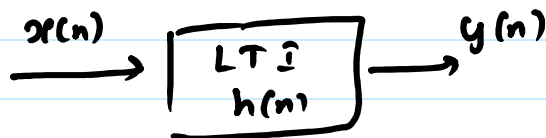


# Frequency Domain Analysis of LTI Systems

$h(n)$  impulse response

$H(e^{j\omega})$  Frequency response



$$y(n) = x(n) * h(n)$$

$$Y(e^{j\omega}) = X(e^{j\omega}) H(e^{j\omega})$$

Two components

- 1) Magnitude Response  $|H(e^{j\omega})|$
- 2) Phase Response  $\angle H(e^{j\omega})$

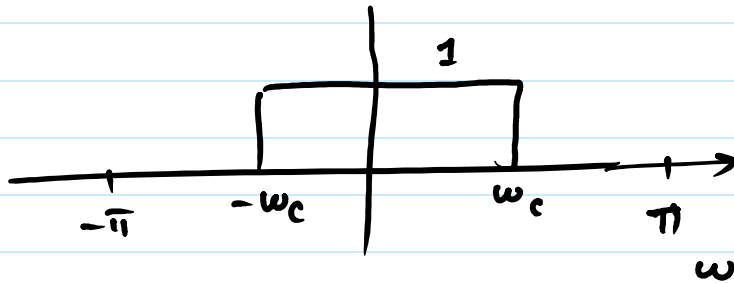
Will address:

(a) What is the effect of  
a given response  $H(e^{j\omega})$   
on the input?

(b) How to design practical  
systems with desired response?

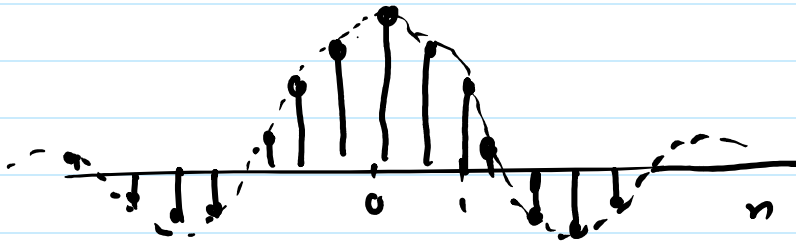
Consider ideal low pass filter

$$H(e^{j\omega}) = \begin{cases} 1; & |\omega| \leq \omega_c \\ 0; & \omega_c < |\omega| \leq \pi \end{cases}$$



impulse response of ideal LPF

$$h(n) = \frac{\sin(\omega_c n)}{\pi n}$$



$h(n)$  is IIR system  
(infinite duration impulse response)

$h(n)$  is not causal

⇒ Not realizable in practice

Let us focus on practical systems

Specifically, systems described by

LCCDE

$$y(n) = - \underbrace{\sum_{k=1}^N a_k y(n-k)}_{\text{feedback terms}} + \underbrace{\sum_{k=0}^M b_k x(n-k)}_{\text{input terms}}$$

Taking z-transforms

$$Y(z) = - \sum_{k=1}^N a_k z^{-k} Y(z) + \sum_{k=0}^M b_k z^{-k} X(z)$$

Transfer function

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^M b_k z^{-k}}{1 + \sum_{k=1}^N a_k z^{-k}} \quad (\text{rational})$$

We can write

$$H(z) = \frac{b_0 \prod_{k=1}^M (1 - q_k z^{-1})}{\prod_{k=1}^N (1 - p_k z^{-1})}$$

$$\prod_{k=1}^N (1 - p_k z^{-1})$$

$$H(z) = b_0 z^{N-M} \frac{\prod_{k=1}^M (z - q_k)}{\prod_{k=1}^N (z - p_k)}$$

$q_1, q_2, \dots, q_M$  are zeros

$p_1, p_2, \dots, p_N$  are poles

$z^{N-M} \Rightarrow$  trivial pole or zero  
at  $z=0$

(depending on  
Sign of  $N-M$ )

We restrict our attention to  
Causal & Stable systems  
1.

