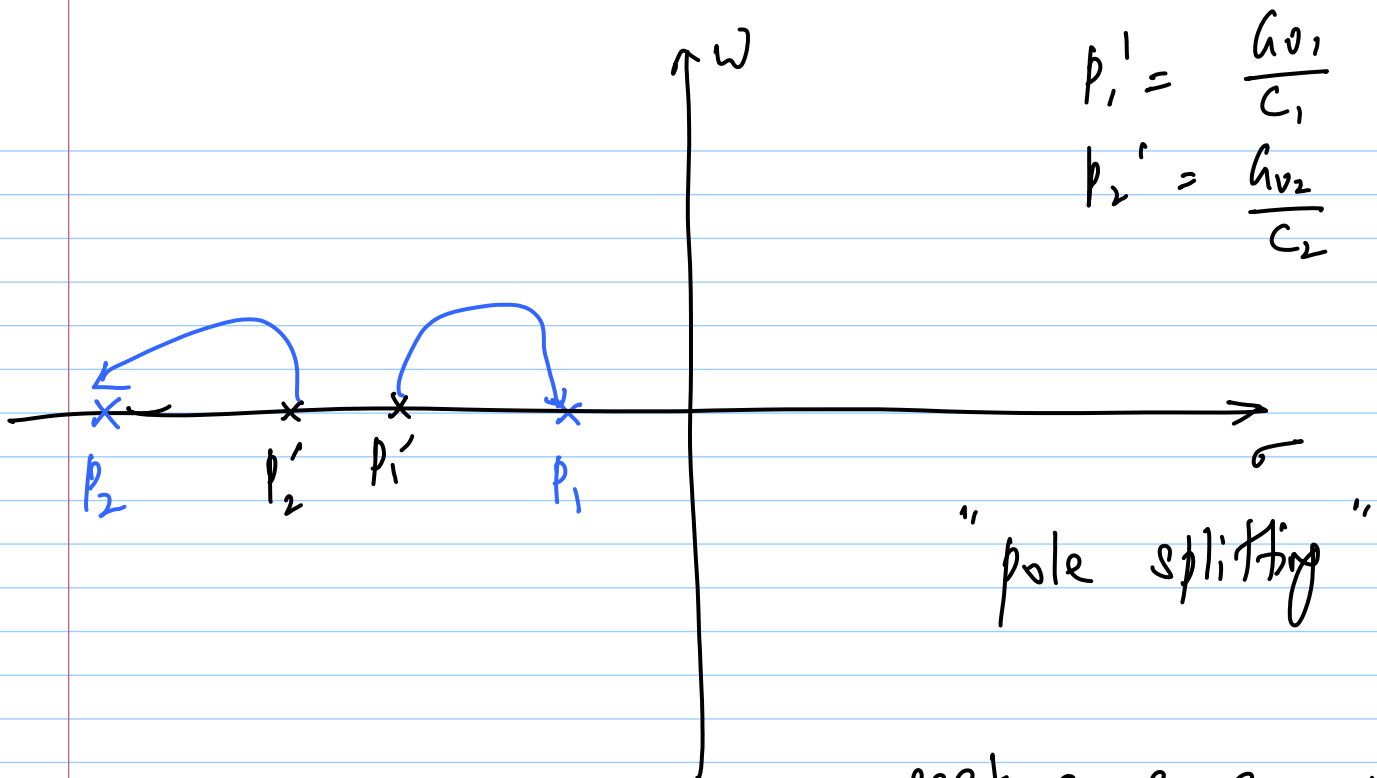
