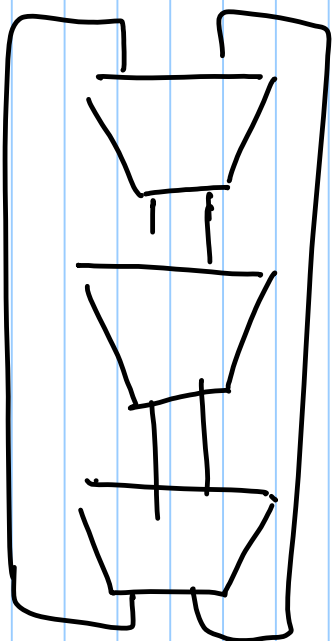
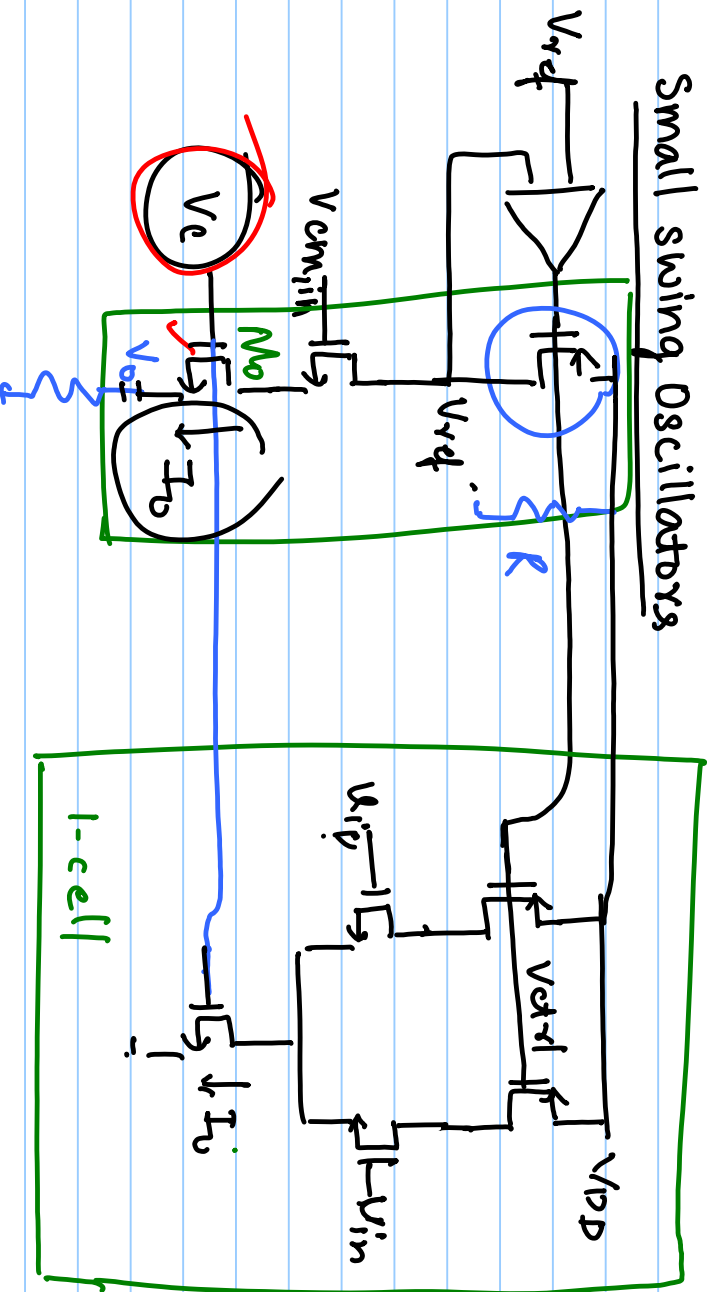


