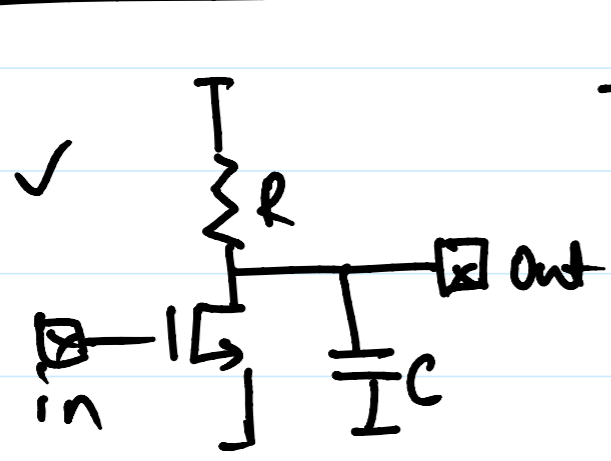
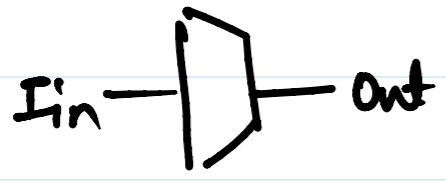
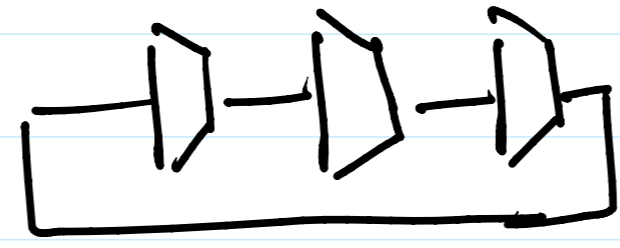


