

Lecture 13: Noise in RF Circuits

Noise - any random interference unrelated to signal of interest

* represents inherent uncertainties at the physical level - is a "random" or "stochastic" process.

* represented by some kind of probability density function (PDF)

* "mean square" noise power is given by

$$\overline{n^2(t)} = \int_{-\infty}^{\infty} n^2(t) P_n(n) dn \quad \{P_n(n) = \text{PDF}\}$$

* PDF provides no info on how fast $n(t)$ varies in time domain

* many natural phenomena exhibit Gaussian Statistics

* Gaussian PDF:

$$P_n(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp \frac{-(x-m)^2}{2\sigma^2}$$

$m = \text{mean}$

$\sigma = \text{std deviation}$

* For a Gaussian,

68% samples lie between $(m-\sigma)$ & $(m+\sigma)$

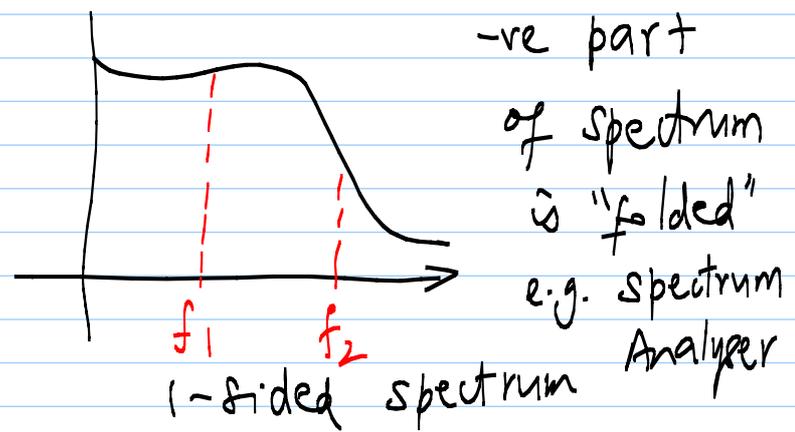
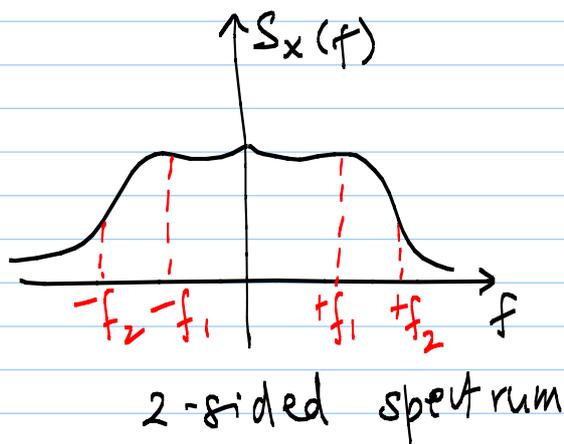
99% samples lie between $(m-3\sigma)$ & $(m+3\sigma)$

Power Spectral Density (PSD)

* Useful to characterise noise in frequency domain for RF Design

$S_x(f) \rightarrow$ provides power carried in a signal in a unit BW around f

* $S_x(f)$ is an even function of f for real $x(t)$



2-sided - often used in graphical analysis of freq. domain operations

1-sided - used in noise calculations at a circuit level

e.g. thermal noise voltage across a resistor of value R

$$S_x(f) = 2kTR$$

k = Boltzmann's constant = 1.38×10^{-23} J/K

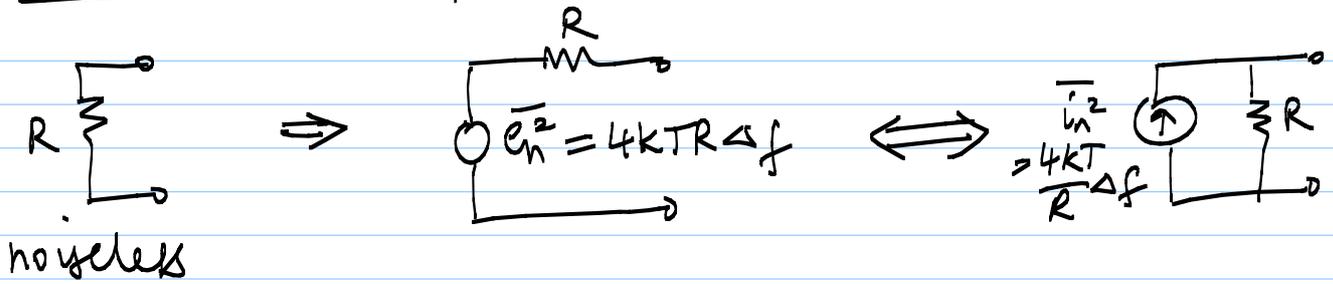
T = absolute temp.

