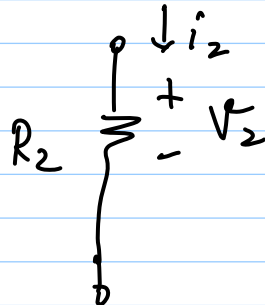
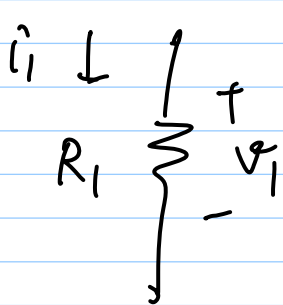


31/1/12

Lec 12

Half-ckt analysis with mismatch:



$$i_d = i_1 - i_2$$

$$i_c = \frac{i_1 + i_2}{2}$$

$$\Delta R = R_1 - R_2$$

$$R = (R_1 + R_2)/2$$

$$v_d = v_1 - v_2 = i_1 R_1 - i_2 R_2$$

$$v_c = \frac{v_1 + v_2}{2} = \frac{i_1 R_1 + i_2 R_2}{2}$$

$$v_d = \left(i_c + \frac{i_d}{2}\right) \left(R + \frac{\Delta R}{2}\right)$$

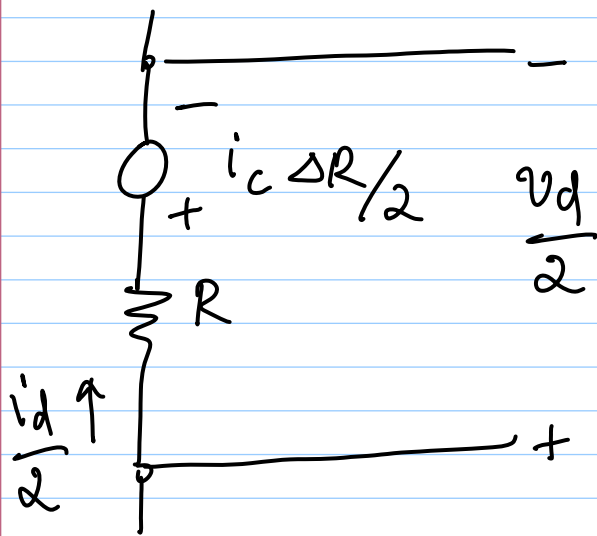
$$- \left(i_c - \frac{i_d}{2}\right) \left(R - \frac{\Delta R}{2}\right)$$

