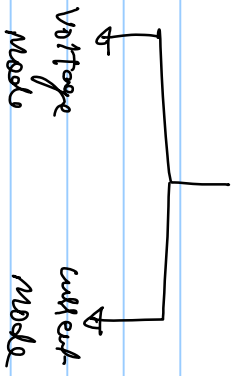
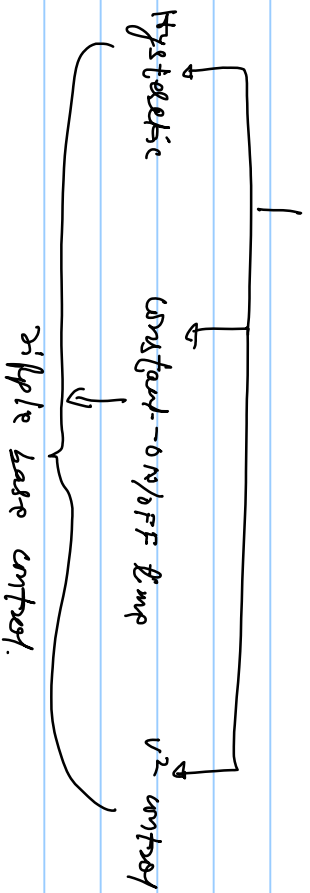


Non-linear control of dc-dc converters

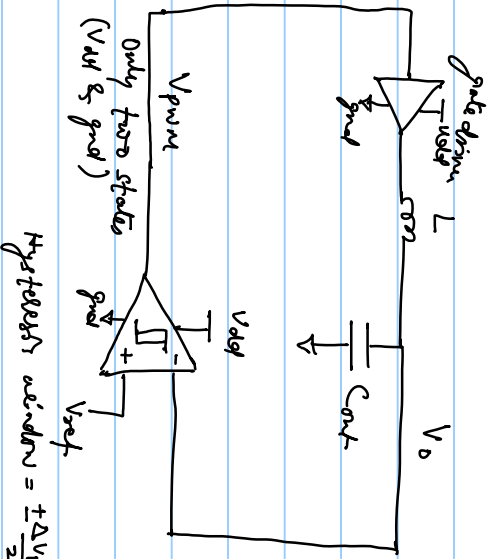
Linear control



Non-linear control

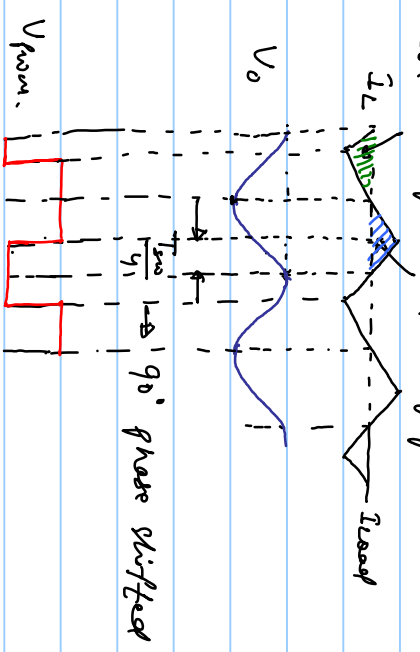


Single base control.



- Bandwidth is not limited as comparator can respond to any change in V_o instantaneously.
- No PWM modulation delay ($t_{d} = (1-D)T_{sw}$ or $D \cdot T_{sw}$)

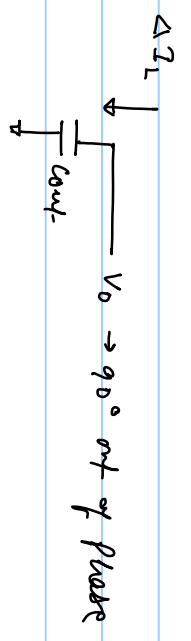
Cont: is discharging Cont: is charging.

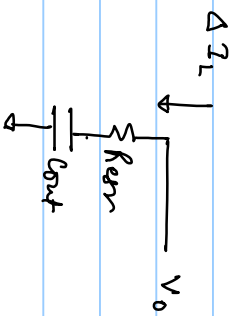


V_o is not bounded between $V_{p1} \pm \frac{\Delta V_{H1}}{2}$ due to 90° phase shift.