Lecture # 22

Note Title

19-09-2018

Small swing Oscillators



$$f_{osc} = \frac{\sqrt{3}}{RC} = \frac{\sqrt{3}}{C} \frac{K_M(V_{DD}-V_{ov1})}{R}$$

$$R = \frac{V_{DD}-V_{rd}}{I_D}$$

$$V_{out,max} \dots I_D \cdot R = \underline{V_{DD}-V_{rd}}$$

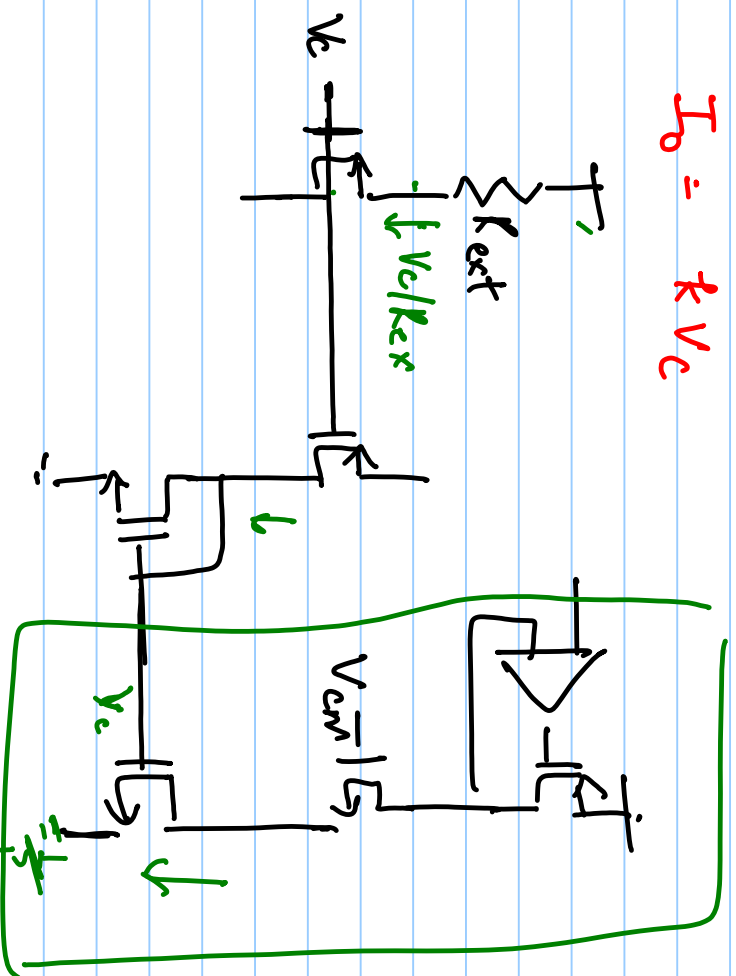
$$V_c / R_{eff}$$

$$W_{osc} = \frac{\sqrt{3}}{RC} \cdot f_{osc} = \frac{1}{2\pi} \frac{\sqrt{3}}{RC} = \frac{\sqrt{3}}{2\pi C} \frac{I_D}{V_{DD}-V_{rd}} \quad \checkmark \quad | I_D = g_m V_c \checkmark \Rightarrow f_{osc} \propto V_c$$

Case 1. f : fixed, vary amp.

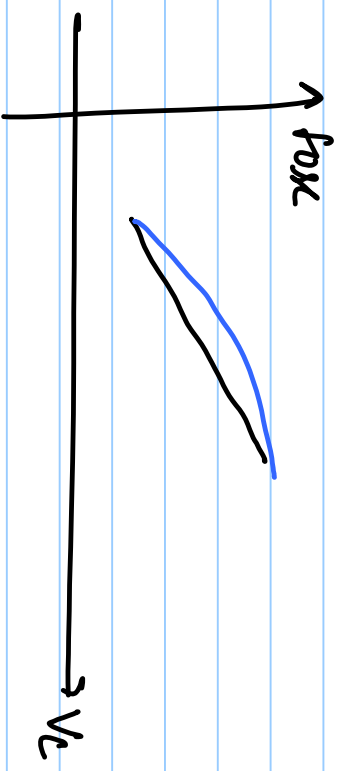
Case 2: f : vary, fixed amp.

