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(LS)

- Alternative to MMSE estimation
- Wide range of applications
- Originally developed by Gauss while studying planetary motions

Problem statement:

Let \underline{x} be $N \times 1$ vector $\underline{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix}$

Let H be $N \times M$ matrix

$$H = \begin{bmatrix} h_{11} & h_{12} & \dots & h_{1M} \\ \vdots & & & \\ h_{N1} & \dots & \dots & h_{NM} \end{bmatrix}$$

Given \underline{x} & H find \underline{w} $M \times 1$ such that

$$\|\underline{x} - H\underline{w}\|^2 \text{ is minimum}$$

Two examples of LS problem

1. Ergodic Averaging of MMSE

Recall MMSE problem

$$E \left\{ |x - \underline{\omega}^T \underline{Y}|^2 \right\} \quad \begin{array}{l} X \text{ is a scalar} \\ \text{random} \\ \text{Variable} \end{array}$$

\underline{Y} is $M \times 1$ random vector

Suppose we have N realizations of X & \underline{Y}

$$x^{(1)}, \dots, x^{(N)} \quad \underline{Y}^{(1)}, \underline{Y}^{(2)}, \dots, \underline{Y}^{(N)}$$

$$E \left\{ |x - \underline{\omega}^T \underline{Y}|^2 \right\} \approx \frac{1}{N} \sum_{i=1}^N |x^{(i)} - \underline{\omega}^T \underline{Y}^{(i)}|^2$$

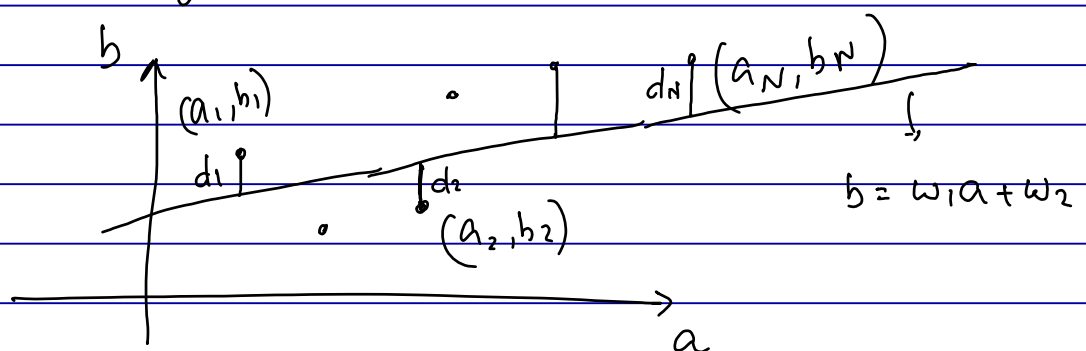
$$\sum_{i=1}^N |x^{(i)} - \underline{\omega}^T \underline{Y}^{(i)}|^2$$

$$= \left\| \begin{bmatrix} x^{(1)} & x^{(2)} & \dots & x^{(N)} \end{bmatrix} - \underline{\omega}^T \begin{bmatrix} \underline{Y}^{(1)} & \dots & \underline{Y}^{(N)} \end{bmatrix} \right\|^2$$

If we take $(\cdot)^T$
then we have the
LS problem.

2. Curve fitting problems.

We are given N points in 2D plane



$(a_1, b_1), (a_2, b_2), \dots, (a_N, b_N)$ are
given points

$$d_i = b_i - (w_1 a_i + w_2)$$

Find w_1, w_2 such that

$$\sum_{i=1}^N |d_i|^2 \text{ is minimized}$$

$$\underline{d} = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_N \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_N \end{bmatrix} - w_1 \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_N \end{bmatrix} - w_2 \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$$

$\underbrace{\hspace{10em}}_{\underline{b}}$

$$= \underline{b} - \underbrace{\begin{bmatrix} a_1 & 1 \\ \vdots & \vdots \\ a_N & 1 \end{bmatrix}}_{\underline{H}} \underbrace{\begin{bmatrix} w_1 \\ w_2 \end{bmatrix}}_{\underline{w}}$$

$$\|\underline{d}\|^2 = \|\underline{b} - \underline{H}\underline{w}\|^2$$

minimizing $\|\underline{d}\|^2$ w.r.t w_1, w_2 is LS problem

Solution for LS Estimation problem

Three Approaches

1. Geometric Approach
2. Differentiation approach
3. Completion of Squares approach

Geometric Approach.

$$\text{Given } \underline{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix} \quad N \times 1$$

$$\text{Given } H = \begin{bmatrix} h_{11} & h_{12} & \dots & h_{1M} \\ \vdots & \vdots & & \vdots \\ h_{N1} & h_{N2} & & h_{NM} \end{bmatrix} \quad N \times M$$

$\downarrow \qquad \downarrow \qquad \downarrow$

$$\underline{h(1)} \quad \underline{h(2)} \quad \underline{h(M)}$$

$\underline{h(i)}$ is i th column of H
 $N \times 1$

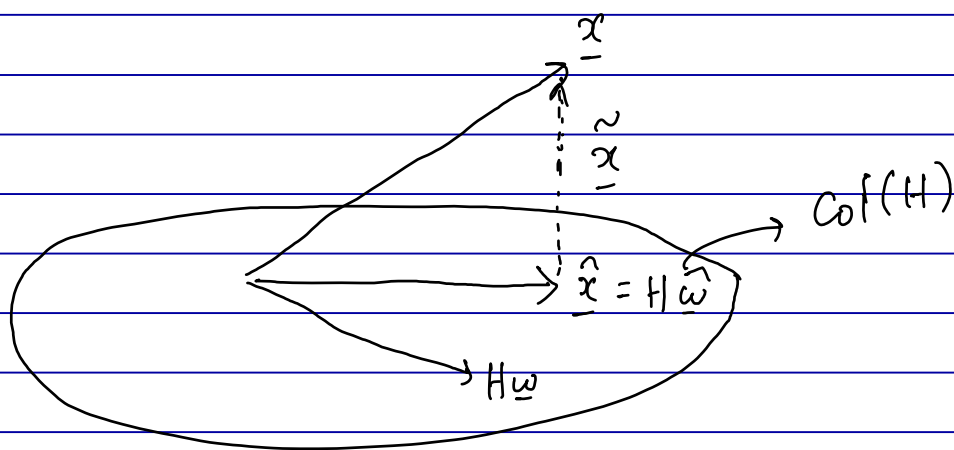
We want to find $\underline{w} = \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_M \end{bmatrix}$

such that

$$\| \underline{x} - H \underline{w} \| \text{ is minimum}$$

$$\underline{x} - H\underline{w} = \underline{x} - (\underbrace{w_1 \underline{h}(1) + w_2 \underline{h}(2) + \dots + w_m \underline{h}(m)}_{\in \text{Column Space of } H})$$

Col(H) is set of all possible
linear combinations of columns of H.



