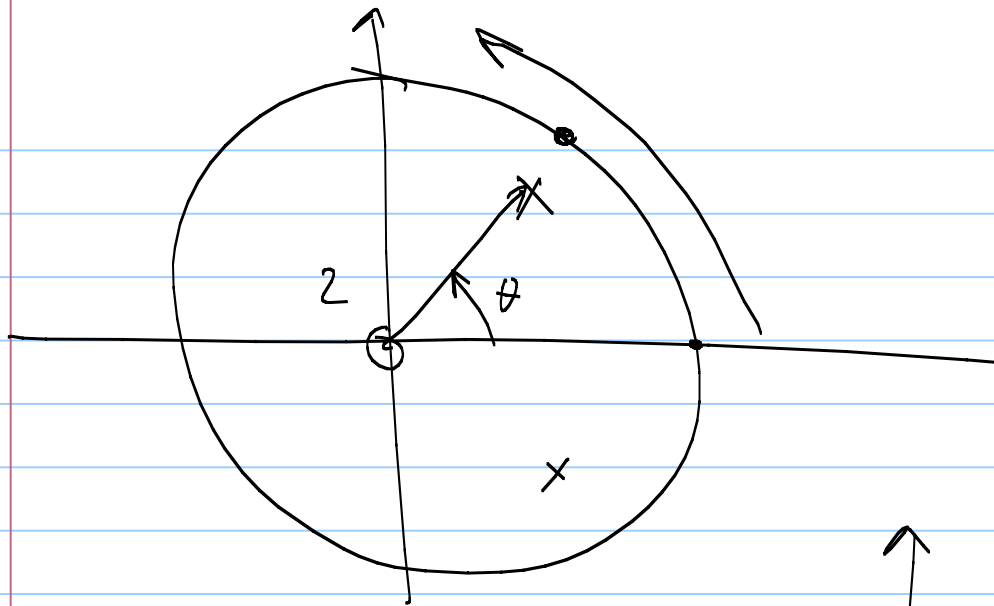
$$\gamma = 0.9$$

Find the
3dB BW



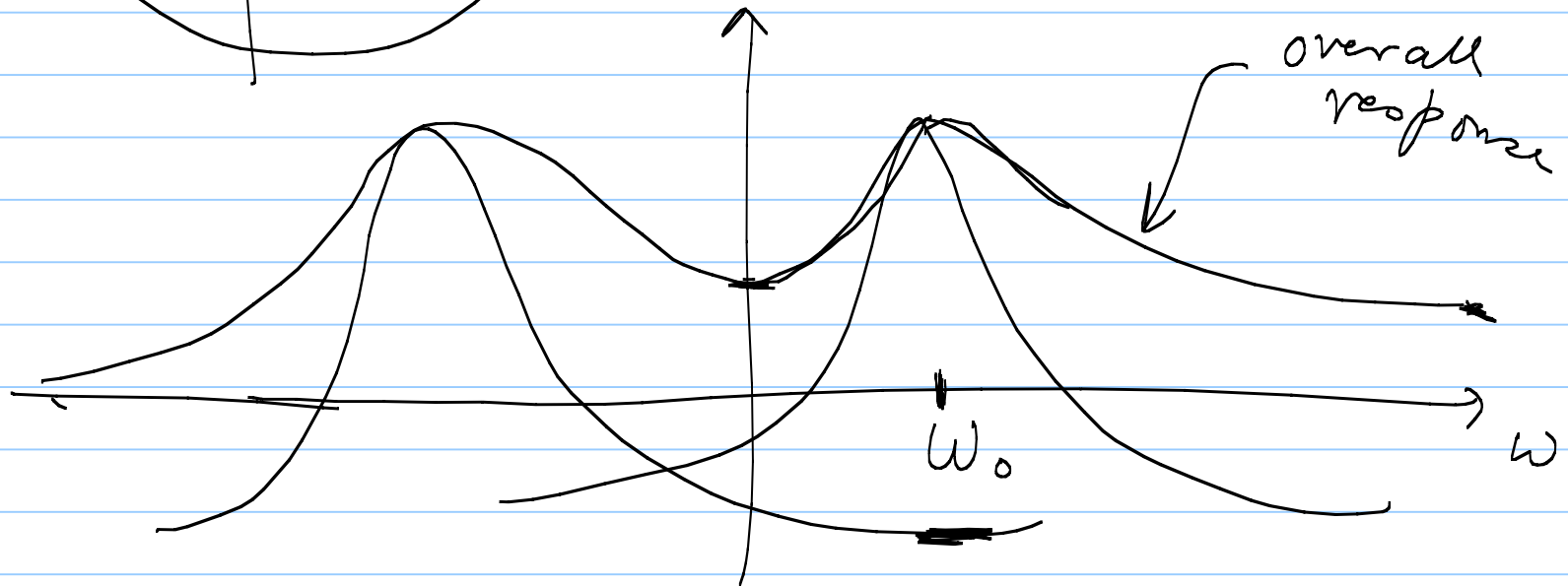
zero: $\pi/2$

pole: $\pi/30$



$$H(z) = \frac{1}{1 - 2r \cos \theta z^{-1} + r^2 z^{-2}}$$

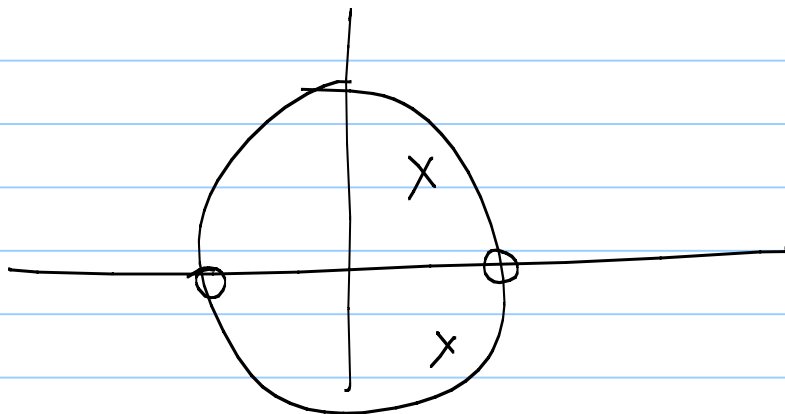
2nd order resonator



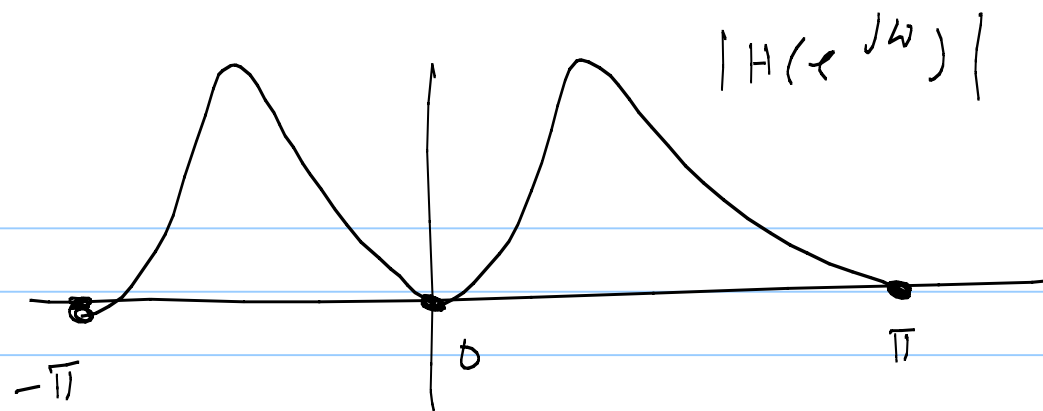
$$w_0 = \cos^{-1} \left[\frac{1+r^2}{2r} \cos \theta \right]$$

$$\text{If } \theta = \pi/2, \quad w_0 = \pi/2$$

$$-1 \leq \frac{1+r^2}{2r} \cos \theta \leq 1$$



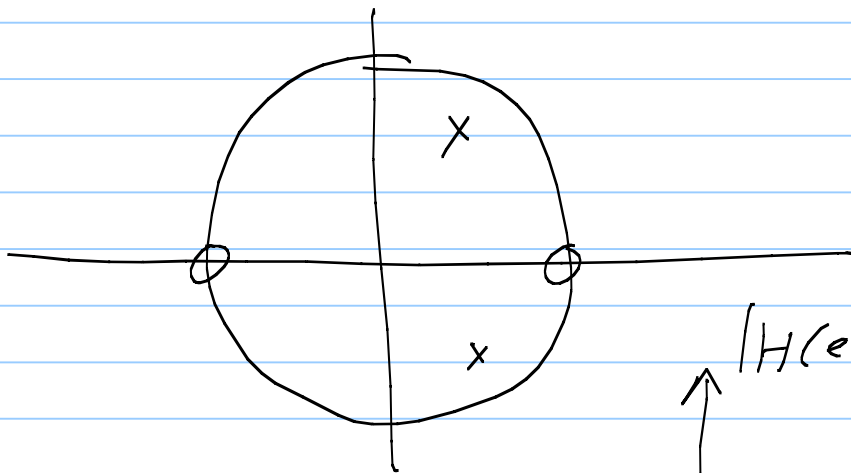
$$\frac{1 - z^{-2}}{1 - 2r \cos \theta \bar{z}^{-1} + r^2 z^{-2}}$$



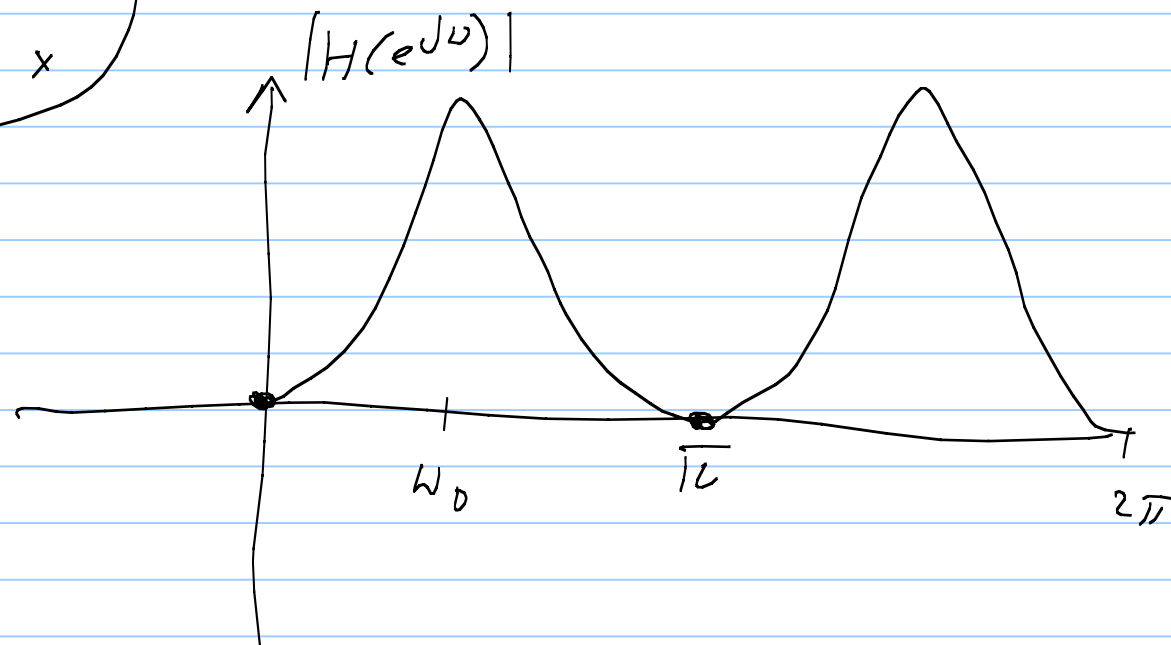
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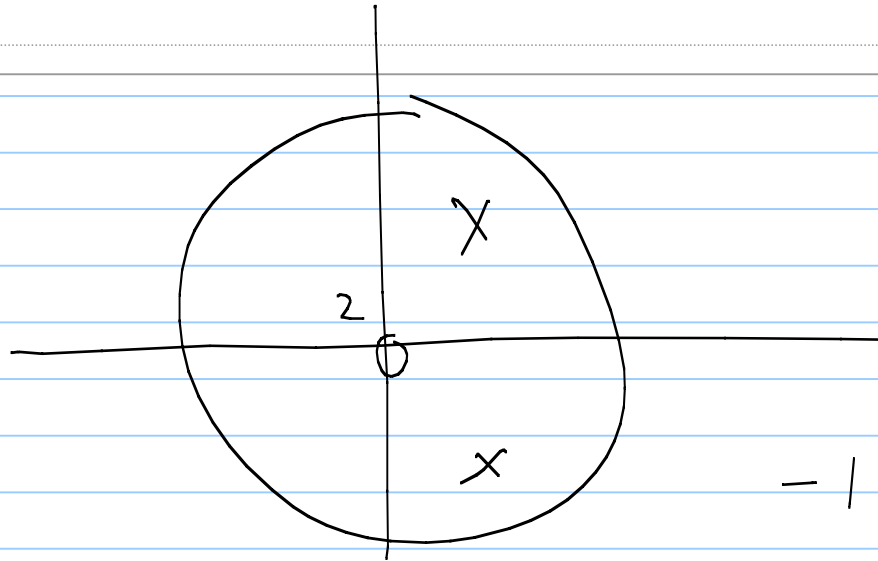
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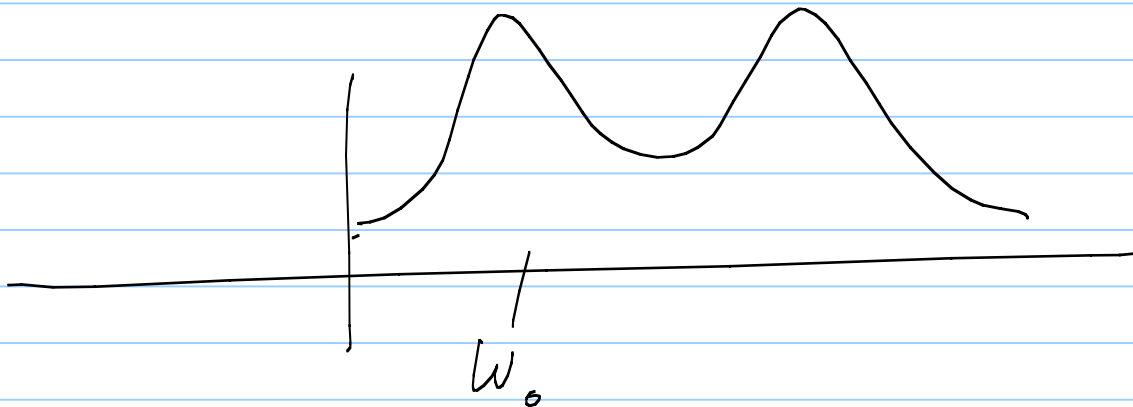
$$\frac{1 - z^{-2}}{1 - 2r \cos \theta \bar{z}' + r^2 z'^2}$$





$$W_0 = \cos^{-1} \left[\frac{1+r^2}{2r} \cos \theta \right]$$

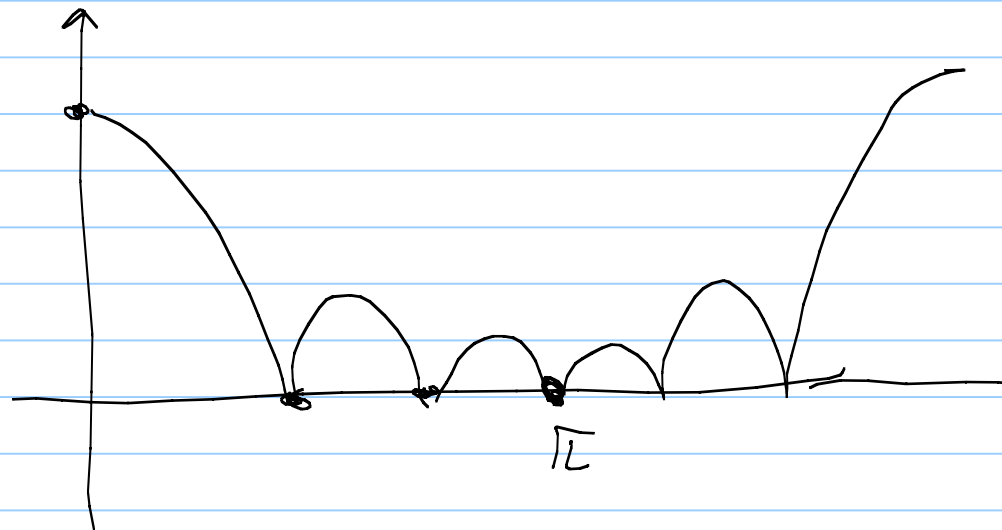
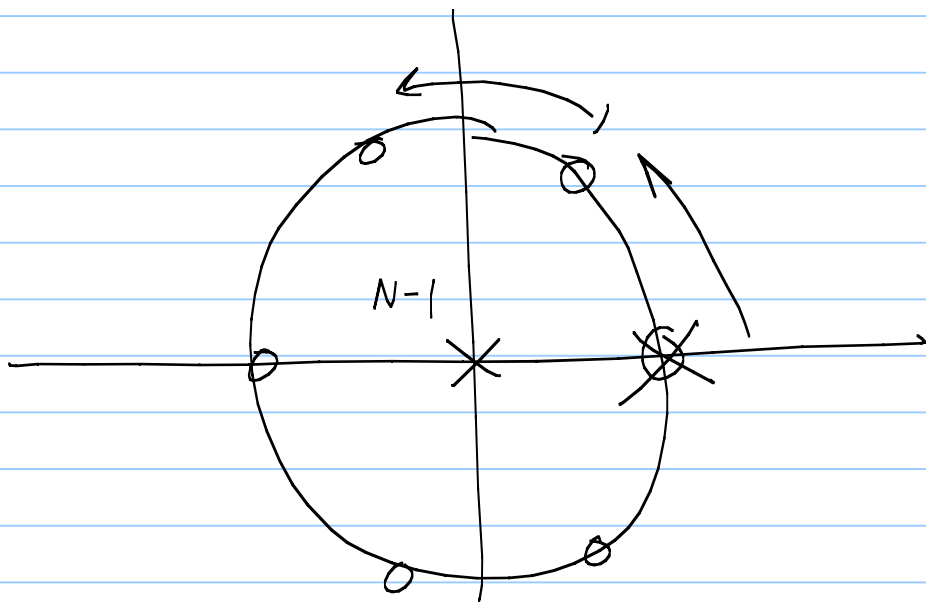
$$-1 \leq \frac{1+r^2}{2r} \cos \theta \leq 1$$



"
freq z
"

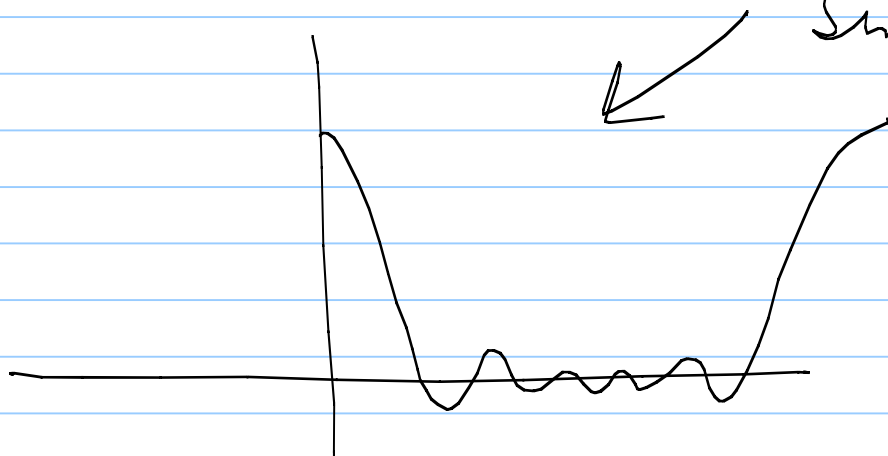
Matlab

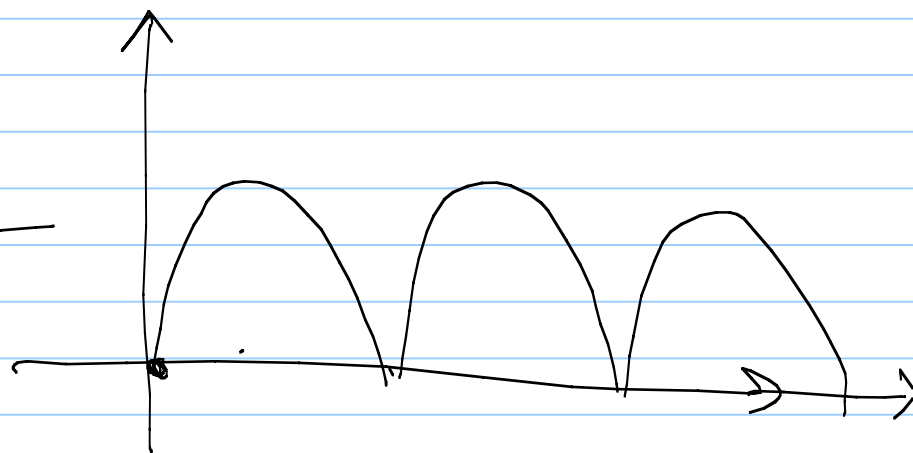
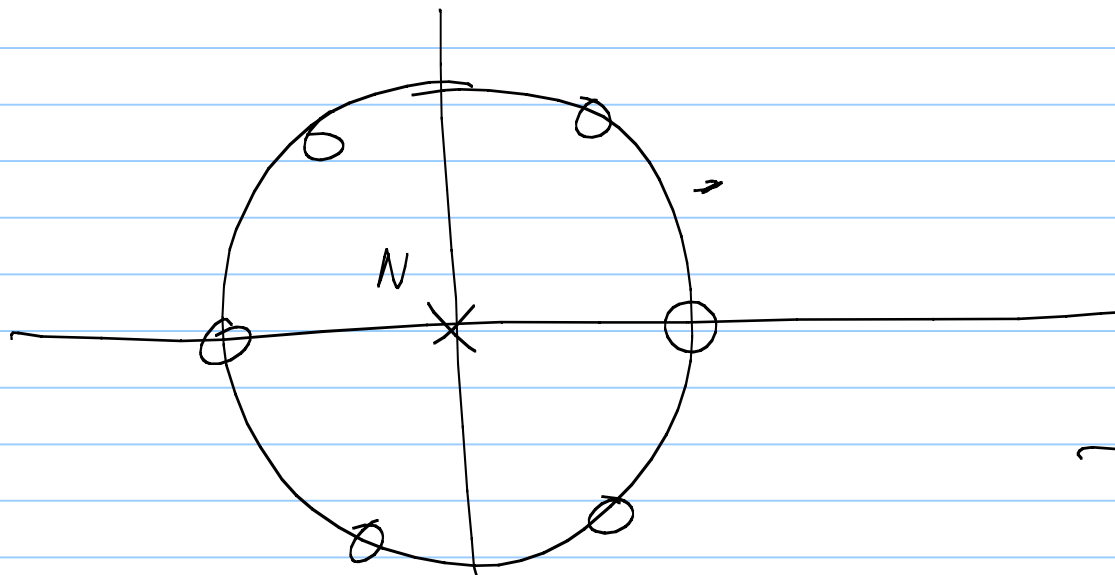
$$h[n] = 1 \quad 0 \leq n \leq N-1 \quad \longleftrightarrow \quad \frac{1 - z^{-N}}{1 - z^{-1}}$$



$$\left| \frac{1 - e^{-j\omega N}}{1 - e^{-j\omega}} \right| = \left| \frac{e^{j\omega N/2}}{e^{j\omega/2}} \frac{\sin N\omega/2}{\sin \omega/2} \right|$$

$$H(e^{j\omega}) = e^{j\omega(N-1)/2} \frac{\sin N\omega/2}{\sin \omega/2}$$

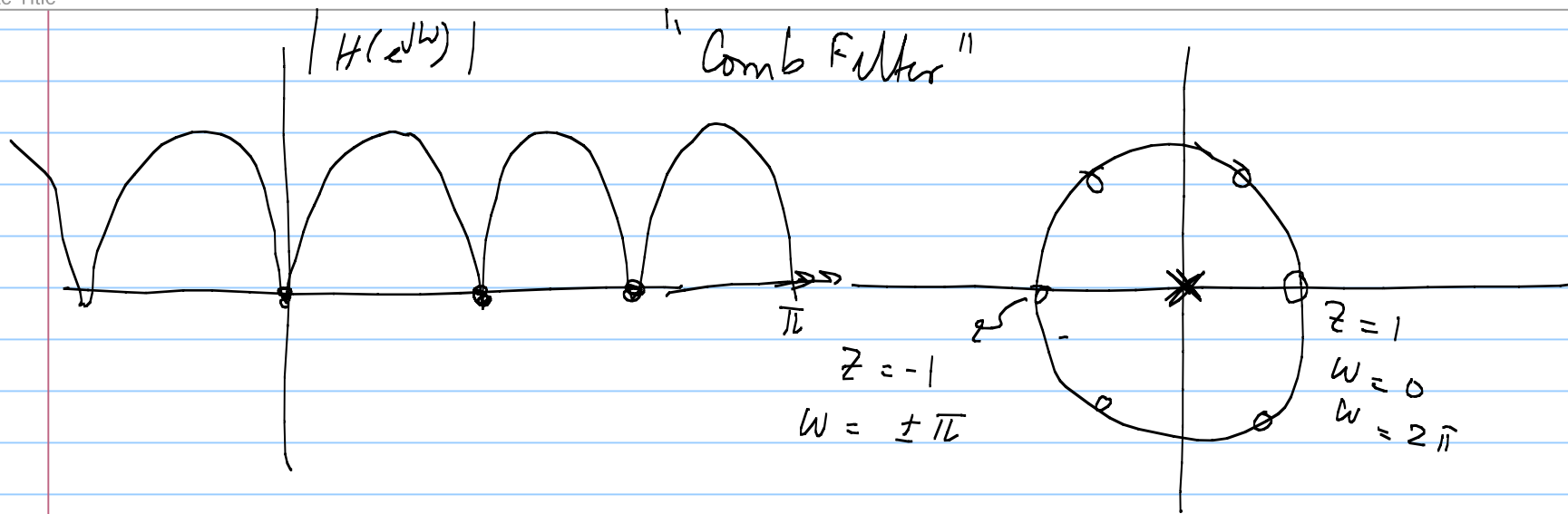




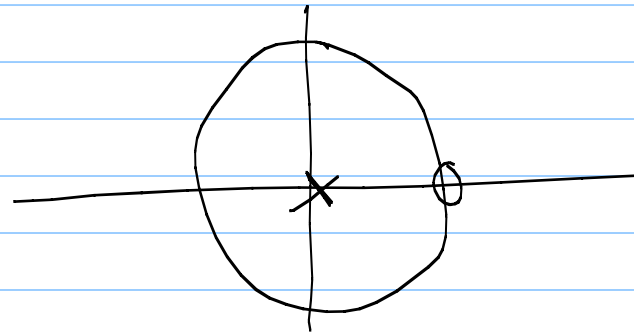
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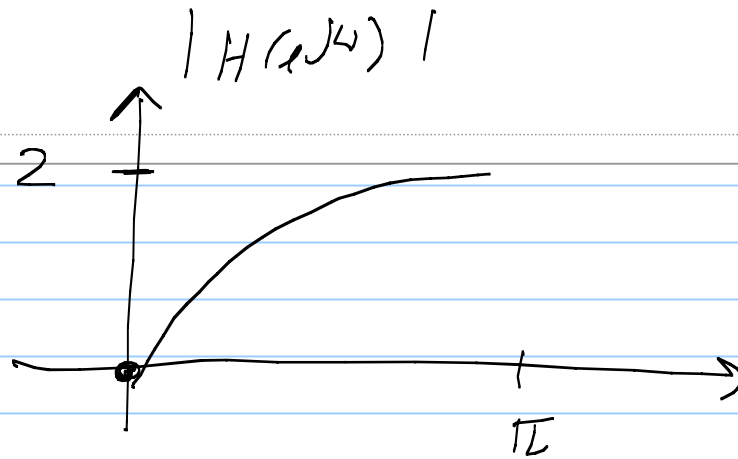
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$$H(z) = \frac{1 - z^{-1}}{z}$$



