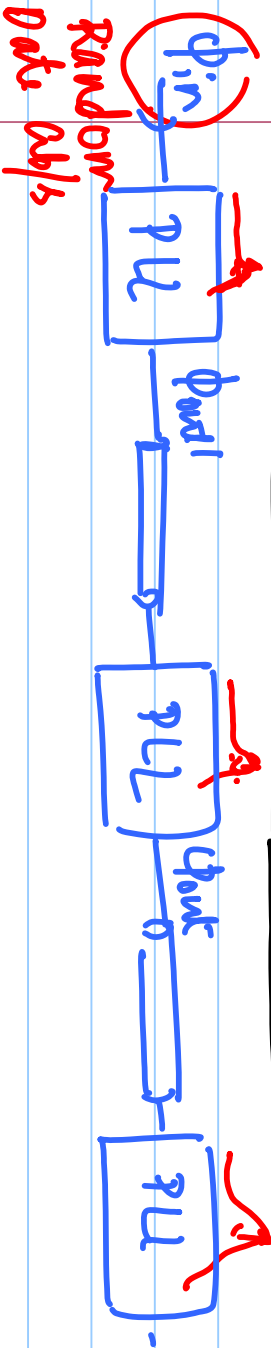
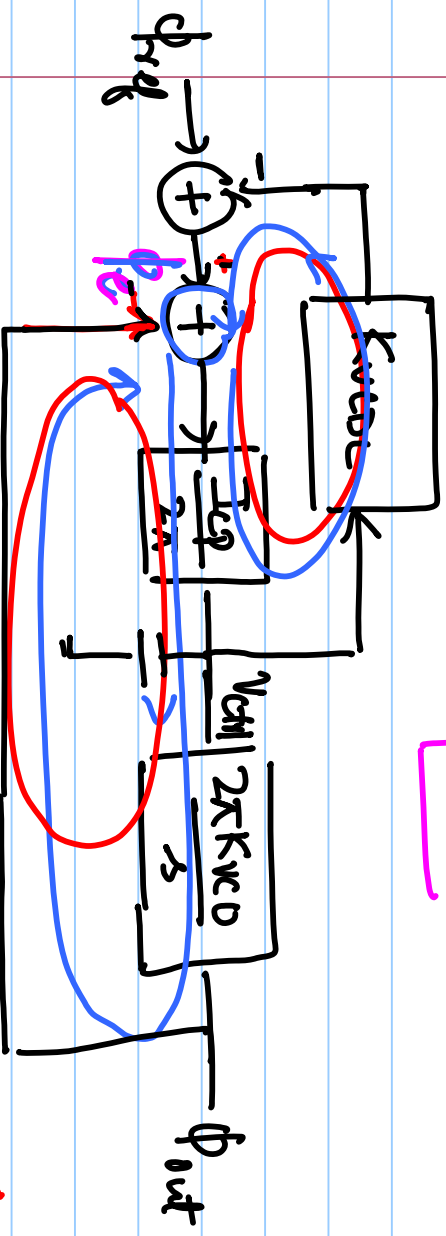
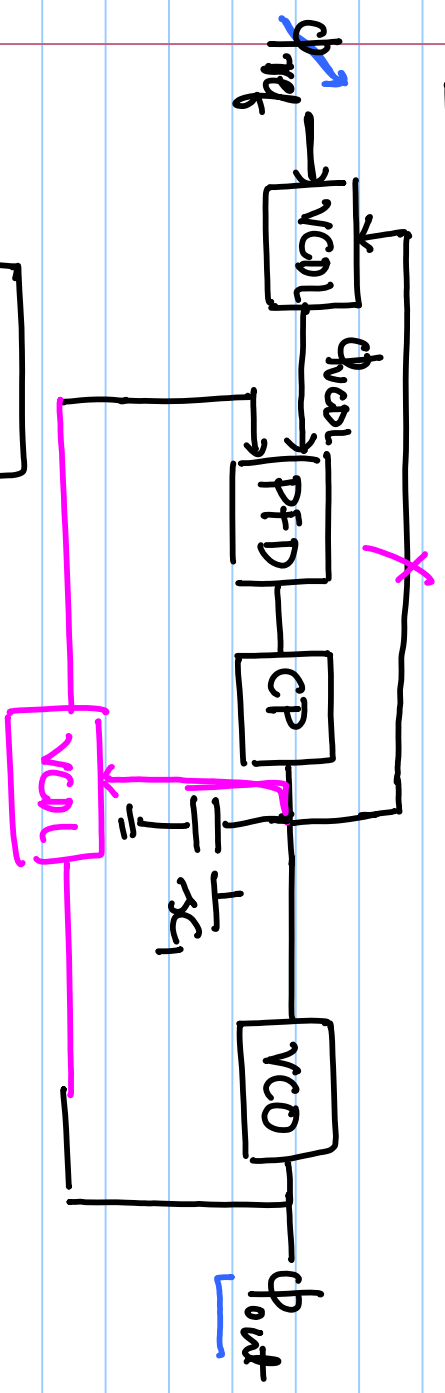


