

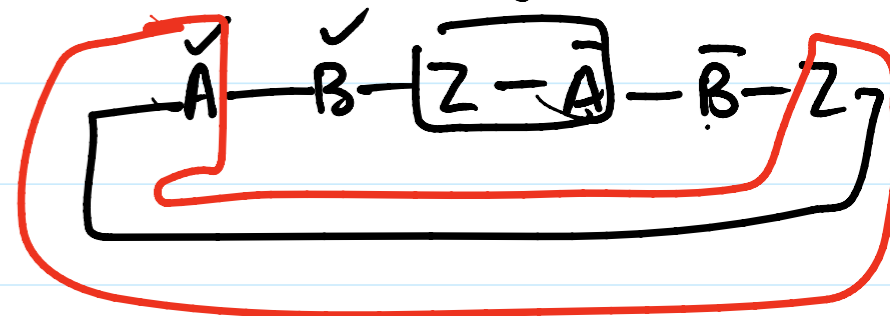
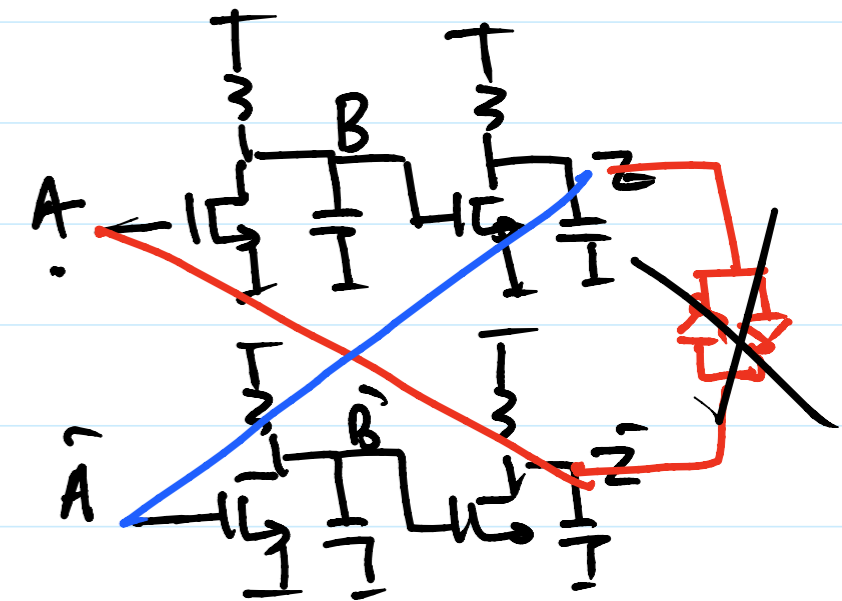
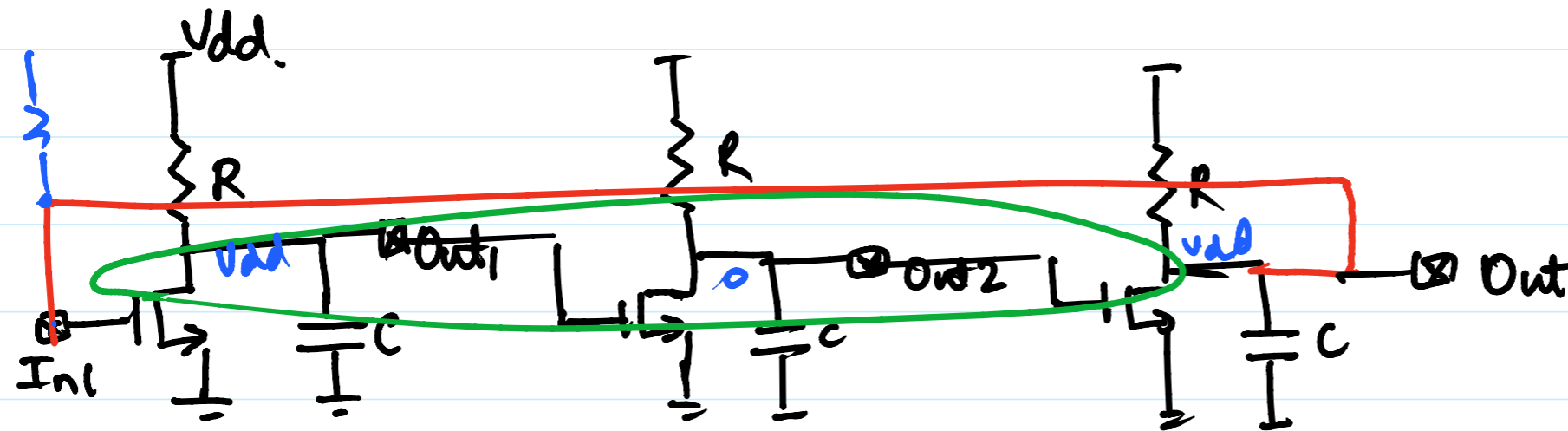
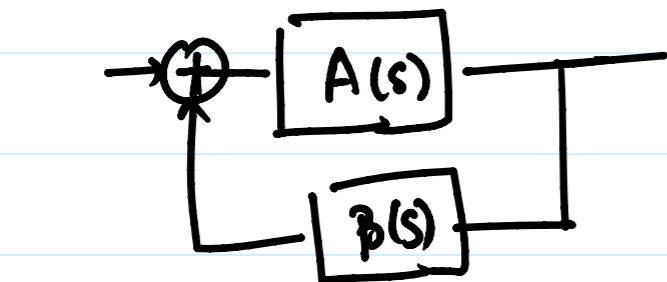
Oscillators.