$$\approx i_d R + i_c (\Delta R)$$

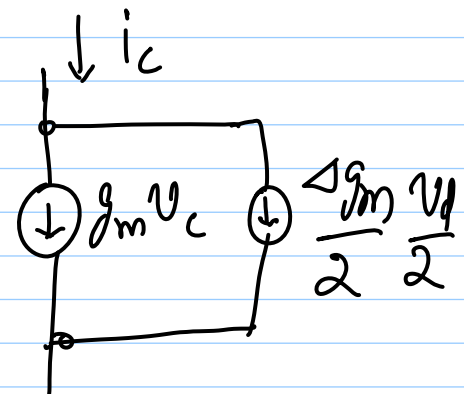
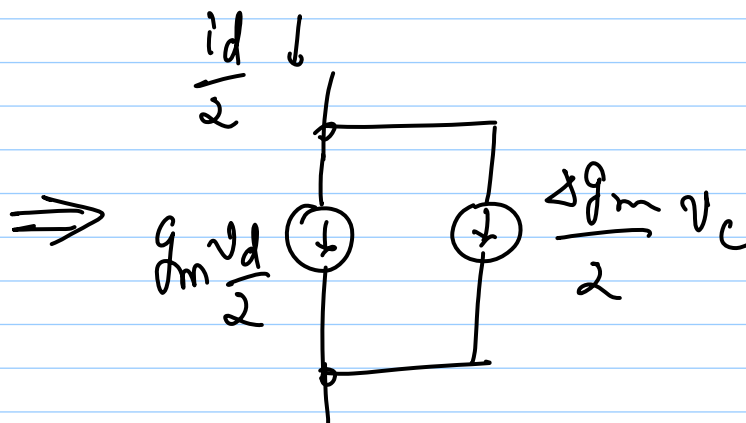
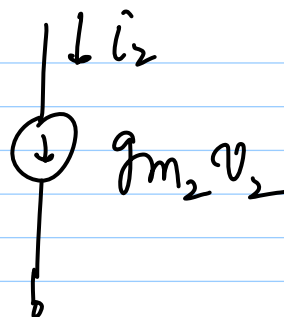
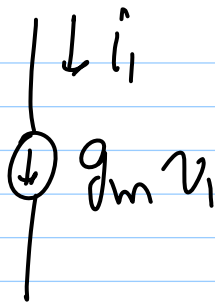
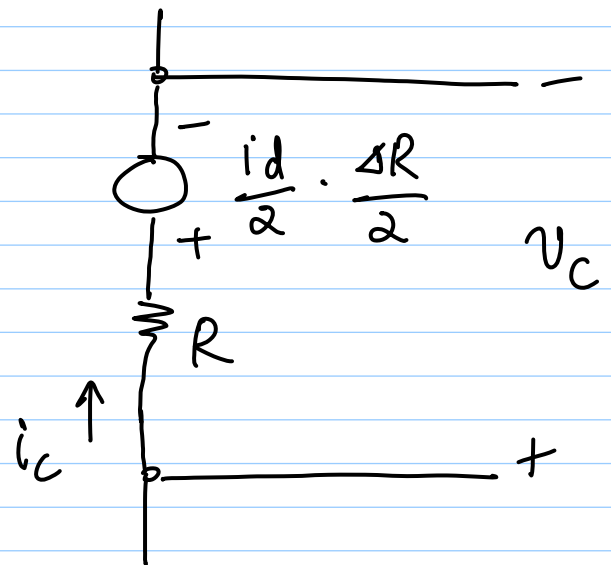
$$v_c = \frac{\left(i_c + \frac{i_d}{2}\right) \left(R + \frac{\Delta R}{2}\right) + \left(i_c - \frac{i_d}{2}\right) \left(R - \frac{\Delta R}{2}\right)}{2}$$

$$\approx i_c R + i_d \frac{(\Delta R)}{4}$$

Diff half ckt :



Cm half ckt :

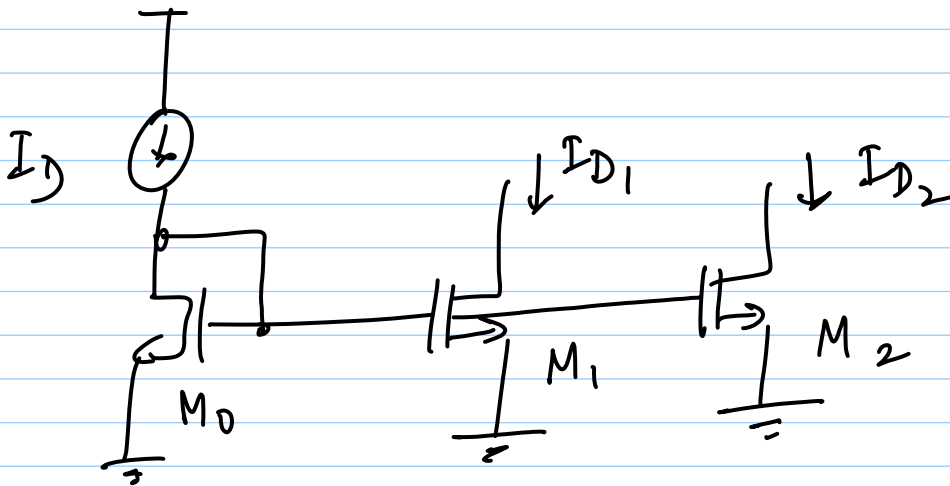


Diff. H.C.

$$\Rightarrow \left\{ A_{dm}, A_{cm} \right\}, \left\{ A_{cm-dm}, A_{dm-cm} \right\}$$

$\frac{v_{od}}{v_{id}}$ (points to A_{dm})
 $\frac{v_{oc}}{v_{ic}}$ (points to A_{cm})
 $\frac{v_{od}}{v_{ic}}$ (points to A_{cm-dm})
 $\frac{v_{oc}}{v_{id}}$ (points to A_{dm-cm})

