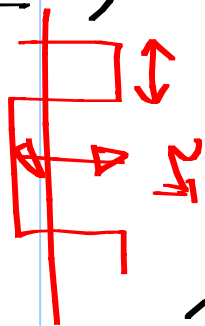


$$p_p: 2\pi$$

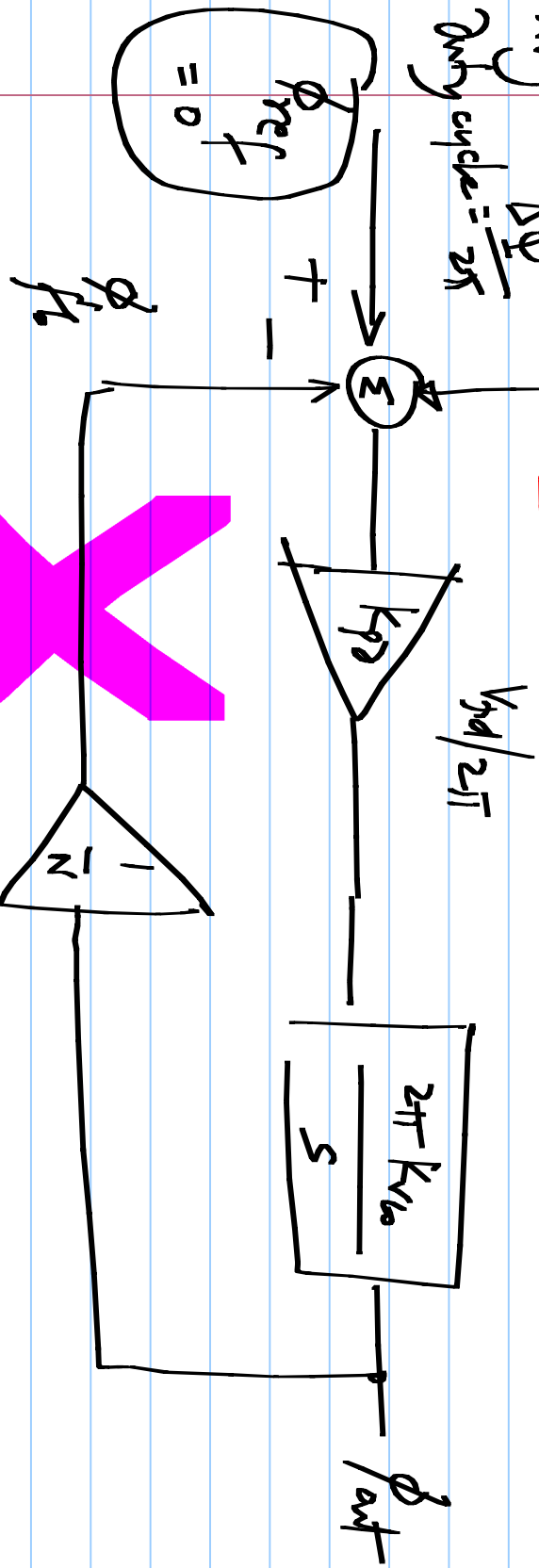
$$avg = 0 \quad \Delta\Phi$$

$$avg \text{ cycle} = \frac{2\pi}{2\pi}$$



