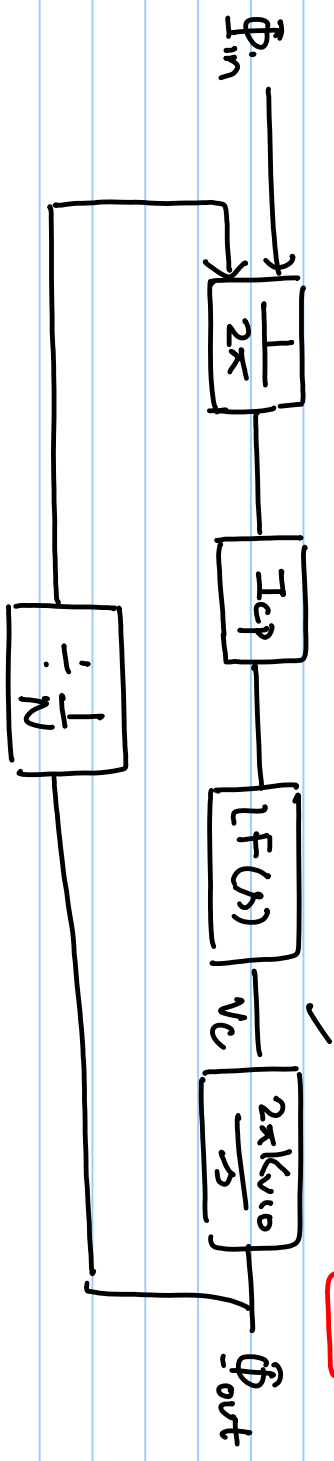


# Lecture #18

$A_{fwd} = K_{vco} \omega_c$



## Application

1. Noise  $\rightarrow$   $\omega_u$ , Power
2. Stability  $\rightarrow$   $\Phi_m$

$\omega_u, \Phi_m$

$$L_{in}(s) = \frac{1}{2K} I_{cp} \frac{(1+s/\omega_z)}{(1+s/\omega_{p3})} \frac{1}{s(1+s/\omega_c)} \frac{2\pi K_{vco}}{s} \frac{1}{N}$$

$I_{cp}$   $R$   $C_1$   $C_2$   $K_{vco}$  ✓ ✓

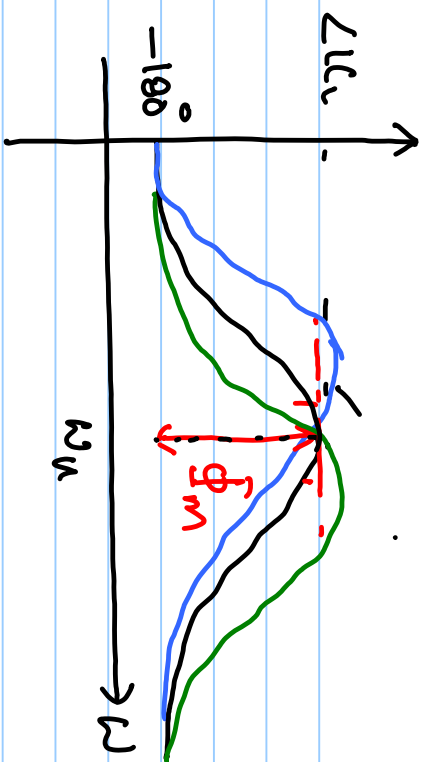
$$\omega_z = \frac{1}{RC_1}$$

$$\omega_{p3} = \frac{1}{RC_1C_2} = \frac{1}{\sqrt{RC_1}} = \frac{C_2}{C_1 + C_2}$$

$$\omega_{p3} = \frac{1}{RC_1C_2} = \frac{1}{\sqrt{RC_1}} = \frac{C_2}{C_1 + C_2}$$

$K_{vco}$  ✓ ✓

$$\omega_{p3} = \frac{1}{RC_1C_2} = 1 + \frac{C_1}{C_2}$$



$$L_C = -180^\circ + \tan^{-1}\left(\frac{\omega_u}{\omega_2}\right) - \tan^{-1}\left(\frac{\omega_u}{\omega_{p3}}\right)$$

$$\Phi_m = \tan^{-1}\left(\frac{\omega_u}{\omega_2}\right) - \tan^{-1}\left(\frac{\omega_u}{\omega_{p3}}\right)$$