Current source mismatch:



$$I_D = \frac{\beta}{2} \left(\frac{W}{L} \right) (V_{gs} - V_T)^2$$

$$\Delta I_D = \frac{\partial I_D}{\partial (W/L)} \Delta \left(\frac{W}{L} \right)$$

$$+ \frac{\partial I_D}{\partial (V_{gs} - V_T)} \cdot \Delta (V_{gs} - V_T)$$

$$= \frac{1}{2} \beta \left(\frac{W}{L} \right) (V_{gs} - V_T)^2 \cdot \Delta \left(\frac{W}{L} \right)$$

$$- \beta \left(\frac{W}{L} \right) (V_{gs} - V_T) \cdot \Delta V_T$$

$$\frac{\Delta I_D}{I_D} = \frac{\Delta(W/L)}{(W/L)} - 2 \frac{\Delta V_T}{(V_{AS} - V_T)}$$

⇒ to minimise current mismatch,
maximise $(V_{AS} - V_T)$

* Dependence of V_{OS} on $(V_{AS} - V_T)$
is similar to that of noise

$$\Rightarrow \overline{v_{n,in}^2}(\text{diff pair}) \propto \frac{1}{g_m} = \frac{V_{AS} - V_T}{2I_D}$$

$$\Rightarrow \overline{v_{n,out}^2}(\text{CM}) \propto g_m = \frac{2I_D}{V_{AS} - V_T}$$

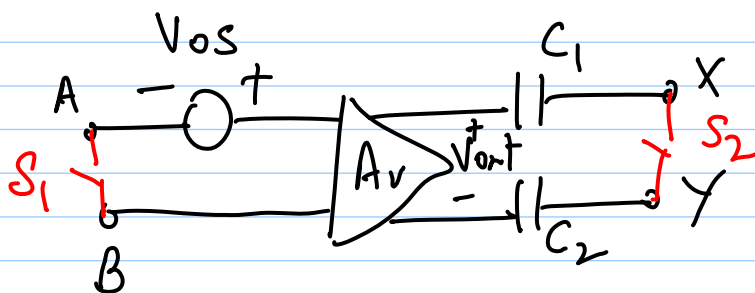
Offset Cancellation

Why?

to reduce $V_{OS} \Rightarrow$ reduce $(V_{AS} - V_T)$

⇒ larger devices ⇒ larger C_{in}

⇒ lower speed and/or higher P_{diss}



* If S_1 & S_2 are ON,

$$V_{out} = A_v \cdot V_{os}$$

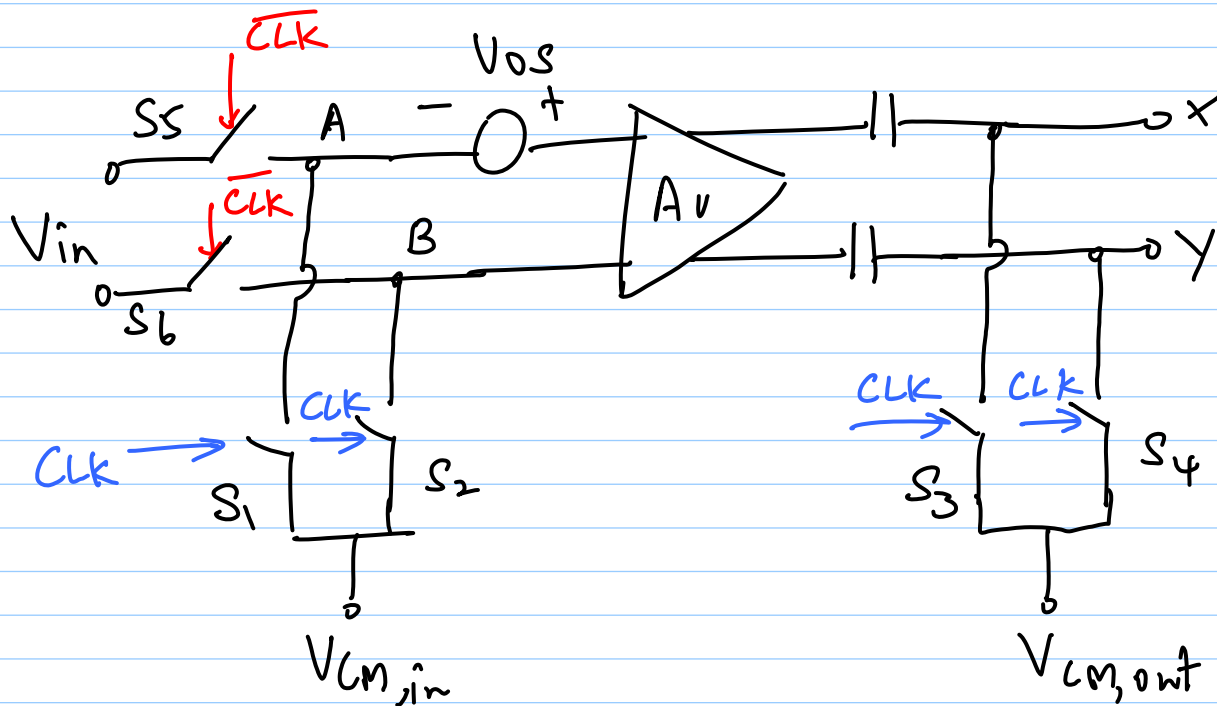
$\Rightarrow$ since $V_{xy} = 0$, $A_V \cdot V_{os}$ is stored across C_1, C_2

