

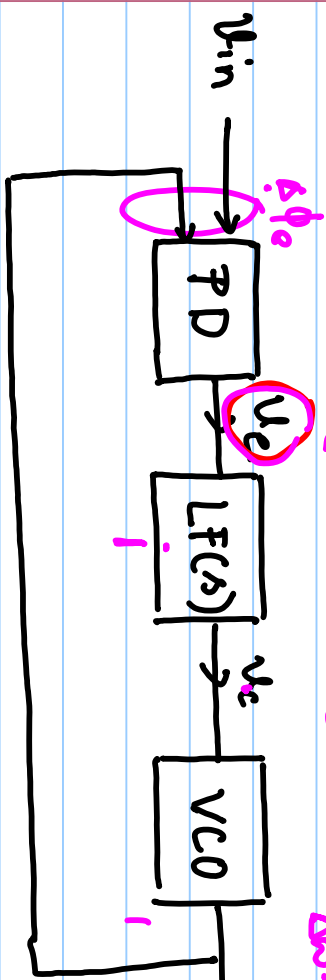
Lecture # 04

$\Delta V_e \rightarrow \Delta V_e$

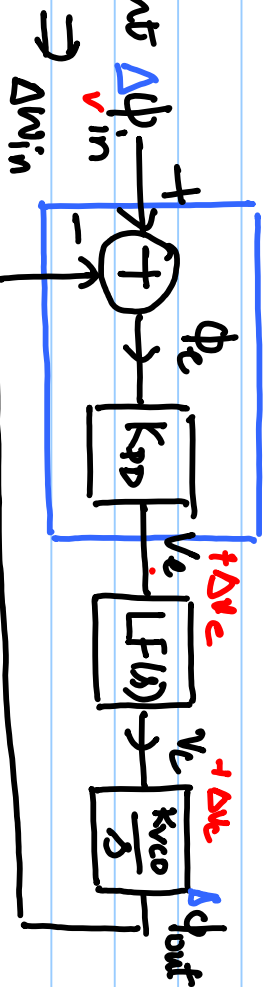
$\Delta \omega \rightarrow \Delta \omega$

PD

✓



Block Diagram of PLL



Small-signal model (linear)

$$V_{in} = A_{in} \sin(\omega_{in} t)$$

$$V_{out} = A_{out} \cos(\omega_0 t)$$

$$\int \phi_{in}(t) dt = \int \omega_{in} dt \quad \left. \vphantom{\int \phi_{in}(t) dt} \right\} \phi_e(t) = \phi_{in}(t) - \phi_0(t)$$

$$\phi_0(t) = \int \omega_0 dt$$

$$\omega_0(t) = \omega_{free} + K_{VCO} V_c(t); [K_{VCO}] = \frac{rad/s}{V}$$

$$\frac{V_c(s)}{V_e(s)} = LF(s) \quad \checkmark$$

$$V_c \propto \phi_e$$

- PLL is locked

$$\omega_0(t) = \omega_{in}(t) \quad \checkmark$$

$$\frac{d\phi_e(t)}{dt} = 0 \quad \checkmark$$

$$- \frac{\Delta V_c}{\Delta \phi_e} = K_{PD} = \frac{dV_c}{d\phi_e} \quad \checkmark$$

$$- \frac{\Delta \omega_0}{\Delta V_c} = K_{VCO}$$

$$- \Delta \phi_{out}(s) = \frac{\Delta \omega_0}{s} = \frac{K_{VCO}}{s} \cdot \Delta V_c(s)$$

$$V_{in} = a_{in} \sin(\omega_{in} t + \phi_{in}(\omega))$$

Gain in forward path

$$V_{out} = a_o \cos(\omega_o t + \phi_o(\omega))$$

$$K_{PD} LF(s) \frac{K_{vco}}{s} = \omega_c(s)$$

$$V_{in} \times V_{out} \checkmark$$

$$\frac{\Delta \phi_o}{\Delta \phi_{in}} = \frac{\omega_c(s)}{1 + (s \cdot \omega_c(s))}$$

$$= \frac{a_{in} a_o}{2} \cdot 2 \sin(\omega_{in} t + \phi_{in}(\omega))$$

$$\cdot \cos(\omega_o t + \phi_o(\omega))$$

$$\frac{\Delta \phi_o}{\Delta \phi_{in}} = H(s) = \frac{K_{PD} LF(s) K_{vco}}{s + K_{PD} LF(s) K_{vco}}$$

$$= \frac{a_{in} a_o}{2} \left[\sin(\overline{\omega_{in} + \omega_o} t + \phi_{in}(\omega) + \phi_o(\omega)) \right.$$

$$\left. + \sin(\overline{\omega_{in} - \omega_o} t + \phi_{in}(\omega) - \phi_o(\omega)) \right]$$