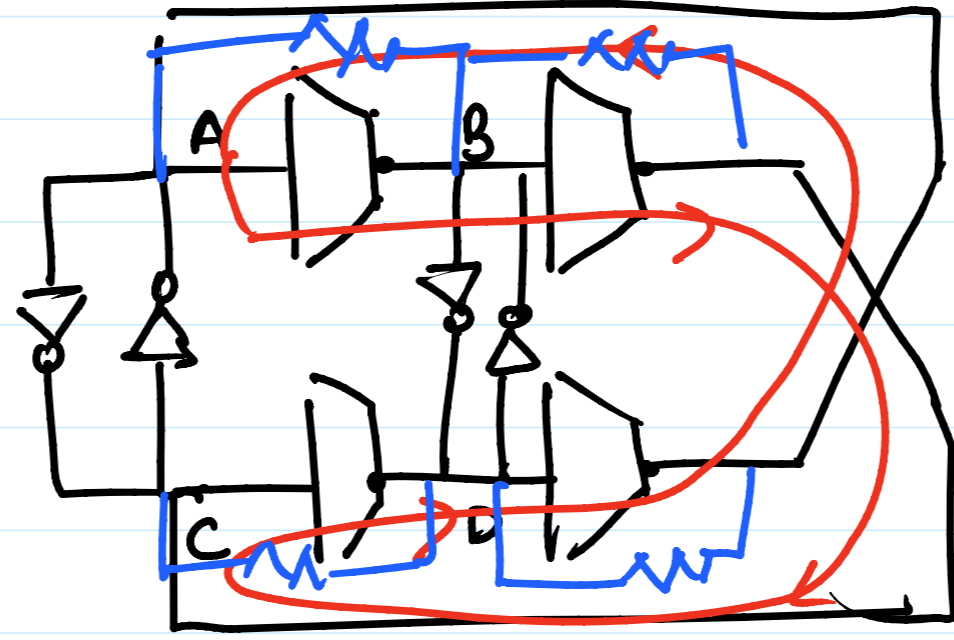
Oscillators



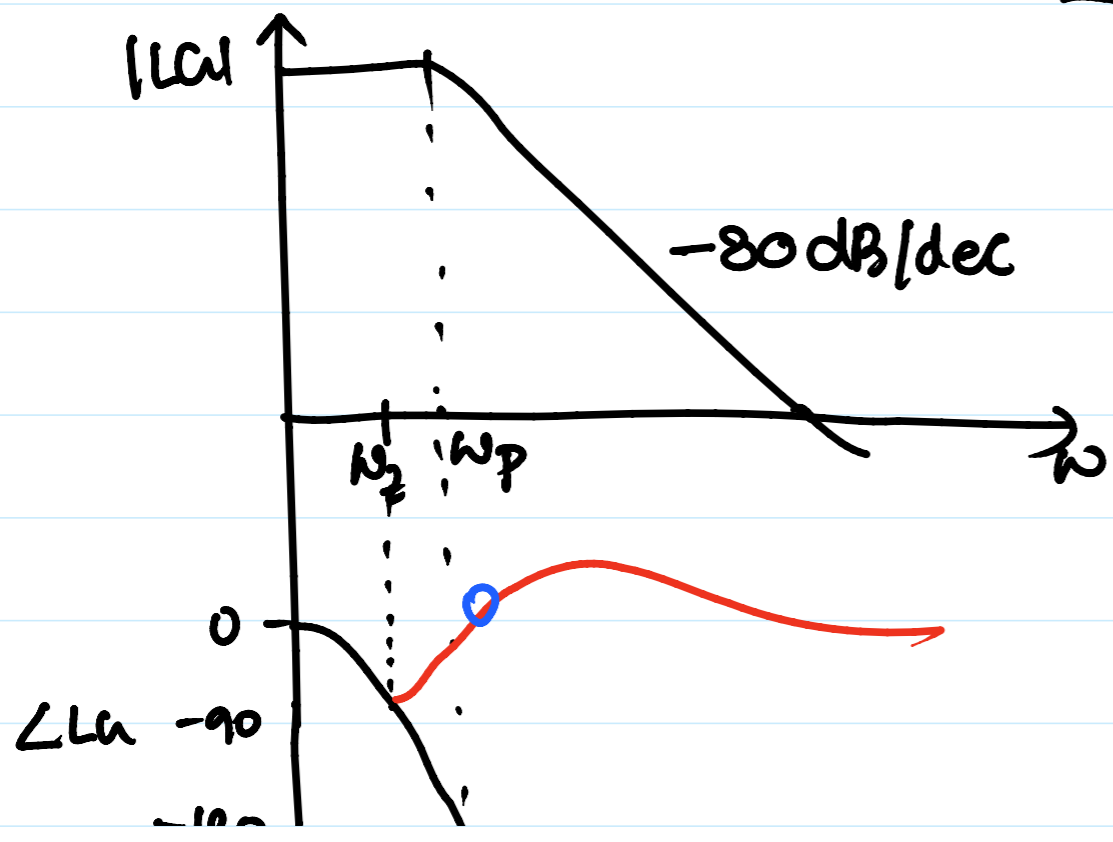
$$\frac{-A_0}{1 + s/\omega_p}$$



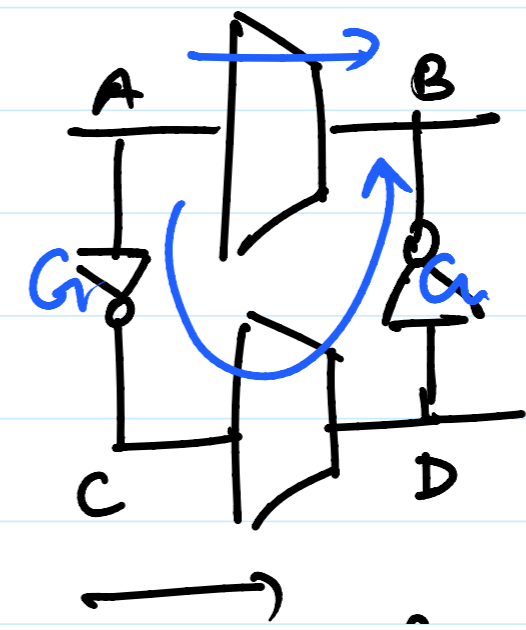
$$A = \bar{C}, B = \bar{D}$$