i.e. $V_{AB} = 0 \Rightarrow V_{xy} = 0$

Now turn off S_1, S_2

$\Rightarrow$ overall exhibits zero effects (amp + $C_1 - C_2$) wmb

In pratica:

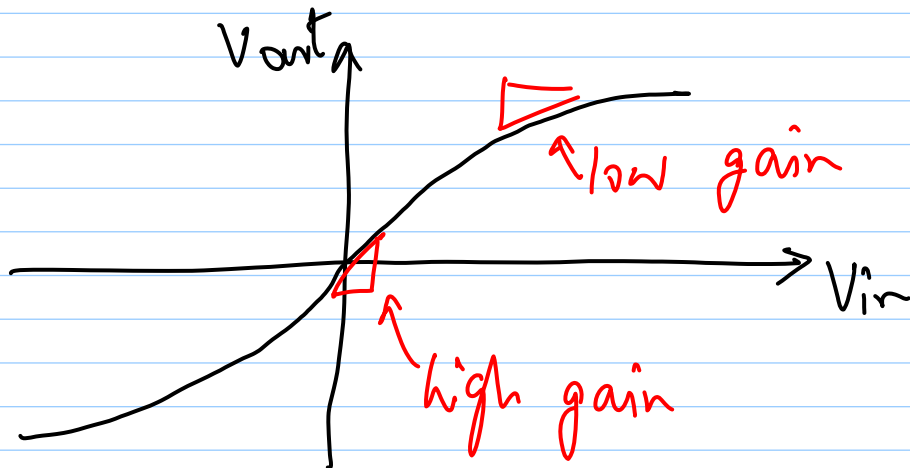


⇒ Output offset storage

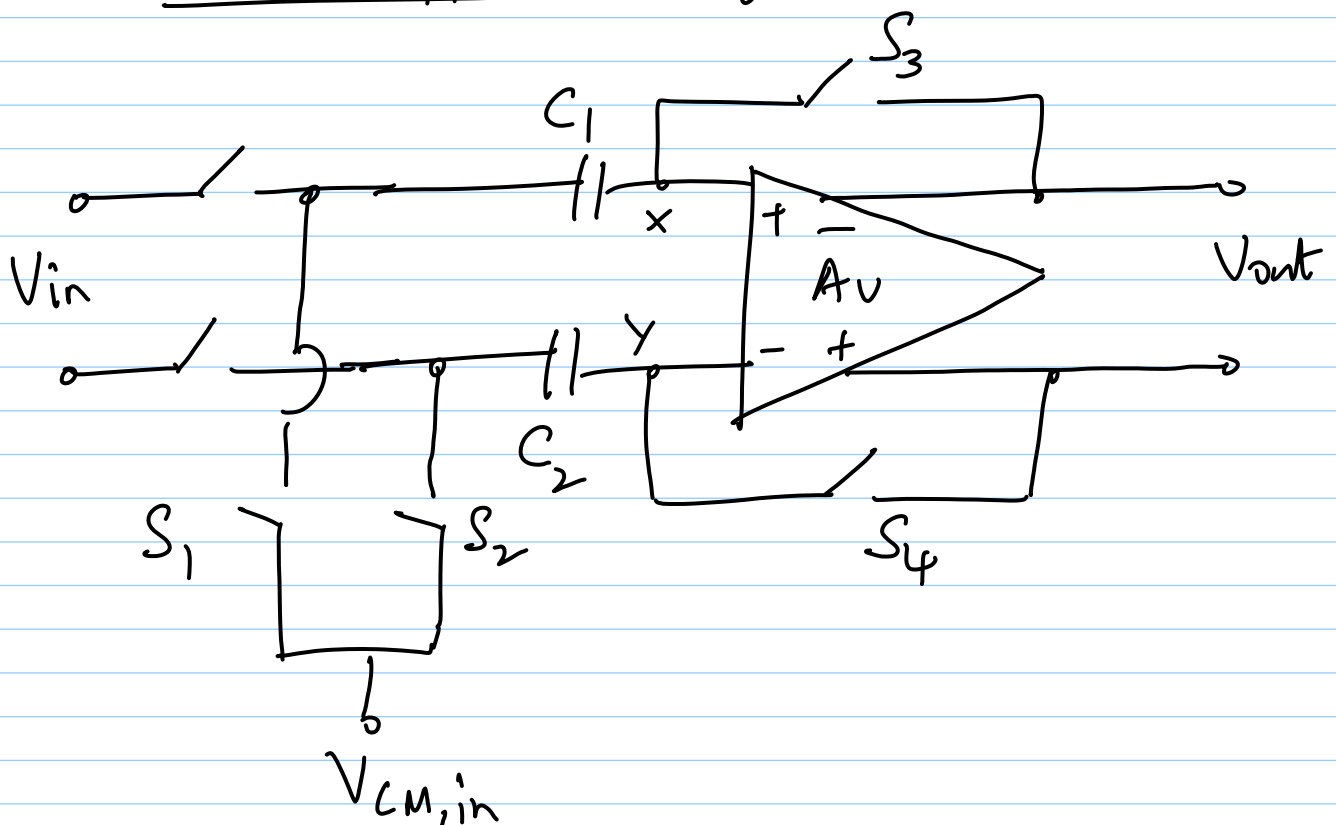