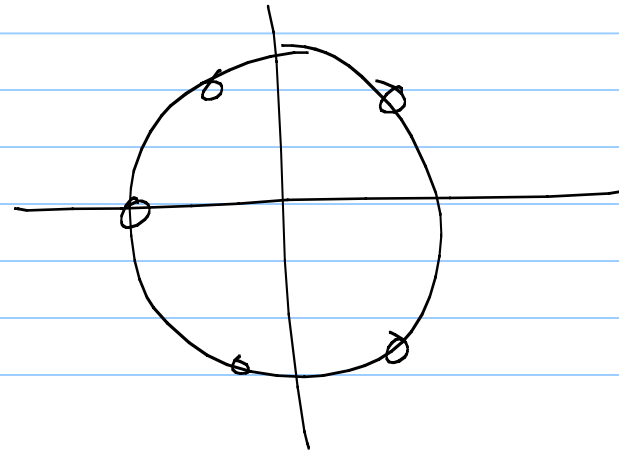


$$|1 - e^{-j\omega}|$$

$$H(z^L) = \frac{1 - z^{-L}}{1 - z^{-1}}$$

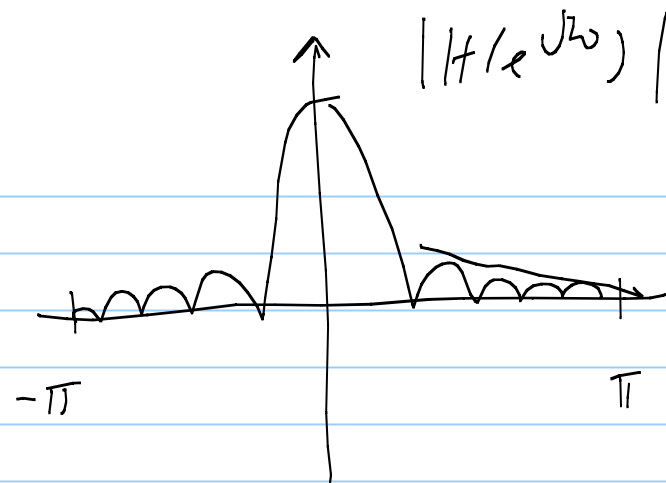
$$|1 - e^{-j\omega L}|$$

$$H(z) = \frac{1 - z^{-N}}{1 - z^{-1}}$$

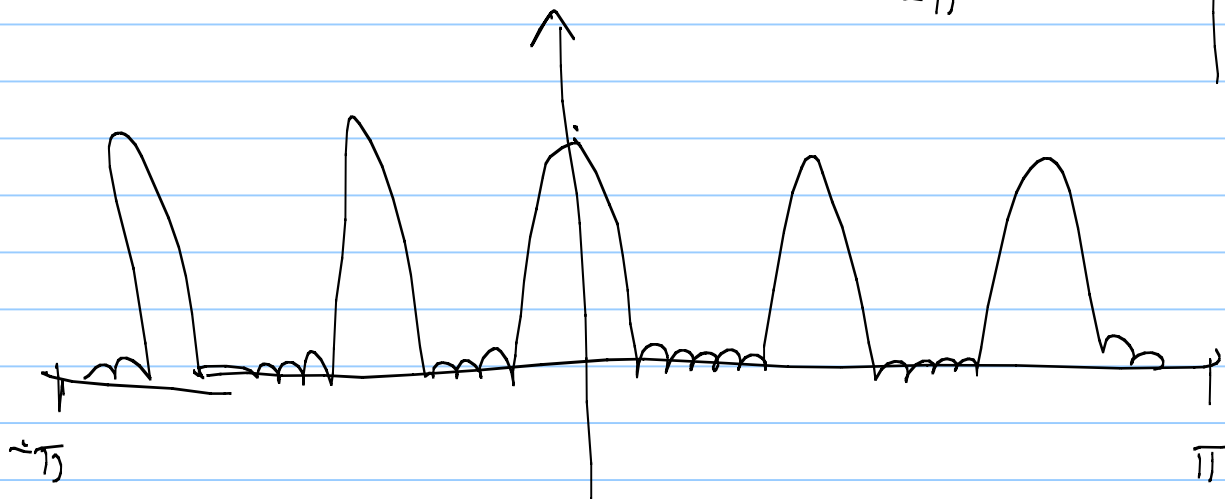


$$H(e^{j\omega}) = e^{-j(N-1)\omega/2}$$

$$\frac{\sin N\omega/2}{\sin \omega/2}$$

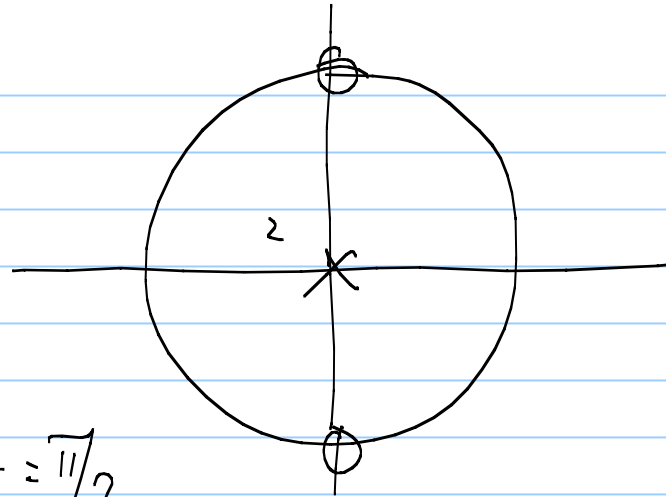


$$|H(e^{j\omega})|$$



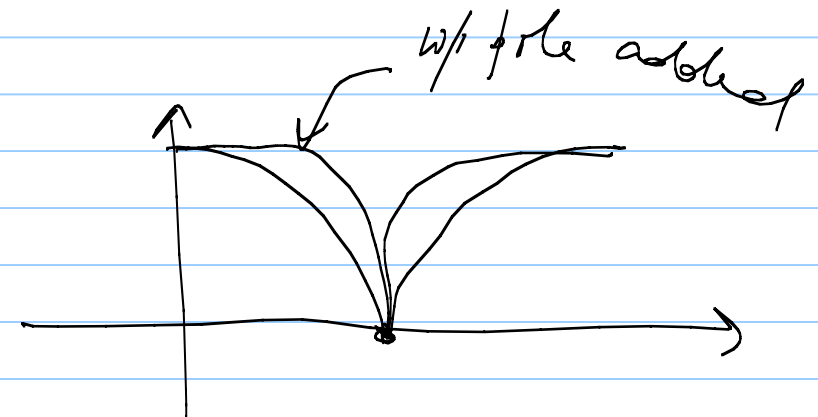
"Comb Filter"

Notch Filter:

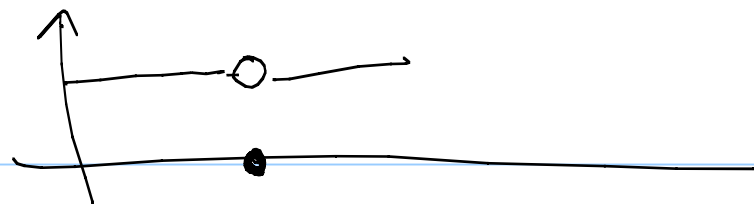


$$H(z) = 1 + z^{-2} \quad r=1, \theta=\pi/2$$

$$H(z) = 1 - 2r \cos \theta z^{-1} + r^2 z^{-2}$$

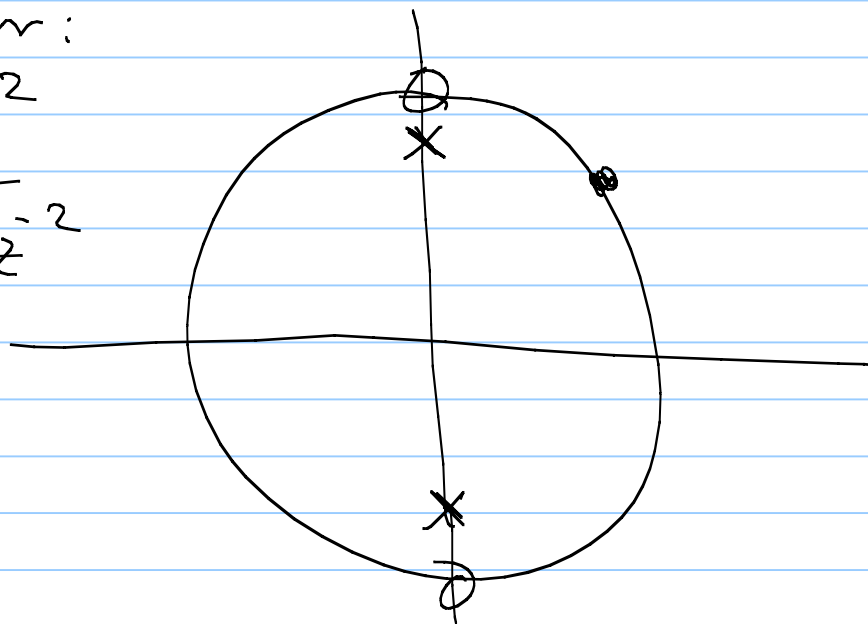


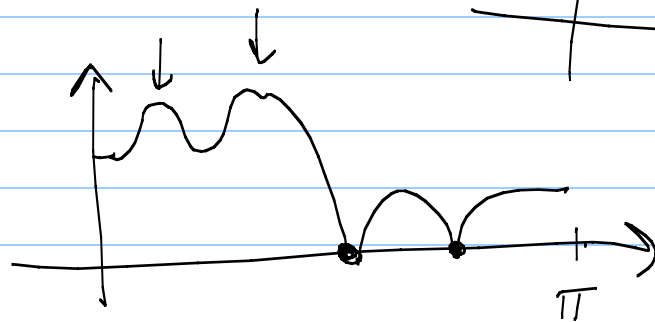
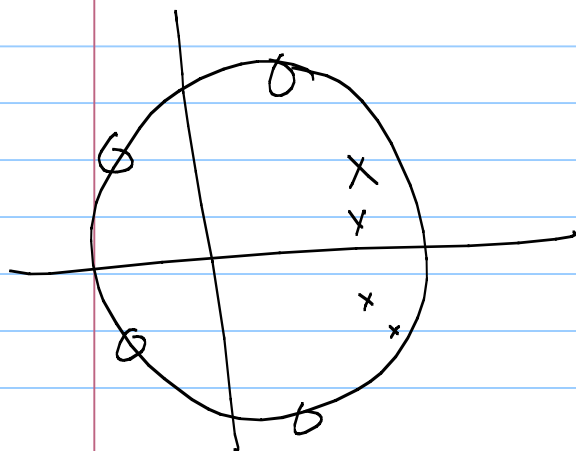
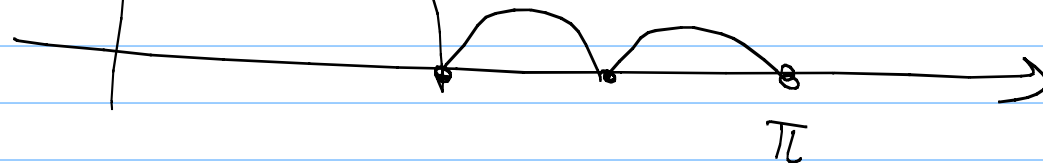
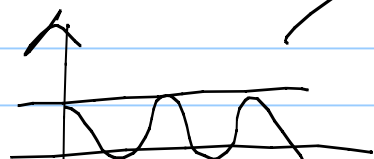
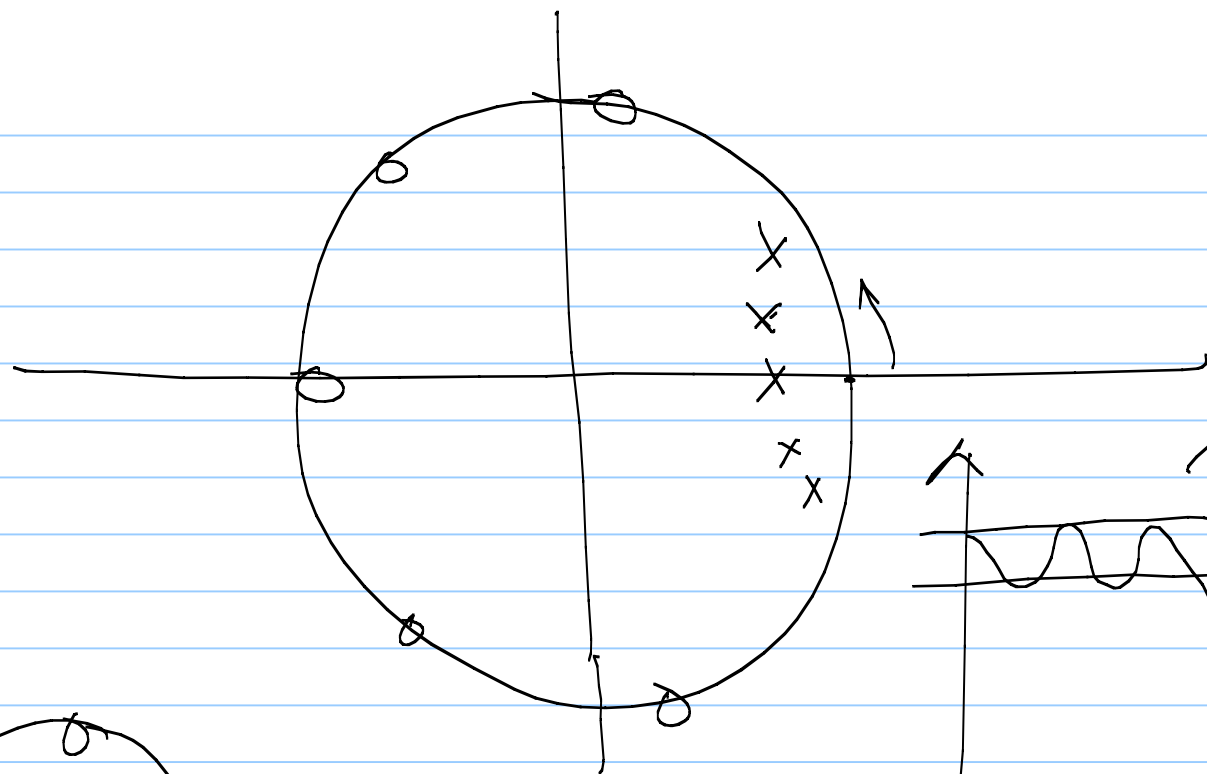
Ideal:

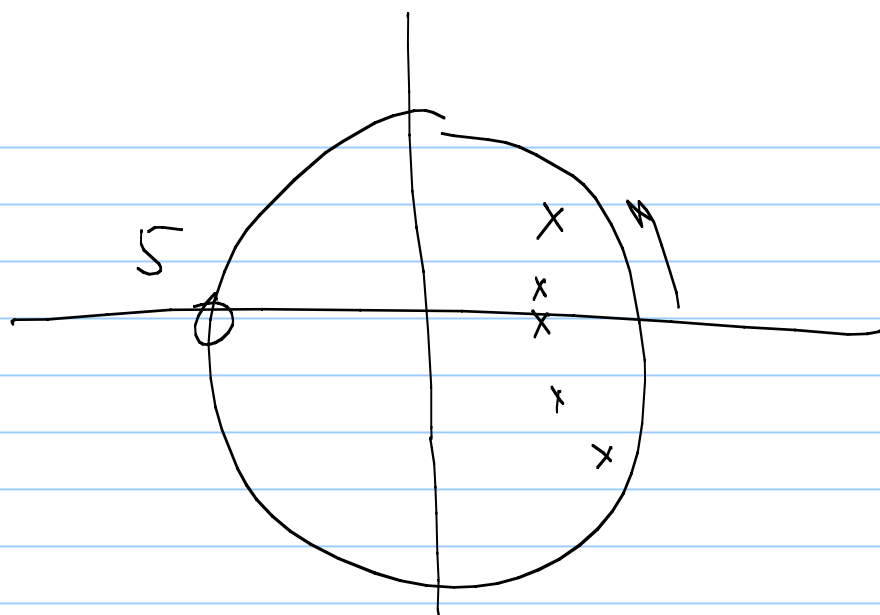


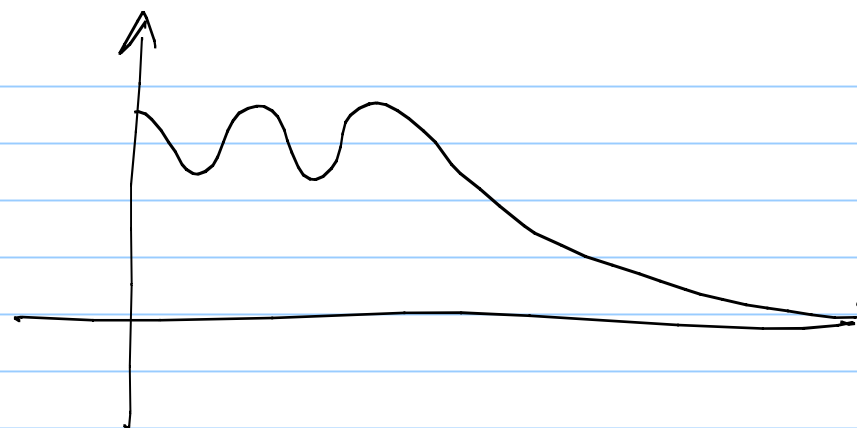
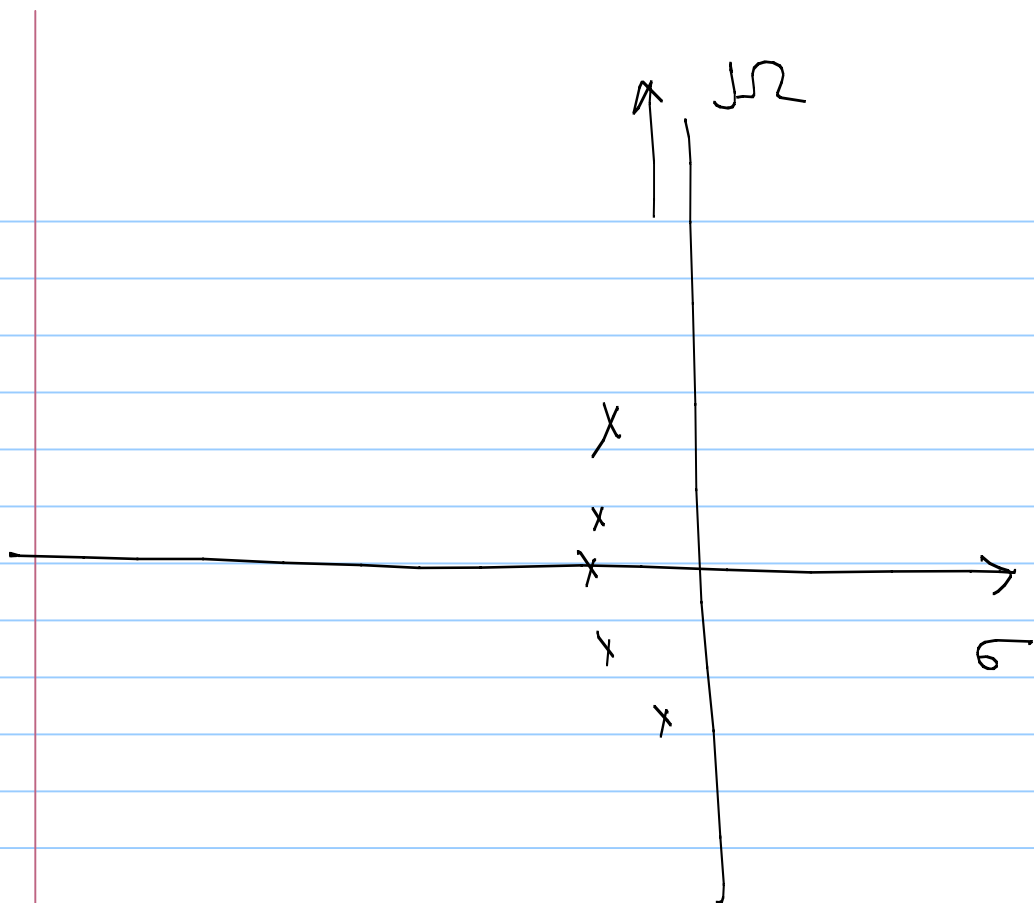
Improved notch filter:

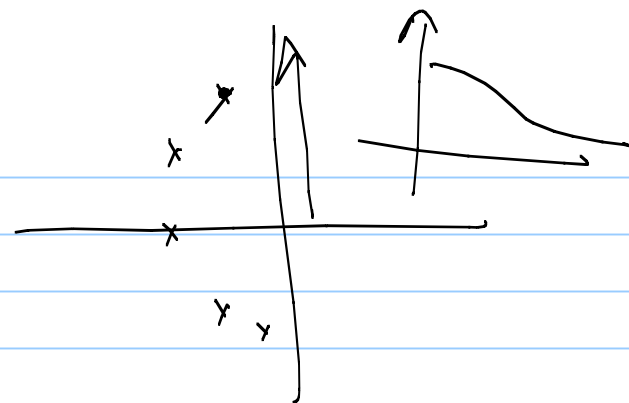
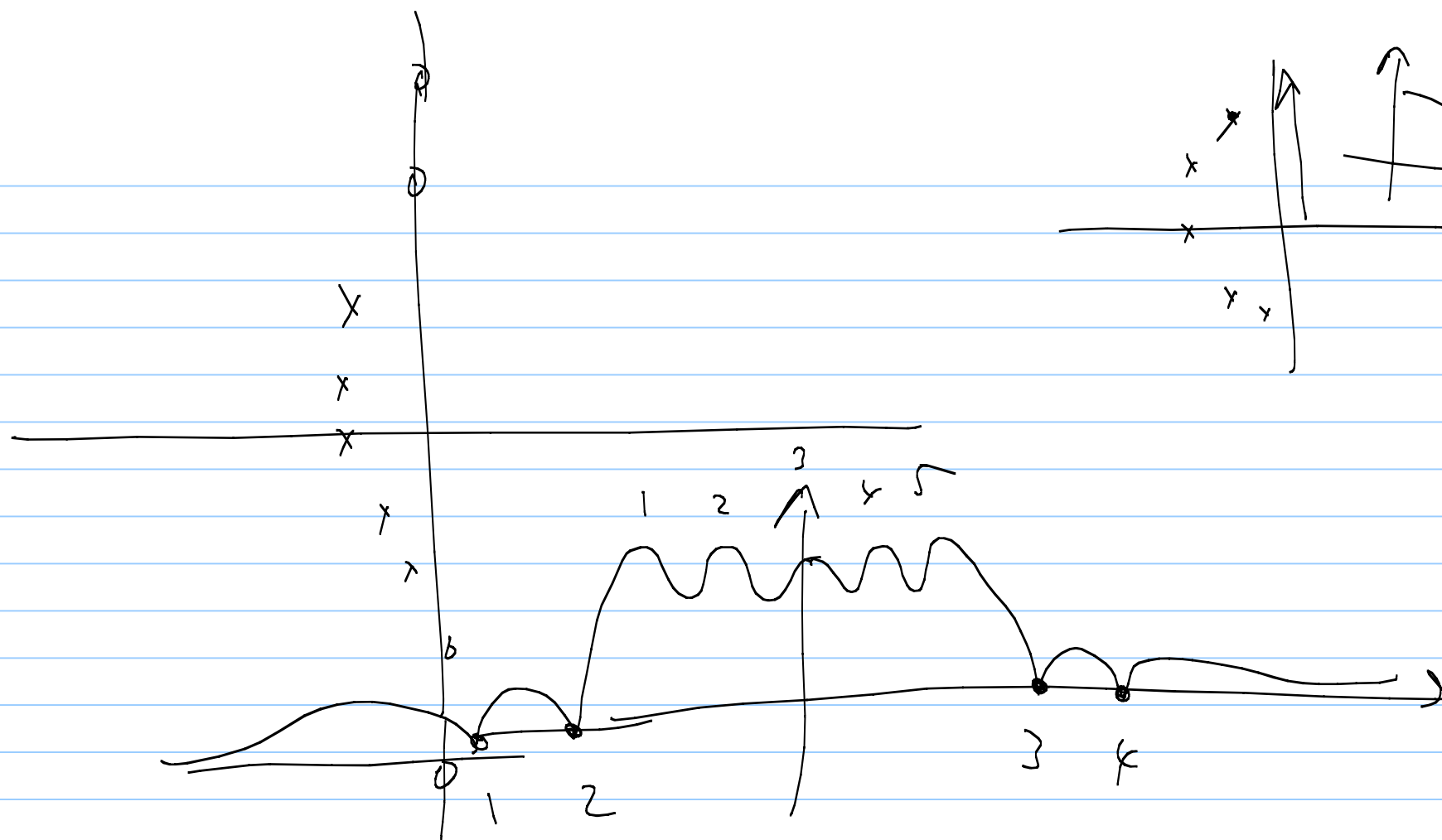
$$H(z) = \frac{1 - 2\cos\theta z^{-1} + z^{-2}}{1 - 2r\cos\theta z^{-1} + r^2 z^{-2}}$$











$$H(e^{j\omega}) = b_0 + \sum_{k=1}^M (1 - b_k e^{-j\omega}) - \sum_{k=1}^N (1 - a_k e^{-j\omega})$$

$$\tan^{-1}(3/4) \neq \tan^{-1}(-3/-4)$$

Single Complex zero

$$1/z = 1 - r e^{j\theta} z^{-1}$$

$$H(e^{j\omega}) = 1 - r e^{j\theta} e^{-j\omega}$$

$$= 1 - r e^{-j(\omega - \theta)}$$

$$= 1 - r \cos(\omega - \theta) + j r \sin(\omega - \theta)$$

$$\angle H(e^{j\omega}) = \tan^{-1} \frac{r \sin(\omega - \theta)}{1 - r \cos(\omega - \theta)}$$