$$I_0 = kV_c$$



1. Amplitude
 2. Frequency
- } Tunability.

linearity in freq. tunability

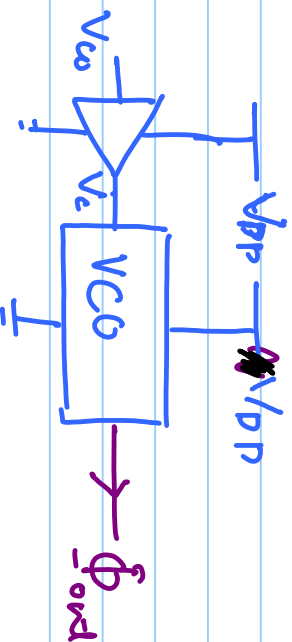
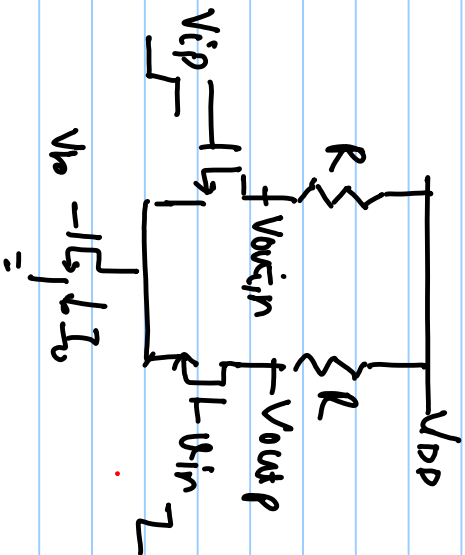
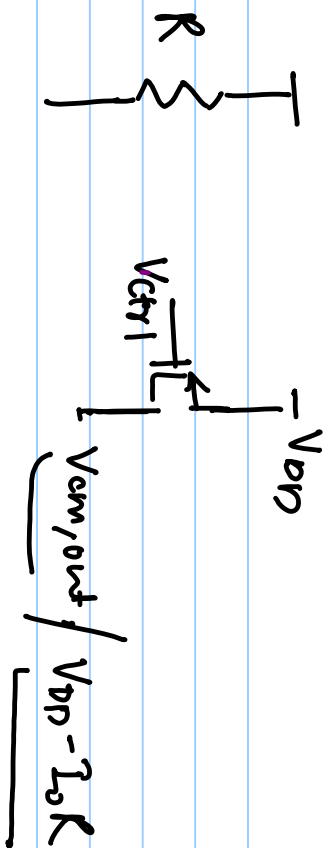


$$I_{ox} = f(V_c)$$

$$I_{ox} = k_0 V_c + k_1 V_c^2 + \dots$$

$$= g_m V_c$$

= /



PSRR: Power Supply Rejection Ratio.

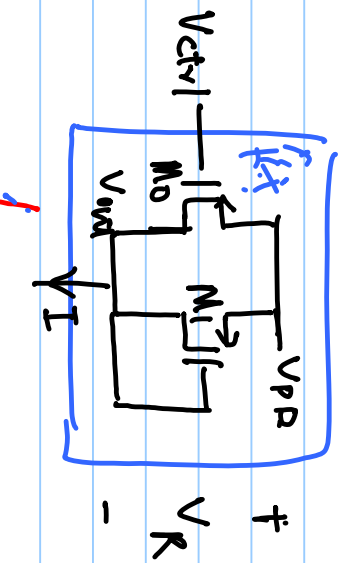
$$V_{out,p} = \Delta V + V_{DD} - \left(\frac{I}{2} - \Delta I\right) R_{right}$$

$$V_{out,n} = \Delta V + V_{DD} - \left(\frac{I}{2} + \Delta I\right) R_{left}$$

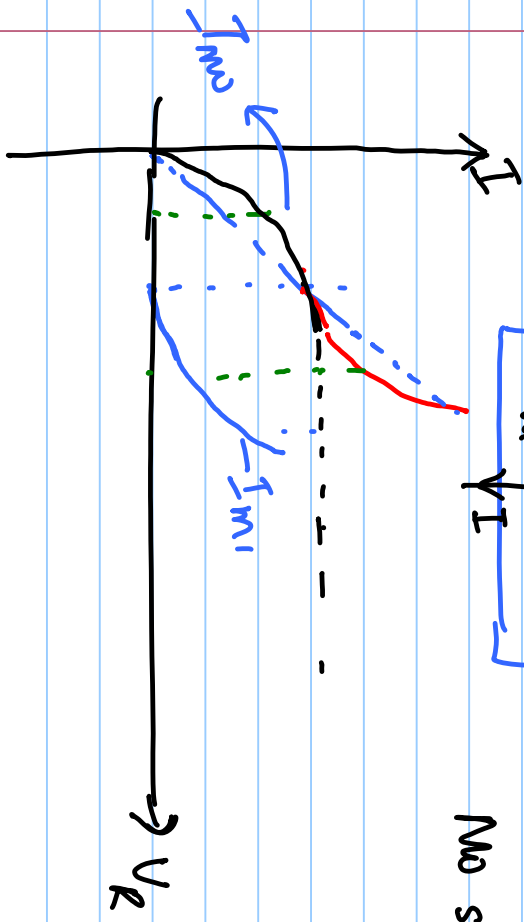
$V_{out,p} - V_{out,n}$	$= \frac{I}{2} (R_{right} - R_{left}) + \Delta I (R_{right} - R_{left})$
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$$V_{out} = \left(\frac{I}{2} - \Delta I \right) (R_{eff} - R_{sig})$$