$\Rightarrow$  All poles  $p_1, p_2, \dots, p_N$

should be inside unit  
circle

$\Rightarrow$  ROC of  ~~$z$~~  transfer function  $H(z)$

should lie outside the  
largest pole

$\rightarrow$

( & thereby contain  
the unit circle)

Since ROC includes unit circle,

$$H(e^{j\omega}) = H(z) \Big|_{z=e^{j\omega}}$$

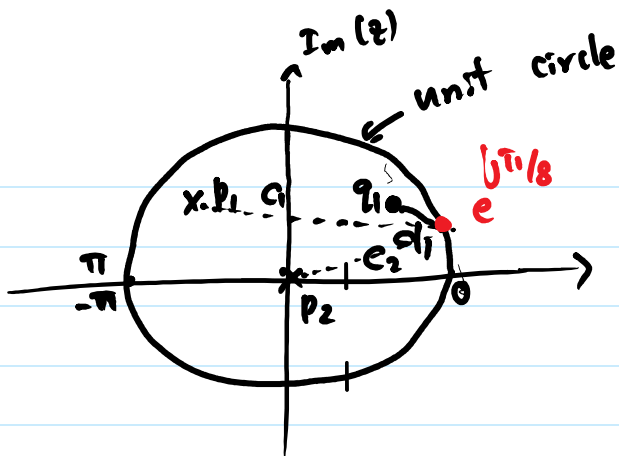
$$= b_0 e^{j\omega(N-M)} \frac{\prod_{k=1}^M (e^{j\omega} - q_k)}{\prod_{k=1}^N (e^{j\omega} - p_k)}$$

Magnitude response

$$|H(e^{j\omega})| = |b_0| \underbrace{|e^{j\omega(N-M)}|}_{=1} \frac{\prod_{k=1}^M |e^{j\omega} - q_k|}{\prod_{k=1}^N |e^{j\omega} - p_k|}$$

$$|H(e^{j\omega})| = |b_0| \frac{\prod_{k=1}^M |e^{j\omega} - q_k|}{\prod_{k=1}^N |e^{j\omega} - p_k|}$$

$$-\pi \leq \omega \leq \pi$$



$$|H(e^{j\pi/8})| = \frac{d_1 |b_0|}{c_1}$$

note  $c_2 = 1$

Say  $\omega = \pi/8$

$$|H(e^{j\pi/8})| = |b_0| \frac{\prod_{k=1}^M |e^{j\pi/8} - z_k|}{\prod_{k=1}^N |e^{j\pi/8} - p_k|}$$

Geometrically,  $|e^{j\omega} - z_k|$  is

distance between the

point  $e^{j\omega}$  on unit circle

with the zero  $z_k$

Numerator is the product of

distances between  $e^{j\omega}$  and

the zeros  $z_1, z_2, \dots, z_M$

Denominator is product of

distances between  $e^{j\omega}$  and

poles  $p_1, \dots, p_N$



Remarks

- Pole or zero at origin does not affect the magnitude response

$$|e^{j\omega} - 0| = 1$$

- Suppose there is zero  $z_k$  on unit circle ;

$$z_k = e^{j\omega_0}$$

for some  $\omega_0$

$$\text{then } H(e^{j\omega_0}) = 0$$

- In general, values of  $\omega \in (-\pi, \pi)$  for which  $e^{j\omega}$  is close to a zero of transfer function

$|H(e^{j\omega})|$  will be small

- ~~It~~ On the other hand,  $e^{j\omega}$  close to a pole will have large gain.

- It is convenient to plot the magnitude response on log scale (dB)

$$\text{Gain in dB} = 20 \log |H(e^{j\omega})|$$

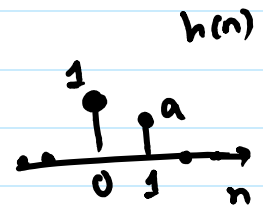
$$= 20 \log |b| + \sum_{k=1}^M 20 \log |e^{j\omega} - q_k| - \sum_{k=1}^N 20 \log |e^{j\omega} - p_k|$$

(  $q_k$  are zeros  
  $p_k$  are poles )

First order system: Single complex zero

$$H(z) = 1 - az^{-1}$$

$$a = re^{j\theta}$$



$r \rightarrow$  mag. of zero

$\theta \rightarrow$  angle of zero

(FIR)

$$Y(z) = H(z) X(z)$$

$$= (1 - az^{-1}) X(z) ;$$

$$y(n) = x(n) - ax(n-1)$$

$$h(n) = \delta(n) - a\delta(n-1)$$

$$\begin{aligned}
 H(e^{j\omega}) &= 1 - a e^{-j\omega} \\
 &= 1 - r e^{j\theta - j\omega} e^{-j\omega}
 \end{aligned}$$

