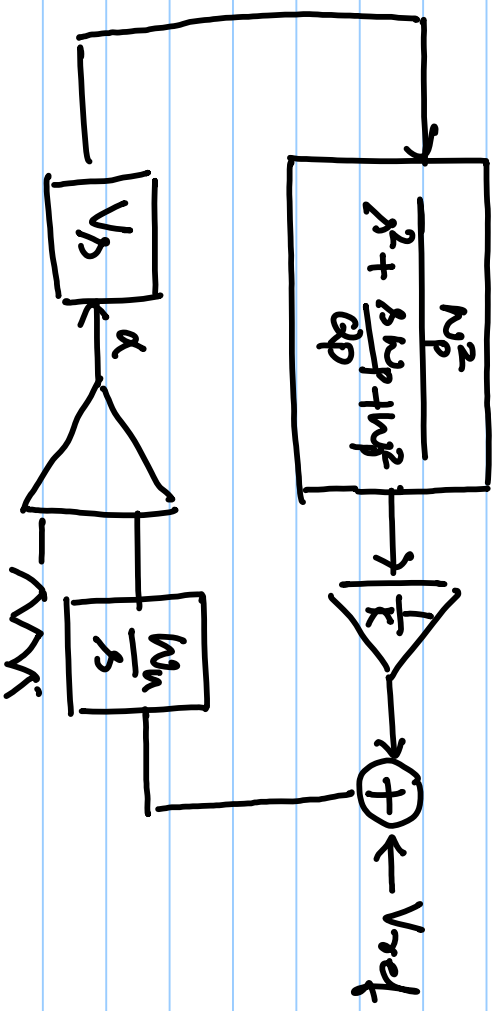


Lecture #26



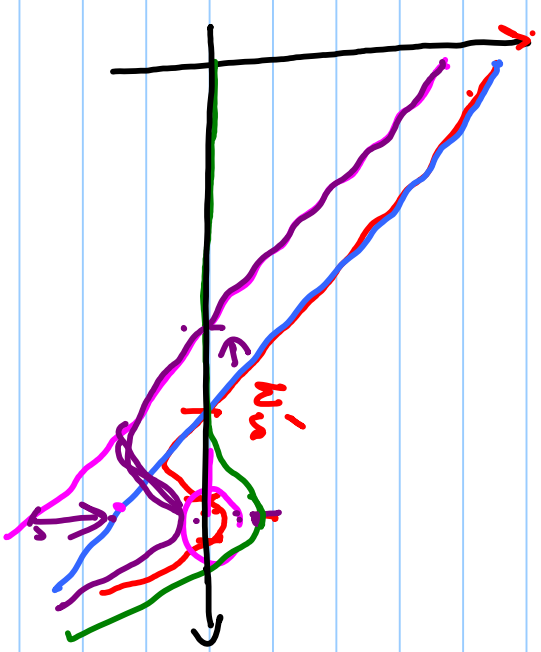
$$|G_u| = \underbrace{\frac{1}{K} \times \frac{\omega_n}{s}}_{H_1} \times \frac{1}{V_f} \times V_s \times \underbrace{\frac{\omega_p^2}{s^2 + 2\zeta \omega_p s + \omega_p^2}}_{H_2}$$

