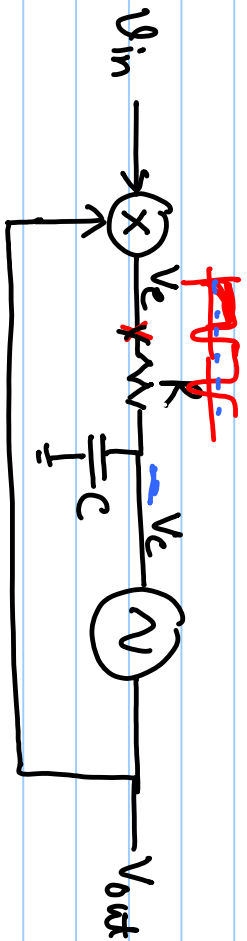


# Lecture #4



$$V_{in} = \sin(\omega_{in} \cdot t)$$

$$V_{out} = \cos(\omega_{out} \cdot t)$$

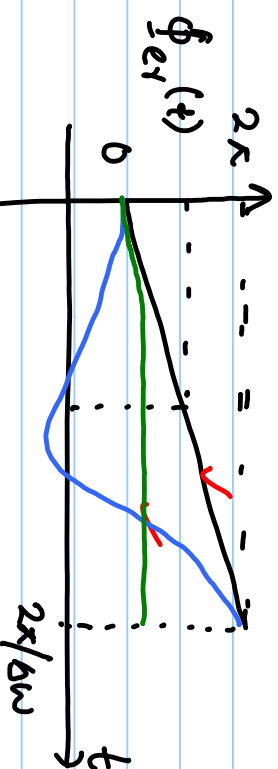
$\omega_{out} = \omega_{free} + 2\pi K_{vco} \cdot V_c$   
 $t=0, V_c=0$   
 $\omega_{out} \approx \omega_{free}$

$$V_c = \frac{1}{2} \left[ \sin(\underbrace{\omega_{in} + \omega_{out}} t) + \sin(\underbrace{\omega_{in} - \omega_{out}} t) \right]$$

$$\Phi_c(t) = \int (\omega_{in} - \omega_{out}) dt$$

$$= \int (\omega_{in} - \omega_{free}) dt - \int 2\pi K_{vco} \cdot V_c \cdot dt$$