In ckt noise calculations, we often write

$$\overline{V_n^2} = 4kTR \Delta f$$

mean square noise voltage

D) Thermal noise of resistor



Δf = measurement BW (brick wall)

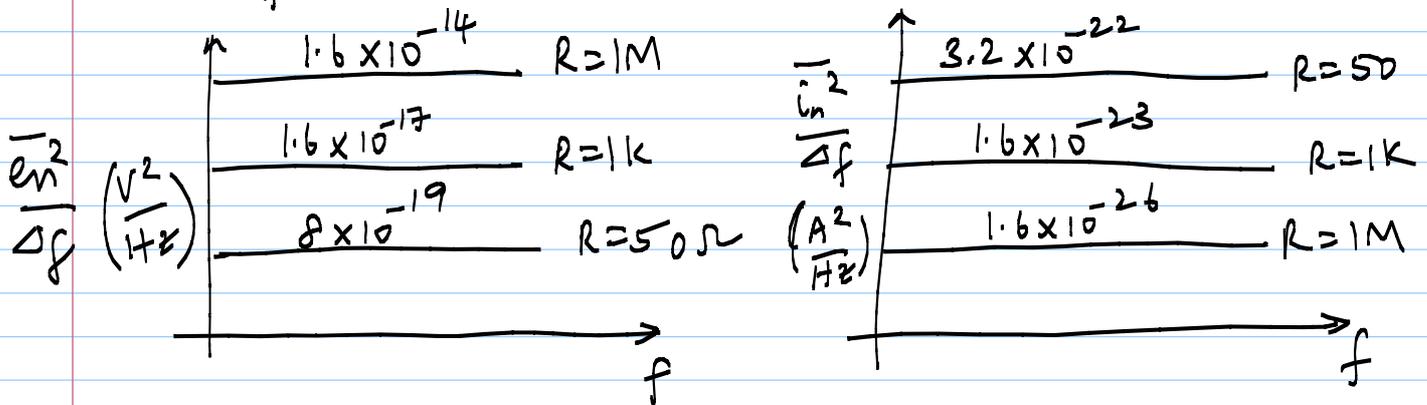
* $\frac{e_n^2}{\Delta f} \equiv$ mean square noise voltage density
 $= 4kTR = 1.6 \times 10^{-20} \cdot R \text{ V}^2/\text{Hz}$ at Room Temp.

* $\frac{i_n^2}{\Delta f} \equiv$ mean square noise current density
 $= \frac{4kT}{R} = \frac{1.6 \times 10^{-20}}{R} \text{ A}^2/\text{Hz}$ at Room temp

$$\overline{e_n^2} = \overline{i_n^2} \cdot R^2 \quad \left\{ \text{note the } R^2 \right\}$$

$\frac{\overline{e_n^2}}{\sqrt{\Delta f}} \equiv$ r.m.s. noise voltage density $\{ \text{V}/\sqrt{\text{Hz}} \}$

$\frac{\overline{i_n^2}}{\sqrt{\Delta f}} \equiv$ r.m.s. noise current density $\{ \text{A}/\sqrt{\text{Hz}} \}$

