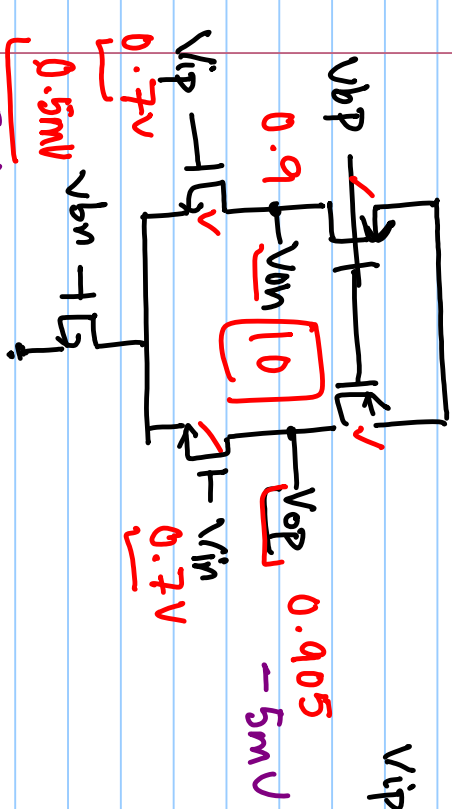
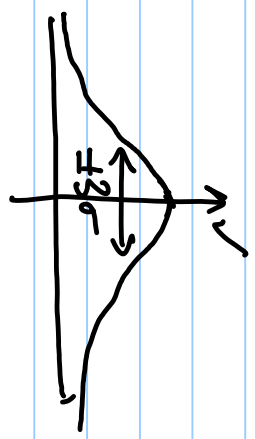


# Lecture # 4b

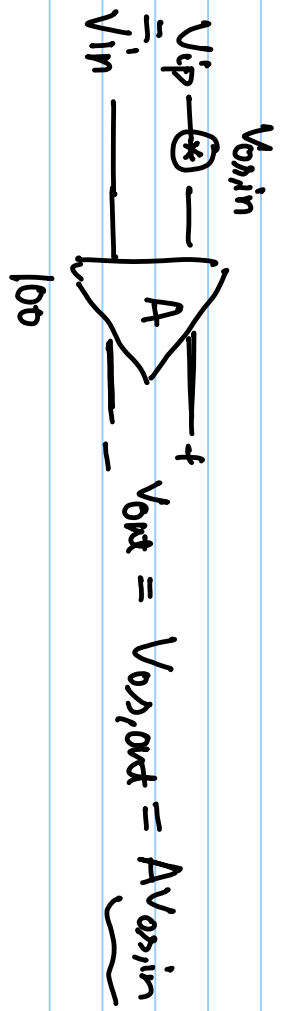
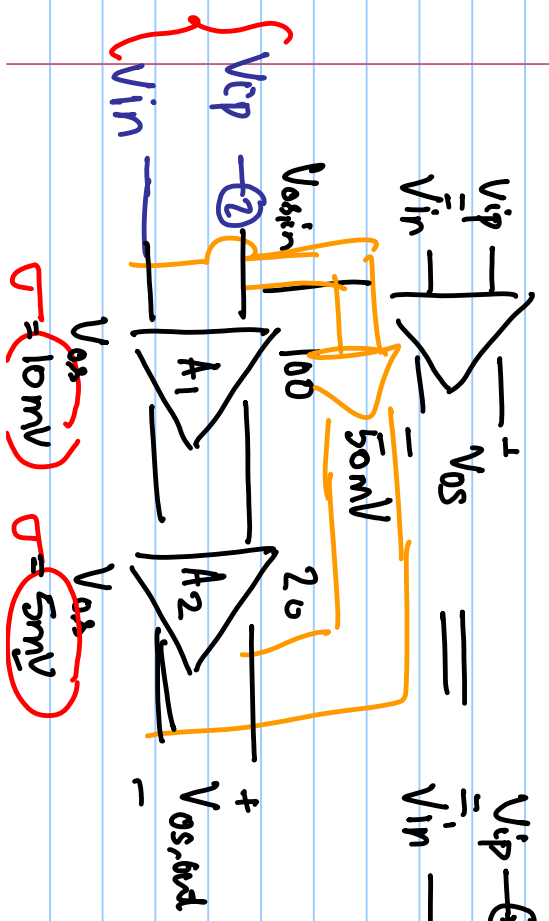