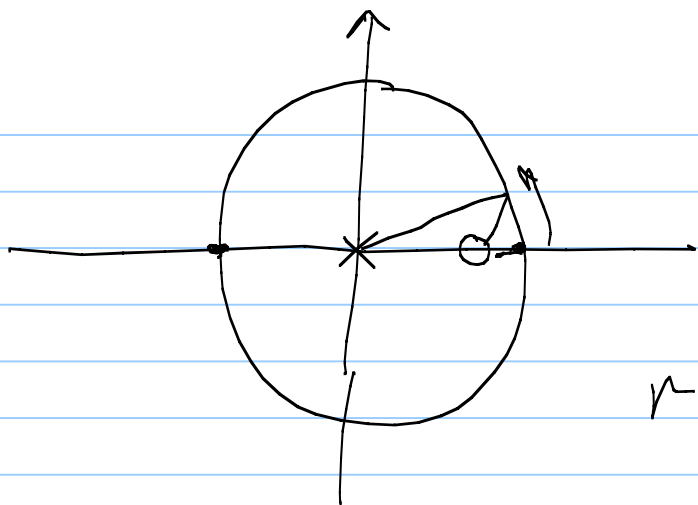
$$H(e^{j\omega}) = b_0 e^{j\omega(N-M)} \frac{\prod_{l=1}^M (e^{j\omega} - z_l)}{\prod_{k=1}^N (e^{j\omega} - p_k)}$$

$$\angle H(e^{j\omega}) = \angle b_0 + \underbrace{\omega(N-M)}_{\text{phase contribution due to trivial poles/zeros}} + \sum_{l=1}^M \angle (e^{j\omega} - z_l) - \sum_{k=1}^N \angle (e^{j\omega} - p_k)$$

phase contribution
due to trivial poles/zeros

Simple complex zeros

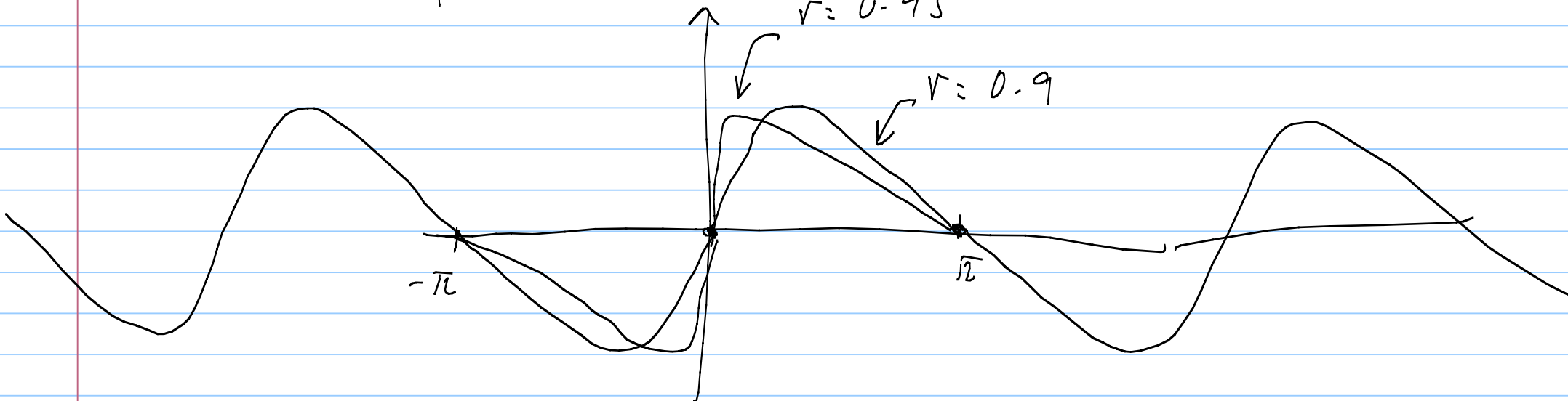
$$\angle H(e^{j\omega}) = \tan^{-1} \frac{r \sin(\omega - \theta)}{1 - r \cos(\omega - \theta)}$$

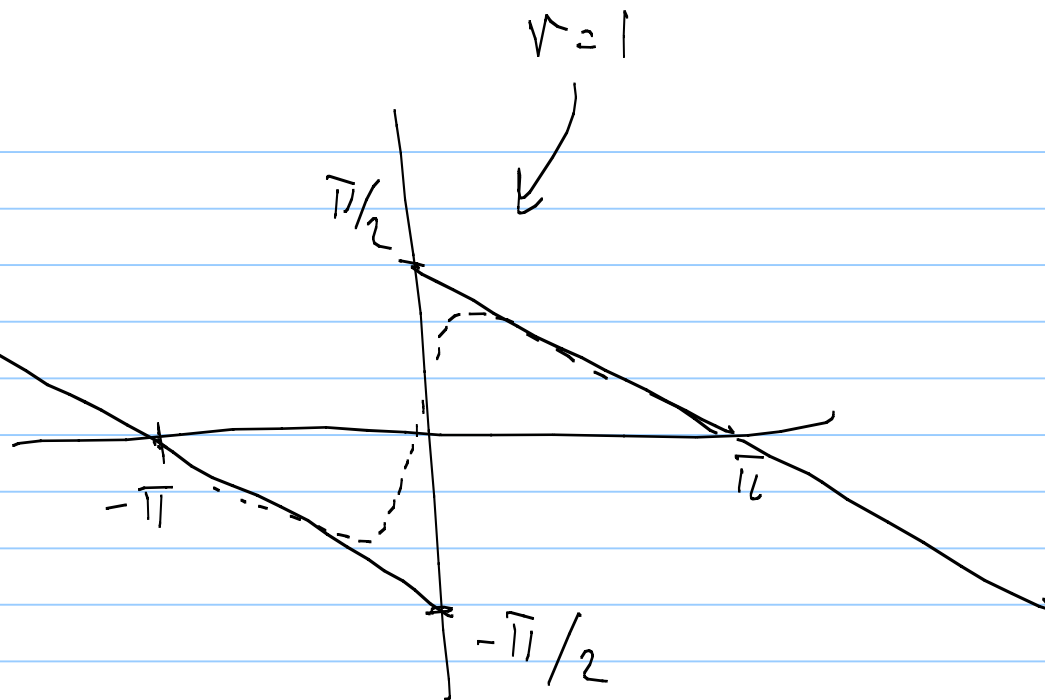
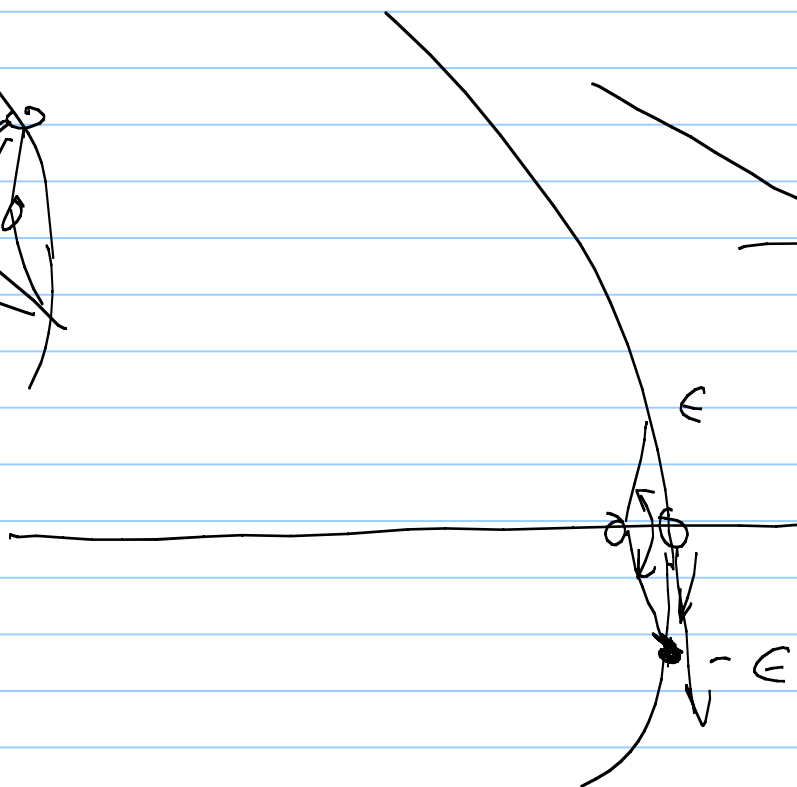
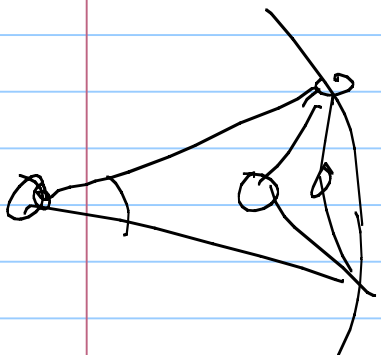


$$r = 0.9, \quad \theta = 0$$

$$r = 0.95$$

$$r = 0.9$$

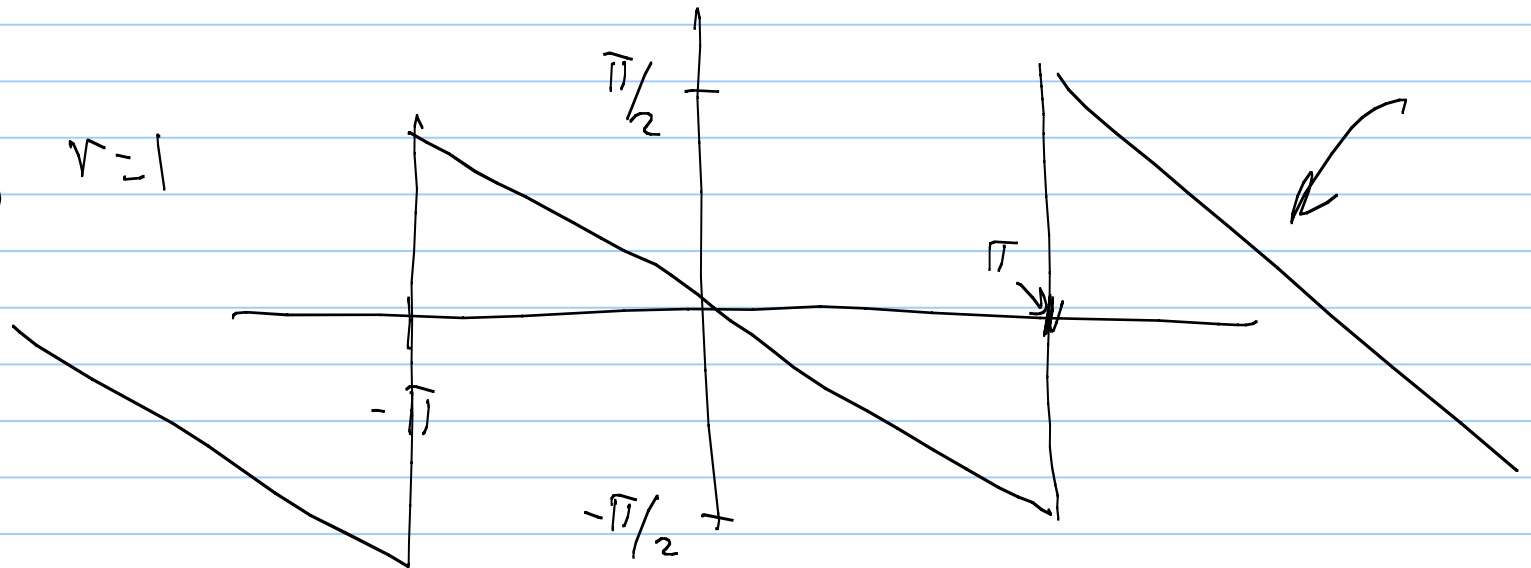


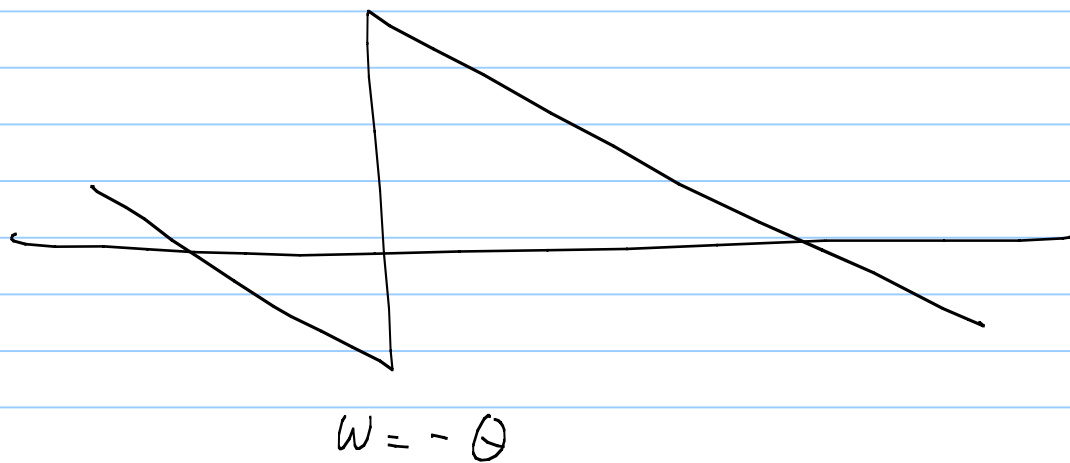
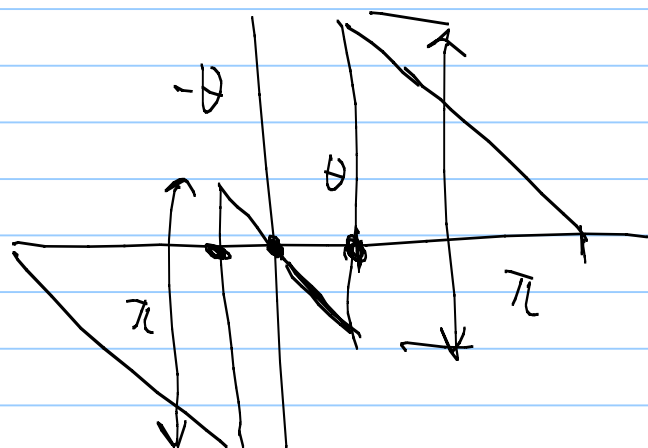
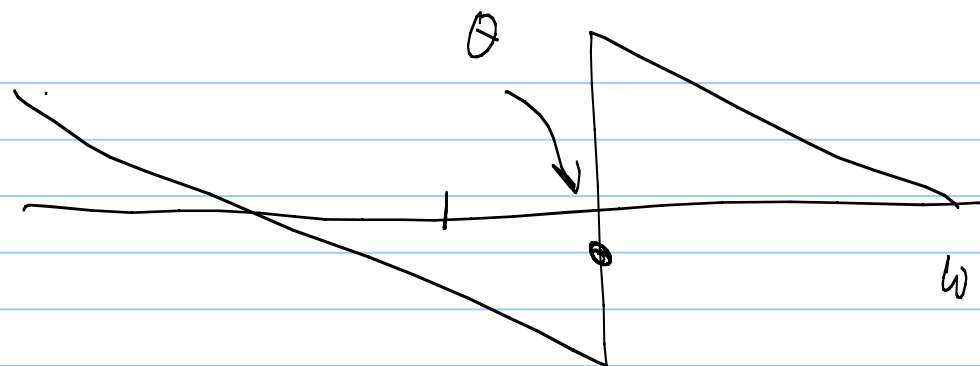
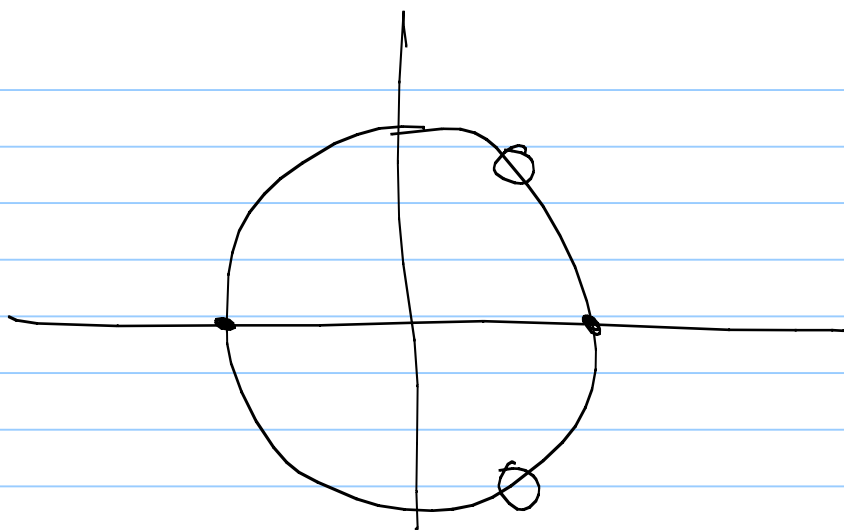


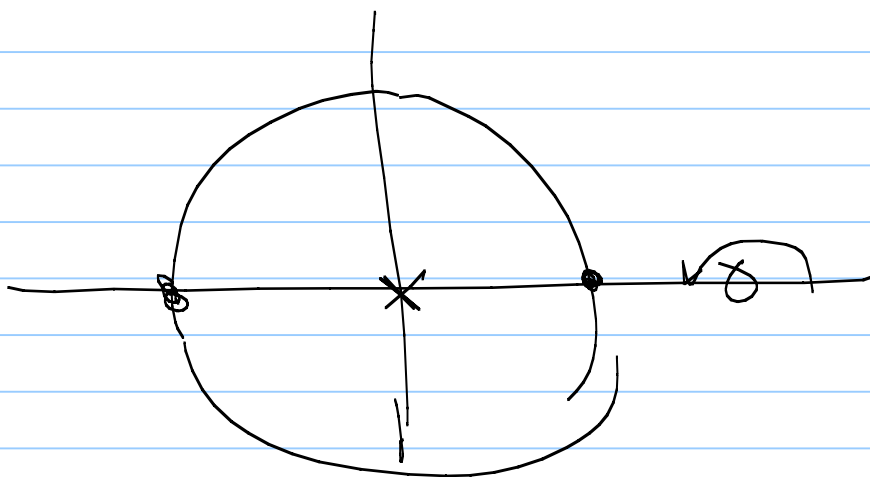
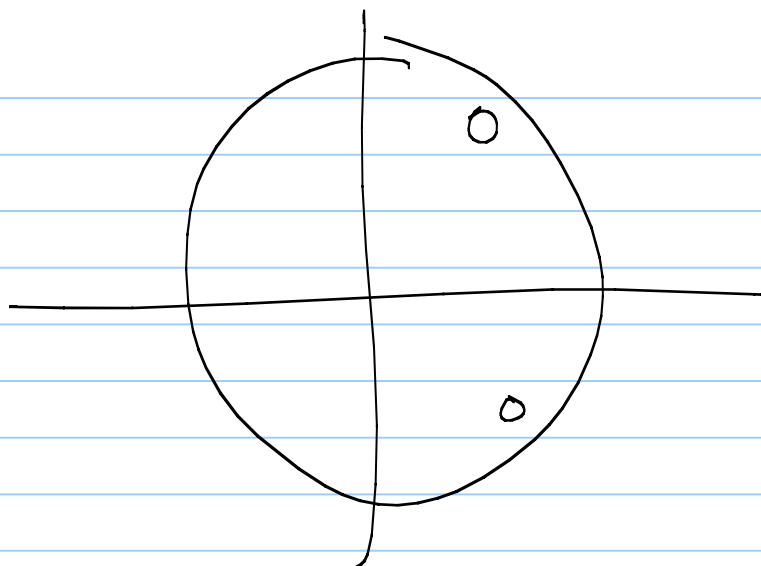
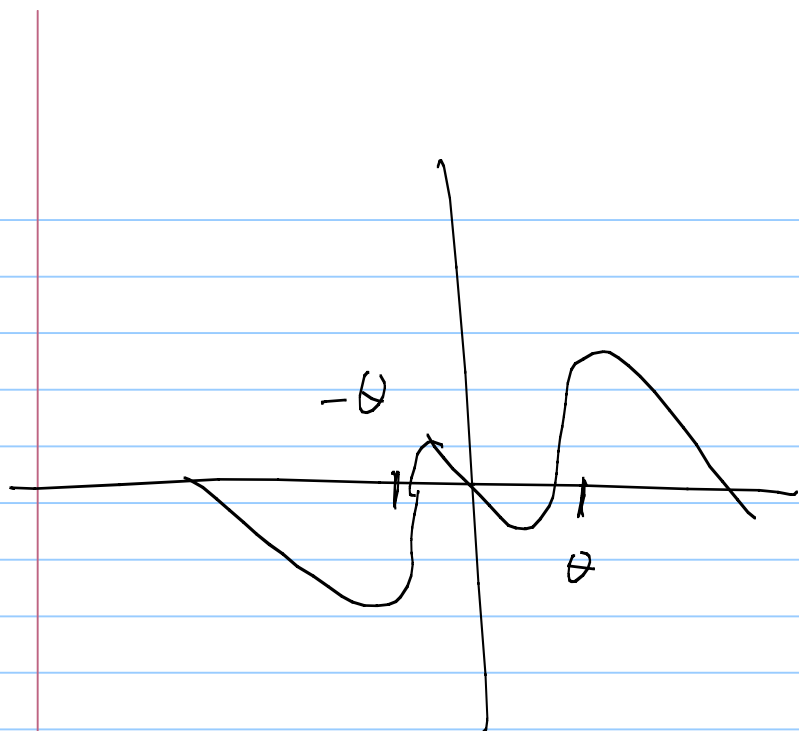
$$\tan^{-1} \frac{\sin \omega}{1 - \cos \omega} = \begin{cases} \pi/2 - \frac{\omega}{2} & \omega > 0 \\ -\frac{\pi}{2} - \frac{\omega}{2} & \omega < 0 \end{cases}$$

