

Steepest Descent Algorithm

(A gradient descent technique)

Recall LMMSE

X is Random Variable

Y is random vector

$$\hat{X}_{\text{LMMSE}} = \underline{w}_{\text{opt}}^* Y \quad \text{where}$$

$$R_Y \underline{w}_{\text{opt}} = R_{YX}$$

We will always assume R_Y is invertible
(unless otherwise stated)

$$\underline{w}_{\text{opt}} = R_Y^{-1} R_{YX}$$

steepest Descent Algorithm

* An iterative approach to find optimal LMMSE weight $\underline{w}_{\text{opt}}$

* Applies to more general cost functions (other than MSE)

* leads to adaptive filters

Algorithm

Start with weight vector $\underline{w}(0)$

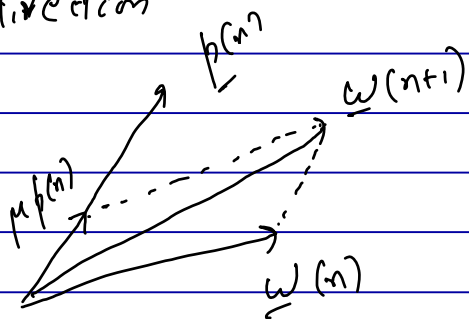
↓
time index
denoted within
braces

Update the vector as follows

$$\underline{w}(n+1) = \underline{w}(n) + \mu \underline{p}(n)$$

$\mu \rightarrow$ step size (real positive constant)

$\underline{p}(n) \rightarrow$ update direction



How should I choose μ & $\underline{p}(n)$

such that $\underline{w}(n) \rightarrow \underline{w}_{opt}$ as $n \rightarrow \infty$

Recall

$$\text{MSE}_{\text{cost}} = E (x - \hat{x})^2$$

||

$$\begin{aligned} J(\underline{w}(n)) &= \sigma_x^2 - R_{xy} \underline{w}(n) - \underline{w}(n) R_{yx} \\ &\quad + \underline{w}(n) R_y \underline{w}(n) \end{aligned}$$

$$J(\underline{w}(n+1)) = \sigma_x^2 - R_{xy} \underline{w}(n+1) - \underline{w}(n+1) R_{yx} \\ + \underline{w}(n+1) R_y \underline{w}(n+1)$$

" $\underline{w}(n) + \mu \underline{p}(n)$

after some algebra \rightarrow

$$= J(\underline{w}(n)) + \mu^2 \underline{p}(n) R_y \underline{p}(n)$$

$$J(\underline{w}(n+1)) \\ + \mu \underline{p}(n) (R_y \underline{w}(n) - R_{yx}) \\ + \mu (\underline{w}(n) R_y - R_{xy}) \underline{p}(n)$$

$$J(\underline{w}(n+1)) = J(\underline{w}(n)) + \mu^2 \underline{p}(n) R_y \underline{p}(n) \\ + 2\mu \operatorname{Re} \left\{ \underbrace{(\underline{w}(n) R_y - R_{xy}) \underline{p}(n)}_{\nabla J(\underline{w}(n))} \right\}$$

$\underline{w}(n)$

We want $J(\underline{w}(n+1)) < J(\underline{w}(n))$

Since $\mu^2 \underline{p}(n) R_y \underline{p}(n) \geq 0$

We need $\operatorname{Re} \left\{ \nabla J(\underline{w}(n)) \underline{p}(n) \right\} < 0$

$\underline{w}(n)$

first of all Note

$\nabla_{\underline{\omega}} J(\underline{\omega}(n))$ is a row vector
(Size same as $\underline{\omega}(n)$)

$$\text{Take } \underline{p}(n) = - \left[\nabla_{\underline{\omega}} J(\underline{\omega}(n)) \right]^*$$

↓
choice for steepest descent algorithm.

$$\underline{\omega}(n+1) = \underline{\omega}(n) + \mu \left[- \nabla_{\underline{\omega}} J(\underline{\omega}(n)) \right]^*$$

$$= \underline{\omega}(n) + \mu (i) \left(\underline{\omega}(n) R_T - R_T x \right)^*$$

$$\underline{\omega}(n+1) = \underline{\omega}(n) - \mu \left[R_T \underline{\omega}(n) - R_T x \right]$$

steepest
descent algorithm

$$\underline{\omega}(n+1) = \underbrace{(\mathbf{I} - \mu R_T)}_{M \times M} \underbrace{\underline{\omega}(n)}_{M \times 1 \text{ vector}} + \mu \underbrace{R_T x}_{M \times 1}$$

