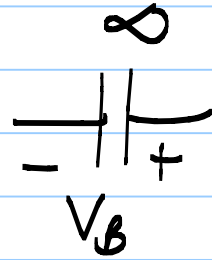
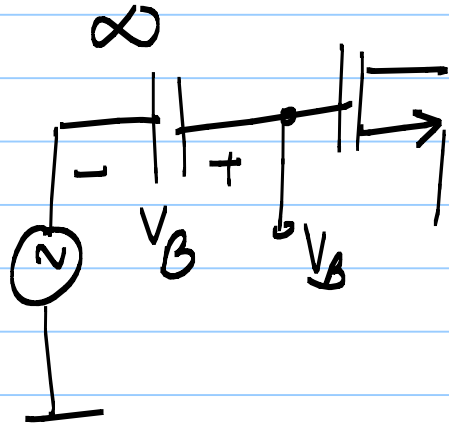
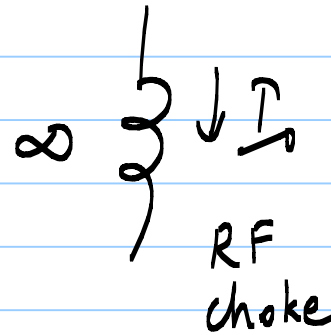
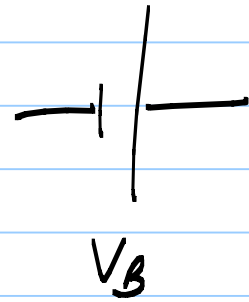


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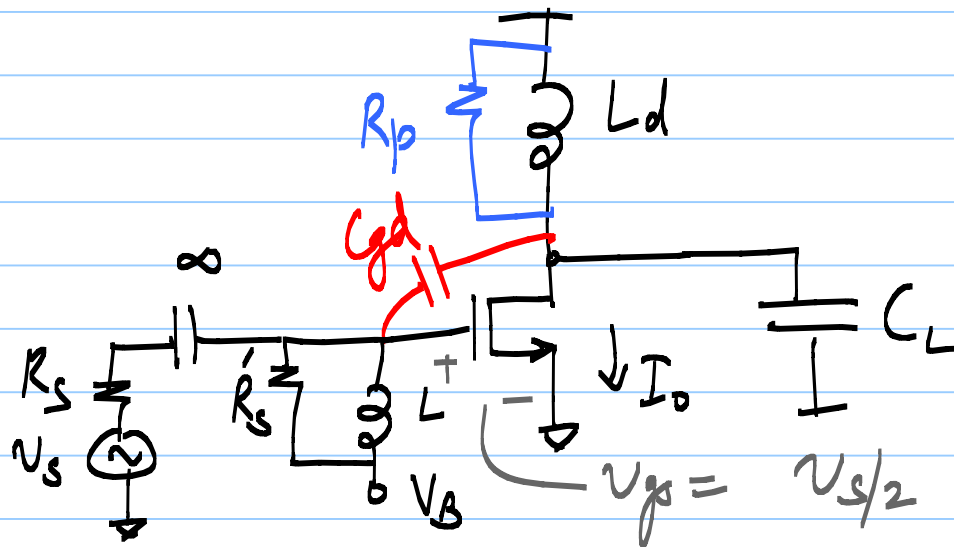
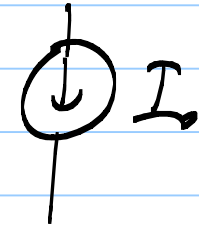
Lec 10



≡



≡



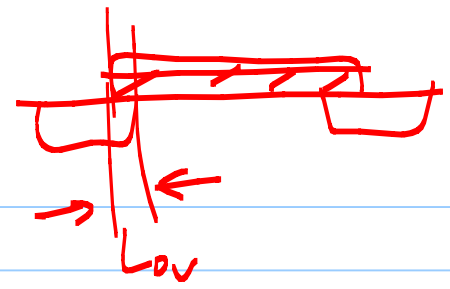
$$C_{gs} = W \cdot L \cdot C_{ox}$$

$$g_m = \mu_n C_{ox} \left(\frac{W}{L}\right) (V_{gs} - V_T)$$

$$L = k L_{min} \Rightarrow C_{gs} \propto k^2$$

$$k > 1$$

$$\text{gain} = \frac{g_m (r_{ds} \parallel R_p)}{2}$$



$C_{gd} \rightarrow$ feedback path that can cause instability

Solutions:

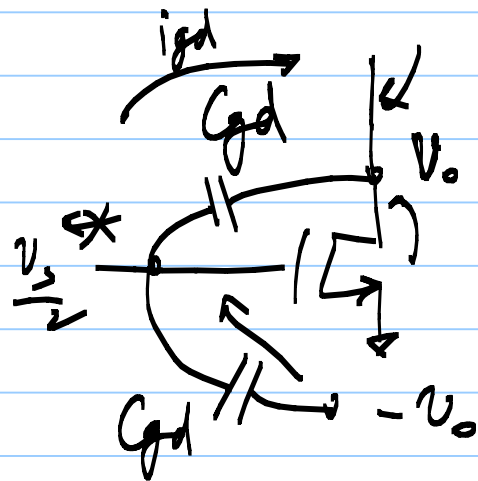
1) L_{gd} to resonate out C_{gd} ?