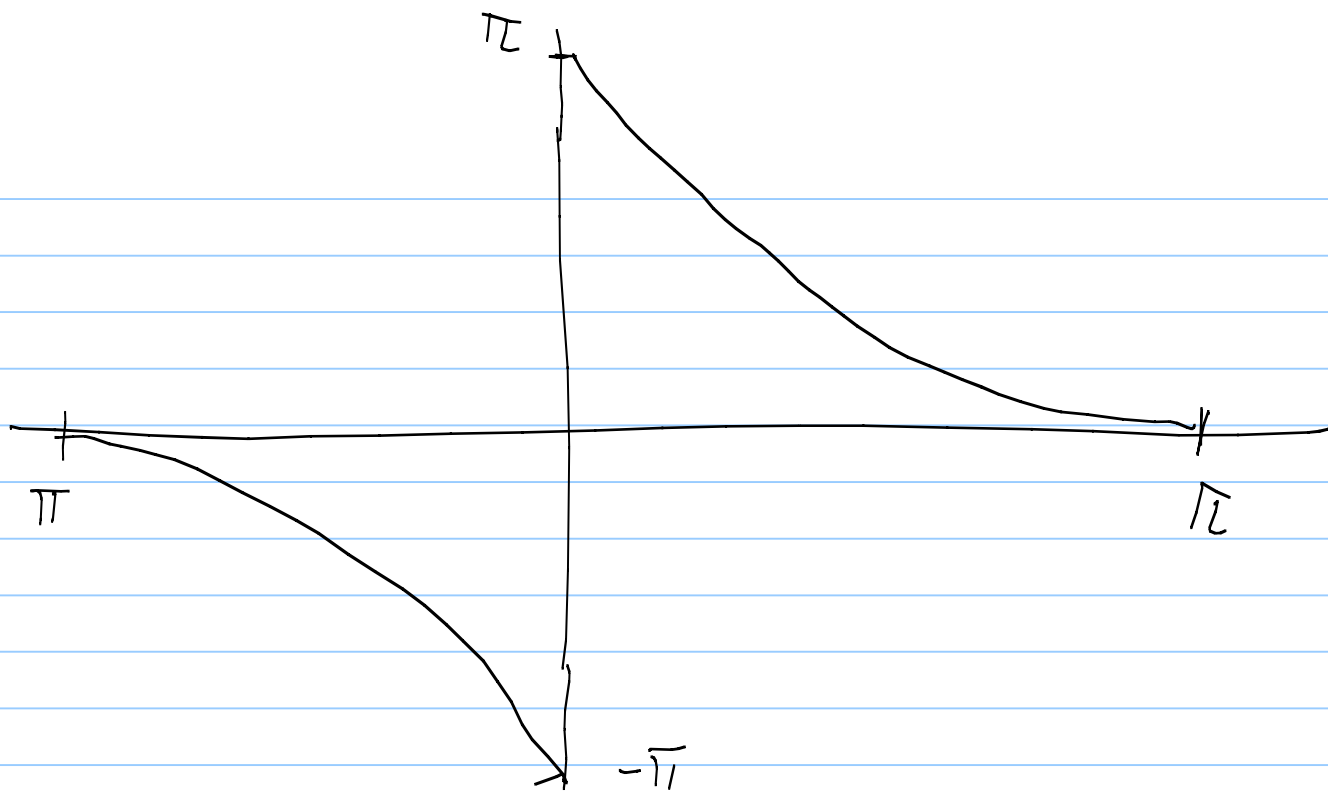
$$\theta = 0, r = 1$$

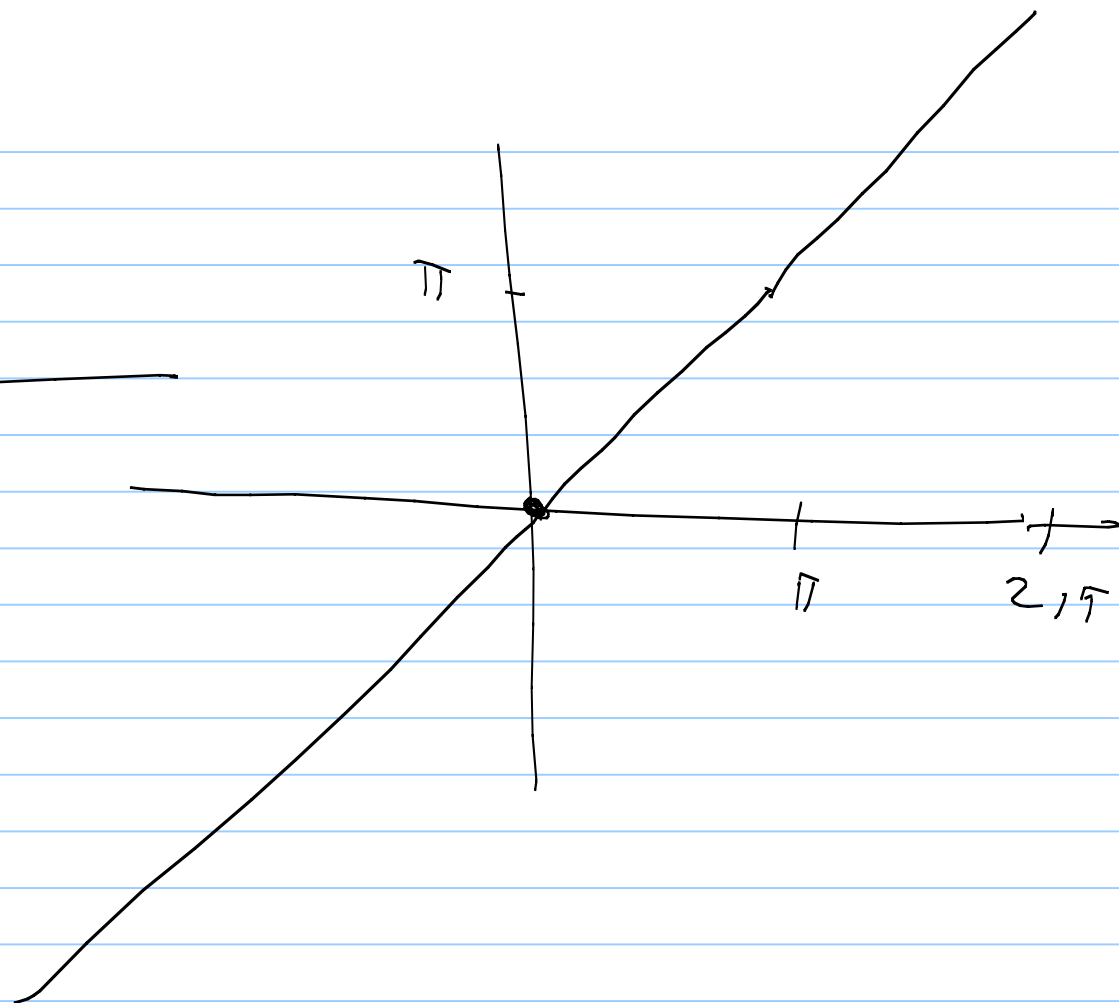
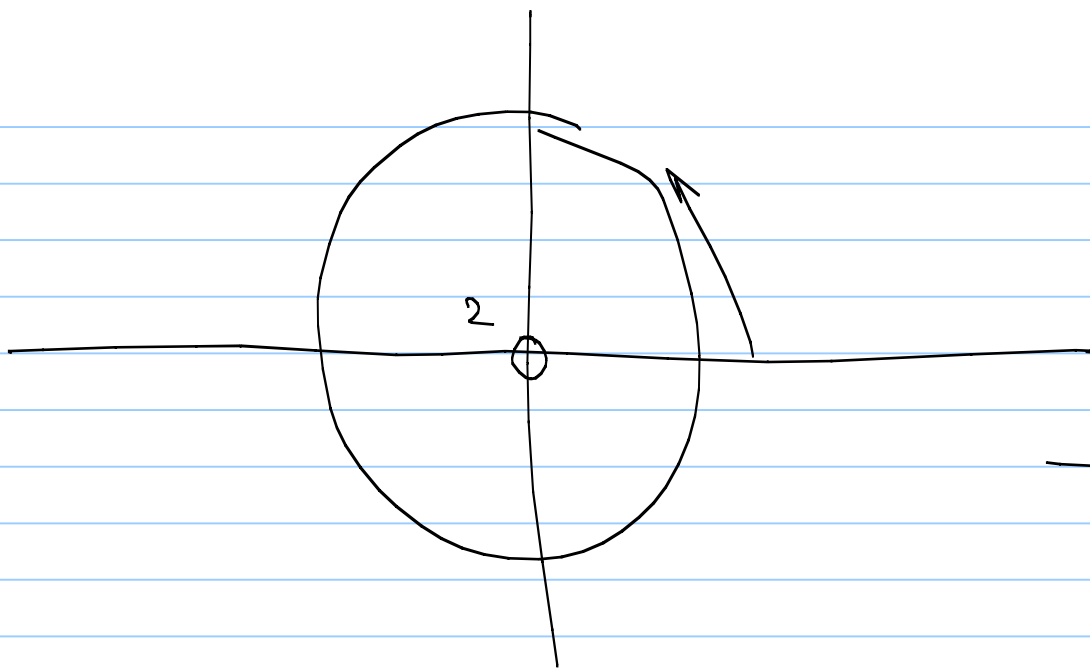
$$\text{For } \theta = \pi, r = 1$$



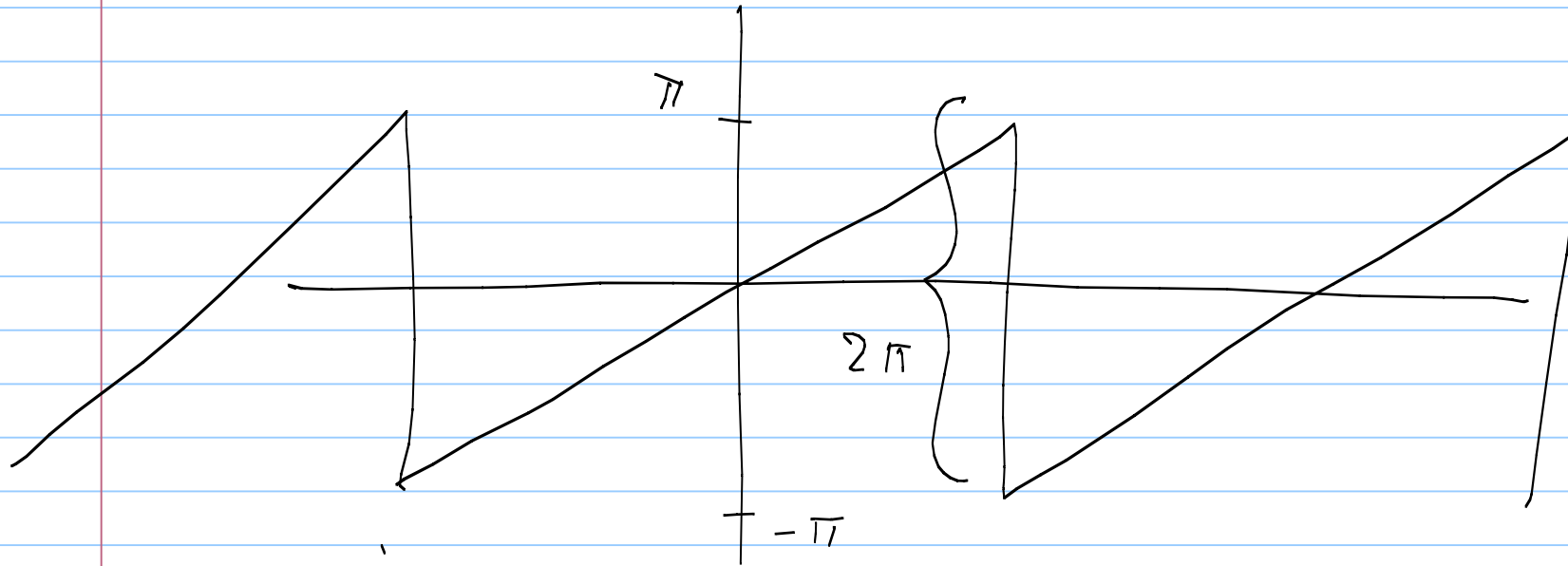








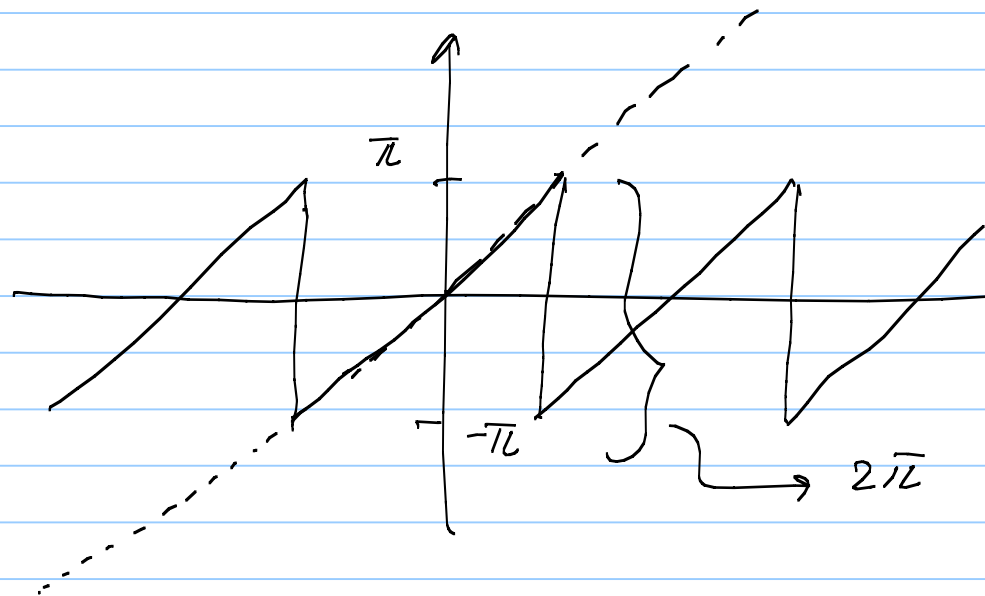
Principal phase. $-\pi \leq \theta < \pi$



EC 5142 Nov 02, 2011

Note Title

02-11-2011



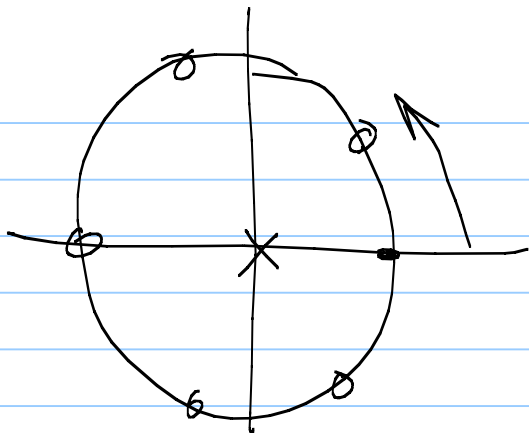
Principal Phase: $-\pi \leq \Phi(\omega) < \pi$ "wrapped phase"
↳ principal
of $H(e^{j\omega})$

From $\underline{\phi}(0)$ we can get back $\phi(\omega)$ by adding or subtracting required multiples of 2π

For rational transfer function, the $\phi(\omega)$ is continuous except for possible jumps of π

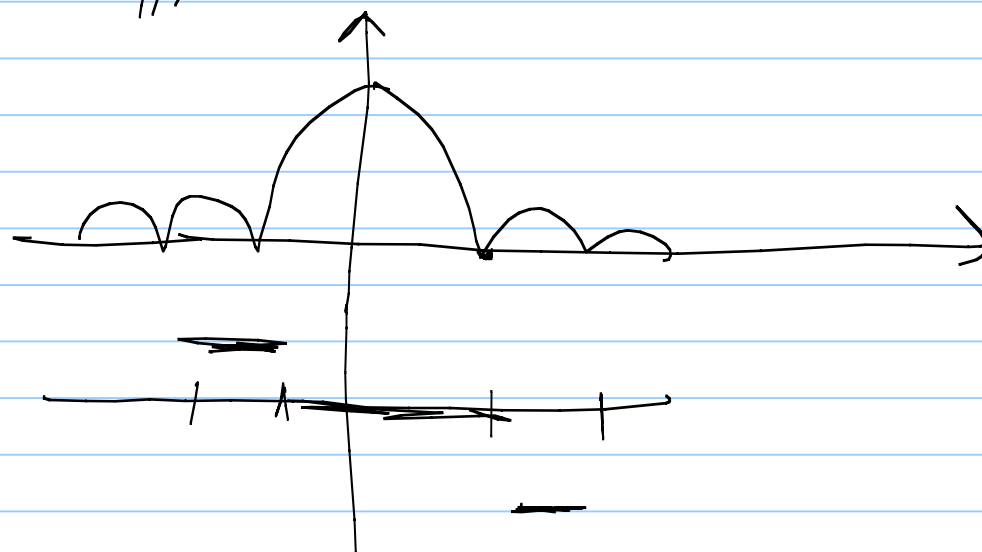
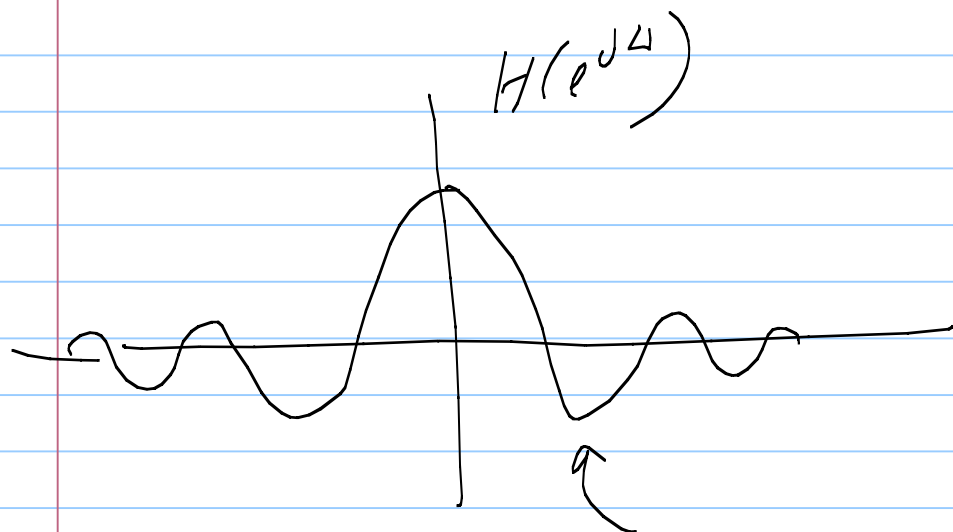
$$H(e^{j\omega}) = |H(e^{j\omega})| e^{j \angle H(e^{j\omega})}$$

$$h[n] = \{1, 1, 1, 1, 1\}$$



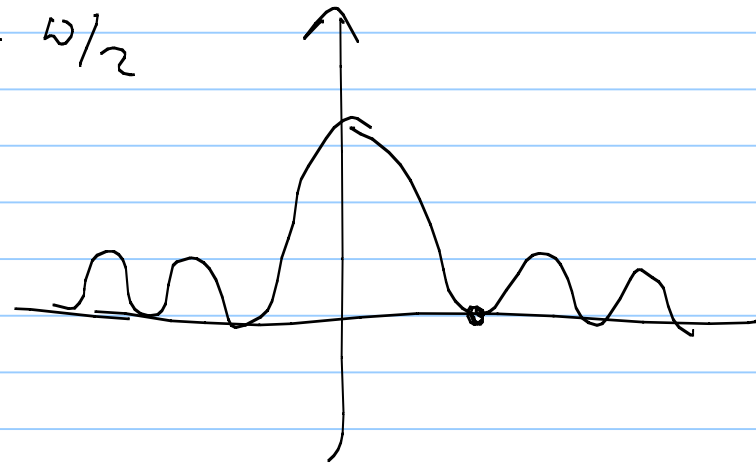
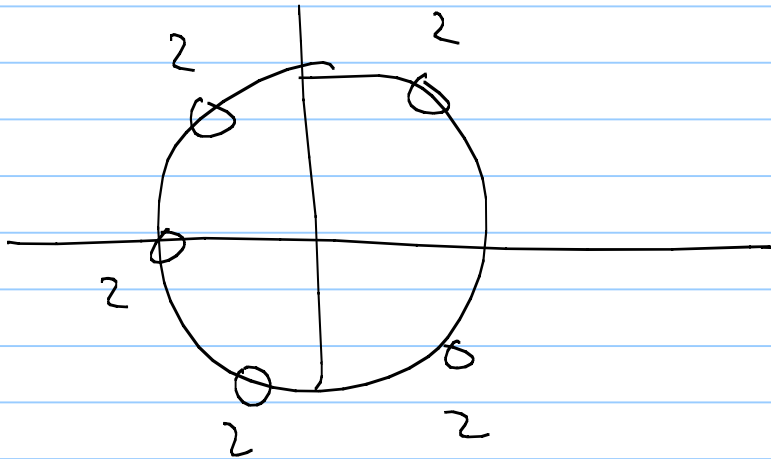
$$\frac{\sin 5\omega/2}{\sin \omega/2}$$

$$|H(e^{j\omega})|$$

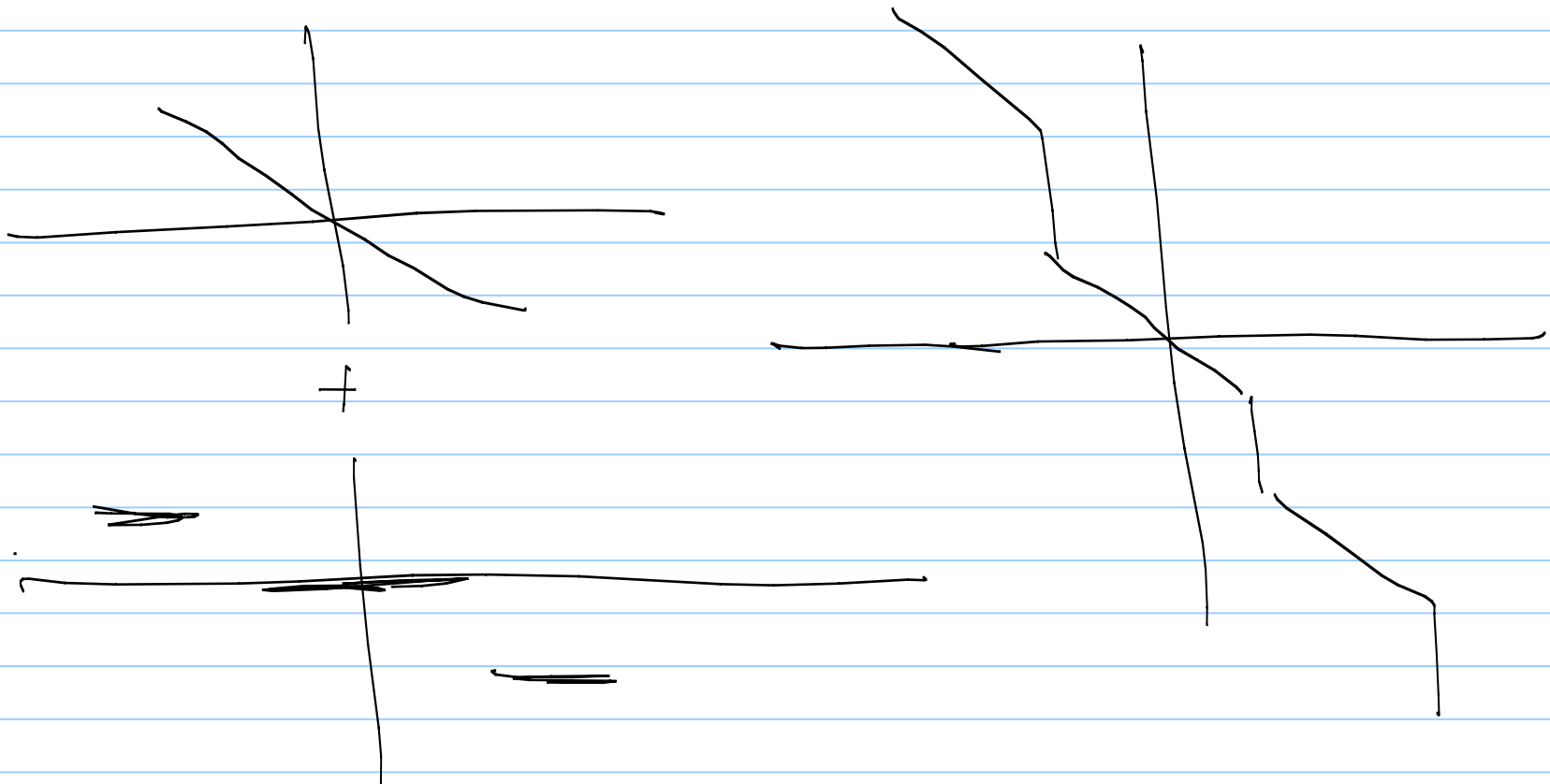


$$h[n] * h[n] \Leftarrow \{1 \ 2 \ 3 \ 4 \ 5 \ 4 \ 3 \ 2 \ 1\}$$

$$H(e^{j\omega}) \cdot H(e^{j\omega}) = \frac{\sin^2 5\omega/2}{\sin^2 \omega/2}$$



$$h(n) = \{1, 1, 1, 1, 1\} \leftrightarrow e^{-j2\omega} \frac{\sin 5\omega/2}{\sin \omega/2} \rightarrow A(\omega)$$



$$H = \text{freqz}(b, a) \rightarrow \Delta H(e^{j\omega})$$

$$H(e^{j\omega}) = |H(e^{j\omega})| e^{j\phi(\omega)}$$

$$= \underbrace{A(\omega)}_{\text{real-valued}} e^{j\phi_1(\omega)}$$

continuous

true for
rational TF

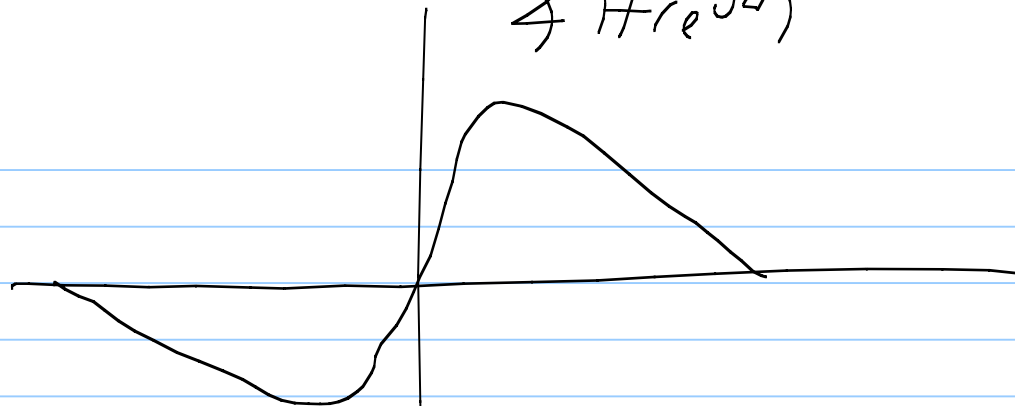
$$\text{Group Delay: } -\frac{d}{d\omega} \phi(\omega) = \tau_g(\omega)$$

Simple complex zero

$$\phi(\omega) = \tan^{-1} \frac{r \sin(\omega - \theta)}{1 - r \cos(\omega - \theta)}$$