8/9 Will $\underline{\omega}(n) \rightarrow \underline{\omega}_{opt}$ as $n \rightarrow \infty$

Answer will depend on the value of μ .

$$(*) \rightarrow \underline{w}(n+1) = (\underline{I} - \mu R_Y) \underline{w}(n) + \mu R_Y x$$

Note $R_Y \underline{w}_{opt} = R_Y x$

Subtracting \underline{w}_{opt} from both sides of (*)

$$\underline{w}(n+1) - \underline{w}_{opt} = (\underline{I} - \mu R_Y) \underline{w}(n) + \mu (R_Y \underline{w}_{opt}) - \underline{w}_{opt}$$

$$\underline{w}(n+1) - \underline{w}_{opt} = (\underline{I} - \mu R_Y) (\underline{w}(n) - \underline{w}_{opt})$$

$$\underline{\tilde{w}}(n+1)$$

$$\underline{\tilde{w}}(n)$$

error between $\underline{w}(n)$ and \underline{w}_{opt} at n^{th} iteration

$$\underline{\tilde{w}}(n+1) = (\underline{I} - \mu R_Y) \underline{\tilde{w}}(n)$$

$$= (\underline{I} - \mu R_Y) \left[(\underline{I} - \mu R_Y) \underline{\tilde{w}}(n-1) \right]$$

Repeating this

$$\underline{\tilde{w}}(n+1) = (\underline{I} - \mu R_Y)^{n+1} \underline{\tilde{w}}(0)$$

will $(\underline{I} - \mu R_Y)^n$ converge to zero matrix

as $n \rightarrow \infty$.

Let the eigen decomposition of R_T be

$$R_T = Q \Lambda Q^*$$

$Q \rightarrow$ is orthonormal eigen vector matrix

$$Q Q^* = Q^* Q = I$$

$\begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_M \end{bmatrix} = \Lambda \rightarrow$ is diagonal matrix of eigenvalues

$$I - \mu R_T = I - \mu Q \Lambda Q^*$$

$$= Q Q^* - \mu Q \Lambda Q^*$$

$$= Q [I - \mu \Lambda] Q^*$$

$$(I - \mu R_T)^2 = Q [I - \mu \Lambda] Q^* \underbrace{Q Q^*}_I [I - \mu \Lambda] Q^*$$

$$= Q [I - \mu \Lambda]^2 Q^*$$

$$(I - \mu R_T)^n = Q [I - \mu \Lambda]^n Q^*$$

$(I - \mu R_Y)^n \rightarrow \text{zero matrix}$ if

$(I - \mu \Lambda)^n \rightarrow \text{zero matrix}$

$$\begin{bmatrix} (1 - \mu \lambda_1)^n & & & \\ & (1 - \mu \lambda_2)^n & & \\ & & \ddots & \\ & & & (1 - \mu \lambda_m)^n \end{bmatrix}$$

will converge to zero (matrix)

iff $(1 - \mu \lambda_i)^n \rightarrow 0$ for $i = 1$ to m

$|1 - \mu \lambda_i| < 1$ for all $i = 1$ to M

$$\Rightarrow -1 < 1 - \mu \lambda_i < 1 \quad \forall i$$

$$\Rightarrow 0 < \mu \lambda_i < 2 \quad \forall i$$

$$\Rightarrow \mu < \frac{2}{\lambda_i} \quad \forall i$$

equivalently

$$\boxed{0 < \mu < \frac{2}{\lambda_{\max}}}$$

→ Condition
for
convergence
of SDA

λ_{max} is the largest eigen value of R_{-1}

\times _____ \times

Other types of cost functions

$$\tilde{x} = \underline{x} - \underline{w}^* \underline{y}$$

$$\text{MSE} : E\{|\tilde{x}|^2\}$$

$$\text{Absolute Error} : E\{|\tilde{x}|\}$$

$$\text{Fourth power} : E\{|\tilde{x}|^4\}$$

$$\text{Mixed} : E\{|\tilde{x}|^2 + |\tilde{x}|^4\}$$

For all these criteria,

write cost function as a function of $\underline{w}(n)$

$$J(\underline{w}(n))$$

Gradient descent algorithm

$$\underline{w}(n+1) = \underline{w}(n) + \mu \left[-\nabla_{\underline{w}(n)} J(\underline{w}(n)) \right]$$

Convergence may be difficult to analyse

due to existence of local minima

for some types of cost functions.