$$\left. \frac{d\Phi_m}{d\omega} \right|_{\omega=\omega_u} = 0 \Rightarrow \left| \frac{1}{1 + \left(\frac{\omega}{\omega_2}\right)^2} \times \frac{1}{\omega_2} - \frac{1}{1 + \left(\frac{\omega}{\omega_{p3}}\right)^2} \times \frac{1}{\omega_{p3}} \right|_{\omega=\omega_u} = 0$$

$$\frac{\omega_2}{\omega_2^2 + \omega_u^2} - \frac{\omega_{p3}}{\omega_{p3}^2 + \omega_u^2} = 0$$

$$\omega_u = \sqrt{\omega_2 \cdot \omega_{p3}}$$

$$\omega_u = \sqrt{\frac{1}{R C_1} \times \frac{1}{\frac{R C_1 C_2}{C_1 + C_2}}} = \frac{1}{R C_1} \sqrt{\frac{C_1 + C_2}{C_2}} = \omega_2 \sqrt{\frac{C_1 + 1}{C_2}} \quad \checkmark$$

$$\frac{\omega_1}{\omega_2} = \sqrt{1 + \frac{C_1}{C_2}}$$

$\omega$

$$\frac{\omega_1}{\omega_{p3}} = \frac{\omega_2 \sqrt{1 + C_1/C_2}}{\omega_2 \left(1 + \frac{C_1}{C_2}\right)}$$

$$\Phi_m = \tan^{-1} \left( \frac{\omega_1}{\omega_2} \right) - \tan^{-1} \left( \frac{\omega_{p3}}{\omega_2} \right)$$

$=$

$$\frac{1}{\sqrt{1 + \frac{C_1}{C_2}}}$$

$$\begin{aligned} &= \tan^{-1} \left( \sqrt{1 + \frac{C_1}{C_2}} \right) - \tan^{-1} \left( \sqrt{\frac{1}{1 + \frac{C_1}{C_2}}} \right) \\ &= \tan^{-1}(x) - \tan^{-1} \left( \frac{1}{x} \right) \end{aligned}$$

$$\tan(\dot{\Phi}_m) = \frac{x - \frac{1}{x}}{1 + x \cdot \frac{1}{x}} = \frac{x - \frac{1}{x}}{2}$$

$$\frac{C_1}{C_2} = f(\Phi_m)$$

✓

$$\checkmark \frac{C_1}{C_2}$$

$$\checkmark \omega_z = \omega_u \sqrt{1 + \frac{C_1}{C_2}} = \frac{1}{RC_1} \xrightarrow{R} C_1 \xrightarrow{\frac{C_1}{C_2}} C_2$$

$$\omega_u = \sqrt{\omega_z \cdot \omega_{p3}}$$

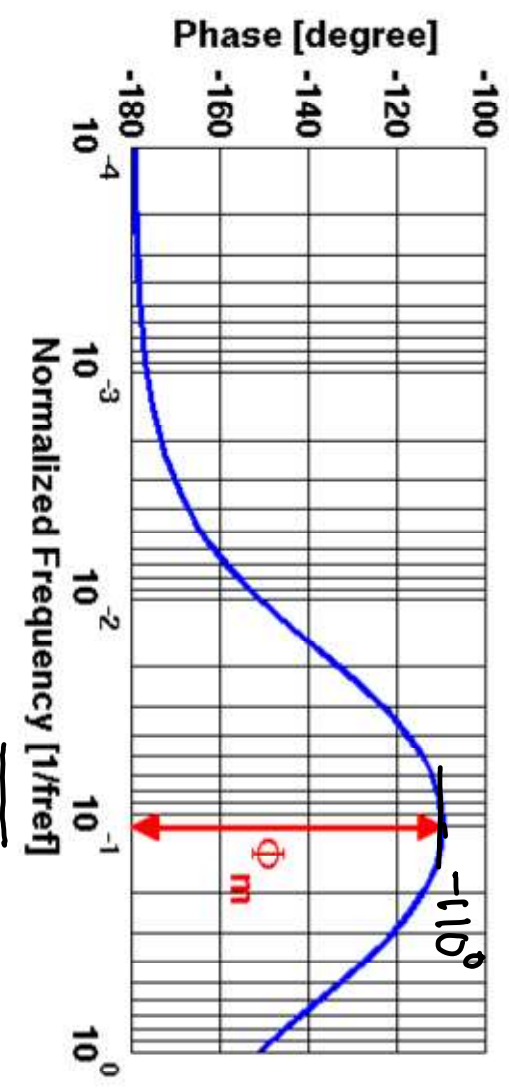
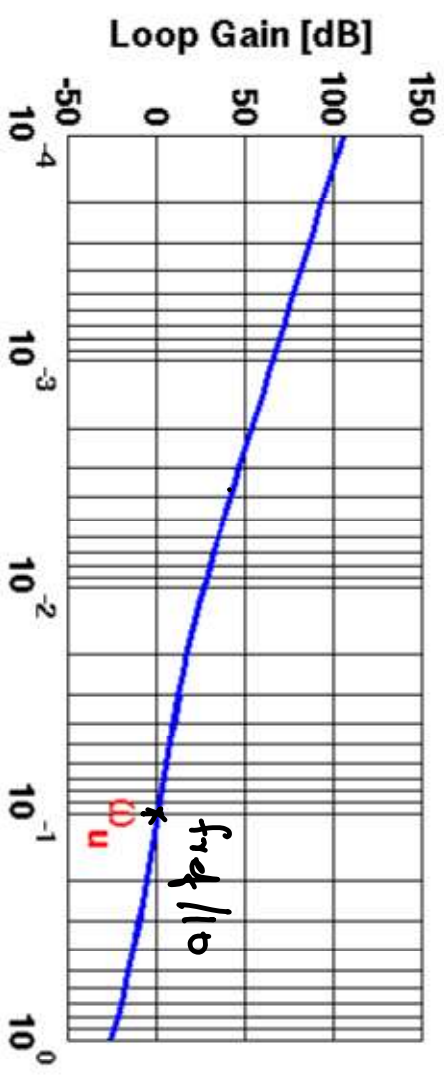
Noisy  $\uparrow$