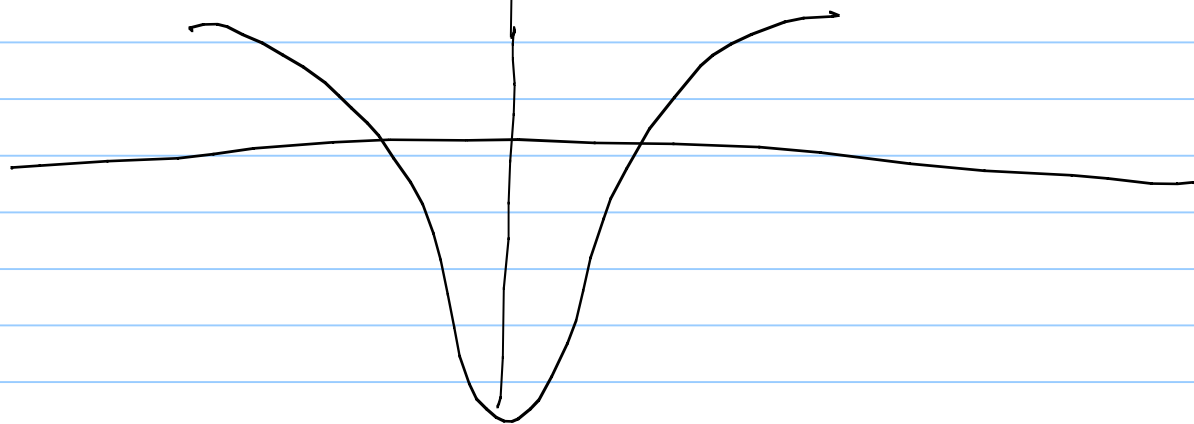
$$-\frac{d}{d\omega} \phi(\omega) = \frac{r(r - \cos(\omega - \theta))}{|1 - r e^{j\theta} e^{j\omega}|^2}$$

$\angle H(e^{j\omega})$



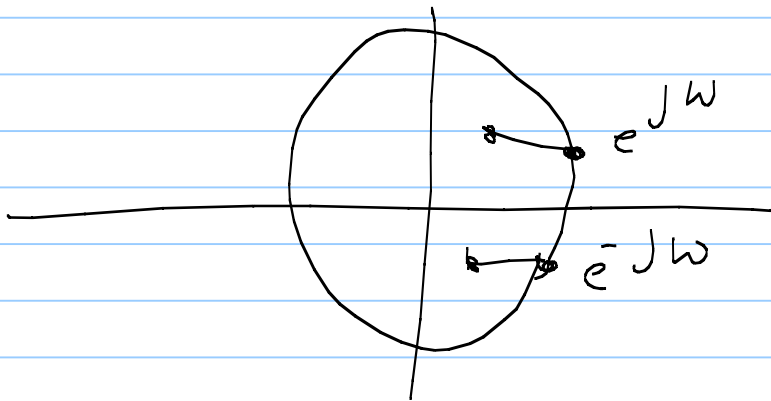
Single complex zero

$\angle g(\omega)$



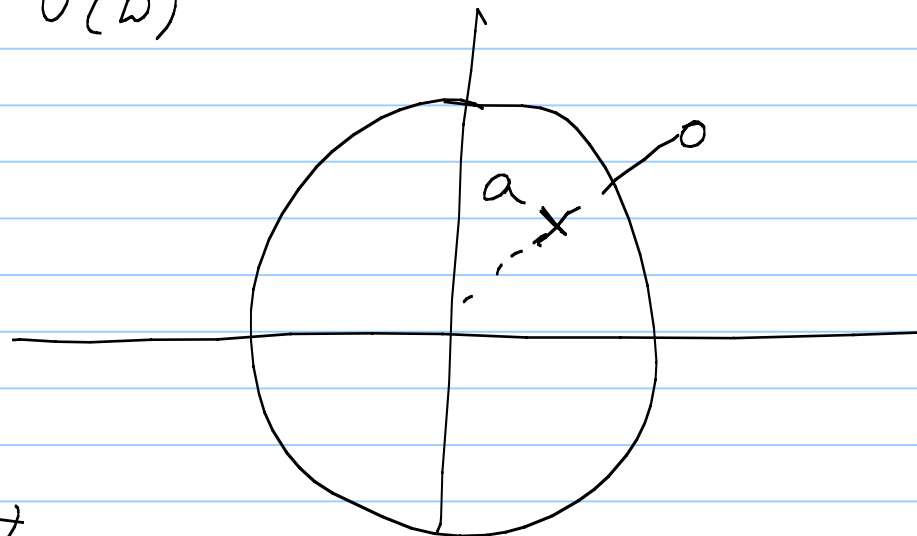
$$H(z) = \frac{-a^* + z^{-1}}{1 - a \bar{z}^*}$$

$$H(e^{j\omega}) = \frac{-a^* + e^{-j\omega}}{1 - a e^{-j\omega}} = \frac{e^{-j\omega} - a^*}{e^{-j\omega} (e^{j\omega} - a)}$$



$$|H(e^{j\omega})| = \left| \frac{e^{-j\omega} - a^*}{e^{j\omega} - a} \right| = 1$$

$$H(e^{j\omega}) = e^{j\theta(\omega)}$$



pole: $a = r e^{j\theta}$

zero: $1/a^* = \frac{1}{r} e^{j\theta}$

reflected across the unit circle

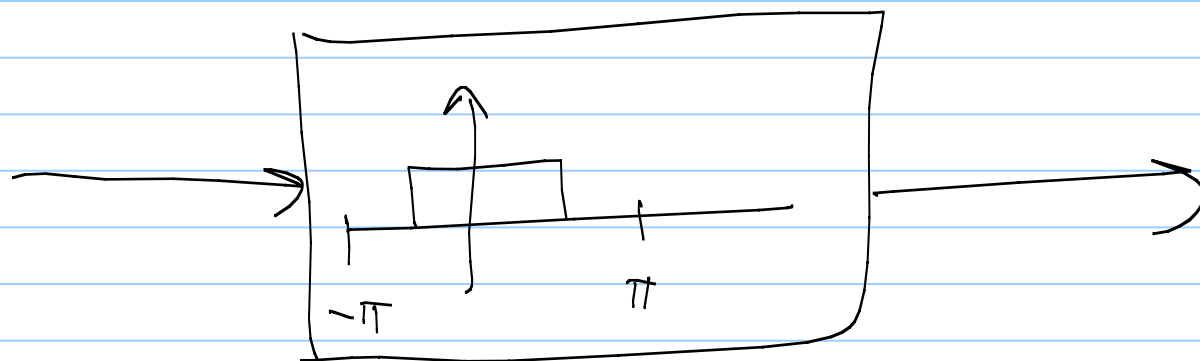
$$H(z) = \frac{-a^* \left(1 - \frac{1}{a^*} z^{-1}\right)}{1 - a z^{-1}}$$

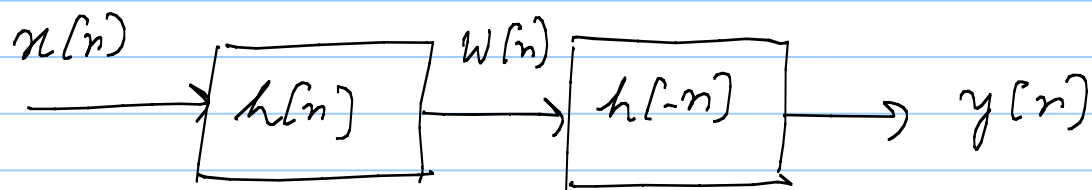
$$|H(e^{j\omega})| = 1 \quad \text{"All pass" Section}$$

$$H_{AP}(z) = \frac{a_N^* + a_{N-1}^* z^{-1} + \dots + a_1^* z^{-(N-1)} + z^{-N}}{1 + a_1 z^{-1} + \dots + a_N z^{-N}}$$

$$= \frac{z^{-N} A^*(z^*)}{A(z)}$$

$$\begin{cases} 1 & |W| < W_c \\ 0 & \text{otherwise} \end{cases}$$





$$W(e^{j\omega}) = X(e^{j\omega}) H(e^{j\omega})$$

$$Y(e^{j\omega}) = X(e^{j\omega}) H(e^{j\omega}) H(e^{-j\omega})$$

For real-valued $h[n]$, $H(e^{-j\omega}) = H^*(e^{j\omega})$

$$\begin{aligned} Y(e^{j\omega}) &= X(e^{j\omega}) H(e^{j\omega}) H^*(e^{j\omega}) \\ &= X(e^{j\omega}) |H(e^{j\omega})|^2 \end{aligned}$$

$$|H(e^{j\omega})|^2 = \text{"zero phase filter"}$$

Note Title

03-11-2011

Not practical because $h[-n]$ is non-causal if $h[n]$ is causal

$$\begin{aligned} x[n] &\longleftrightarrow X(e^{j\omega}) \\ x[n-n_0] &\longleftrightarrow e^{-j\omega n_0} X(e^{j\omega}) \end{aligned}$$

$$x[n] = A_1 \cos \omega_1 n + A_2 \cos \omega_2 n$$

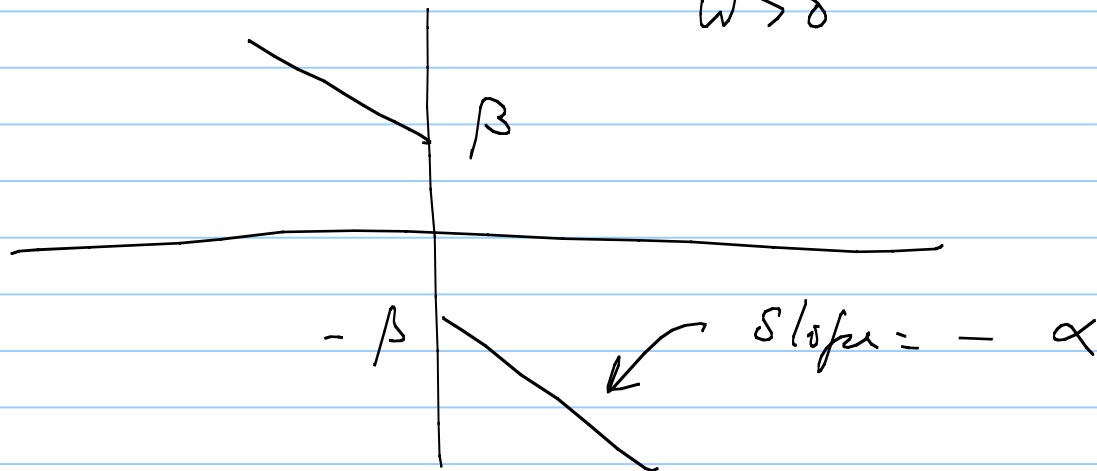
$$x[n-n_0] = A_1 \cos \omega_1 (n-n_0) + A_2 \cos \omega_2 (n-n_0)$$

$$= A_1 \cos(\omega_1 t - \underbrace{\omega_1 t_0}_{\phi_1}) + A_2 \cos(\omega_2 t - \underbrace{\omega_2 t_0}_{\phi_2})$$

$$\phi(\omega) = -\alpha\omega + \beta$$

generalized
linear phase

$\omega > 0$

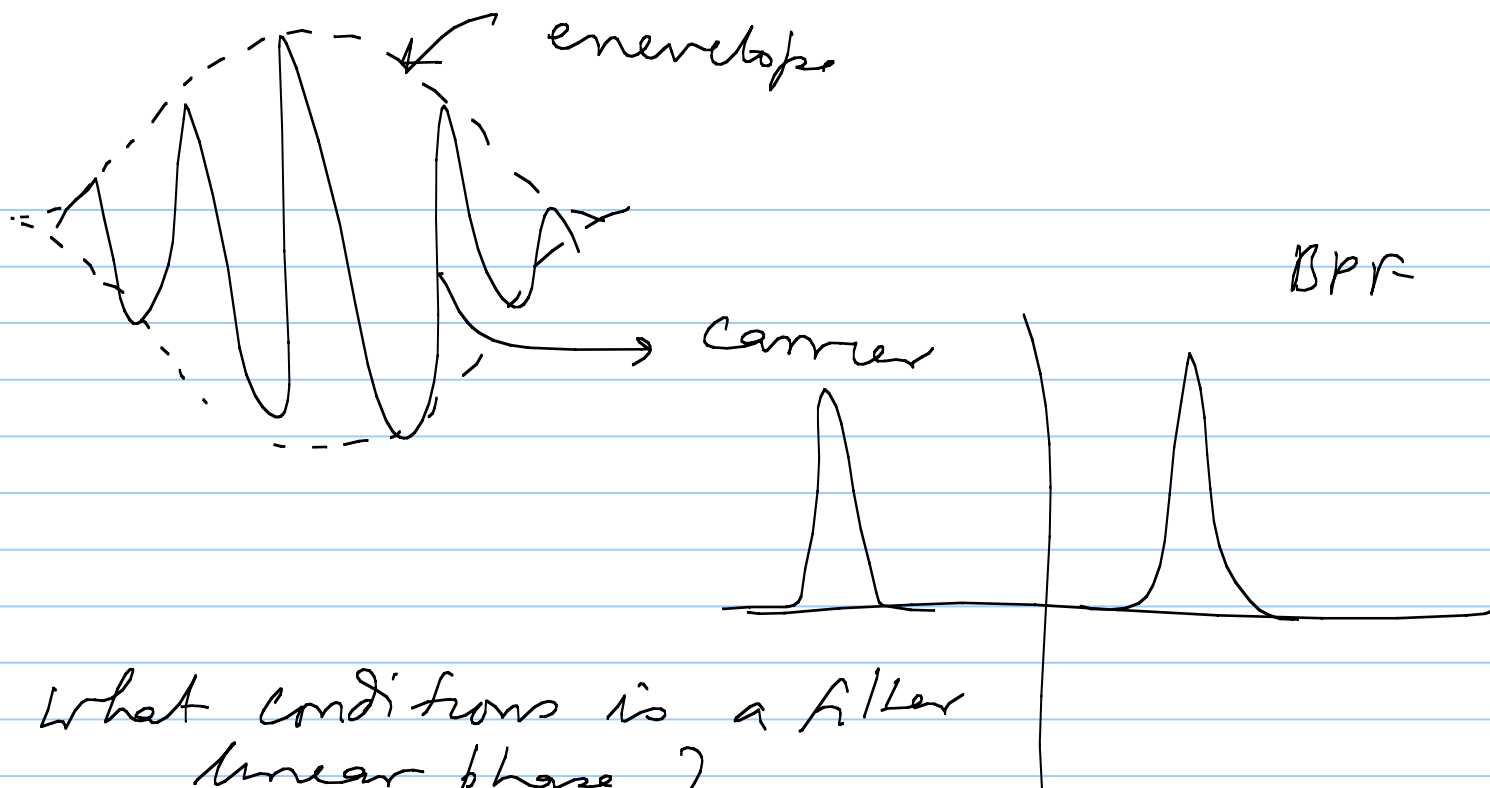


$$\tau_g(\omega) = - \frac{d\phi}{d\omega} = \alpha$$

Phase delay: $\tau_{ph}(\omega) = - \frac{\phi(\omega)}{\omega}$

For $\phi(\omega) = -\alpha\omega$ $\tau_g(\omega) = \alpha$

$$\tau_{ph}(\omega) = \alpha$$



Under what conditions is a filter linear phase?

$$\phi(\omega) = -\alpha\omega + \beta$$

$$H(e^{j\omega}) = \sum_n h[n] e^{-j\omega n}$$

$$= |H(e^{j\omega})| e^{j(-\alpha\omega + \beta)}$$

$$\sum_n h[n] \cos \omega n - j \sum_n h[n] \sin \omega n = |H(e^{j\omega})| e^{j(-\alpha\omega + \beta)}$$

$$\frac{-\sum_n h[n] \sin \omega n}{\sum_n h[n] \cos \omega n} = \frac{\sin(-\alpha\omega + \beta)}{\cos(-\alpha\omega + \beta)}$$

$$\sum_n h(n) \sin \omega n \cos (-\alpha \omega + \rho)$$

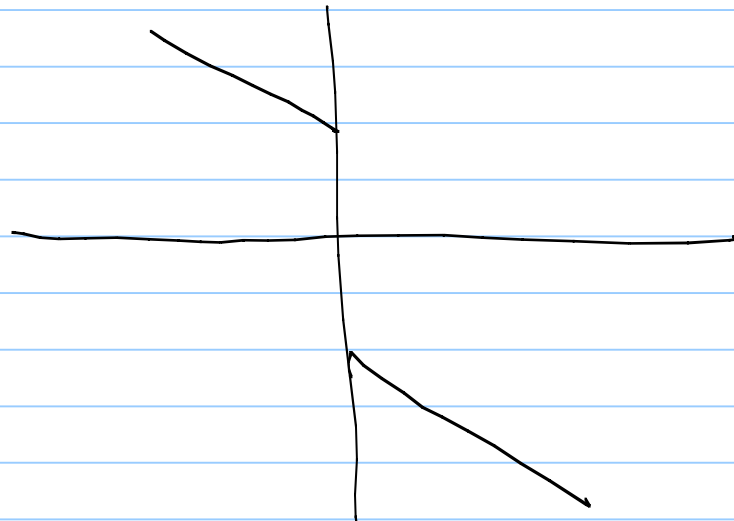
$$+ \sum_n \sin (-\alpha \omega + \rho) h(n) \cos \omega n = 0$$

$$\sum_n h(n) \sin ((\alpha + n)\omega + \rho) = 0$$

EC5142 Nov 10 2011

Note Title

10-11-2011



Generalized linear phase.

$$\phi(\omega) = -\alpha\omega + \beta \quad \omega > 0$$

$$H(e^{j\omega}) = |H(e^{j\omega})| e^{j(-\alpha\omega + \beta)} = \sum_n h[n] e^{-j\omega n}$$

$$\sum_n h[n] \sin(-\alpha + n\omega + \beta) = 0$$

$h[n] = 0 \quad \forall n$ is the trivial solution

First, assume $\beta = 0$

$$\sum_n h[n] \sin(-\alpha + n\omega) = 0$$

Assume $h[n] = 0$ for n outside $[0, N-1]$

i.e., $h[n]$ is an FIR filter

$$\sum_{n=0}^{N-1} h[n] \sin(\overline{-\alpha + n} \omega) = 0$$

$$h[0] \sin(-\alpha \omega)$$

$$h[N-1] \sin(\overline{-\alpha + N-1} \omega)$$

$$\alpha = -\alpha + N-1 \Rightarrow \alpha = \frac{N-1}{2}$$

$$h[0] = h[N-1]$$

$$h[1] \sin(\overline{-\alpha + 1} \omega)$$

$$h[N-2] \sin(\overline{-\alpha + N-2} \omega)$$

$$\alpha - 1 = -\alpha + N - 2 \Rightarrow \alpha = \frac{N-1}{2}$$

$$h[1] = h[N-2]$$

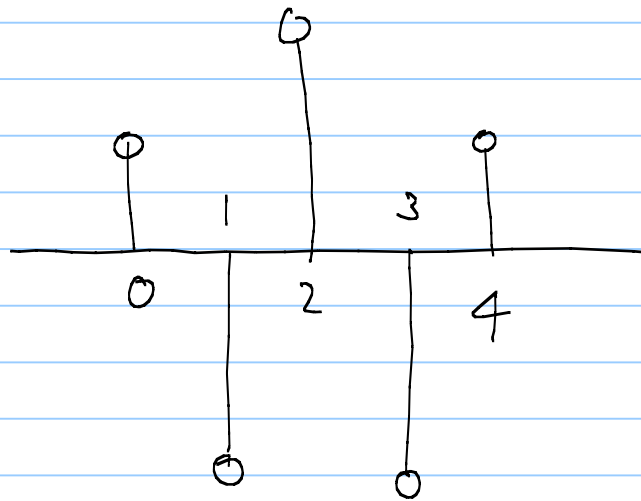
In general, if $h[N-1-n] = h[n]$

& $\alpha = \frac{N-1}{2}$ = Centre of symmetry

pairwise cancellation will occur,

Eg:

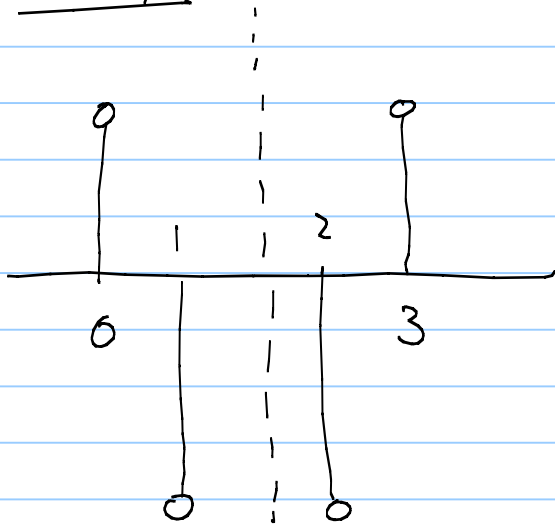
$$\underline{N=5}$$



$$h[n] \sin \left(-\frac{5-1}{2} + n \omega \right) = 0$$

Since $n = \frac{N-1}{2}$ & $\omega = \frac{2\pi}{N}$

For $N=4$



$$\phi(\omega) = -\alpha \omega$$

$$= -\frac{N-1}{2} \omega$$

$$T_g(\omega) = \frac{N-1}{2}$$

Now consider $\beta \neq 0$. Let $\beta = \frac{\pi}{2}$

$$\sum_{n=0}^{N-1} h[n] \sin \left(\overline{-\alpha + n} \omega + \pi/2 \right) = 0$$

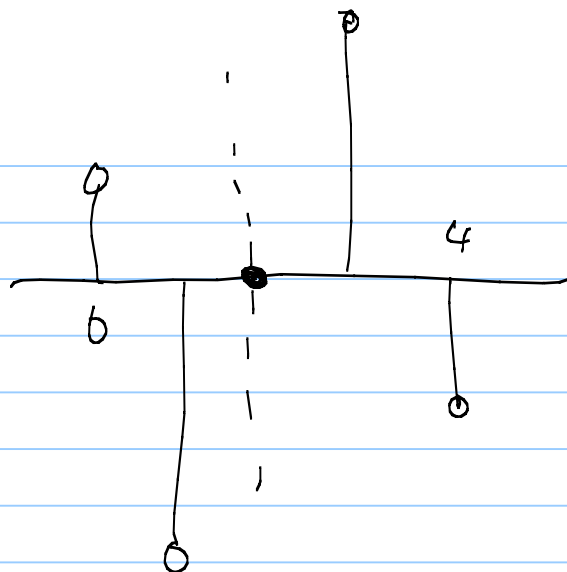
$$\sum_{n=0}^{N-1} h[n] \cos \left(\overline{-\alpha + n} \omega \right) = 0$$

$$h[0] \cos(-\alpha \omega)$$

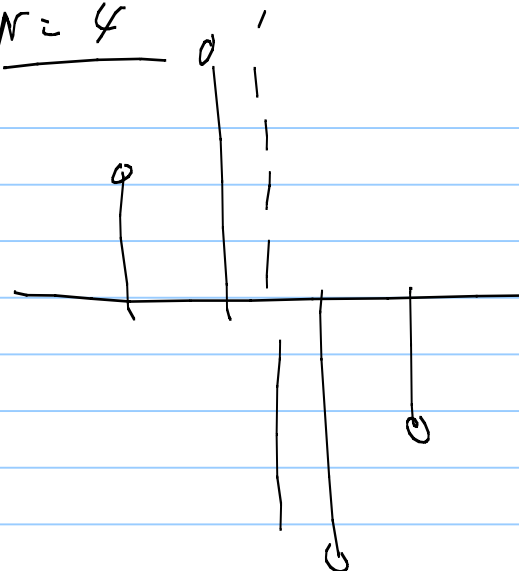
$$h[N-1] \cos \left(\overline{-\alpha + N-1} \omega \right) \quad \alpha = \frac{N-1}{2}$$

$$h[0] = -h[N-1]$$

$$\underline{N=5}$$

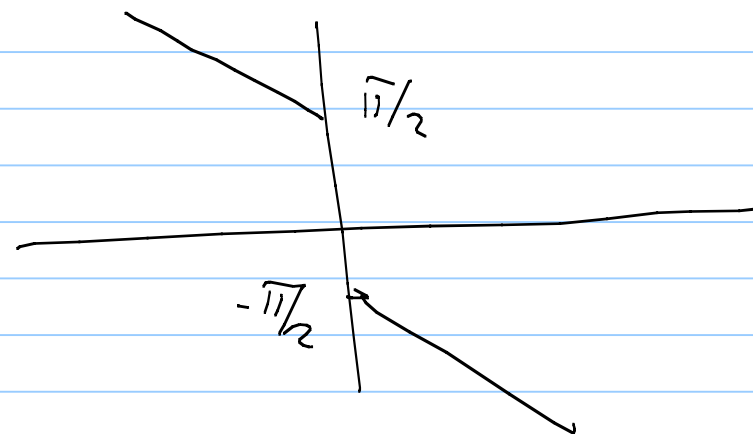


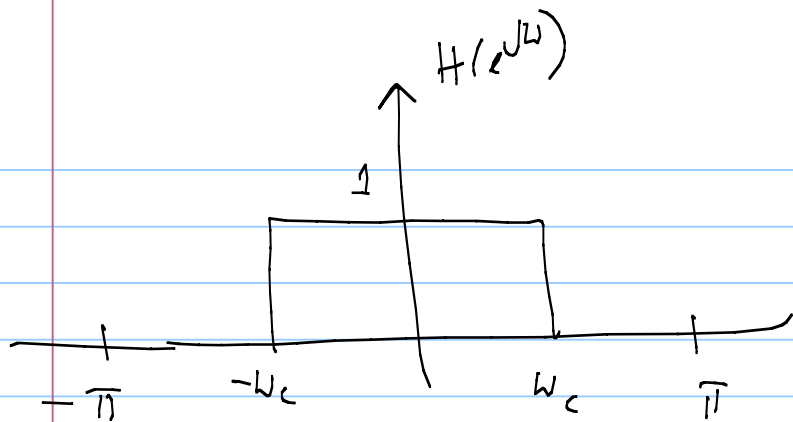
$$\underline{N=4}$$



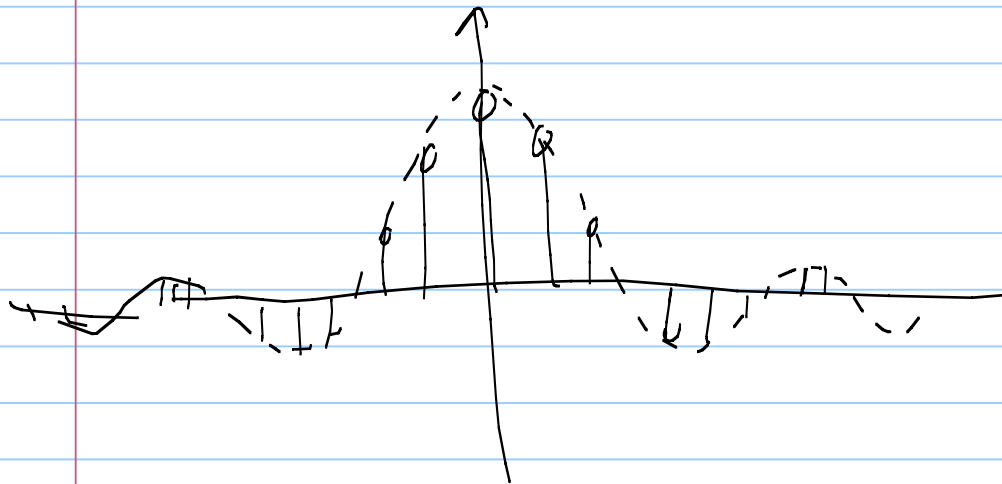
$$\phi(\omega) = -\frac{N-1}{2}\omega + \frac{\pi}{2}$$

