

$$\textcircled{1} \quad s_0(t) = \cos\left(\frac{2\pi t}{T}\right) \quad s_1(t) = \cos\left(\frac{4\pi t}{T}\right), \quad 0 \leq t \leq T$$

$$(a) \quad \psi_1(t) = \frac{s_0(t)}{\|s_0(t)\|}$$

$$\begin{aligned} \|s_0(t)\|^2 &= \int_0^T \cos^2\left(\frac{2\pi t}{T}\right) dt = \int_0^T \frac{1 + \cos\left(\frac{4\pi t}{T}\right)}{2} dt \\ &= \frac{T}{2} + \frac{1}{2} \left[\sin\left(\frac{4\pi t}{T}\right) \cdot \frac{T}{4\pi} \right]_0^T = \frac{T}{2} \end{aligned}$$

$$\therefore \psi_1(t) = \sqrt{\frac{2}{T}} \cos\left(\frac{2\pi t}{T}\right)$$

$$\phi_2(t) = s_1(t) - \langle \psi_1(t), s_1(t) \rangle \psi_1(t)$$

$$= \cos\left(\frac{4\pi t}{T}\right) - \left\langle \sqrt{\frac{2}{T}} \cos\left(\frac{2\pi t}{T}\right), \cos\left(\frac{4\pi t}{T}\right) \right\rangle \cdot \sqrt{\frac{2}{T}} \cos\left(\frac{2\pi t}{T}\right)$$

$$\textcircled{A} = \int_0^T \sqrt{\frac{2}{T}} \cdot \frac{1}{2} \left[\cos\left(\frac{6\pi t}{T}\right) + \cos\left(\frac{2\pi t}{T}\right) \right] dt$$

$$= \sqrt{\frac{2}{T}} \frac{1}{2} \left[\frac{T}{6\pi} \sin\left(\frac{6\pi t}{T}\right) \Big|_0^T + \frac{T}{2\pi} \sin\left(\frac{2\pi t}{T}\right) \Big|_0^T \right]$$

$$= \frac{1}{\sqrt{2T}} \cdot 0 = 0$$

$$\therefore \phi_2(t) = \cos\left(\frac{4\pi t}{T}\right), \quad \|\phi_2(t)\|^2 = \frac{T}{2}$$

$$\psi_2(t) = \frac{\phi_2(t)}{\|\phi_2(t)\|} = \sqrt{\frac{2}{T}} \cos\left(\frac{4\pi t}{T}\right)$$

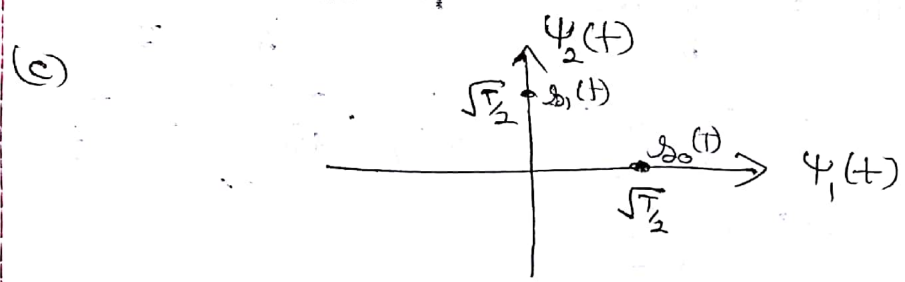
$$\text{Also, } \langle \psi_1(t), \psi_2(t) \rangle = \int_0^T \sqrt{\frac{2}{T}} \cos\left(\frac{2\pi t}{T}\right) \cdot \sqrt{\frac{2}{T}} \cos\left(\frac{4\pi t}{T}\right) dt$$

$$= 0 \text{ from (A)}$$

∴ set of orthonormal bases are
 $\psi_1(t) = \sqrt{\frac{2}{T}} \cos\left(\frac{2\pi t}{T}\right)$ and $\psi_2(t) = \sqrt{\frac{2}{T}} \cos\left(\frac{4\pi t}{T}\right)$

(b) We can observe that,

$$s_0(t) = \sqrt{\frac{T}{2}} \psi_1(t) \text{ and } s_1(t) = \sqrt{\frac{T}{2}} \psi_2(t)$$



signal space constellation

(d) Now, $s_0(t) = \cos\left(\frac{\pi t}{T}\right)$ $s_1(t) = \cos\left(\frac{3\pi t}{2T}\right)$ $0 \leq t \leq T$