Modes of convergence

Recall:

$$\underline{\tilde{w}}(n) = (\mathbf{I} - \mu \mathbf{R}_Y)^n \underline{\tilde{w}}(0)$$

$$= \mathbf{Q} [\mathbf{I} - \mu \mathbf{\Lambda}]^n \mathbf{Q}^T \underline{\tilde{w}}(0)$$

$$\mathbf{Q}^T \underline{\tilde{w}}(n) = \underbrace{\mathbf{Q}^T \mathbf{Q}}_{\mathbf{I}} [\mathbf{I} - \mu \mathbf{\Lambda}]^n \underbrace{\mathbf{Q}^T \underline{\tilde{w}}(0)}$$

$$\underline{\tilde{u}}(n) = (\mathbf{I} - \mu \mathbf{\Lambda})^n \underline{\tilde{u}}(0)$$

$$\text{Note } \|\underline{\tilde{u}}(n)\|^2 = \underline{\tilde{u}}(n)^* \underline{\tilde{u}}(n)$$

$$= (\mathbf{Q}^T \underline{\tilde{w}}(n))^* \mathbf{Q}^T \underline{\tilde{w}}(n)$$

$$= \underline{\tilde{w}}(n)^* \underbrace{\mathbf{Q} \mathbf{Q}^T}_{\mathbf{I}} \underline{\tilde{w}}(n)$$

$$= \underline{\tilde{w}}(n)^* \underline{\tilde{w}}(n)$$

$$= \|\underline{\tilde{w}}(n)\|^2$$

$\underline{\tilde{u}}(n)$ & $\underline{\tilde{w}}(n)$ have same norm

$\underline{\tilde{u}}(n) \rightarrow 0$ then $\underline{\tilde{w}}(n) \rightarrow 0$ (and vice versa)

$$\underline{\tilde{u}}(n) = \begin{bmatrix} \tilde{u}_1(n) \\ \tilde{u}_2(n) \\ \vdots \\ \tilde{u}_M(n) \end{bmatrix}$$

$$\underline{\tilde{u}}(n) = (\mathbf{I} - \mu \mathbf{A})^n \underline{\tilde{u}}(0)$$

i th coordinate

$$\tilde{u}_i(n) = (1 - \mu \lambda_i)^n \tilde{u}_i(0)$$

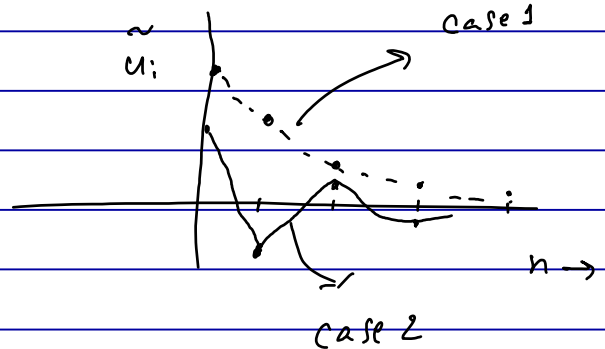
i th mode of convergence is determined

by $(1 - \mu \lambda_i)$

We need $|1 - \mu \lambda_i| < 1$ for convergence

Case 1 $0 < 1 - \mu \lambda_i < 1$

Convergence is monotonic



Case 2

$$-1 < 1 - \mu \lambda_i < 0$$

Convergence is oscillating

x ————— x

Rate of convergence is determined by
 $|1 - \mu\lambda_i|$

$$\text{fastest mode} = \min_i |1 - \mu\lambda_i|$$

$$\text{slowest mode} = \max_i |1 - \mu\lambda_i|$$

Optimal step size

In asymptotic regime (large n)

