

$$\Delta v_{out,dm} = a_0 + \sum a_n \cos(n\omega_c t) + b_n \sin(n\omega_c t)$$

$$a_n = \frac{1}{n\pi} I_{DQ} \sin\left(n\pi \frac{T_{OS}}{T_R}\right)$$

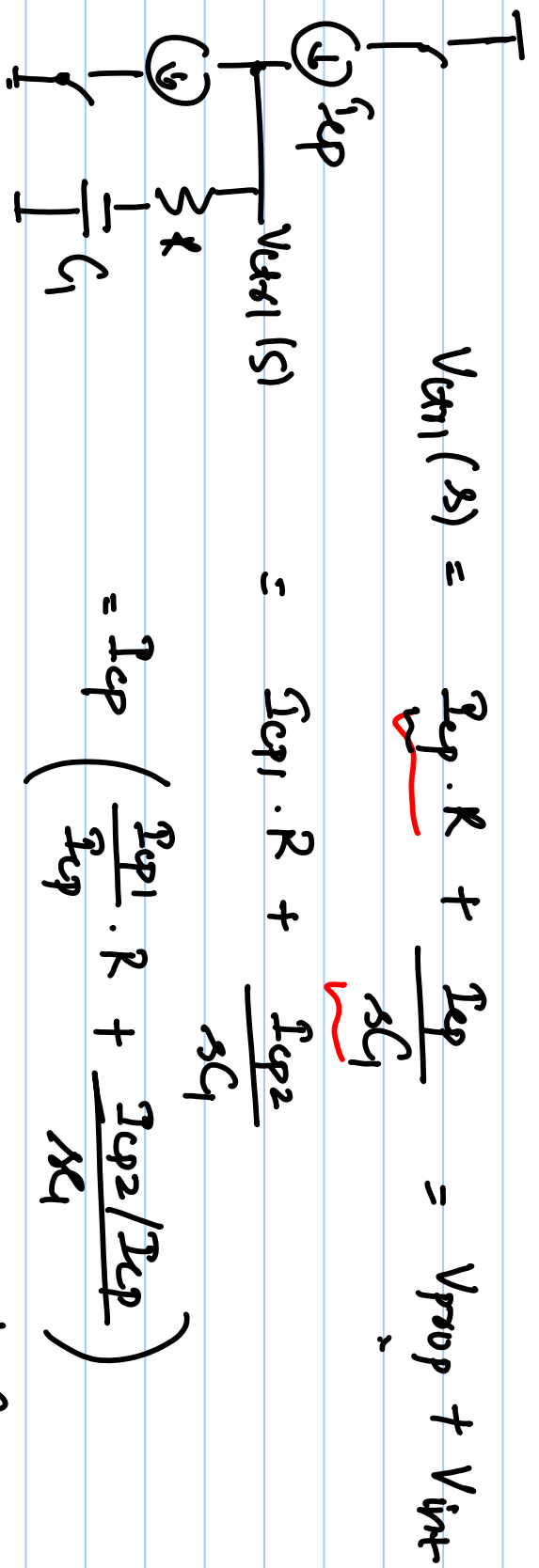
$$b_n = \frac{1}{n\pi} I_{DQ} \cos\left(n\pi \frac{T_{OS}}{T_R}\right)$$

$$\Delta v_{out,dm} = a_0 + I_{DQ} \sum \frac{1}{n\pi} \left\{ \sin\left(n\pi \frac{T_{OS}}{T_R}\right) \cos(n\omega_c t) + \cos\left(n\pi \frac{T_{OS}}{T_R}\right) \sin(n\omega_c t) \right\}$$

$$v_{out} = \sin\left(\omega_c t + \theta\right) \int \Delta v_{out,dm} \cdot dt$$

$$= \sin\left(\omega_c t + \theta\right) \int \frac{K_{VDS} I_{DQ} R}{\pi} \left[\sin(\theta) \cos(\omega_c t) + \cos(\theta) \sin(\omega_c t) \right] dt$$

$$= \sin\left(\omega_c t + \theta\right) \left\{ \frac{K_{VDS} I_{DQ} R}{\pi \omega_c} \left[\sin(\theta) \sin(\omega_c t) - \cos(\theta) \cos(\omega_c t) \right] \right\}$$



$$V_{out}(s) = \frac{I_{cp} \cdot R}{sC_1} + \frac{I_{cp}}{sC_1} = V_{prop} + V_{int}$$

$$= I_{cp1} \cdot R + \frac{I_{cp2}}{sC_1} = I_{cp} \left(\frac{I_{cp1}}{I_{cp}} \cdot R + \frac{I_{cp2}/I_{cp}}{sC_1} \right)$$

$$= I_{cp} \left(k \cdot R + \frac{1}{sC_1} \right) \quad \left| \quad \frac{I_{cp1}}{I_{cp}} = k \right.$$