Need to choose w such that
Euclidean distance between x and $H\underline{w}$ is minimized

Will use the following result from linear algebra

Theorem: Any vector x can be
uniquely written as

$$\underline{x} = \hat{\underline{x}} + \tilde{\underline{x}}$$

where $\hat{\underline{x}} \in \text{Col}(H)$

and $\tilde{\underline{x}}$ is orthogonal to $\text{Col}(H)$

• $\hat{\underline{x}}$ is called projection of \underline{x}
onto $\text{Col}(H)$

• $\tilde{\underline{x}}$ is called projection of \underline{x}
onto orthogonal complement of $\text{Col}(H)$

Theorem:

Suppose $\hat{\underline{w}}$ is such that

$$H\hat{\underline{w}} = \hat{\underline{x}}.$$

Then $\hat{\underline{w}}$ is optimal LS solution

Proof:

Consider $\|\underline{x} - H\underline{w}\|^2$

$\hat{\underline{x}} \in \text{Col}(H)$

$\tilde{\underline{x}}$ is orthogonal
to $\text{Col}(H)$

$$= \|\hat{\underline{x}} + \tilde{\underline{x}} - H\underline{w}\|^2$$

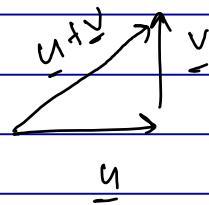
$$= \|H\hat{\underline{w}} + \tilde{\underline{x}} - H\underline{w}\|^2$$

$$= \|\tilde{\underline{x}} + (H\hat{\underline{w}} - H\underline{w})\|^2$$

$\tilde{\underline{x}}$ is orthogonal to $H\hat{\underline{w}} - H\underline{w}$

Pythagoras theorem $\rightarrow = \|\tilde{\underline{x}}\|^2 + \underbrace{\|H\underline{\hat{w}} - H\underline{w}\|^2}_{\geq 0}$

$$\geq \|\tilde{\underline{x}}\|^2$$



equality if and only if

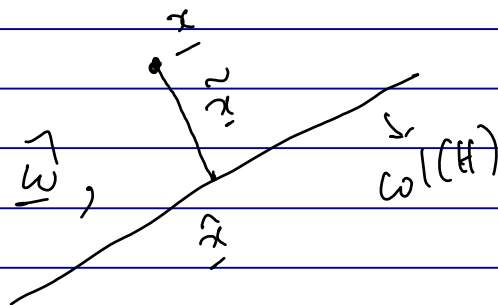
$$H\underline{\hat{w}} = H\underline{w} = \underline{x}$$

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Orthogonality Criterion

For the optimal LS solution $\underline{\hat{w}}$,



$\tilde{\underline{x}} = \underline{x} - H\underline{\hat{w}}$ is orthogonal to the column space of H .

$\underline{x} - H\underline{\hat{w}}$ is orthogonal to every vector in $\text{col}(H)$

Let $\underline{p} = \begin{bmatrix} p_1 \\ p_2 \\ \vdots \\ p_m \end{bmatrix}$

$$\underline{H}\underline{p} = p_1 \underline{h}(1) + p_2 \underline{h}(2) + \dots + p_m \underline{h}(m)$$

$$\underline{H}\underline{p} \in \text{col}(\underline{H})$$

$$\underline{x} - \underline{H}\hat{\underline{w}} \perp \underline{H}\underline{p}$$

$$(\underline{H}\underline{p})^* (\underline{x} - \underline{H}\hat{\underline{w}}) = 0$$

$$\text{for any } \underline{p}, \quad \underline{p}^* \underline{H}^* (\underline{x} - \underline{H}\hat{\underline{w}}) = 0$$

$$\Rightarrow \underline{H}^* (\underline{x} - \underline{H}\hat{\underline{w}}) = 0$$

$$\Rightarrow \boxed{\underline{H}^* \underline{H} \hat{\underline{w}} = \underline{H}^* \underline{x}}$$

Normal equations for LS

Differentiation Approach to LS solution.

Consider the cost function

$$J(\underline{w}) = \|\underline{x} - \underline{H}\underline{w}\|^2$$

$$= (\underline{x} - \underline{H}\underline{w})^* (\underline{x} - \underline{H}\underline{w})$$

$$= \|\underline{x}\|^2 - \underline{x}^T H \underline{w} - \underline{w}^T H^T \underline{x} + \underline{w}^T H^T H \underline{w}$$

Take derivative w.r.t \underline{w} and equate to zero

$$\nabla_{\underline{w}} J(\underline{w}) = 0$$

$$\Rightarrow -\underline{x}^T H + \underline{w}^T H^T H = 0$$

$$\Rightarrow \boxed{H^T H \underline{w} = H^T \underline{x}}$$

Optimal LS solution satisfies the normal equation

← →

Properties of LS Solution.

Summary of LS

- LS criterion is minimize

$$\|\underline{x} - H\underline{w}\|^2 \quad \text{w.r.t } \underline{w}$$

given \underline{x} , H

Let $\hat{\underline{w}}$ be optimal solution

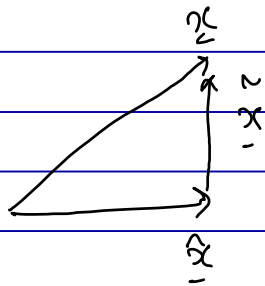
- $H^T H \hat{\underline{w}} = H^T \underline{x}$

Normal equations

$$\bullet \quad H \hat{\underline{w}} = \hat{\underline{x}} \rightarrow \text{projection of } \underline{x} \text{ onto } \text{col}(H)$$

$$\bullet \quad \tilde{\underline{x}} = \underline{x} - \hat{\underline{x}} \text{ is orthogonal to } \text{col}(H)$$

$$\bullet \quad \|\underline{x} - H\hat{\underline{w}}\|^2 = \|\tilde{\underline{x}}\|^2$$



From Pythagoras Theorem,

$$\|\underline{x}\|^2 = \|\tilde{\underline{x}}\|^2 + \|\hat{\underline{x}}\|^2$$

$$\text{So } \|\tilde{\underline{x}}\|^2 = \|\underline{x}\|^2 - \|\hat{\underline{x}}\|^2$$

The minimum LS cost

$$= \|\tilde{\underline{x}}\|^2 = \|\underline{x}\|^2 - \|\hat{\underline{x}}\|^2$$

$$= \|\underline{x}\|^2 - \|H\hat{\underline{w}}\|^2$$

x ————— x

Properties of LS solution.

