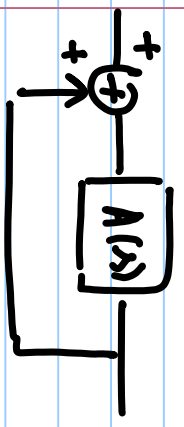
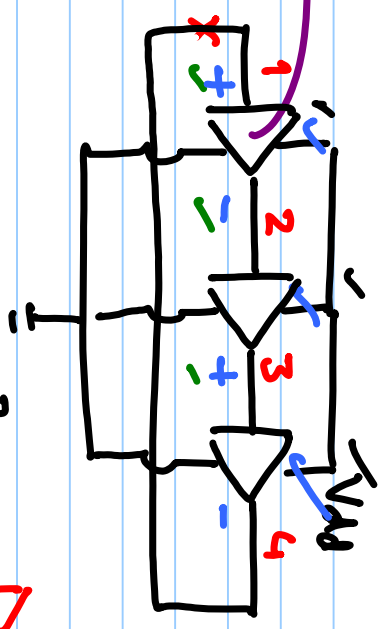
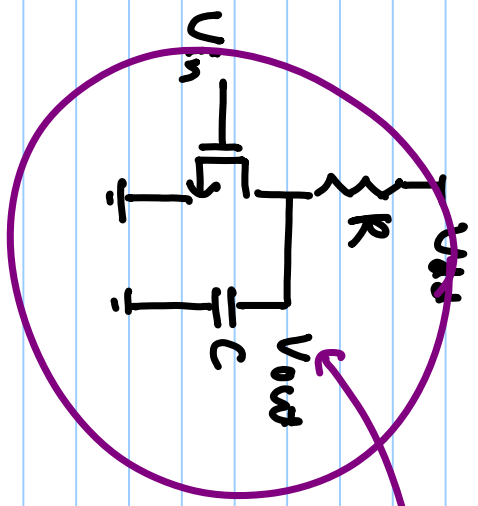


# Lecture # 31

## Oscillator



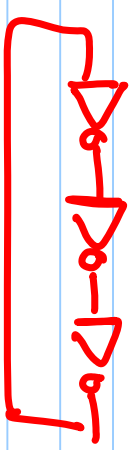
$$|A(j\omega_{osc})| = 1, \quad \angle A(j\omega_{osc}) = 2\pi$$



$$LC_n = \left( \frac{-A_0}{1 + s/\omega_p} \right)^3$$

$$\frac{V_{out}}{V_{in}} = \frac{-g_m(r_o || R)}{1 + sC(r_o || R)}$$

$$\approx \frac{-g_m R}{1 + sCR} = A_0$$



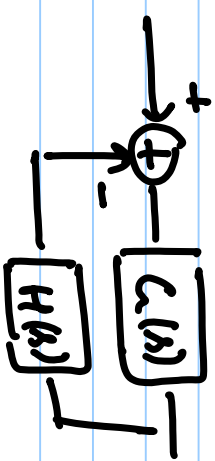
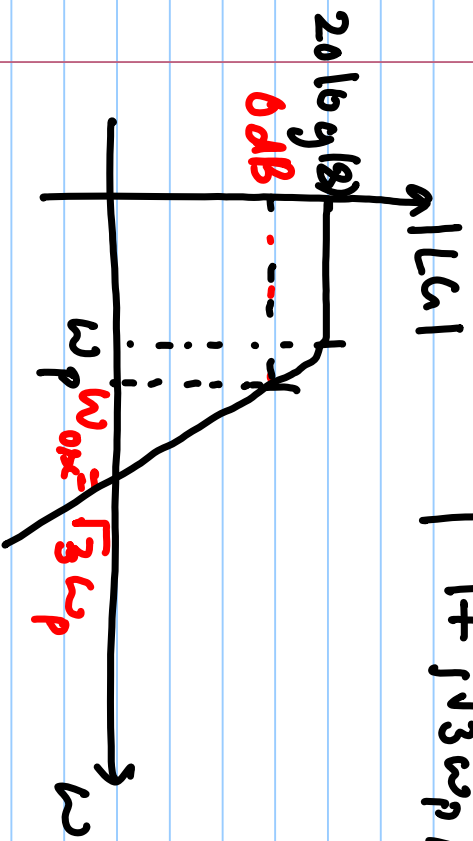
$$|LC_n(\omega_{osc})| = 1$$

$$\angle LC_n(\omega_{osc}) = 2\pi \times 3 = -180^\circ - 3\text{tan}^{-1}(\omega_{osc}/\omega_p) = -360^\circ$$

$$\tan^{-1}\left(\frac{\omega_{0RC}}{\omega_p}\right) = 60^\circ \Rightarrow \frac{\omega_{0RC}}{\omega_p} = \tan(60^\circ)$$