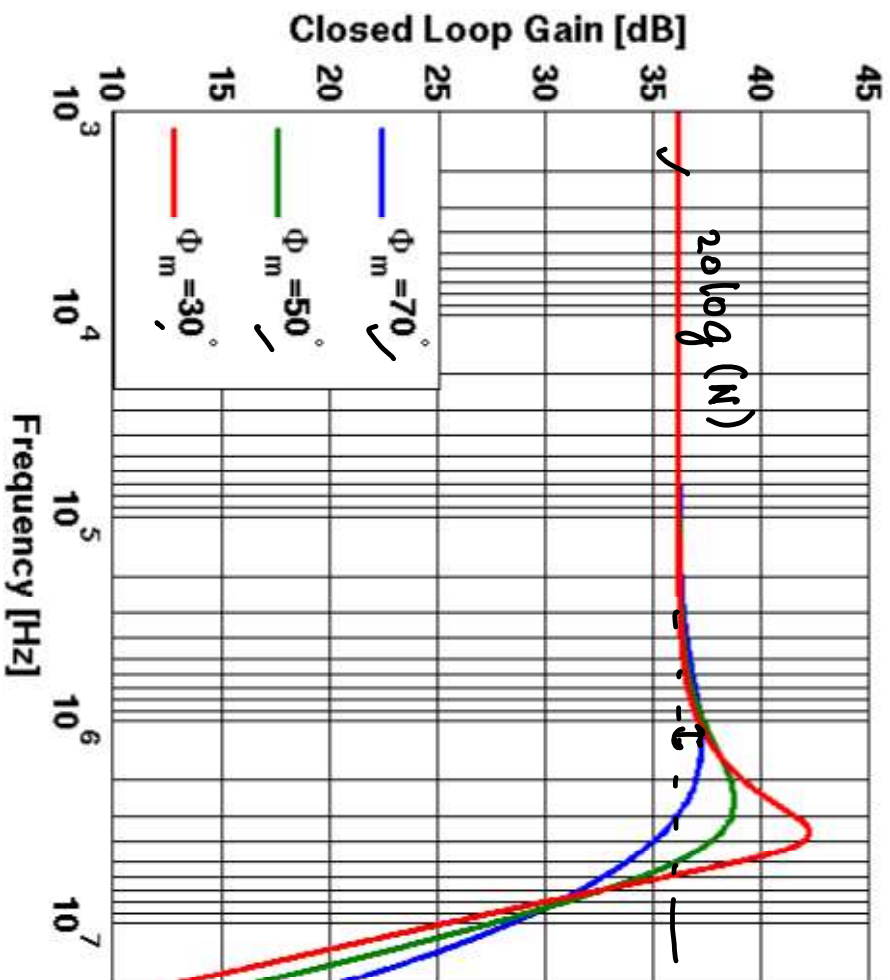
$$|LC_u(\omega_u)| = 1$$

$$\Rightarrow \frac{K_{UCD}}{N} \frac{1}{\omega_u^2 (C_1 + C_2)} \frac{\sqrt{1 + (\omega_u/\omega_z)^2}}{\sqrt{1 + (\omega_u/\omega_{p3})^2}}$$

