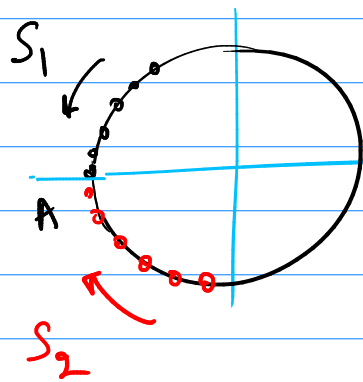


Context \rightarrow Bring algebra & geometry into sync.
 "Tangent Cone"

\hookrightarrow ① Feasible sequence: Given an $x \in \Omega$
 $\{z_k\}$ is a F.S. if

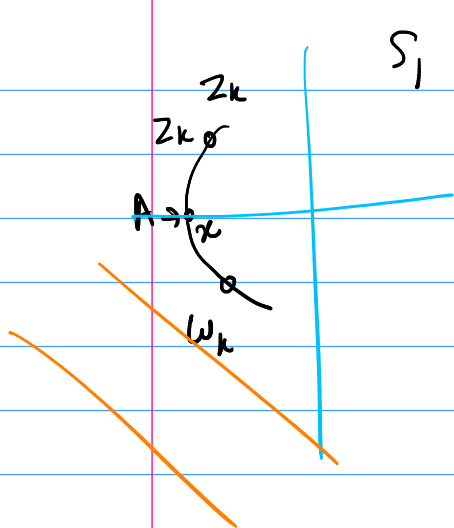
a) $z_k \in \Omega$	} for large k . $k \gg 1$.
b) $z_k \rightarrow x$	



$$f(x) = x_1 + x_2, \quad C_1(z) = x_1^2 + x_2^2 - 2 = 0$$

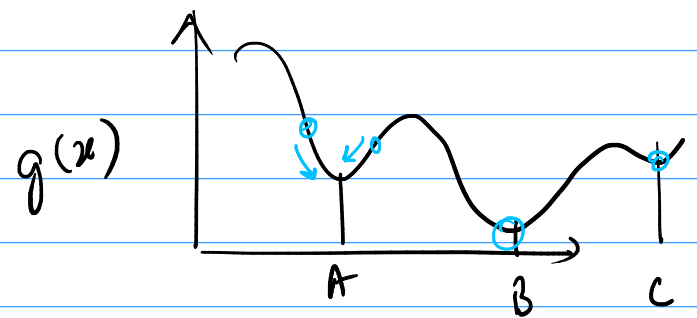
$$S_1 = \begin{bmatrix} -\sqrt{2 - 1/k^2} \\ 1/k \end{bmatrix}, \quad S_2 = \begin{bmatrix} -\sqrt{2 - 1/k^2} \\ -1/k \end{bmatrix}$$

② Local minimizer \rightarrow A point x at which all feasible sequences satisfy $f(x) \leq f(z_k)$
 \rightarrow Large k .

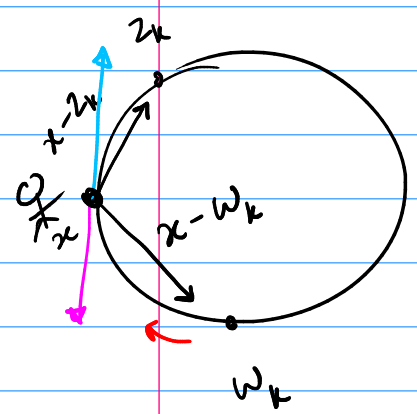


$$S_1 \rightarrow \{z_k\}, \quad S_2 \rightarrow \{w_k\}, \quad f(x) = x_1 + x_2$$

$$\left. \begin{aligned} f(x) &\leq f(z_k) \\ f(x) &\geq f(w_k) \end{aligned} \right\} \Rightarrow A \text{ is not a } \text{local minimizer.}$$



③ Tangent \rightarrow A limiting direction of a F.S.



In addition to $\{z_k\}$, I define a ⁺ve scalar $\{t_k\} \rightarrow$ has a property $\lim_{k \rightarrow \infty} t_k = 0$

$d = \lim_{k \rightarrow \infty} \frac{x - z_k}{t_k}$, $t_k = \|z_k - x\|_2$ ✓

↳ Tangent Cone: Set of all tangents to Ω at a feasible point x , is called the T.C.

$T_{\Omega}(x)$. At A , we have $T_{\Omega}(x) = \begin{bmatrix} 0 \\ d_2 \end{bmatrix}$,

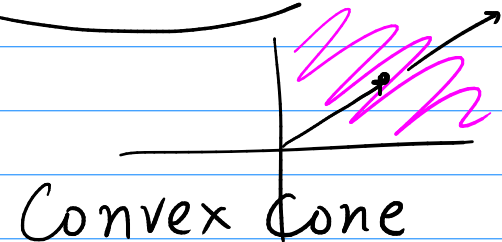
$d_2 \in \mathbb{R}$.

Aside

Cone:

A set M . s.t. $\forall x \in M, \alpha x \in M \forall \alpha > 0$

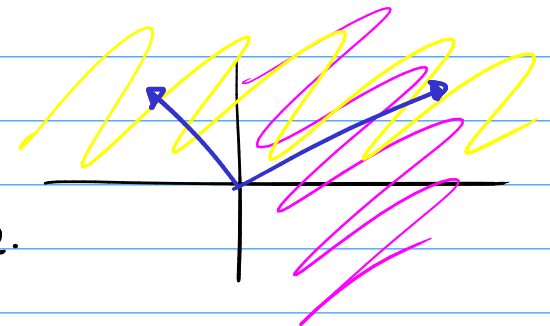
eg. 1) $\left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mid x_1 > 0, x_2 > 0 \right\}$



Convex Cone

eg. 2) $\left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mid x_1 \geq 0 \text{ OR } x_2 \geq 0 \right\}$

nonconvex cone.