$$|H_1(j\omega_{pk}) \times H_2(j\omega_{pk})| < 1$$

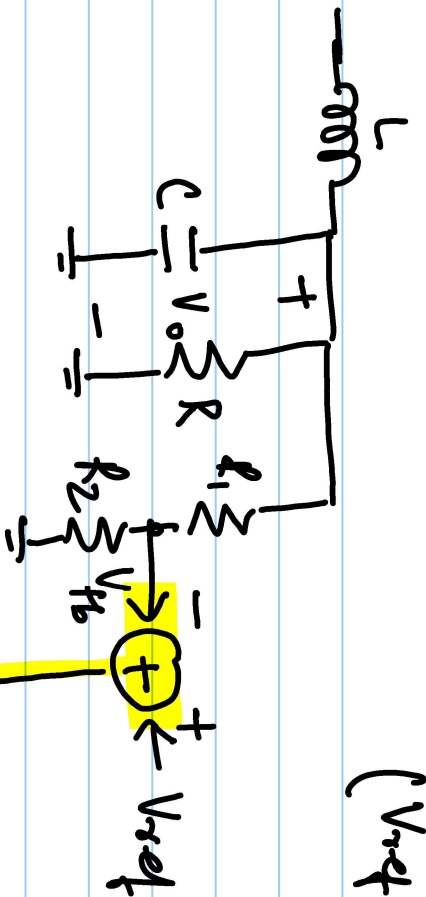
$$\omega_{pk} = \omega_p \sqrt{1 - \frac{1}{2\zeta^2}}$$

$$\frac{\omega_n V_s}{K V_f} \times \frac{1}{\omega_{pk}} \times \zeta_p < 1$$

ω_n



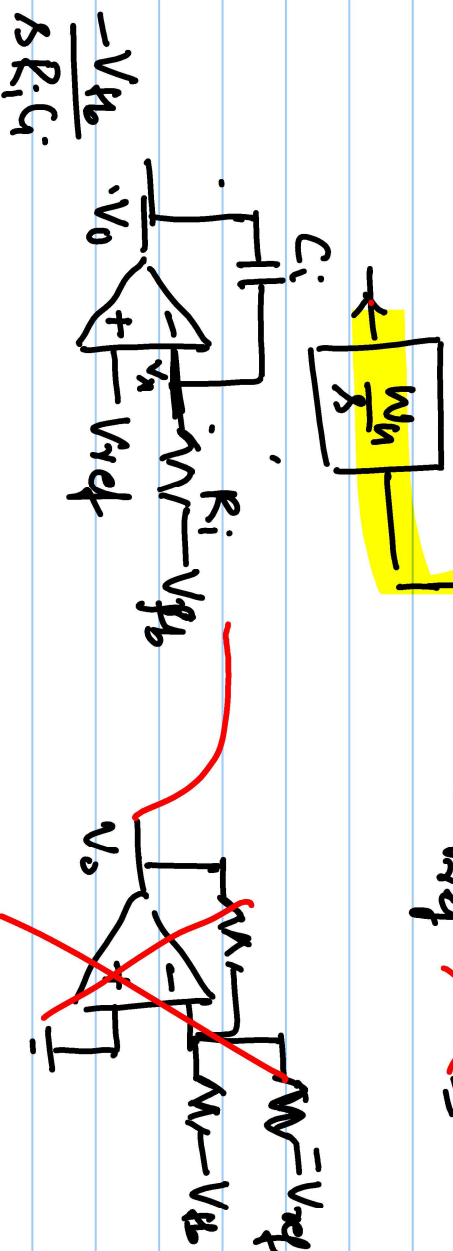
$$(V_{rd} - V_{Hb}) \frac{1}{s} \frac{1}{s}$$



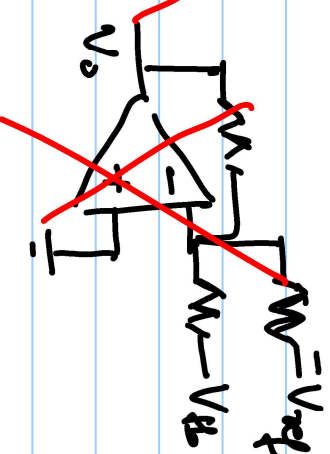
$$\frac{(V_{Hb} - V_{rd})}{R_i} = \frac{V_{rd} - V_0}{1/s C_i}$$