$V_{ip} = V_{in} \rightarrow V_{op} \neq V_{on}$

$\Delta V_{out} = V_{op} - V_{on} \sigma_{os}$   
 $V_{ip} = V_{in}$



Input referred offset —



$V_{os,out} = A_1 \cdot A_2 \cdot V_{os,in}$

$V_{os,out} = 5 \text{ mV} + A_2 \cdot 10 \text{ mV}$

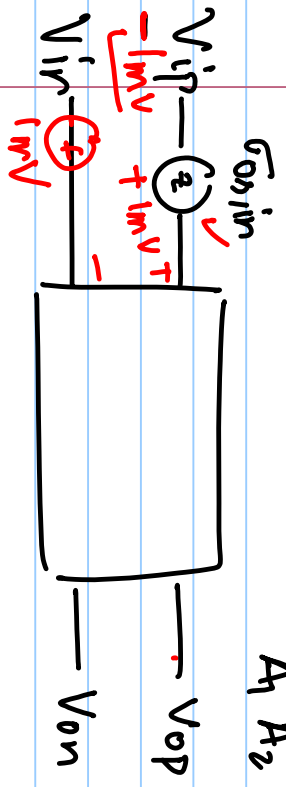
$\sigma_{os,out}^2 = \sigma_{os,avg2}^2 + A_2^2 \cdot \sigma_{os,avg1}^2$

$$V_{out} = V_{os,amp2} + A_2 \cdot V_{os,amp1}$$

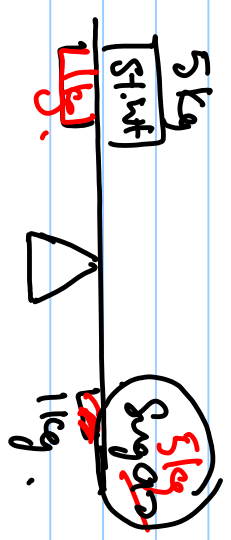
$$V_{o1,out} = A_1 \cdot A_2 \cdot V_{os,in}$$

$$\sigma_{o1,out}^2 = A_1^2 A_2^2 \sigma_{os,in}^2$$

$$\sigma_{os,in}^2 = \frac{\sigma_{o1,out}^2}{A_1^2 A_2^2} + \frac{1}{A_1^2} \sigma_{os,amp1}^2$$

