

Define  $W = \frac{w-1}{w+1} \Rightarrow w = \frac{1+W}{1-W}$

Since  $Z = \frac{\eta-1}{\eta+1}$ , we get  $\eta = \frac{1+Z}{1-Z}$

Recall that  $w = \frac{1}{2}(\eta + \eta^{-1})$ . Hence  $\underbrace{\frac{w-1}{w+1}}_W = \left[ \underbrace{\frac{\eta-1}{\eta+1}}_{Z^2} \right]^2 \Rightarrow W = Z^2$

Therefore,  $H(\eta)H(1/\eta) = H\left(\frac{1+Z}{1-Z}\right)H\left(\frac{1-Z}{1+Z}\right) = \mathcal{V}(w) = \mathcal{V}\left(\frac{1+W}{1-W}\right)$

Define  $H\left(\frac{1+Z}{1-Z}\right) = H_1(Z) \quad \mathcal{V}_1(W) = \mathcal{V}\left(\frac{1+W}{1-W}\right)$

Hence,  $V_r(W) = H_r(Z)H_r(-Z) = V_r(Z^2)$

The above formulation is analogous to the spectral factorization problem of continuous-time systems with rational transfer function.

The steps for the alternate method are:

- 1) Replace  $\cos w$  by  $\frac{1+W}{1-W}$  to get  $V_r(W)$
- 2) Find all the roots  $W_i$  of  $V_r(W)$ .
- 3) Form the eqn  $Z^2 = W_i \Rightarrow Z_i = \sqrt{W_i}$  and  $-\sqrt{W_i}$   
 $Z_i$  denotes the root with negative real part.

4) The poles/zeros of  $H_1(z)$  are the  $z_i$  so obtained.

5) The unknown  $H(z)$  equals  $H_1\left(\frac{z-1}{z+1}\right)$ .

The gain term is found from  $H_1^2(0) = V_1(0)$ .

### Example

$$A^2(\omega) = \frac{10 - 6 \cos \omega}{\frac{5}{4} - \cos \omega}$$

$$V_1(\omega) = \frac{4 - 16\omega}{\frac{1}{4} - \frac{9}{4}\omega} \quad W_1 = \frac{1}{4}, \quad W_2 = \frac{1}{9}$$

$$z_1^2 = \frac{1}{4} \Rightarrow z_1 = -\frac{1}{2} \text{ (solution with negative real part)}$$

$$z_2^2 = \frac{1}{9} \Rightarrow z_2 = -\frac{1}{3}$$

$$H_1(z_1) = K \cdot \frac{z + \frac{1}{2}}{z + \frac{1}{3}}$$

$$H_1^2(0) = K^2 \left(\frac{3}{2}\right)^2 = V_1(0) = 16 \Rightarrow K = \frac{8}{3}$$

$$H(\omega) = H_1\left(\frac{\omega - 1}{\omega + 1}\right) = \frac{8}{3} \frac{9\omega - 3}{8\omega - 4} = \frac{3\omega - 1}{\omega - \frac{1}{2}}$$

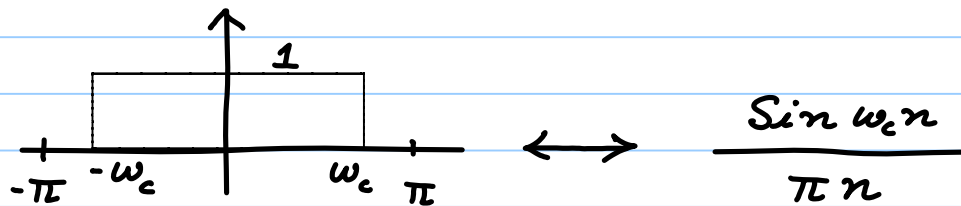
Note: By construction,  $\min^m$  phase solution is obtained.

## Group Delay

The phase response can be either strictly linear or nonlinear.