Consider

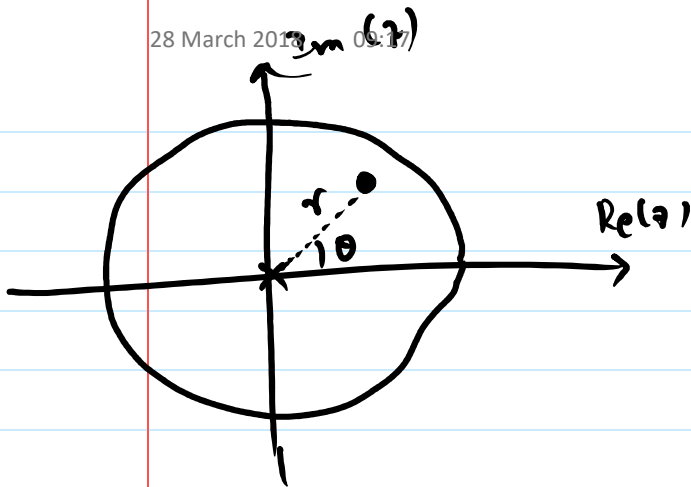
$$\begin{aligned}
 |H(e^{j\omega})|^2 &= H(e^{j\omega}) \cdot H^*(e^{j\omega}) \\
 &= (1 - r e^{j\theta - j\omega}) (1 - r e^{-j\theta + j\omega}) \\
 &= 1 + r^2 - 2r \cos(\omega - \theta)
 \end{aligned}$$

$$20 \log |H(e^{j\omega})|$$

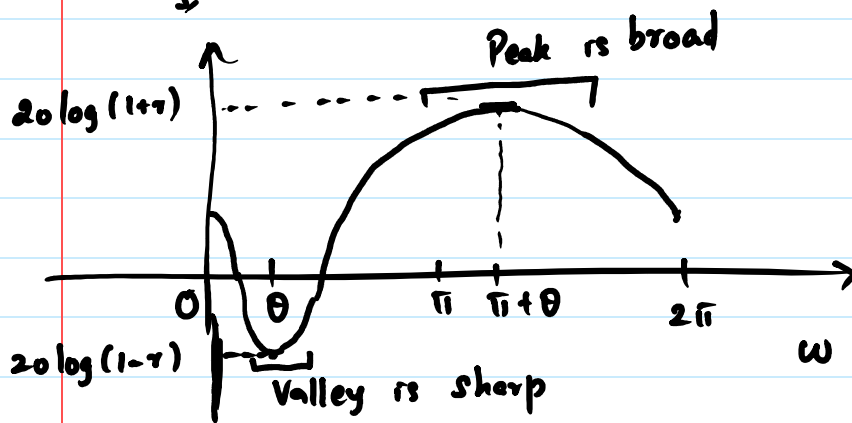
$$= 10 \log (1 + r^2 - 2r \cos(\omega - \theta))$$

$$\begin{aligned}
 \text{Min of } |H(e^{j\omega})| \text{ occurs at } \omega = \theta \\
 |H_{\min}|^2 &= 1 + r^2 - 2r \\
 &= (1 - r)^2
 \end{aligned}$$

$$\begin{aligned}
 \text{Max of } |H(e^{j\omega})| \text{ occurs at } \omega = \theta + \pi \\
 |H_{\max}|^2 &= 1 + r^2 + 2r \\
 &= (1 + r)^2
 \end{aligned}$$