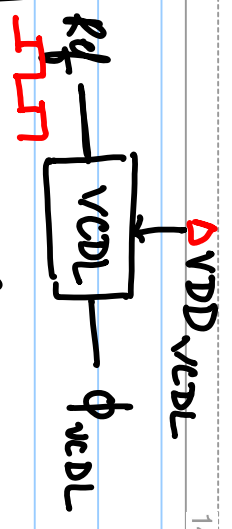
Lecture # 34

$$V_{out} = V_{OS} (\omega_0 t + \alpha_m \sin(\omega_0 t - 1))$$

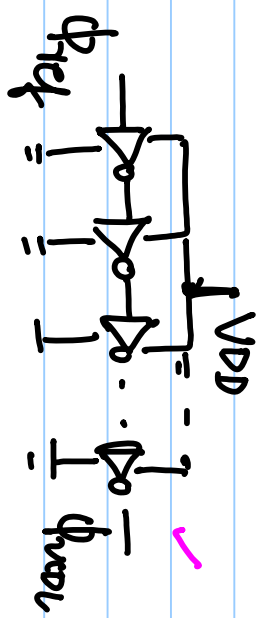


$$(\phi_{req} - K_{VCO1} \cdot V_{ctrl} - \phi_{out}) \frac{I_{CP}}{2\pi} \times \frac{1}{sC_1} = V_{ctrl}$$

$$V_{ctrl} = \frac{2\pi K_{VCO}}{s} \phi_{out} \quad (2)$$



$$\phi_{VCO} = \phi_{req} + K_{VCO} \cdot \Delta V_{DD}$$



$$\Delta \omega = \frac{I_{CP}}{2\pi} \frac{2\pi K_{VCO}}{s} \times \frac{1}{sC_1}$$

$$(1) \quad + \frac{I_{CP}}{2\pi} \frac{1}{sK_1}$$

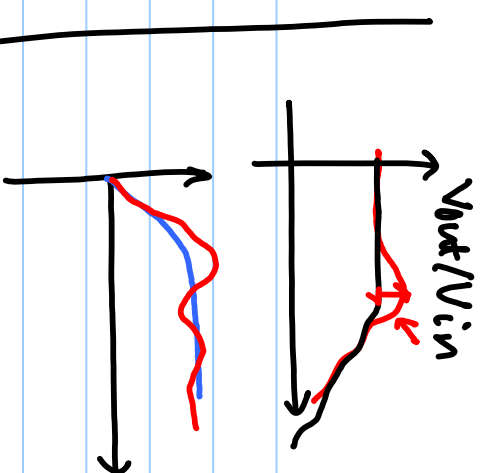
$$\Rightarrow V_{out} = \frac{s \phi_{out}}{2\pi K_{vco}}$$

$$(\phi_{req} - \phi_{out}) = \left(\frac{2\pi s C_1}{I_{cp}} + K_{vco} \right) \frac{s \phi_{out}}{2\pi K_{vco}}$$