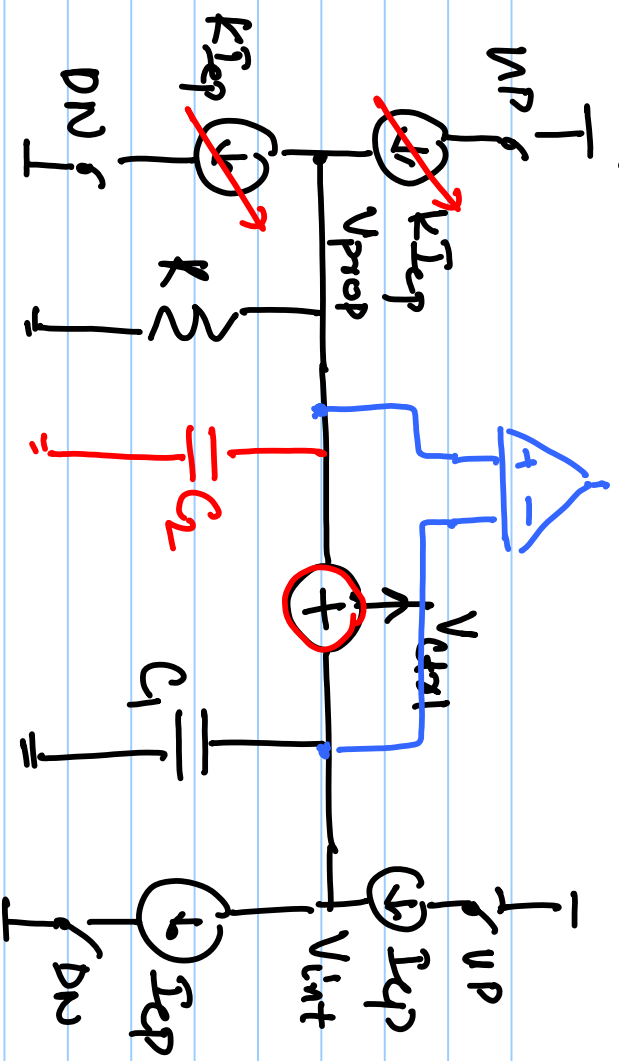
$$\Rightarrow \omega_z = \frac{1}{k \cdot R C_1} = \frac{1}{R (k C_1)} = \frac{1}{R C_1'} \quad \left| \quad \frac{I_{cp2}}{I_{cp}} = 1 \right.$$

$$\omega_z = \frac{1}{k R C_1}$$

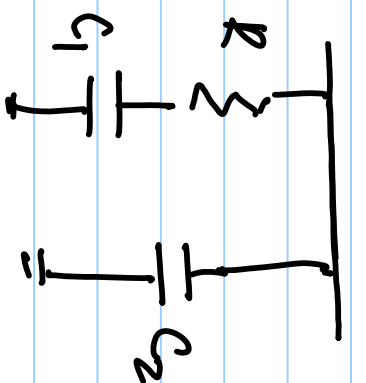
$$R, k C_1, I_{cp} \quad \left| \quad \omega_z = \frac{1}{k R C_1} \quad R, C_1, I_{cp} = k I_{cp} \right.$$

$$I_c = I_{cp}$$

Dual-path loop filter (DPLF)