$$20 \log |H(e^{j\omega})| = 10 \log (1 + r^2 - 2r \cos(\omega - \theta))$$



r \_\_\_\_\_ x

### Single Complex Pole

$$H(z) = \frac{1}{1 - az^{-1}}$$

causal, stable

$$|a| < 1$$

$$h(n) = a^n u(n)$$

$$Y(z)(1 - az^{-1}) = X(z)$$

$$y(n) = x(n) + \underbrace{ay(n-1)}_{\text{feedback}}$$



IIR System  
causal } implementable

$$a = r e^{j\theta}$$

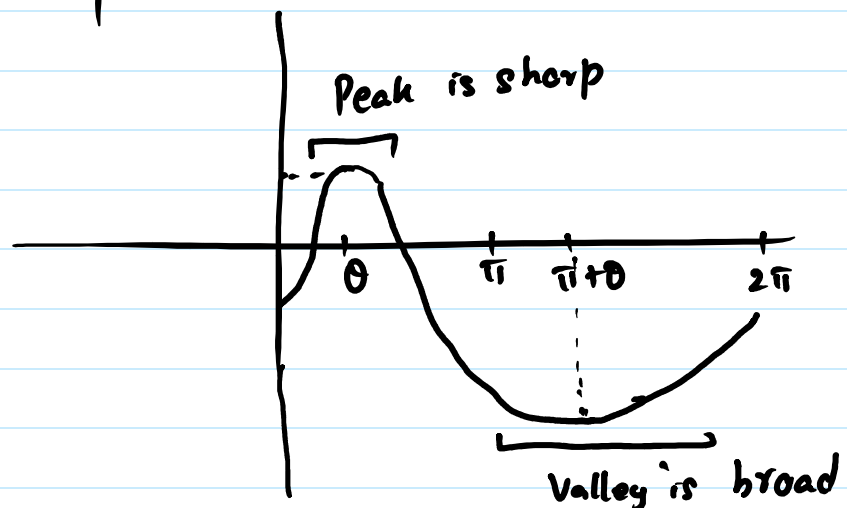
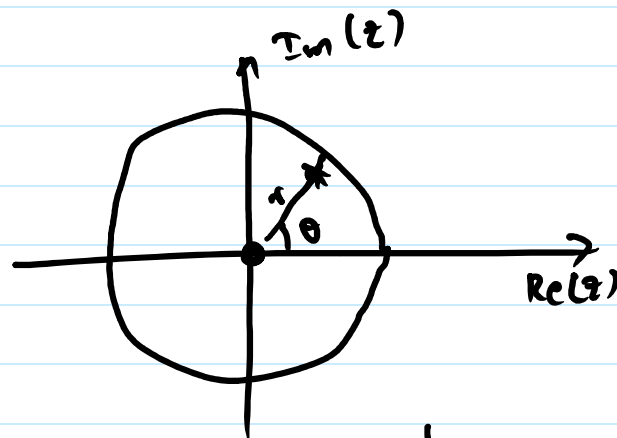
$$H(e^{j\omega}) = \frac{1}{1 - r e^{j\theta} e^{-j\omega}}$$

$$20 \log |H(e^{j\omega})| = -20 \log |1 - r e^{j\theta} e^{-j\omega}|$$

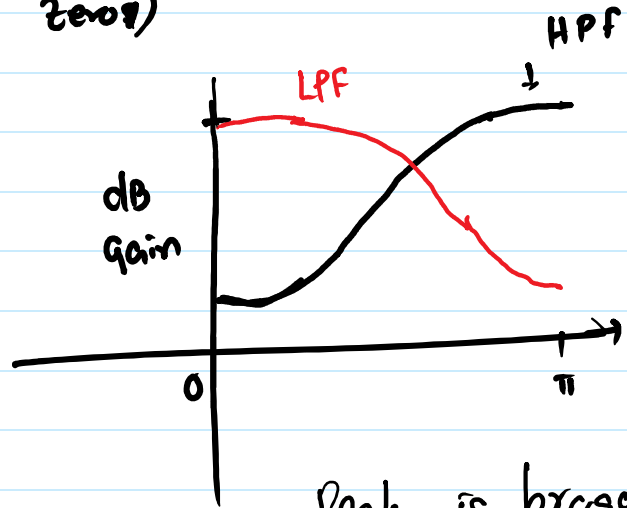
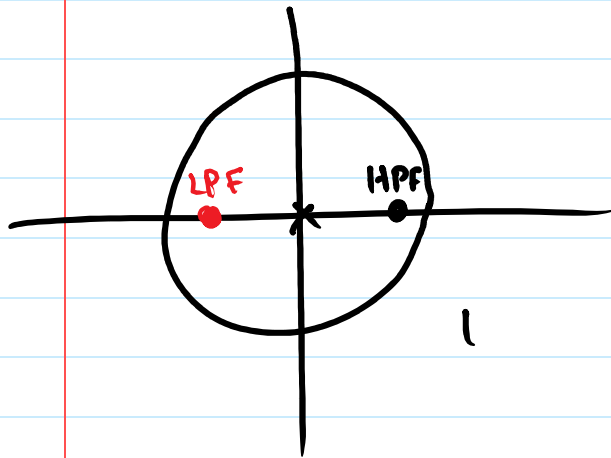
$$= -10 \log (1 + r^2 - 2r \cos(\omega - \theta))$$

