

Systems $\begin{cases} \text{Finite Impulse Response (FIR)} \\ \text{Infinite Impulse Response (IIR)} \end{cases}$

$$y[n] = - \sum_{k=1}^N a_k y[n-k] + \sum_{l=0}^M b_l x[n-l]$$

If the system is IIR, then at least one a_k is non-zero

If the system is FIR, then $a_k = 0$ for $k=1, 2, \dots, N$.

Consider the following system:

$$y[n] = \frac{1}{N} \sum_{k=n-N+1}^n x[k] \quad \text{--- (I) (FIR system)}$$

The above is the same as

$$y[n] = y[n-1] + \frac{1}{N} x[n] - \frac{1}{N} x[n-N] \quad \text{--- (II)}$$

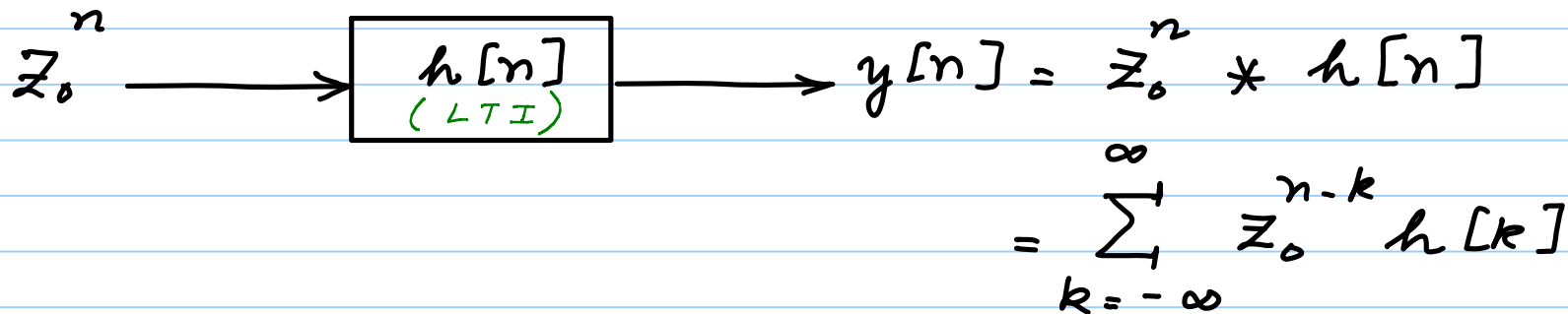
Eqn. (II) is a **recursive implementation** of a non-recursive equation, i.e., even though a_1 is non-zero, the system is not IIR

Z-Transform

The z-transform of a sequence $x[n]$ is defined as

$$X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

One way of arriving at this is by applying the **eigen signal** z_0^n as the input to an LTI system:



The diagram shows an input signal z_0^n entering a block labeled $h[n]$ (LTI). The output is $y[n] = z_0^n * h[n]$. Below this, the convolution is expanded as $= \sum_{k=-\infty}^{\infty} z_0^{n-k} h[k]$.

$$z_0^n \rightarrow \boxed{h[n] \text{ (LTI)}} \rightarrow y[n] = z_0^n * h[n]$$
$$= \sum_{k=-\infty}^{\infty} z_0^{n-k} h[k]$$

$$= z_0^n \sum_{k=-\infty}^{\infty} h[k] z_0^{-k}$$

$$= z_0^n H(z_0)$$

Where $H(z_0) = \sum_{k=-\infty}^{\infty} h[k] z_0^{-k}$

The z-transform is a complex function of a complex variable and hence requires 4 dim. to plot: 2 for the indep. var. and 2 for the dep. variable

Refer to CONFORMAL MAPPING

Examples: $x[n] = a^n u[n]$

$$X(z) = \sum_{n=0}^{\infty} a^n z^{-n}$$

$$= \frac{1}{1 - az^{-1}} \quad \text{if } |az^{-1}| < 1$$

i.e., $|z| > |a|$

Example

$$x[n] = -a^n u[-n-1]$$

$$X(z) = -\sum_{n=-\infty}^{-1} a^n z^{-n}$$

$$= \frac{1}{1 - az^{-1}} \quad \text{if } |z| < |a|$$

The algebraic expression for $X(z)$ is the same as before but the region over which it is valid is different

The range of z over which the z-transform expression is valid is called **Region of Convergence (ROC)**