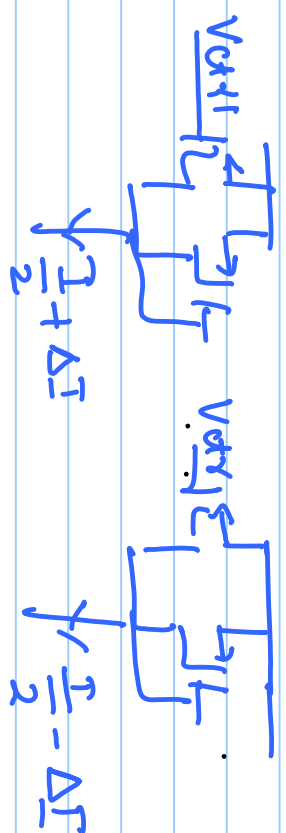
$$= \left(\frac{I}{2} - \Delta I \right) \left[R (V_{DD} + \Delta V, V_{out,n}) - R (V_{DD} + \Delta V, V_{out,p}) \right]$$

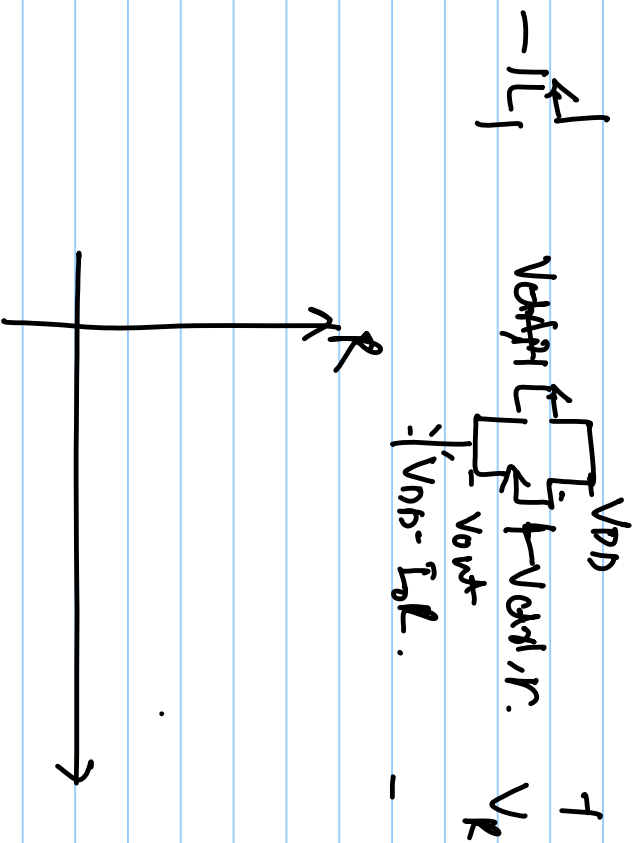


$V_R = 0, V_{out} = V_{DD} ; M_0 = ON, M_1 = OFF$
 $V_R \gg |V_{TP}|, V_{out} = V_{DD} - |V_{TP}| ; M_1 : \text{saturation.}$
 $M_0 \text{ sakti } V_R > |V_{DD} - V_{ctrl} - |V_{TP}|$



$$I_{M1} = \frac{K_N}{2L} (V_R - |V_{TP}|)^2$$





$$R_{pmos} = \frac{1}{\frac{k_p}{L} \left(V_{DD} - V_{GM1,r} - \frac{V_R}{2} - |V_{TP}| \right)}$$

$$R_{nmos} = \frac{1}{\frac{k_n}{L} \left(V_{GM1,n} - V_{TN} - \frac{V_R}{2} \right)}$$