↓  
Same as the single zero

except for negative sign

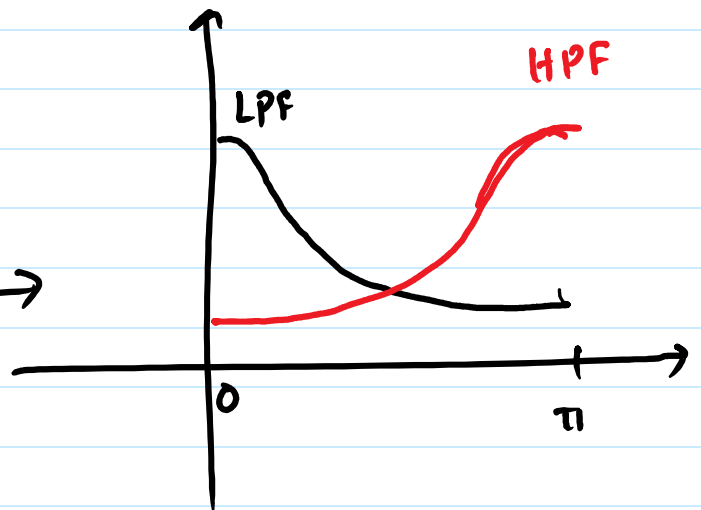
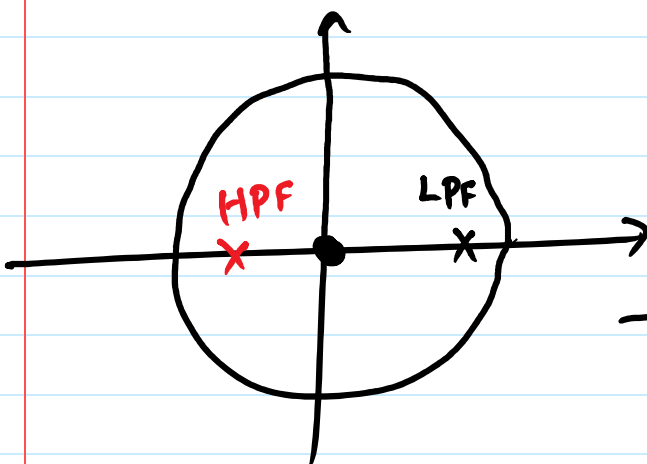