1. Solution for LS problem always exists

Given \underline{x} and H we can
always find $\hat{\underline{x}}$ which is
projection of \underline{x} onto $\text{col}(H)$.

Since $\hat{\underline{x}} \in \text{col}(H)$, $\hat{\underline{x}}$ can
be written linear combination of
columns of H

$\exists \hat{w}_1, \hat{w}_2, \dots, \hat{w}_m$ such that

$$\hat{\underline{x}} = \hat{w}_1 \underline{h}(1) + \hat{w}_2 \underline{h}(2) + \dots + \hat{w}_m \underline{h}(m)$$

$$= H \hat{\underline{w}}$$

where $\hat{\underline{w}} = \begin{bmatrix} \hat{w}_1 \\ \hat{w}_2 \\ \vdots \\ \hat{w}_m \end{bmatrix}$

So LS solution $\hat{\underline{w}}$ always exist

\checkmark $\underline{H}^T \underline{H} \hat{\underline{w}} = \underline{H}^T \underline{x}$ will always have
solution

2. Uniqueness of Solution

LS solution $\hat{\underline{w}}$ is unique
if and only if all the columns
of H are linearly independent, i.e. $\text{rank}(H) = M$

$$H_{N \times M}$$

Proof: We need the following result

$$\text{rank}(H^T H) = \text{rank}(H)$$

$$\text{rank}(H) = M = \text{rank}(H^T H)$$

$$H^T H \rightarrow M \times M \text{ matrix}$$

\rightarrow full rank

\rightarrow it is invertible

Normal equation

$$H^T H \hat{\underline{w}} = H^T \underline{x}$$

$$\hat{\underline{w}} = (H^T H)^{-1} H^T \underline{x}$$

\rightarrow unique solution

3. If $\text{rank}(H) < M$ then
there are infinitely many LS solutions.

Proof: $H_{N \times M}$

$$\text{rank}(H) < M$$

\Downarrow
number of linearly independent rows or columns

The columns of H are linearly dependent

since $\text{rank}(H) < \text{number of columns}$

So $\exists p_1, p_2, \dots, p_m$ (not all zeros)

such that

$$p_1 \underline{h(1)} + p_2 \underline{h(2)} + \dots + p_m \underline{h(m)} = \underline{0}$$

$$H \underline{p} = \underline{0} \quad \text{where} \quad \underline{p} = \begin{bmatrix} p_1 \\ p_2 \\ \vdots \\ p_m \end{bmatrix}$$

$\underline{p} \in \text{Null space of } H$

\Downarrow

set of all \underline{q} such that

$$H \underline{q} = \underline{0}$$

$\alpha \underline{p} \in \text{Null space of } H$ for any scalar α

There are infinitely many vectors in Null space

Now, let $\hat{\underline{w}}$ be a LS solution of H .

Then $\hat{\underline{w}} + \underline{q}$ for any $\underline{q} \in \text{Null space of } H$

is also a LS solution

We can verify this easily

$$H^T H \hat{\underline{w}} = H^T \underline{x}$$

$$\begin{aligned} \text{Now, } H^T H (\hat{\underline{w}} + \underline{q}) &= \underbrace{H^T H \hat{\underline{w}}}_{H^T \underline{x}} + \underbrace{H^T H \underline{q}}_{\underline{0}} \\ &= H^T \underline{x} + \underline{0} \end{aligned}$$

$\hat{\underline{w}} + \underline{q}$ also satisfies the normal equation.

$\hat{\underline{w}} + \underline{q}$ is also LS solution

So there are infinitely many LS solutions

Remarks

1. Underdetermined LS problem

$H_{N \times M}$ with $N < M$.

$$\text{rank}(H) \leq \min(N, M)$$

$$\leq N$$

$$< M$$

\Rightarrow There are infinite LS solutions

2. Over determined LS problem

$$H_{N \times M} \quad \text{with} \quad N \geq M.$$

unique if $\text{rank}(H) = M$
LS
solution

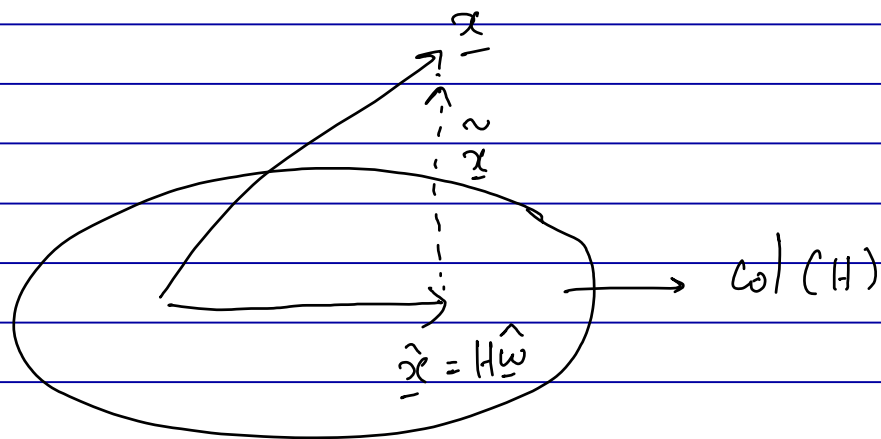
Infinitely many solutions if $\text{rank}(H) < M$.

Projection Matrices.