~~∴~~ $\psi_1(t) = \frac{s_0(t)}{\|s_0(t)\|}$, Again $\|s_0(t)\|^2 = \frac{T}{2}$

∴ $\psi_1(t) = \sqrt{\frac{2}{T}} \cos\left(\frac{\pi t}{T}\right)$

$\psi_2(t) = s_1(t) - \langle s_1(t), \psi_1(t) \rangle \psi_1(t)$

$\langle s_1(t), \psi_1(t) \rangle = \int_0^T \cos\left(\frac{3\pi t}{2T}\right) \cdot \sqrt{\frac{2}{T}} \cos\left(\frac{\pi t}{T}\right) dt$

$\int_0^T \cos\left(\frac{3\pi t}{2T}\right) \cdot \cos\left(\frac{\pi t}{T}\right) dt = \frac{\sqrt{2T}}{\pi} \frac{6}{5}$

$\int_0^T (\dots) dt = \frac{T \cdot 6}{5\pi}$

$= \frac{T \cdot 6}{5\pi}$

$\odot \cdot 1$

$= \sqrt{\frac{2}{T}} \cdot \frac{1}{2} \int_0^T \left(\cos\left(\frac{5\pi t}{2T}\right) + \cos\left(\frac{\pi t}{2T}\right) \right) dt$

$= \frac{1}{\sqrt{2T}} \left[\sin\left(\frac{5\pi t}{2T}\right) \cdot \frac{T}{5\pi} + \sin\left(\frac{\pi t}{2T}\right) \cdot \frac{T}{\pi} \right]_0^T$

$= \frac{1}{\sqrt{2T}} \left[\frac{2T}{\pi} \frac{6}{5} \right] = \frac{\sqrt{2T}}{\pi} \frac{6}{5} \quad \text{--- (1)}$

$$\therefore \phi_2(t) = \cos\left(\frac{3\pi t}{T}\right) - \frac{\sqrt{2T} \cdot b}{\pi \cdot 5} \cdot \sqrt{\frac{2}{T}} \cos\left(\frac{\pi t}{T}\right)$$

$$\bullet \frac{12}{5\pi} = k$$

$$\|\phi_2(t)\|^2 = \int_0^T \left(\underbrace{\cos^2\left(\frac{3\pi t}{T}\right)}_{(A)} + \underbrace{k^2 \cos^2\left(\frac{\pi t}{T}\right)}_{(B)} - \underbrace{2k \cos\left(\frac{3\pi t}{2T}\right) \cos\left(\frac{\pi t}{T}\right)}_{(C)} \right) dt$$

$$(A) = \int_0^T \cos^2\left(\frac{3\pi t}{T}\right) dt = \int_0^T \frac{1 + \cos\left(\frac{6\pi t}{T}\right)}{2} dt = \frac{T}{2}$$

$$(B) = \int_0^T k^2 \cos^2\left(\frac{\pi t}{T}\right) dt = k^2 \int_0^T \frac{1 + \cos\left(\frac{2\pi t}{T}\right)}{2} dt = k^2 \frac{T}{2}$$

$$(C) = \int_0^T 2k \cos\left(\frac{3\pi t}{2T}\right) \cdot \cos\left(\frac{\pi t}{T}\right) dt$$

$$= k \int_0^T \sin\left(\cos\left(\frac{5\pi t}{2T}\right) + \cos\left(\frac{\pi t}{2T}\right)\right) dt$$

$$= k \left[\sin\left(\frac{5\pi t}{2T}\right) \cdot \left(\frac{T}{5\pi}\right) + \sin\left(\frac{\pi t}{2T}\right) \cdot \left(\frac{T}{\pi}\right) \right]_0^T$$

$$= k \cdot \frac{2T}{\pi} \cdot \frac{b}{5} \quad \text{--- See (1)}$$

$$= \frac{12}{5\pi} \cdot k \cdot T = k^2 T$$

$$\therefore \|\phi_2(t)\|^2 = \frac{T}{2} + k^2 \frac{T}{2} - k^2 T = \frac{T}{2} - k^2 \left(\frac{T}{2}\right)$$

$$= \frac{T}{2} (1 - k^2)$$

$$\therefore \phi_2(t) = \frac{\cos\left(\frac{3\pi t}{2T}\right) - k \cos\left(\frac{\pi t}{T}\right)}{\sqrt{\frac{T}{2} (1 - k^2)}}$$

