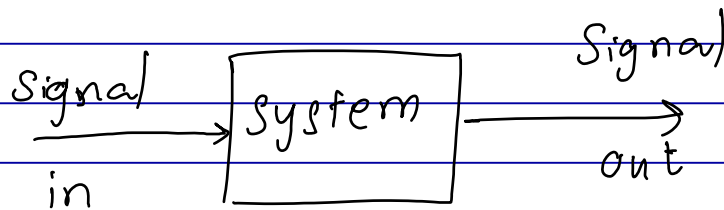


Abstract Model:



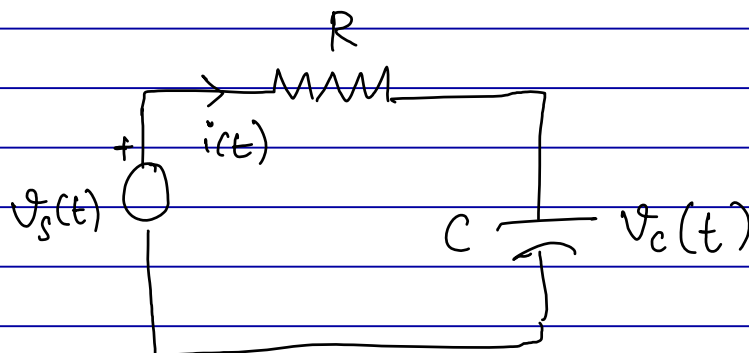
Signal: information bearing quantity

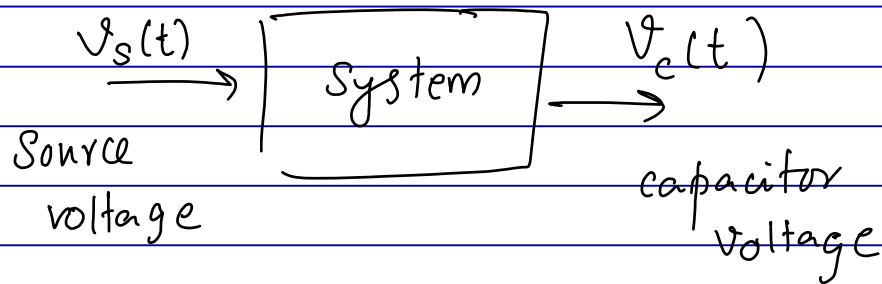
eg: ECG, Traffic signal, signals from cell phone

System: Does some operation/processing on signals (input) and produces another signal (output)

Examples:

① Electrical System

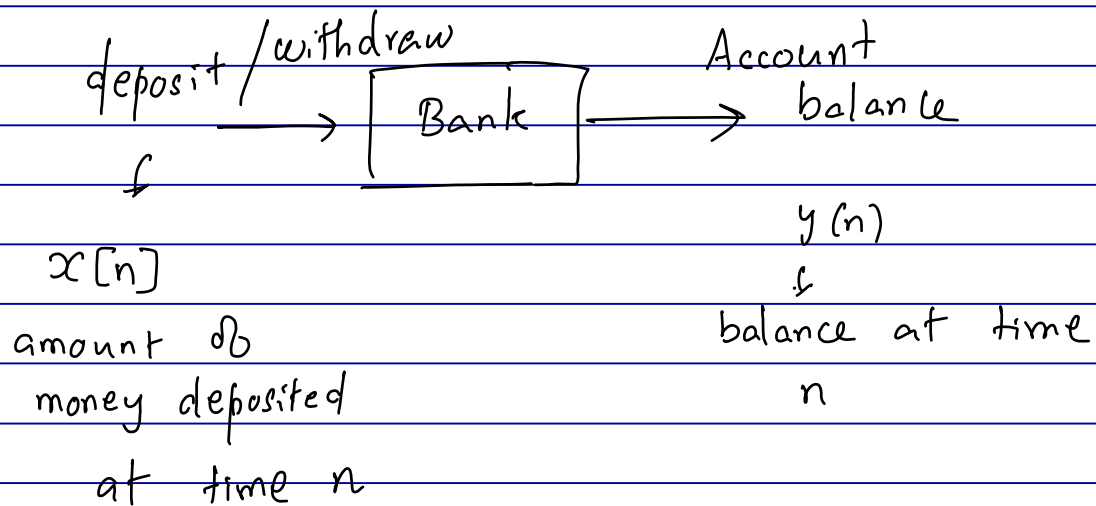




$t \rightarrow$ time variable

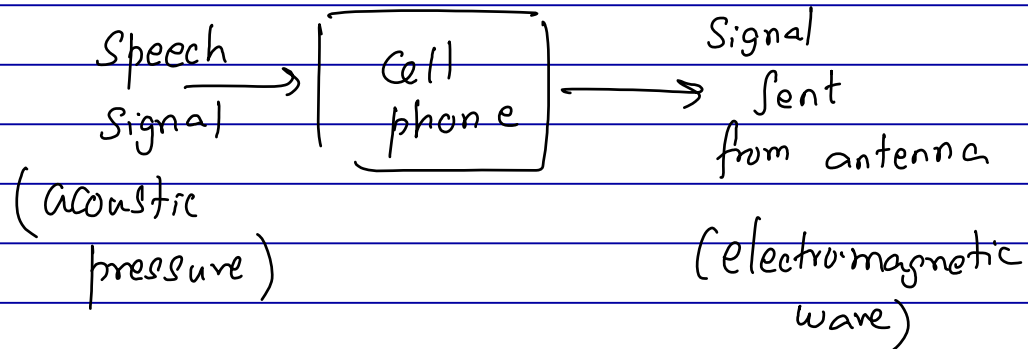
EMC course tells you how to analyse this electrical system

② Financial system



Here time n takes only discrete values

③ Communication System



Main Theme

- As long as systems (which may look different) satisfy some mathematical properties, they can be studied under a common mathematical framework
- This course develops powerful mathematical tools to study a class of systems (linear and time-invariant)

Signals / Systems

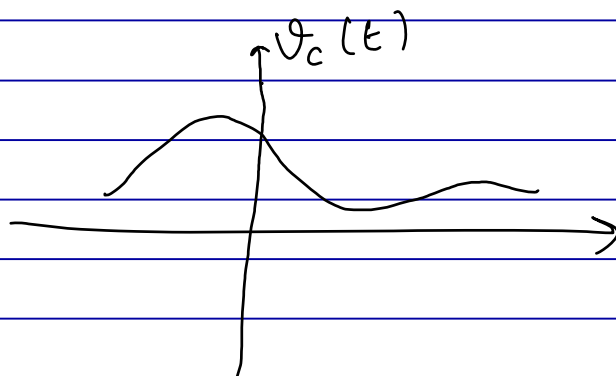
- ① Continuous-time (CT) Signals / Systems
- ② Discrete-time (DT) Signals / Systems

CT Signal

A signal specified for continuum of values of time t is CT signal

Examples: Many physical signals are CT signals

for instance $V_c(t) \rightarrow$ voltage across a capacitor



Independent Variable t

t takes continuum of values

In some situations, t may denote space, height, distance etc (not necessarily time)