Feedback Analysis:

Barkhausen Criterion —

$$|A(j\omega_0) \beta(j\omega_0)| = 1$$

$$\angle(A(j\omega_0) \beta(j\omega_0)) = 2k\pi, \quad k = 0, \pm 1, \dots$$



$$\frac{V_{out}(s)}{V_{in}(s)} = \frac{-A_0}{1 + s/\omega_p}$$

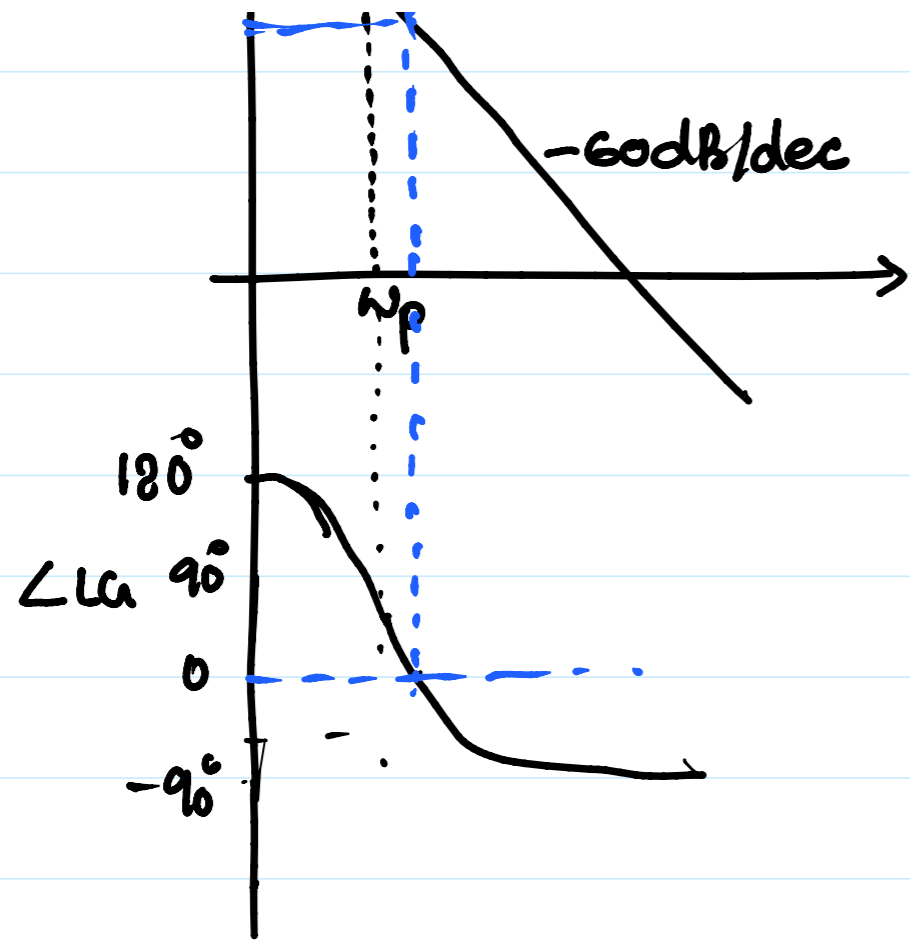
$$; A_0 \approx g_m R, \quad \omega_p = \frac{1}{RC}$$