$$\therefore \psi_1(t) = \sqrt{\frac{2}{T}} \cos\left(\frac{\pi t}{T}\right)$$

$$\text{and } \psi_2(t) = \frac{\cos\left(\frac{3\pi t}{2}\right) - k \cos\left(\frac{\pi t}{T}\right)}{\left(\frac{T}{2}(1-k^2)\right)^{\frac{1}{2}}}$$

are the orthonormal bases

→ To find $s_0(t)$ and $s_1(t)$ in terms of $\psi_1(t)$ and $\psi_2(t)$ we find their projections on $\psi_1(t)$ and $\psi_2(t)$

$$\text{i.e. } \langle s_0(t), \psi_1(t) \rangle = \int_0^T \cos\left(\frac{\pi t}{T}\right) \cdot \sqrt{\frac{2}{T}} \cos\left(\frac{\pi t}{T}\right) dt$$

$$\int_0^T \cos\left(\frac{\pi t}{T}\right) \cdot \cos\left(\frac{\pi t}{T}\right) dt = \sqrt{\frac{T}{2}}$$

$$\int_0^T (1) dt = \frac{T}{2} \quad \text{from } (*)$$

$$= \sqrt{\frac{2}{T}} \cdot \frac{1}{2} \int_0^T (1 + \cos\left(\frac{2\pi t}{T}\right)) dt$$

$$= \sqrt{\frac{T}{2}} \quad \text{from } (2)$$

$$\langle s_0(t), \psi_2(t) \rangle = \int_0^T \cos\left(\frac{\pi t}{T}\right) \cdot \frac{\cos\left(\frac{3\pi t}{2}\right) - k \cos\left(\frac{\pi t}{T}\right)}{\left(\frac{T}{2}(1-k^2)\right)^{\frac{1}{2}}} dt$$

$$= \frac{1}{\left(\frac{T}{2}(1-k^2)\right)^{\frac{1}{2}}} \left(\frac{T \cdot k}{2} - k \cdot \frac{T}{2} \right) = 0$$

from (*)

Similarly, we find,

$$\therefore s_0(t) = \langle s_0(t), \psi_1(t) \rangle \psi_1(t)$$

$$+ \langle s_0(t), \psi_2(t) \rangle \psi_2(t)$$

$$s_0(t) = \sqrt{\frac{T}{2}} \psi_1(t) + 0 \cdot \psi_2(t)$$

Similarly, $\langle s_1(t), \psi_1(t) \rangle = \frac{\sqrt{2T}}{\pi} \cdot \frac{6}{5}$ from (1)

$$= \sqrt{2T} \cdot \frac{k}{2} = \sqrt{\frac{T}{2}} k$$

$$\langle s_1(t), \psi_2(t) \rangle = \int_0^T \cos\left(\frac{3\pi t}{2T}\right) \cdot \frac{\cos\left(\frac{3\pi t}{T}\right) - k \cos\left(\frac{\pi t}{T}\right)}{\left(\frac{T}{2}(1-k^2)\right)^{\frac{1}{2}}} dt$$

wkt, $\int_0^T \cos^2\left(\frac{3\pi t}{2T}\right) dt = \frac{T}{2}$ from (A)

also, $\int_0^T \cos\left(\frac{3\pi t}{2T}\right) \cdot \cos\left(\frac{\pi t}{T}\right) dt = \frac{T \cdot k}{2}$ from (B.1)

$$\therefore \langle s_1(t), \psi_2(t) \rangle = \frac{1}{\left(\frac{T}{2}(1-k^2)\right)^{\frac{1}{2}}} \cdot \left(\frac{T}{2} - \frac{T \cdot k}{2}\right)$$

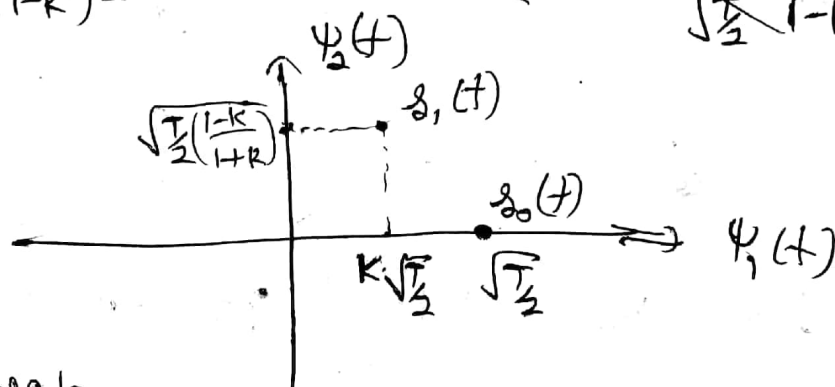
$$= \frac{\sqrt{\frac{T}{2}} (1-k)}{(1-k^2)^{\frac{1}{2}}} = \sqrt{\frac{T}{2}} \left(\frac{1-k}{1+k}\right)$$

$$\therefore s_1(t) = \sqrt{\frac{T}{2}} k \cdot \psi_1(t) + \sqrt{\frac{T}{2}} \left(\frac{1-k}{1+k}\right) \psi_2(t)$$