$$\Rightarrow \omega_{0RC} = \sqrt{3} \omega_p = \frac{\sqrt{3}}{RC}$$

$$|G_u| = \frac{A_0^3}{\left|1 + j\sqrt{3}\omega_p/\omega_p\right|^3} = \frac{A_0^3}{2^3} \Rightarrow A_0 = 2$$



$$\frac{C_u(s)}{1 + C_u(s)H(s)}$$

$$L_u = \frac{-(2)^3}{(1 + s/\omega_p)^3}$$

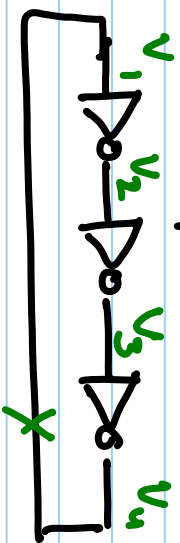
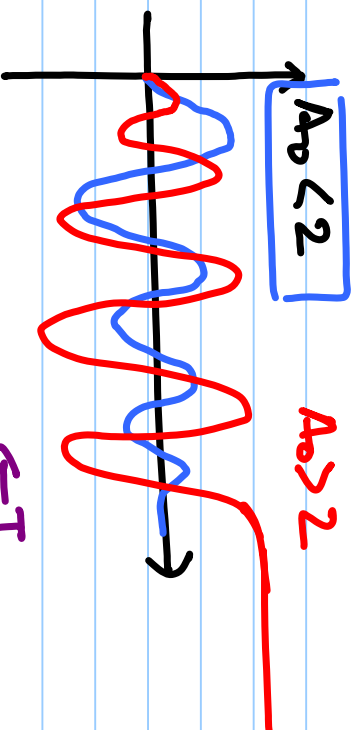
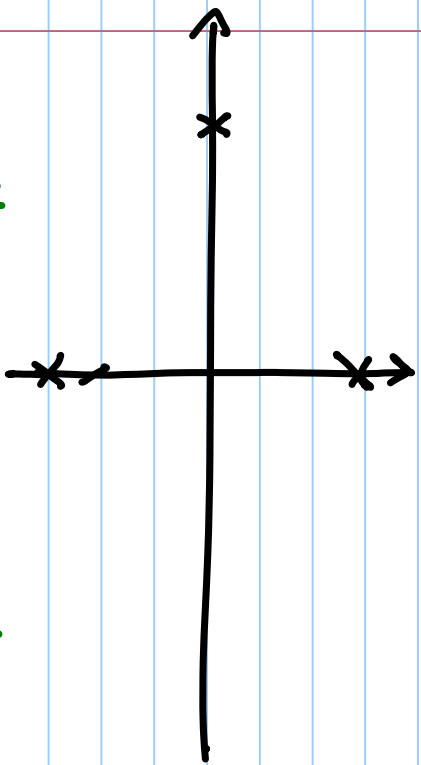
$$\frac{L_u}{1 + L_u} = \frac{-A_0^3}{-A_0^3 - (1 + s/\omega_p)^3}$$

$$(1 + s/\omega_p)^3 + A_0^3 = 0$$

$$(1 + s/\omega_p)^3 = -A_0^3$$

$$(-1)^{1/3} = e^{j\pi/3} + j2e^{2\pi/3}$$

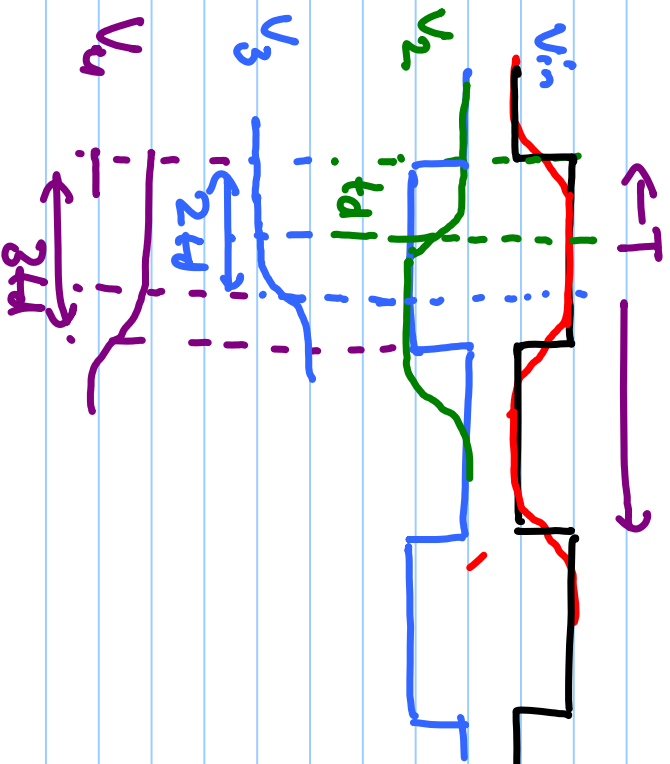
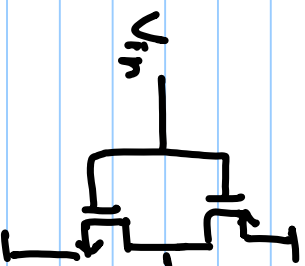
$$, k = 0, 1, 2$$