$$= \Delta\omega(0)t - 2\pi K_{vco} \int V_c dt = 0$$



$$V_e = \frac{1}{2} \sin(\Phi_e(t))$$

$$= \frac{1}{2} \sin(\Delta\omega(t) \cdot t - 2\pi K_{VCO} \int V_e \cdot dt)$$

$$V_e \approx V_e$$

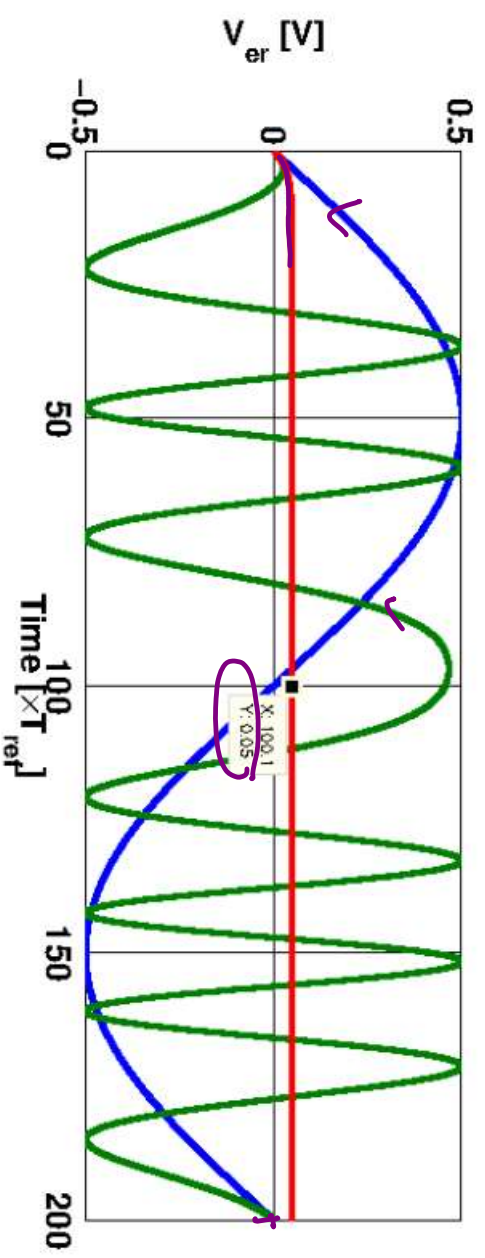
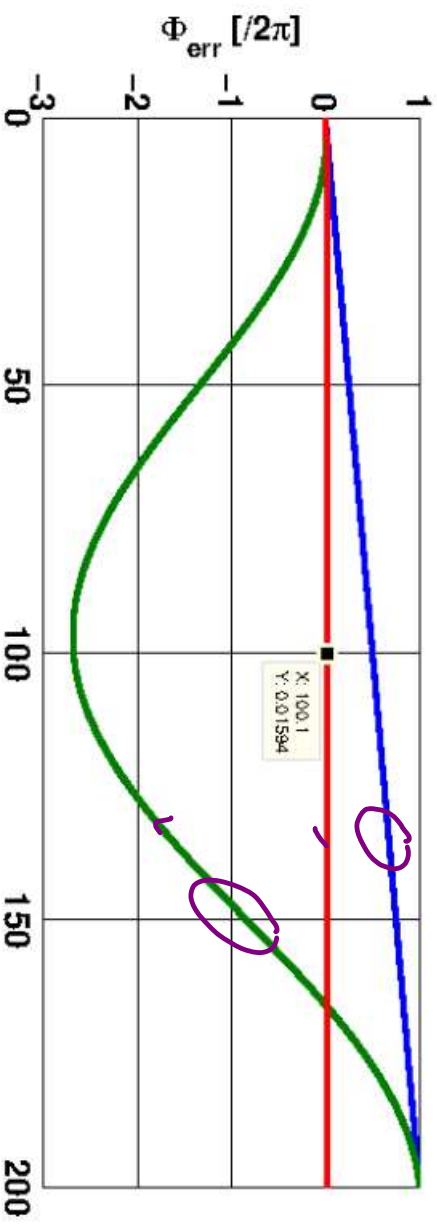
$$= \frac{1}{2} \sin(\Phi_{e,r}(t)) = \frac{1}{2} \sin(\Delta\omega(t) \cdot t)$$

$$\Phi_e(t) = \Delta\omega(0) \cdot t - 2\pi K_{VCO} \cdot K_{pd} \int_0^t \sin(\Phi_{e,r}(t)) \, dt$$

$$= \underbrace{\Delta\omega(0) \cdot t}_0 - \frac{2\pi K_{VCO} \cdot K_{pd}}{\Delta\omega(0)} \underbrace{(1 - \cos(\Delta\omega(0) \cdot t))}_0$$

$$\frac{d\Phi_e(t)}{dt} = \Delta\omega(0) - 2\pi K_{VCO} \cdot K_{pd} \sin(\Phi_{e,r}(t)) = 0$$