\hookrightarrow DC short bet. h & d

\hookrightarrow L_{gd} can be very large

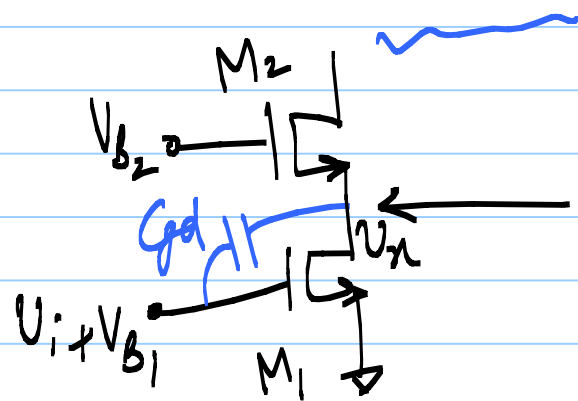
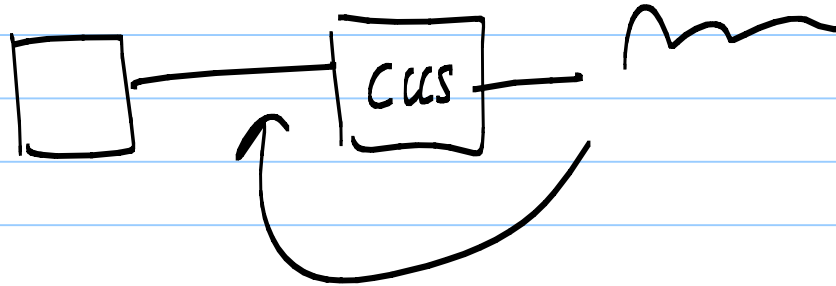
2) $-C_{gd}$ for incremental signal \rightarrow gyrator based circuits?

\rightarrow Miller effect



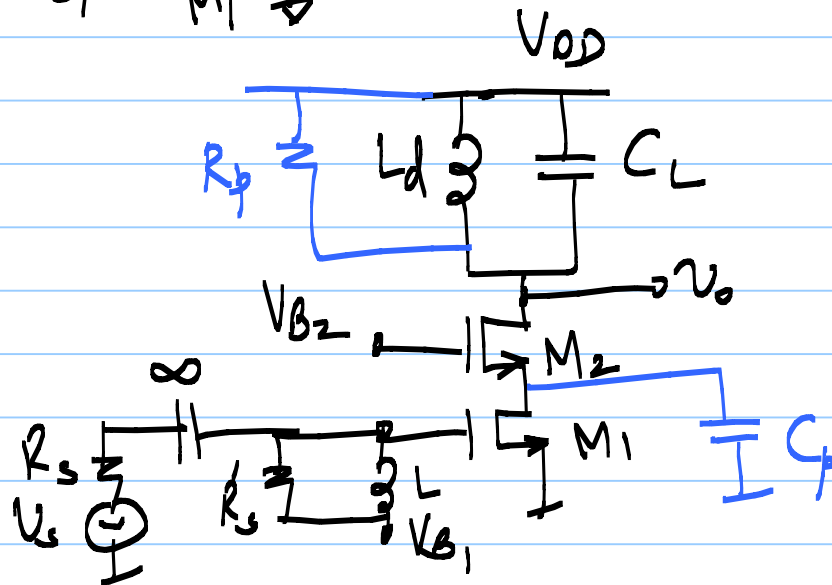
"capacitive neutralisation"