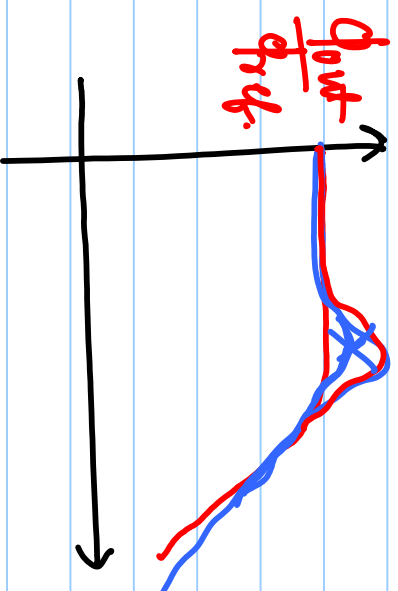
$$= \left(\frac{s^2 C_1}{I_{cp} \cdot K_{vco}} + \frac{s K_{vco}}{2\pi K_{vco}} \right) \phi_{out}$$

$$\frac{\phi_{out}}{\phi_{req}} = \frac{1}{1 + s \left(\frac{K_{vco}}{2\pi K_{vco}} + \frac{s^2 C_1}{I_{cp} K_{vco}} \right)}$$

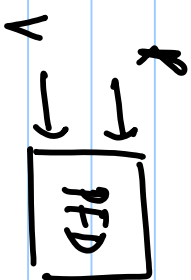
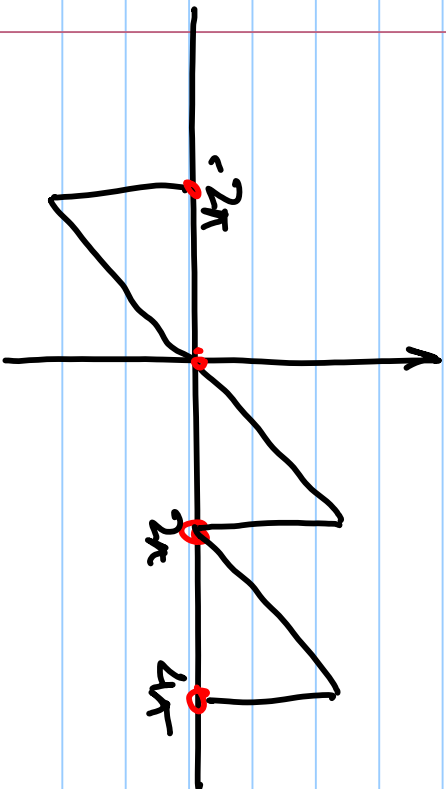
$$= \frac{1}{1 + s \left(\frac{K_{vco}'}{K_{vco}} + \frac{s C_1}{I_{cp} K_{vco}} \right)}$$