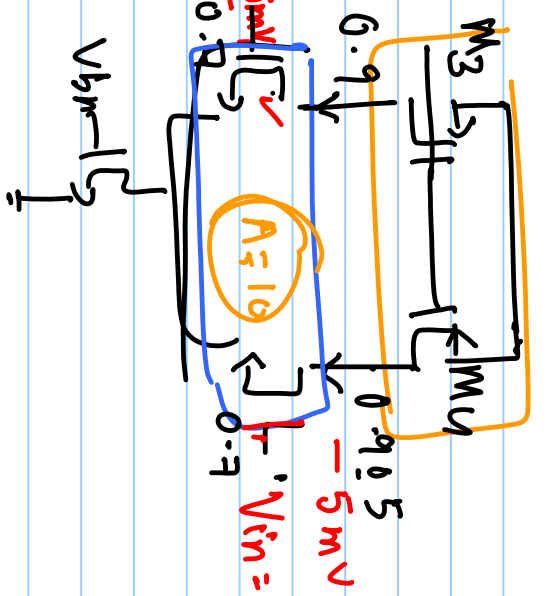


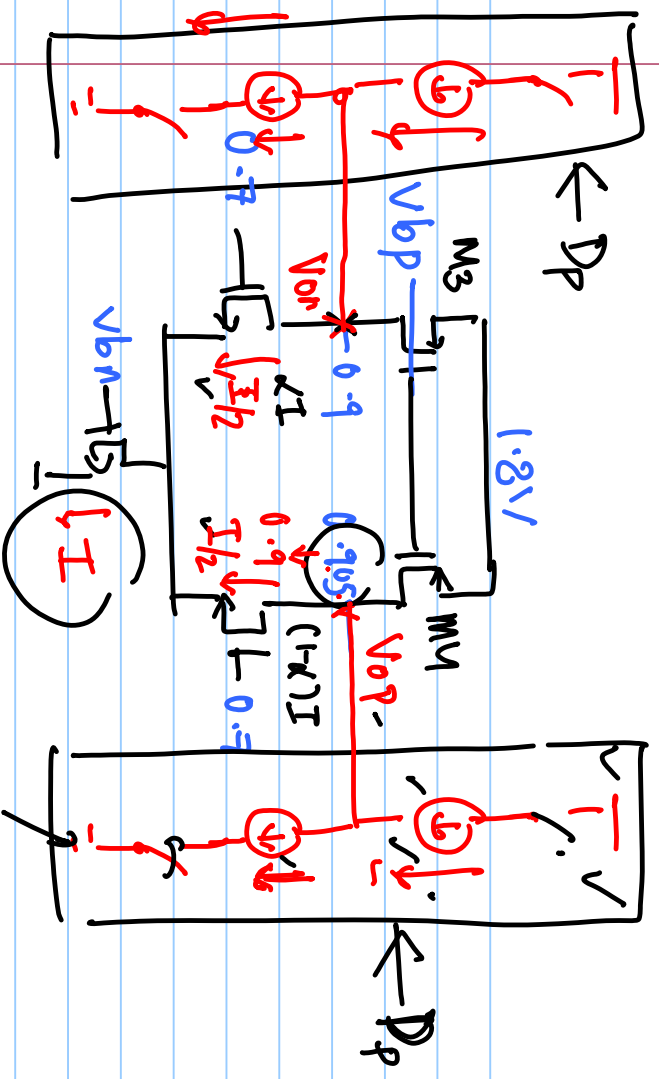
$$|V_{os,in}| < 3\sigma$$



$$V_{ip} = \frac{V_{diff}}{2} = \frac{0.5mV}{2} = 0.25mV$$

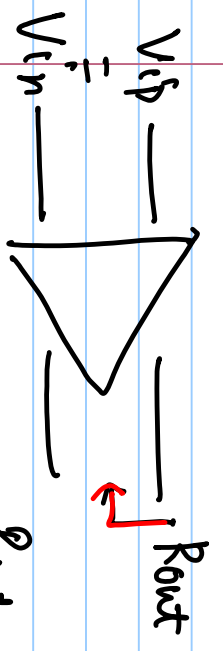
$$V_{in} = -\frac{V_{diff}}{2}$$





$V_{op} = V_{on}$

$V_{op} - V_{on} \neq 0$



$R_{out} \times I_{DACLSB} = V_{res}$

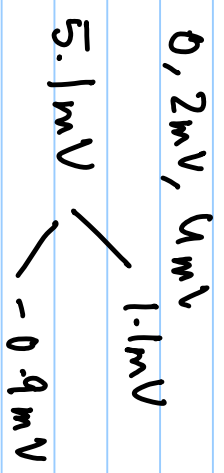
$\sigma_{\text{resout}} = 10 \text{ mV}$   
 $V_{op} - V_{on} \mid V_{ip} = V_{in} \mid \leq 3\sigma = \pm 30 \text{ mV}$

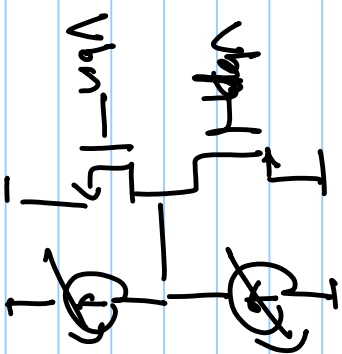
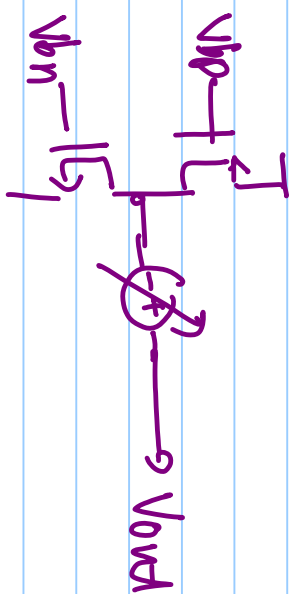
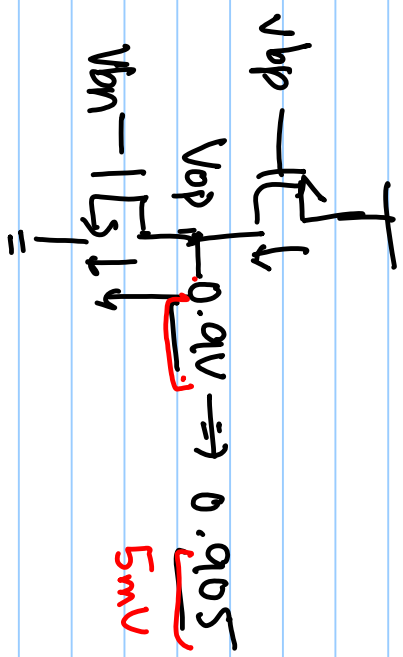
$-30 \text{ mV} < V_{\text{resout}} < 30 \text{ mV} \rightarrow$

Range =  $64 \text{ mV}$

Resolution of offset cancellation

=  $2 \text{ mV}$  ← Residual offset





$$I_p = \frac{K_p}{2} \left(\frac{W}{L}\right)_p (V_{DD} - V_{bp} - \underbrace{1V_{TP1}})^2 (1 + \lambda (V_{DD} - V_{out}))$$

$$I_n = \frac{K_n}{2} \left(\frac{W}{L}\right)_n (V_{bn} - \underbrace{V_{tn}})^2 (1 + \lambda (V_{out})) + \underbrace{\Delta I} = I_p$$

$$\Delta V = \Delta I \cdot R_{out}$$