$$LG_1 = \left(\frac{-A_0}{1 + s/\omega_p} \right)^3 ;$$



$$\angle LG_1 = 180^\circ - 3 \tan^{-1} \left(\frac{\omega_0}{\omega_p} \right) = 2k\pi$$

$$0 = 180^\circ - 2 \tan^{-1} (\omega_0)$$



$$0 = 180^\circ - 3 \tan^{-1} \left(\frac{\omega_0}{\omega_p} \right)$$

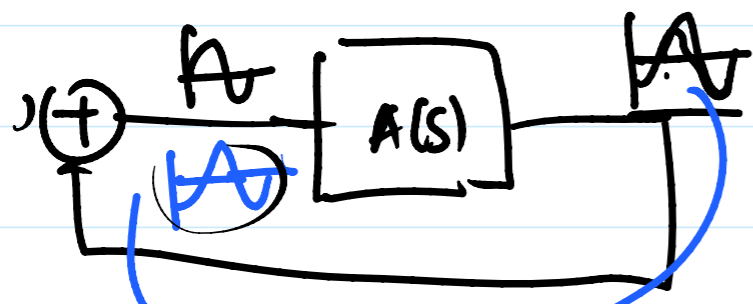
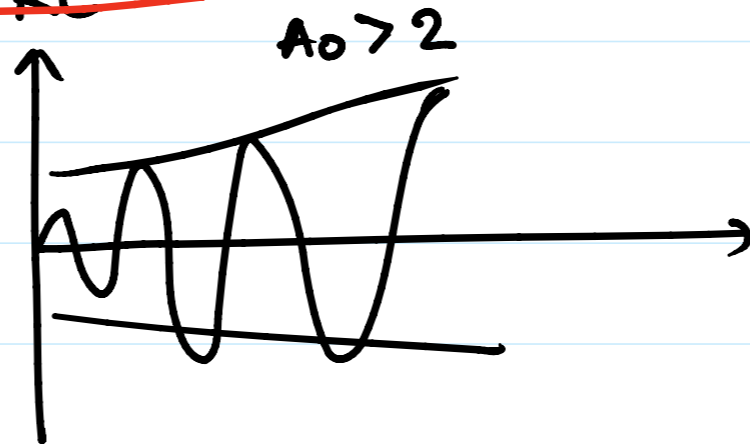
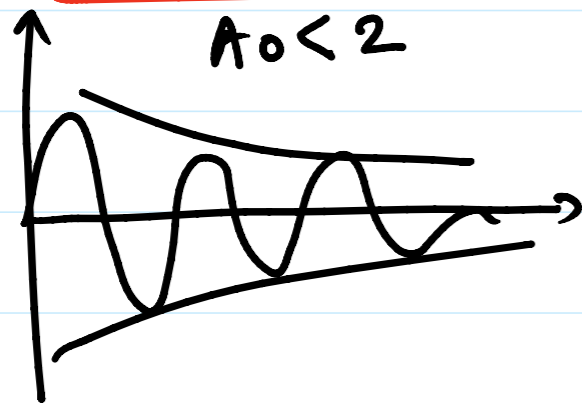
$$\omega_0 = \omega_p \tan(60^\circ) = \sqrt{3}$$