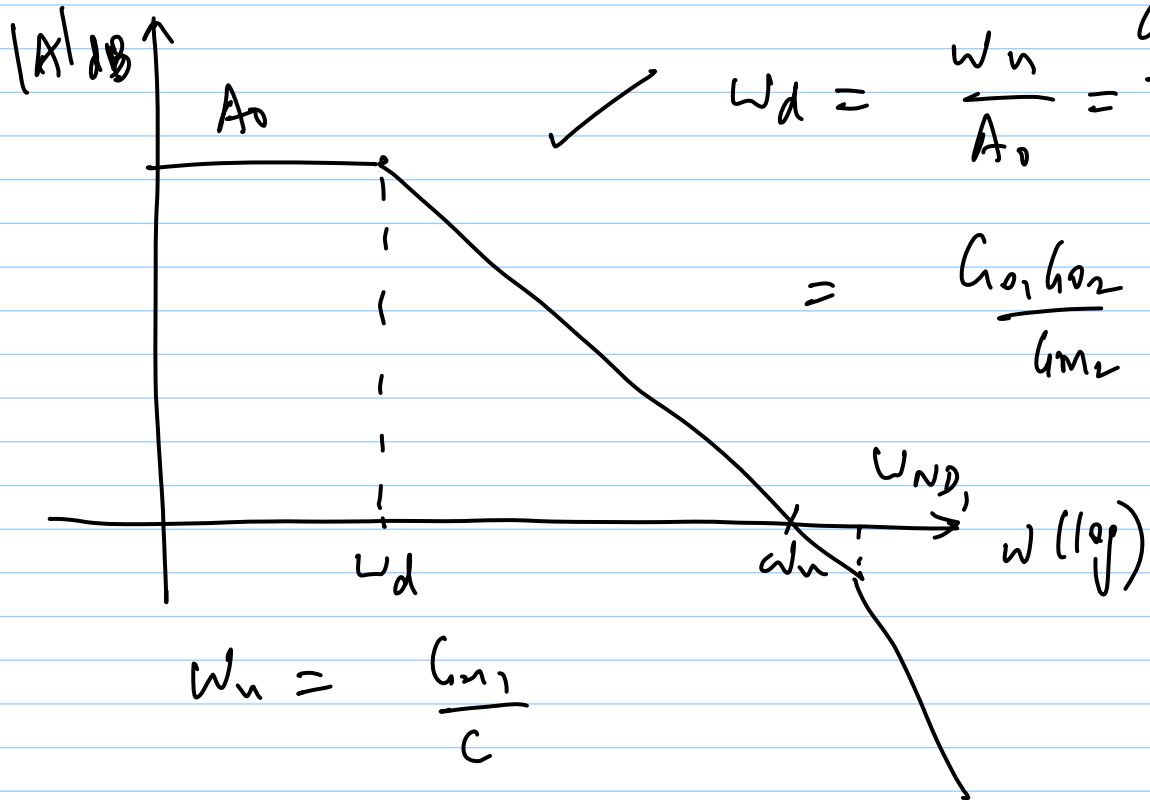