$$\tau_g(\omega) = \frac{N-1}{2}$$

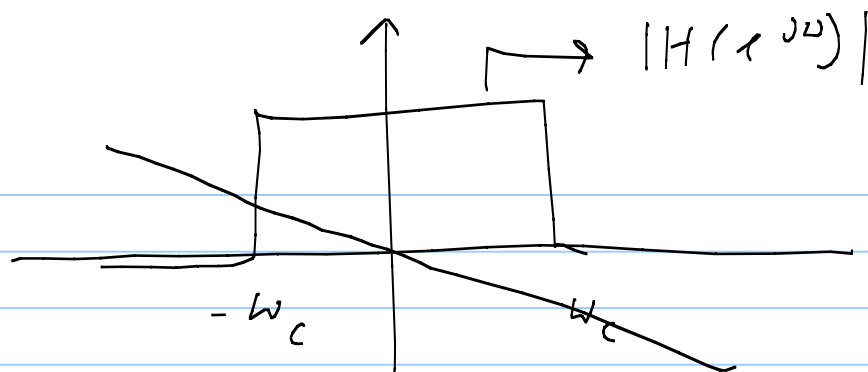




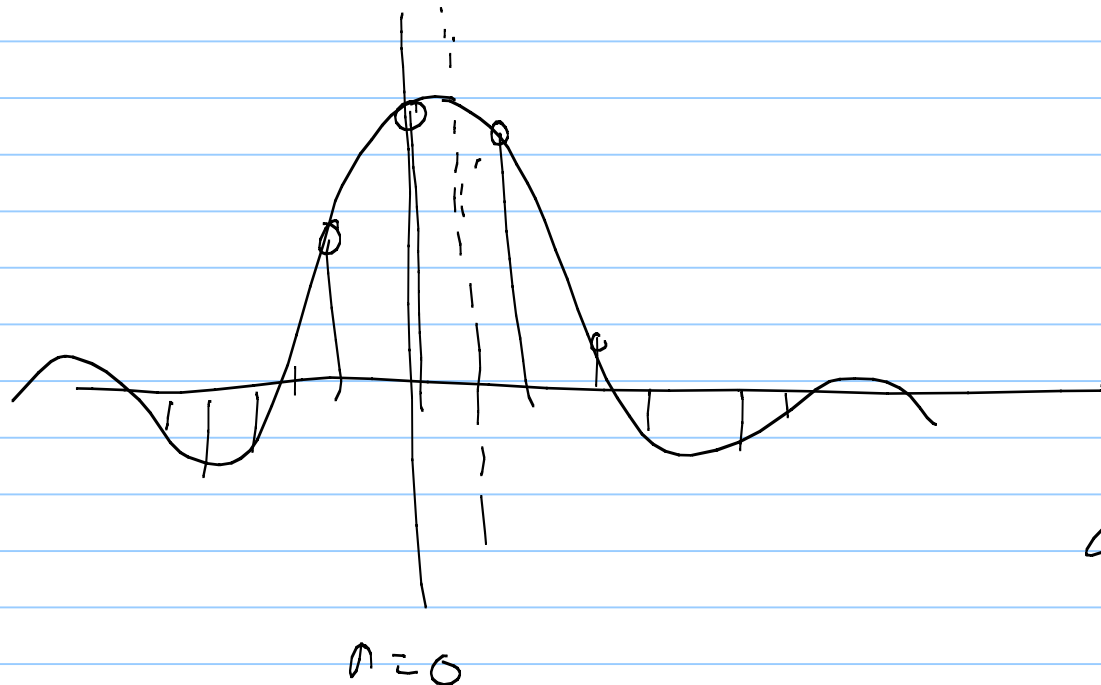
$$h(n) = \frac{\sin \omega_c n}{\pi n}$$



IR



$$H(e^{j\omega}) = \begin{cases} e^{-j\alpha\omega} & |\omega| < \omega_c \\ 0 & \omega_c < |\omega| < \pi \end{cases}$$

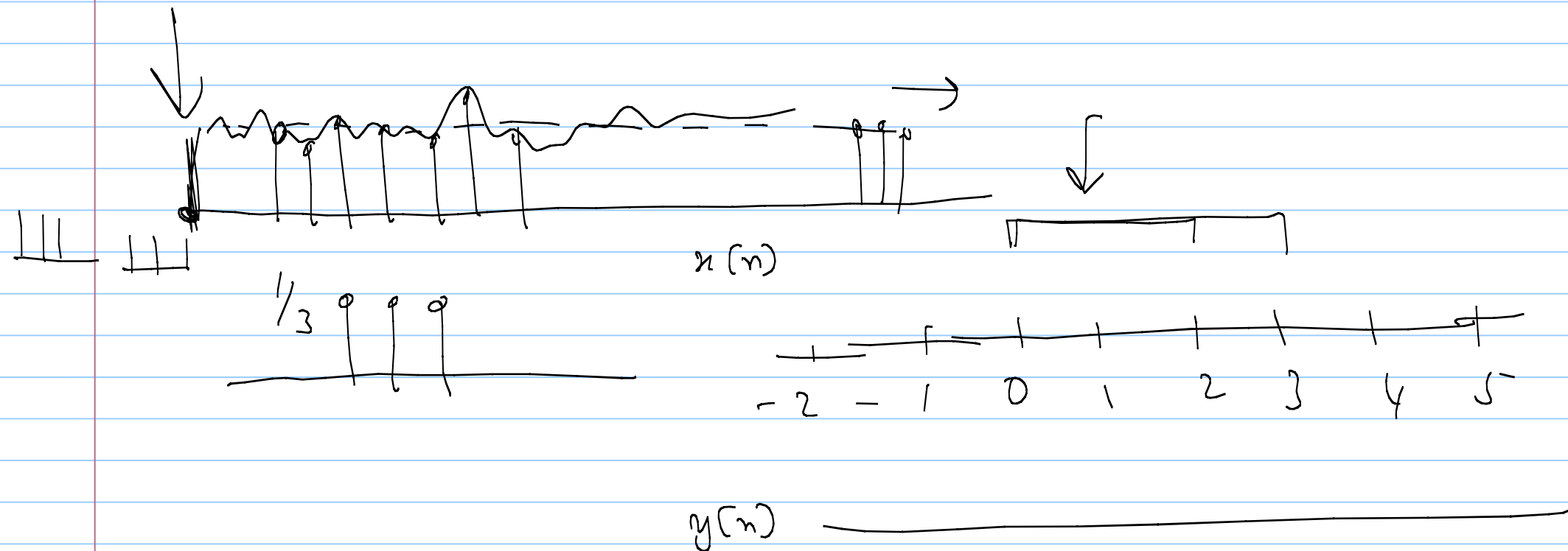
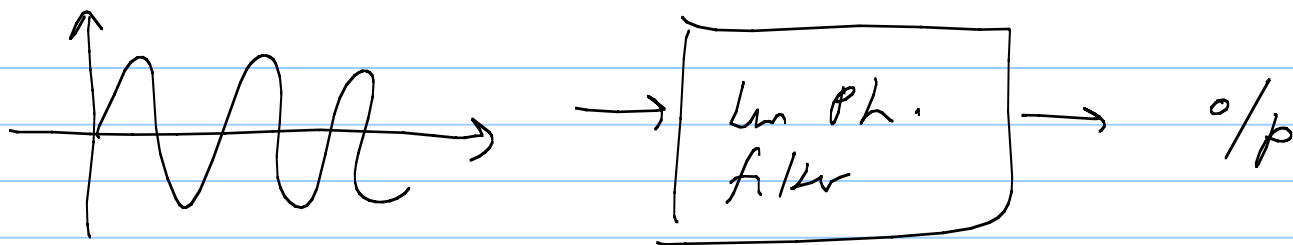


Symmetry is sufficient
but not necessary for
linear phase in the
case for IIR filters

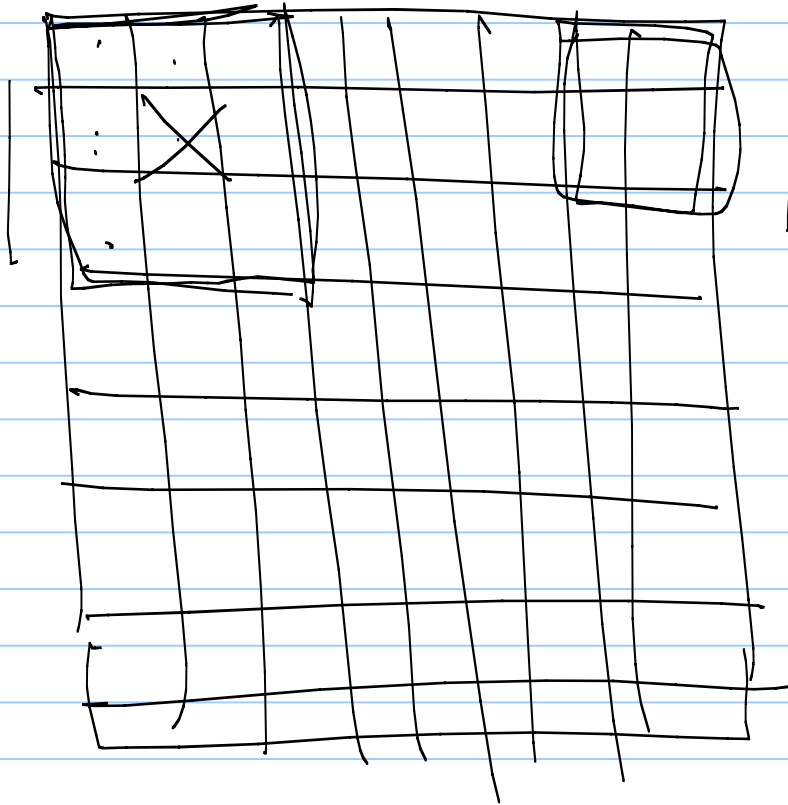
However, for FIR filters, symmetry is both necessary & sufficient for generalized linear phase

Length: N

Symmetry	Length	Name	$\tau_g(\omega)$
Even	Odd	Type I	$\frac{N-1}{2}$ integer
Even	Even	Type II	" integer + $\frac{1}{2}$
Odd	Odd	Type III	" integer
Odd	Even	Type IV	" integer + $\frac{1}{2}$



$\frac{1}{9}$



$\frac{1}{9}$	$\frac{1}{9}$	$\frac{1}{9}$
$\frac{1}{9}$	$\frac{1}{9}$	$\frac{1}{9}$
$\frac{1}{9}$	$\frac{1}{9}$	$\frac{1}{9}$

$$H(e^{j\omega}) = |H(e^{j\omega})| e^{j\theta(\omega)}$$

$\theta(\omega)$: linear phase

Consider $G(z) = \frac{1}{H(z)}$

$$G(e^{j\omega}) = \frac{1}{|H(e^{j\omega})|} e^{-j\theta(\omega)}$$

$$h[N-1-n] = h[n]$$

$$h[n] \leftrightarrow H(z)$$

$$h[n+N] \leftrightarrow z^N H(z)$$

$$h[N-n] \leftrightarrow \bar{z}^N H(\bar{z}^{-1})$$

$$h[N-1-n] \leftrightarrow z^{-(N-1)} H(\bar{z}^{-1})$$

$$h[n] = \pm h[N-1-n] \quad (\text{real-valued})$$

$$H(z) = \pm z^{-(N-1)} H(z^{-1})$$

For the general case

$$h[n] = \pm h^*[N-1-n]$$

$$H(z) = \pm z^{-(N-1)} H^*(z^{*-1})$$

If z_0 is a zero of $H(z)$,

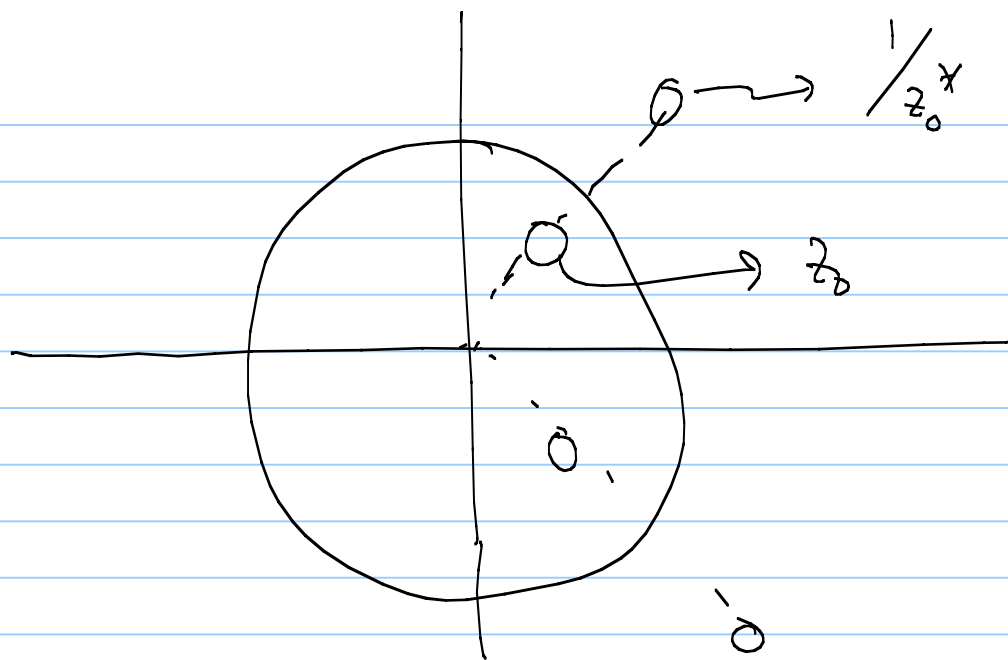
$$H(z_0) = 0$$

$$H(z_0) = \pm z_0^{-(N-1)} H^*(z_0^{*-1}) = 0$$

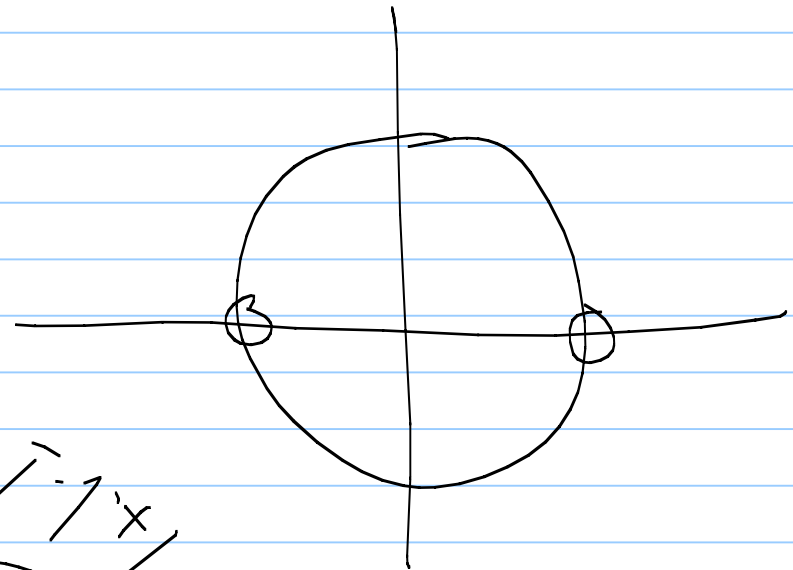
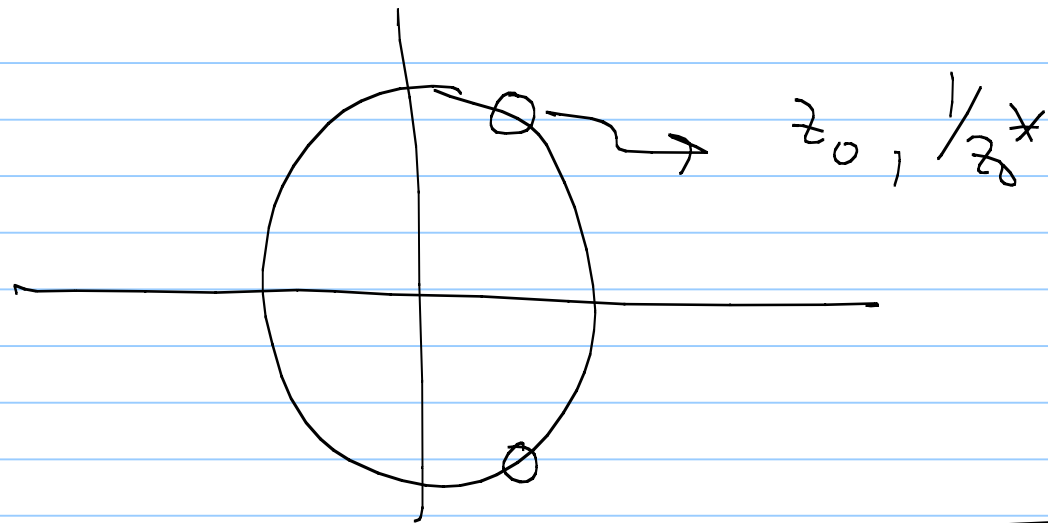
$$\Rightarrow H^*(z_0^{*-1}) = 0$$

$$\Rightarrow \frac{1}{z_0^*} \text{ is also a zero}$$

$$\text{If } z_0 = r e^{j\theta}, \text{ then } \frac{1}{z_0^*} = \frac{1}{r} e^{j\theta}$$

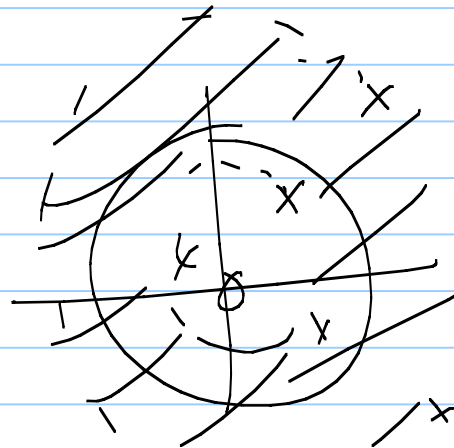
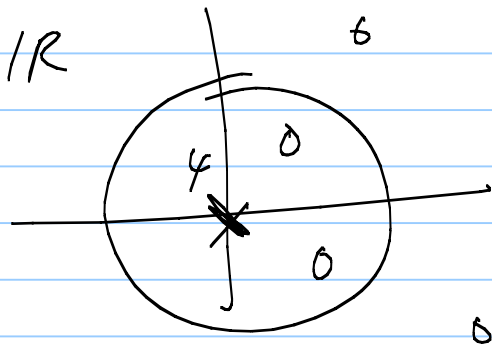


$$r e^{j\theta}, \quad r e^{-j\theta}, \quad \frac{1}{r} e^{j\theta}, \quad \frac{1}{r} e^{-j\theta}$$



Lin Phase

FIR



Lin. Phase IIR

— — —

4

For FIR filters, $h[N-1-n] = \pm h[n]$
gives rise to linear phase

For $\beta = \pi/2$, $h[N-1-n] = -h[n]$
i.e. sequence is real-valued & odd

$$h[n] \longleftrightarrow H(e^{j\omega})$$

$\hookrightarrow$ imaginary & odd

$$H(e^{j\omega}) = j G(e^{j\omega}).$$

Where $G(e^{j\omega})$ is real-valued

$$H(e^{j\omega}) = e^{j\pi/2} G(e^{j\omega})$$

Type I length odd, symmetry is even $M = N-1$

$$H(e^{j\omega}) = \sum_{n=0}^{\boxed{N-1} \rightarrow M} h[n] e^{-j\omega n}$$

$$\begin{aligned} &= h[0] + h[M] e^{-j\omega M} \\ &+ h[1] e^{-j\omega} + h[M-1] e^{-j\omega(M-1)} \\ &\vdots \end{aligned}$$

$$\begin{aligned}
 & + h\left[\frac{M}{2}-1\right] e^{-j\omega\left(\frac{M}{2}-1\right)} + h\left[\frac{M}{2}+1\right] e^{-j\omega\left(\frac{M}{2}+1\right)} \\
 & + h\left[\frac{M}{2}\right] e^{-j\omega\frac{M}{2}} e^{-j\omega\frac{M}{2}} \cdot e^{j\omega}
 \end{aligned}$$

$$h[0] = h[M] \quad h[1] = h[M-1], \text{ etc.}$$

$$\begin{aligned}
 H(e^{j\omega}) &= e^{-j\omega\frac{M}{2}} h[0] \left[e^{+j\omega\frac{M}{2}} + e^{-j\omega\frac{M}{2}} \right] \\
 &+ \vdots \\
 &+ e^{-j\omega\frac{M}{2}} h\left[\frac{M}{2}-1\right] \left[e^{j\omega} + e^{-j\omega} \right]
 \end{aligned}$$

$$+ e^{-j\omega \frac{M}{2}} h\left[\frac{M}{2}\right]$$

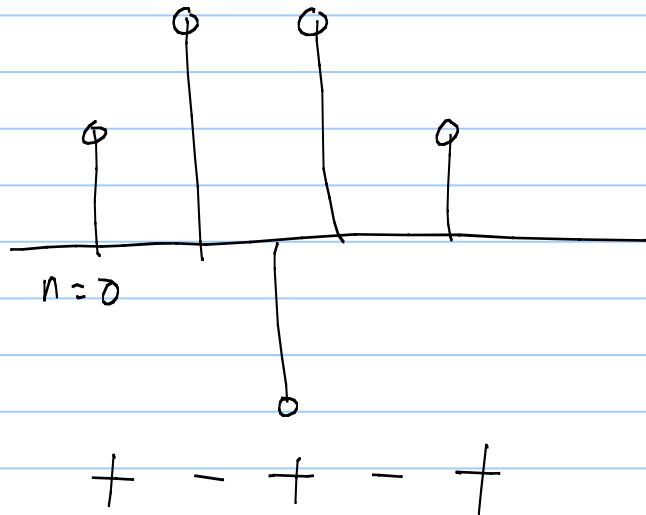
$$= e^{-j\omega \frac{M}{2}} \left[\sum_{n=0}^{\frac{M}{2}-1} h[n] 2 \cos\left(\omega\left(\frac{M}{2}-n\right)\right) + h\left[\frac{M}{2}\right] \right]$$

$$= e^{-j\omega \frac{M}{2}} \underbrace{A(\omega)}$$

Real-valued Continuous function

Constrained Zeros

Type 1 $N=5$



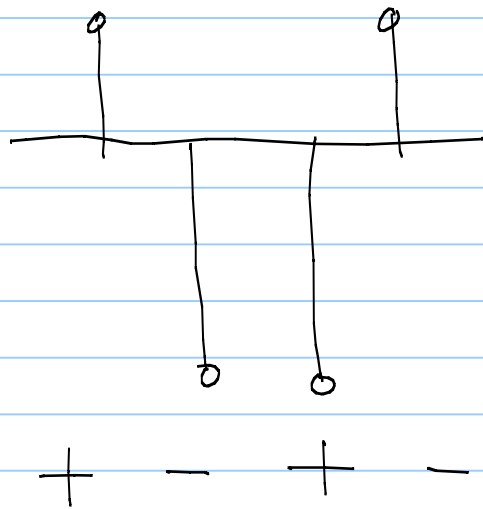
$$H(z) \Big|_{z=1} = \sum_{n=0}^{N-1} h[n] 1^{-n}$$