Examples

$$\left\{ \begin{array}{c} -1, 2, 4, \pi \\ \uparrow \end{array} \right\} \longleftrightarrow -1 + 2z^{-1} + 4z^{-2} + \pi z^{-3} \quad 0 \notin \text{ROC}$$

right sided, $n > 0$

$$\left\{ \begin{array}{c} -1, 2, 4, \pi \\ \uparrow \end{array} \right\} \longleftrightarrow -z + 2 + 4z^{-1} + \pi z^{-2} \quad 0, \infty \notin \text{ROC}$$

two-sided

$$\left\{ \begin{array}{c} -1, 2, 4, \pi \\ \uparrow \end{array} \right\} \longleftrightarrow -z^3 + 2z^2 + 4z + \pi \quad \infty \notin \text{ROC}$$

left sided, $n \leq 0$

Example

$$x[n] = \left(-\frac{1}{2}\right)^n u[n] + \left(\frac{1}{3}\right)^n u[n]$$

$$\left(-\frac{1}{2}\right)^n u[n] \leftrightarrow \frac{1}{1 + \frac{1}{2}z^{-1}} \quad |z| > \frac{1}{2}$$

$$\left(\frac{1}{3}\right)^n u[n] \leftrightarrow \frac{1}{1 - \frac{1}{3}z^{-1}} \quad |z| > \frac{1}{3}$$

$$X(z) = \frac{1}{1 + \frac{1}{2}z^{-1}} + \frac{1}{1 - \frac{1}{3}z^{-1}} = \frac{2 - \frac{1}{6}z^{-1}}{\left(1 + \frac{1}{2}z^{-1}\right)\left(1 - \frac{1}{3}z^{-1}\right)}$$

$$\text{ROC: } |z| > \frac{1}{2} \cap |z| > \frac{1}{3} = |z| > \frac{1}{2}$$

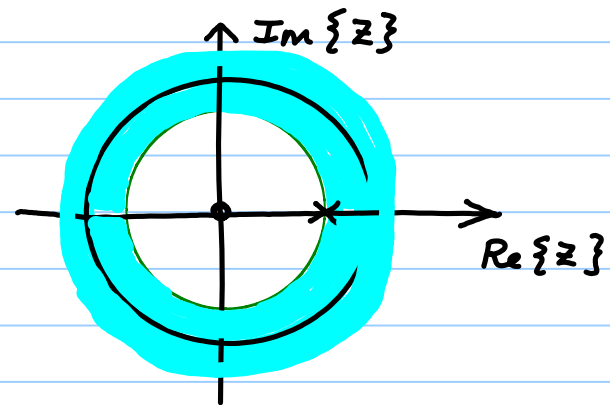
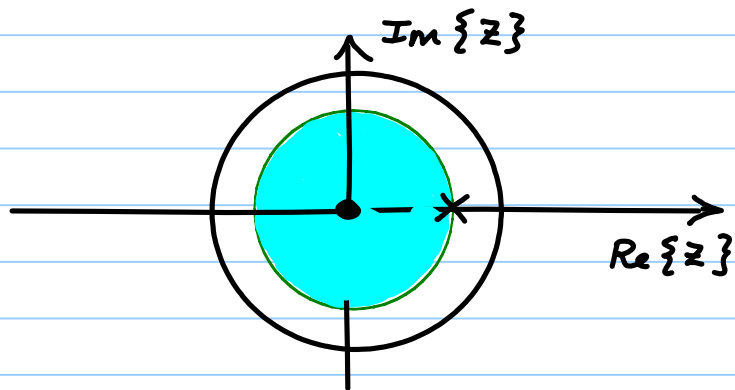
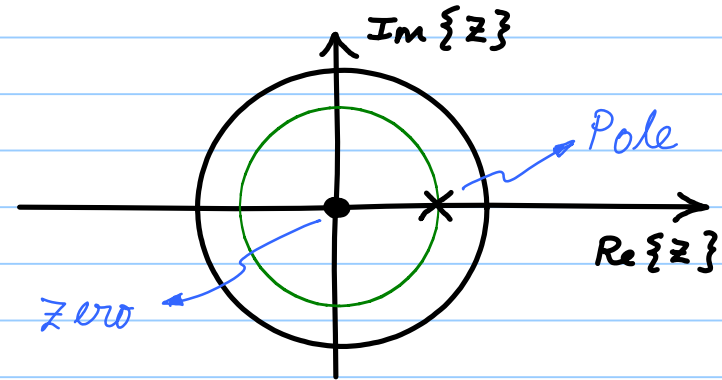
The final ROC is the INTERSECTION of the individual ROCs.

Poles and Zeros

$$X(z) = \frac{1}{1 - az^{-1}} = \frac{z}{z - a}$$

Pole: $z = a$

Zero: $z = 0$



$$\text{ROC: } |z| < |a| \Rightarrow x[n] = -a^n u[-n-1]$$

$$\text{ROC: } |z| > |a| \Rightarrow x[n] = a^n u[n]$$

Suppose $e^{j\omega} \in \text{RoC}$. We can then evaluate $H(z)$ at $z = e^{j\omega}$

$$H(z) \Big|_{z=e^{j\omega}} = \sum_{n=-\infty}^{\infty} h[n] e^{-j\omega n}$$

$$= H(e^{j\omega}) \quad \text{Discrete-Time Fourier Transform}$$

DTFT is a complex function of a single real variable ω . Hence can be plotted in one 3-D plot.

Typically two 2-D plots are shown: mag. vs. ω & phase vs. ω