$$\times I_{cp} = 1$$

$$I_{cp} =$$



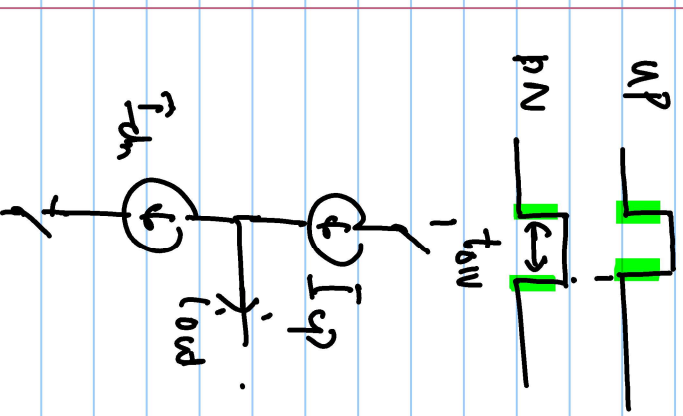
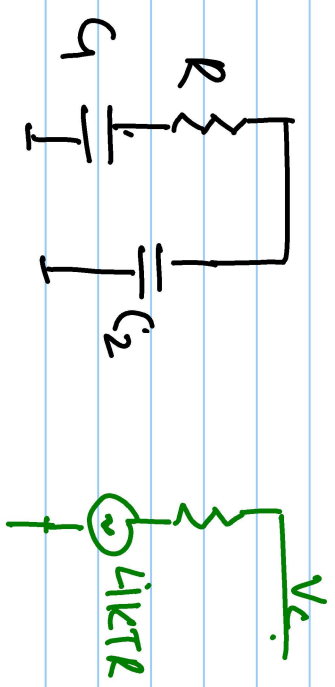
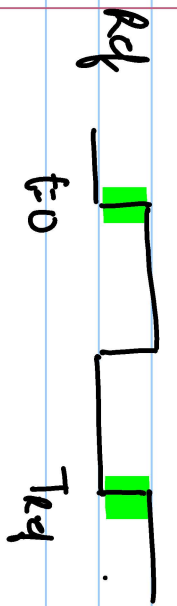
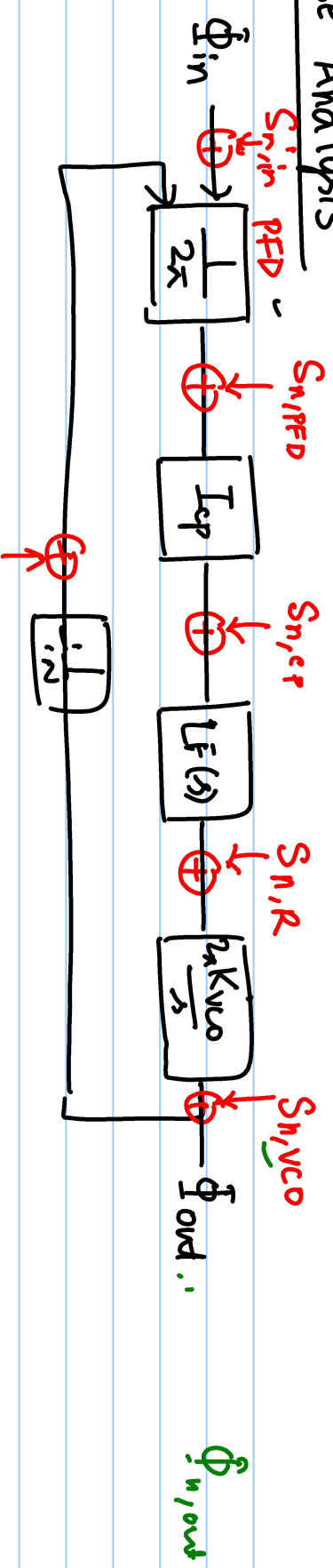


