

Optimization - Review of Calculus.

↳ Derivative of a function

$$f'(x) = \lim_{y \rightarrow 0} \frac{f(x+y) - f(x)}{y}$$

$x, y \in \mathbb{R}$

→ $\lim_{y \rightarrow 0} \left[\frac{f(x+y) - f(x) - y f'(x)}{y} \right] = 0$

Go to $x, y \in \mathbb{R}^n$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix}_{n \times 1}$$

Col vector.

↳ Define ∇f : $\lim_{\|y\| \rightarrow 0} \left[\frac{f(x+y) - f(x) - \nabla f^T y}{\|y\|} \right] = 0$

If ∇f exists s.t. \uparrow holds the ∇f is called the Frechet derivative of f . —

$$\nabla f \rightarrow \nabla_z f$$

↳ If ∇f exists $\forall x \in \text{dom} f$. \rightarrow f is differentiable.
 \rightarrow If ∇f is a continuous fn \rightarrow f is continuously differentiable.

$$\hookrightarrow f: \mathbb{R}^n \rightarrow \mathbb{R}^{(m)}$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$\nabla f \rightarrow$ Jacobian:

$$J \in \mathbb{R}^{m \times n}$$

$$J_{ij} = \frac{\partial f_i}{\partial x_j}$$

$$\begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \dots & \dots & \frac{\partial f_m}{\partial x_n} \end{bmatrix}_{m \times n}$$

\hookrightarrow Chain rule

$x(t)$ & $y(x)$

$$\frac{dy}{dt} = \frac{d}{dt} y(x(t))$$

Scalar case.

$$= \frac{dy}{dx} \cdot \frac{dx}{dt}$$

$$\hookrightarrow x \in \mathbb{R}^n$$

$$h(t) = f(x(t))$$

$$\nabla h(t) = \frac{\partial f}{\partial x_1} \frac{\partial x_1}{\partial t} + \frac{\partial f}{\partial x_2} \frac{\partial x_2}{\partial t} + \dots + \frac{\partial f}{\partial x_n} \frac{\partial x_n}{\partial t}$$

$$= (\nabla f)^T \Delta x$$

e.g.

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$f(u, v, w) = uv + vw - uw$$

$$g: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$g(x, y) = (x+y, x+y^2, x^2+y)$$

$$\mathbb{R}^2 \rightarrow \mathbb{R}$$

$$\nabla (f \circ g)(x, y) ?$$

$$f(g(x, y))$$

$$= f(u(x, y), v(x, y), w(x, y))$$

$$\nabla (f \circ g) = \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \end{bmatrix}$$

$$\begin{bmatrix} \frac{\partial f \circ g}{\partial x} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial x} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial x} + \frac{\partial f}{\partial w} \frac{\partial w}{\partial x} \\ \frac{\partial f \circ g}{\partial y} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial y} + \dots \dots \dots \end{bmatrix}$$

$$\frac{\partial f}{\partial u} = v - w$$

$$= x + y^2 - (x^2 + y)$$

$$\frac{\partial u}{\partial x} = 1$$

↳ Quadratic form $\phi(x): \mathbb{R}^n \rightarrow \mathbb{R}$

$$\phi(x) = x^T A x + b^T x + c$$

Claim is $\nabla \phi(x) = (A^T + A)x + b$ ✓

Proof:

$$\nabla(b^T x)$$

$$\nabla(\sum b_j x_j)$$

$$\begin{bmatrix} \uparrow \\ \frac{\partial}{\partial x_i} \\ \downarrow \end{bmatrix}$$

$$= \begin{bmatrix} b_1 \\ \vdots \\ b_i \\ \vdots \\ b_n \end{bmatrix} = b$$

$$\begin{bmatrix} \frac{\partial}{\partial x_1} \\ \frac{\partial}{\partial x_2} \\ \vdots \\ \frac{\partial}{\partial x_n} \end{bmatrix}$$

↳ $\frac{d}{dx} f \cdot g = f'g + fg'$ prod rule.