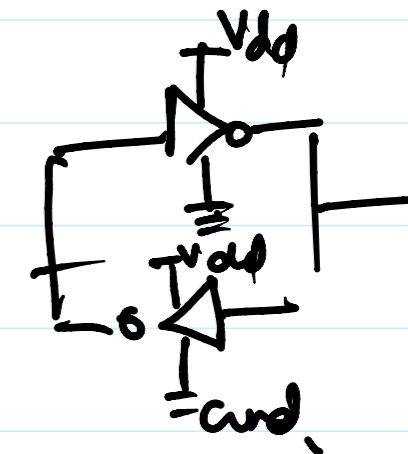
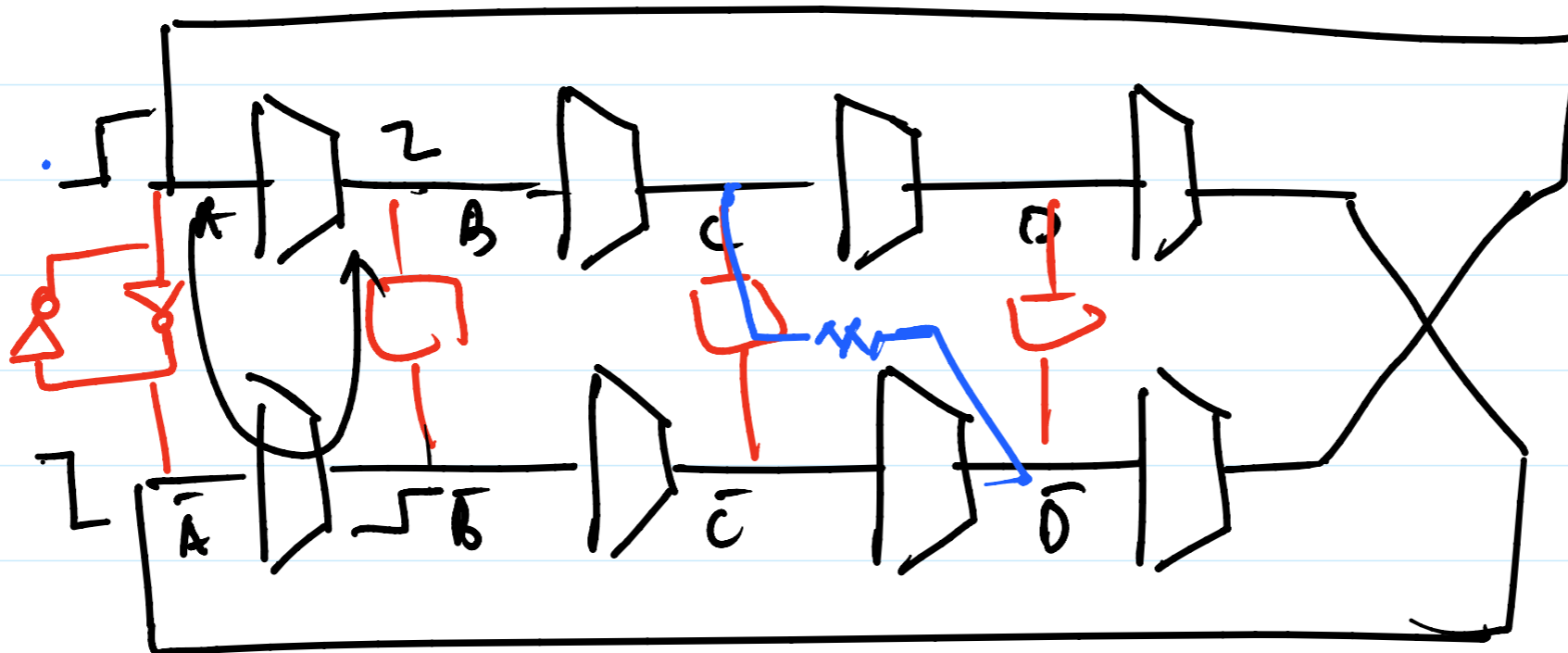
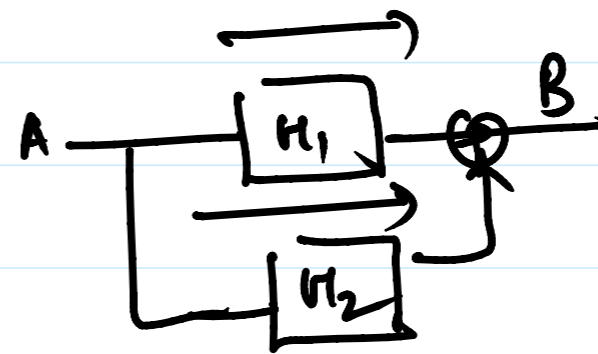
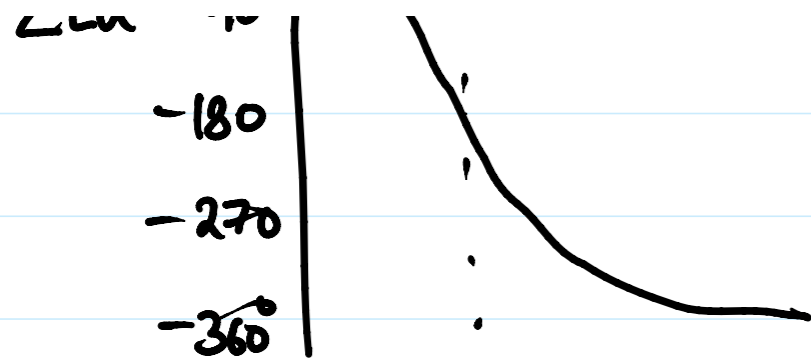
w/ cross-coupled inverters
- enforce $A = \bar{C}, B = \bar{D}$