$$V_{err1} = I_{dep} \left(kR + \frac{1}{sC_1} \right) - \text{Opamp.}$$



$$V_{err1}(s) = k_{dep} \frac{R}{1 + sRC_2} + I_{dep} \frac{1}{sC_1}$$

$$= \frac{I_{dep}}{1 + sRC_2} \left(\frac{1 + s(C_2 + kC_1)R}{sC_1} \right)$$

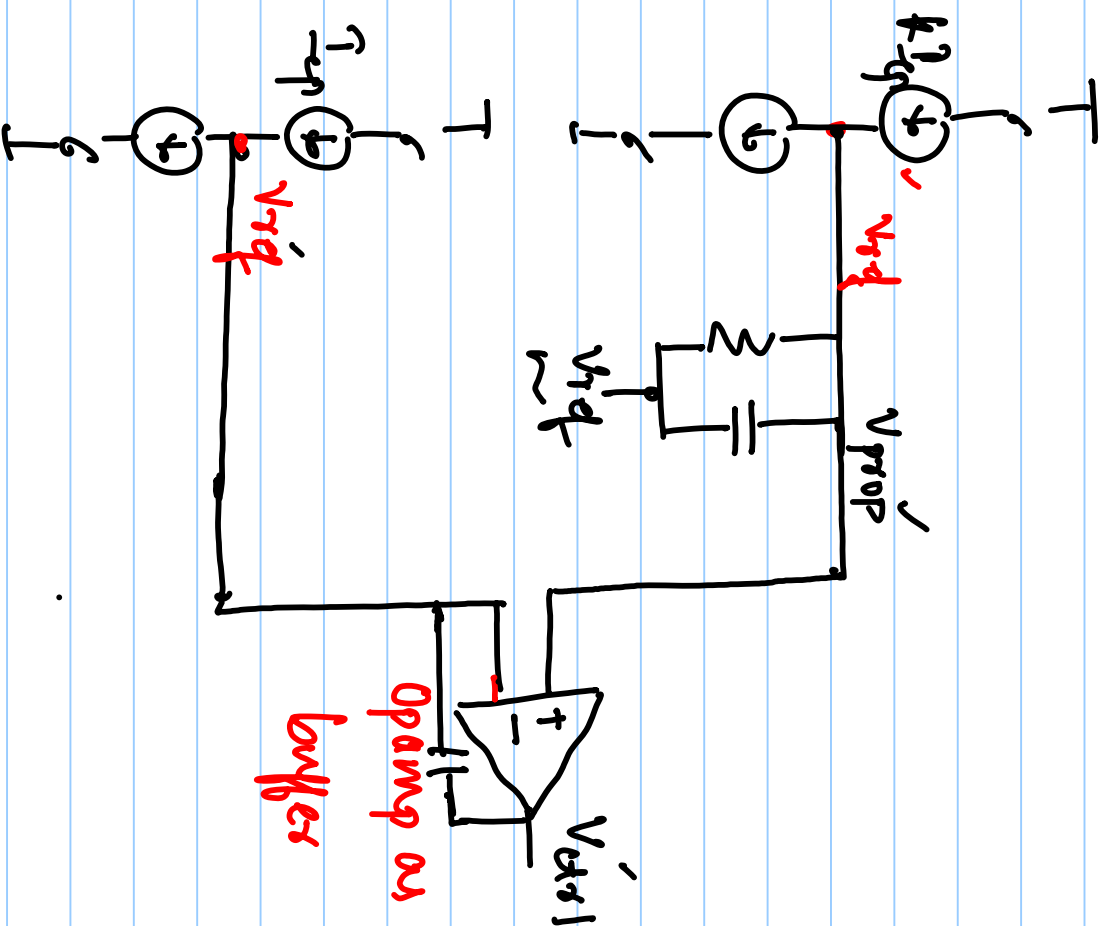
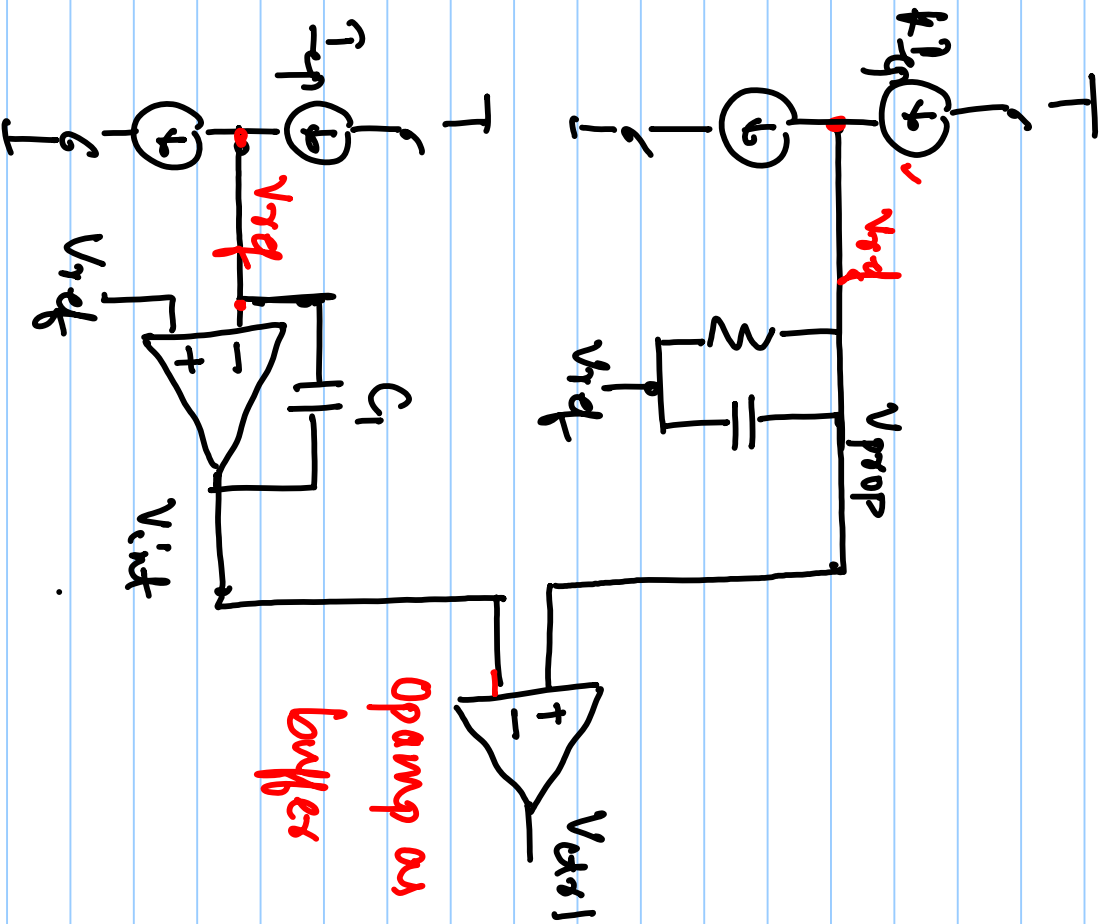
$$\omega_z = \frac{1}{R(C_2 + kC_1)} \approx \frac{1}{kC_1}, \quad \omega_{p1} = 0, \quad \omega_{p2} = \frac{1}{RC_2}$$