PFD period error

21/4/2016



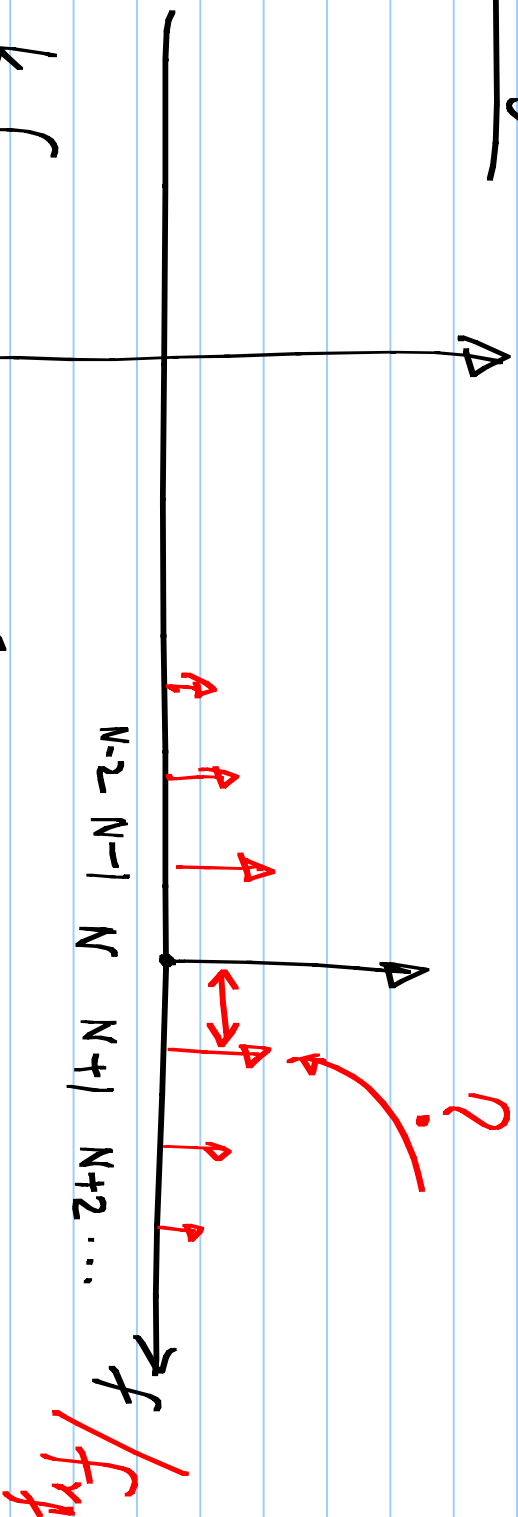
$$\Delta\Phi = \Phi_{ref} - \Phi_{fb}$$

$$\frac{N f_{ref} - f_o}{K_{vco} \cdot K_{pd}}$$