$H_{N \times M}$ matrix

We assume H is full column rank

$$\text{ie } \text{rank}(H) = M.$$



Given x and H , how to find the
projection of x onto $\text{col}(H)$

Let \hat{w} be LS solution

$$H^{\top} H \hat{w} = H^{\top} x$$

$$\hat{w} = (H^{\top} H)^{-1} H^{\top} x \quad \text{since } (H^{\top} H)^{-1} \text{ exist.}$$

\hat{x} is given by projection of x onto $\text{col}(H)$

$$\hat{x} = H \hat{w}$$

$$\hat{x} = H (H^{\top} H)^{-1} H^{\top} x$$

Define Projection matrix $P_H = H (H^{\top} H)^{-1} H^{\top}$

$$\hat{x} = P_H x$$

Now the projection onto orthogonal complement of $\text{col}(H)$

\tilde{x} is given by

$$\tilde{x} = x - \hat{x}$$

$$= x - P_H x$$

$$\tilde{x} = (I - P_H)x$$

x ————— x

Properties of projection matrix

(1) (conjugate) Symmetry $P_H^* = P_H$

$$P_H^* = \left(H (H^* H)^{-1} H^* \right)^*$$

$$= (H^*)^* \left((H^* H)^{-1} \right)^* (H)^*$$

$$(A^{-1})^* = (A^*)^{-1}$$

$$= H \left((H^* H)^* \right)^{-1} H^*$$

$$= H (H^* H)^{-1} H^*$$

$$= P_H$$

(2) Idempotent $P_H^2 = P_H$

$$P_H^2 = P_H \cdot P_H$$

$$= H (H^* H)^{-1} H^* \cdot H (H^* H)^{-1} H^*$$

$$= H (H^* H)^{-1} H^* = P_H$$

(a) This implies $P_H \hat{x} = \hat{x}$

$$\begin{aligned} P_H (P_H \underline{x}) &= P_H^2 \underline{x} \\ &= P_H \underline{x} \\ &= \hat{x} \end{aligned}$$

Projection of a vector which is
already in $\text{col}(H)$ onto the
(subspace)

same subspace gives the same vector.

(b) $P_H \tilde{x} = \underline{0}$

Projection of a vector orthogonal to
the subspace gives $\underline{0}$

$$\begin{aligned} P_H \tilde{x} &= P_H (I - P_H) \underline{x} \\ &= (P_H - P_H^2) \underline{x} \\ &= (P_H - P_H) \underline{x} \\ &= \underline{0} \end{aligned}$$

x



x

ASP HW3

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Weighted Least Squares (WLS)

Let A be (conjugate) symmetric and

positive definite matrix.

$$\text{LS: } \min_{\underline{w}} \|\underline{x} - H\underline{w}\|^2$$

$$\text{WLS: } \min_{\underline{w}} (\underline{x} - H\underline{w})^* A (\underline{x} - H\underline{w})$$

$A \rightarrow$ flexibility to weigh each coordinate

of $\underline{x} - H\underline{w}$ separately

For instance, if $A = \begin{bmatrix} a_1 & & 0 \\ & a_2 & \\ 0 & & \ddots \\ & & & a_N \end{bmatrix}$

then i th coordinate of $\underline{x} - H\underline{w}$

gets weighted by a_i

Want to solve WLS problem:

By using change of coordinates

we can transform WLS problem to LS problem

Let eigen decomposition of

$$A = U \Delta U^*$$

$U \rightarrow$ orthonormal eigen vector matrix

$\Delta \rightarrow$ diagonal eigen value matrix

$$\text{Let } \Delta = \begin{bmatrix} d_1 & & 0 \\ & d_2 & \\ 0 & & \ddots \\ & & & d_N \end{bmatrix}$$

$$\text{Define } \Delta^{1/2} = \begin{bmatrix} \sqrt{d_1} & & 0 \\ & \sqrt{d_2} & \\ 0 & & \ddots \\ & & & \sqrt{d_N} \end{bmatrix}$$

Consider WLS cost.

$$(\underline{x} - H\underline{w})^* A (\underline{x} - H\underline{w})$$

$$= (\underline{x} - H\underline{w})^* U \Delta U^* (\underline{x} - H\underline{w})$$

change of
variables

$$\underline{b} = \Delta^{1/2} U^* \underline{x}$$

$$B = \Delta^{1/2} U^* H$$

$$= \underbrace{(\underline{x} - H\underline{w})^* U \Delta^{1/2}}_{\downarrow} \underbrace{\Delta^{1/2} U^* (\underline{x} - H\underline{w})}_{\downarrow}$$
$$= (\underline{b} - B\underline{w})^* (\underline{b} - B\underline{w})$$

$$= \| \underline{b} - B \underline{\omega} \|^2$$

→ LS cost

By doing change of variables

$$\left. \begin{array}{l} \text{WLS problem} \\ \min_{\underline{\omega}} (\underline{x} - H \underline{\omega})^T A (\underline{x} - H \underline{\omega}) \end{array} \right\} \text{ is equivalent LS problem} \\ \text{to } \min_{\underline{\omega}} \| \underline{b} - B \underline{\omega} \|^2$$

We know how to solve LS problem

Normal equation is

$$B^T B \underline{\hat{\omega}} = B^T \underline{b}$$

Now,

$$B^T B = (\Delta^{1/2} U^T H)^T (\Delta^{1/2} U^T H)$$

$$= H^T U \underbrace{\Delta^{1/2} \Delta^{1/2}}_A U^T H$$

$$= H^T A H$$

Similarly

$$B \underline{b} = H^T A \underline{x}$$

Optimal WLS satisfies

$$\boxed{H^T A H \hat{\underline{w}} = H^T A \underline{x}} \rightarrow \text{Normal eqn for WLS}$$

Properties WLS solution

1. Solution $\hat{\underline{w}}$ will always exist
2. If $\text{rank}(H) = M$ (full column rank)

then WLS solution $\hat{\underline{w}}$ is unique

3. If $\text{rank}(H) < M$ then infinitely many WLS solutions

4. minimum WLS cost:

$$= \underline{x}^T A \underline{x} - (H \hat{\underline{w}})^T A (H \hat{\underline{w}})$$