* fine for low-gain stages

What happens if A_v is too large?

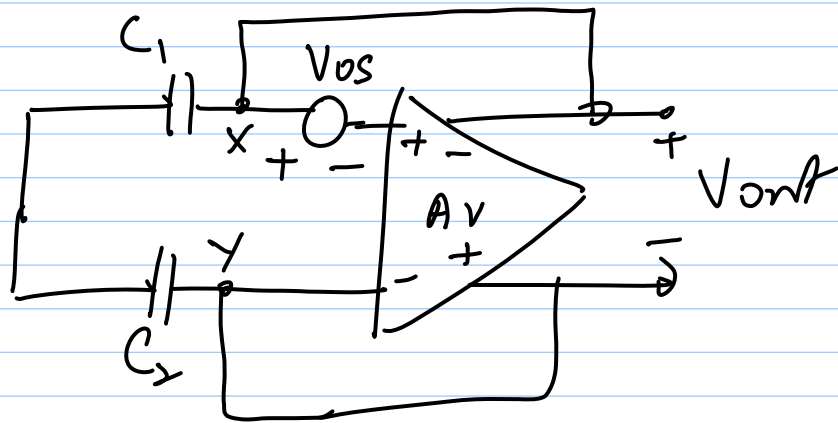
$V_{out} = A_v \cdot V_{os}$ can
"saturate" the amplifier



Input - offset storage



When $S_1 - S_4$ are closed:



Unity
gain
config.

