

AAC - Feature #4032

Development Model-Based Digital Twin and Torque Vectoring Control for Three-Wheeler EV

02/19/2026 01:23 PM - DEV YADAV

Status:	New	Start date:	02/19/2026
Priority:	High	Due date:	05/01/2026
Assignee:	DEV YADAV	% Done:	0%
Category:		Estimated time:	0:00 hour
Target version:		Spent time:	0:00 hour
Description			