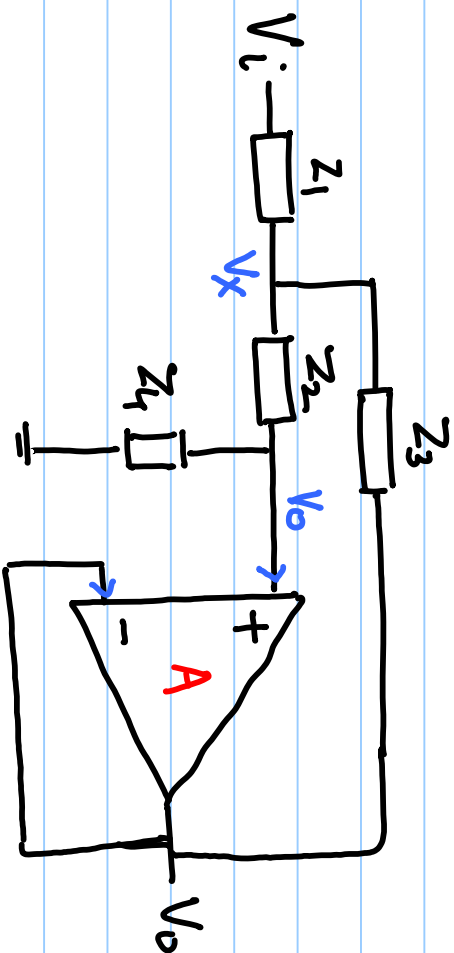


Lecture # 34Sallen-Key Filter.

$$\frac{V_x - V_o}{Z_2} = \frac{V_o}{Z_4}$$

$$\Rightarrow V_x = V_o \left( 1 + \frac{Z_2}{Z_4} \right) \quad (1)$$

$$\frac{V_x - V_i}{Z_1} + \frac{V_x - V_o}{Z_2} + \frac{V_x - V_o}{Z_3} = 0$$

$$V_x \left( \frac{1}{Z_1} + \frac{1}{Z_2} + \frac{1}{Z_3} \right) = V_o \left( \frac{1}{Z_2} + \frac{1}{Z_3} \right) + \frac{V_i}{Z_1} \quad (2)$$

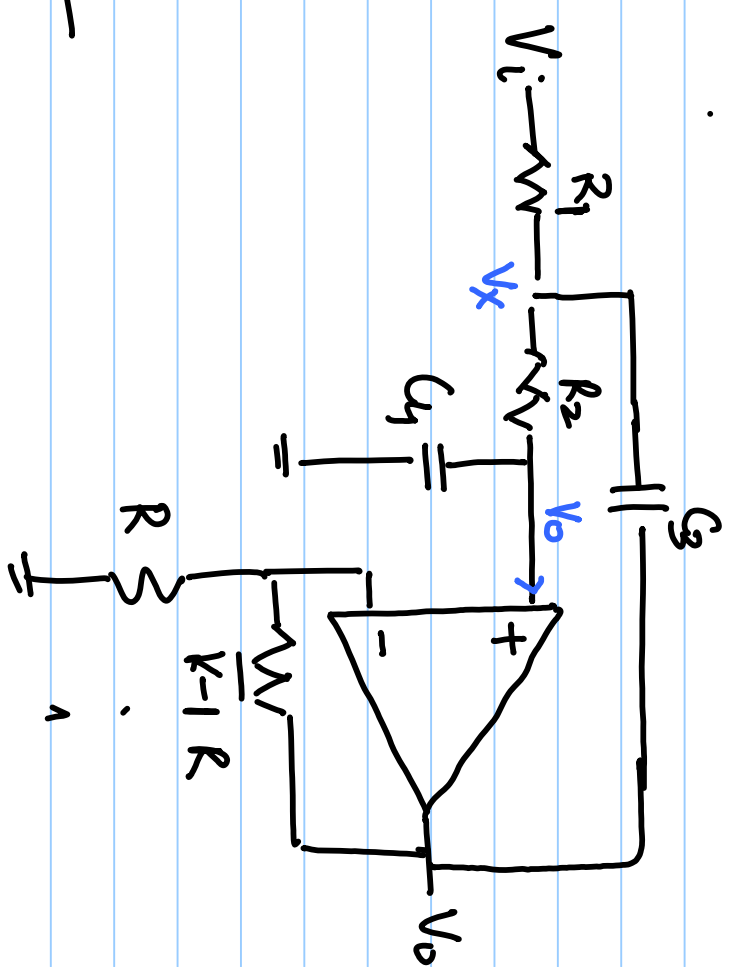
$$V_o \left( 1 + \frac{Z_2}{Z_4} \right) \left( \frac{1}{Z_1} + \frac{1}{Z_2} + \frac{1}{Z_3} \right) = V_o \left( \frac{1}{Z_2} + \frac{1}{Z_3} \right) + \frac{V_i}{Z_1}$$

$$\frac{V_o}{V_i} = \frac{Z_3 Z_4}{Z_1 Z_2 + Z_1 Z_3 + Z_2 Z_3 + Z_3 Z_4} = \frac{1}{\frac{s^2 R_1^2}{\omega_p^2} + \frac{s}{\omega_p Q_p} + 1}$$