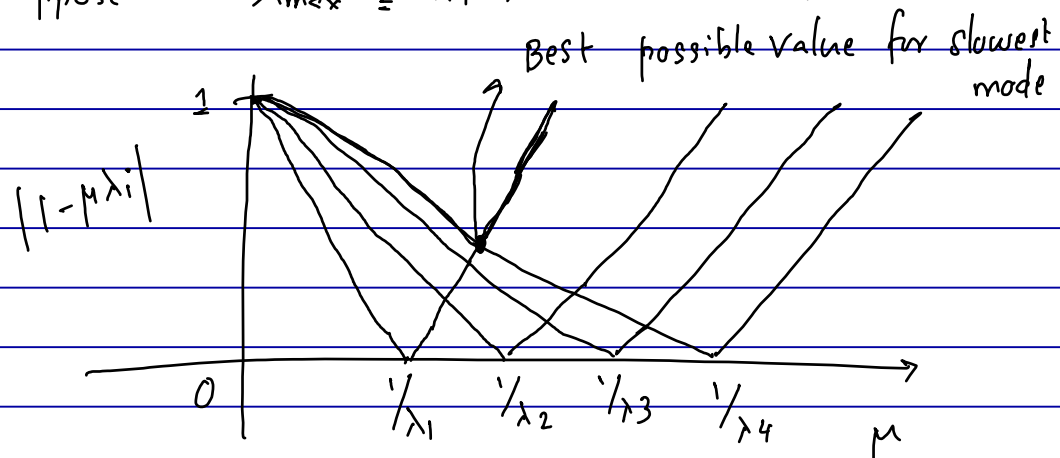
slowest mode determines overall behaviour.

Choose step size μ such that
we get the best possible slowest mode.

$$\mu_{\text{opt}} = \min_{\mu} \max_i |1 - \mu\lambda_i|$$

Consider 4 modes

Suppose $\lambda_{\text{max}} = \lambda_1 > \lambda_2 > \lambda_3 > \lambda_4 = \lambda_{\text{min}}$



slowest mode takes the minimum value
when mode 1 and mode 4 intersect.

At the intersection point

$1 - \mu \lambda_{max}$ will be negative

$1 - \mu \lambda_{min}$ will be positive

$$|1 - \mu \lambda_{max}| = |1 - \mu \lambda_{min}| \rightarrow \text{for optimal step size}$$

$$-(1 - \mu \lambda_{max}) = (1 - \mu \lambda_{min})$$

$$\boxed{\mu_{opt} = \frac{2}{\lambda_{max} + \lambda_{min}}}$$

Corresponding slowest mode

$$= (1 - \mu_{opt} \lambda_{max}) \& (1 - \mu_{opt} \lambda_{min})$$

$$= \frac{\lambda_{max} - \lambda_{min}}{\lambda_{max} + \lambda_{min}}$$

τ ————— x

Time constant of convergence (of i^{th} mode)

is defined as

$$\tau_i = \frac{-1}{2 \ln |1 - \mu \lambda_i|}$$

MSE Behavior [Learning Curve]

So far, we studied how $\underline{w}(n) \rightarrow \underline{w}_{opt}$

Now, let us see how mse $J(\underline{w}(n))$
converge to minimum?

$$J(\underline{w}(n)) = E \left\{ |x - \underline{w}(n)^T \underline{r}|^2 \right\}$$

$$= E \left\{ \underbrace{|x - \underline{w}_{opt}^T \underline{r}|^2}_I + \underbrace{|\underline{w}_{opt}^T \underline{r} - \underline{w}(n)^T \underline{r}|^2}_{II} \right\}$$

[I & II are orthogonal/uncorrelated
from Orthogonality principle]

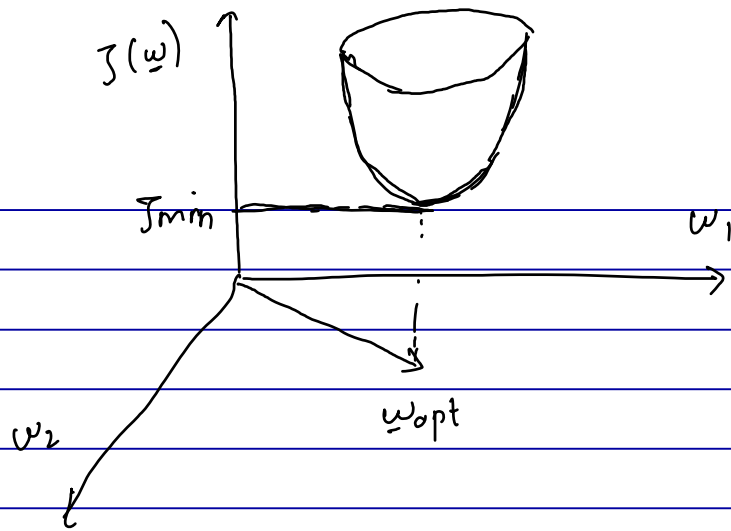
$$= E \underbrace{|x - \underline{w}_{opt}^T \underline{r}|^2}_{J_{min}} + E \left\{ \underbrace{|\underline{w}_{opt}^T \underline{r} - \underline{w}(n)^T \underline{r}|^2}_{\tilde{w}(n)} \right\}$$