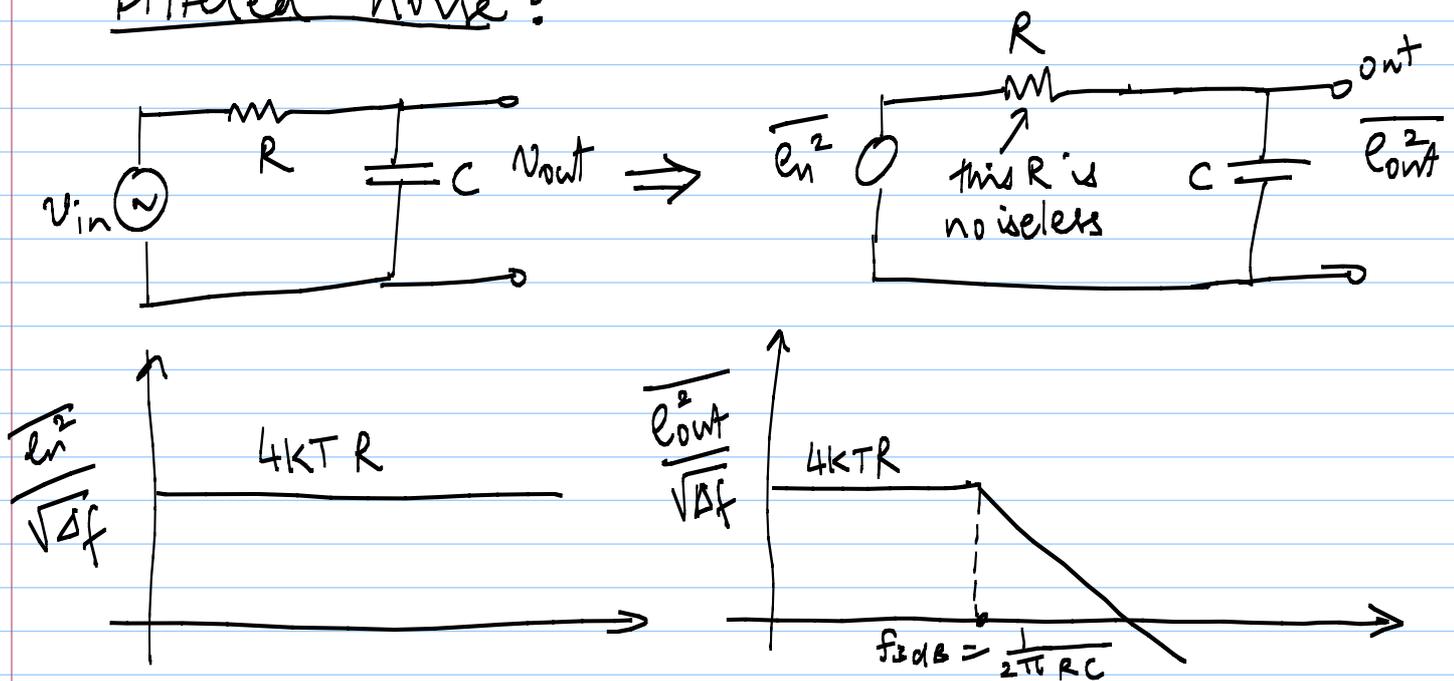


Spot noise = mean square noise density integrated over 1 Hz BW @ freq. of interest

* White Noise \equiv Spot noise is independent of frequency (ie. flat PSD)

$$1k\Omega \rightarrow 4nV/\sqrt{Hz} ; 50\Omega \rightarrow 0.9nV/\sqrt{Hz}$$

Filtered noise:



* Noise is low-pass filtered

* Integrated mean-square noise:

$$\begin{aligned} \overline{e_{out}^2} &= \int_0^{\infty} \frac{\overline{e_n^2}}{|1+j2\pi fRC|^2} df \\ &= \frac{\overline{e_n^2}}{2\pi RC} \cdot \frac{\pi}{2} \end{aligned}$$

$$\boxed{\overline{e_{out}^2} = \frac{kT}{c} V^2}$$

* Equivalent Noise BW \equiv BW of brick-wall filter whose output integrated noise power is same as above 1-pole filter



$$\frac{kT}{C} = \overline{e_n^2} \cdot f_{eqv}$$

$$= 4kTR \cdot f_{eqv}$$

$$\Rightarrow \boxed{f_{eqv} = \frac{1}{4RC} = \frac{\pi}{2} f_{3dB}}$$

* Available Noise Power :



$$\left. \begin{array}{l} \text{Noise power delivered to} \\ \text{load resistor in a 1Hz BW} \end{array} \right\} = \frac{(\overline{e_n}/2)^2}{R} = \frac{\overline{e_n^2}}{4R} \text{ (W/Hz)}$$

$$\Rightarrow \text{available noise power} = \frac{4kTR}{4R} \cdot B$$

where $B =$ bandwidth of interest

$$\boxed{P_{avl} = kTB \text{ Watts}}$$

independent of
resistance R !