Let us verify this

$$(\underline{x} - H \hat{\underline{w}})^T A (\underline{x} - H \hat{\underline{w}})$$

$$= \underline{x}^T A (\underline{x} - H \hat{\underline{w}}) - (H \hat{\underline{w}})^T A (\underline{x} - H \hat{\underline{w}})$$

$$= \underline{x}^T A \underline{x} - \underline{x}^T A H \hat{\underline{w}} - \hat{\underline{w}}^T H^T A (\underline{x} - H \hat{\underline{w}})$$

$$\underbrace{H^T A \underline{x} - H^T A H \hat{\underline{w}}}$$

$$\begin{aligned} x^T A H &= (H^T A x)^T \\ &= (H^T A H \hat{w})^T \end{aligned}$$

||,
 0 from
 WLS
 normal equation

So min WLS cost is

$$\begin{aligned} x^T A x - (H^T A H \hat{w})^T \hat{w} \\ = x^T A x - (H \hat{w})^T A (H \hat{w}) \end{aligned}$$

r ----- x

Regularized Least Squares

Cost function includes a term
 on the norm of the solution.
 (similar to leaky LMS)

Reg. LS criterion is

$$\min_{\underline{w}} \underline{w}^T \underline{\Pi} \underline{w} + \| \underline{x} - H \underline{w} \|^2$$

$\underline{\Pi}$ is a symmetric positive definite
 (weighting) matrix

\underline{x} , H are given data

Here also we can do change of variables
and reduce it to a LS problem.

$$\text{Define } \underline{b} = \begin{bmatrix} \underline{0}_{M \times 1} \\ \underline{x} \end{bmatrix}$$

$(M+N) \times 1$ vector.

Let eigen decomposition of

$$\Pi = U \Delta U^*$$

$$\text{Define matrix } B = \begin{bmatrix} \Delta^{1/2} U^* \\ \dots \\ H \end{bmatrix}$$

$(M+N) \times M$ matrix

$$\text{Consider } \|\underline{b} - B\underline{w}\|^2$$

$$= \left\| \begin{bmatrix} \underline{0} \\ \underline{x} \end{bmatrix} - \begin{bmatrix} \Delta^{1/2} U^* \\ H \end{bmatrix} \underline{w} \right\|^2$$

$$= \left\| \begin{bmatrix} 0 - \Delta^{1/2} U^* \underline{w} \\ \underline{x} - H \underline{w} \end{bmatrix} \right\|^2$$

easy to
verify

$$\rightarrow = \left\| 0 - \Delta^{1/2} U^T \underline{w} \right\|^2 + \left\| \underline{x} - H \underline{w} \right\|^2$$

$$= \underline{w}^T U \Delta^{1/2} \Delta^{1/2} U^T \underline{w} + \left\| \underline{x} - H \underline{w} \right\|^2$$

$$= \underline{w}^T \Pi \underline{w} + \left\| \underline{x} - H \underline{w} \right\|^2$$

We have reduced
reg. LS problem to (standard)
LS problem

$$\min_{\underline{w}} \underline{w}^T \Pi \underline{w} + \left\| \underline{x} - H \underline{w} \right\|^2 \quad \min_{\underline{w}} \left\| \underline{b} - B \underline{w} \right\|^2$$

Optimal Reg. LS solution $\hat{\underline{w}}$

satisfies normal equation

$$B^T B \hat{\underline{w}} = B^T \underline{b}$$

↓

we can write this in terms

of original variables

$$\left(\Pi + H^T H \right) \hat{\underline{w}} = H^T \underline{x}$$

$\Pi + H^T H$ is always full rank

So reg. LS has unique solution

$$\hat{\underline{w}} = (\underline{\Pi} + \underline{H}^T \underline{H})^{-1} \underline{H}^T \underline{x}$$

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Minimum Reg. LS Cost:

$$\mathcal{E} = (\underline{b} - \underline{B} \hat{\underline{w}})^T (\underline{b} - \underline{B} \hat{\underline{w}})$$

using the
equivalence with
standard LS

$$\begin{aligned} &= \underline{b}^T (\underline{b} - \underline{B} \hat{\underline{w}}) - \hat{\underline{w}}^T \underline{B}^T (\underline{b} - \underline{B} \hat{\underline{w}}) \\ &= \underline{b}^T \underline{b} - \underline{b}^T \underline{B} \hat{\underline{w}} \end{aligned}$$

$= 0$
↓
Normal equation

$$\underline{b} = \begin{bmatrix} \underline{0}_{m \times 1} \\ \underline{x} \end{bmatrix}$$

$$= \underline{x}^T \underline{x} - \underline{x}^T \underline{H} \hat{\underline{w}}$$

$$\underline{B} = \begin{bmatrix} \Delta^{1/2} \underline{U} \\ \dots \\ \underline{H} \end{bmatrix}$$

$$= \underline{x}^T (\underline{x} - \underline{H} \hat{\underline{w}})$$

Simplify further

$$= \underline{x}^T (\underline{x} - \underline{H} (\underline{\Pi} + \underline{H}^T \underline{H})^{-1} \underline{H}^T \underline{x})$$

$$= \underline{x}^T (\underline{I} - \underline{H} (\underline{\Pi} + \underline{H}^T \underline{H})^{-1} \underline{H}^T) \underline{x}$$

$$= \underline{x}^T (\underline{I} + \underline{H} \underline{\Pi}^{-1} \underline{H}^T)^{-1} \underline{x}$$

Matrix
inversion
lemma

→

Weighted Regularized Least Squares

$$\text{Criterion: } \min_{\underline{w}} \underline{w}^* \Pi \underline{w} + (\underline{x} - H\underline{w})^* A (\underline{x} - H\underline{w})$$

Given data \underline{x} , H

Your choice of Π , A (Symmetric & positive definite)

Again, using similar change of variables ideas, we can solve this problem.

$$\text{Normal Equation: } (\Pi + H^* A H) \hat{\underline{w}} = H^* A \underline{x}$$

Unique solution will always exist

$$\hat{\underline{w}} = (\Pi + H^* A H)^{-1} H^* A \underline{x}$$

Corresponding minimum cost

$$\mathcal{E} = \underline{x}^* A (\underline{x} - H \hat{\underline{w}})$$

$$= \underline{x}^* \underbrace{[A^{-1} + H \Pi^{-1} H^*]^{-1}}_x \underline{x}$$

Recursive Least Squares (RLS)

$$\text{Given } \underline{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix} \quad H = \begin{bmatrix} h_{11} & \dots & h_{1M} \\ \vdots & & \vdots \\ h_{N1} & \dots & h_{NM} \end{bmatrix}$$

$N \times 1$ $N \times M$ matrix

& Choice of Π (symmetric & positive definite)

$$\text{Regularized LS} \quad \min_{\underline{w}} \underline{w}^T \Pi \underline{w} + \|\underline{x} - H\underline{w}\|^2$$

We know the optimal solution is

$$\hat{\underline{w}} = \left(\Pi + H^T H \right)^{-1} H^T \underline{x}$$

Since we have N dimensional data

(\underline{x} has N entries

H has N rows) we

denote this dimension explicitly & write

$$\hat{\underline{w}}_N = \left(\Pi + H_N^T H_N \right)^{-1} H_N^T \underline{x}_N$$

Say we have solved the LS problem with N dimensional data.