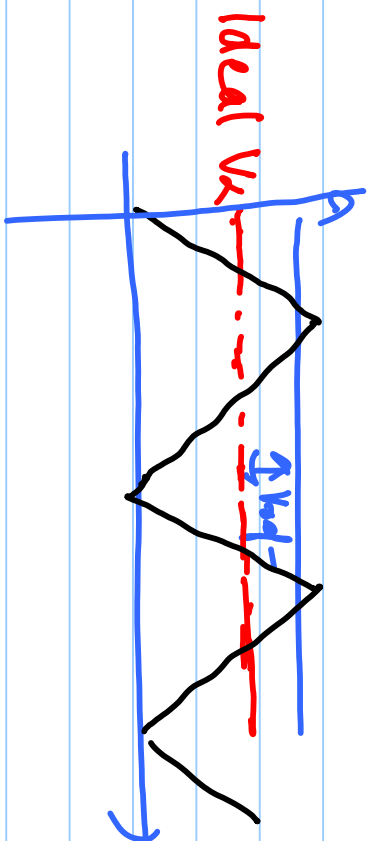
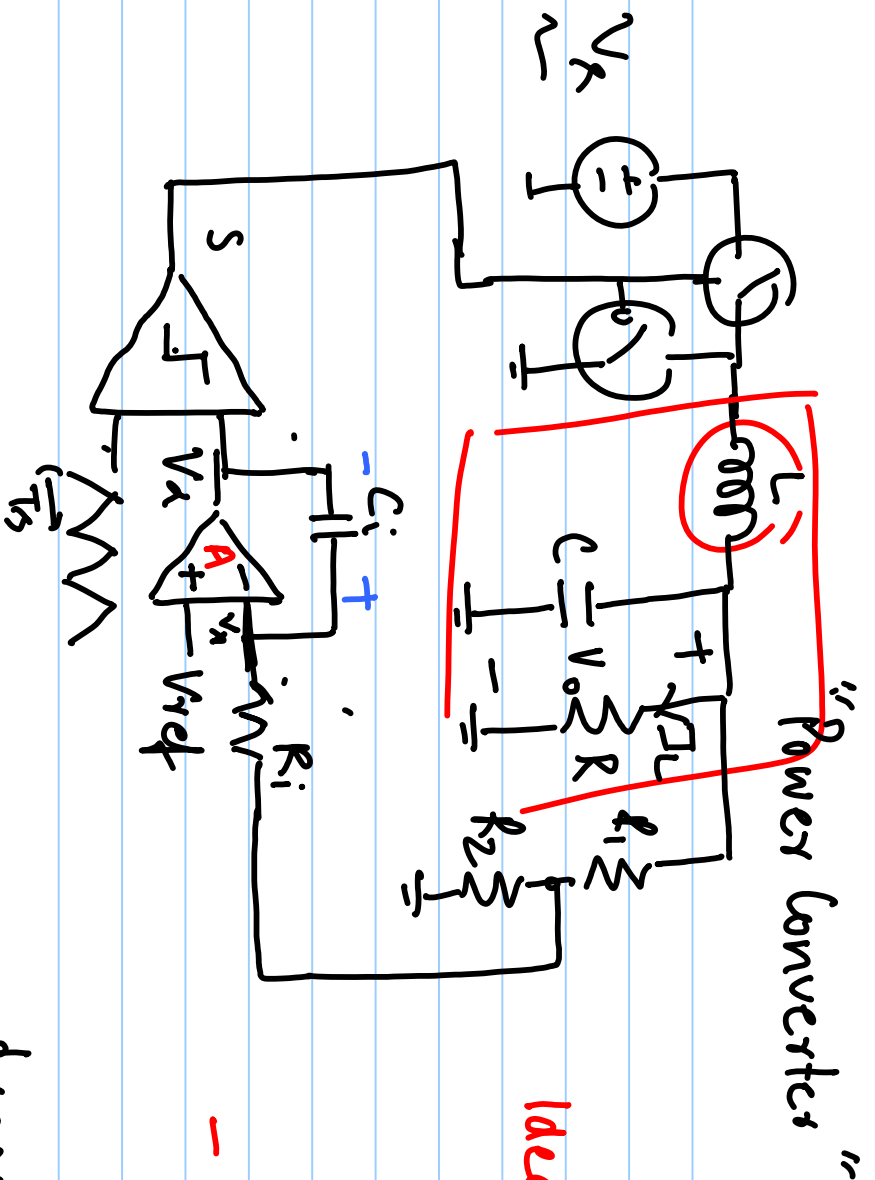
$$V_0 = \frac{-1}{s C_i R_i} (V_{Hb} - V_{rd}) + V_{rd}$$

