

Line Search \rightarrow Analysis

Recap \rightarrow

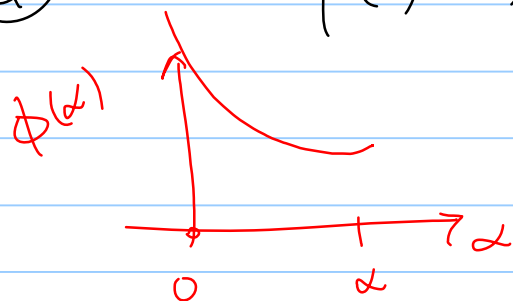
(1) Backtracking line search

Repeat until $\left[f(x_k + \alpha p_k) \leq f(x_k) + c_1 \alpha \nabla f_k^T p_k \right]$
 $\alpha \leftarrow \alpha \rho$, $\rho \in (0, 1)$

\nearrow at $\alpha = 0$

(2)

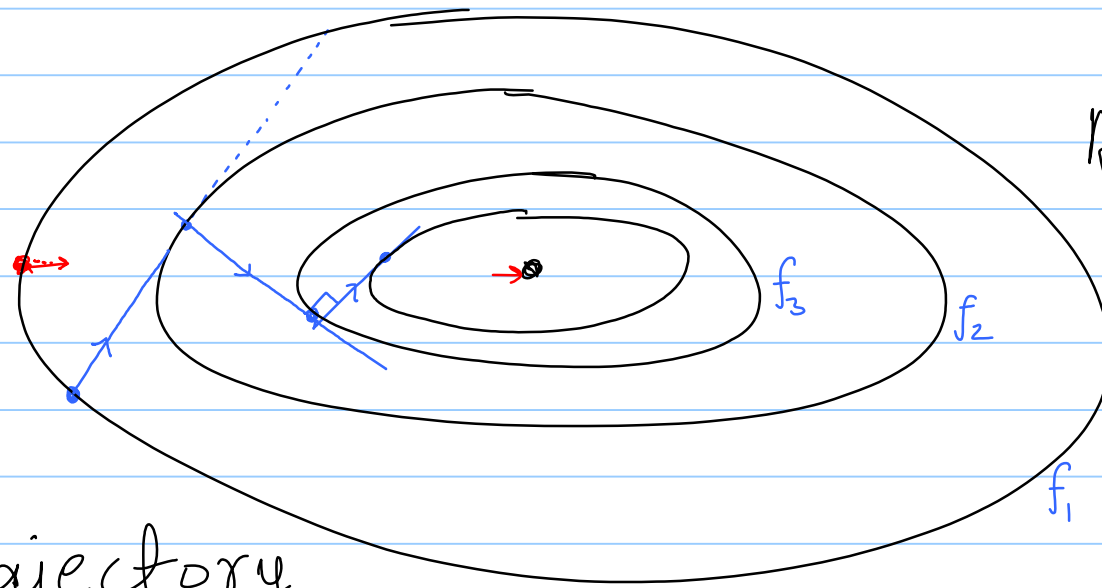
$\phi(\alpha) \rightarrow \phi(\alpha) \leftarrow$ Calculate pick any α



$\rightarrow \phi(0)$
 $\rightarrow \phi'(0)$

} fit a quadratic & minimize

Observe?



Assume $f_1 > f_2 > f_3$

$\hookrightarrow p_k \rightarrow -\nabla f_k$
(grad descent)
 \hookrightarrow Exact line searches

- ① Zig-zag trajectory
- ② step sizes are decreasing
- ③ Each step is \perp to previous step! \leftarrow