$$\frac{V_B}{V_A} = \frac{-A_0}{1 + s/\omega_p} \text{ (old)}$$



$$\frac{V_B}{V_A} = \frac{-A'_0}{(1 + s/\omega_p)}$$



Drawbacks of cross-coupled inverter

- frequency of oscillation reduces,
- Power consumption increases

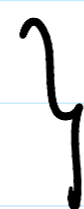
Oscillators Parameter / Performance metrics

1. Amplitude

2. Frequency

- Tuning Range

- Tuning Uncertainty

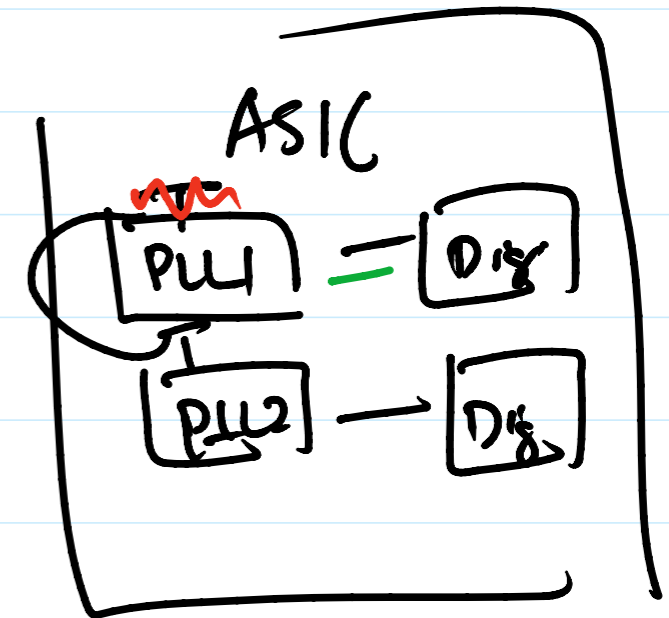
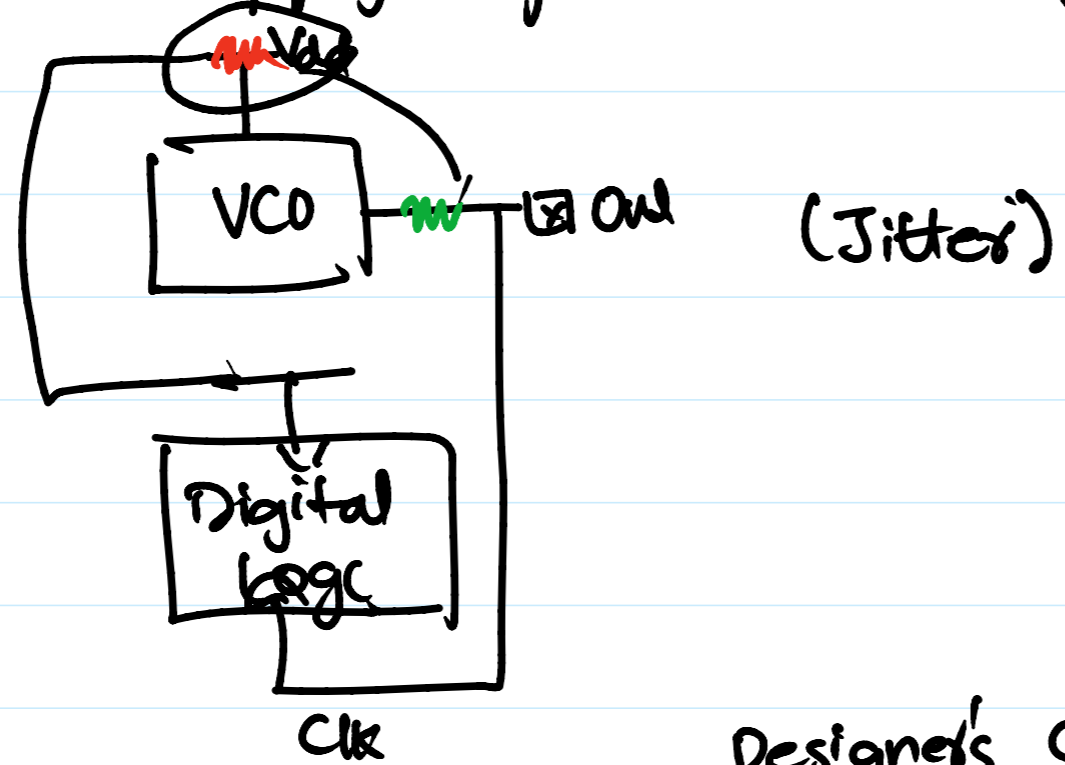