$$= \underbrace{V_{rd}} + \frac{1}{s C_i R_i} \underbrace{(V_{rd} - V_{Hb})}$$

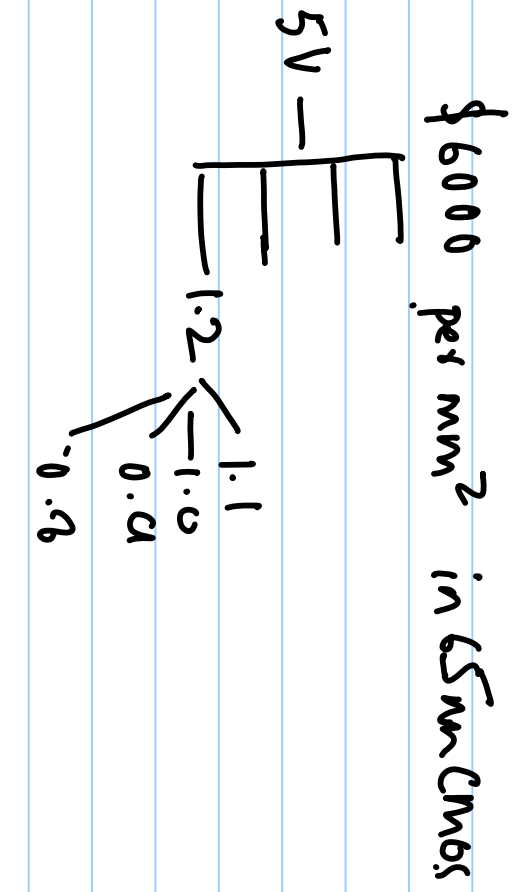
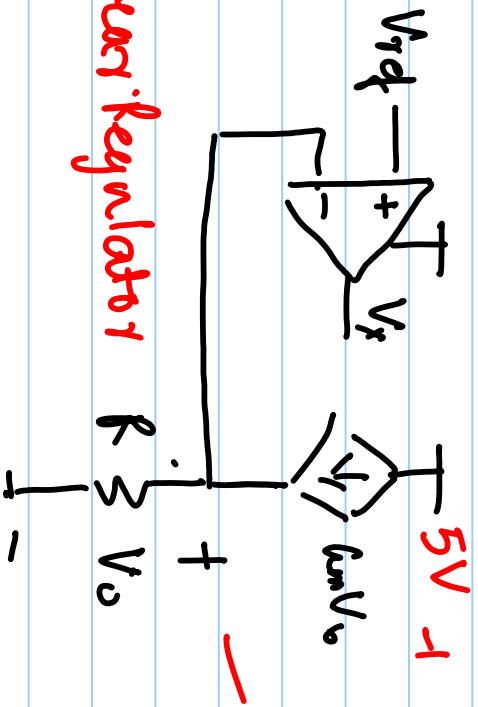


