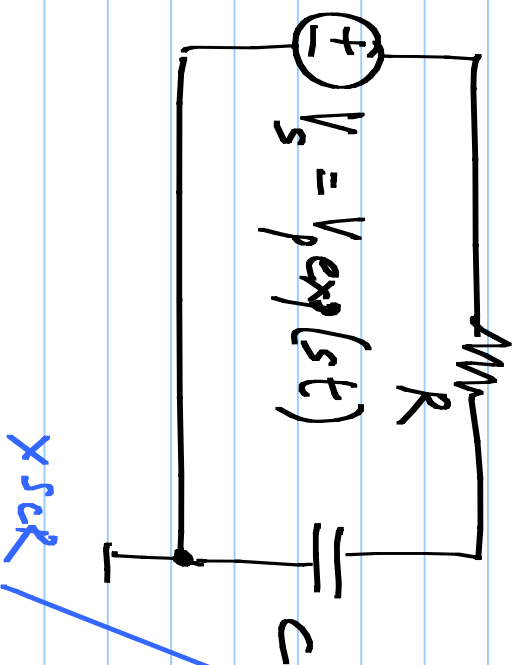


EC1010: Lecture 26



$$RC \frac{dV_2}{dt} + V_2 = 0 \quad \underline{V_2 = V_{2s} \exp\left(-\frac{t}{RC}\right)}$$

$$RC \frac{dV_c}{dt} + V_c = V_p \exp(st)$$

$$\underline{V_{c1} = V_c - V_p \exp(st)}$$

$$RC \frac{dV_{c1}}{dt} + V_{c1} = -sCR \cdot V_p \cdot \exp(st)$$

$$RC \frac{d}{dt} \left(\underbrace{sCR \cdot V_c + V_{c1}}_{V_{c2}} \right) + \left(\underbrace{sCR \cdot V_c + V_{c1}}_{V_{c2}} \right) = 0$$

$$V_p \exp(-t/Rc)$$

$$V_{c2} = V_{c20} \exp\left(-\frac{t}{Rc}\right) = s_{cr} V_c + V_{c1}$$

$$s_{cr} + 1 = 0$$

$$V_c(t) = V_p \exp(st) + V_{c20} \exp\left(-\frac{t}{Rc}\right) = s_{cr} V_c + V_c - V_p \exp(st)$$

Found from initial conditions

Lim
|t s_{cr} → 0 =

$$\frac{V_p \exp(st)}{s_{cr} + 1}$$

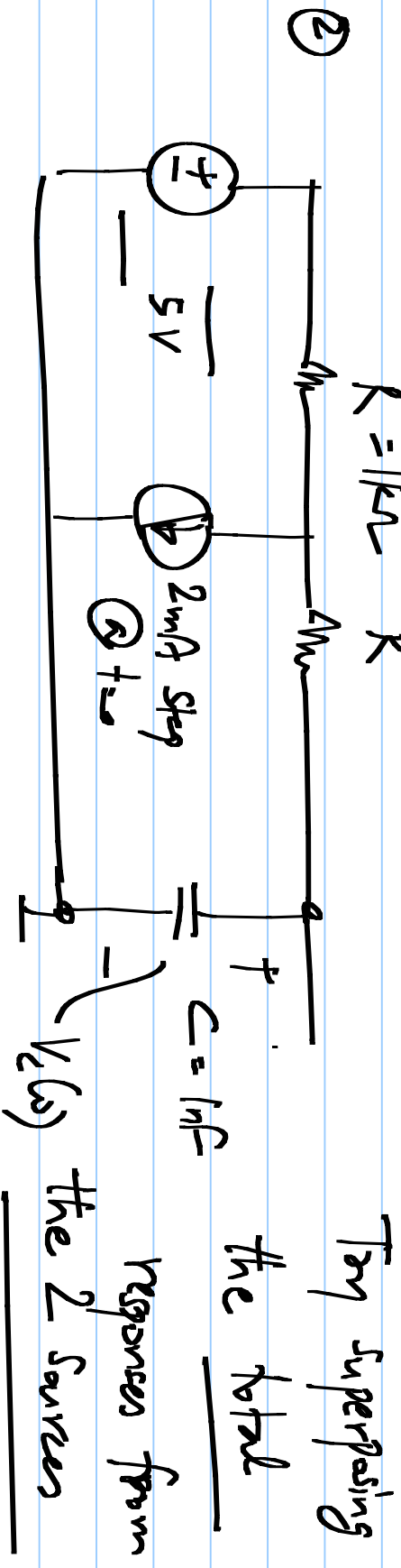
$$+ (V_0) \cdot \exp\left(-\frac{t}{Rc}\right)$$