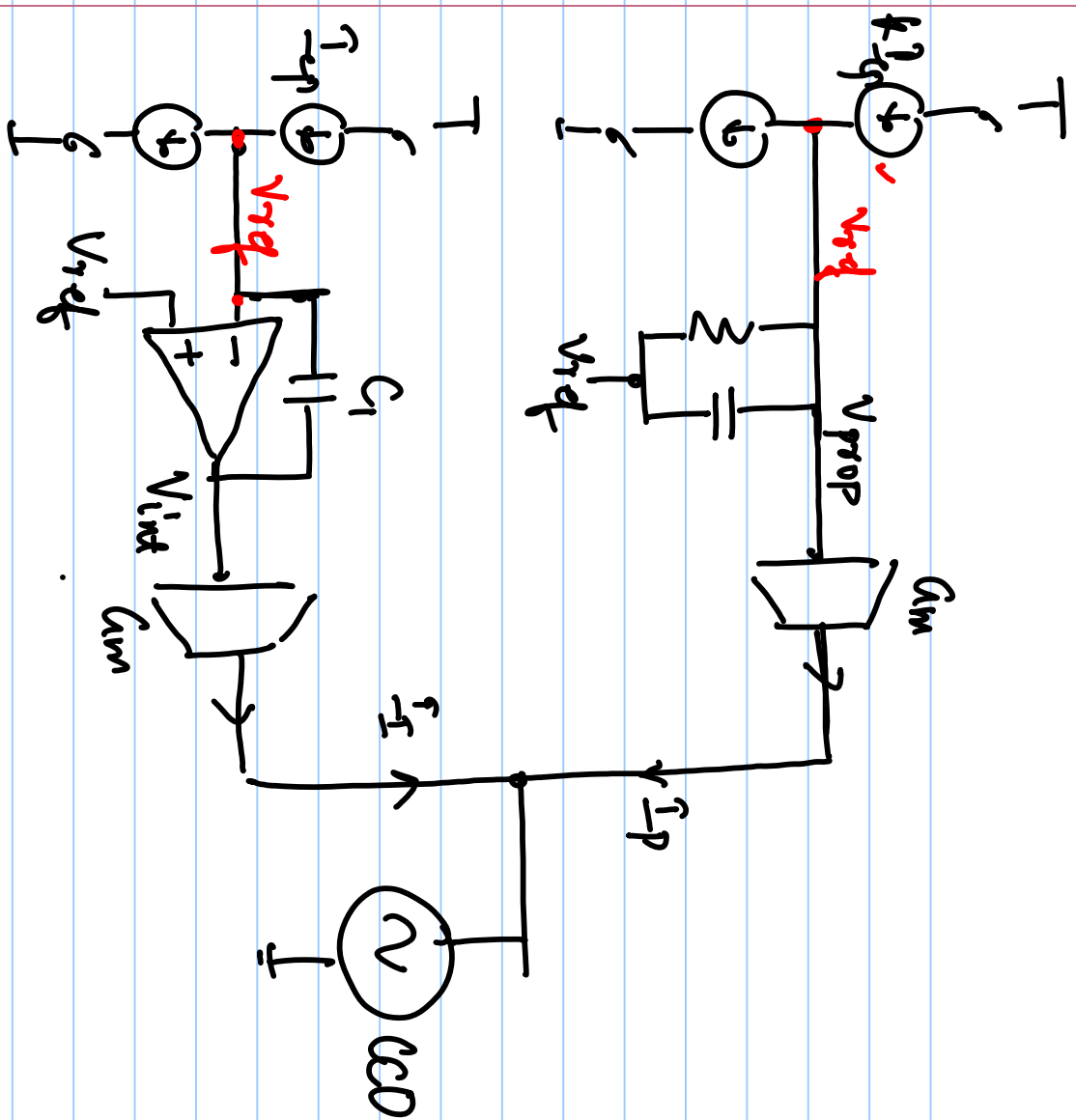
$$\omega_z = \frac{1}{RC_1}$$

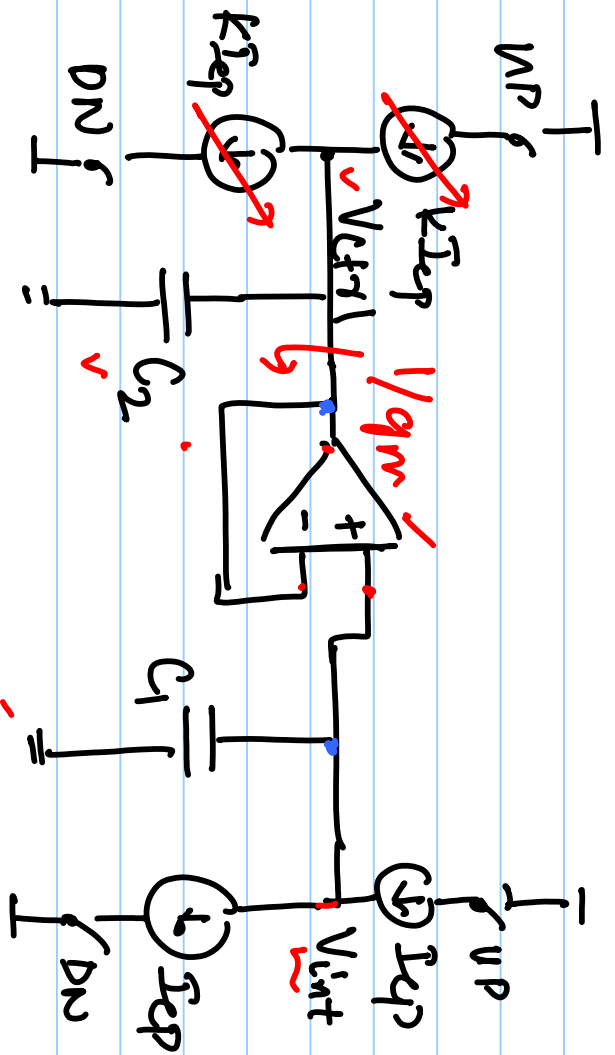
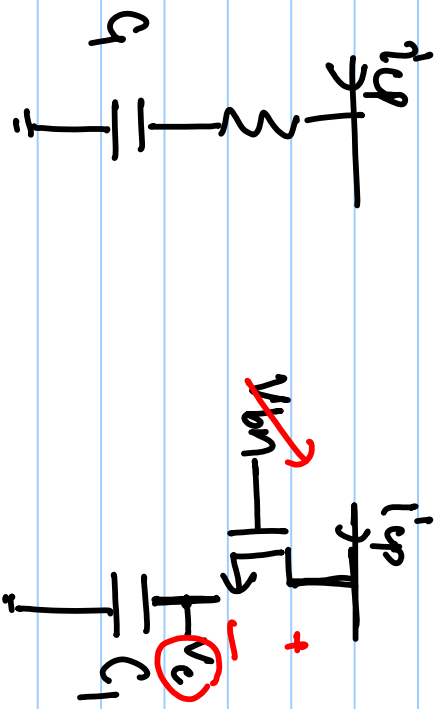
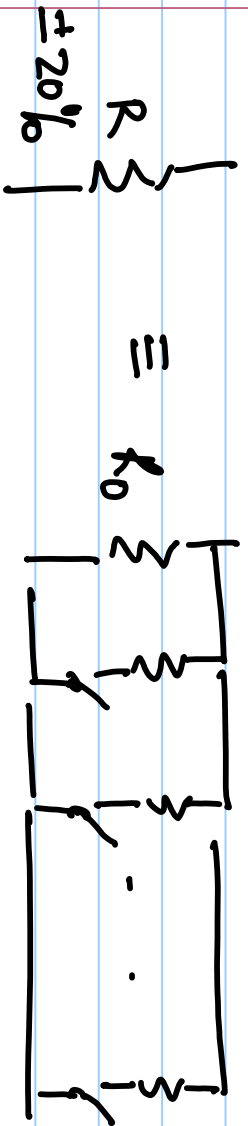
$$\omega_{p1} = 0$$

$$\omega_{p2} = \frac{1}{\frac{RC_1 C_2}{C_1 + C_2}}$$