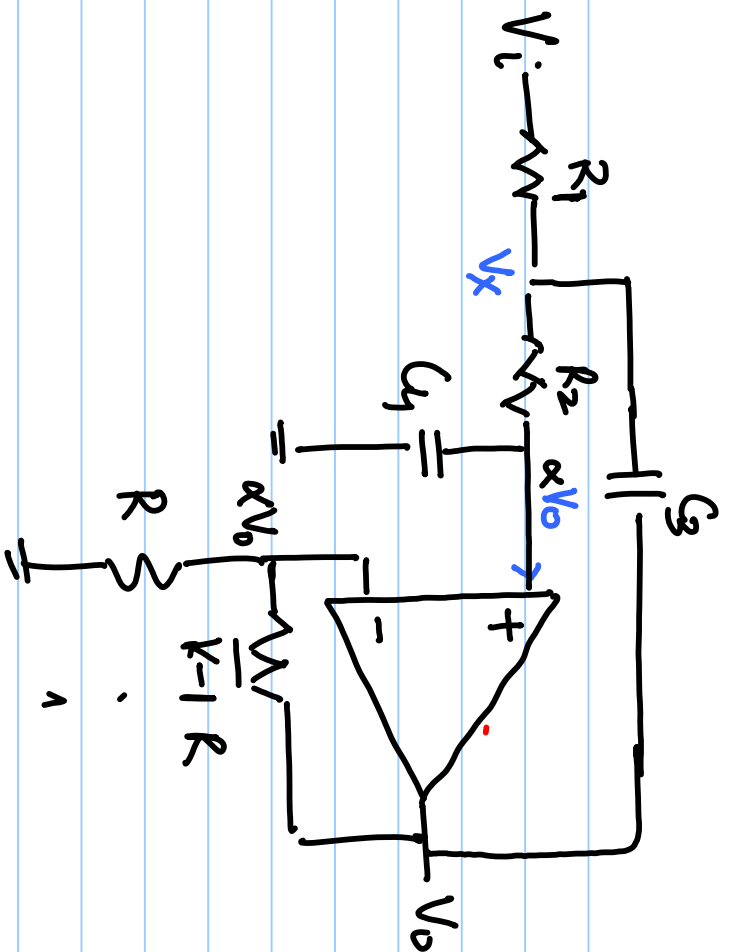
$$= \frac{Y_1 Y_2}{Y_3 Y_4 + Y_2 Y_1 + Y_1 Y_4 + Y_1 Y_2}$$

- |       |       |        |        |
|-------|-------|--------|--------|
| $Y_1$ | $Y_2$ | $Y_3$  | $Y_4$  |
| $G_1$ | $G_2$ | $sC_3$ | $sC_4$ |

$$\frac{V_o}{V_i} = \frac{G_1 G_2}{s^2 C_3 C_4 + s C_4 (G_1 + G_2) + G_1 G_2} = \frac{1}{s^2 R_1 R_2 C_3 C_4 + s C_4 (R_1 + R_2) + 1}$$



1



$$\alpha = \frac{1}{2}$$

$$\alpha V_o = \frac{1/sC_3}{R_2 + \frac{1}{sC_3}} \quad V_x = \frac{1}{1 + sC_3 R_2} V_x$$

$$\frac{V_x - V_i}{R_1} + \frac{V_x - \alpha V_o}{R_2} + \frac{V_x - V_o}{1/sC_3} = 0$$

$$V_x \left( \frac{1}{R_1} + \frac{1}{R_2} + sC_3 \right) = V_o \left( \frac{\alpha}{R_2} + sC_3 \right) + \frac{V_i}{R_1}$$

$$\alpha V_o (1 + sC_3 R_2) \left( \frac{R_1 + R_2 + sC_3 R_1 R_2}{R_1 R_2} \right) = V_o \left( \frac{\alpha + sC_3 R_2}{R_2} \right) + \frac{V_i}{R_1}$$

$$V_o \left\{ \alpha (1 + sC_3 R_2) \left( \frac{R_1 + R_2 + sC_3 R_1 R_2}{R_1 R_2} \right) - \frac{\alpha}{R_1} - \frac{sC_3 R_1 R_2}{R_2} \right\} = V_i \cdot \frac{R_2}{\alpha}$$