$$\frac{\Phi_{out}}{\Phi_{in}} = \frac{N \cdot L(s)}{1 + L(s)}$$

$$\approx \frac{N L(s)}{L(s)}$$

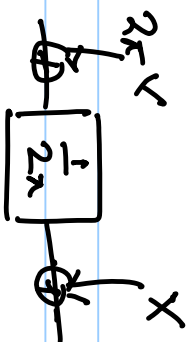
$$N \ll \frac{2\pi f T}{10}$$

# Noise Analysis



$$i_{out} = i_{n,uP} - i_{n,pN}$$

# Noise Transfer Functions



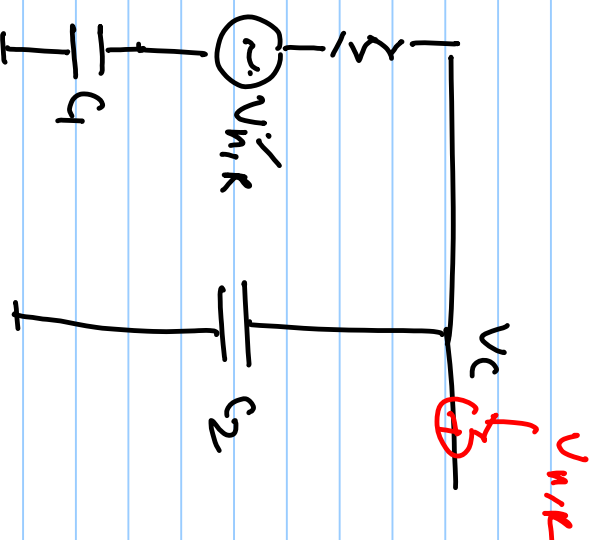
$$NTF_{in} = \frac{\Phi_{n,out}}{\Phi_{n,in}} = 1 \times \frac{N \cdot L_n}{1 + L_n}$$

$$NTF_{PFD} = 2k \frac{N \cdot L_n}{1 + L_n}$$

$$NTF_{CP} = \frac{2k}{I_{CP}} \frac{N \cdot L_n}{1 + L_n}$$

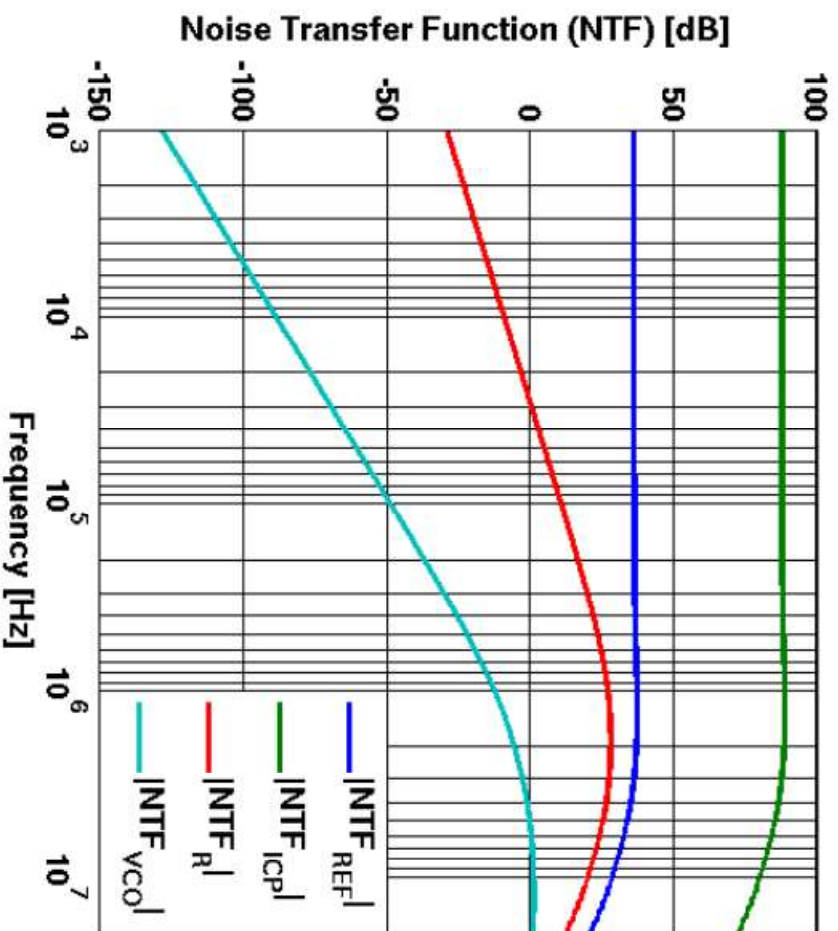
$$NTF_R = \frac{\Phi_{n,out}}{V_{n,R}} = \frac{V_{n,e}}{V_{n,R}} \times \frac{\Phi_{n,out}}{V_{n,e}}$$