A system which operates on
CT signals is a continuous-time system

x $\xrightarrow{\hspace{2cm}}$ x

A Discrete-time (DT) signal is
specified only for discrete values
of time

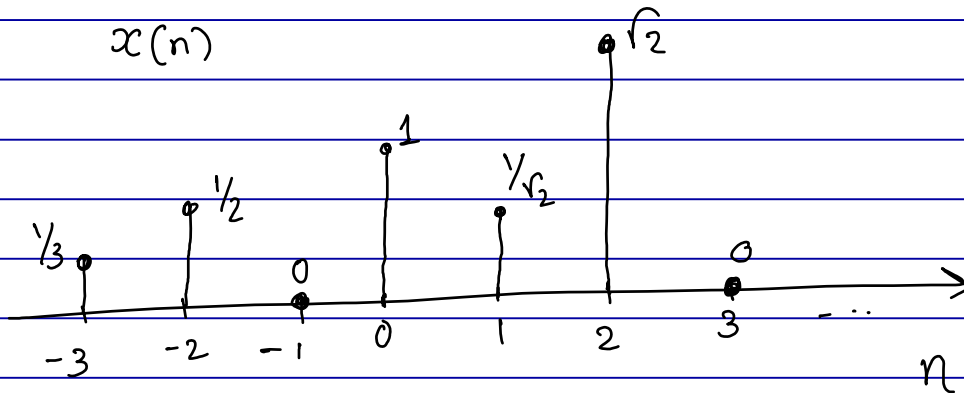
Examples: real world signals
(bank account balance
at end of each day)

- In this course, we consider the
discrete values of time to be integers.

Let $x[n]$ be a discrete-time signal

$x[n]$ is defined only for $n \in \mathbb{Z}$
Set of integers

If $n \notin \mathbb{Z}$, $x[n]$ is undefined



$n \rightarrow$ discrete-time index

(takes only integer values)

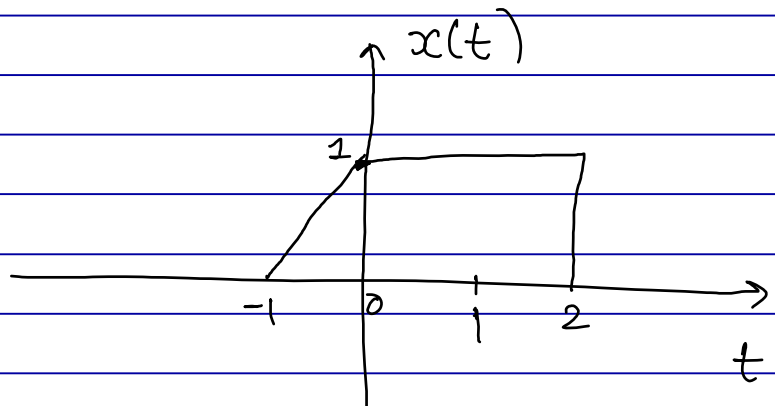
A DT system takes DT signal as input and produces DT signal as output.

$x \xrightarrow{\hspace{10em}}$

Basic Signal Transformations (on independent time variable)

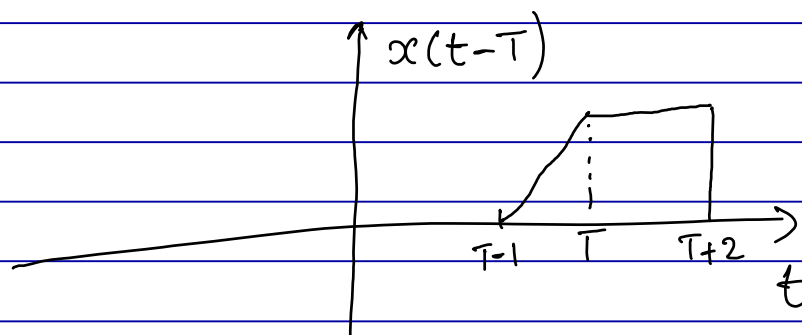
- 1* Translation or time shifting
- 2* Time scaling
- 3* Time scaling and time shifting

Time shifting:

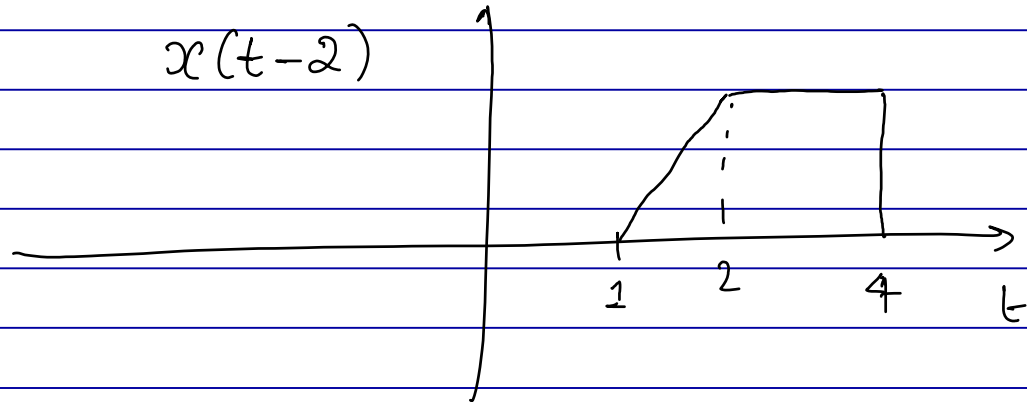


A signal $x(t)$ is time shifted by T seconds by replacing t with $t - T$.

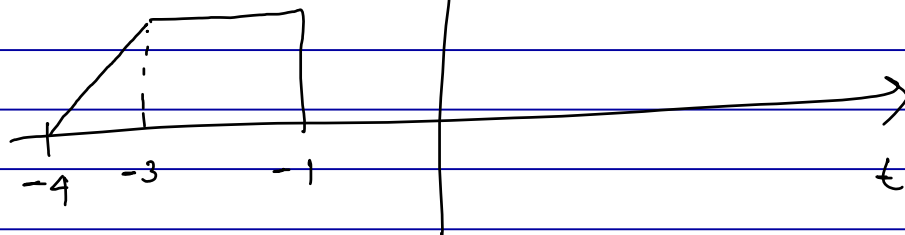
$x(t - T)$ is time shifted version of $x(t)$, shifted by T seconds



Case (i) $T = 2$



Case (ii) $T = -3$ $x(t - (-3)) = x(t+3)$



for $T > 0$; $x(t-T)$ is ^{time} delayed version of $x(t)$

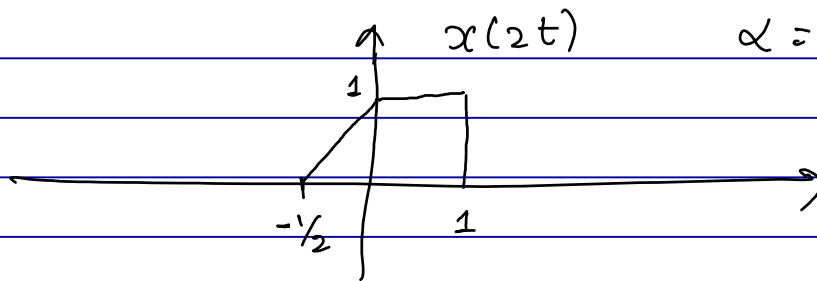
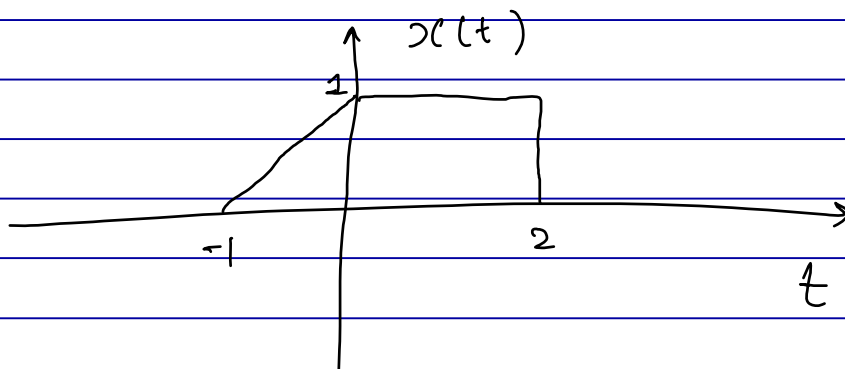
For $T < 0$; $x(t-T)$ is time advanced/ version of $x(t)$