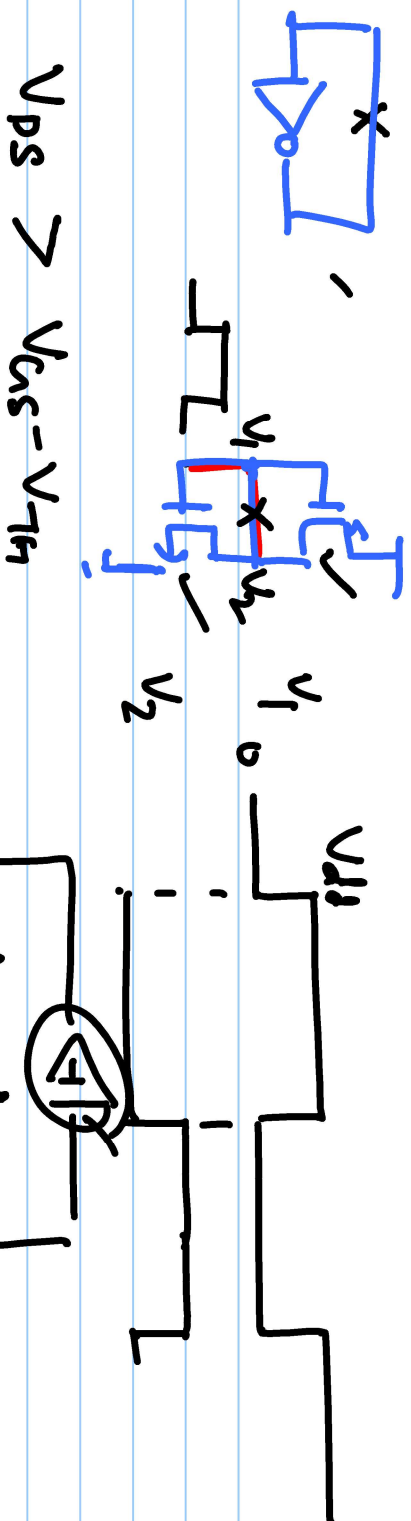


$$T = 3td$$

$$T = 6td$$

$$f_{osc} = \frac{1}{T} = \frac{1}{6td}$$





## Oscillator Summary:

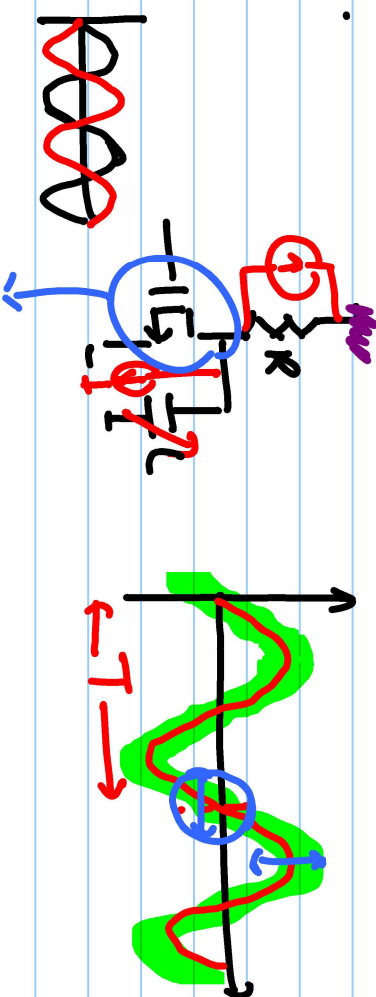
- 1) Oscillation frequency,  $\omega_{osc} = \frac{\sqrt{3}}{RC}$ ,  $f_{osc} = \frac{\sqrt{3}}{2\pi RC}$
- 2) Amplitude: limited output swing.