$$\frac{(V_{Hb} - V_{rd})}{R_i} = \frac{(V_{rd} - V_0)}{1/s C_i} \dots$$





- Fast transient will prefer LDOs



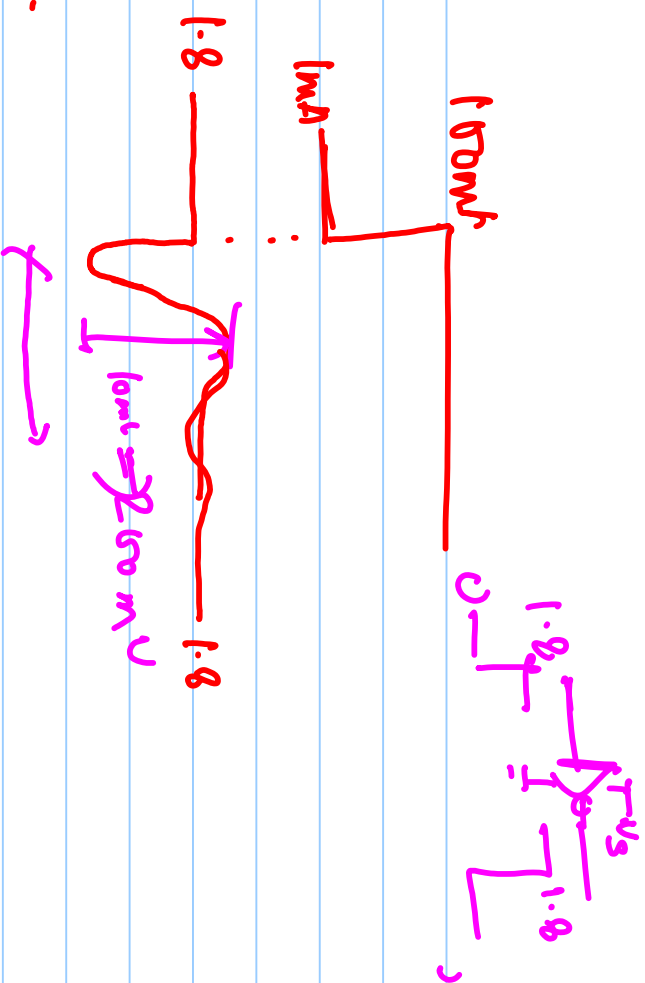
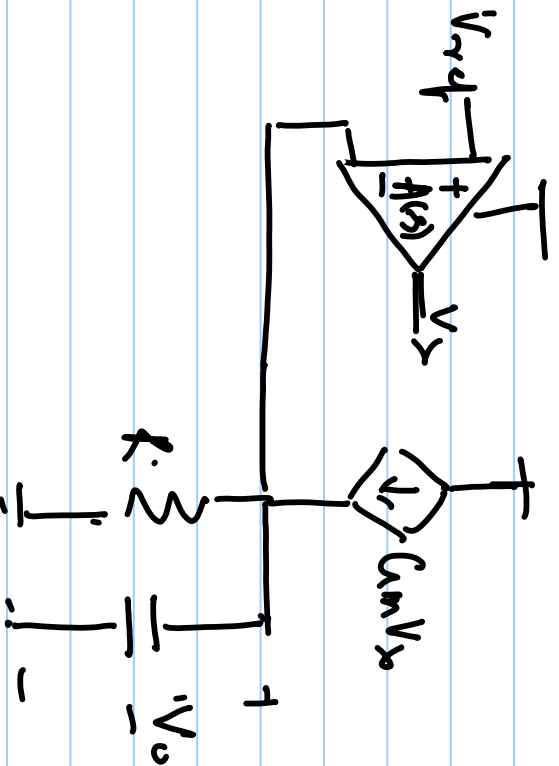
Linear Regulator
LDO

$$\text{Load Regulation} = \frac{\Delta V_{out}}{\Delta V_s}$$

$$\text{Line Regulation} = \frac{\Delta V_{out}}{\Delta V_s}$$

(Load)
Output transient =

Efficiency =



$$A(s) = \frac{A_0}{1 + s/\omega_p}$$

$A_0 \omega_p = \text{Gain} \times \text{Bandwidth}$

Product