(MSE of optimal filter)

$$J(\underline{w}(n)) = J_{min} + \underbrace{\tilde{w}(n)^T R_r \tilde{w}(n)}_{\geq 0}$$

2D example

$$\underline{w} = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$$



$$J(\underline{w}(n)) = J_{\min} + \underbrace{\underline{\tilde{w}}(n) R_Y \underline{\tilde{w}}(n)}_{\text{excess MSE}}$$

$\xi(n)$ → denote excess MSE at n^{th} iteration

$$\xi(n) = \underline{\tilde{w}}(n) R_Y \underline{\tilde{w}}(n)$$

$$R_Y = Q \Lambda Q^T$$

$$\underline{\tilde{u}}(n) = Q^T \underline{\tilde{w}}(n)$$

$$= \underline{\tilde{u}}(n) \Lambda \underline{\tilde{u}}(n)$$

$$(*) \rightarrow \xi(n) = \sum_{i=1}^M |\tilde{u}_i(n)|^2 \lambda_i \quad \underline{\tilde{u}}(n) = \begin{bmatrix} \tilde{u}_1(n) \\ \vdots \\ \tilde{u}_M(n) \end{bmatrix}$$

We know $\tilde{u}_i(n) \rightarrow 0$ as $n \rightarrow \infty$ if $\mu < \frac{2}{\lambda_{\max}}$

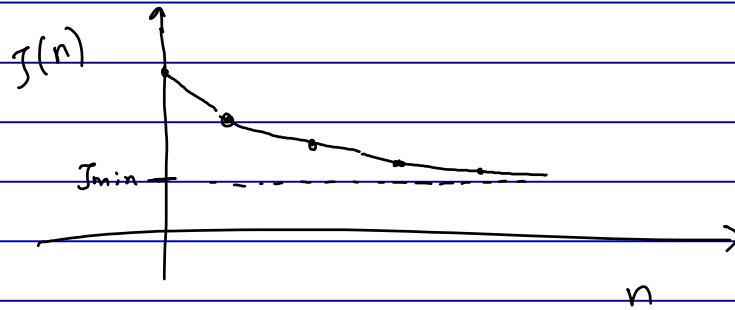
i^{th} mode convergence $\rightarrow \tilde{u}_i(n) = (1 - \mu \lambda_i)^n \tilde{u}_i(0)$

→ Put this in (*)

$$\xi(n) = \sum_{i=1}^M \lambda_i (1 - \mu \lambda_i)^{2n} |\tilde{u}_i(0)|^2$$

$$\lambda_i (1 - \mu \lambda_i)^{2n} \rightarrow 0 \text{ monotonically}$$

$$\xi(n) \rightarrow 0 \text{ monotonically as } n \rightarrow \infty.$$



Contours of Error Surface

$$J(\underline{\omega}) = c \quad (c \text{ is a constant})$$

↓
set of all $\underline{\omega}$ which give same cost

what is the shape of this contour?

$$J(\underline{\omega}) = J_{\min} + \underline{\tilde{\omega}}^T R_Y \underline{\tilde{\omega}}$$

$$\underline{\tilde{\omega}} = \underline{\omega} - \underline{\omega}_{\text{opt}}$$

$$J(\underline{\omega}) = c \Rightarrow$$

$$\underline{\tilde{\omega}}^T R_Y \underline{\tilde{\omega}} = c - J_{\min} = c_1$$

change of coordinates

$$R_Y = Q \Lambda Q^T$$

$$\underline{\tilde{u}} = Q^T \underline{\tilde{\omega}}$$

$$\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{bmatrix}$$

$$\vec{u}^T \Lambda \vec{u} = C_1$$

$$\lambda_1 |\tilde{u}_1|^2 + \lambda_2 |\tilde{u}_2|^2 + \dots + \lambda_m |\tilde{u}_m|^2 = C_1$$

\Leftrightarrow

Ellipsoid in m dim space.