$$K_{vco} = 2\pi K_{vco}'$$



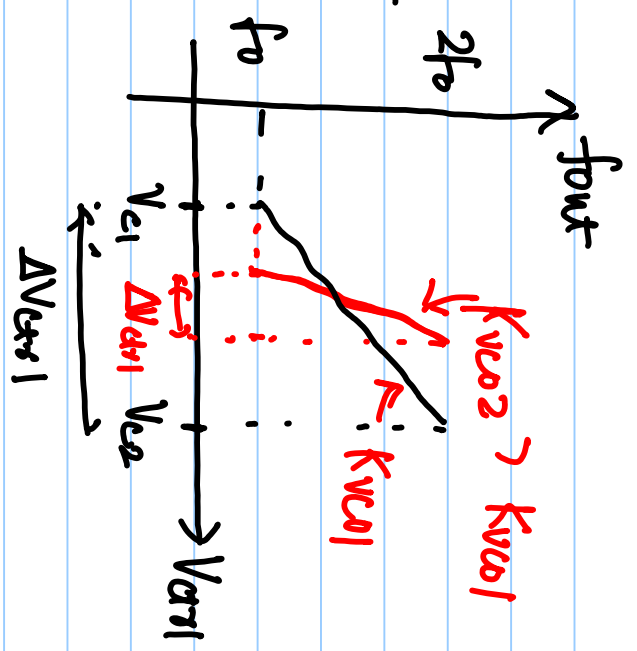
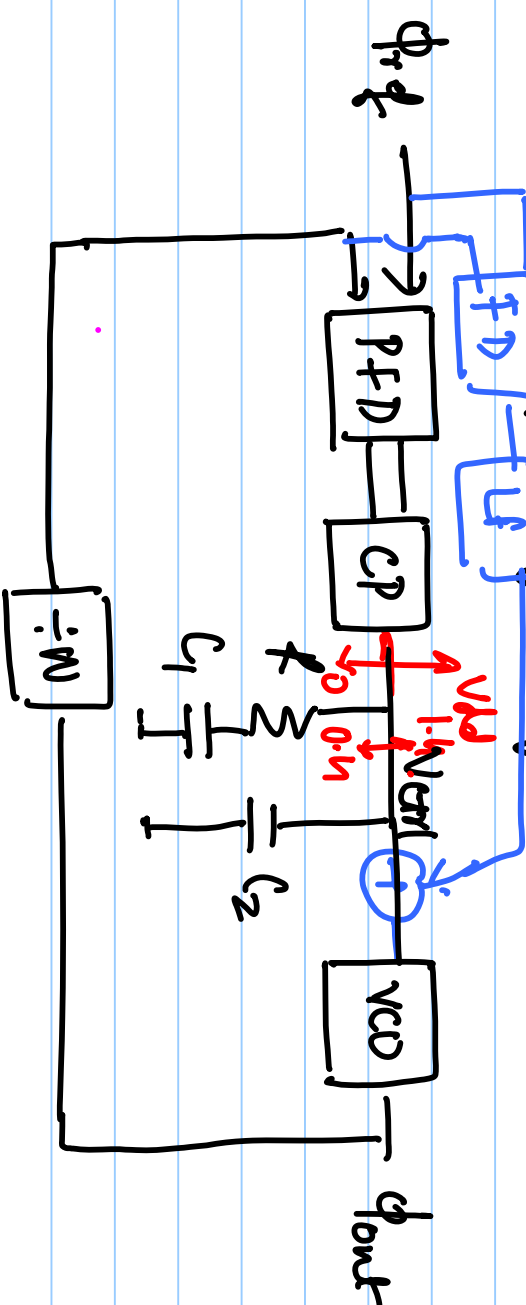
$$\begin{aligned}
 \omega_0 &= \frac{I_{CP}}{2\pi} \frac{2\pi K_{VCO}}{\Delta} + \frac{I_{CP}}{2\pi} \frac{1}{\Delta} 2\pi K_{VCO}' \\
 &= \frac{I_{CP}}{\Delta C_1} (K_{VCO} + \Delta K_{VCO}')
 \end{aligned}$$



$$\omega_{2\pi} \leq K_{VCO} \times \Delta \leq 2\pi \quad \text{w.r.t } T_{req}$$

Tunable delay, $\Delta t_d = \pm T_{req}$.