$1/\alpha$

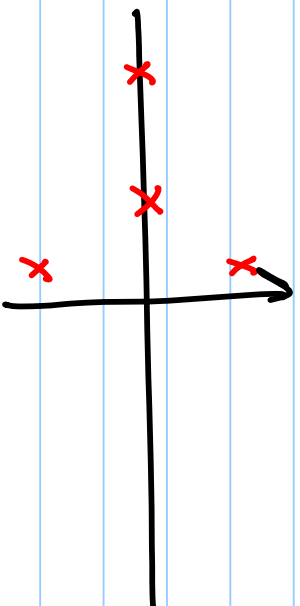
$$\begin{aligned} \frac{V_0}{V_i} &= \frac{1/\alpha}{\lambda^2 C_3 C_{n1} R_1 R_2^2 + \lambda (C_{n1} R_1 R_2 + C_{n1} R_1^2 + C_3 R_1 R_2) - \lambda \frac{C_3 R_1 R_2 + R_1 R_2}{R_2}} \\ &= \frac{k}{\lambda^2 C_3 C_{n1} R_1 R_2 + \lambda (C_{n1} R_1 + C_{n1} R_2 + C_3 R_1 - k C_3 R_1) + \underbrace{(1-k) C_3 R_1}} \end{aligned}$$

$$ax^2 + bx + c = 0$$

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$x_1 + x_2 = \frac{-b}{2a} < 0$$

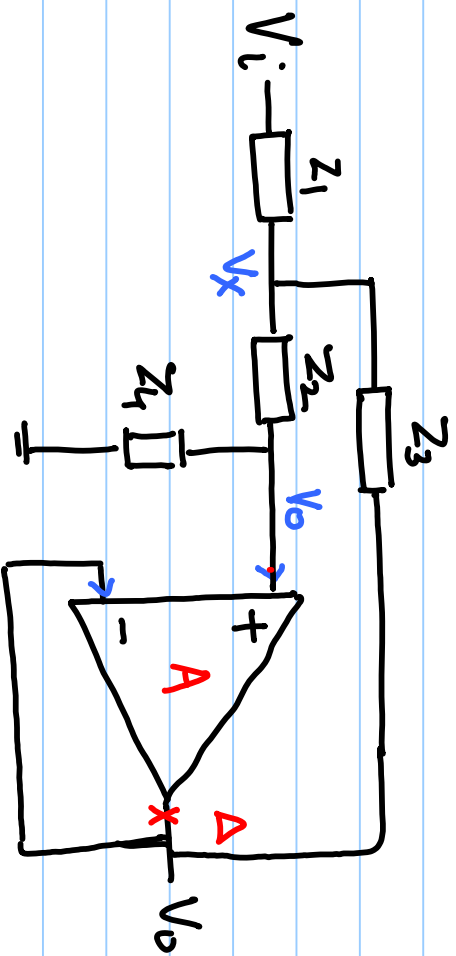
$b > c$



$$C_4 R_1 + C_{n1} R_2 + C_3 R_1 (1-k) > 0$$

$$\frac{C_1}{C_3} + \frac{C_1}{C_3} \frac{R_2}{R_1} + (1-k) > 0$$

$$k < 1 + \frac{C_1}{C_3} + \frac{C_1}{C_3} \frac{R_2}{R_1}$$



$k$

-

$$\frac{V_o}{V_i} = \frac{Z_3 Z_4}{Z_1 Z_2 + Z_1 Z_3 + Z_2 Z_3 + Z_3 Z_4} = \frac{s^2 / \omega_p^2}{\frac{s^2}{\omega_p^2} + \frac{s}{\omega_p Q_p} + 1}$$

$$= \frac{Y_1 Y_2}{Y_3 Y_4 + Y_2 Y_4 + Y_1 Y_4 + Y_1 Y_2} = \frac{s / \omega_p Q_p}{\frac{s^2}{\omega_p^2} + \frac{s}{\omega_p Q_p} + 1}$$

$$Y_1 \quad Y_2 \quad Y_3 \quad Y_4$$

$$sC_1 \quad sC_2 \quad \frac{1}{R_3} \quad \frac{1}{R_4}$$

(High Pass Filter)