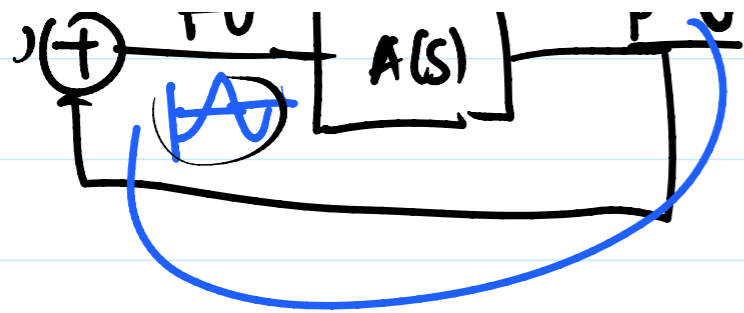
$$\boxed{\omega_0 = \sqrt{3} \omega_p}$$

$$|L_c(j\omega_0)| = \frac{A_0^3}{\left(\sqrt{1 + \left(\frac{\omega_0}{\omega_p} \right)^2} \right)^3} = 1$$

$$\frac{A_0^3}{2^3} = 1 \Rightarrow \boxed{A_0 = 2}$$

$$\boxed{A_0 = 2, \omega_0 = \sqrt{3} \omega_p = \frac{\sqrt{3}}{RC}}$$





$$LG_1 = \left[\frac{-A_0^3}{(1+s/\omega_p)^3} \right]$$

closed loop gain, $LG_{cl}(s) = \frac{(-A_0)^3 / (1+s/\omega_p)^3}{1 - \frac{(-A_0)^3}{(1+s/\omega_p)^3}}$

$$LG_{cl}(s) = \frac{-A_0^3}{(1+s/\omega_p)^3 + A_0^3}$$

closed loop poles:

$$(1+s/\omega_p)^3 = -A_0^3$$

$$(1+s/\omega_p)^3 = (-1) A_0^3 = e^{j\pi} A_0^3$$

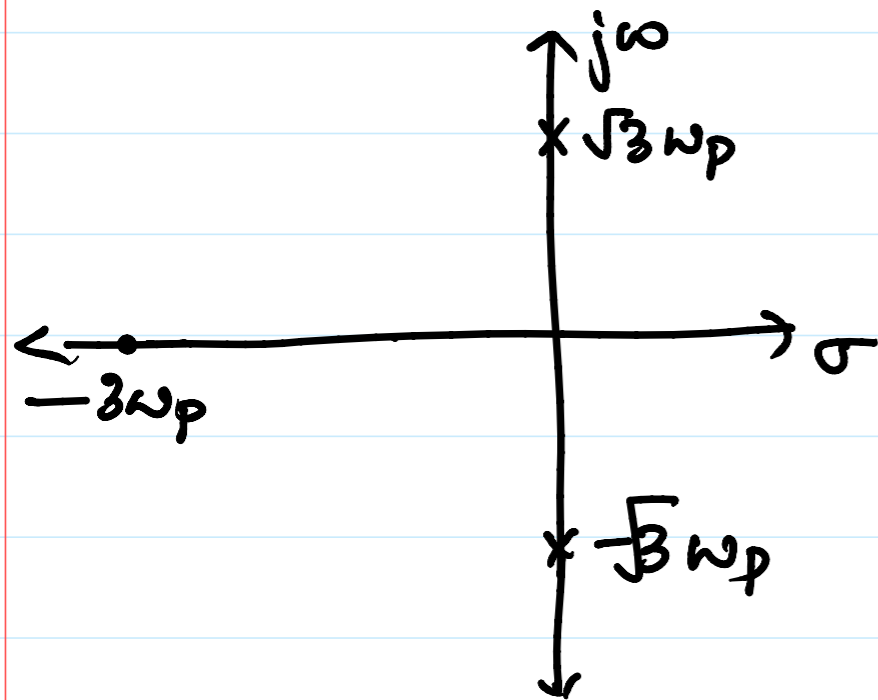
$$(s/\omega_p) = -1 + e^{j(\pi+2k\pi)/3} \cdot A_0 \quad ; \quad k = 0, 1, 2.$$