$$S_k = x_{k+1} - x_k \quad \text{①} \quad \#3 \rightarrow S_k^T S_{k+1} = 0$$

$$S_{k+2}^T S_{k+1} = 0$$

$$x_{k+1} = x_k + \alpha_k p_k \quad \text{①}$$

$$\Rightarrow S_k = \alpha_k p_k$$

$$\phi(\alpha) = f(x_k + \alpha p_k)$$

Exact line search

$$\frac{d\phi}{d\alpha} = \nabla f(x_k + \alpha p_k)^T p_k$$

$$\Rightarrow \frac{d\phi}{d\alpha} = 0$$

$$\Rightarrow \nabla f(x_k + \alpha_k p_k)^T p_k = 0 \quad \text{②}$$

$$p_{k+1} = -\nabla f_{k+1} = -\nabla f(x_k + \alpha_k p_k) \quad \text{③}$$

$$\Rightarrow S_{k+2}^T S_{k+1} = \alpha_{k+2} \alpha_{k+1} p_{k+1}^T p_k$$

$$= -\alpha_{k+2} \alpha_{k+1} \nabla f(x_k + \alpha_k p_k)^T p_k = 0$$

Convergence & Rate

Yes! Wherever I start \rightarrow I reach a stationary pt.

a) Define $\theta_k \rightarrow \cos \theta_k = \frac{-\nabla f_k^T P_k}{\|\nabla f_k\| \|P_k\|}$

$\theta_k = 0 \rightarrow$ Steepest descent.

$-90 < \theta_k < 90$ IN General

$$\cos \theta_k > 0$$

(b) Zoutendijk Condition. $x_{k+1} = x_k + \alpha_k P_k$

Satisfies Wolfe Conditions \downarrow descent $\textcircled{1}$
 dir

Conditions of the thm:

- $\hookrightarrow f_n$ should be bounded from below.
- $\hookrightarrow f$ is continuously differentiable
- \hookrightarrow the gradient of f is Lipschitz conts

$$\Rightarrow \|\nabla f(x) - \nabla f(y)\| \leq L \|x - y\| \quad \forall x, y \in \mathcal{N}$$

Then :

$$\sum_{j=0}^k \cos^2(\theta_j) \|\nabla f_j\|^2 < \infty$$

Curvature condition

$$-\nabla f_{k+1}^T P_k \leq -c_2 \nabla f_k^T P_k \quad \rightarrow$$

$$\nabla f(x_k + \alpha_k P_k)^T P_k \geq c_2 \underbrace{\nabla f(x_k)^T P_k}_{\text{Sub } \nabla f_k^T P_k}$$

$$\left[(\nabla f_{k+1} - \nabla f_k)^T P_k \right] \geq (c_2 - 1) \nabla f_k^T P_k \quad - (1)$$

Talk about Lipschitz. $\left[(\nabla f_{k+1} - \nabla f_k)^T P_k \right] \leq \|\nabla f_{k+1} - \nabla f_k\| \|P_k\|$

Combine (1) & (2)

$$L \alpha_k \|P_k\|^2 \geq (c_2 - 1) \nabla f_k^T P_k$$

$$\leq L \alpha_k \|P_k\|^2 \quad - (2)$$

$$\alpha_k \geq \left[\frac{c_2 - 1}{L} \frac{\nabla f_k^T P_k}{\|P_k\|^2} \right] \quad \text{--- (3)}$$

Sufficient decrease

$$\begin{aligned} \longrightarrow f_{k+1} &\leq f_k + c_1 \alpha_k \nabla f_k^T P_k \\ &\leq f_k + \frac{c_1 (c_2 - 1)}{L} \frac{(\nabla f_k^T P_k)^2}{\|P_k\|^2} \end{aligned}$$

$$\leq f_k - c \frac{(\nabla f_k^T P_k)^2}{\|P_k\|^2} \quad c = \frac{c_1 (1 - c_2)}{L}$$

$$f_{k+1} \leq f_k - c \cos^2 \theta_k \|\nabla f_k\|^2$$

Telescoping.

- f is bounded from below



$$f_{k+1} \leq f_0 - c \sum_{j=0}^k \cos^2 \theta_j \|\nabla f_j\|^2$$

$$\sum_{j=0}^k \cos^2 \theta_j \|\nabla f_j\|^2 < \infty$$

QED

⇓

$$\text{Corollary} \rightarrow \lim_{k \rightarrow \infty} \cos^2 \theta_k \|\nabla f_k\|^2 \rightarrow 0$$

$$P_k \text{ is a descent dir} \Rightarrow \cos \theta_k \neq 0$$

$$\Rightarrow \lim_{k \rightarrow \infty} \|\nabla f_k\| \rightarrow 0$$

i.e. a stationary point.