$$V_{xy} = V_{out}$$

$$\Rightarrow V_{out} = (-A_v) (V_{out} - V_{os})$$

$$\Rightarrow V_{out} = \frac{A_v}{1+A_v} \cdot V_{os} \approx V_{os}$$

$$\Rightarrow V_{xy} \approx V_{os}$$

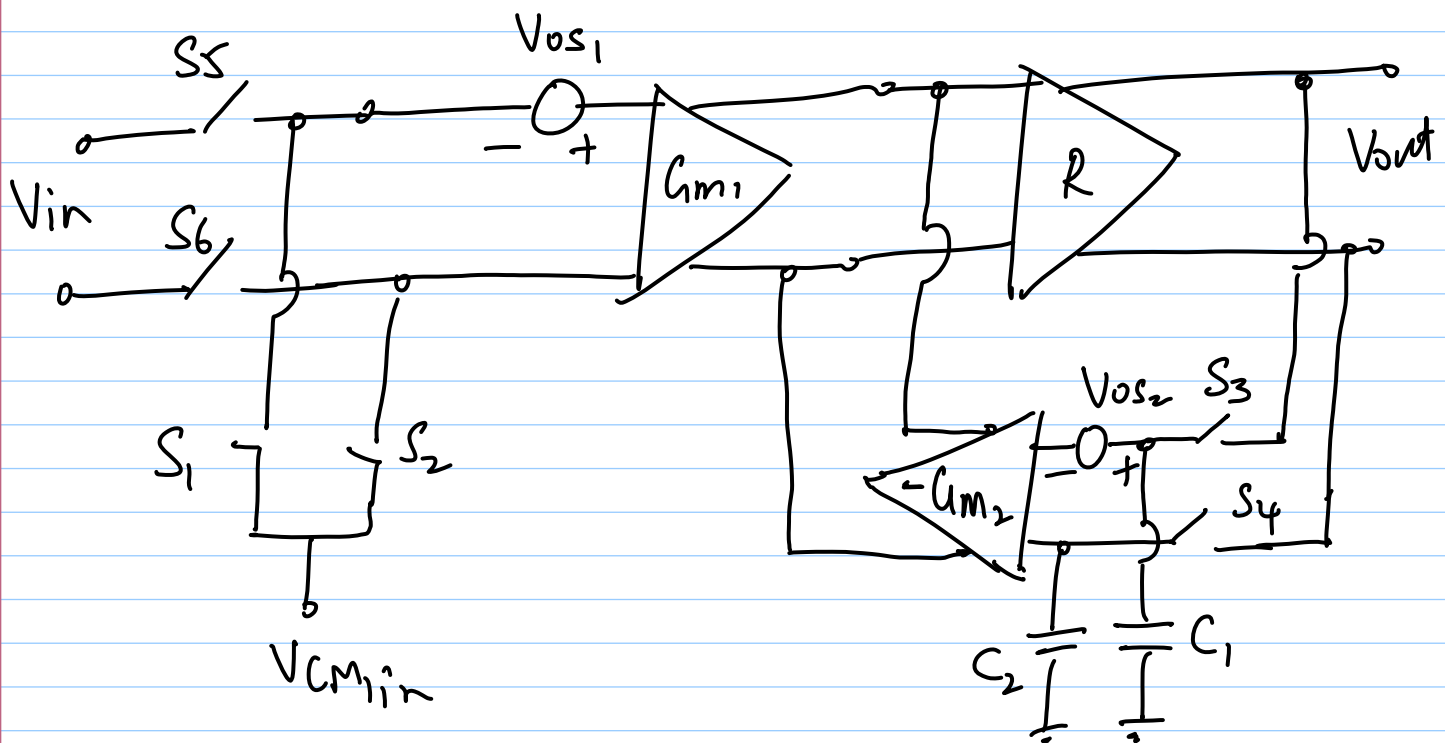
Offset voltage is stored on $C_1 - C_2$

* Both techniques introduce caps
in signal path

→ cap parasitics degrade phase
margin

→ limits settling speed

Aux. Amp



* G_m stages : currents are easier to add

Phase 1 : $S_1 - S_4$ are ON, $S_5 - S_6$ OFF

$$\left\{ G_{m1} \cdot V_{os1} - G_{m2} (V_{out} - V_{os2}) \right\} \cdot R = V_{out}$$

$$\Rightarrow V_{out} = \frac{G_{m1} R V_{os1} + G_{m2} R V_{os2}}{1 + G_{m2} R}$$

this is stored on C_1, C_2

Phase 2 : $S_1 - S_4$ are off, $S_5 - S_6$ ON

$$V_{os, tot.} = V_{out} / (G_{m1} R)$$

$$= \frac{V_{OS1}}{1 + G_{m2}R} + \frac{G_{m2}}{G_{m1}} \frac{V_{OS2}}{1 + G_{m2}R}$$

$$\approx \frac{V_{OS1}}{G_{m2}R} + \frac{V_{OS2}}{G_{m1}R}$$

* Assume amplifier offset cancellation happens @ every sampling operation

→ Can show that noise @ low freq. also gets cancelled

(freq. depends on sampling freq. f_s)