$$\approx \frac{1}{RC_2}$$

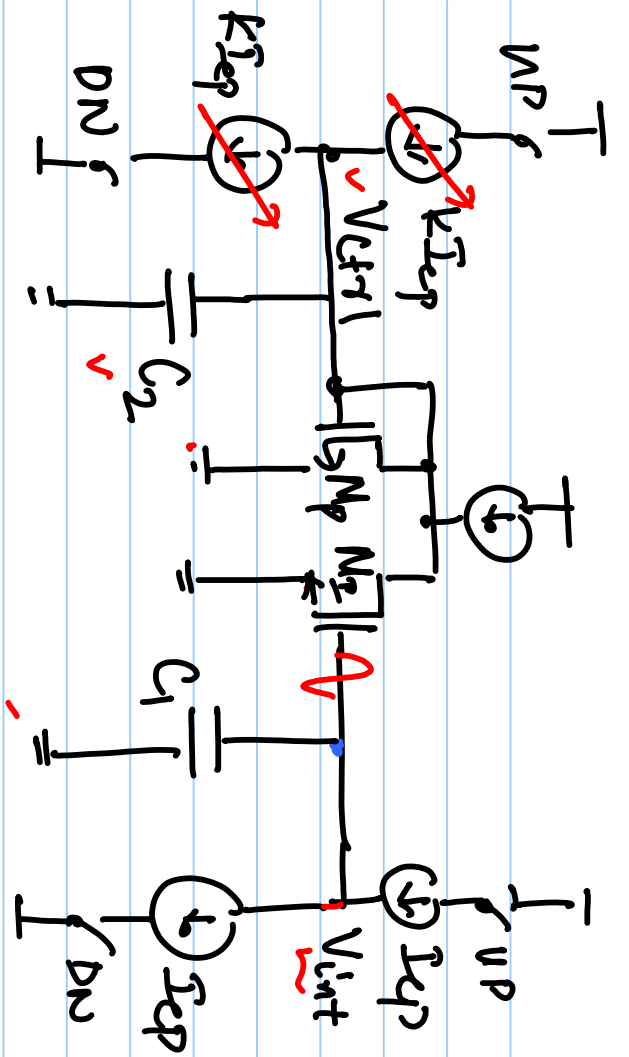






$$V_{out1}(s) = \frac{I_{cp}}{sC_1} + \frac{kI_{cp} / g_m}{1 + \frac{sC_2}{g_m}}$$

$$\frac{V_{out1}}{I_{cp}} = \frac{1 + \frac{kC_1 + C_2}{g_m}}{sC_1 \left(1 + \frac{sC_2}{g_m} \right)}$$