keys to low-noise design

→ minimise temp

→ use minimum BW necessary (don't overdesign!)

$$\begin{aligned} \text{Pave./Hz} &= \frac{kTB}{B} = kT \text{ W/Hz} \\ &= 4.14 \times 10^{-21} \text{ W/Hz} \\ &= -174 \text{ dBm/Hz} \end{aligned}$$

* Total RMS noise over BW defines minimal signal

* Total distortion defines maximum signal

2) Noise in MOSFETS

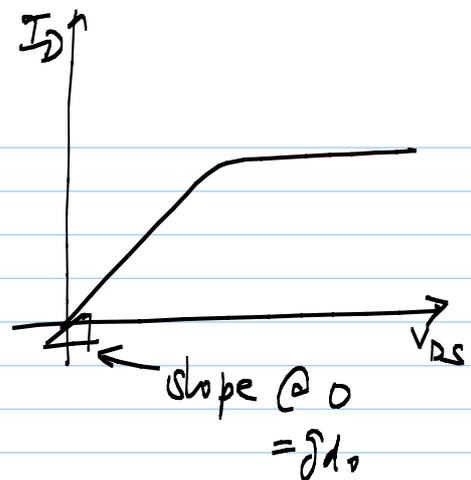
A) Thermal noise:

I In triode region:

$$I_d = k' \left(\frac{W}{L} \right) \left[(V_{GS} - V_T) V_{DS} - \frac{V_{DS}^2}{2} \right]$$

$$g_d = \frac{\partial I_D}{\partial V_{DS}} = k' \left(\frac{W}{L} \right) (V_{GS} - V_T - V_{DS})$$

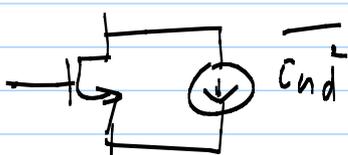
$$\Rightarrow g_{d0} = k' \left(\frac{W}{L} \right) (V_{GS} - V_T)$$



$$\overline{i_{nd}^2} = 4kT \gamma g_{d0} \Delta f$$

γ is an empirical parameter ($=1$ in triode region)

II. Long channel device in sat:



$$\overline{i_{nd}^2} = 4kT \gamma g_{d0} \Delta f$$

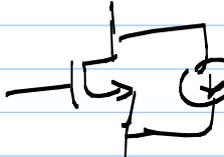
$\gamma = \frac{2}{3}$ for a long-channel device

$$I_D = \frac{k'}{2} \left(\frac{W}{L}\right) (V_{GS} - V_T)^2$$

$$\Rightarrow g_m = \frac{\partial I_D}{\partial V_{GS}} = k' \left(\frac{W}{L}\right) (V_{GS} - V_T) = g_{d0}$$

$$\therefore \boxed{\overline{i_{nd}^2} = 4kT \cdot \frac{2}{3} g_m \Delta f} \quad \text{common form}$$

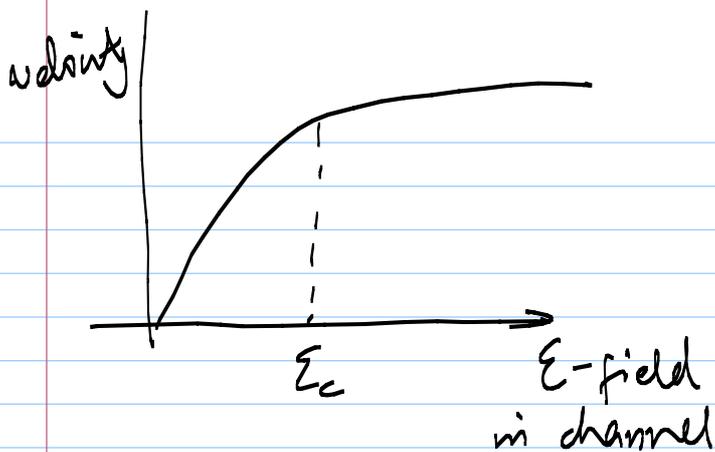
II. Short-channel device in fact:



$$\overline{i_{nd}^2} = 4kT \gamma g_{d0} \Delta f$$

typical $\gamma = 2-3$, but can even be 4-5

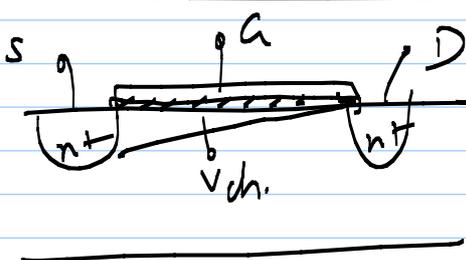
* excess noise (larger γ) due to "hot carriers"



as $E \uparrow$ beyond E_c , v does not \uparrow

\Rightarrow excess energy goes into heat (ie. thermal energy) ie into increased noise