Ideally, large tuning range
Linear Kvco

- Tuning Unearity]

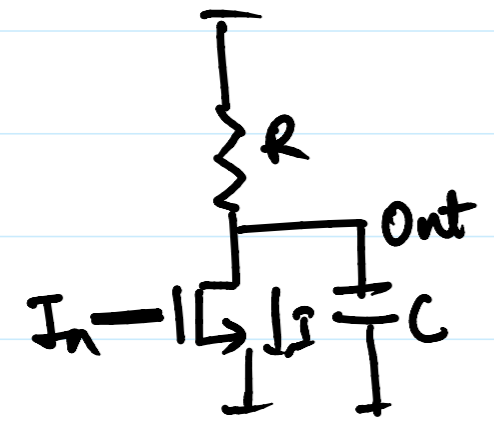
Linear K_{vco}

3. Power supply rejection ratio (PSRR)



- 4) Power
- 5) Phase noise

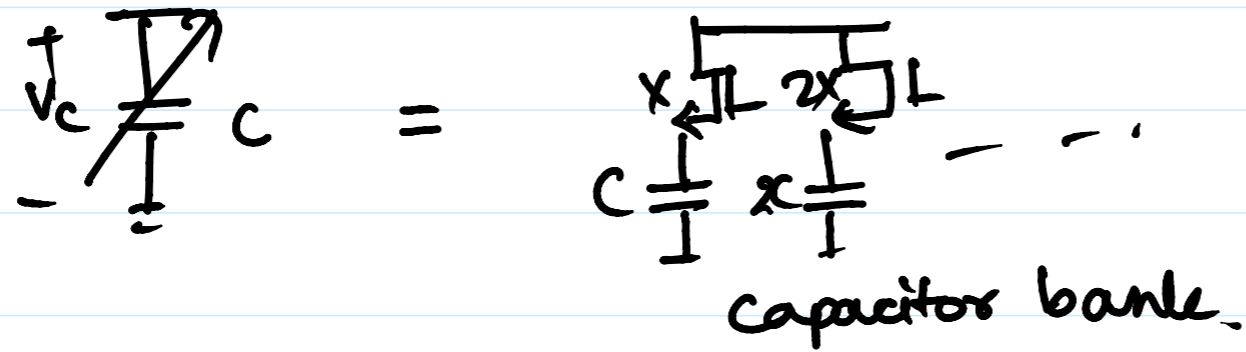
Designer's Choice
lowest power
Low phase noise