$$\Rightarrow \Delta\omega(0) = 2\pi K_{VCO} \cdot K_{pd} \sin(\Phi_{e,r}(0))$$



$$\Delta f = 5 \text{ MHz}$$

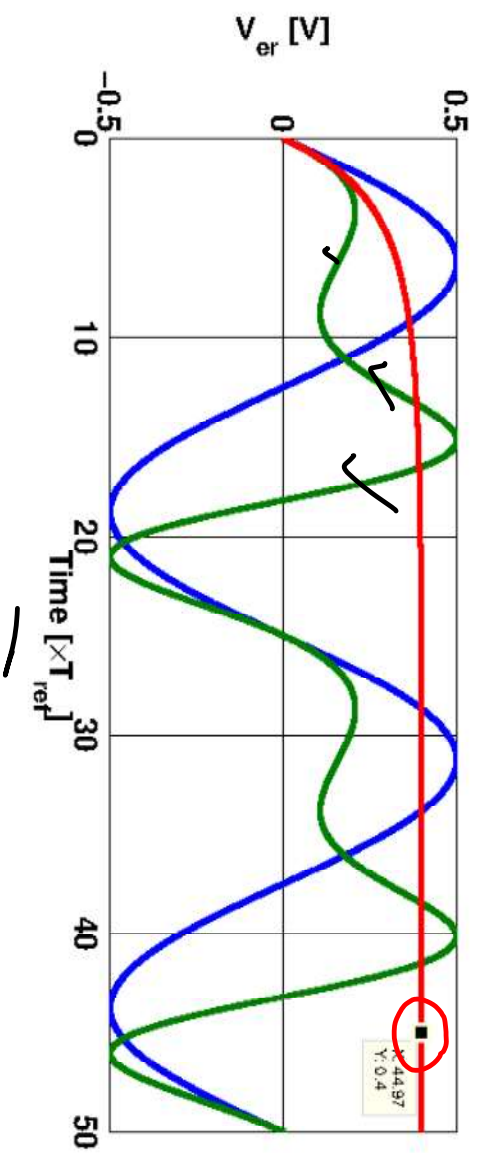
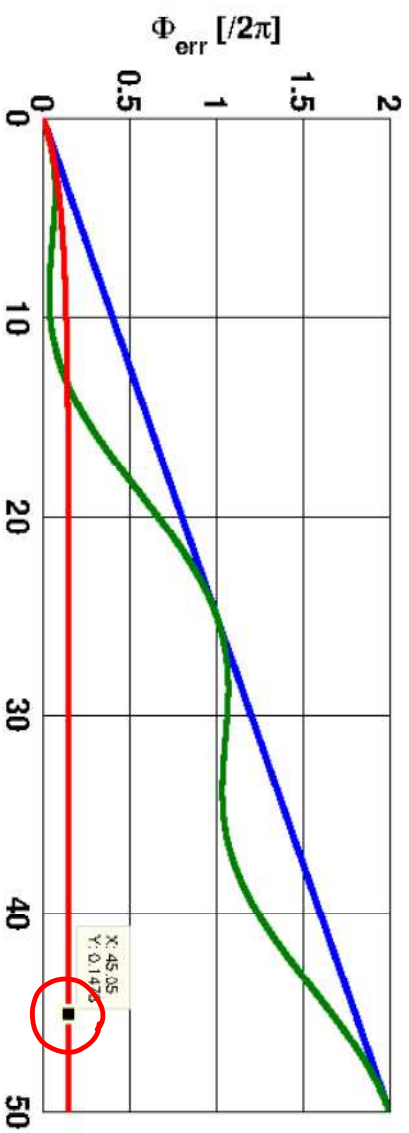
$$2\pi K_{VCO} = 2\pi \times 100 \text{ MHz/s}$$