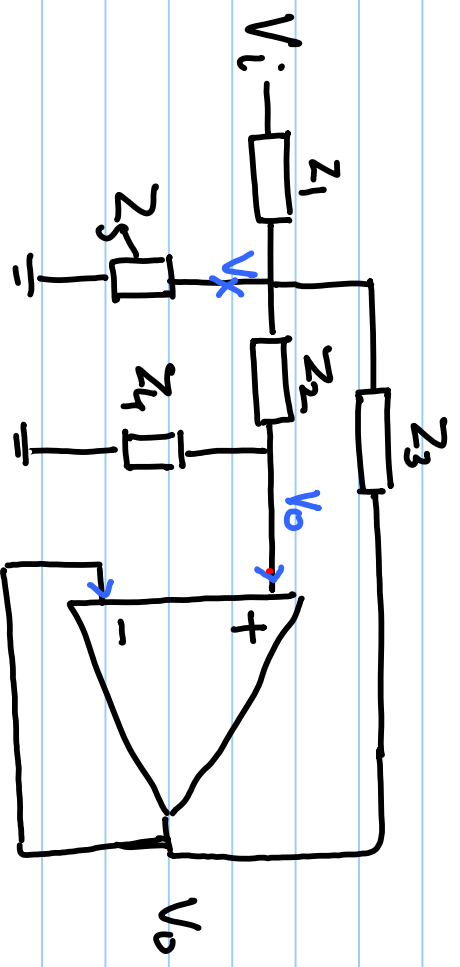
$$Y_1 \quad Y_2 \quad Y_3 \quad Y_4$$

$$sC_1 \quad \frac{1}{R_2} \quad \frac{1}{sL_3} \quad sC_4$$

$$sC_3 \quad \frac{1}{R_4}$$

$$H(s) = \frac{sC_1 / R_2}{s^2 C_1 C_4 + s \frac{C_1}{R_2} + s \frac{C_4}{R_2} + \frac{sC_4}{sL_3}}$$

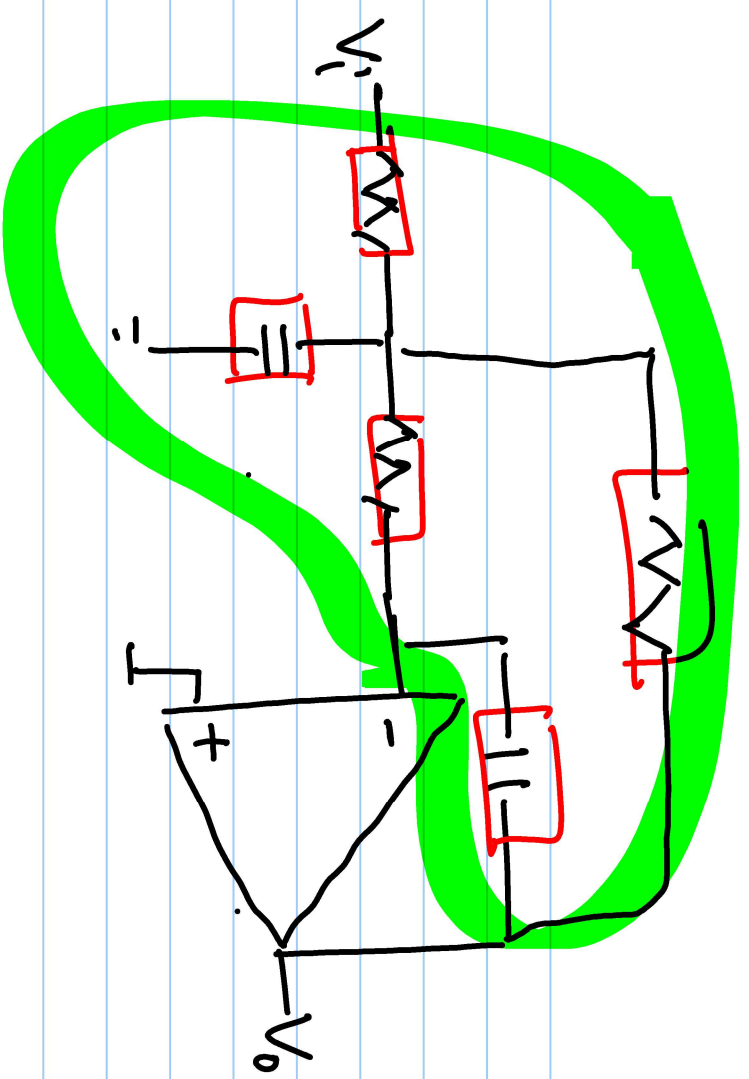
$$= \frac{sC_1 L_3 / C_4 R_2}{s^2 C_1 L_3 + s \frac{C_1 L_3}{C_4 R_2} + \frac{sL_3}{R_2} + 1}$$



$$\frac{V_o}{V_i} = \frac{Y_1 Y_2}{Y_2 Y_5 + Y_2 Y_4 + Y_4 Y_5 + Y_3 Y_4 + Y_1 Y_2 + Y_1 Y_4}$$

$Y_1$	$Y_2$	$Y_3$	$Y_4$	$Y_5$
$\frac{1}{R_1}$	$\frac{1}{R_2}$	$\frac{1}{R_3}$	$\frac{1}{R_4}$	$\frac{1}{R_5}$

"Raukh Filter"



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