ϕ_{out} : components @ f_{ref} and its harmonics

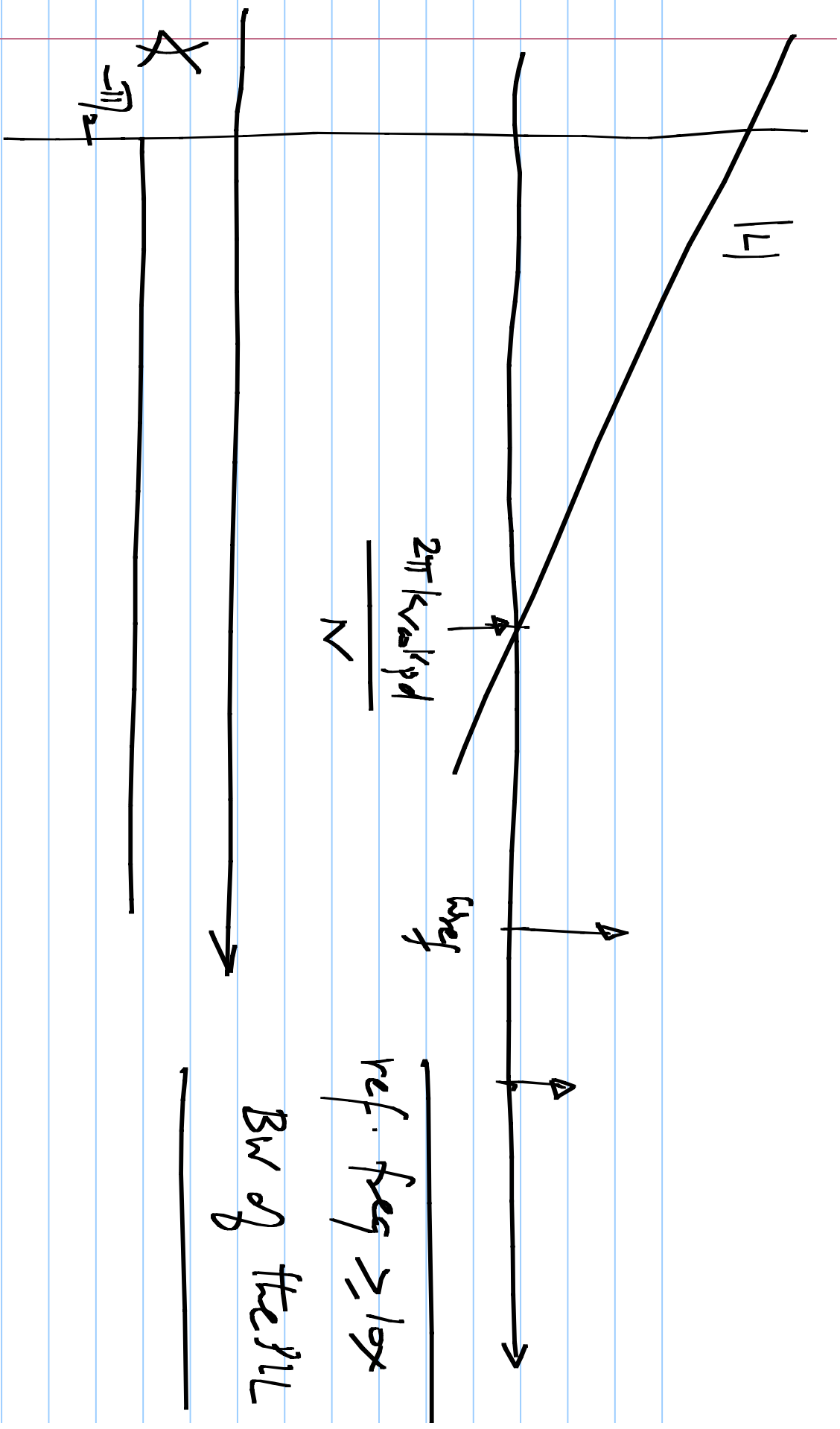
$$\cos(2\pi N f_{ref} t + \underbrace{\Phi_{ref} + \Phi_{out}})$$

output signal:



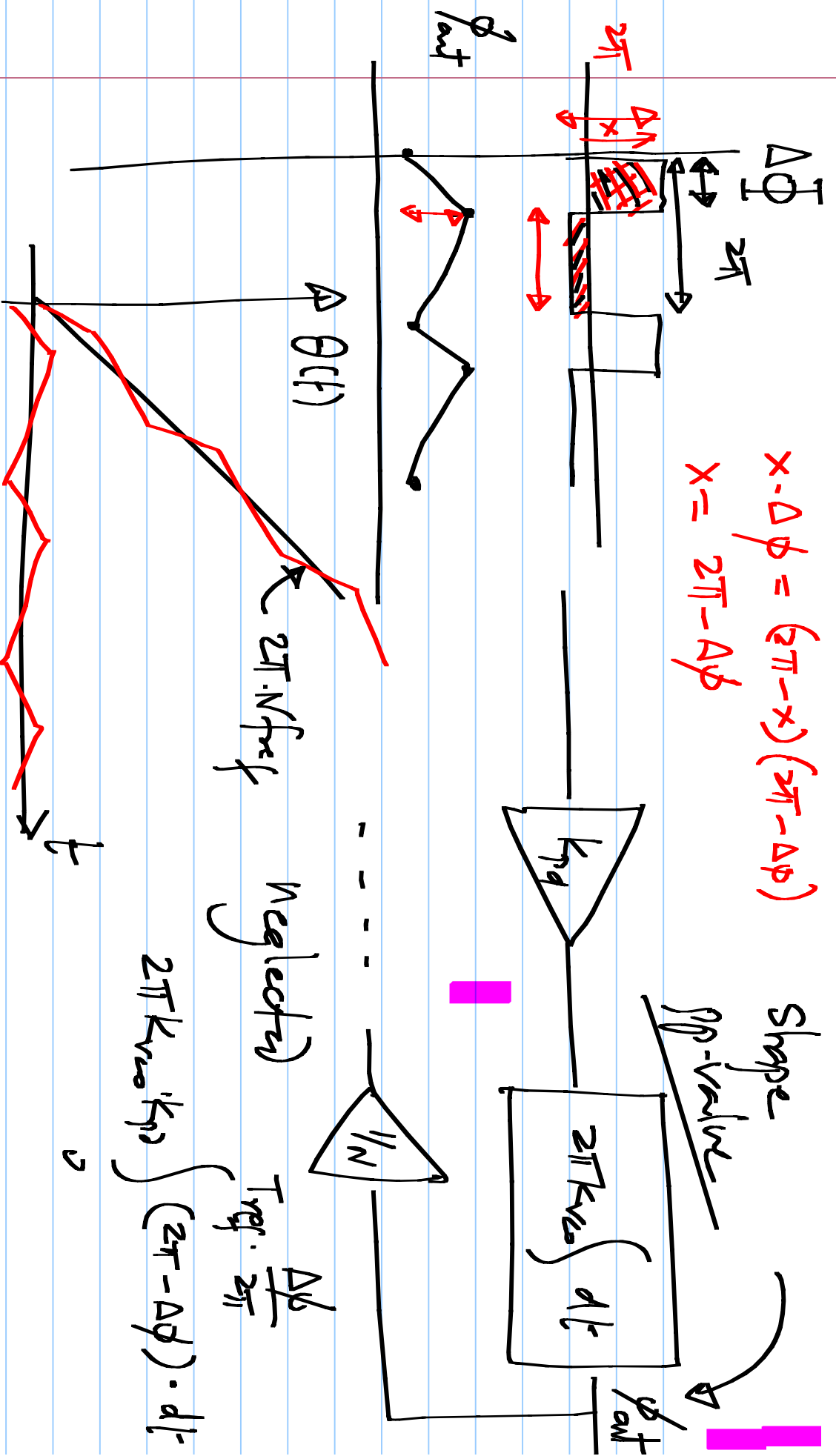
$$\underline{f \pm k \cdot f_m}$$

$$\cos(2\pi f t + \underbrace{a}_{\text{gain}} \underbrace{\sin(2\pi f_m t)}_{\text{modulation}})$$



$$x - \Delta\phi = (2\pi - x)(2\pi - \Delta\phi)$$

$$x = 2\pi - \Delta\phi$$



Shape
pp-value

neglects

$$2\pi K_{vco} K_{pd} \int T_{ref} \cdot \frac{\Delta\phi}{2\pi} (2\pi - \Delta\phi) \cdot dt$$

$$\phi_{out,pp} = 2\pi \cdot k_{veo} \cdot k_{pd} \cdot (2\pi - \Delta\phi) \frac{\Delta\phi}{2\pi} \cdot T_{ref}$$