↳ Tangent cone?

Say $d \in T_{\Omega}(x)$, then

$$\boxed{\alpha d \in T_{\Omega}(x)}$$

$$d = \lim_{k \rightarrow \infty} \frac{z_k - x}{t_k}$$

$t_k \rightarrow 0$
 $t_k \rightarrow 0$ for large k .

$$t'_k = t_k / \alpha$$

$\rightarrow \alpha d$.

↳ Defn: LICQ: Linear independence ^{defn}

constraint qualification:

Given a feasible pt x & the active constraint set $A(x)$,

we say that LICQ holds if the set of active constraint gradients $\{\nabla C_i(x) \mid i \in A(x)\}$ is linearly indepⁿ.

↳ Reln between algebra & geometry

Linearized feasible directions

Tangent cone

Following are true:

① $T_{\Omega}(x) \subset \mathcal{F}(x)$

② If LICQ holds $T_{\Omega}(x) = \mathcal{F}(x)$

$\nabla c_1 = \begin{pmatrix} 2x_1 \\ 2x_2 \end{pmatrix}$

NW 12.2

~~LICQ~~

$\mathcal{F}(x) = \begin{pmatrix} 0 \\ d_2 \end{pmatrix}$

$\nabla c_1 = \begin{pmatrix} -2\sqrt{2} \\ 0 \end{pmatrix}$

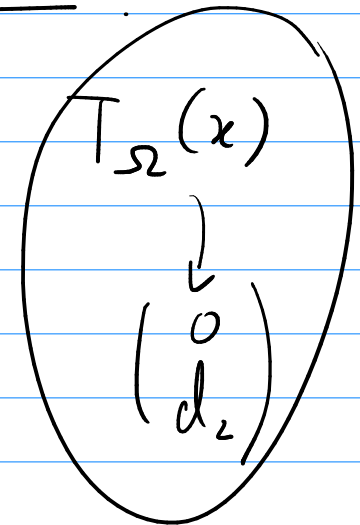
$c_1(x) = x_1^2 + x_2^2 - 2 = 0$
 $c_1'(x) = \begin{pmatrix} \quad \quad \quad \end{pmatrix}^T = 0$

$\mathcal{F}(x) = \begin{pmatrix} d_1 \\ d_2 \end{pmatrix}$

$\nabla c_1' = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

× LICQ.

$\sum_{i=1}^N \alpha_i v_i = 0$
 $\alpha_i v_i = 0$
 only $\alpha_1 = 0$



↳ First order Necessary Conditions (FONC)
Karush Kuhn Tucker (KKT) Conditions.

As before
$$\mathcal{L}(x, \lambda) = f(x) - \sum_i \lambda_i c_i(x)$$

$$i \in E \cup I.$$

- If
- ① If x^* is a local soln to $\min_{x \in \Omega} f(x)$.
 - ② f and c_i 's are continuously differentiable
 - ③ LICQ holds at x^*

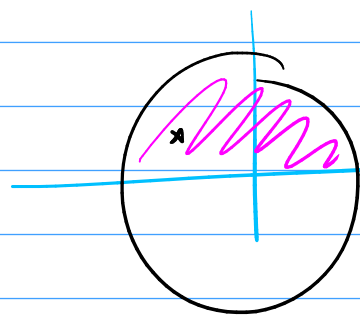
Then: There is a set of Lagrange multipliers s.t. the foll are satisfied at (x^*, λ^*) :

- a) $\nabla_x \mathcal{L}(x^*, \lambda^*) = 0$
- b) $c_i(x^*) = 0, i \in E$
- c) $c_i(x^*) \geq 0, i \in I$
- d) $\lambda_i \geq 0, i \in I$
- e) $\lambda_i c_i = 0, i \in E \cup I$

There can be many pts where a-e hold. But if ③ holds x^* is unique.

↳ Proof sketch.

$$f(x) = x_1 + x_2 \quad \text{s.t.} \quad \begin{aligned} 2 - x_1^2 - x_2^2 &\geq 0 \\ x_2 &\geq 0 \end{aligned}$$



FONC for x^* to be a local min

$$1) \quad C_1(x^*) \geq 0, \quad C_2(x^*) \geq 0$$

2) a) If $C_1(x^*) = 0, C_2(x^*) = 0$, then

$$\nabla_x \mathcal{L} = \nabla f(x^*) - \lambda_1 \nabla C_1 - \lambda_2 \nabla C_2 = 0, \quad \lambda_1 \geq 0, \lambda_2 \geq 0$$

b) $C_1(x^*) > 0, C_2(x^*) = 0$, then $\Rightarrow \lambda_1 = 0$

$$\nabla_x \mathcal{L} = \nabla f(x^*) - \lambda_2 \nabla C_2(x^*) = 0, \quad \lambda_2 \geq 0.$$

c) $C_1(x^*) = 0, C_2(x^*) > 0$, then $\Rightarrow \lambda_2 = 0$

$$\nabla_x \mathcal{L} = \nabla f(x^*) - \lambda_1 \nabla C_1(x^*) = 0, \quad \lambda_1 \geq 0$$

d) $C_1(x^*) > 0, C_2(x^*) > 0$, then $\lambda_1 = 0, \lambda_2 = 0$

$$\nabla_x \mathcal{L} = \nabla f(x^*) = 0$$