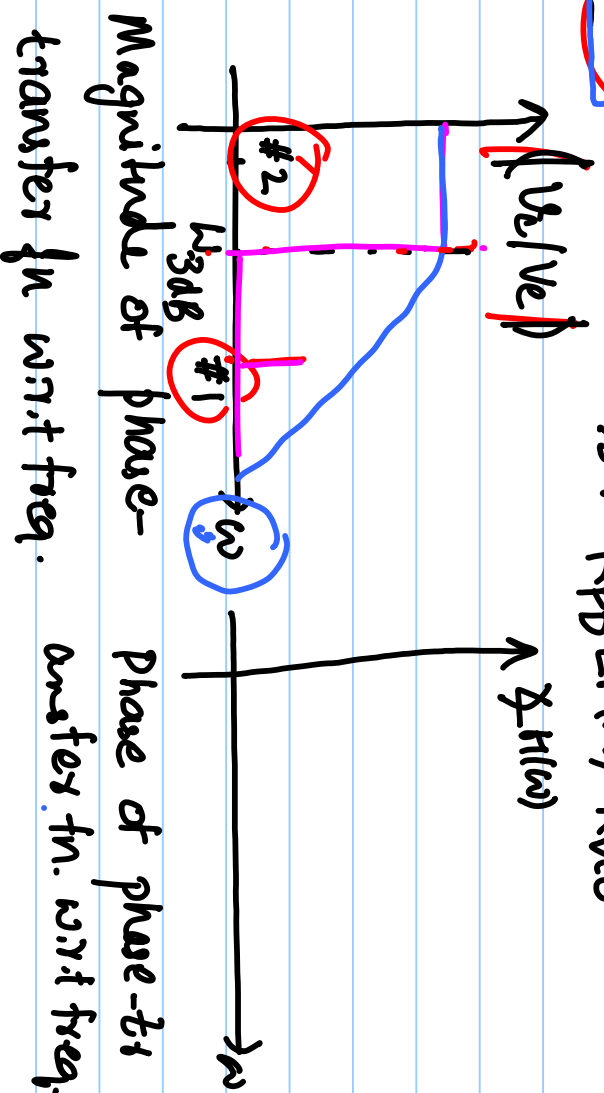
$$= \frac{a_{in} a_o}{2} \left[\sin(\overline{\omega_{in} + \omega_o} t + \dots) \right]$$

$$+ \sin(\overline{\Delta \omega} t + \phi_{er}(\omega)) \checkmark$$

$$\omega_{in} = \omega_o \times 1.001$$

$$\Rightarrow \omega_{in} + \omega_o = 2.001 \omega_o \quad \#1 \text{ filter}$$

$$\omega_{in} - \omega_o = 0.001 \omega_o \quad \#2 \checkmark$$



$$V_c = \frac{a_{in} a_o}{2} \left[\sin(\overline{\omega_{in} + \omega_o} t + \phi_{in}(0) + \phi_o(0)) + \sin(\Delta \omega(t) + \phi_{ex}(0)) \right]$$

$$V_c = \frac{a_{in} a_o}{2} \sin(\Delta \omega(t) + \phi_{ex}(0)) \quad v = \frac{a_{in} a_o}{2} \sin(\Delta \omega(0) \cdot t - K_{vco} V_c(t) + \phi_{ex}(0))$$

$$\omega_{in}(t) = \omega_{in}(0) = \frac{a_{in} a_o}{2} \sin(\Delta \omega(0) \cdot t - K_{vco} V_c(t) + \phi_{ex}(0))$$

$$\omega_o(t) = \omega_{free} + K_{vco} \cdot V_c(t)$$

$$\omega_{in}(t) - \omega_o(t) = \omega_{in}(0) - \omega_{free} - K_{vco} \cdot V_c(t)$$