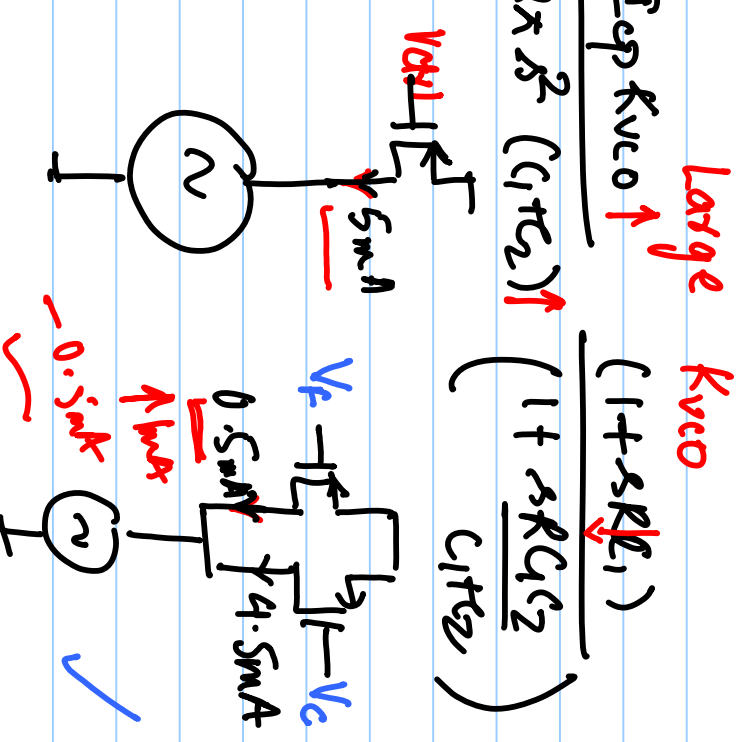
Wide-output frequency range PLL



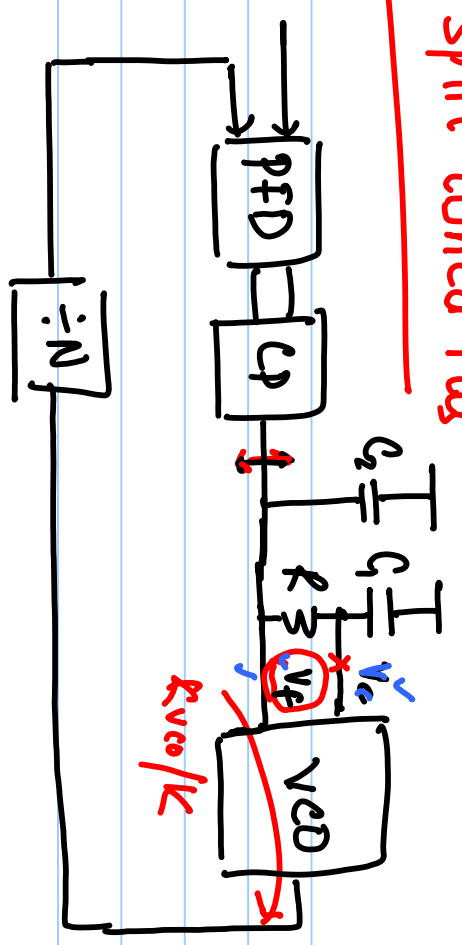
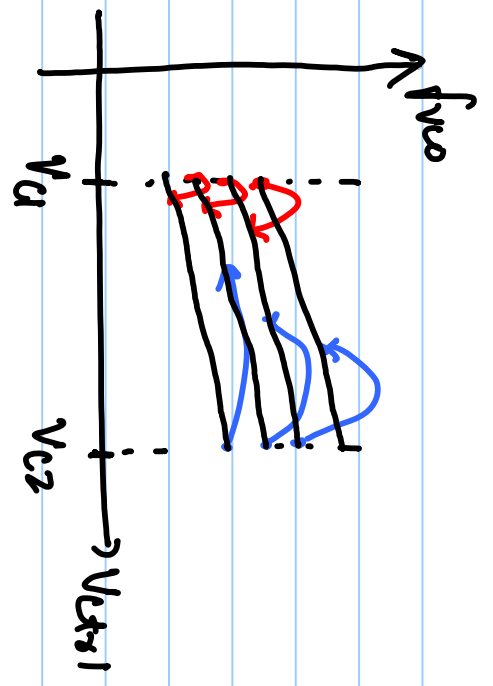
$$L_u = \frac{I_{cp} K_{vco}}{2\pi} \frac{s + \frac{1}{RC_1}}{s^2 C_2 \left(s + \frac{1}{RC_2} \right)} = \frac{I_{cp} K_{vco}}{2\pi s^2 (C_1 C_2)} \frac{(1 + sRC_1)}{(1 + sRC_2)}$$

$K_{vco} \uparrow \Rightarrow I_{cp} \downarrow \Rightarrow \text{Increase Noise}$

$K_{vco} \uparrow \Rightarrow S_{Vc}^2 \propto K_{vco}^2$



Split-tuned PLLs



$$L_u = \frac{I_{cp}}{2\pi} f(s) \frac{K_{vco}/k}{s} + \frac{I_{cp}}{2\pi} f(s) \frac{(K+1)K_{vco}}{s}$$

$$\underbrace{V_f}_{\text{control}} \times \frac{Y_{sc1}}{sC_1 + R_1}$$

$$F(s) = \frac{1}{s + 1/R_1}$$

$$sC_2 \left(s + \frac{1}{4C_1C_2} \right) \frac{1}{C_1R_2}$$

$$L_u = \frac{I_{cp}}{2\pi} f(s) \frac{K_{vco}/k}{s} \left(1 + \frac{k-1}{1+sR_1C_1} \right)$$