does not always
add up to zero

$$H(z) \Big|_{z=-1} = \sum_{n=0}^{N-1} h[n] (-1)^{-n}$$

does not always add up to zero

Type II



$$\sum_{n=0}^{N-1} h(n) = 0 ?$$

$H(1) = 0$ not always

$$H(-1) = 0 \text{ always}$$

Type II

$$\sum_{n=0}^{N-1} h(n) = 0 \text{ since it is odd symmetric}$$

$$\sum_{n=0}^{N-1} h(n) (-1)^n = 0$$

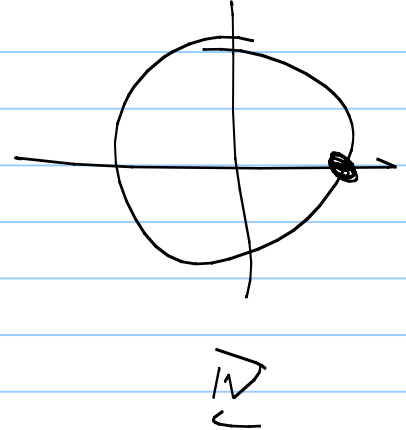
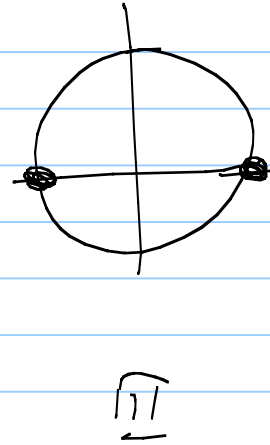
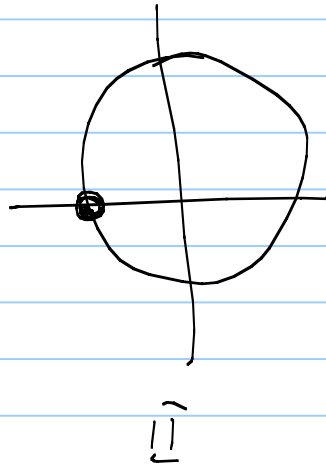
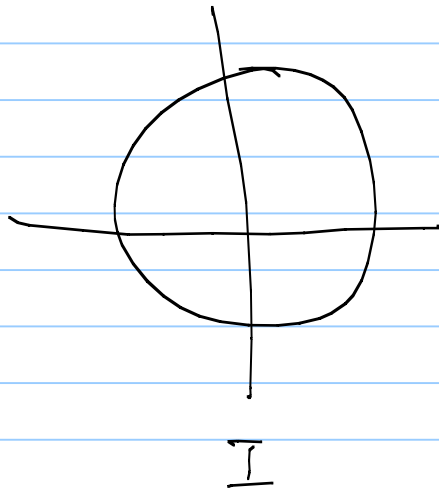
Type II

$$\sum_{n=0}^{N-1} h[n] = 0$$

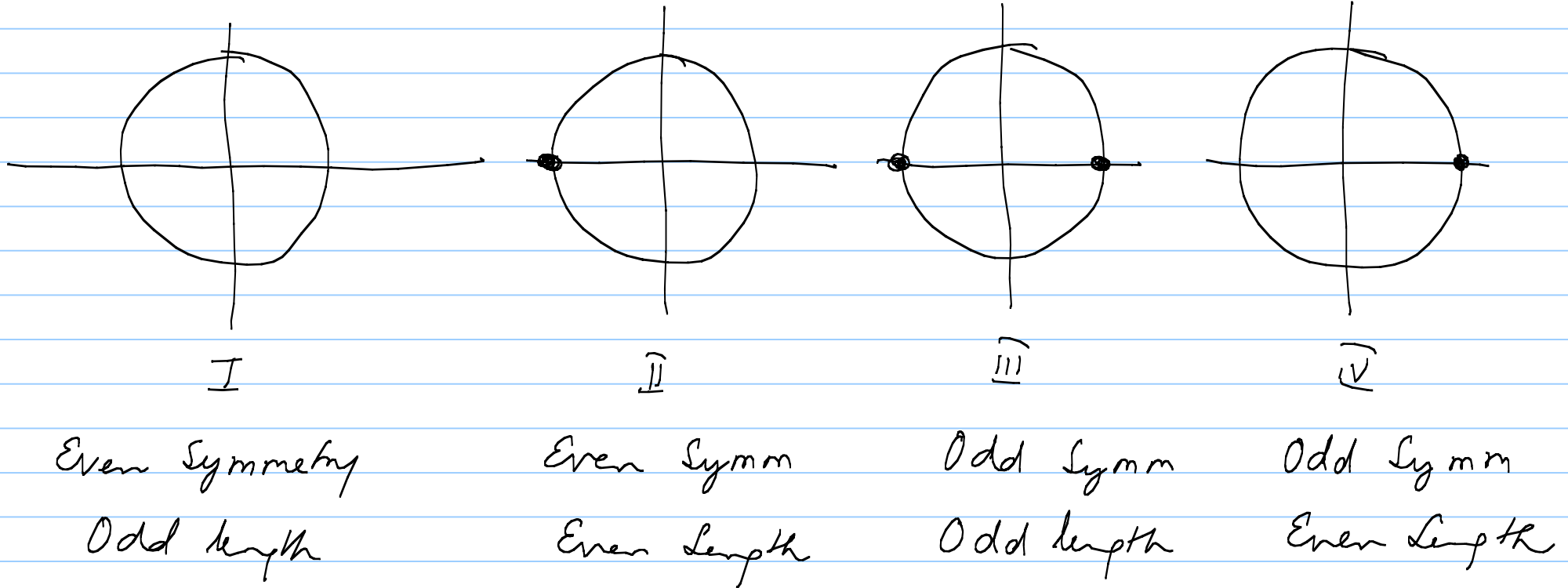
since it is odd symm

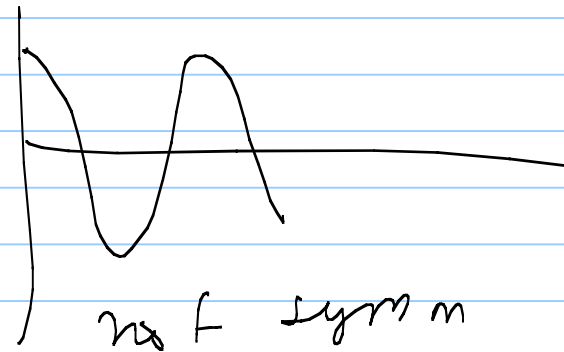
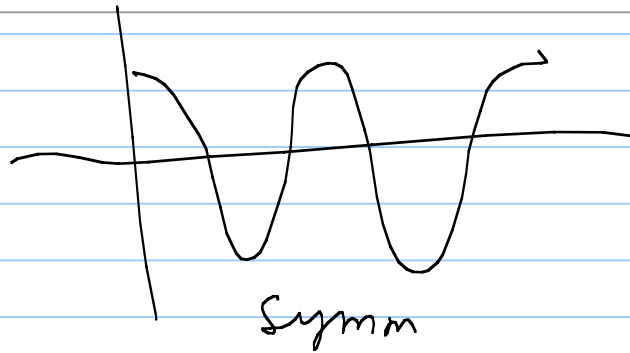
$$\sum_{n=0}^{N-1} h[n] (-1)^n$$

not always zero

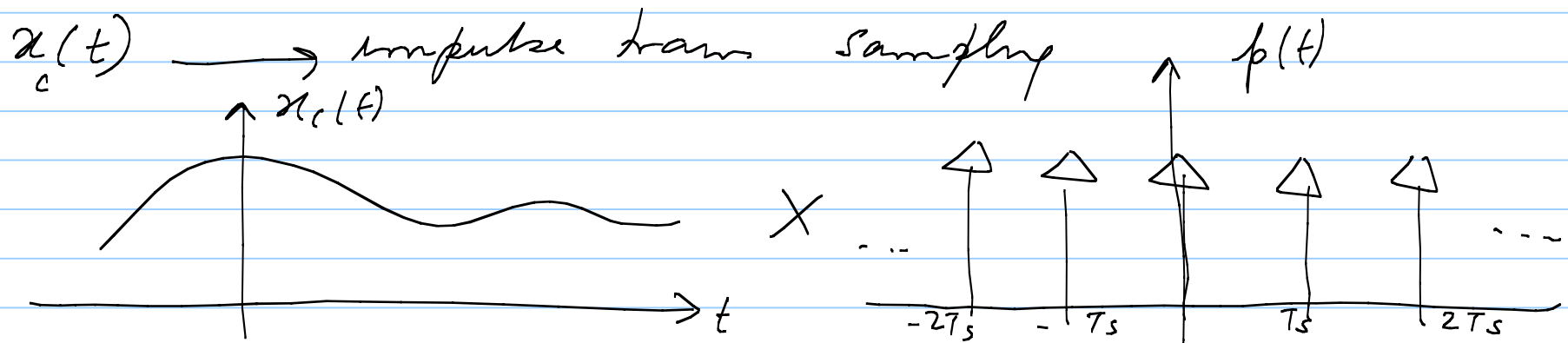


Constrained Zeros:





Sampling:

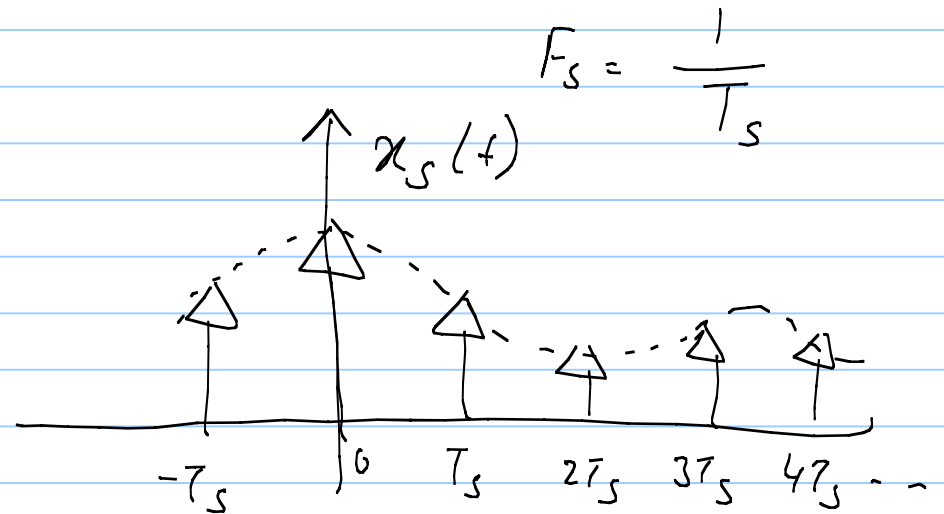


$$p(t) = \sum_{k=-\infty}^{\infty} \delta(t - kT_s) \longleftrightarrow \frac{1}{T} \sum_{k=-\infty}^{\infty} \delta(F - kF_s)$$

$$x_c(t) \cdot p(t) = x_s(t)$$

$$x_s(t) = \sum_{n=-\infty}^{\infty} x_c(t) \delta(t - nT_s)$$

$$= \sum_{n=-\infty}^{\infty} x_c(nT_s) \delta(t - nT_s)$$



$$X_s(F) = \int_{-\infty}^{\infty} x_s(t) e^{-j 2\pi F t} dt$$

$$= \int_{-\infty}^{\infty} \left[\sum_{n=-\infty}^{\infty} x_c(nT_s) \delta(t - nT_s) \right] e^{-j 2\pi F t} dt$$

$$\stackrel{?}{=} \sum_{n=-\infty}^{\infty} x_c(nT_s) \int_{-\infty}^{\infty} \delta(t - nT_s) e^{-j 2\pi F t} dt$$

$$= \sum_{n=-\infty}^{\infty} x_c(nT_s) e^{-j 2\pi F nT_s}$$

$$= \sum_{n=-\infty}^{\infty} a_c(nT_s) e^{-j 2\pi \frac{F}{F_s} n}$$

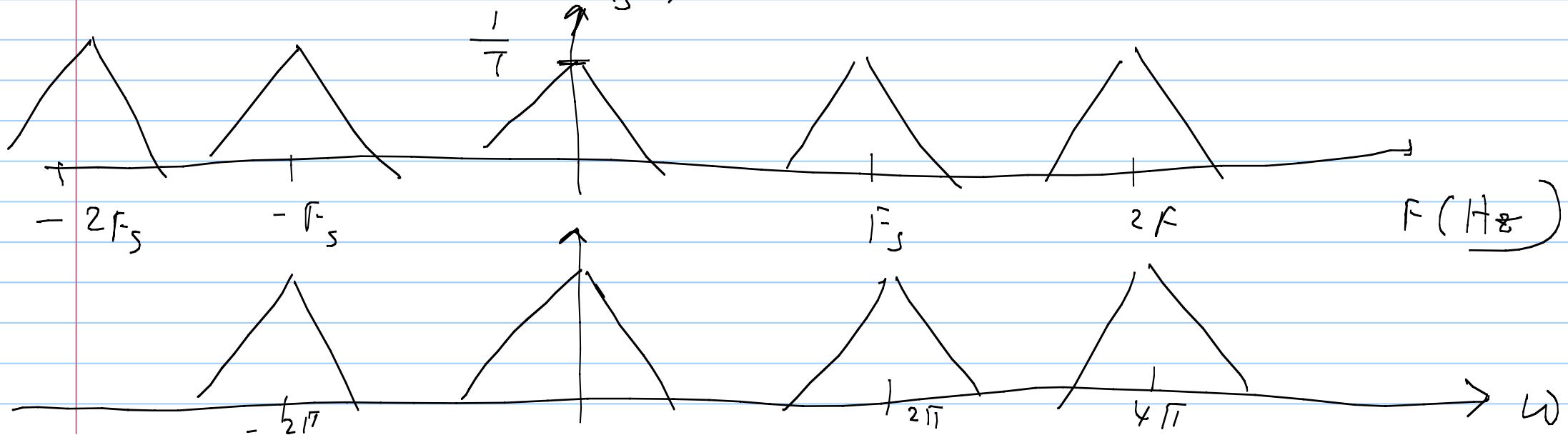
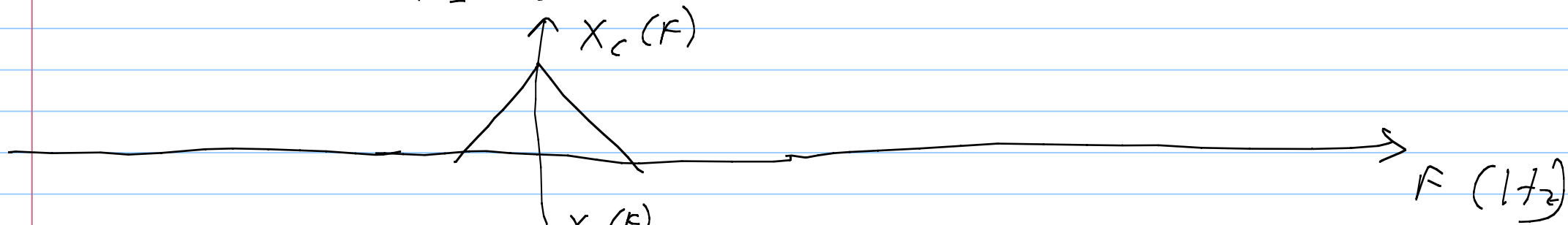
$$P(F) = \frac{1}{T} \sum_{k=-\infty}^{\infty} \delta(F - kF_s)$$

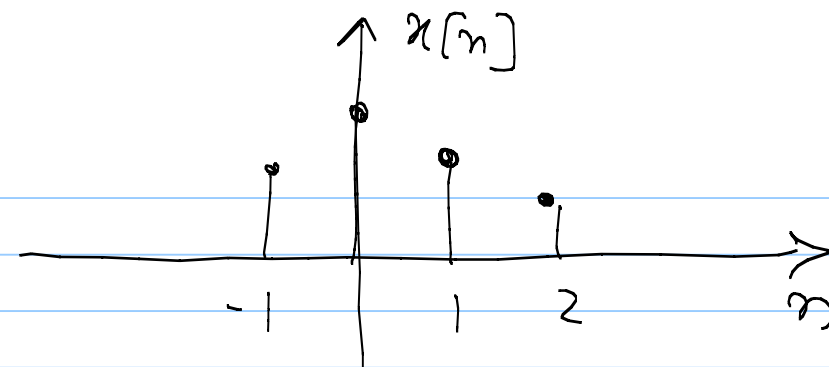
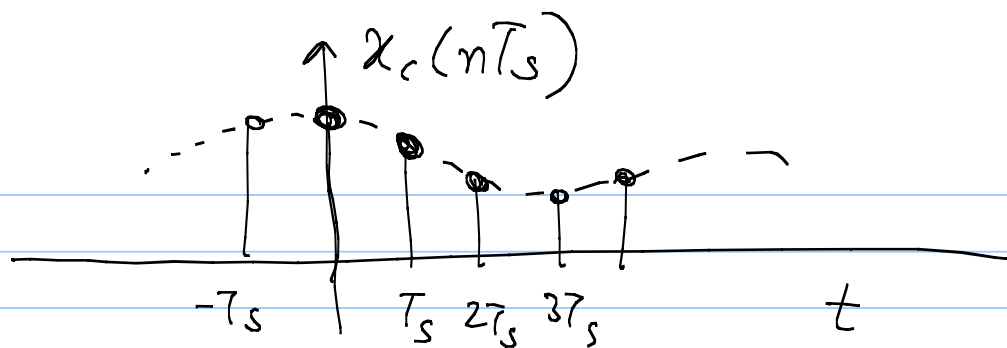
$$X_s(F) = X_c(F) * P(F)$$

$$= \frac{1}{T} \sum_{k=-\infty}^{\infty} \delta(F - kF_s) * X_c(F)$$

$$= \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(F - kF_s)$$

$$X_s(f) = \sum_{n=-\infty}^{\infty} x_c(nT_s) e^{-j 2\pi \frac{f}{f_s} n}$$





$$x[n] = x_c(nT_s)$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$

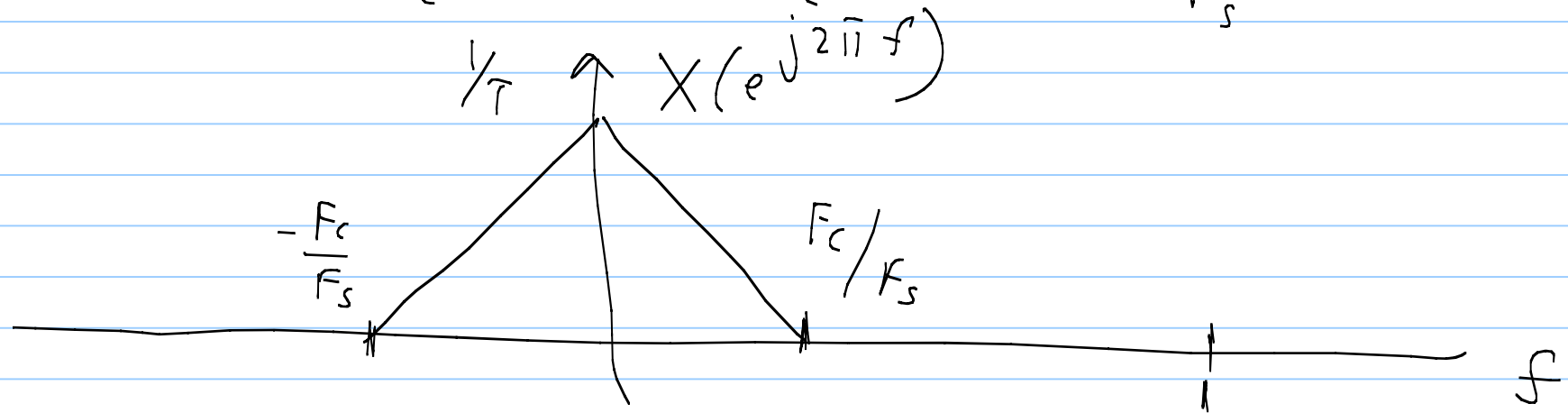
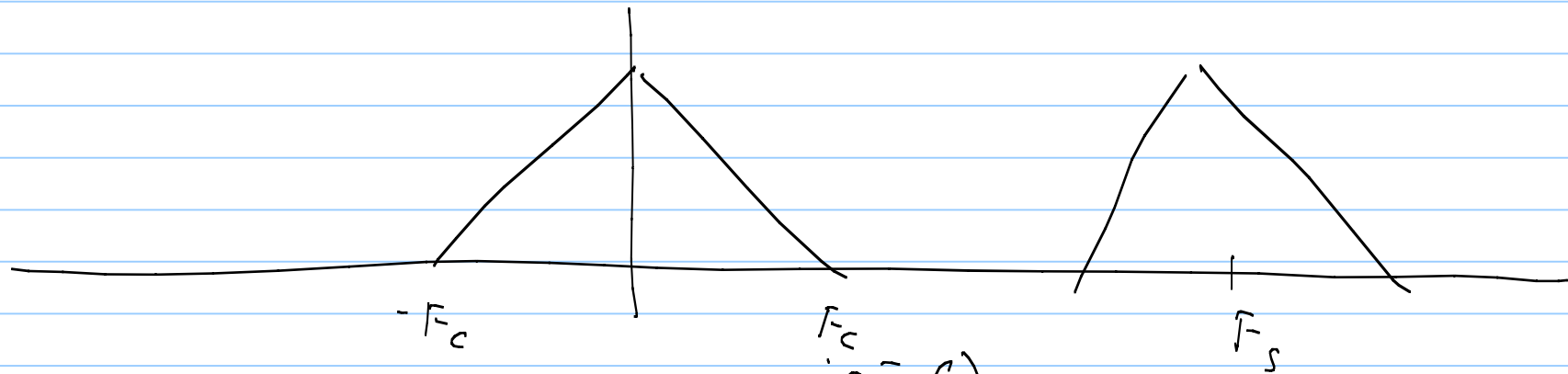
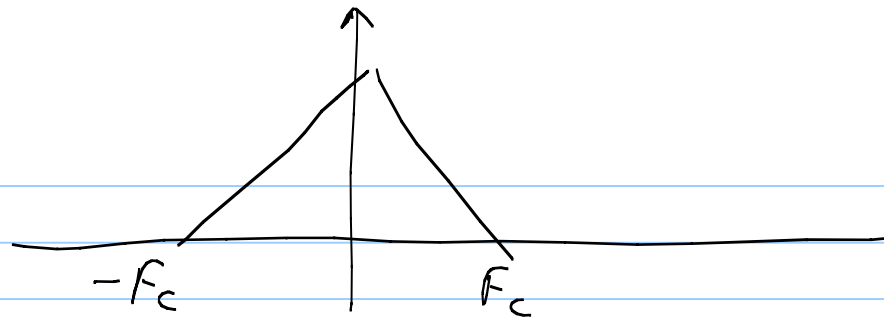
$$X_s(F) = \sum_{n=-\infty}^{\infty} \underbrace{x_c(nT_s)}_{x[n]} e^{-j 2\pi \frac{F}{F_s} n}$$

$$\frac{F}{F_s} = f$$

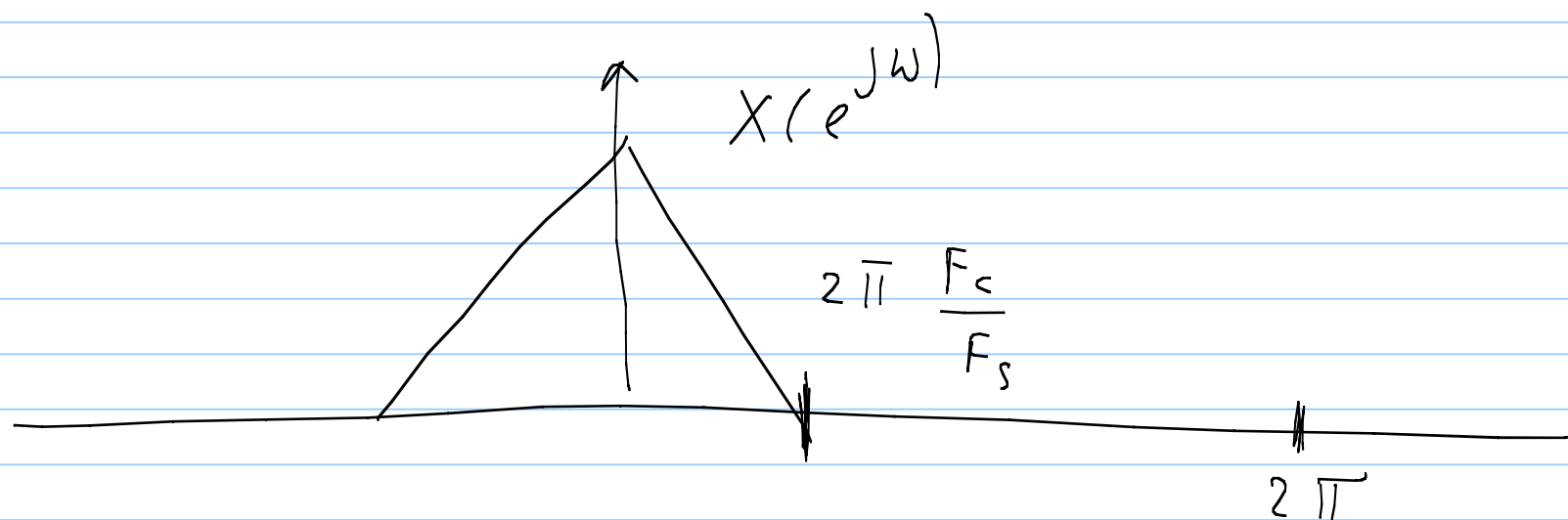
$$\omega = 2\pi f$$

$$F \rightarrow \frac{\omega}{2\pi T_s}$$

$$2\pi \frac{F}{F_s} n \rightarrow 2\pi \frac{\omega}{2\pi T_s} \frac{1}{F_s} n = \omega n$$



$$X(e^{j2\pi f}) \quad \text{or} \quad X(e^{j\omega})$$



$$x_c(t) \xleftrightarrow{\text{CTFT}} X_c(F)$$

$$x_s(t) \xleftrightarrow{\text{CTFT}} X_s(F) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(F - kF_s)$$

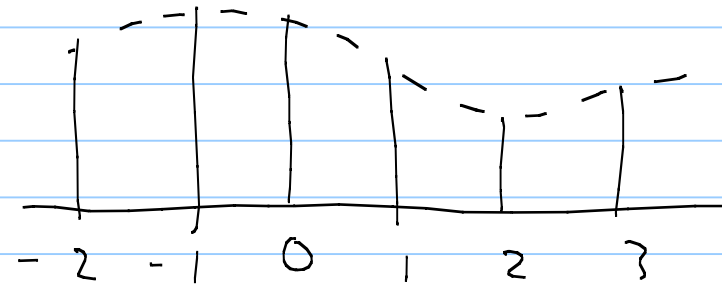
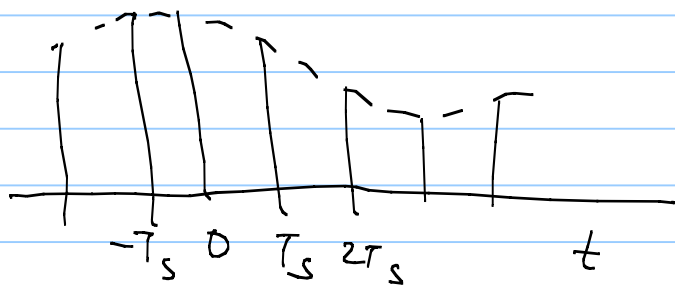
$$X_s(F) = \sum_{n=-\infty}^{\infty} x_c(nT_s) e^{-j2\pi \frac{F}{F_s} n}$$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$