B. Gate-induced noise:

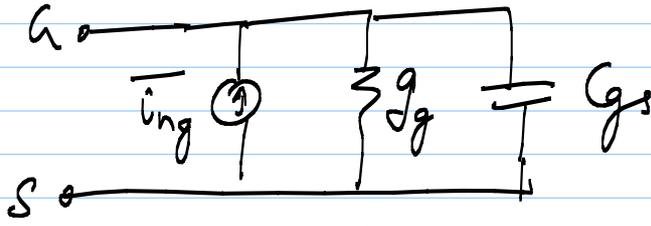


* thermal noise in i_{d0} causes channel voltage V_{ch} to fluctuate

* V_{ac} gate-channel voltage varies through gate oxide cap.

⇒ noise current flows through the gate

Van der Ziel's model:



$$\overline{i_{ng}^2} = 4kT \delta g_g \Delta f$$

$$* g_g = \frac{w^2 C_{gs}^2}{5 g_{do}}$$

* $\delta = 28$ for long-channel mosfets

* $\overline{i_{ng}} \propto w \Rightarrow$ "blue noise"

* Use series-parallel transformations to use a voltage noise source:



* $C_{gs}' \approx C_{gs}$ (assume high Q) $\left\{ C_{gs}' = C_{gs} \cdot \frac{1+Q^2}{Q^2} \right\}$

* r_{gate} :

recall: $R_p = R_s (Q^2 + 1)$

$$Q = \frac{w C_{gs}}{g_g}$$

$$\Rightarrow r_{gate} = \frac{1}{g_g} \cdot \frac{1}{(1+Q^2)} \approx \frac{1}{g_g Q^2}$$

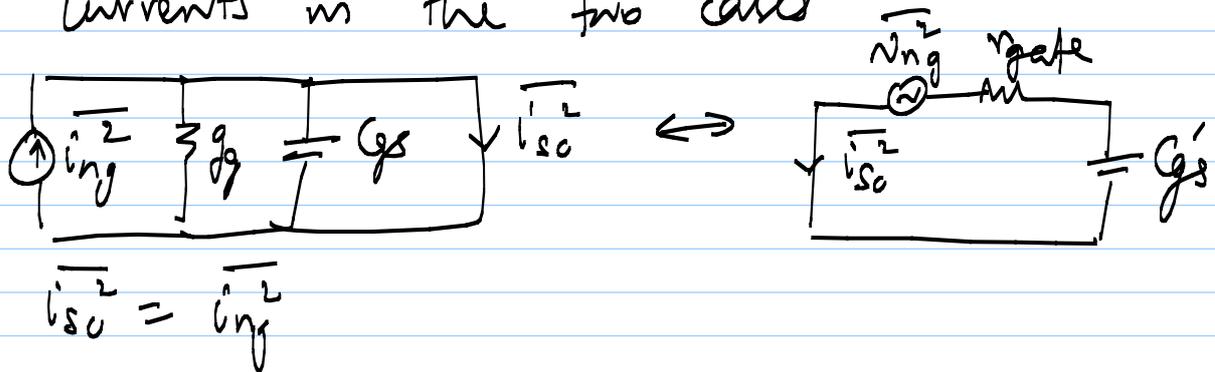
$$= \frac{1}{g_g} \cdot \frac{g_g^2}{w^2 C_{gs}^2} = \frac{1}{5 g_{do}}$$

* This model is narrowband only!