~~Alt. way~~

$$\psi_1(t) = \sqrt{\frac{T}{2}} \cos\left(\frac{\pi t}{T}\right) = \sqrt{\frac{T}{2}} s_0(t) \therefore s_0(t) = \sqrt{\frac{T}{2}} \psi_1(t)$$

$$\psi_2(t) = \frac{\cos\left(\frac{3\pi t}{2T}\right) - k \cos\left(\frac{\pi t}{T}\right)}{\sqrt{\frac{T}{2}(1-k^2)}} = \frac{s_1(t) - k \sqrt{\frac{T}{2}} \psi_1(t)}{\sqrt{\frac{T}{2}(1-k^2)}}$$



Signal space constellation

(3)

$$y_1 = \delta + n_1, \quad \delta \text{ can be } \delta_1 = \sqrt{E_3} \text{ or } -\sqrt{E_3}$$

$$n_1, n_2 \text{ iid } \sim N(0, \sigma^2)$$

$$y_1 = \sqrt{E_3} + n_1 \quad \text{wp } 0.5$$

$$= -\sqrt{E_3} + n_1 \quad \text{wp } 0.5$$

$$y_2 = 0 + n_1 + n_2$$

$$(a) \text{ Say, } \underline{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} \delta \\ 0 \end{bmatrix} + \begin{bmatrix} n_1 \\ n_1 + n_2 \end{bmatrix}$$

$$\text{Under } H_1: \underline{y} = \begin{bmatrix} \sqrt{E_3} \\ 0 \end{bmatrix} + \begin{bmatrix} n_1 \\ n_1 + n_2 \end{bmatrix}$$

$$\text{Under } H_0: \underline{y} = \begin{bmatrix} -\sqrt{E_3} \\ 0 \end{bmatrix} + \begin{bmatrix} n_1 \\ n_1 + n_2 \end{bmatrix}$$

Let C = Covariance matrix of $\begin{bmatrix} n_1 \\ n_1 + n_2 \end{bmatrix}$

$$C = \begin{bmatrix} E(n_1^2) & E(n_1(n_1+n_2)) \\ E((n_1+n_2)n_1) & E((n_1+n_2)^2) \end{bmatrix}$$

$$= \begin{bmatrix} \sigma^2 & \sigma^2 + 0 \\ \sigma^2 + 0 & \sigma^2 + \sigma^2 + 0 \end{bmatrix} = \sigma^2 \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$$

Since $\left. \begin{array}{l} E(n_1^2) = \text{Var}(n_1) = \sigma^2 \\ E(n_2^2) = \text{Var}(n_2) = \sigma^2 \\ E[n_1, n_2] = 0 \end{array} \right\} \begin{array}{l} \text{since } n_1, n_2 \\ \text{are zero mean} \\ \text{and independent} \end{array}$

$$\therefore f(\underline{y} | H_1) \sim N\left(\begin{bmatrix} \sqrt{E_3} \\ 0 \end{bmatrix}, C\right), \quad f(\underline{y} | H_0) \sim N\left(\begin{bmatrix} -\sqrt{E_3} \\ 0 \end{bmatrix}, C\right)$$

$$C^{-1} = \frac{1}{\sigma^2} \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\text{let } m_0 = \begin{bmatrix} \sqrt{E_3} \\ 0 \end{bmatrix} \text{ then } -m_0 = \begin{bmatrix} -\sqrt{E_3} \\ 0 \end{bmatrix}$$

$$\frac{1}{2\pi|\underline{C}|^{1/2}} e^{-\frac{1}{2}(\underline{\eta} - \underline{m}_0)^T \underline{C}^{-1} (\underline{\eta} - \underline{m}_0)} \stackrel{H_1}{\sim} \frac{1}{2\pi|\underline{C}|^{1/2}} e^{-\frac{1}{2}(\underline{\eta} + \underline{m}_0)^T \underline{C}^{-1} (\underline{\eta} + \underline{m}_0)} \stackrel{H_0}{\sim}$$