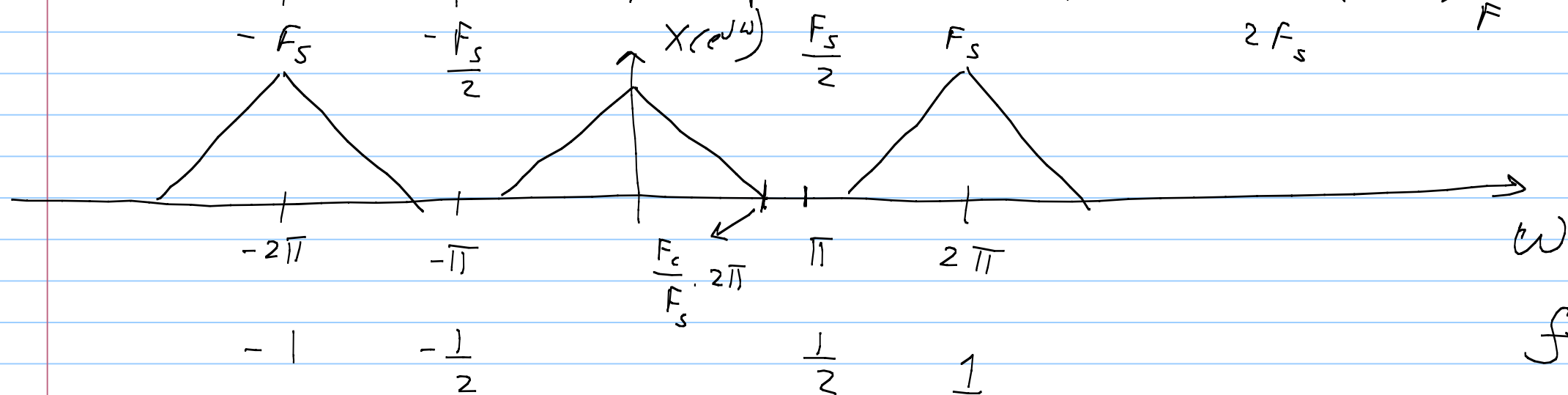
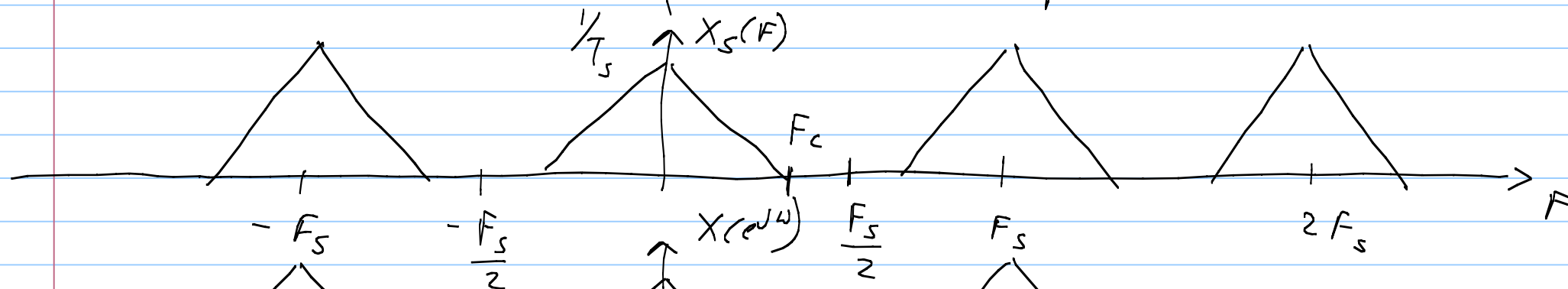
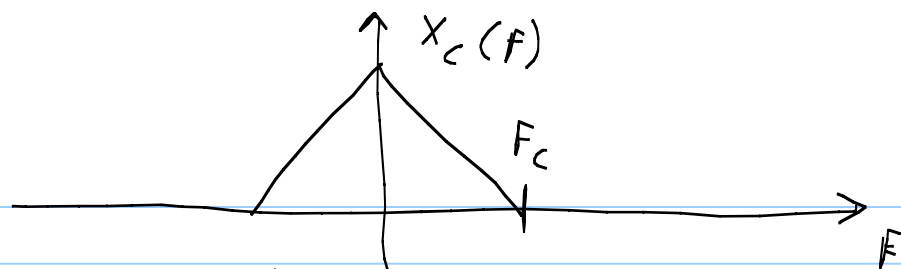
$$x[n] \equiv x_c(nT_s)$$

$$X_s(F) \Big|_{F \rightarrow \frac{\omega}{2\pi T_s}} = X(e^{j\omega})$$

$$\frac{\omega}{2\pi T_s} = \frac{\omega}{2\pi} F_s = f F_s$$

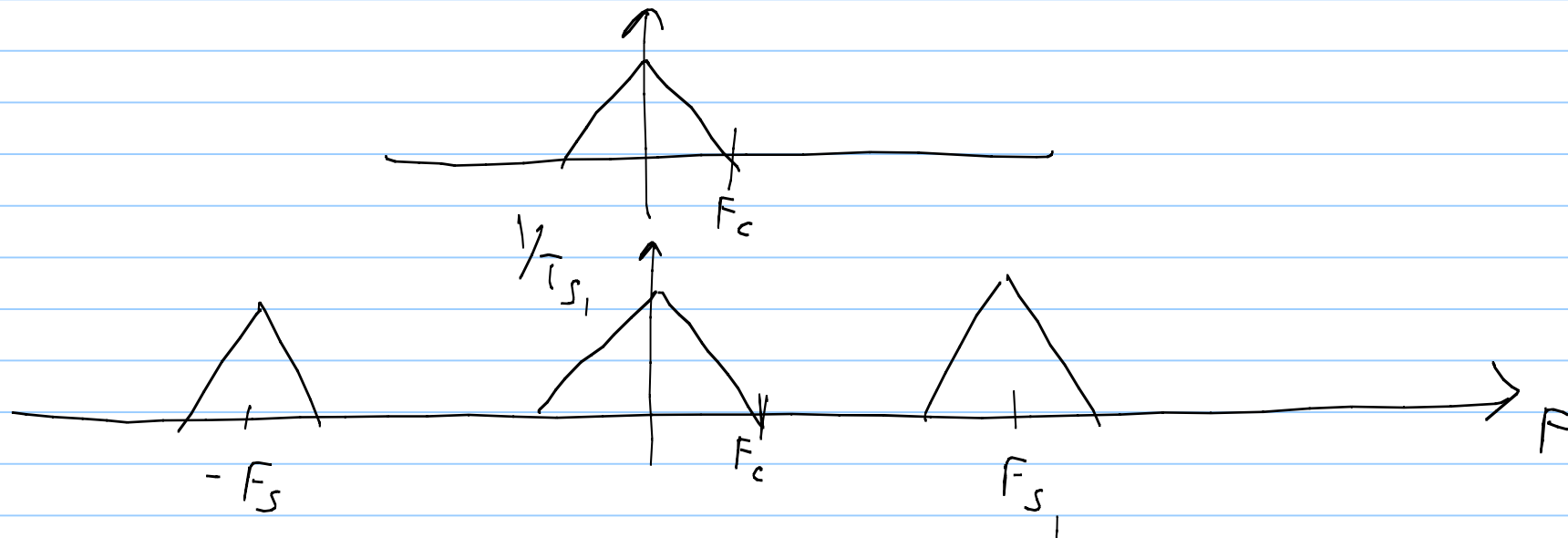


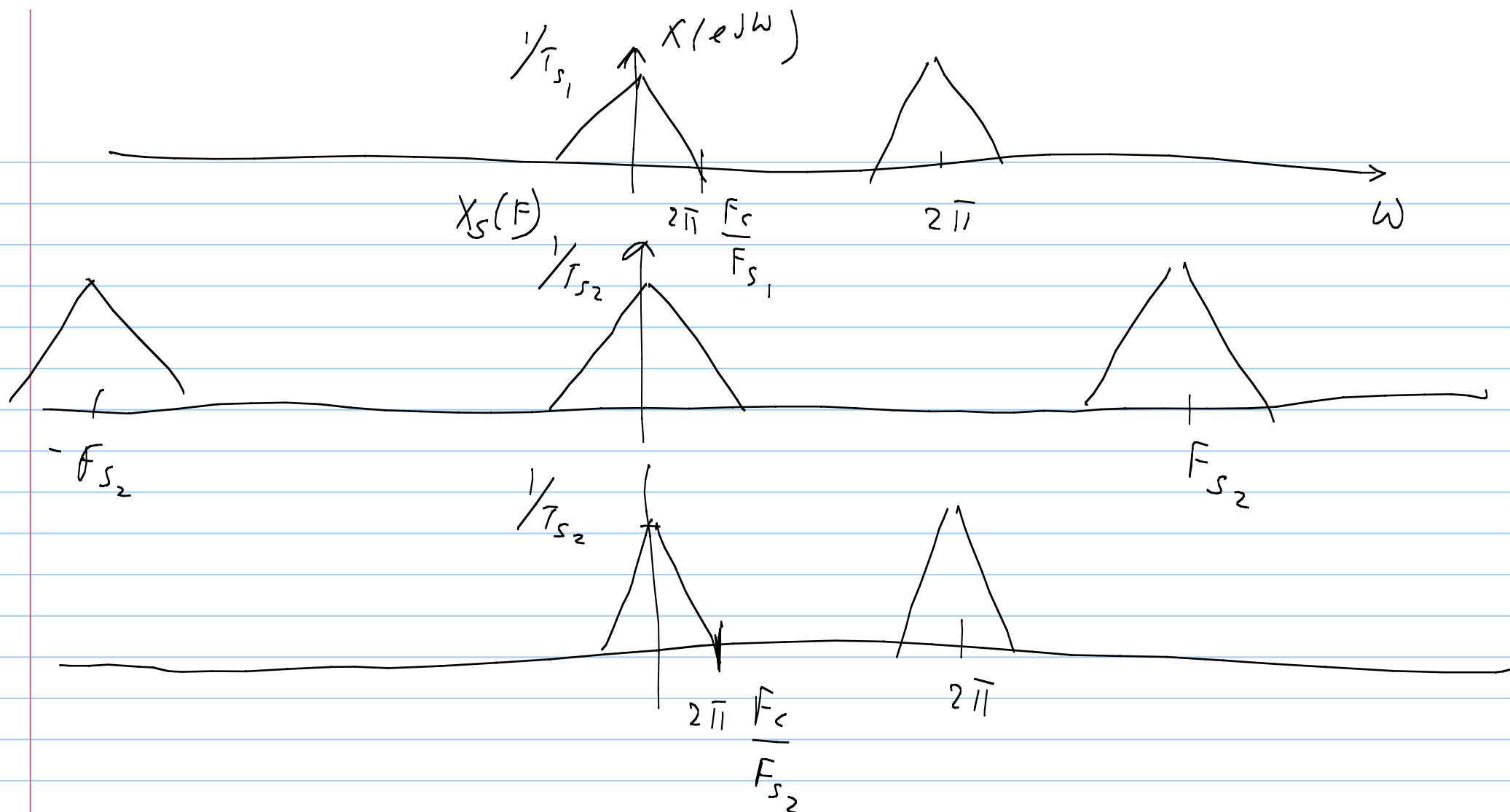
$$y(t) = x_c(t \cdot T_s) \iff \frac{1}{T_s} X_c(F/T_s) = \frac{1}{T_s} X_c(F \cdot F_s)$$



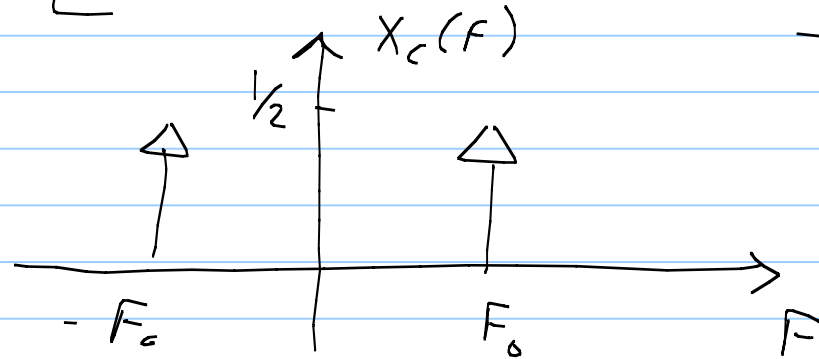
$$X_s(F) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X_c(F - kF_s)$$

$$X(e^{j\omega}) = \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X_c\left(\frac{\omega}{2\pi T_s} - kF_s\right)$$





$$\cos 2\pi F_0 t \longleftrightarrow \frac{1}{2} \left[\delta(F - F_0) + \delta(F + F_0) \right]$$



$$\begin{aligned} x[n] = x_c(nT_s) &= \cos 2\pi F_0 nT_s \\ &= \cos 2\pi \frac{F_0}{F_s} n \\ &= \cos 2\pi f_0 n \end{aligned}$$

$$= \cos \omega_0 n$$

$$\cos \omega_0 n \longleftrightarrow \frac{1}{2\pi} \left[\delta(\omega - \omega_0) + \delta(\omega + \omega_0) \right] \quad -\pi \leq \omega < \pi$$

$$X_S(F) \longleftrightarrow \frac{1}{2T_s} \left[\delta(F - F_0) + \delta(F + F_0) \right] \quad -\frac{F_s}{2} \leq F < \frac{F_s}{2}$$

$$X_S(F) \Big|_{F \rightarrow \frac{\omega}{2\pi T_s}} = X(e^{j\omega})$$

$$\frac{1}{2T_s} \delta(F - F_0) \rightarrow \frac{1}{2T_s} \delta\left(\frac{\omega}{2\pi T_s} - F_0\right)$$

$$\delta(at+b) = \frac{1}{|a|} \delta\left(t + b/a\right)$$

$$\frac{1}{2T_s} \delta\left(\frac{\omega}{2\pi T_s} - F_0\right) = \frac{1}{2T_s} 2\pi T_s \delta(\omega - 2\pi T_s F_0)$$

$$= \pi \delta\left(\omega - 2\pi \frac{F_0}{f_s}\right)$$

$$= \pi \delta(\omega - 2\pi f_0)$$

$$= \pi \delta(\omega - \omega_0)$$

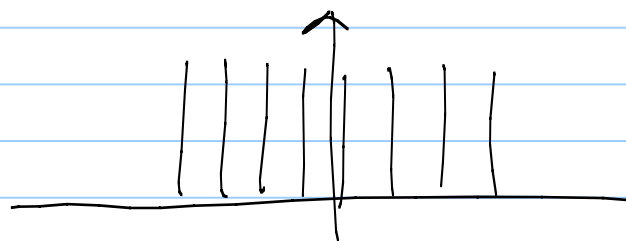
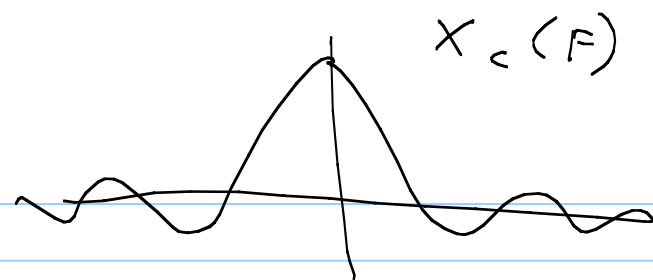
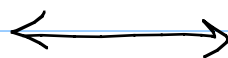
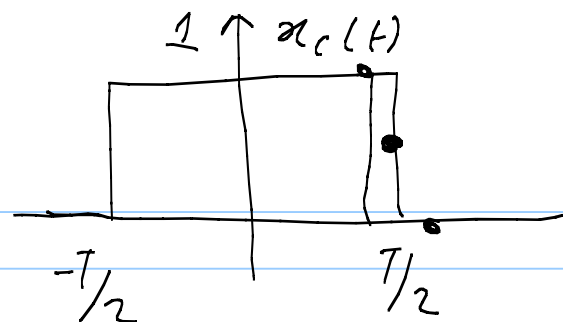
$$\cos 2\pi F_0 t$$

$$(i) \quad F_0 = 8 \text{ kHz} \quad F_s = 24 \text{ kHz}$$

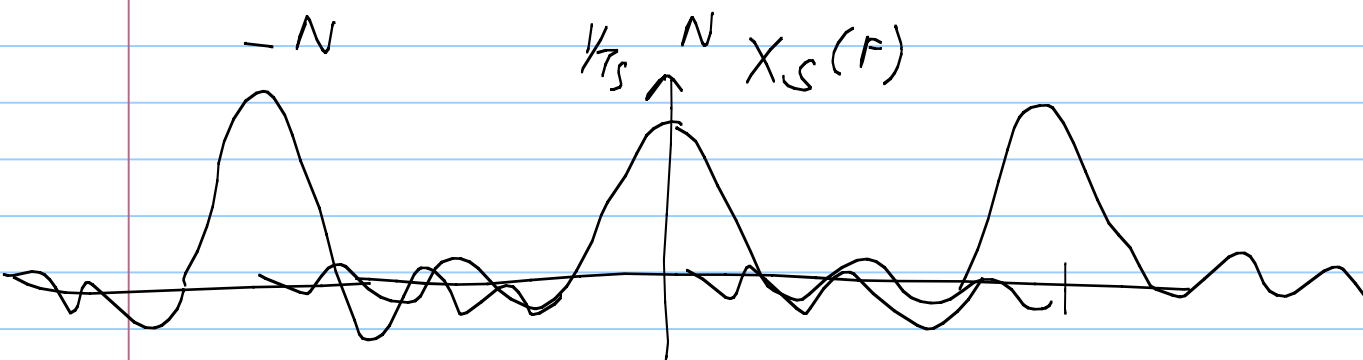
$$x[n] = x_c(nT_s) = \cos 2\pi \frac{8 \times 10^3}{24 \times 10^3} n = \cos \frac{2\pi n}{3}$$

$$(ii) \quad F_0 = 16 \text{ kHz} \quad F_s = 48 \text{ kHz}$$

$$x[n] = x_c(nT_s) = \cos 2\pi \frac{16 \times 10^3}{48 \times 10^3} n = \cos \frac{2\pi n}{3}$$



$$\frac{\sin((2N+1)\omega/2)}{\sin \omega/2}$$



EC 5142 Nov. 17 2011

Note Title

17-11-2011

FFT Algorithm

$$\underline{X} = \underline{W} \underline{x}$$

$$\begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & W_N & W_N^2 & \dots & W_N^{N-1} \\ 1 & W_N^2 & W_N^4 & \dots & W_N^{2(N-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & W_N^{(N-1)(N-1)} & \dots & \dots & 1 \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ \vdots \\ x_{N-1} \end{bmatrix} = \begin{bmatrix} X_0 \\ X_1 \\ \vdots \\ X_{N-1} \end{bmatrix}$$

$N \times N$

$N \times 1$

$N \times 1$

$$W_N = e^{-j \frac{2\pi}{N}}$$

$$\begin{array}{c} \uparrow \\ e^{-j \frac{2\pi k n}{N}} \end{array} \longrightarrow n = 0, 1, \dots, N-1$$

$$| \quad k = 0, 1, \dots, N-1$$

Requires roughly N^2 mult. & N^2 add

Decimation in Time Algorithm

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j \frac{2\pi k n}{N}} \quad k = 0, 1, \dots, N-1$$

$$= \sum_{n=0}^{N-1} x[n] W_N^{kn}$$

Split the i/p seq into odd & even indices

$$= \sum_{l=0}^{\frac{N}{2}-1} x[2l] e^{-j \frac{2\pi}{N} (2l)k} + \sum_{r=0}^{\frac{N}{2}-1} x[2r+1] e^{-j \frac{2\pi}{N} (2r+1)k}$$

$$= \sum_{l=0}^{\frac{N}{2}-1} g[l] e^{-j \frac{2\pi}{N/2} l k} + \underbrace{e^{-j \frac{2\pi}{N} k}}_{r=0} \sum_{r=0}^{\frac{N}{2}-1} h[r] e^{-j \frac{2\pi}{N/2} k r}$$

$$= \sum_{l=0}^{\frac{N}{2}-1} g[l] W_{\frac{N}{2}}^{lk} + \underbrace{e^{-j \frac{2\pi}{N} k}}_{r=0} \sum_{r=0}^{\frac{N}{2}-1} h[r] W_{\frac{N}{2}}^{kr}$$

$$k = 0, 1, \dots, N-1$$

$$N^2 \xrightarrow{G[k]} N + 2 \left(\frac{N}{2}\right)^2 \quad W_N^k \quad H[k]$$

$$N = 8 \quad N^2 = 64$$

$$8 + 2 \cdot 16 = 40$$

$$\left(\frac{N}{2}\right)^2 \xrightarrow{\quad} \frac{N}{2} + 2 \left(\frac{N}{4}\right)^2$$

$$N^2 \rightarrow N + 2 \left[\frac{N}{2} + 2 \left(\frac{N}{4}\right)^2 \right]$$

$$= N + N + 4 \left(\frac{N}{4}\right)^2$$

$$N = 2^L \Rightarrow L = \log_2 N$$

We have L stages

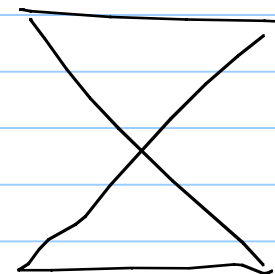
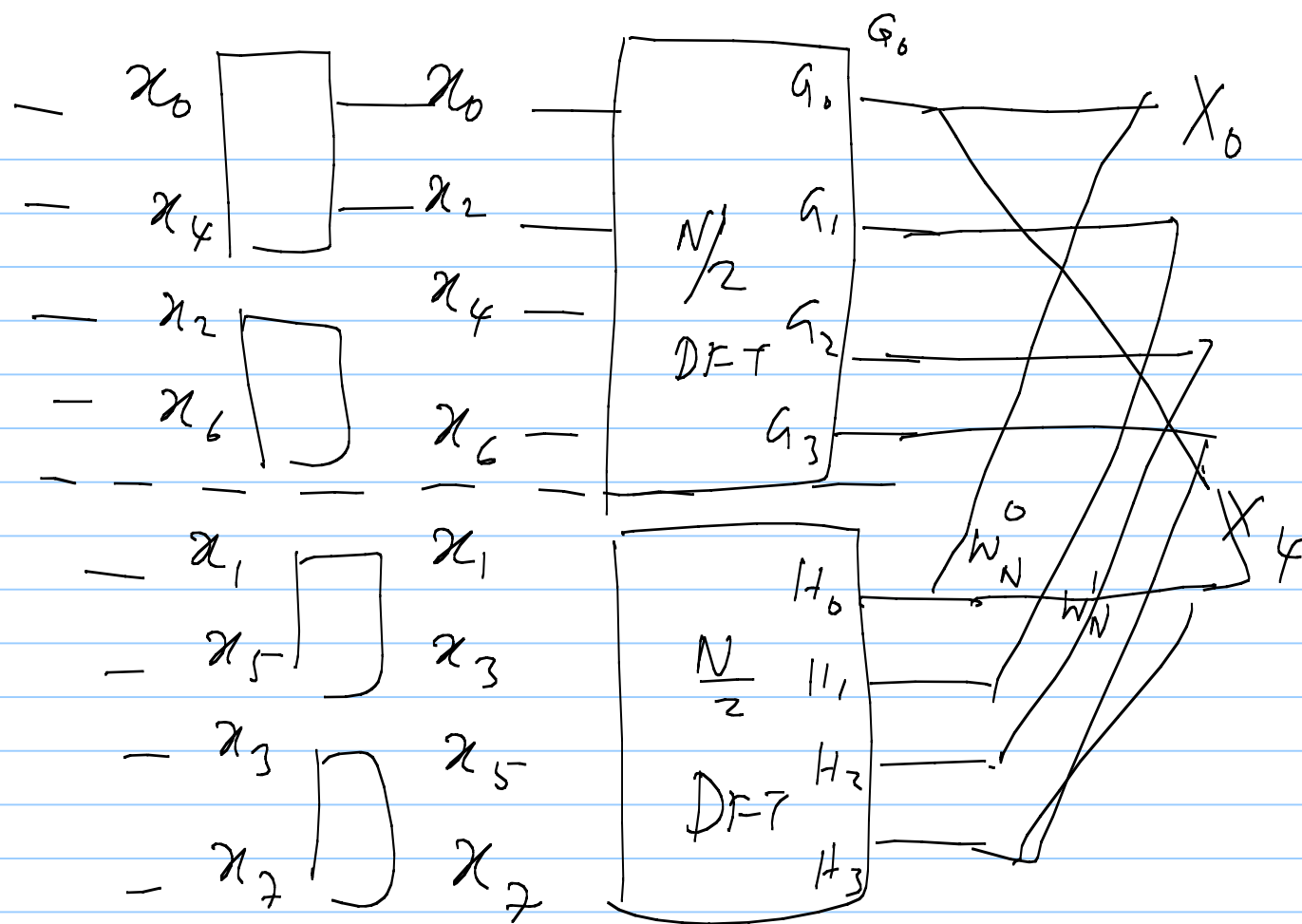
$$N^2 \rightarrow NL = N \log_2 N$$

$$\underline{N=8}$$

2 pt.
DFT

$$x_0 + x_1$$

$$x_0 - x_1$$



x_0	000	→	000	0
x_4	001		100	4
x_2	010		010	2
x_6	011		110	6
x_1	100		001	1
x_5	101		101	5
x_3	110		011	3
x_7	111		111	7