→ converts blue noise to white at freq. of interest

* Gate noise is typically important at high freq. only $\{\overline{i_{ng}^2} \propto \omega^2\}$

* to determine $\overline{v_{ng}^2}$, equate short-ckt noise currents in the two cases



$$\overline{i_{sc}^2} = \frac{\overline{v_{ng}^2}}{r_{gate} + \frac{1}{sC_{gs}}} = \frac{\overline{v_{ng}^2}}{r_{gate}} \cdot \frac{1}{1 + \frac{1}{sC_{gs}r_{gate}}}$$

$$\overline{i_{ng}^2} = \frac{\overline{v_{ng}^2}}{r_{gate}^2} \cdot \frac{1}{1 + \frac{1}{r_{gate}^2 \omega^2 C_{gs}^2}}$$

$$\approx \overline{v_{ng}^2} \cdot \omega^2 C_{gs}^2$$

$$\Rightarrow \overline{v_{ng}^2} = \frac{1}{\omega^2 C_{gs}^2} \cdot 4kT f g_g \cdot \Delta f$$

recall: $r_{gate} = \frac{g_g}{\omega^2 C_{gs}^2}$

$$\Rightarrow \overline{v_{ng}^2} = 4kT f r_{gate} \Delta f //$$

Notes :

→ BSIM3 uses fixed $\gamma = \frac{2}{3}$

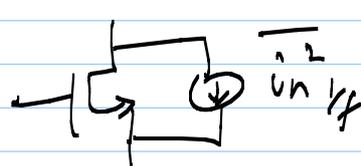
→ BSIM3 does not include $\overline{i_{n_f}^2}$ model

→ Excess noise is to be included separately in design simulations (also for projects)

C. Flicker ($1/f$) Noise

In general $\overline{v^2} = \frac{K}{f^n} \Delta f$ (K, n - empirical constants)

In MOSFETs:

 $\overline{i_{n_f}^2} = \frac{K}{f} \frac{g_m^2}{W L C_{ox}^2} \cdot \Delta f$

 $\overline{v_{n_f}^2} = \frac{K}{f} \cdot \frac{1}{W L C_{ox}^2} \cdot \Delta f$

* Recall: $W_T = \frac{g_m}{C_{gs}}$

we can also write

$$\overline{i_{n_f}^2} = \frac{K}{f} \cdot W_T^2 A \cdot \Delta f$$

$A = W \cdot L = \text{gate area}$

→ for the same area, faster process has worse $1/f$ noise

* Use large area for low flicker noise

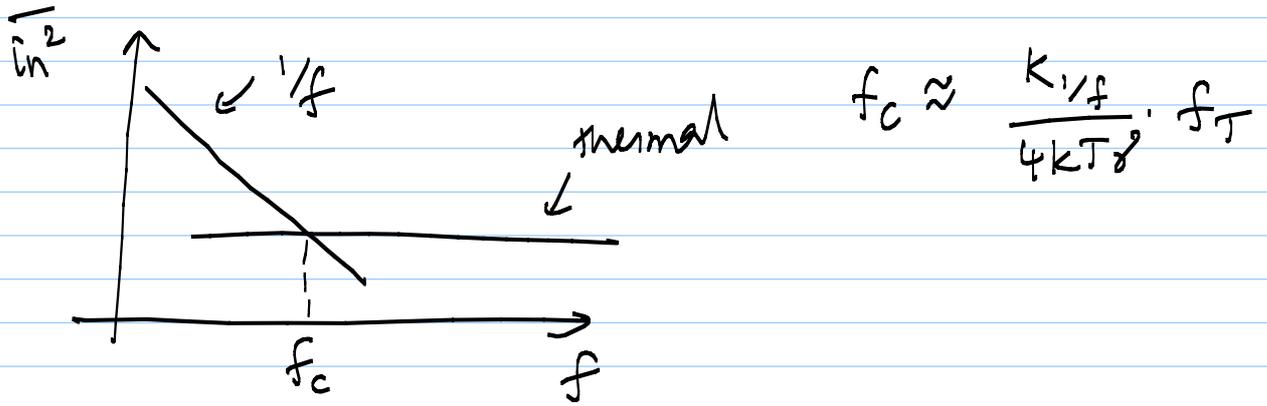
* $K_p \sim 10^{-28} \text{ C}^2/\text{m}^2$ (PMOS)

$K_n \sim 50 \cdot K_p$ (NMOS)

→ PMOS often have lower $1/f$ noise, but this is process dependent

→ PMOS need more current for given g_m

* flicker noise is important at low freq
(for LTI circuits)



* In many RF circuits, $1/f$ noise can get
"up-converted" to desired frequency bands
→ especially important in oscillator & Freq.
synthesizer design (N.L. or T.V. circuits)