$$= k_{veo} \cdot k_{pd} (2\pi - \Delta\phi) \cdot \Delta\phi \cdot T_{ref}$$

$$f_{ref} = 10 \text{ MHz}$$

$$N = 100$$

$$N = 101$$

$$f_{out} = 1 \text{ kHz}$$

$$1.01 \text{ kHz}$$

$$\pi k_{veo} \cdot k_{pd} \ll 20 \text{ MHz}$$

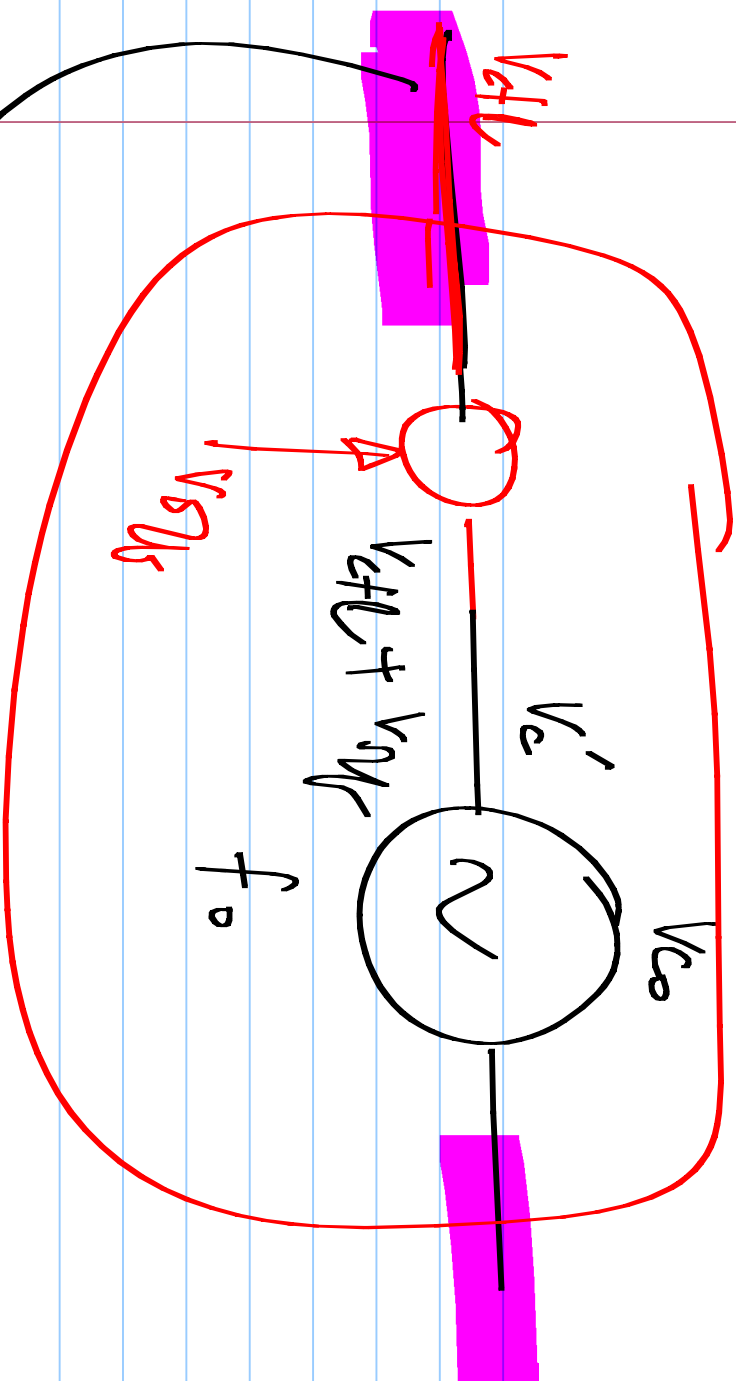
$$\pi k_{veo} \cdot k_{pd} = 0.2 \text{ MHz}$$

$$\phi_{out,pp-max} = k_{veo} \cdot k_{pd} \cdot \pi T, T_{ref} \ll 2T$$

$$\pi \cdot k_{veo} \cdot k_{pd} \ll \frac{2}{T_{ref}} = 2 f_{ref}$$

$$|N f_{ref} - \phi|$$

$$= \frac{\pi \cdot k_{pd} \cdot v_{eo}}{\pi \cdot k_{pd} \cdot v_{eo}}$$



$$V_{ctl} = 0 \longrightarrow f_0 + K_{vo} \cdot V_{ny}$$