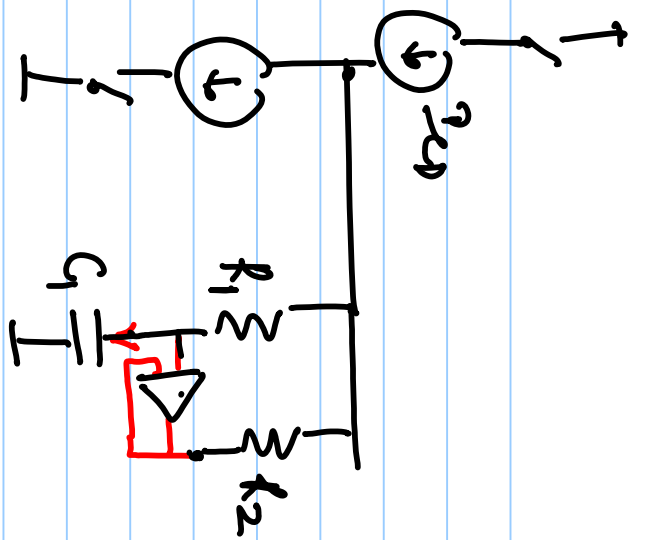
$$V_{out}(s) = \left[\frac{I_{cp}}{sC_1} \text{amp}_2 + k I_{ep} \right] \frac{1}{\text{amp}}$$

n/o C_2

$$V_{out} = k I_{cp} \cdot R + \frac{I_{cp}}{sC_1} \Rightarrow \frac{V_{out}}{I_{cp}}$$

$$= I_{cp} \cdot R + \frac{(I_{cp}/k)}{sC_1}$$

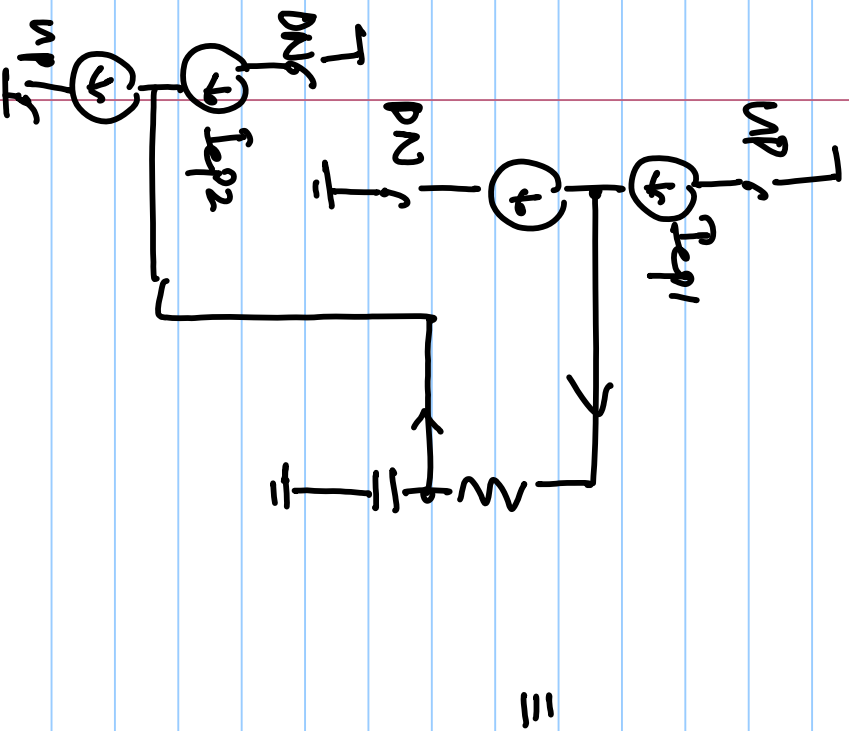
$$= I_{cp} \left(\frac{1 + s k C_1 R}{s C_1} \right)$$



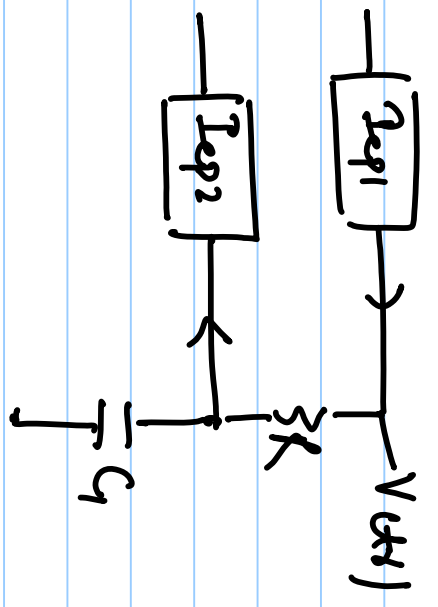
$$V_{th1} = I_{cp1} \cdot \frac{R_2}{R_1 + R_2} \times \frac{1}{sC_1} + I_{cp1} (sL_1 || R_2)$$

$$= \frac{I_{cp1}}{sC_1 \left(1 + \frac{L_1}{R_2}\right)} + I_{cp1} R_{eff}$$

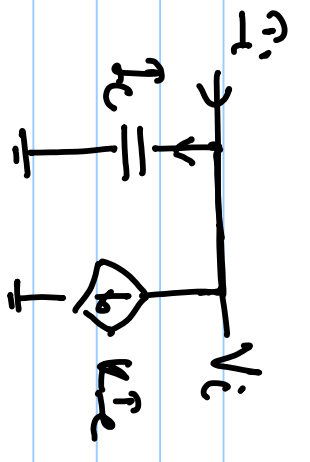
$$R_2 = R_{eff} C_1 \left(1 + \frac{L_1}{R_2}\right) = R_1 C_1$$