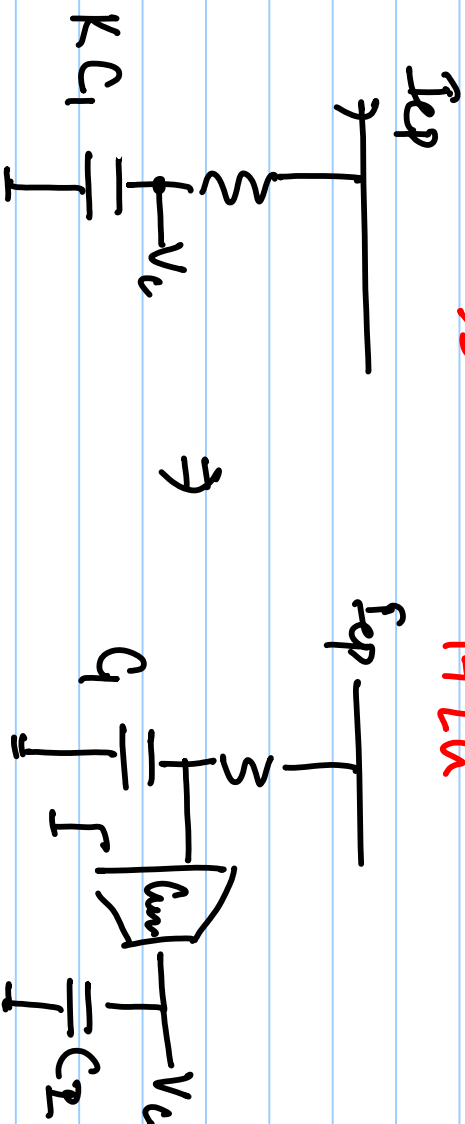
$$= \frac{K I_{cp}}{2\pi} \frac{K_{vco}}{s^2 R_1 C_1 R_2} \frac{(1+sR_1C_1/k)}{(1+sR_1C_1/k)}$$

$$\omega_z = \frac{1}{RC_1/k} \quad , \quad \omega_{p1} = \omega_{p2} = 0 \quad , \quad \omega_{p3} = \frac{1}{RC_2} \frac{1}{C_1 k_2}$$

$$k_h = \frac{I_{ep}}{2k} \frac{K_{vco}}{s^2(C_1 + C_2)} \frac{(1 + sRC_1)}{\left(1 + sR \frac{KC_1 C_2}{kC_1 + k_2}\right)}$$

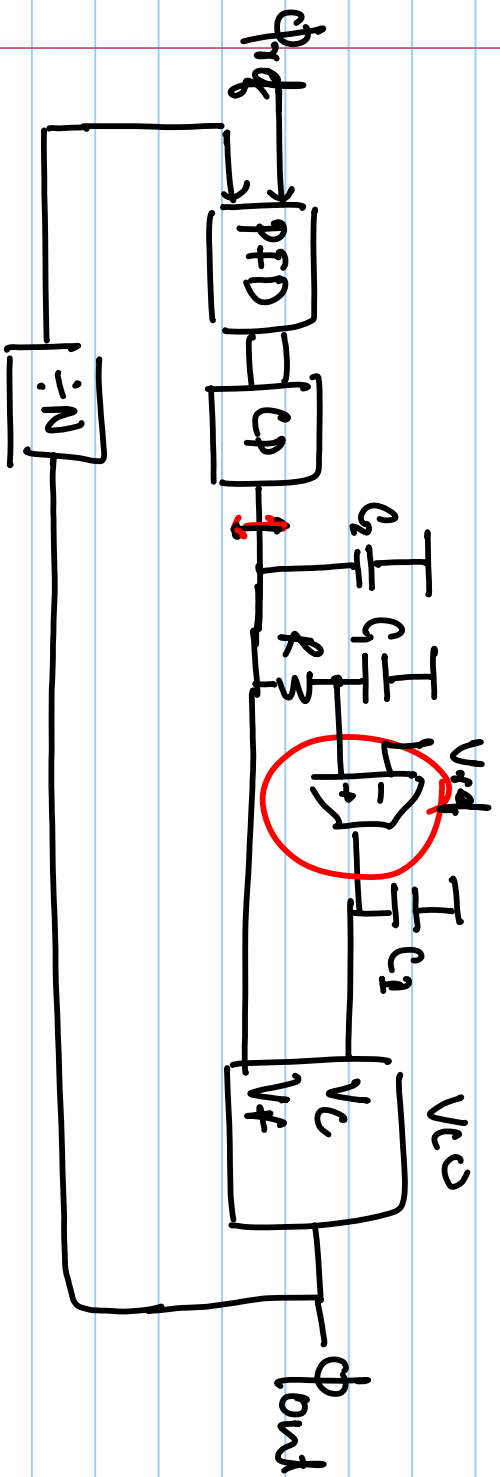
$V_c, V_f:$
 $C_1 \rightarrow kC_1$
 $I_{ep} \rightarrow kI_{ep}$