Taking log,

$$-(\underline{\eta} - \underline{m}_0)^T \underline{C}^{-1} (\underline{\eta} - \underline{m}_0) \stackrel{H_1}{\sim} -(\underline{\eta} + \underline{m}_0)^T \underline{C}^{-1} (\underline{\eta} + \underline{m}_0) \stackrel{H_0}{\sim}$$

$$\begin{pmatrix} -\underline{\eta}^T \underline{C}^{-1} \underline{\eta} + \underline{\eta}^T \underline{C}^{-1} \underline{m}_0 \\ + \underline{m}_0^T \underline{C}^{-1} \underline{\eta} - \underline{m}_0^T \underline{C}^{-1} \underline{m}_0 \end{pmatrix} \stackrel{H_1}{\sim} \begin{pmatrix} -\underline{\eta}^T \underline{C}^{-1} \underline{\eta} + \underline{\eta}^T \underline{C}^{-1} \underline{m}_0 \\ - \underline{m}_0^T \underline{C}^{-1} \underline{\eta} - \underline{m}_0^T \underline{C}^{-1} \underline{m}_0 \end{pmatrix} \stackrel{H_0}{\sim}$$

$$\cancel{\underline{\eta}^T \underline{C}^{-1} \underline{m}_0 + \underline{m}_0^T \underline{C}^{-1} \underline{\eta}} \stackrel{H_1}{\sim} \stackrel{H_0}{\sim} 0$$

$$\underline{\eta}^T \underline{C}^{-1} \underline{m}_0 = [\eta_1, \eta_2] \frac{1}{\sigma^2} \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{E_s} \\ 0 \end{bmatrix}$$

$$= \frac{1}{\sigma^2} [2\eta_1 - \eta_2 \quad -\eta_1 + \eta_2] \begin{bmatrix} \sqrt{E_s} \\ 0 \end{bmatrix}$$

$$= (2\eta_1 - \eta_2) \left(\frac{\sqrt{E_s}}{\sigma^2} \right)$$

$$\underline{m}_0^T \underline{C}^{-1} \underline{\eta} = [\sqrt{E_s} \quad 0] \frac{1}{\sigma^2} \begin{bmatrix} 2 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} \eta_1 \\ \eta_2 \end{bmatrix}$$

$$= \frac{1}{\sigma^2} [2\sqrt{E_s} \quad -\sqrt{E_s}] \begin{bmatrix} \eta_1 \\ \eta_2 \end{bmatrix} = \frac{\sqrt{E_s}}{\sigma^2} (2\eta_1 - \eta_2)$$

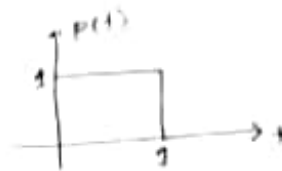
$$\therefore \frac{2\sqrt{E_s}}{\sigma^2} (2\eta_1 - \eta_2) \stackrel{H_1}{\sim} \stackrel{H_0}{\sim} 0, \quad 2\eta_1 - \eta_2 \stackrel{H_1}{\sim} \stackrel{H_0}{\sim} 0$$

$$\downarrow$$

$$g(\eta_1, \eta_2) \stackrel{H_1}{\sim} \stackrel{H_0}{\sim} 0$$

(b) The optimal rule depends on η_2 , since the optimal decision rule depends on η_2

$$2) p(t) = \mathbb{I}_{[0,1]}(t)$$

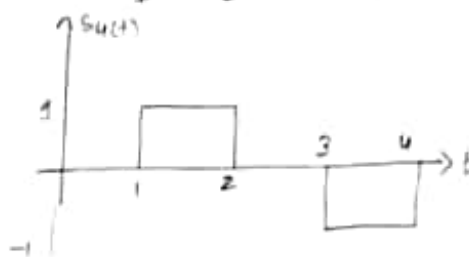
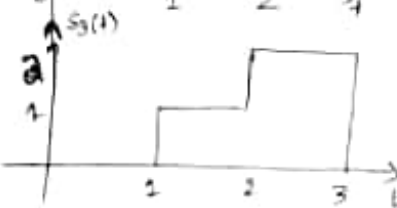
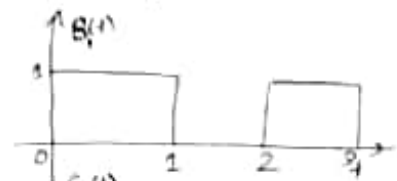