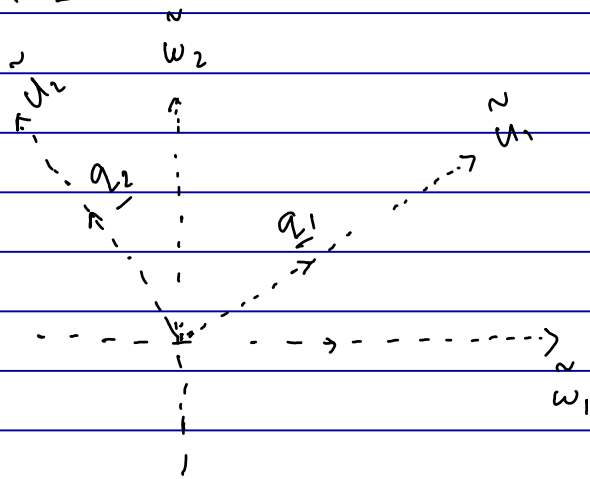
Take 2D example

$$Q = \begin{bmatrix} q_1 & q_2 \\ - & - \end{bmatrix} \quad \Lambda = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

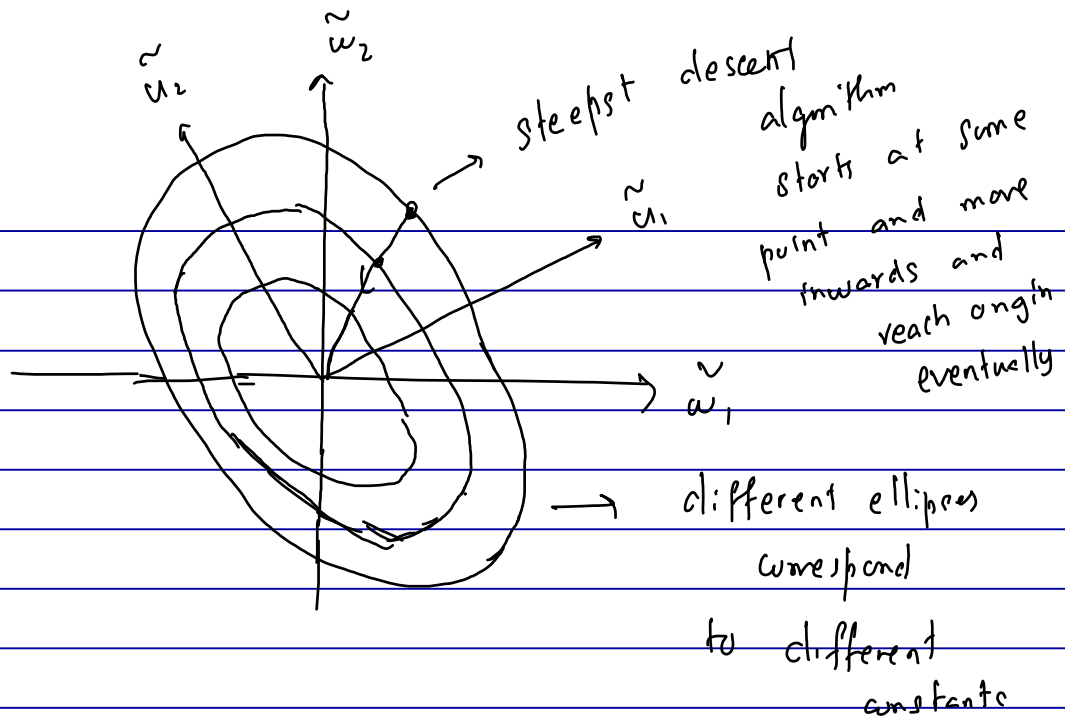
$$\vec{u} = Q \vec{w}$$

$$\vec{w} = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$$

$$\vec{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$$



Note $Q \vec{q}_1 = \begin{bmatrix} q_1 \\ q_2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$



Modifications to SDA

$$\text{SDA: } \underline{w}(n+1) = \underline{w}(n) + \mu \left[-\nabla_{\underline{w}} J(\underline{w}(n)) \right]^*$$

Iteration dependent step size

$$\underline{w}(n+1) = \underline{w}(n) + \mu(n) \left[-\nabla_{\underline{w}} J(\underline{w}(n)) \right]^*$$

choose $\mu(n)$ appropriately at each iteration to have faster convergence.