$$K_{PD} = 1/2$$

$$V_{err} = \sin(\Delta\omega \cdot t)$$

$$\Delta\omega \leq 2\pi K_{VCO} \cdot K_{PD} \sin(\Phi_e)$$

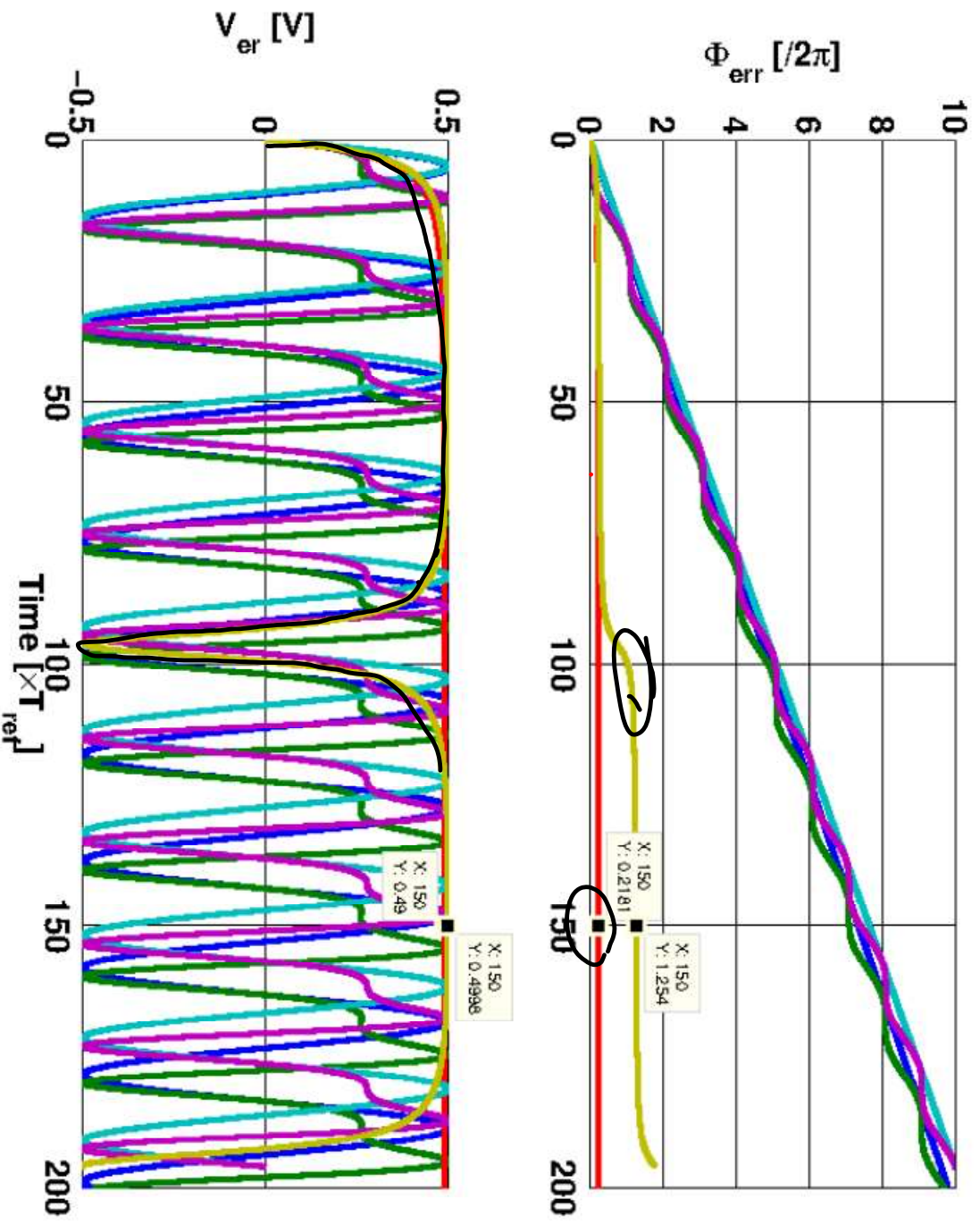
$$\Delta f \leq K_{VCO} \cdot K_{PD}$$



$$\omega_{out} = \omega_{free} + 2\pi K_{vco} \cdot K_{pd} \cdot \sin(\phi_e)$$

$$= \omega_{in}$$

$$\frac{\omega_{in} - \omega_{free}}{2\pi K_{vco} \cdot K_{pd}} = \sin(\phi_e)$$



$$\Delta f_1 = 49 \text{ MHz}$$

$$\Delta f_2 = 51 \text{ MHz}$$

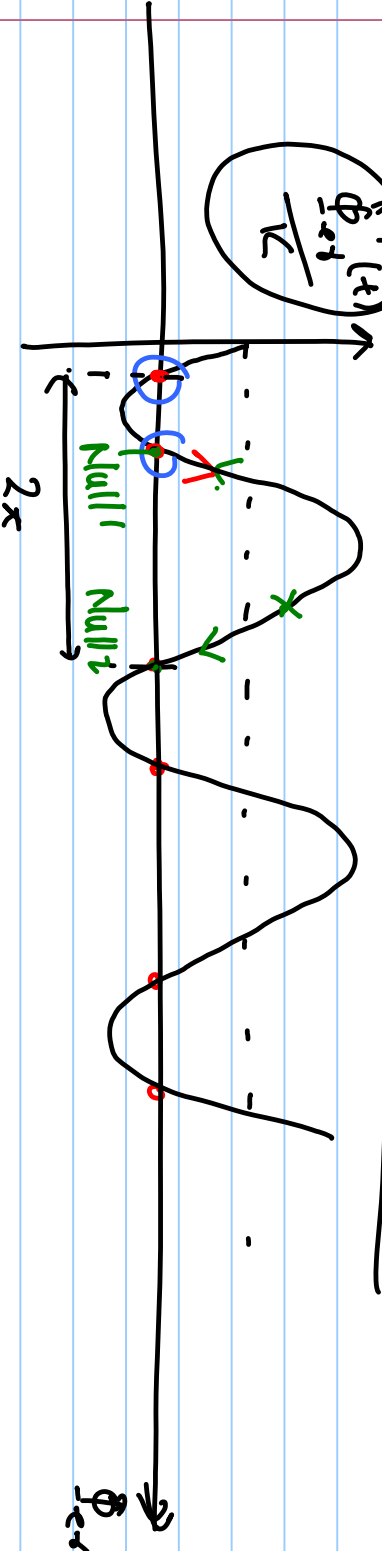
$$\Phi_{in}(t) = \omega_{in} \cdot t + \Phi_{in}(0) \quad \checkmark$$