Suppose we add one more data point.

ie) Add one more entry x_{N+1} to \underline{x}

$$\underline{x}_{N+1} = \begin{bmatrix} x_1 \\ \vdots \\ x_N \\ x_{N+1} \end{bmatrix} \begin{array}{l} \rightarrow \text{previous data} \\ \rightarrow \text{New data point.} \end{array}$$

Add one more row to H

$$H_{N+1} = \begin{array}{c} \begin{bmatrix} h_{11} & \dots & h_{1M} \\ \vdots \\ h_{N1} & \dots & h_{NM} \end{bmatrix} \rightarrow \text{previous data} \\ \begin{array}{c} \leftarrow h_{N+1} \\ \hline \begin{bmatrix} h_{(N+1)1} & \dots & h_{(N+1)M} \end{bmatrix} \rightarrow \text{new data} \end{array} \end{array}$$

Now, we want to solve the problem

$$\min_{\underline{w}} \underline{w}^T \underline{w} + \left\| \underline{x}_{N+1} - H_{N+1} \underline{w} \right\|^2$$

Note that size of \underline{w} has not changed

$$\text{We know } \underline{\hat{w}}_{N+1} = \left(\underline{\Pi} + H_{N+1} H_{N+1}^T \right)^{-1} H_{N+1}^T \underline{x}_{N+1}$$

\downarrow
MxM inversion

Can we compute \hat{w}_{N+1} efficiently
(without $M \times M$ matrix inversion)

using the fact that we have
already computed \hat{w}_N .

Yes, Recursive Least Squares (RLS)

gives a method for this

(using matrix inversion lemma)

Derivation of RLS.

$$\text{Define } P_N = \left(\Pi + H_N^* H_N \right)^{-1}$$

$$P_{N+1} = \left(\Pi + H_{N+1}^* H_{N+1} \right)^{-1}$$

$$\text{Now, } \hat{w}_N = P_N H_N^* z_N$$

$$\hat{w}_{N+1} = P_{N+1} H_{N+1}^* z_{N+1}$$

$$H_{N+1} = \begin{bmatrix} H_N \\ \vdots \\ h_{N+1}^* \end{bmatrix} \quad h_{N+1}^* \text{ is the last row of } H_{N+1}$$

$$P_{N+1}^{-1} = \Pi + H_{N+1}^{\rightarrow} H_{N+1}$$

$$= \Pi + \begin{bmatrix} \vec{H}_N & \underline{h}_{N+1} \end{bmatrix} \begin{bmatrix} \underline{H}_N \\ \vec{h}_{N+1} \end{bmatrix}$$

$$= \underbrace{\Pi + H_N^{\rightarrow} H_N}_{P_N^{-1}} + \underline{h}_{N+1} \cdot \vec{h}_{N+1}$$

$$P_{N+1}^{-1} = P_N^{-1} + \underline{h}_{N+1} \vec{h}_{N+1}$$

We need to compute P_{N+1}

$$P_{N+1} = \left(P_{N+1}^{-1} \right)^{-1} = \left(P_N^{-1} + \underline{h}_{N+1} \vec{h}_{N+1} \right)^{-1}$$

We can use matrix inversion lemma

$$(A + BCD)^{-1} = A^{-1} - A^{-1}B(C^{-1} + DA^{-1}B)^{-1}DA^{-1}$$

Take $A = P_N^{-1}$ $B = \underline{h}_{N+1}$ $C = 1$ $D = \vec{h}_{N+1}$

recursion for P_N \rightarrow
$$P_{N+1} = P_N - \frac{P_N \underline{h}_{N+1} \vec{h}_{N+1} P_N}{(1 + \vec{h}_{N+1} P_N \underline{h}_{N+1})}$$

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The new LS estimate $\hat{\underline{w}}_{N+1}$ is obtained as

$$\hat{\underline{w}}_{N+1} = P_{N+1} \underline{H}_{N+1}^* \underline{x}_{N+1}$$

$$= \left[P_N - \frac{P_N \underline{h}_{N+1} \underline{h}_{N+1}^* P_N}{1 + \underline{h}_{N+1}^* P_N \underline{h}_{N+1}} \right] [\underline{H}_N^* \underline{h}_{N+1}]$$

$$\times \begin{bmatrix} \underline{x}_N \\ \underline{x}_{N+1} \end{bmatrix}$$

$$= \underbrace{P_N \underline{H}_N^* \underline{x}_N}_{\hat{\underline{w}}_N} - \frac{P_N \underline{h}_{N+1} \underline{h}_{N+1}^* P_N \underline{H}_N^* \underline{x}_N}{1 + \underline{h}_{N+1}^* P_N \underline{h}_{N+1}} \underbrace{\underline{h}_{N+1}^* P_N \underline{H}_N^* \underline{x}_N}_{\hat{\underline{w}}_N}$$

$$= P_N \underline{h}_{N+1} \left(1 - \frac{\underline{h}_{N+1}^* P_N \underline{h}_{N+1}}{1 + \underline{h}_{N+1}^* P_N \underline{h}_{N+1}} \right) \underline{x}_{N+1}$$

$$\hat{\underline{w}}_{N+1} = \hat{\underline{w}}_N + \frac{P_N \underline{h}_{N+1}}{1 + \underline{h}_{N+1}^* P_N \underline{h}_{N+1}} (\underline{x}_{N+1} - \underline{h}_{N+1}^* \hat{\underline{w}}_N)$$