$$s_1(t) = p(t) + p(t-2)$$

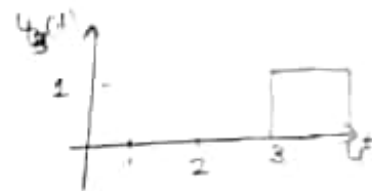
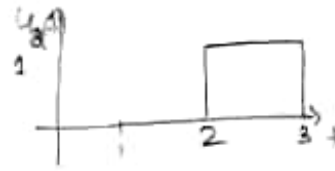
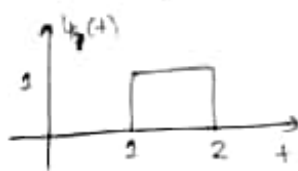
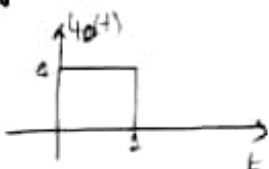
$$s_2(t) = p(t-1) + p(t-3)$$

$$s_3(t) = p(t-1) + 2p(t-2)$$

$$s_4(t) = p(t-1) - p(t-3)$$



a) By inspection, $\{u_0(t), u_1(t), u_2(t), u_3(t)\}$ forms the basis.



$$\text{Here, } u_i(t) = p(t-i)$$

$$\therefore s_1(t) = u_0(t) + u_2(t)$$

$$s_2(t) = u_1(t) + u_3(t)$$

$$s_3(t) = u_1(t) + 2u_2(t)$$

$$s_4(t) = u_1(t) - u_3(t)$$

\Rightarrow the vector representations in terms of $\{u_i(t)\}_{i=0,1,2,3}$

$$\underline{s}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \quad \underline{s}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \quad \underline{s}_3 = \begin{bmatrix} 0 \\ 1 \\ 2 \\ 0 \end{bmatrix}, \quad \underline{s}_4 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix}$$

b) Let $\{\phi_1(t), \phi_2(t), \phi_3(t), \phi_4(t)\}$ be the Basis for $\{s_i(t)\}$ using Gram-Schmidt procedure.

$$* \phi_1(t) = \frac{s_1(t)}{\|s_1(t)\|}$$

$$\|s_1(t)\|^2 = \int_0^1 1^2 dt + \int_2^3 1^2 dt = 2 \quad \Rightarrow \quad \boxed{\phi_1(t) = \frac{1}{\sqrt{2}} s_1(t)}$$

$$* \phi_2(t) = \frac{s_2(t) - \langle s_2(t), \phi_1(t) \rangle \phi_1(t)}{\|s_2(t) - \langle s_2(t), \phi_1(t) \rangle \phi_1(t)\|}$$

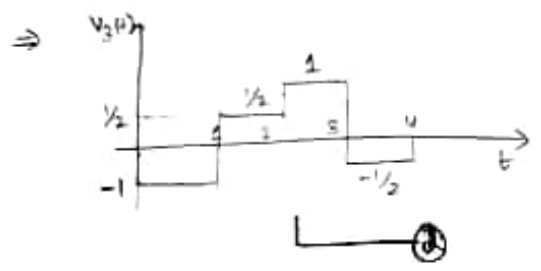
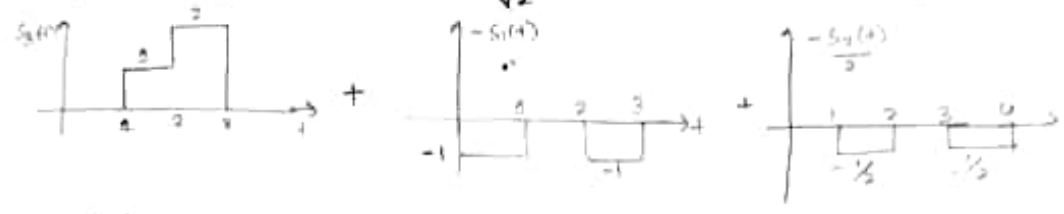
$$\langle s_2(t), \phi_1(t) \rangle = 0 \quad \& \quad \|s_2(t)\| = \|s_1(t)\| = \sqrt{2} \quad \Rightarrow \quad \boxed{\phi_2(t) = \frac{1}{\sqrt{2}} s_2(t)}$$

* $\phi_3(t) = \frac{v_3(t)}{\|v_3(t)\|}$ where $v_3(t) = s_3(t) - \langle s_3(t), \phi_1(t) \rangle \phi_1(t) - \langle s_3(t), \phi_2(t) \rangle \phi_2(t)$ (2)