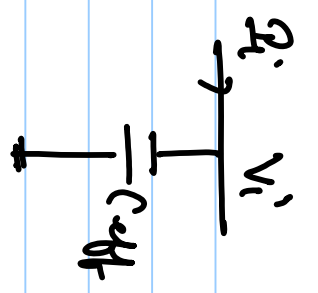
$$R_2 = \frac{R C_1}{1 - \alpha} = R \left(\frac{C_1}{1 - \alpha}\right)$$



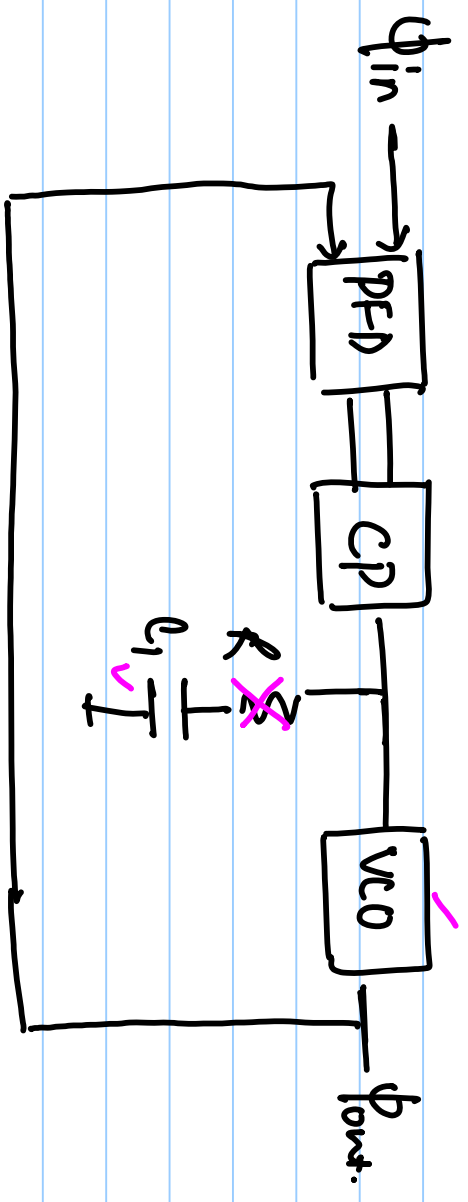
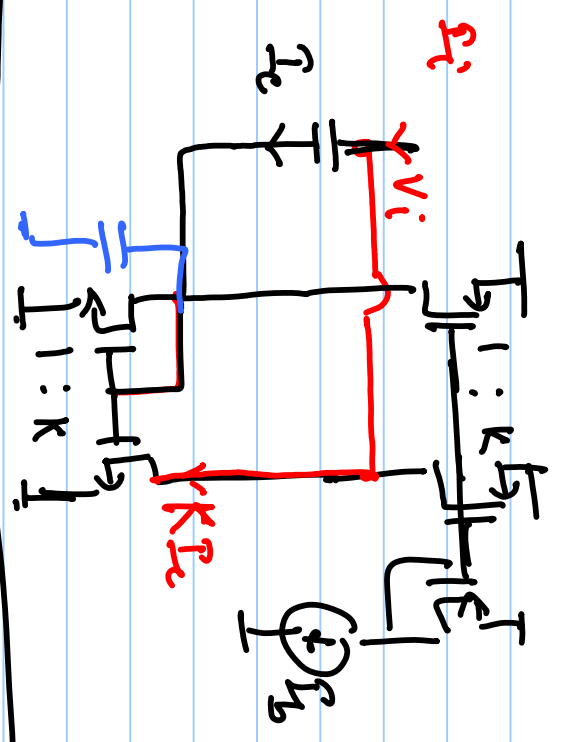
$$\begin{aligned} V_{th1}(s) &= I_{cp1} \cdot R + \frac{(I_{cp1} - I_{cp2})}{sC_1} \\ &= I_{cp1} \left[R + \frac{(1 - \frac{I_{cp2}}{I_{cp1}})}{sC_1} \right] \\ &= I_{cp1} \left[R + \frac{(1 - \alpha)}{sC_1} \right] \end{aligned}$$