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Iteration dependent step size

$$w(n+1) = w(n) + \mu(n) [R_T x - R_T w(n)]$$

$$\text{Error } \underline{\tilde{w}}(n+1) = \underline{w}(n+1) - \underline{w}_{opt}$$

$$= [\mathbf{I} - \mu(n) \mathbf{R}_Y] \underline{\tilde{w}}(n)$$

(change of coordinates)

$$\underline{\tilde{u}}(n) = \mathbf{Q}^T \underline{\tilde{w}}(n)$$

$$\underline{\tilde{u}}(n+1) = [\mathbf{I} - \mu(n) \mathbf{\Lambda}] \underline{\tilde{u}}(n)$$

i th mode

$$\tilde{u}_i(n+1) = \left(\prod_{k=0}^n [1 - \mu(k) \lambda_i] \right) \tilde{u}_i(0)$$

want $\prod_{k=0}^n [1 - \mu(k) \lambda_i] \rightarrow 0$ as $n \rightarrow \infty$

Note that $|1 - \mu(k) \lambda_i| < 1$ for all k

is not sufficient ensure convergence.

Example -

$$a(k) = e^{-\frac{1}{(k+1)^2}}$$

$$|a(k)| < 1 \text{ for all } k$$

$$\prod_{k=1}^n a(k) \rightarrow e^{-\pi^2/6}$$

Following are some sufficient conditions
(but not necessary)

① Choose $\mu(n) \rightarrow 0$ as $n \rightarrow \infty$

and $\sum \mu(n) = \infty$

~~For~~ for instance $\mu(n) = \frac{\alpha}{n+\beta}$, $\alpha > 0$
 $\beta > 0$

or any $\mu(n)$ such that

$$\sum \mu(n) = \infty \quad \& \quad \sum \mu(n) < \infty$$

② choose $\mu(n)$ such that

$$0 < |\mu(n)| < \alpha < 1$$

Optimal choice of $\mu(n)$ for fastest convergence

$$\underline{\tilde{w}}(n+1) = (\underline{I} - \mu(n) R_Y) \underline{\tilde{w}}(n)$$

$$J(\underline{w}(n+1)) = J_{\min} + \underline{\tilde{w}}(n+1)^T R_Y \underline{\tilde{w}}(n+1)$$

$$= J_{\min} + \left[(\underline{I} - \mu(n) R_Y) \underline{\tilde{w}}(n) \right]^T R_Y \left[\cdot \right]$$

$$= J_{\min} + \underbrace{\tilde{\omega}^{\downarrow}(n) R_Y \tilde{\omega}(n)} - \left[2 \mu(n) \tilde{\omega}^{\downarrow}(n) R_Y^2 \tilde{\omega}(n) - \mu^2(n) \tilde{\omega}^{\downarrow}(n) R_Y^3 \tilde{\omega}(n) \right]$$

$$J(\omega(n+1)) = J(\omega(n)) - \underbrace{[A]}$$

Choose $\mu(n)$ so that term A is maximized

$$\frac{dA}{d\mu} = 0$$

$$\mu^{\text{opt}}(n) = \frac{\tilde{\omega}^{\downarrow}(n) R_Y^2 \tilde{\omega}(n)}{\tilde{\omega}^{\downarrow}(n) R_Y^3 \tilde{\omega}(n)}$$

For this $\mu^{\text{opt}}(n)$, will this algorithm converge?

$$\text{Excess MSE } \xi(n) = J(\omega(n)) - J_{\min}$$

$$\xi(n+1) = \xi(n) - A \Big|_{\text{evaluated at } \mu^{\text{opt}}}$$

$$= \xi(n) - \frac{\left[\tilde{\omega}^{\downarrow}(n) R_Y^2 \tilde{\omega}(n) \right]^2}{\tilde{\omega}^{\downarrow}(n) R_Y^3 \tilde{\omega}(n)}$$

If R_Y is positive definite,
 R_Y^2, R_Y^3 are also positive definite

$$0 \leq \xi(n+1) < \xi(n)$$

$\xi(n)$ is monotonically decreasing and bounded

$\Rightarrow \xi(n)$ converges

To show it converges to zero

start with some initial condition $\underline{w}(0)$

Run fixed μ SDA

$$\underline{w}^M(n+1) = \underline{w}^M(n) + \mu [R_{yx} - R_Y \underline{w}^M(n)]$$

