

# Matrix Computations

$$1) \quad A = U \Sigma V^T \begin{array}{l} \xrightarrow{\quad} n \times n \\ \swarrow \quad \searrow \\ m \times n \quad m \times m \quad m \times n \end{array}$$

Say  $m = n$

$$A^{-1} = (U \Sigma V^T)^{-1} = V \Sigma^{-1} U^T$$

Define:

$$A^+ = V \Sigma^+ U^T \begin{array}{l} \xrightarrow{\quad} n \times n \\ \swarrow \quad \searrow \\ n \times m \quad m \times m \end{array}$$

$$= \text{diag}(1/\sigma_i)$$

When  $\sigma_i \neq 0$ .

$$(\Sigma^+)_{ii} = \begin{cases} \frac{1}{\sigma_i}, & \sigma_i \neq 0 \\ 0 & \text{else} \end{cases}$$

When  $m > n$ .

$$\Sigma = \begin{bmatrix} \sigma_i \\ \vdots \\ 0 \end{bmatrix}, \quad \Sigma^+ = \begin{bmatrix} 1/\sigma_i \\ \vdots \\ 0 \end{bmatrix}$$

$$\Sigma \Sigma^+ = \begin{bmatrix} 1 & 0 \\ \vdots & \vdots \\ 0 & 0 \end{bmatrix}, \quad \Sigma^+ \Sigma = \begin{bmatrix} 1 & \vdots \\ \vdots & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & & \\ & \ddots & \\ & & 1 \\ & & & 0 \end{bmatrix}, \Sigma = \begin{bmatrix} 1 & & \\ & \ddots & \\ & & 1 \\ & & & 0 \end{bmatrix} = I.$$

$$AA^+ = (U\Sigma V^T)(V\Sigma^+ U^T) = U \Sigma \Sigma^+ U^T$$

$$A^+A = (V\Sigma^+ U^T)(U\Sigma V^T) = I.$$

$\Rightarrow A^+$  is the left inverse of  $A$ . when  $m > n$

$\Rightarrow A^+$  is the right inverse of  $A$  when  $m < n$ .

$$\hat{x} = \underbrace{(A^T A)^{-1}}_{n \times n} A^T b$$

$$A^T A = (V\Sigma^T U^T)(U\Sigma V^T) = V \underbrace{(\Sigma^T \Sigma)}_{\text{diag}(\sigma_i^2)} V^T$$

$$(U^T)^{-1} \quad (V^T)^{-1} \quad T$$

$$\Rightarrow (A^T A)^{-1} = V \underbrace{(\Sigma^T \Sigma)^{-1}}_{\text{diag}(1/\sigma_i^2)} V^T$$

$$\begin{aligned} (A^T A)^{-1} A^T &= \left( V \underbrace{(\Sigma^T \Sigma)^{-1}}_{\text{diag}(1/\sigma_i^2)} V^T \right) \left( V \Sigma^T U^T \right) \\ &= V \underbrace{\Sigma^+}_{n \times m} U^T \end{aligned}$$

$$Ax = b \rightarrow x = A^+ b$$

2)

"Condition number"

$$Ax = b \quad \text{--- ①}$$

$$A(x + \Delta x) = b + \Delta b \quad \text{--- ②}$$

due to errors

$$[ A \Delta x = \Delta b \Rightarrow \Delta x = A^{-1} \Delta b ]$$

Quantify error by  $\| \cdot \|_2$

$$\text{Define: } \kappa = \frac{\| \Delta x \|}{\| x \|} = \frac{\| A^{-1} \Delta b \|}{\| \Delta b \|} \times \frac{\| b \|}{\| A^{-1} b \|}$$

$$\frac{\| A^{-1} \Delta b \|_2^2}{\| \Delta b \|_2^2} = \frac{\| V \Sigma^{-1} U^T \Delta b \|_2^2}{\| \Delta b \|_2^2} = \frac{\| \Sigma^{-1} U^T \Delta b \|_2^2}{\| \Delta b \|_2^2}$$

$$= \frac{\sum_i \left( \frac{1}{\sigma_i^2} \right) y_i^2}{\sum y_i^2}$$

$$z = U^T b$$

$$\frac{\|A b\|}{\|b\|^2} = \frac{\sum_i \left( \frac{1}{\sigma_i^2} \right) z_i^2}{\sum z_i^2}$$

$$\sum_i \left( \frac{1}{\sigma_i^2} \right) \left( \frac{y_i^2}{\sum y_i^2} \right) = \sum \left( \frac{1}{\sigma_i^2} \right) \eta_i$$

$$\sum \eta_i = 1$$

$$\eta_i \geq 0$$

$$K^2 = \frac{\sum \left( \frac{1}{\sigma_i^2} \right) \left[ \frac{y_i^2}{\sum y_i^2} \right]}{\sum \left( \frac{1}{\sigma_i^2} \right) \left[ \frac{z_i^2}{\sum z_i^2} \right]}$$

→ MAX  
→ MIN

same form

$$\left( \frac{1}{\sigma_{\max}^2} \right) \sum \eta_i \leq \sum \left( \frac{1}{\sigma_i^2} \right) \eta_i \leq \left( \frac{1}{\sigma_{\min}^2} \right) \sum \eta_i$$

$\hat{v}$   
1

$$\kappa = \left( \frac{\sigma_{\max}}{\sigma_{\min}} \right) = \frac{\sigma_1}{\sigma_r} \quad \text{Condition no of } A.$$

e.g.  $A = \begin{pmatrix} 1 & 1000 \\ 0 & 1 \end{pmatrix}, \quad \lambda = 1, 1$

$$A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{Orig.} \quad A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 0.01 \end{pmatrix} \quad \text{New}$$

Soln:  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$

Soln:  $\begin{pmatrix} -9 \\ 0.01 \end{pmatrix}$

$$\sigma = 10^3, 10^{-3} \Rightarrow \kappa = 10^6$$

Convention  $\kappa \geq 10^4 \rightarrow A$  is ill conditioned.

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$$Ax = b \rightarrow \kappa(A)$$

$$A^T A x = A^T b$$

$$\text{SVD } (A^T A) : (V \Sigma^T U^T) (U \Sigma V^T)$$

$$= (V \underbrace{\Sigma^T \Sigma}_{\sigma_i^2} V^T)$$

bad condn no became worse.

$$\hookrightarrow A = \sum_{i=1}^r \sigma_i u_i v_i^T \quad \leftarrow \quad \underline{A = U \Sigma V^T}$$

$$A x = b \quad \rightarrow \quad \hat{x} = A^+ b$$

$V \Sigma U^T$

$$= \sum_{i=1}^r \frac{1}{\sigma_i} v_i u_i^T$$

$$\Rightarrow \hat{x} = \sum_{i=1}^d \left( \frac{u_i^T b}{\sigma_i} \right) v_i$$

scalar vector

$\Rightarrow$  Smallest  $\sigma_i$  has max influence on soln.

$\rightarrow$  Truncated SVD  $d$  is  $\leq r$

$$\Rightarrow \hat{x} = \sum_{i=1}^d \left( \frac{u_i^T b}{\sigma_i} \right) v_i$$

Choosing  $d$  like cooking!

$\hookrightarrow$  (2) Tikhonov regularization.

$$\hat{x} = \sum_{i=1}^r (u_i^T b) \left( \frac{\phi_i}{\sigma_i^2 + \lambda^2} \right) v_i$$