↪ recursion for LS solution

For convenience, we define two terms

$$\text{Conversion factor } \gamma(N+1) = \frac{1}{1 + \underline{h}_{N+1}^T P_N \underline{h}_{N+1}}$$

$$\text{Gain factor } \underline{g}(N+1) = P_N \underline{h}_{N+1} \gamma(N+1)$$

We can verify that

$$\gamma(N+1) = 1 - \underline{h}_{N+1}^T P_N \underline{h}_{N+1}$$

$$\text{and } \underline{g}(N+1) = P_N \underline{h}_{N+1}$$

x _____ x

Summary of RLS

Consider regularized LS problem

$$\min_{\underline{w}} \underline{w}^T \underline{\Pi} \underline{w} + \|\underline{x} - \underline{H} \underline{w}\|^2$$

The optimal solution can be recursively computed as follows.

$$\text{Initialize } \underline{\hat{w}}_{-1} = \underline{0} \quad P_{-1} = \underline{\Pi}^{-1}$$

For $i \geq 0$, compute

$$\gamma(i) = \frac{1}{\underline{h}_i^* \underline{P}_{i-1} \underline{h}_i}$$

where \underline{h}_i is i th row of H matrix

$$\text{and } \underline{g}(i) = \underline{P}_{i-1} \underline{h}_i \gamma(i)$$

Optimal Reg. LS solution

(with i data samples)

$$\underline{\hat{w}}_i = \underline{\hat{w}}_{i-1} + \underline{g}_i [x_i - \underline{h}_i^* \underline{\hat{w}}_{i-1}]$$

$x_i \rightarrow i$ th coordinate of \underline{x}

$$\underline{P}_i = \underline{P}_{i-1} - \frac{\underline{g}(i) \underline{g}^*(i)}{\gamma(i)}$$

\underline{P}_i has interpretation $\underline{P}_i = (\underline{\Pi} + \underline{H}_i^* \underline{H}_i)^{-1}$

$\underline{H}_i \rightarrow$ matrix with first i rows
of H .

x x

Remarks:

Regularization

The presence of a regularization term (using positive definite Π), we are guaranteed to have unique solution.

$(\Pi + H_N^T H_N)^{-1}$ exists for any N rows of H

Without regularization; the matrix $H_N^T H_N$ may not be invertible

1) If $N < M$ then $H_N^T H_N$ is not invertible.

2) If $N \geq M$ then $H_N^T H_N$ may or may not be invertible

Conversion factor

Define two error quantities

a priori estimation error

$$e_a(N+1) = x_{N+1} - h_{N+1}^T \hat{w}_N$$

last entry in $x_{N+1} - H_{N+1} \hat{w}_N$

$\hat{\underline{w}}_N \rightarrow$ LS estimate using N data samples

a posteriori estimation error

$$e_p(N+1) = x_{N+1} - \underline{h}_{N+1}^T \hat{\underline{w}}_{N+1}$$

\downarrow
error after updating LS solution
using new data sample

We have

$$e_p(N+1) = x_{N+1} - \underline{h}_{N+1}^T \hat{\underline{w}}_{N+1}$$

$$= x_{N+1} - \underline{h}_{N+1}^T \left(\hat{\underline{w}}_N + \underline{g}(N+1) \underbrace{\left[x_{N+1} - \underline{h}_{N+1}^T \hat{\underline{w}}_N \right]}_{e_a(N+1)} \right)$$

$$= \underbrace{x_{N+1} - \underline{h}_{N+1}^T \hat{\underline{w}}_N}_{e_a(N+1)} - \underline{h}_{N+1}^T \underline{g}(N+1) e_a(N+1)$$

$$= \left[1 - \underline{h}_{N+1}^T \underline{g}(N+1) \right] e_a(N+1)$$

$$\boxed{e_p(N+1) = \gamma(N+1) e_a(N+1)}$$

From the definition, $\gamma(N+1) = \frac{1}{1 + \underbrace{\underline{h}_{N+1}^T \underline{P}_N \underline{h}_{N+1}}_{\geq 0}}$

$$0 < \gamma(N+1) \leq 1.$$

We always have

$$|e_p(N)| \leq |e_a(N)| \text{ for any } N.$$

x _____ x

Recursion for the minimum cost

$$\xi = \underline{x}^T \underline{x} - \underline{x}^T H \underline{\hat{w}}$$

(from before)

$$= \underline{x}^T (\underline{x} - H \underline{\hat{w}})$$

With N observations

$$\xi_p(N) = \underline{x}_N^T (\underline{x}_N - H_N \underline{\hat{w}}_N)$$

With the additional $(N+1)^{\text{th}}$ observation

$$\xi_p(N+1) = \underline{x}_{N+1}^T (\underline{x}_{N+1} - H_{N+1} \underline{\hat{w}}_{N+1})$$

$$\underline{\hat{w}}_{N+1} = \underline{\hat{w}}_N + g(N+1) \underbrace{[\underline{x}_{N+1} - h_{N+1}^T \underline{\hat{w}}_N]}_{e_a(N+1)}$$

$$\xi(N+1) = \begin{bmatrix} \underline{x}_N \\ \underline{x}_{N+1} \end{bmatrix}^T \left(\begin{bmatrix} \underline{x}_N \\ \underline{x}_{N+1} \end{bmatrix} - \begin{bmatrix} H_N \\ \underline{h}_{N+1} \end{bmatrix} \hat{\underline{w}}_N + \underline{g}(N+1) e_a(N+1) \right)$$

$$= \begin{bmatrix} \underline{x}_N & \underline{x}_{N+1} \end{bmatrix} \begin{bmatrix} \underline{x}_N - H_N (\hat{\underline{w}}_N + \underline{g}(N+1) e_a(N+1)) \\ \underline{x}_{N+1} - \underline{h}_{N+1} (\hat{\underline{w}}_N + \underline{g}(N+1) e_a(N+1)) \end{bmatrix}$$

$$= \underbrace{\begin{bmatrix} \underline{x}_N & \underline{x}_{N+1} \end{bmatrix}}_{\xi(N)} \begin{bmatrix} \underline{x}_N - H_N \hat{\underline{w}}_N \\ \underline{x}_{N+1} - \underline{h}_{N+1} \hat{\underline{w}}_N \end{bmatrix} - \underline{x}_N^T H_N \underline{g}(N+1) e_a(N+1) \\ + \underline{x}_{N+1}^T e_a(N+1) (1 - \underline{h}_{N+1}^T \underline{g}(N+1))$$