$\langle s_3(t), \phi_1(t) \rangle = \frac{1}{\sqrt{2}} \langle s_3(t), s_1(t) \rangle = \frac{1}{\sqrt{2}} \left[\int_2^3 2 dt \right] = \sqrt{2}$

$\langle s_3(t), \phi_2(t) \rangle = \frac{1}{\sqrt{2}} \langle s_3(t), s_2(t) \rangle = \frac{1}{\sqrt{2}}$

$v_3(t) = s_3(t) - \sqrt{2} \phi_1(t) - \frac{1}{\sqrt{2}} \phi_2(t) = s_3(t) - s_1(t) - \frac{1}{2} s_2(t)$ (1)



$\Rightarrow \|v_3(t)\|^2 = (-1)^2 + (1/2)^2 + 1^2 + (1/2)^2 = 2 + 1/2 = 5/2$

$\Rightarrow \phi_3(t) = \sqrt{\frac{2}{5}} v_3(t)$ where $v_3(t)$ is shown in fig (2). (3)

* $\phi_4(t) = \frac{v_4(t)}{\|v_4(t)\|}$ where $v_4(t) = s_4(t) - \langle s_4(t), \phi_1(t) \rangle \phi_1(t) - \langle s_4(t), \phi_2(t) \rangle \phi_2(t) - \langle s_4(t), \phi_3(t) \rangle \phi_3(t)$

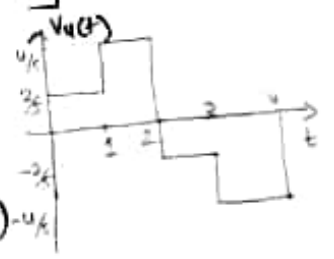
Here $\langle s_4(t), \phi_1(t) \rangle = 0$

$\langle s_4(t), \phi_2(t) \rangle = 0$

$\langle s_4(t), \phi_3(t) \rangle = \sqrt{\frac{2}{5}} \langle s_4(t), v_3(t) \rangle = \sqrt{\frac{2}{5}} \left[\int_1^2 1/2 dt + \int_3^4 1/2 dt \right] = \sqrt{2/5}$

$\therefore \phi_4(t) = \frac{v_4(t)}{\|v_4(t)\|} = \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} s_4(t) = \frac{1}{2} s_4(t)$

$v_4(t) = s_4(t) - \sqrt{\frac{2}{5}} \phi_3(t) = s_4(t) - \frac{2 \cdot v_3(t)}{5}$



$\|v_4(t)\| = \sqrt{8/5}$
 $\phi_4(t) = v_4(t) / \|v_4(t)\|$ (4)

Vector representation

$s_1(t) = \sqrt{2} \phi_1(t)$

$s_2(t) = \sqrt{2} \phi_2(t)$

$s_3(t) = v_3(t) + \sqrt{2} \phi_1(t) + \frac{1}{\sqrt{2}} \phi_2(t)$ (eqn 1)

$= \sqrt{\frac{5}{2}} \phi_3(t) + \sqrt{2} \phi_1(t) + \frac{1}{\sqrt{2}} \phi_2(t)$ (eqn 3)

$s_4(t) = \sqrt{2} \phi_4(t) + \sqrt{\frac{2}{5}} \phi_3(t)$ (eqn 4)

$= \sqrt{8/5} \phi_4(t) + \sqrt{2/5} \phi_3(t)$

$\Rightarrow \bar{s}_1 = \begin{bmatrix} \sqrt{2} \\ 0 \\ 0 \\ 0 \end{bmatrix}, \bar{s}_2 = \begin{bmatrix} 0 \\ \sqrt{2} \\ 0 \\ 0 \end{bmatrix}$
 $\bar{s}_3 = \begin{bmatrix} \sqrt{2} \\ 1/\sqrt{2} \\ \sqrt{5/2} \\ 0 \end{bmatrix}, \bar{s}_4 = \begin{bmatrix} 0 \\ 0 \\ \sqrt{2/5} \\ \sqrt{8/5} \end{bmatrix}$ (5)

c). From part (a)

$$\|s_1\|^2 = 2, \|s_2\|^2 = 2, \|s_3\|^2 = 5, \|s_4\|^2 = 2$$

Also from (4),

$$\|\bar{s}_1\|^2 = 2, \|\bar{s}_2\|^2 = 2, \|\bar{s}_3\|^2 = 5, \|\bar{s}_4\|^2 = 2$$

ie, since in energies in both representations $\|s_i\|^2$ & $\|\bar{s}_i\|^2$ are equal