We know that

excess error
for fixed μ
algo $\xi^M(n) \rightarrow 0$ if $0 < \mu < 2/\lambda_{\max}$

For optimal iteration dependent step size

$$\xi(n) \leq \xi^M(n) \quad \forall n$$

$$\xi(n) \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

Newton's Method

$$\text{SDA} : \underline{w}(n+1) = \underline{w}(n) + \mu \underbrace{[-\nabla_{\underline{w}} J(\underline{w}(n))]}^*$$

$$J(\underline{w}) \text{ is } \begin{matrix} \text{(MSE)} \\ \text{cost} \end{matrix} \text{ as function of } \underline{w} = \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_m \end{bmatrix}$$

$$\nabla_{\underline{w}} (J(\underline{w})) = \begin{bmatrix} \frac{\partial J}{\partial w_1} & \frac{\partial J}{\partial w_2} & \dots & \frac{\partial J}{\partial w_m} \end{bmatrix}$$

Hessian Matrix is defined as

$$\nabla_{\underline{w}}^2 (J) = \nabla_{\underline{w}} \left[\nabla_{\underline{w}} J(\underline{w}) \right]$$

$$\nabla_{\underline{w}}^2 (J(\underline{w})) = \begin{bmatrix} \frac{\partial^2 J}{\partial w_1 \partial w_1} & \frac{\partial^2 J}{\partial w_1 \partial w_2} & \dots & \frac{\partial^2 J}{\partial w_1 \partial w_m} \\ \vdots & & & \\ \frac{\partial^2 J}{\partial w_m \partial w_1} & \dots & \dots & \frac{\partial^2 J}{\partial w_m \partial w_m} \end{bmatrix}$$

For Newton algorithm

$$\underline{w}(n+1) = \underline{w}(n) + \mu (-) \left[\nabla_{\underline{w}}^2 (J(\underline{w})) \right]^{-1} \left[\nabla_{\underline{w}} (J(\underline{w})) \right]^*$$

For mse cost

$$\left[\nabla_{\underline{\omega}} (J(\underline{\omega})) \right] = \underline{\omega}^* R_Y - R_{YX}$$

$$\nabla_{\underline{\omega}}^2 (J) = \nabla_{\underline{\omega}}^* \left[\nabla_{\underline{\omega}} J \right] = R_Y$$

$$\underline{\omega}(n+1) = \underline{\omega}(n) + \mu R_Y^{-1} (R_{YX} - R_Y \underline{\omega}(n))$$

$$= \underline{\omega}(n) + \mu \underbrace{(R_Y^{-1} R_{YX})}_{\underline{\omega}_{opt}} - \underline{\omega}(n)$$

$$= \underline{\omega}(n) + \mu (\underline{\omega}_{opt} - \underline{\omega}(n))$$

Error vector

$$\tilde{\underline{\omega}}(n+1) = (1-\mu) \tilde{\underline{\omega}}(n)$$

Convergence when $|1-\mu| < 1$

For $\mu=1$, convergence happens in one iteration

$$\text{ie) } \underline{\omega}(n+1) = \underline{\omega}(n) + 1 \cdot R_Y^{-1} (R_{YX} - R_Y \underline{\omega}(n))$$

$$= R_Y^{-1} R_{YX} = \underline{\omega}_{opt}$$

equivalent to finding optimal filter directly

Learning Curve (for $\mu \neq 1$)

$$J(\underline{w}(n)) = J_{\min} + \underline{\tilde{w}}^T(n) R \underline{\tilde{w}}(n)$$

Coordinate transformation

$$\underline{\tilde{u}}(n) = Q^T \underline{\tilde{w}}(n)$$

$$= J_{\min} + \underline{\tilde{u}}^T(n) \Lambda \underline{\tilde{u}}(n)$$

$$= J_{\min} + \sum_{i=1}^M \lambda_i |\tilde{u}_i(n)|^2$$

$$= J_{\min} + \sum_{i=1}^M \lambda_i |1-\mu|^{2n} |\tilde{u}_i(0)|^2$$

∴,

Monotonically converge to

zero if $|1-\mu| < 1$

* Contour Curves (set of \underline{w} with same cost)

are same as SDA

* Convergence does not depend on λ_i 's.

* Time constant for rate of convergence

$$\text{is } \frac{-1}{2 \ln |1-\mu|}$$