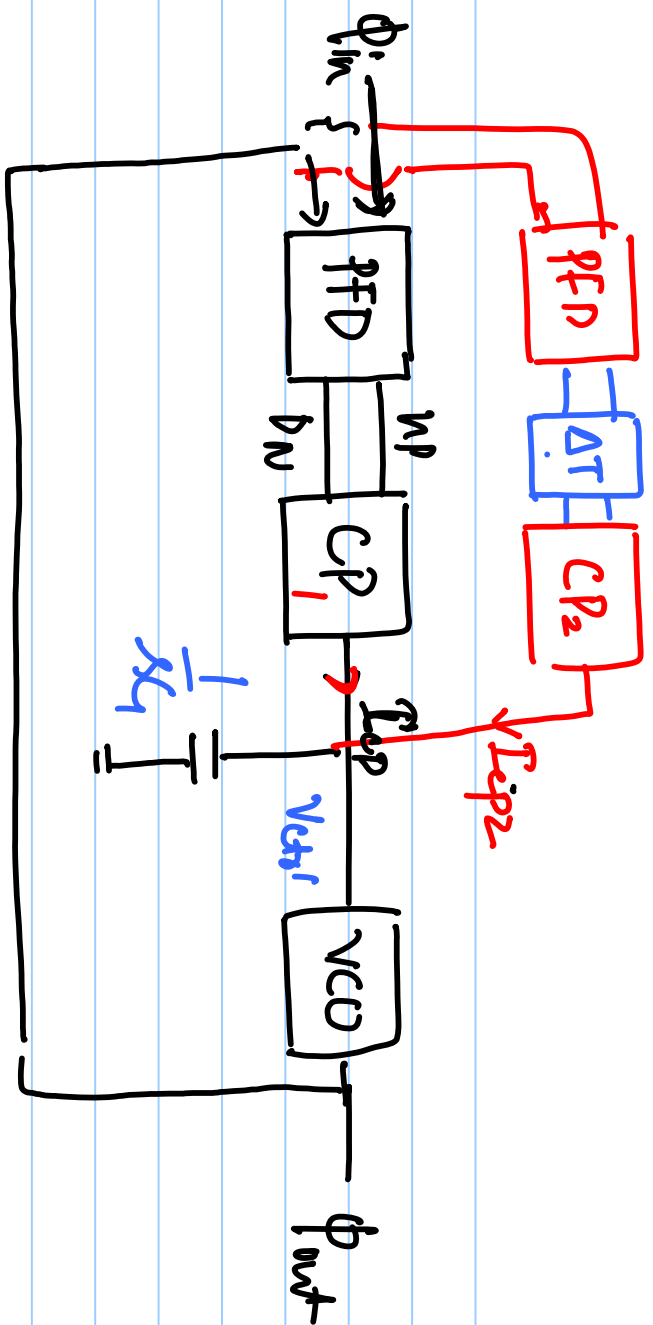


\Leftrightarrow



$$C_{eff} = (k+1)C$$





$$\left[\frac{\phi_{out}}{\phi_{in}} \right] \approx (1 + s/\omega_2)$$

$$V_{ct}(s) = I_{cp1} \times \frac{1}{s\tau_1} + I_{cp} e^{-s\Delta T} \frac{1}{s\tau_1}$$

$$\tau_{cp1} = \tau_{cp} = -\frac{\tau_{cp2}}{\alpha}$$

$$= \frac{1}{s\tau_1} \left[I_{cp1} + I_{cp2} e^{-s\Delta T} \right]$$

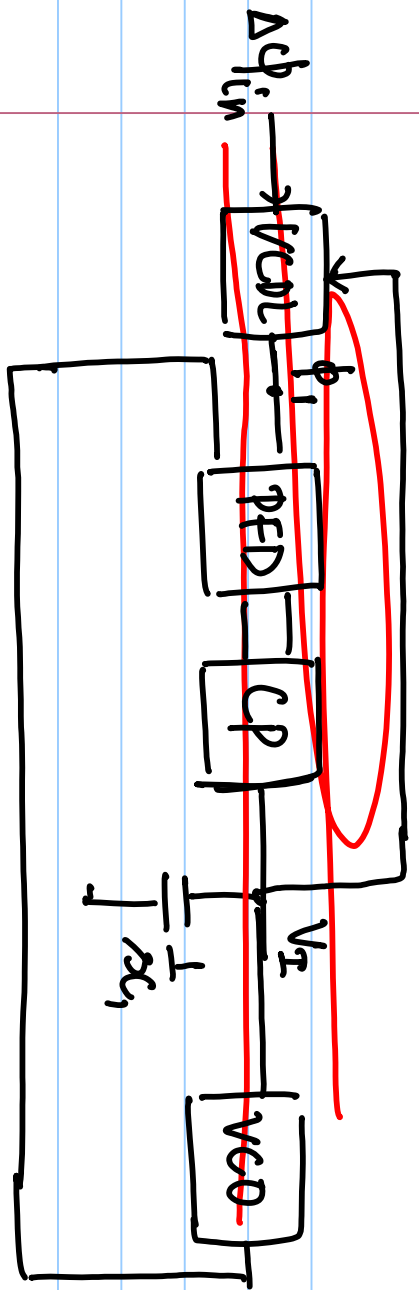
(Wind/s = $\frac{0.75}{0.25} \times \frac{1}{\Delta T}$)

$$= \frac{1}{s\tau_1} \left[I_{cp1} + I_{cp2} (1 - s\Delta T) \right]$$

$$= \frac{1}{s\tau_1} \left[(I_{cp1} + I_{cp2}) - I_{cp2} \cdot s\Delta T \right]$$

$$= \frac{1}{s\tau_1} \left[I_{cp} (1 - \alpha) + \alpha I_{cp} s \Delta T \right]$$

$$\left| \omega_2 = \frac{1 - \alpha}{\alpha} \frac{1}{\Delta T} \right.$$



$$\phi_i = \Delta\phi_{in} + K_{VCDL} \cdot V_e$$

$$[K_{VCDL}] = \frac{\text{rad}}{V}$$