after some

algebra $\rightarrow = \xi(N) + |e_a(N+1)|^2 \gamma(N+1)$

$$\xi(N+1) = \xi(N) + \gamma(N+1) |e_a(N+1)|^2$$

$$\text{We had } e_p(N+1) = x_{N+1} - h_{N+1}^T \hat{w}_{N+1}$$

$$e_p(N+1) = e_a(N+1) \gamma(N+1)$$

$$\begin{aligned} \text{So } |e_a(N+1)|^2 \gamma(N+1) &= e_a^*(N+1) e_p(N+1) \\ &= \frac{|e_p(N+1)|^2}{\gamma(N+1)} \end{aligned}$$

x ←————→ x

Exponentially weighted RLS

Choose a weighting factor $0 << \lambda < 1$
(λ is close to 1)

$$\underline{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_N \end{bmatrix} \quad H = \begin{bmatrix} h_{11} & \dots & h_{1M} \\ \vdots & & \vdots \\ h_{N1} & \dots & h_{NM} \end{bmatrix} \quad \underline{w} = \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_M \end{bmatrix}$$

$$\underline{x} - H\underline{w} = \underline{d} = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_N \end{bmatrix}$$

Exponentially weighted cost

$$\min_{\underline{w}} \lambda^N \underline{w}^T \Pi \underline{w} + \sum_{i=1}^N \lambda^{(N+1-i)} |d_i|^2$$

Equivalently

$$\min_{\underline{w}} \lambda^N \underline{w}^T \Pi \underline{w} + (\underline{x} - H\underline{w})^T \begin{matrix} \Lambda_N \\ \left[\begin{array}{c} \lambda^N & 0 \\ \vdots & \lambda^2 \\ 0 & \lambda \end{array} \right] \\ (\underline{x} - H\underline{w}) \end{matrix}$$

$$\min_{\underline{w}} \lambda^N \underline{w}^T \Pi \underline{w} + (\underline{x} - H\underline{w})^T \Lambda_N (\underline{x} - H\underline{w})$$

Optimal solution from normal equations

$$\left(\lambda^N \Pi + H_N^T \Lambda_N H_N \right) \hat{\underline{w}}_N = H_N^T \Lambda_N \underline{x}_N$$

$$\text{Let } P_N = \left(\lambda^N \Pi + H_N^T \Lambda_N H_N \right)^{-1}$$

Recursive way of updating $\hat{\underline{w}}_N$

$$\text{Initialization } \underline{w}_0 = \underline{0} \quad P_0 = \Pi^{-1}$$

$$E(0) = 0$$

for $i \geq 1$

$$\gamma(i) = \frac{1}{1 + \underline{h}_i^T P_{i-1} \underline{h}_i}$$

$\underline{h}_i^T \rightarrow i$ th row of H

$$\underline{g}(i) = \lambda^{-1} P_{i-1} \underline{h}_i \gamma(i)$$

$$e_a(i) = x_i - \underline{h}_i^T \underline{\hat{w}}_{i-1}$$

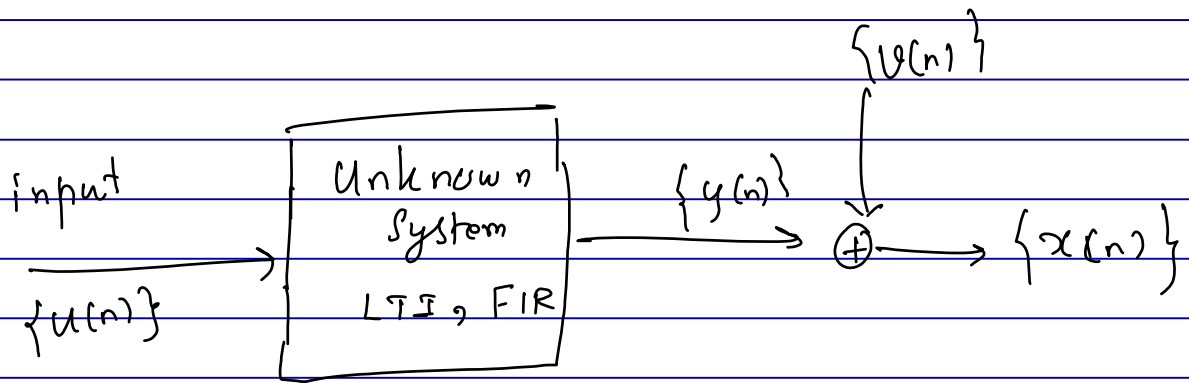
$$\rightarrow \underline{\hat{w}}_i = \underline{\hat{w}}_{i-1} + \underline{g}_i e_a(i)$$

Optimal weighted RLS solution with i data samples

$$P_i = \lambda^{-1} P_{i-1} - \frac{\underline{g}_i \underline{g}_i^T}{\gamma(i)}$$

$$\xi(i) = \xi(i-1) + \gamma(i) |e_a(i)|^2$$

Least Squares in System identification



$$y(n) = \sum_{l=0}^{L-1} \alpha_l u(n-l)$$

$\alpha_0, \alpha_1, \dots, \alpha_{L-1}$ are unknown

Collect the measurements ($N+1$ samples)

$$\underbrace{\begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N) \end{bmatrix}}_{\underline{x}} = \underbrace{\begin{bmatrix} u(0) & u(-1) & \dots & u(-L+1) \\ \vdots & \vdots & \ddots & \vdots \\ u(N) & u(N-1) & \dots & u(N-L+1) \end{bmatrix}}_{\underline{H}} \underbrace{\begin{bmatrix} \alpha_0 \\ \alpha_1 \\ \vdots \\ \alpha_L \end{bmatrix}}_{\underline{\alpha}} + \underbrace{\begin{bmatrix} w(0) \\ \vdots \\ w(N) \end{bmatrix}}_{\underline{w}}$$

$$\underline{x} = \underline{H} \underline{\alpha} + \underline{w}$$

$$\text{find } \min_{\underline{\alpha}} \|\underline{x} - H\underline{\alpha}\|^2$$

$$\hat{\underline{\alpha}}_{\text{LS}} = (H^T H)^{-1} H^T \underline{x}$$

Assuming H is full column rank.

α ————— x