# Low Pass & High Pass filters (using zeros)



Peak is broad  
Valley is sharp

# LPF & HPF using pole

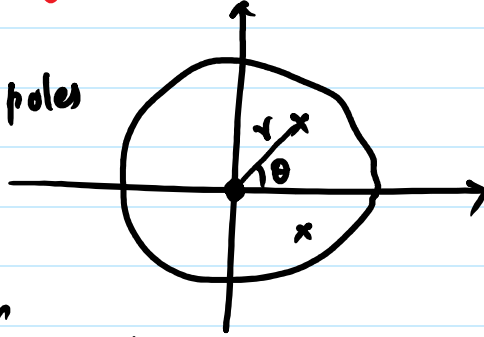


Valley is broad  
Peak is sharp

## Second Order System

Two conjugate poles

$$re^{j\theta}, re^{-j\theta}$$



This system is called a RESONATOR

$$H(z) = \frac{1}{(1 - az^{-1})(1 - a^*z^{-1})}$$

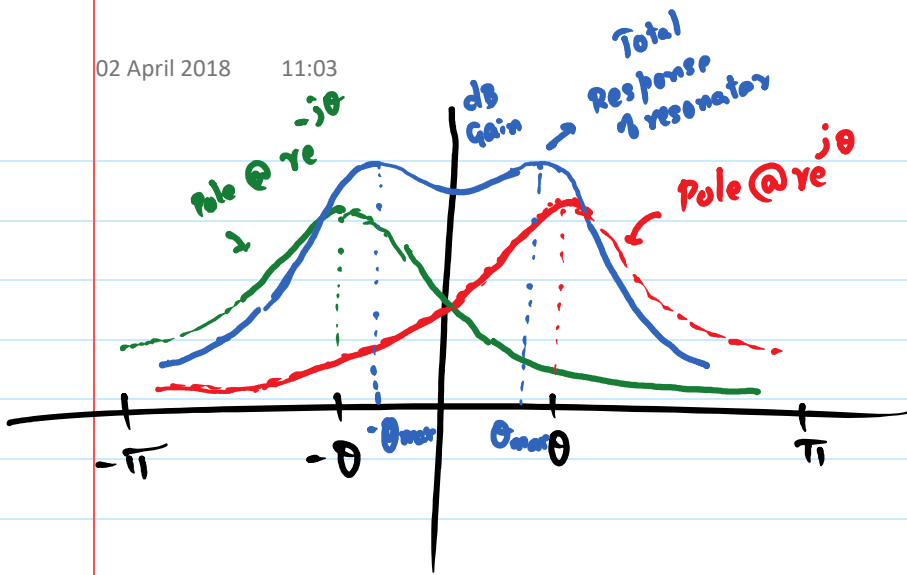
where  $a = re^{j\theta}$

Can show that

$$h(n) = \frac{r^n \sin((n+1)\theta)}{\sin \theta} u(n)$$

$$|H(e^{j\omega})| = \frac{1}{|1 - ae^{-j\omega}|} \cdot \frac{1}{|1 - a^*e^{-j\omega}|}$$

$$\begin{aligned} 20 \log |H(e^{j\omega})| &= \underbrace{-20 \log |1 - re^{j\theta} e^{-j\omega}|}_{\substack{\downarrow \\ \text{pole @ } re^{j\theta}}} \\ &\quad - \underbrace{20 \log |1 - re^{-j\theta} e^{-j\omega}|}_{\substack{\downarrow \\ \text{pole @ } re^{-j\theta}}} \end{aligned}$$



We can show that

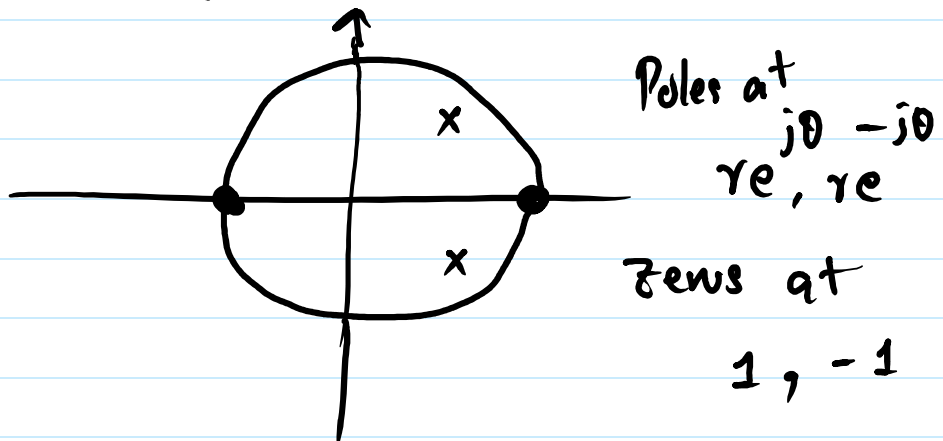
$$\theta_{max} = \cos^{-1} \left( \frac{1+r^2}{2r} \cos \theta \right)$$