$$\Phi_{out}(t) = \omega_{out} \cdot t + \Phi_{out}(0) \quad \checkmark$$

$$\Phi_{er}(t) = \omega_{in} - \omega_{out} \cdot t + [\Phi_{in}(0) - \Phi_{out}(0)]$$

$$\Phi_{er}(t) = \Delta\omega \cdot t - \int 2\pi K_{VCO} \cdot K_{PD} \sin(\Phi_{er}) dt + \Phi_{er}(0)$$

$$\frac{d\Phi_{er}(t)}{dt} = \Delta\omega - 2\pi K_{VCO} \cdot K_{PD} \sin(\Phi_{er}(t)) = \Phi_{er}'(t)$$

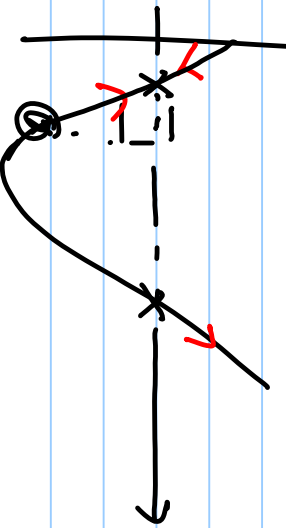


$$\frac{\Phi_{er}'(t)}{K} = \Delta\omega - \sin(\Phi_{er}) = 0 \quad \checkmark$$