$$s = \left[-1 + 2 \cdot e^{j(\pi/3+2k\pi/3)} \right] \omega_p$$

$$k=0, \quad s/\omega_p = -1 + 2e^{j\pi/3} = -1 + 2\left(\frac{1}{2} + j\frac{\sqrt{3}}{2}\right)$$

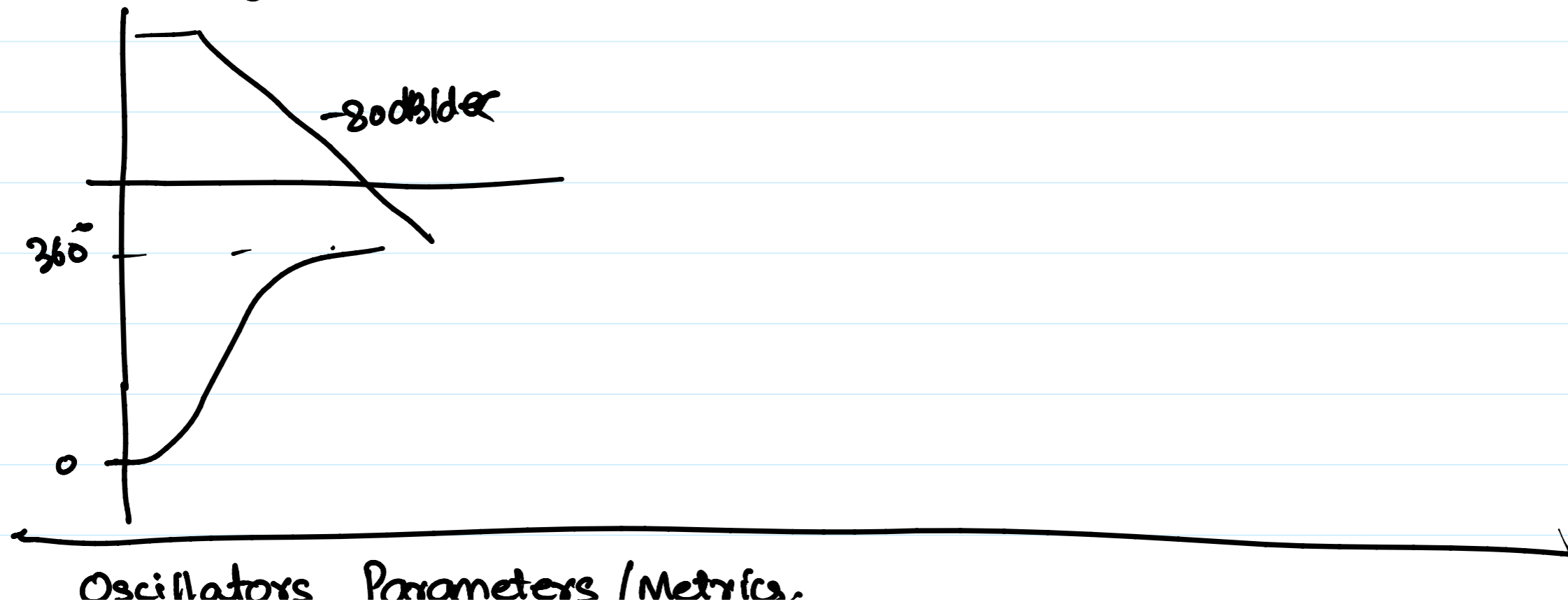
$$-1 + 2e^{j\pi}$$

$$-1 + 2e^{-j\pi/3}$$



$$|G| = \frac{A_0^4}{(1 + s/\omega_p)^4}$$

$$\angle G = -4 \tan^{-1}\left(\frac{\omega}{\omega_p}\right)$$



Oscillators Parameters / Metrics,

1. Amplitude — limited swing / full scale

$$A = f(I_o, V_{dd})$$