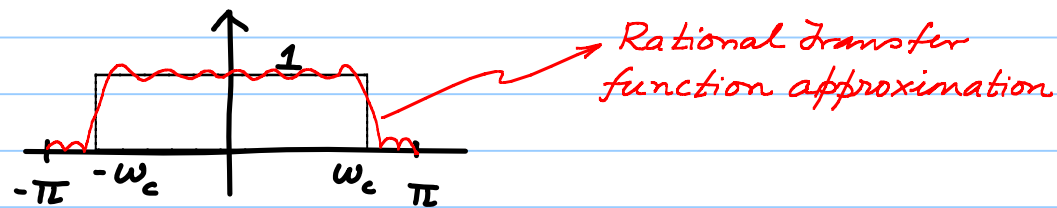
Suppose the frequency response is "zero phase", i.e., purely real-valued, then we need not bother about phase response.

Consider the ideal LPF.

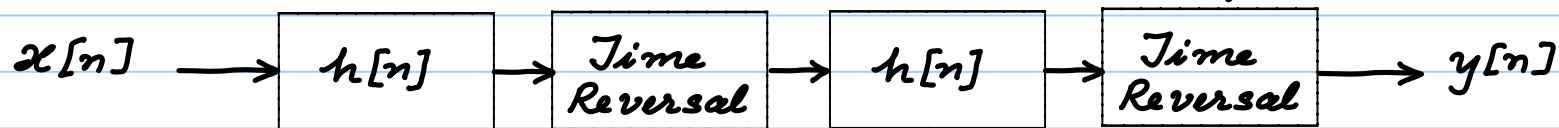


The above filter is not realizable.

Suppose we approximate the ideal LPF using a rational transfer function, with frequency response shown below:



To realize a filter with "zero phase," assuming real-valued impulse response, consider the following sequence of operations:



It is easy to verify that  $Y(e^{j\omega}) = X(e^{j\omega}) \underbrace{|H(e^{j\omega})|^2}_{\text{zero phase filter}}$

Unfortunately, the above sequence of operations results in a **non-causal filter**, and hence not realizable.

Instead of zero phase, if we had **linear phase**, the output of the linear phase filter will be a **delayed version** of zero phase filter's output. **Although delay is a distortion in the strict sense, it is a benign one.**

If rational transfer function approximations with linear phase are realizable, then they are what will be implemented in practice.

Let  $\cos \omega_1 n + \cos \omega_2 n$  be an input to a filter.

Recall the following result:

$$\cos \omega_0 n \longrightarrow \boxed{H(e^{j\omega})} \longrightarrow |H(e^{j\omega_0})| \cos(\omega_0 n + \angle H(e^{j\omega_0}))$$



If we want only delay distortion, i.e., output can, at the worst, only be a delayed version of the input, then

$$\begin{aligned}y[n] &= x[n-\alpha] = \cos(\omega_0 \overline{n-\alpha}) \\ &= \cos(\omega_0 n - \omega_0 \alpha)\end{aligned}$$

This means,  $|H(e^{j\omega_0})| = 1$  and also  $\angle H(e^{j\omega_0}) = -\alpha \omega_0$ .

That is, the phase response must be proportional to frequency, apart from unity gain at that frequency.

When there are two components, for delay distortion,

$$y[n] = \cos(\omega_1 \overline{n-\alpha}) + \cos(\omega_2 \overline{n-\alpha})$$

$$= \cos(\omega_1 n - \omega_1 \alpha) + \cos(\omega_2 n - \omega_2 \alpha)$$

where once again the phase shift has to be proportional to frequency, i.e., linear.

Suppose a filter has gain  $|H(e^{j\omega_i})| = 1$  for  $i=1,2$ , but the phase response is not linear. The output  $y[n]$  will be

$$y[n] = \cos(\omega_1 n + \theta_1) + \cos(\omega_2 n + \theta_2)$$

where  $\theta_i$  is not proportional to  $\omega_i$ .

Will the waveshape be preserved?