As  $r \rightarrow 1$ , we have

$$\theta_{max} \rightarrow \theta$$

If  $\theta = \pi/2$  then  $\theta_{max} = \pi/2$   
for any  $r$

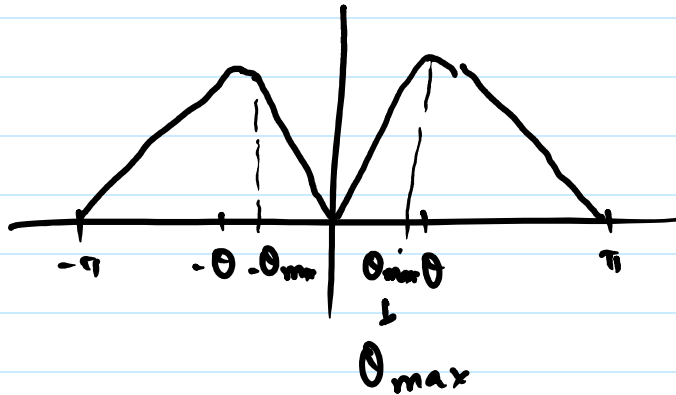
Band Pass filter using resonator





$$H(z) = \frac{(1 - z^{-1})(1 + z^{-1})}{(1 - az^{-1})(1 - a^*z^{-1})}$$

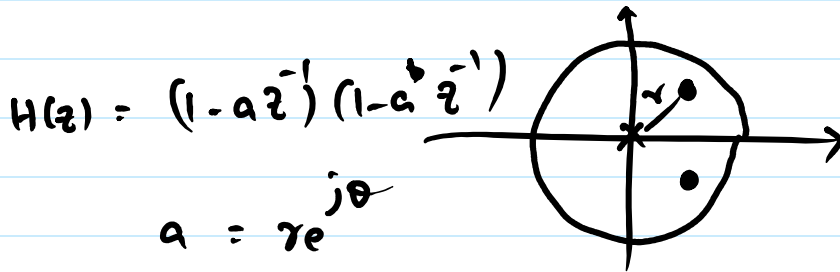
$$a = re^{j\theta}$$



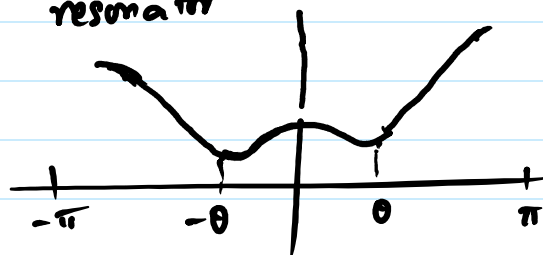
$$\theta_{max} = \cos^{-1} \left( \frac{2r \cos \theta}{1+r^2} \right)$$

Notch filter (Second order)

zeros at  $re^{j\theta}$ ,  $re^{-j\theta}$



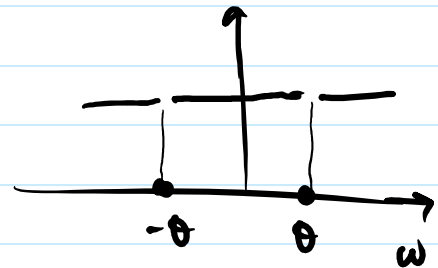
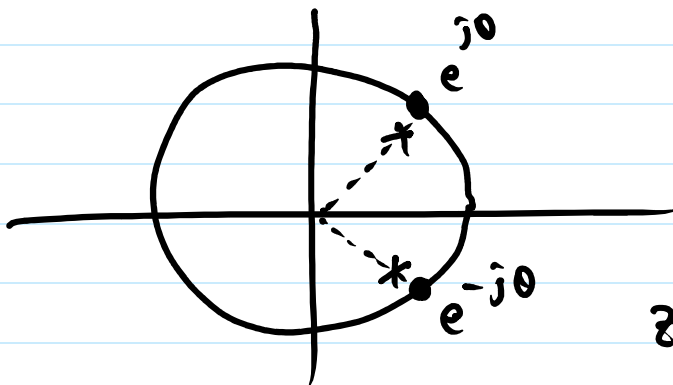
Magnitude response (dB) is negative w.r. resonator



## Improved notch filter

Ideal Notch filter

$$|H(e^{j\omega})| = \begin{cases} 0 & \text{if } \omega = \pm\theta \\ 1 & \text{if } |\omega| \neq \theta \end{cases}$$

Zeros at  $e^{j\theta}, e^{-j\theta}$ Poles at  $re^{j\theta}, re^{-j\theta}$ 

$$H(z) = \frac{1 - 2\cos\theta z^{-1} + z^{-2}}{1 - 2r\cos\theta z^{-1} + r^2 z^{-2}}$$

# Moving Average Filter (FIR)

$$h(n) = \begin{cases} 1/N, & 0 \leq n \leq N-1 \\ 0, & \text{else} \end{cases}$$

$$H(z) = \frac{1}{N} (1 + z^{-1} + \dots + z^{-(N-1)})$$

$$= \frac{1}{N} \frac{1 - z^{-N}}{1 - z^{-1}}$$

No. of zeros is governed by  $N$

$N=7$