$$= \Delta \omega(0) - K_{vco} \cdot V_c(t)$$

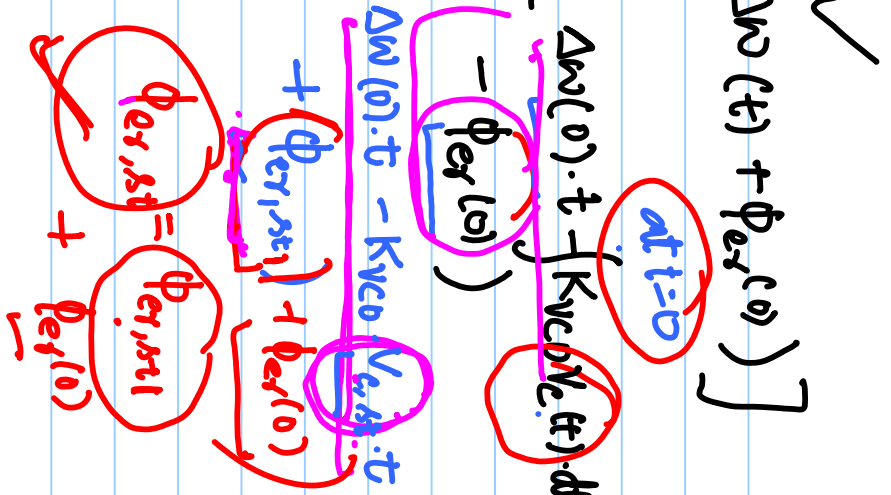
#1: $\Delta \omega(0) = 0$

$$\Delta \omega(t) = \Delta \omega(0) - K_{vco} \cdot V_c(t)$$

$$0 = 0 - K_{vco} \cdot V_c \Rightarrow V_c = 0$$

#2: $\Delta \omega(0) \neq 0$ (in steady state)

$$\omega_{in} = \omega_o \Rightarrow \Delta \omega(0) = K_{vco} \cdot V_{c,ss} = K_{vco} \left(\frac{1}{t \rightarrow \infty} V_c \right)$$

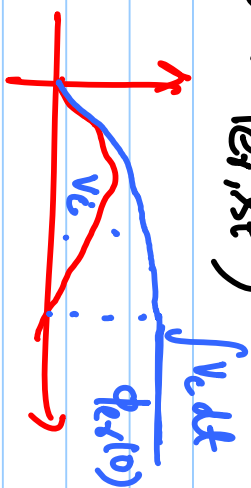


$$V_{crst} = \frac{\Delta \omega(0)}{K_{vco}}$$

$$\Delta \omega(0) = K_{vco} \cdot V_{crst}$$

$$V_{crst} = \frac{a_{in} a_0}{2} \sin \left(\Delta \omega(0) \cdot t + \phi_{crst} \right)$$

$$= \frac{a_{in} a_0}{2} \sin(\phi_{crst})$$



$$\phi_{crst} = \sin^{-1} \left(\frac{2 V_{crst}}{a_{in} a_0} \right)$$

$$V_c(t) = \frac{a_{in} a_0}{2} \sin(\phi_{crst}(0) + \Delta \omega(0) \cdot t - \int_0^t K_{vco} V_c(\tau) \cdot d\tau)$$

= 0

$$(0) \quad \phi_{crst}(0)$$

$$\sin(\phi_{crst}) = \frac{2 V_{crst}}{a_{in} a_0} \Big|_{a_{in}, a_0=1} = 2 V_{crst}$$

$$\Rightarrow -1 \leq \sin(\varphi_{er,st}) \leq +1$$

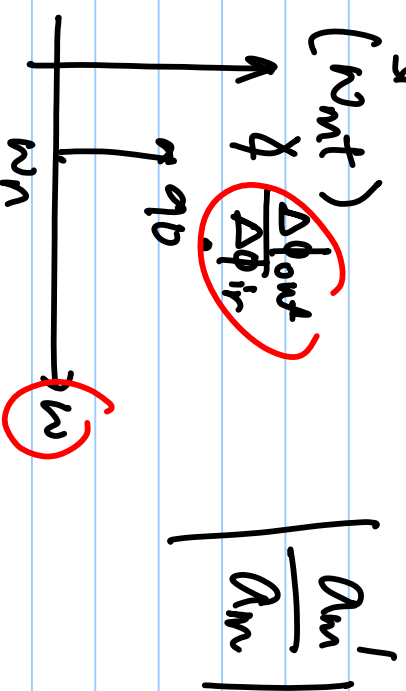
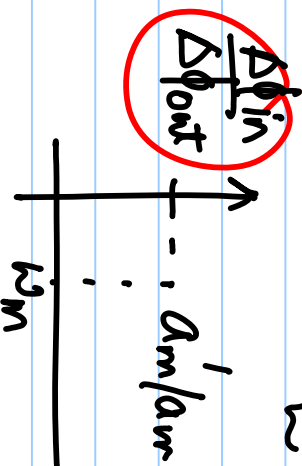
$$-\frac{1}{2} \leq v_{er,st} \leq \frac{1}{2}$$

$$-\frac{1}{2} \leq \frac{\Delta v_{lo}}{k_{ve}} \leq \frac{1}{2}$$

$$-\frac{k_{ve}}{2} \leq \Delta v_{lo} \leq \frac{k_{ve}}{2}$$

$$v \Delta \phi_{in} = a_m \sin(\omega_m t)$$

$$v \Delta \phi_{out} = a_m' \cos(\omega_m t)$$



$$\left| \frac{a_m'}{a_m} \right|$$