4-3-13

Lec 30



feature of a coupled system

Conditions for Stability

$$|w_{p2}| \gg |w_u|$$

$$\phi_{uLF} = -90^\circ - \tan^{-1}\left(\frac{w_u}{w_{p2}}\right) - \tan^{-1}\left(\frac{w_u}{w_{z1}}\right)$$

1) w_z

$G_{m1} = G_{m2} \Rightarrow 45^\circ$ phase from zero

We want $G_{m2} \gg G_{m1}$

$-\tan^{-1}\left(\frac{G_{m1}}{G_{m2}}\right)$

2) w_{p2}

$$w_{p2} \gg w_u$$

$$\Rightarrow \frac{G_{m2} \cdot \frac{C}{C+C_1}}{C_2 + \frac{CC_1}{C+C_1}} \gg \frac{G_{m1}}{C}$$

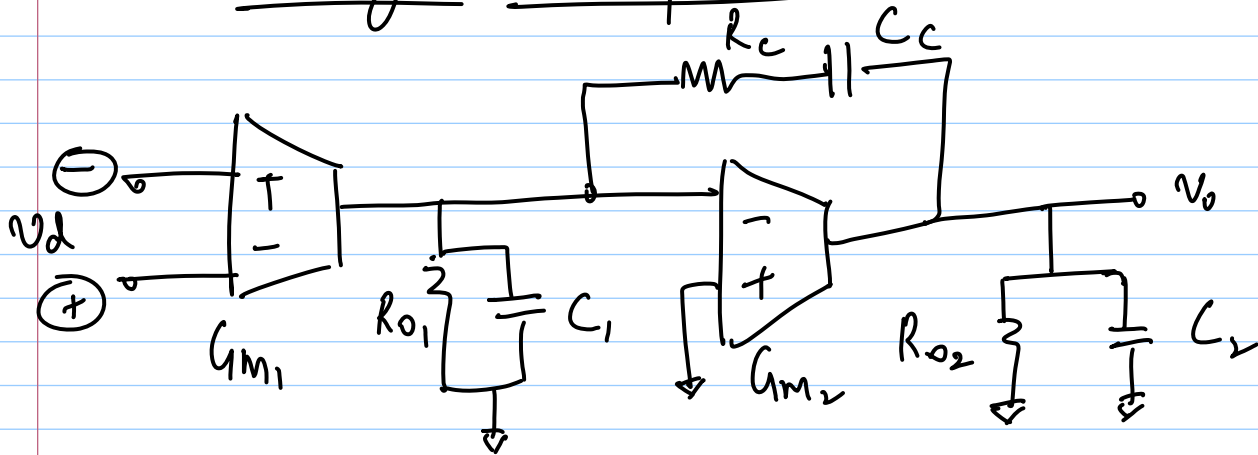
$$G_{m2} \gg G_{m1}$$

$$\uparrow \left(\frac{w}{C}\right) \Rightarrow C_1, C_2 \text{ also increase}$$

$\Rightarrow \uparrow I_2$ (keep $\frac{\omega}{\omega_c}$ small)

worry about Voltage swings

Moving zero position



After long analysis:

$$p_1 \approx \frac{G_{o1} G_{o2}}{G_{m2} C_c}$$

$$\underline{C_2 \gg C_1, C_c}$$

$$p_2 \approx \frac{G_{m2} C_c}{C_1 C_2 + C_c (C_1 + C_2)} \approx \frac{G_{m2}}{G_{o2}} \cdot \frac{G_{o2}}{C_2}$$

$$p_3 \approx \frac{1}{R_c C_1} ; z_1 = \frac{1}{\left(\frac{C_c}{G_{m2}} - R_c C_c \right)}$$