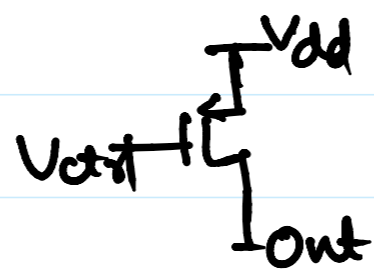
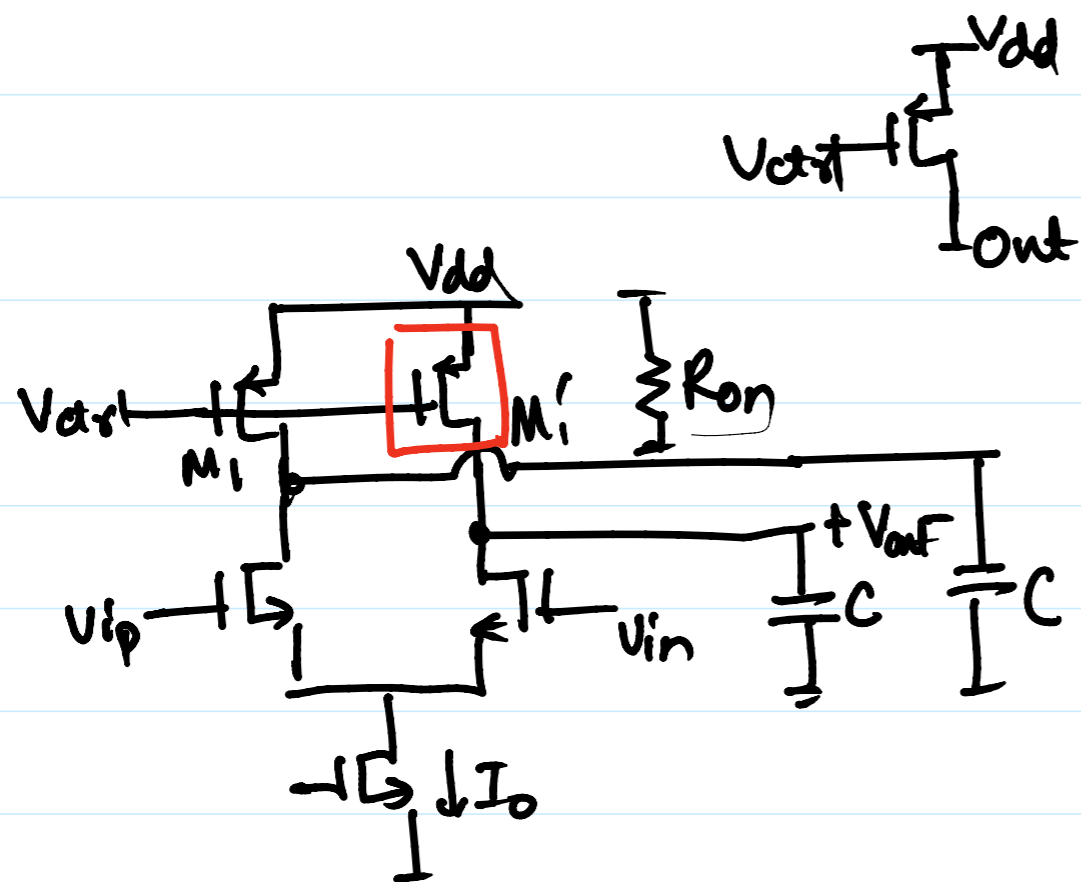
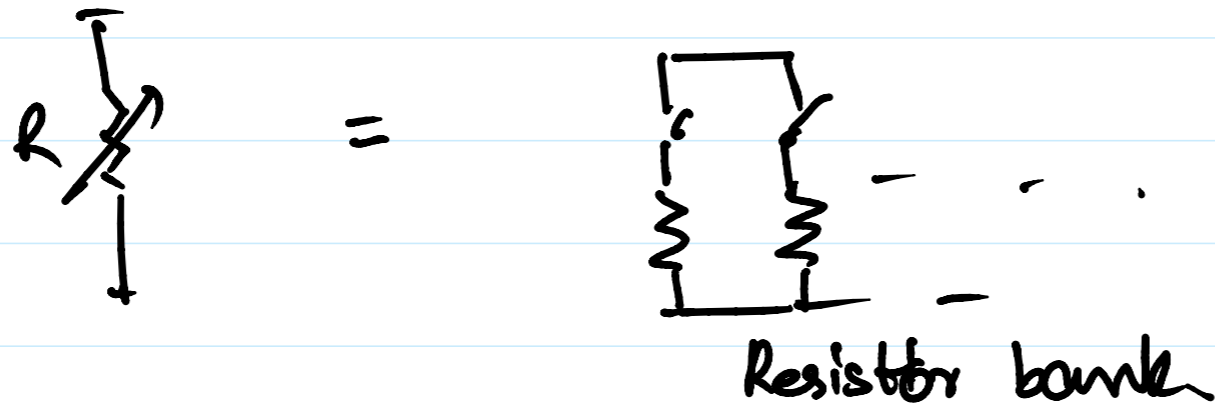
$$\omega_p = \frac{1}{RC}$$