This makes is unstable.

In order to stabilize the output we want V_o in phase with I_p

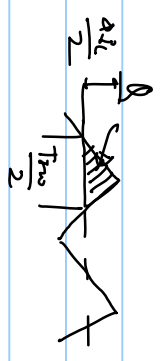




$$\Delta V_0 = \Delta I_L R_{err} + \frac{\Delta I_L}{Q C_{out} f_{sw}}$$

\downarrow $I_{in\ phase}$ \downarrow 90° out of phase.

$$\Delta I_L R_{err} \gg \frac{\Delta I_L}{Q C_{out} f_{sw}}$$



$$\frac{1}{2} \times \frac{T_{sw}}{2} \times \frac{\Delta I_L}{2}$$

$$Q = C \Delta V_0 \Rightarrow \Delta V_0 = \frac{Q}{C}$$

Usually if $R_{err} \cdot C_{out} > D \cdot \frac{T_{sw}}{2}$ & $(1-D) \frac{T_{sw}}{2}$

then output is stable $\rightarrow \Delta V_0$ is in phase with ΔI_L and V_0 is bounded.

for $D = 0$ to 1

$$R_{err} \cdot C_{out} > \frac{T_{sw}}{2}$$

ΔI_L Resr $\Rightarrow \frac{\Delta I_L}{8c F_{sw}}$ then we can ignore $\frac{\Delta I_L}{8c F_{sw}}$

$$\Delta V_o = \Delta I_L \cdot R_{esr}$$

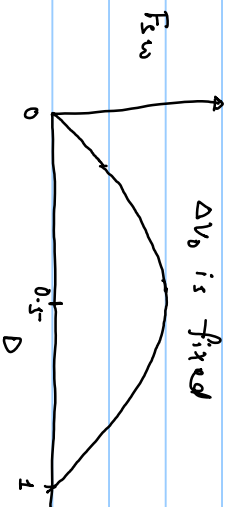
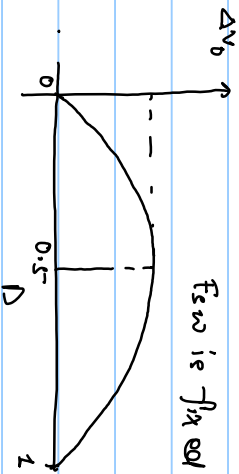
$$\Delta I_L = \frac{V_{in} D \cdot (1-D) T_{sw}}{L}$$

$$\Delta V_o = \frac{V_{in} D \cdot (1-D) T_{sw}}{L} \times R_{esr}$$

$$\Delta V_o = \Delta V_H$$

$$F_{sw} = \frac{1}{T_{sw}} = \frac{V_{in} D \cdot (1-D)}{\Delta V_H \cdot L} \times R_{esr}$$

Assume V_{in} , ΔV_H , L & R_{esr} are fixed but V_o is variable $\rightarrow D$ is varying



Switching frequency is not constant.

$$f_{sw} \propto V_{in} \cdot D(1-D) \cdot R_{err}$$

$$f_{sw} \propto \frac{1}{\Delta V_H \cdot L}$$

$$f_{sw} = 1 \text{ MHz at } D = 0.5$$

$$V_{in} = 1.8 \text{ V, } L = 1 \mu\text{H, } C_{out} = 10 \mu\text{F}$$

$$\Delta V_H = 10 \text{ mV}$$

$$f_{sw} = \frac{1}{T_{sw}} = \frac{V_{in} \cdot D \cdot (1-D)}{\Delta V_H \cdot L} \times R_{err}$$

$$R_{err} = \frac{10^8 \times 10^{-2} \times 10^{-6}}{1.8 \times 0.5 \cdot (1-0.5)} = \frac{10^{-2}}{1.8 \times 0.25} = \frac{10}{0.45} \approx 20 \text{ m}\Omega$$

$$R_{err} \cdot C_{out} > \frac{T_{sw}}{2}$$

$$\frac{T_{sw}}{2} = 500 \text{ ns}$$

$$\begin{aligned} \text{Ker. cut} &= 20 \times 10^{-3} \times 10^{-5} \\ &= 2 \times 10^{-7} = 200 \text{ nJ} \end{aligned}$$