3) Power

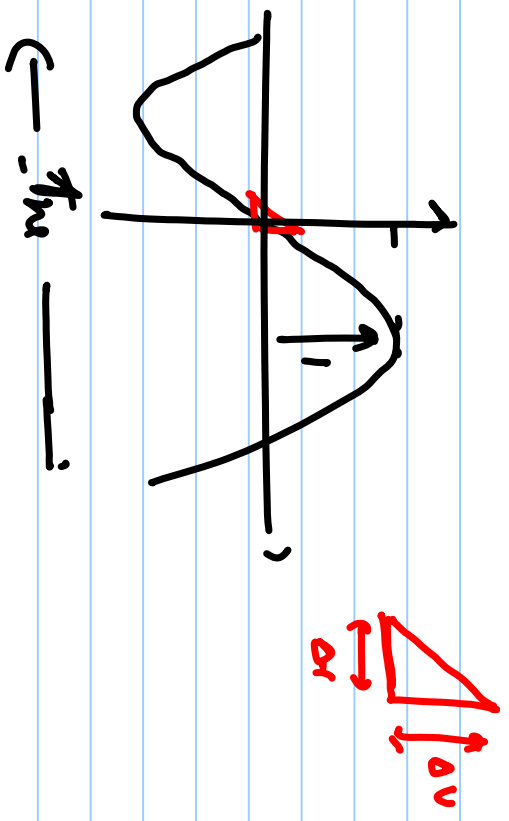
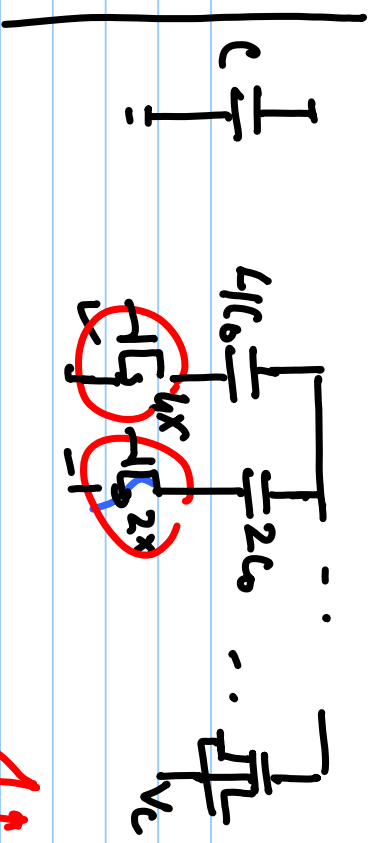
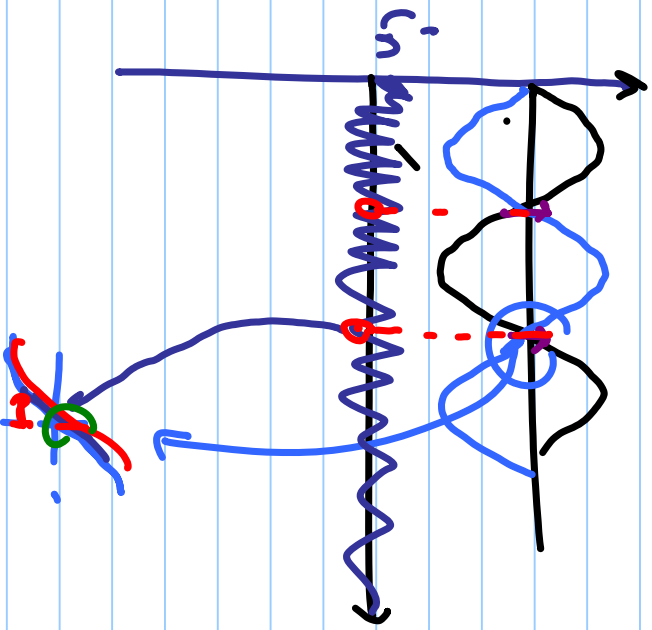
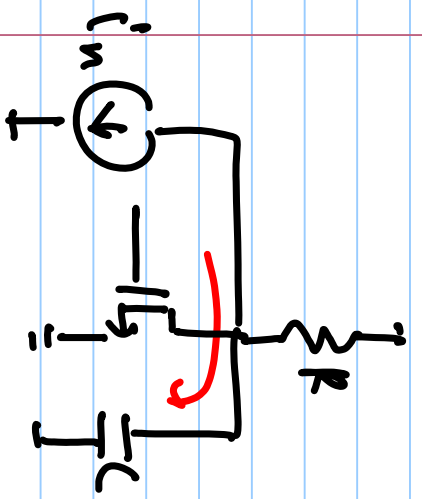
4) Phase noise / Jitter

$$\text{For } R \quad \bar{i}_n^2 = \frac{4kT}{R} \quad A^2 / \text{Hz}$$

$$\text{Model } \bar{i}_n^2 = 8kT/3 g_m \quad A^2 / \text{Hz}$$



5)



$$\frac{dV_{out}}{dt} : AW = 1 \cdot 2\pi \cdot 10^9 = \frac{\Delta V}{\Delta t}$$

$$\Delta V = 2\pi \times 10^9 \times 1 \text{ ps} = 6.28 \times 10^{-3} = \underline{\underline{6.28 \text{ mV}}}$$