$$NTF_R = \frac{(K_{vco}/k)}{s} \frac{1}{1 + L\omega}$$



$$V_c = \frac{I_{ep}}{s(kC_1)}$$

$$V_c = \frac{I_{ep}}{sC_1} \times k_{um} \times \frac{1}{sC_2} = \frac{I_{ep}}{s^2 C_1 \left(\frac{C_2}{k_{um}}\right)}$$



$$K_{VCO} = \frac{I_{ep}}{2\pi N} \frac{K_{VCO}^F}{s^2(C_1\tau_2)} \frac{1+sR_1C_1}{1+sR_1C_2/C_1\tau_2}$$

$$L_{fc} = \frac{I_{ep}}{2\pi N} \frac{K_{VCO}^C}{s^2(C_1\tau_2)} \frac{1}{1+sR_1C_2/C_1\tau_2} \times \frac{G_m}{sC_I}$$

$$L_{CL} = K_{VCO} + L_{VCO} = \frac{I_{ep}}{2\pi N} \frac{1}{s^2(C_1\tau_2)} \frac{1}{\underbrace{\frac{1}{C_1\tau_2}}_{\left[K_{VCO}^F(1+sR_1C_1) + K_{VCO}^C \frac{G_m}{sC_I} \right]}}$$

$$\frac{K_{vcd}^c (1 + sRC_1) + K_{vcd}^c \frac{C_m}{sC_2}}{sC_2^2}$$

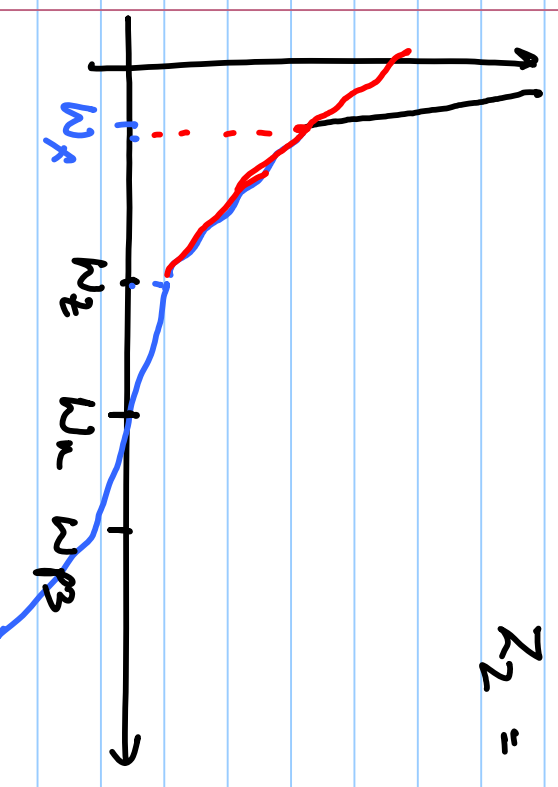
$$s K_{vcd}^f C_2 + s^2 RC_1 C_2 K_{vcd}^f + K_{vcd}^c C_m$$

$$K_{vcd}^f RC_1 C_2 s^2 + K_{vcd}^f C_2 s + K_{vcd}^c C_m$$

$$z_1 = - \frac{K_{vcd}^f C_2}{K_{vcd}^f RC_1 C_2} = - \frac{1}{RC_1}$$

$$z_2 = - \frac{K_{vcd}^c C_m}{K_{vcd}^f RC_1 C_2} \quad * RC_1 = - \frac{K_{vcd}^c C_m}{K_{vcd}^f C_2}$$

ω_p



$$\omega_x \ll \omega_z$$

$$\frac{K_{vcd}^c C_m}{K_{vcd}^f C_2} \ll \frac{1}{RC_1}$$