Now $\underbrace{x^T A x}$

Aside: prod rule

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$f(x) = g^T(x) h(x)$$

$$, g, h \in \mathbb{R}^{n \times 1}$$

$$g: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$\nabla g = \begin{bmatrix} \overline{\nabla g_i^T} \\ \vdots \\ \vdots \end{bmatrix}$$

$$g = \begin{bmatrix} g_1(x) \\ g_2(x) \\ \vdots \\ g_n(x) \end{bmatrix}$$

$$\nabla f \rightarrow \frac{\partial f}{\partial x_i} = \frac{\partial}{\partial x_i} \left[\sum_j g_j(x) h_j(x) \right]$$

$$= \sum_j \left[\underbrace{\frac{\partial}{\partial x_i} g_j(x) h_j(x)}_{i^{\text{th}} \text{ col of } \nabla g} + g_j(x) \underbrace{\frac{\partial}{\partial x_i} h_j(x)}_{i^{\text{th}} \text{ col of } \nabla h} \right]$$

$$\frac{\partial f}{\partial x_i} = h^T (\nabla g)_{i^{\text{th}} \text{ col}} + g^T (\nabla h)_{i^{\text{th}} \text{ col}}$$

$$\left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_n} \right) = h^T \nabla g + g^T \nabla h = \nabla f^T$$

$$\nabla f = \nabla g^T h + \nabla h^T g$$

prod rule
where $f = g^T h$

$$(AB)^T = B^T A^T$$

$$\hookrightarrow \nabla \left(\underbrace{x^T}_g \underbrace{Ax}_h \right) = \underbrace{(\nabla x)^T}_I Ax + (\nabla Ax)^T x = Ax + A^T x$$

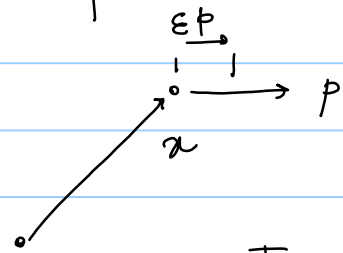
$$\nabla(Ax) = A$$

$$(Ax)_i = \sum_j A_{ij} x_j$$

$$\Rightarrow \nabla \phi(x) = (A + A^T)x + b$$

↳ Directional derivative: → direction ' \hat{p} '

$$D(f(x), p) = \lim_{\varepsilon \rightarrow 0} \frac{f(x + \varepsilon p) - f(x)}{\varepsilon}$$



When f is continuously differentiable: $D(f(x), p) = \nabla f^T p$

↳ Defn: Hessian matrix $f: \mathbb{R}^n \rightarrow \mathbb{R}$

$$\nabla^2 f(x) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \dots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \dots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \dots & \frac{\partial^2 f}{\partial x_n^2} \end{bmatrix}_{n \times n}$$

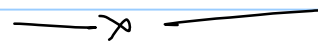
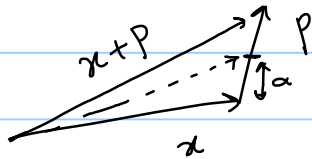
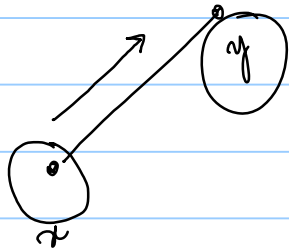
↳ Mean Value Theorem : $f: \mathbb{R} \rightarrow \mathbb{R}$ and $x, y \in \mathbb{R}$ s.t.

$$\text{MVT} \rightarrow f(y) = f(x) + f'(z)(y-x) \quad \begin{matrix} x < y \\ z \in (x, y) \end{matrix}$$

Extend this to $f: \mathbb{R}^n \rightarrow \mathbb{R}$

$$f(x+p) = f(x) + \overbrace{\nabla f(x+\alpha p)}^T p$$

$$\alpha \in (0, 1)$$



$$x + \alpha p \rightarrow \begin{matrix} \alpha = 0 \rightarrow x \\ \alpha = 1 \rightarrow x + p \end{matrix}$$