$$= \frac{1/sG_2}{R + 1/sC_2 + 1/sC_1} \times \left[ \frac{2k \cdot |G_0| \cdot s}{1 + L_n} \right] \cdot \left[ \frac{s^2 \cdot L_n}{1 + L_n} \right]$$





$$\frac{\Phi_{n, out}}{\Phi_{n, vco}} = \frac{1}{|1 + L_n|}$$



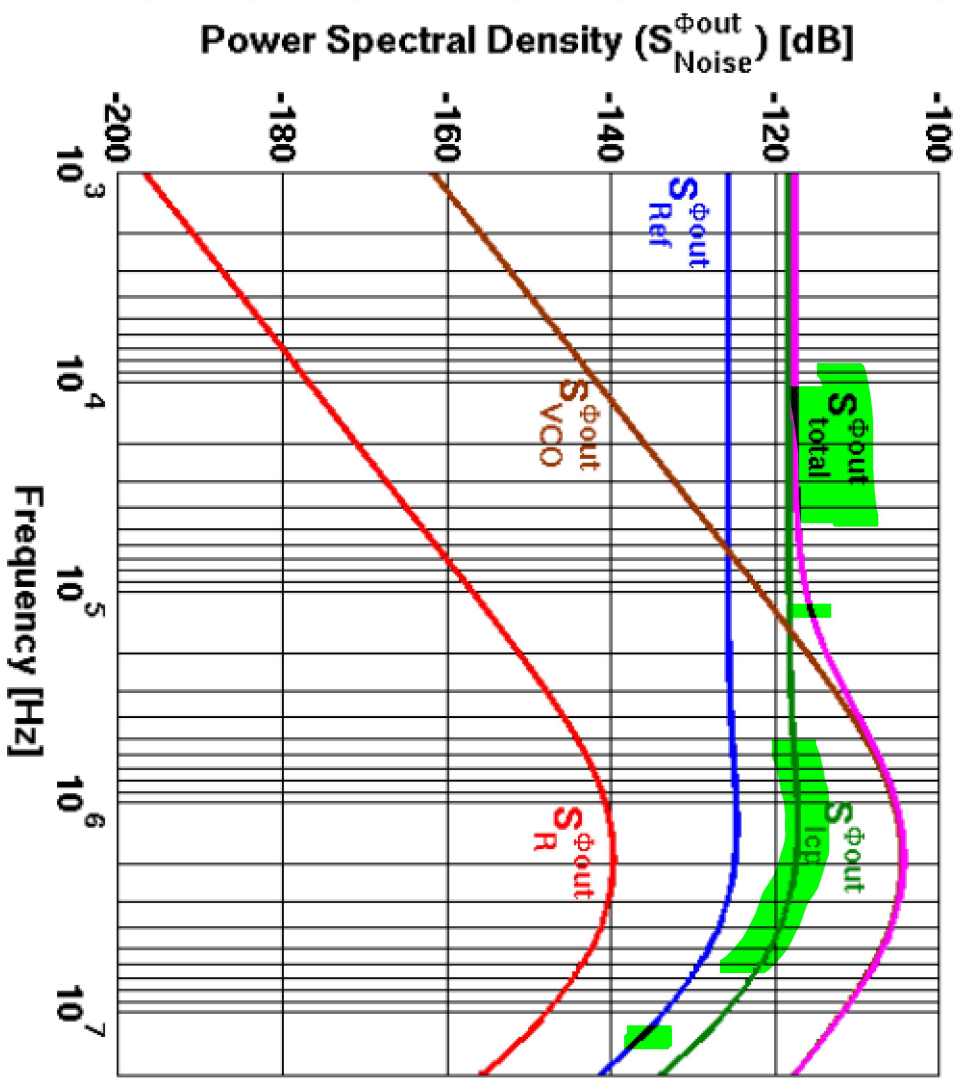
$$S_{n, req}^{out} = S_{n, req} \times |NTF_{ref}|^2$$

$$S_{n, ip}^{out} = S_{n, cp} \times |NTF_{cp}|^2$$

.

$$S_{n, total}^{out} = S_{n, req}^{out} + S_{n, cp}^{out} + \dots$$

$$+ S_{n, vco}^{out} + \dots$$



■