2. Frequency — $\omega_{osc} = \sqrt{3} \omega_p = \frac{\sqrt{3}}{RC}$

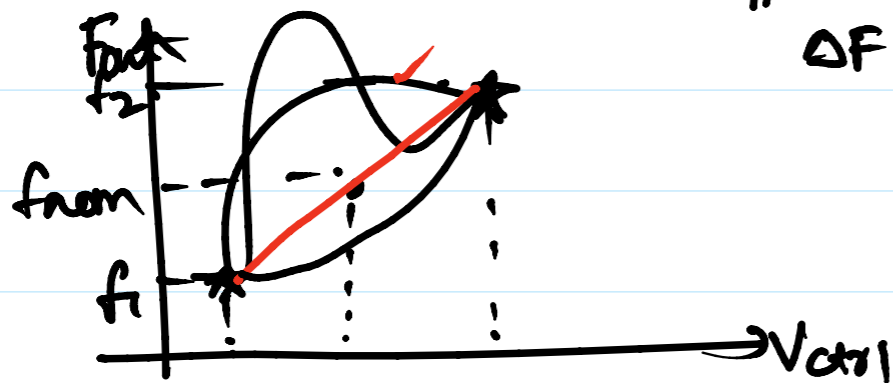
Vary R & C \rightarrow Vary freq.
 $\pm 20\%$ $\pm 30\%$

Frequency is susceptible to PVT variations.

Tuning Range

- Variation in frequency

around a nominal op freq. (ΔF)
 $\Delta F = f_2 - f_1$

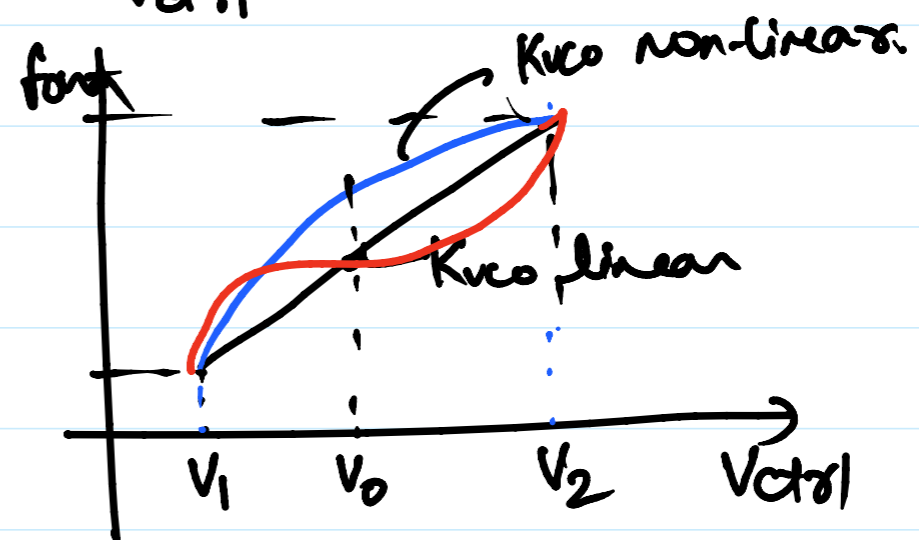


- Large tuning range



Tuning Linearity

- $\frac{\Delta F}{V_{ctrl}} = \text{constant (ideal)}$



- $K_{vc} = \frac{\Delta F}{V_{ctrl}}$

$\frac{1}{V_{ch}}$