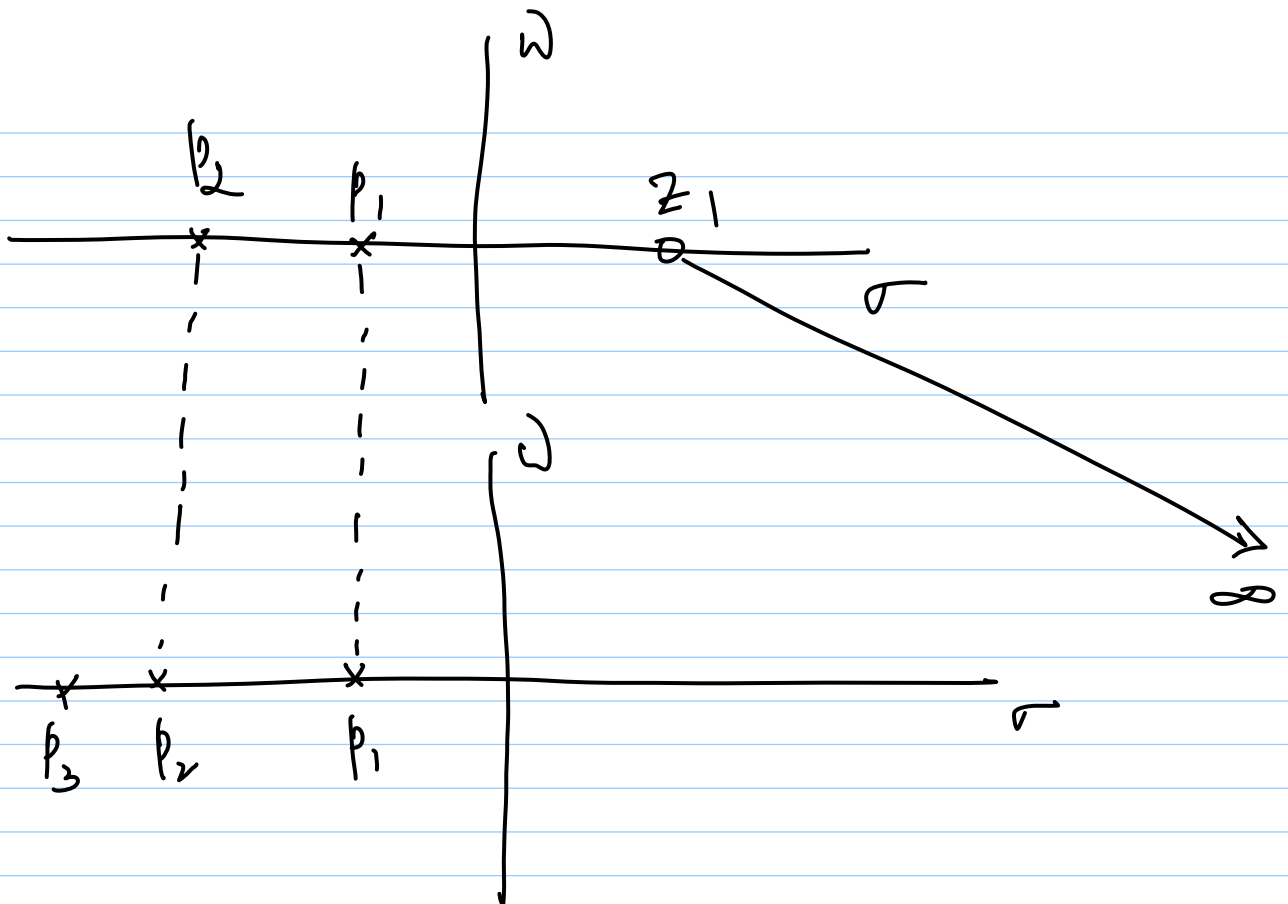
1) Move z_1 to ∞

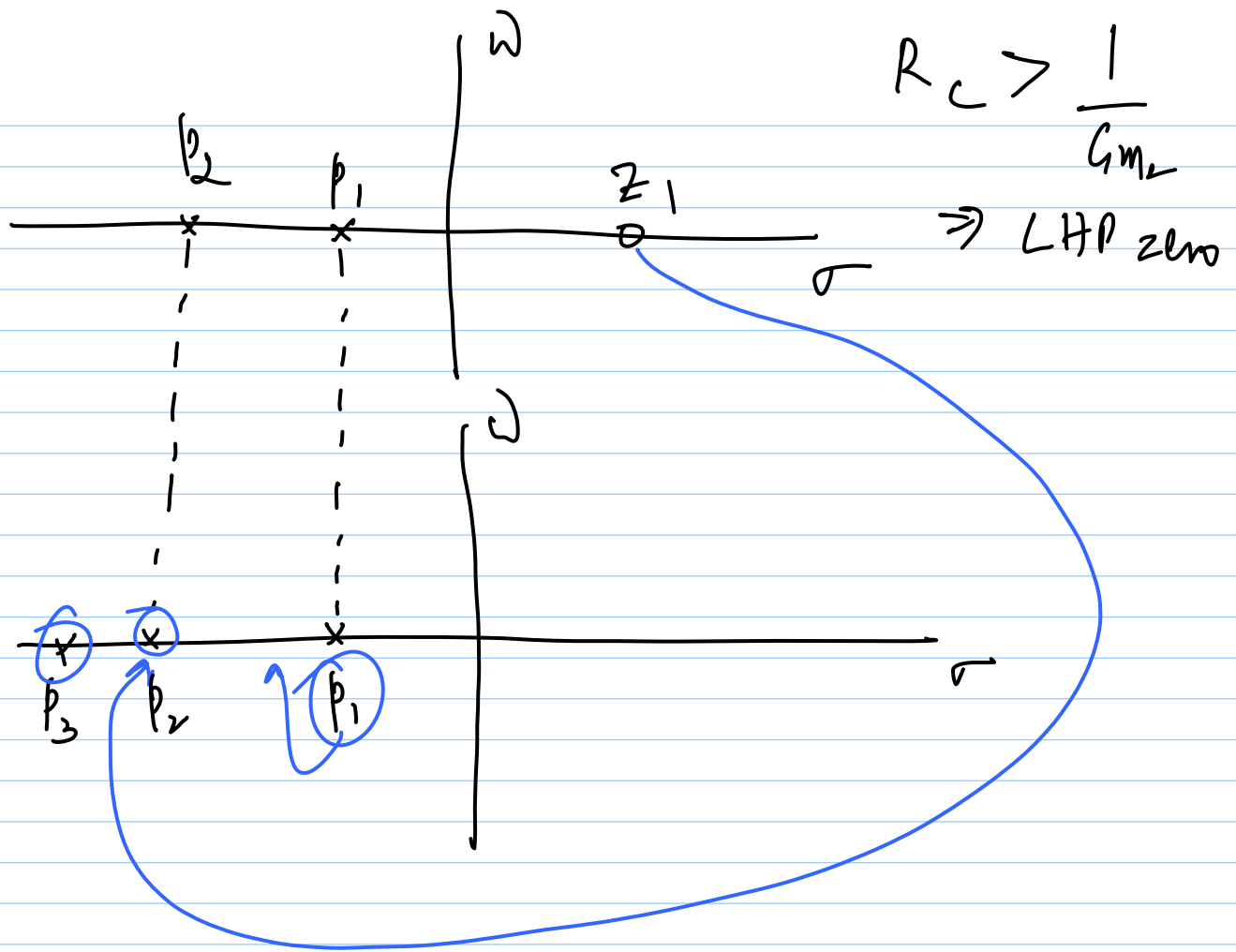
$$R_c = \frac{1}{g_{m2}}$$

$$p_1 \approx \frac{g_{o1}, g_{o2}}{g_{m2} C_c} ; \quad p_2 \approx \frac{g_{m2}}{g_{o2}} \cdot \frac{g_{o2}}{C_c}$$

$$\boxed{p_3} \approx \frac{1}{R_c C_1} = \frac{g_{m2}}{C_1} \approx \boxed{p_2} \cdot \frac{C_2}{C_1}$$

$$\underline{C_2 \gg C_1}$$





2) $z_1 = \frac{1}{\frac{C_c}{G_{m2}} - R_c C_c}$

move z_1 into LHP by $R_c > \frac{1}{G_{m2}}$

& cancel p_2

$$z_1 = p_2 \Rightarrow R_c = \frac{1}{G_{m2}} \left[1 + \frac{C_2}{C_c} \right]$$

for $PM \geq 45^\circ \Rightarrow p_3 \geq \underbrace{A_0 \phi_1}_{\omega_w}$

$$\frac{1}{R_c \cdot C_1} \geq \frac{G_{m1}}{C_c}$$

$$\frac{1}{C_1} \cdot \frac{G_{m2} \cdot C_c}{C_c + C_2} \geq \frac{G_{m1}}{C_c} \quad \checkmark$$

$$C_c \geq \frac{G_{m1} C_1 + \sqrt{G_{m1}^2 C_1^2 + 4 G_{m1} G_{m2} C_1 C_2}}{2 G_{m2}}$$