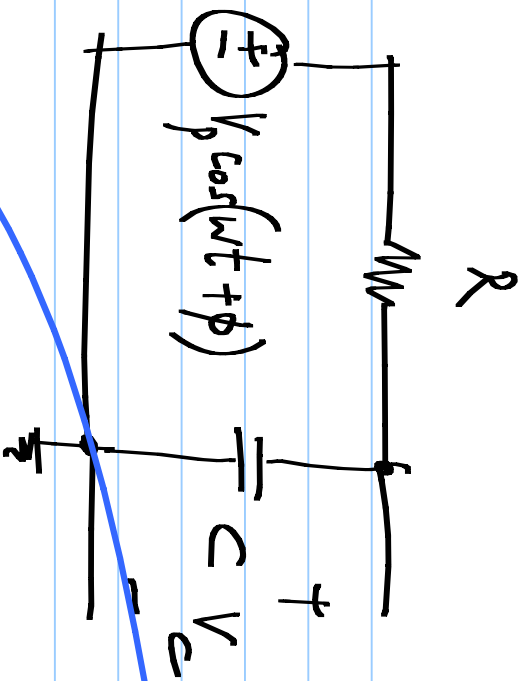
Steady state / Forced response

Natural response

Steady state response \downarrow to exploit: scaled version of itself
(of any linear system)

Exercise: ① Find out $V_C(t)$ for $s \ll \pm 1 \Rightarrow \infty$
by taking the appropriate limit-





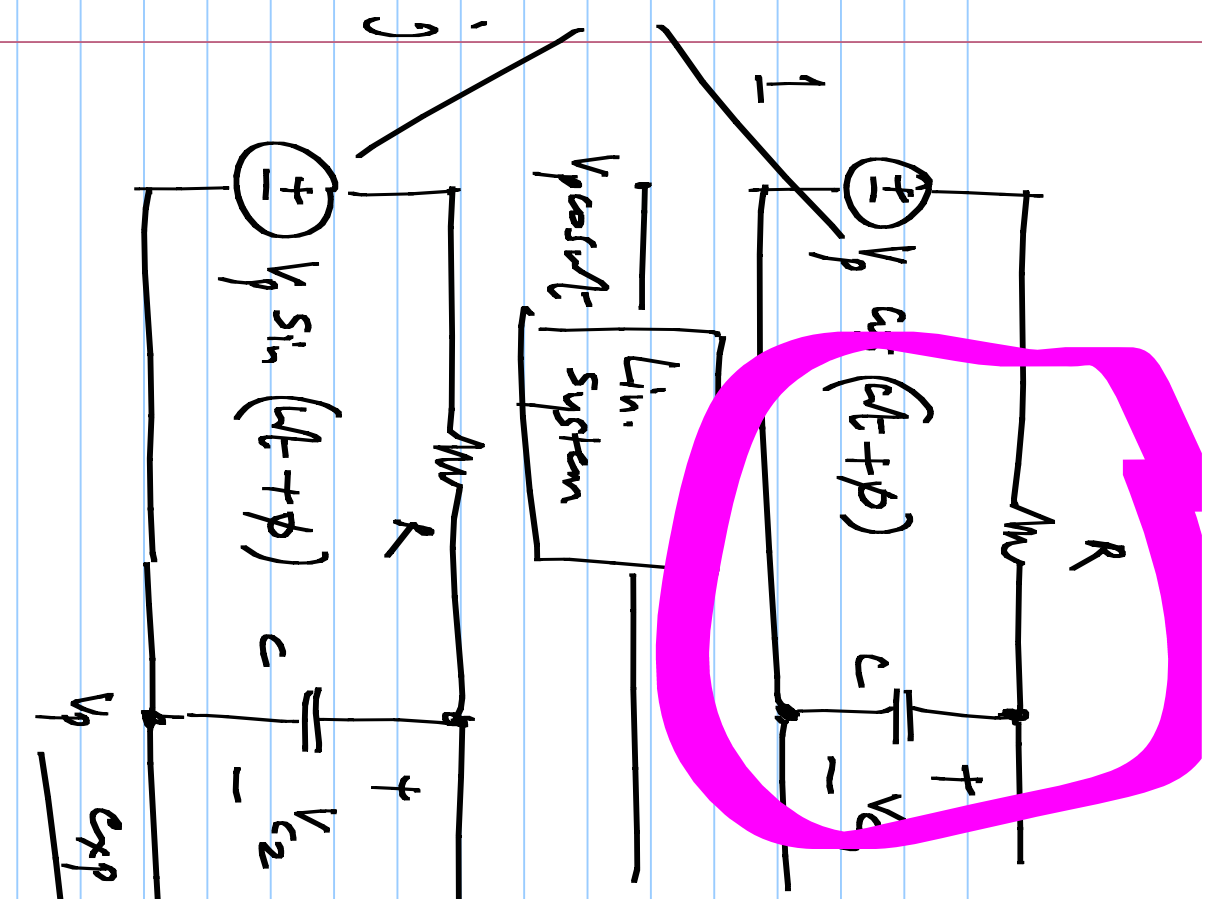
$$RC \frac{dV_c}{dt} + V_c = V_p \cos(\omega t + \phi)$$

$$V_c(t) = V_p \left[\alpha \cos(\omega t + \phi) + \beta \sin(\omega t + \phi) \right]$$

$$\frac{dV_c}{dt} = V_p \cdot \omega \left[-\alpha \sin(\omega t + \phi) + \beta \cos(\omega t + \phi) \right]$$

$$V_p \cos(\omega t + \phi) = \frac{V_p}{2} \left[\exp(j(\omega t + \phi)) + \exp(-j(\omega t + \phi)) \right]$$

exp(st)