3) Cascode



$$v_x = -\frac{g_{m1}}{g_{m2}} \cdot v_i$$

← Unilateral amplifier

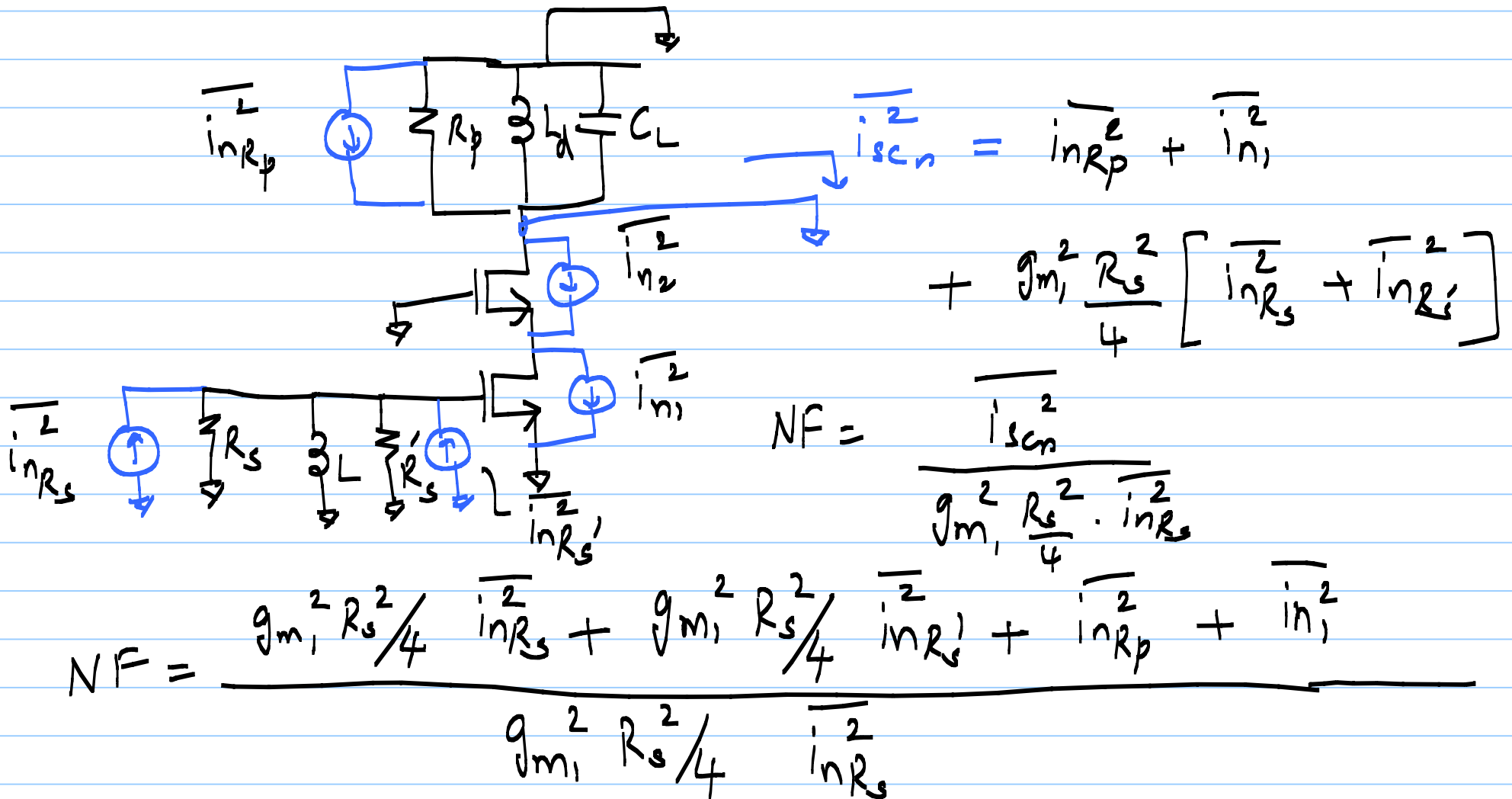


$$\text{gain} = -\frac{g_m R_p}{2}$$

NF = ?

Even if M_1, M_2 & R_p are noiseless,

$$F = 2, \quad NF = 3 \text{ dB}$$



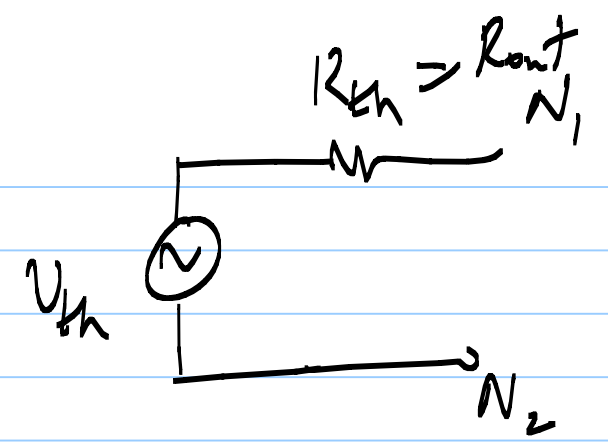
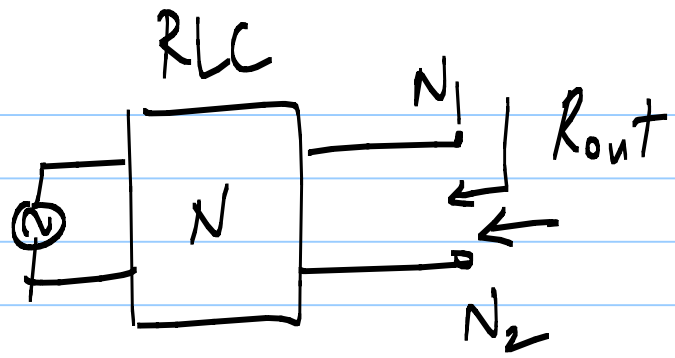
$$NF = 2 + \frac{4kT/R_p \Delta f + \frac{8kT}{3} g_{m1} \Delta f}{g_{m1}^2 \frac{R_s^2}{4} \cdot \frac{4kT}{R_s} \Delta f}$$

$$= 2 + \frac{4}{g_{m1}^2 R_s R_p} + \frac{8}{3 g_{m1} R_s}$$

fundamentally limited to be $\geq 3dB$

maximise Q of drain LC tank

maximise g_{m1}



Noise produced by network N across $N_1 - N_2$ } \Rightarrow Noise produced by R_{th}