\* PLL locks before

$\Phi_e$  cross  $2\pi$

$$\frac{d\eta(t)}{dt} = 0$$



— locks before phase error exceeds  $2\pi$

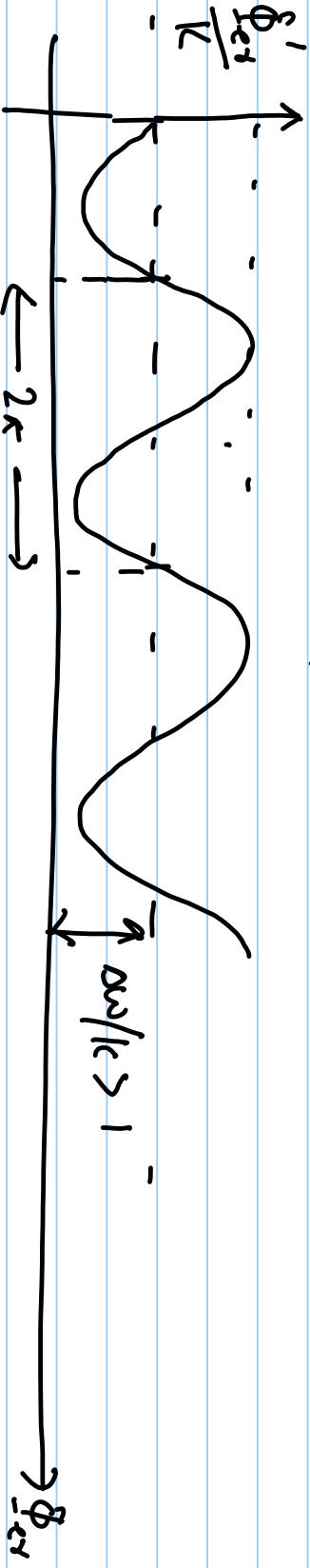
lock-in-range: Frequency ( $\Delta\omega$ ) error which PLL can lock before phase error exceeds  $2\pi$ .

$$\Delta\omega = 2\pi K_{vco} \cdot K_{pd} \leq 1$$

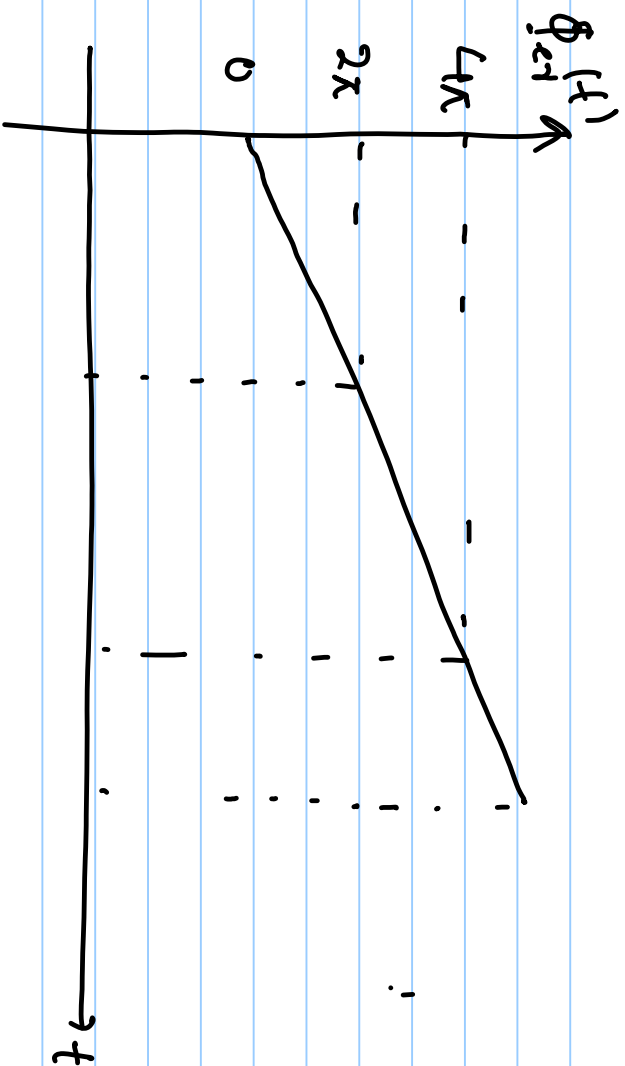
$$\frac{\Delta\omega}{K} > 1$$

$$\Phi_{er}(t) = \Delta\omega(0) \cdot t - 2\pi K_{vco} \cdot K_{pd} \int v_e \cdot dt$$

$$\frac{d\Phi_{er}(t)}{dt} = \Delta\omega(0) - 2\pi K_{vco} K_{pd} \sin(\Phi_{er}(t))$$



$$\Phi_{er}(t) = \Phi_{er}(\theta) + \frac{d\Phi_{er}(t)}{dt} \cdot t$$



$\frac{\Delta \omega}{K} > 1 \rightarrow$  Asymmetric phase error & voltage error w/ non-zero  
 ac voltage