• Relative distance for $\{s_i\}$.

$$\|s_1 - s_2\|^2 = \|(1 \ -1 \ 1 \ -1)^T\|^2 = 4$$

$$\|s_1 - s_3\|^2 = \|(1 \ -1 \ -1 \ 0)^T\|^2 = 3$$

$$\|s_1 - s_4\|^2 = 4.$$

$$\|s_2 - s_3\|^2 = 5$$

$$\|s_2 - s_4\|^2 = 4$$

$$\|s_3 - s_4\|^2 = 5$$

Relative distance for $\{\bar{s}_i\}$

$$\|\bar{s}_1 - \bar{s}_2\|^2 = 4.$$

$$\|\bar{s}_1 - \bar{s}_3\|^2 = 3$$

$$\|\bar{s}_1 - \bar{s}_4\|^2 = 4.$$

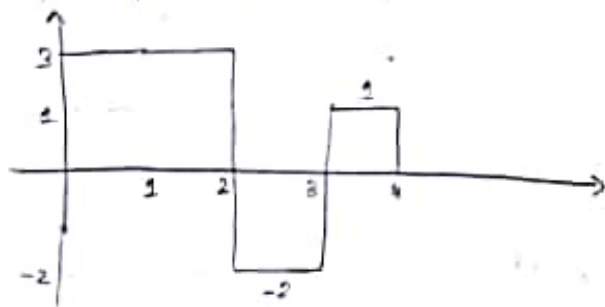
$$\|\bar{s}_3 - \bar{s}_4\|^2 = \left\| \left[\sqrt{2}, \frac{1}{\sqrt{2}}, \frac{\sqrt{2}}{2}, 0 \right]^T \right\|^2 = 5$$

$$\|\bar{s}_2 - \bar{s}_4\|^2 = 4.$$

$$\|\bar{s}_3 - \bar{s}_4\|^2 = \left\| \left[\sqrt{2}, \frac{1}{\sqrt{2}}, \sqrt{\frac{3}{2}} - \sqrt{\frac{2}{5}}, \sqrt{\frac{2}{5}} \right]^T \right\|^2 = 2 + \frac{1}{2} + \frac{9}{10} + \frac{8}{5} = 5 //$$

Relative distances for $\{s_i\}$ & $\{\bar{s}_i\}$ are same.

d) $s(t) = 3p(t) + 3p(t-1) - 2p(t-2) + p(t-3)$



$$\langle s(t), \phi_1(t) \rangle = \frac{1}{\sqrt{2}} \langle s(t), s_1(t) \rangle = \frac{1}{\sqrt{2}} \left[3 \int_0^2 dt + -2 \int_2^3 dt \right] = \frac{1}{\sqrt{2}}$$

$$\langle s(t), \phi_2(t) \rangle = \frac{1}{\sqrt{2}} \langle s(t), s_2(t) \rangle = \frac{1}{\sqrt{2}} \left[2 \int_1^2 dt + \int_3^4 dt \right] = 2\sqrt{2}$$

$$\langle s(t), \phi_3(t) \rangle = \sqrt{\frac{2}{5}} \langle s_3(t), v_3(t) \rangle = \sqrt{\frac{2}{5}} \left[-3 \int_0^1 dt + \frac{9}{2} \int_1^2 dt + -2 \int_2^3 dt + -\frac{1}{2} \int_3^4 dt \right] = \sqrt{\frac{2}{5}} [-4] = -4\sqrt{\frac{2}{5}}$$

$$\langle s(t), \phi_4(t) \rangle = \sqrt{\frac{8}{5}} \langle s(t), v_4(t) \rangle = \sqrt{\frac{8}{5}} \left[\frac{6}{5} + \frac{12}{5} + \frac{4}{5} - \frac{4}{5} \right] = \frac{18}{5} \sqrt{\frac{8}{5}}$$

$$\Rightarrow s(t) = \frac{1}{\sqrt{2}} \phi_1(t) + 2\sqrt{2} \phi_2(t) - 4\sqrt{\frac{2}{5}} \phi_3(t) + \frac{18}{5} \sqrt{\frac{8}{5}} \phi_4(t)$$

$$\therefore \bar{s} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 2\sqrt{2} \\ -4\sqrt{\frac{2}{5}} \\ \frac{18}{5}\sqrt{\frac{8}{5}} \end{bmatrix}$$