V_{c1}, V_{c2} : steady state response

$$V_p \exp(j(\omega t + \phi))$$

$$\downarrow V_p \exp(j\phi) \exp(j\omega t)$$

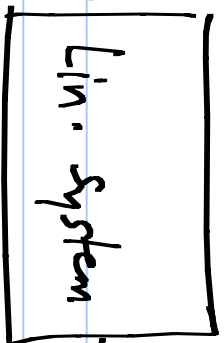
$$V_c + j V_{c2}$$

$$V_p \exp(st) \rightarrow \frac{V_p}{1 + sCR} \exp(st)$$

$$V_p \frac{\exp(j(\omega t + \phi))}{1 + j\omega CR}$$

$$\frac{V_p \exp(j\phi)}{1 + j\omega CR} \exp(j\omega t)$$

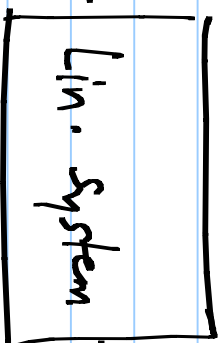
$$V_p \cos(\omega t + \phi)$$



$$V_{e1}$$

$$RC \frac{dV_1}{dt} + V_1 = V_p \cos(\omega t + \phi)$$

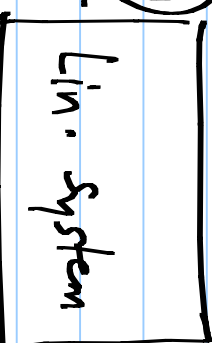
$$V_p \sin(\omega t + \phi)$$



$$V_{e2}$$

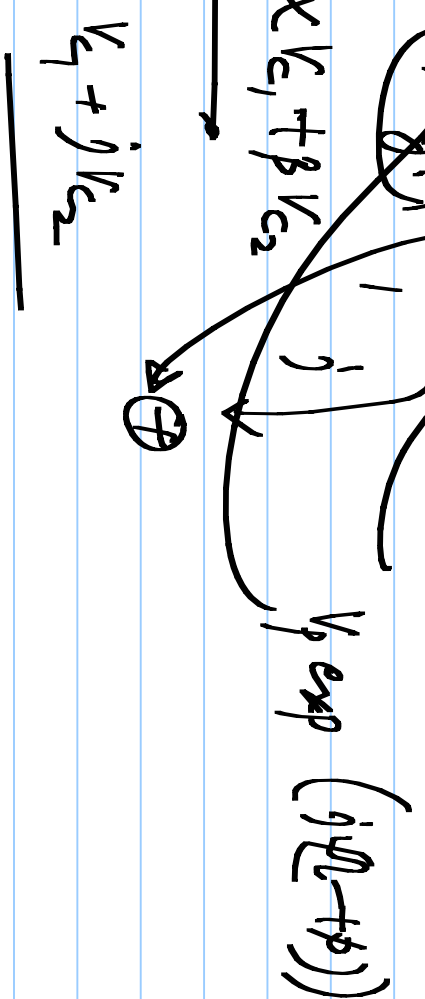
$$RC \frac{dV_2}{dt} + V_2 = V_p \sin(\omega t + \phi)$$

$$V_p (\alpha \cos(\omega t + \phi) + \beta \sin(\omega t + \phi))$$



$$\alpha V_{e1} + \beta V_{e2}$$

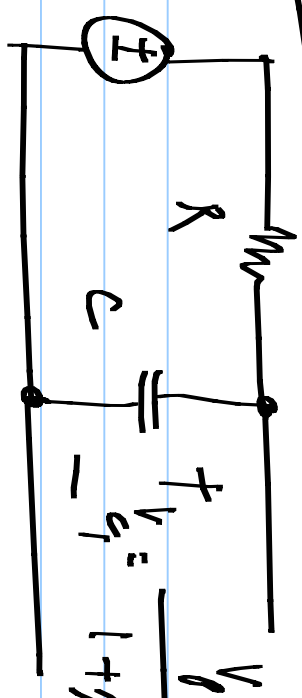
$$V_p \exp(j(\omega t + \phi))$$



$$V_p \exp(j(\omega t + \phi))$$

Forced response:

$$V_p \exp(j\omega t + \phi)$$



$$V_c = \frac{V_p}{1 + j\omega RC} \exp(j\omega t + \phi)$$

real

$$V_p \cos(\omega t + \phi)$$



$$\left(\frac{V_p}{\sqrt{1 + \omega^2 R^2 C^2}} \right) \cos(\omega t + \phi - \tan^{-1}(\omega RC))$$