$R \pm 20\%$, $C \pm 20\% \Rightarrow \omega_{osc}$ variations

Want to vary oscillation frequency — Vary R & C



Use MOS capacitance & vary V_{gs}



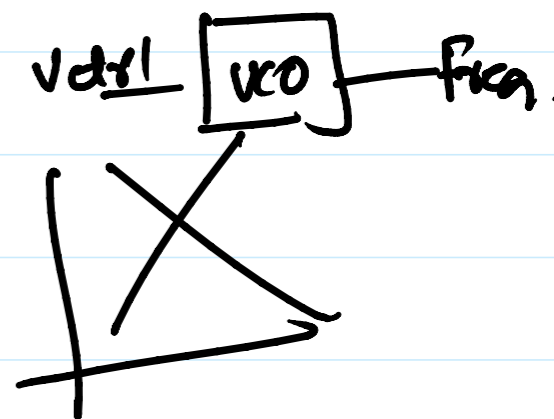
* M_1, M_1' are in linear region of saturation

$$I = \frac{kW}{L} \left((V_{DD} - |V_{th1}| - V_{ctrl}) V_{SD} - \frac{V_{SD}^2}{2} \right)$$

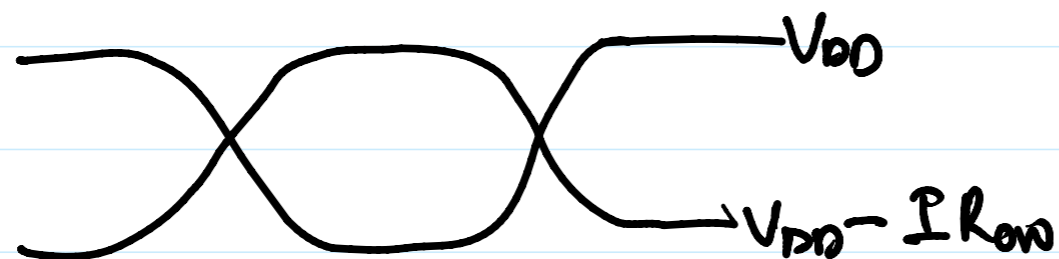
$$R_{on} \approx \frac{1}{\frac{kW}{L} [V_{DD} - |V_{th1}| - V_{ctrl}]}$$

$$f_{max} \propto \frac{1}{L} = \frac{kW}{L} [V_{DD} - |V_{th1}| - V_{ctrl}]$$

$$f_{osc} \propto \frac{I}{R_{on} C} = \frac{\frac{K_N}{L} [V_{DD} - |V_{THN}| - V_{THP}]}{C}$$

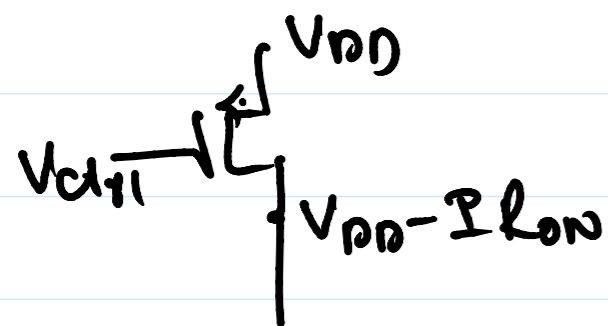


$f_{osc} \propto V_{THP}$



$$\text{Amplitude} = I R_{on}$$

$$= \frac{I}{\frac{K_N}{L} [V_{DD} - |V_{THN}| - V_{THP}]}$$



$$V_{DD} - V_{THP} - |V_{THN}| > I R_{on}$$