* Time scaling

Multiply the independent time variable t by a real constant α

$$y(t) = x(\alpha t)$$

time scaling leads to expansion or compression in time

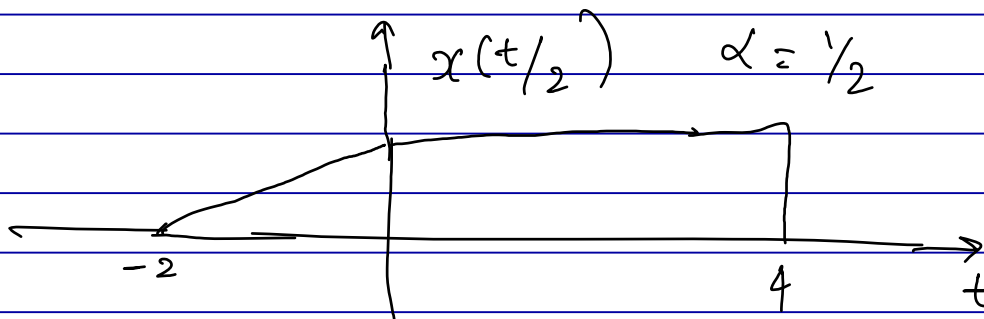


$$\alpha = 2$$

$$\alpha > 1$$

then
it leads
to

compression



$$\alpha = 1/2$$

in time

5/8

Note Title

Transformations on

05-08-2015

independent Variable.

→ Time Scaling

$x(\alpha t)$ is time scaled version
of signal $x(t)$

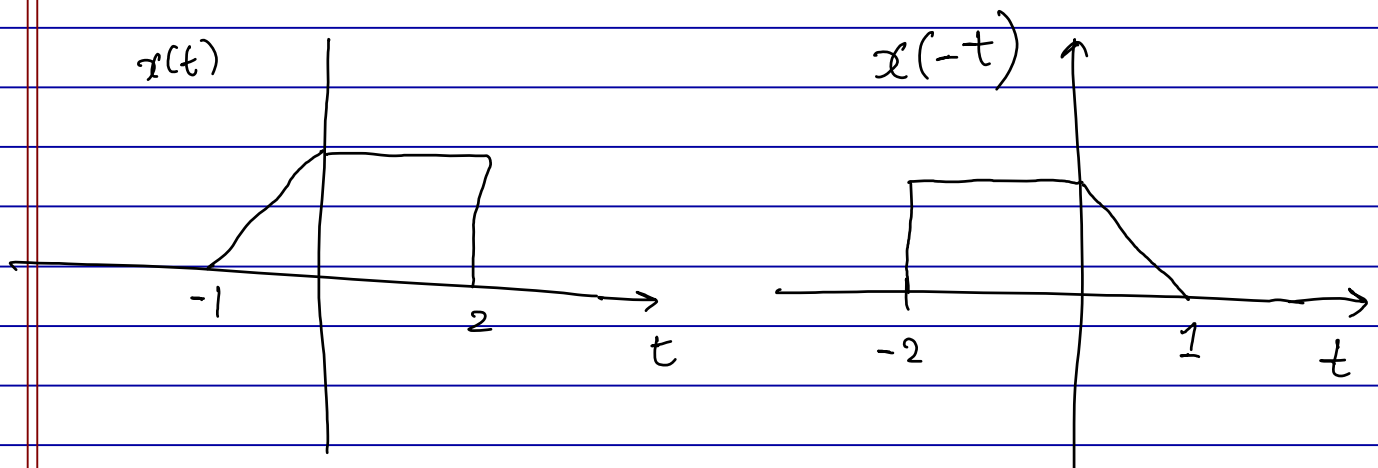
α is a real constant

$\alpha > 1 \rightarrow$ Compression

$0 < \alpha < 1 \rightarrow$ Expansion

What about negative values of α ?

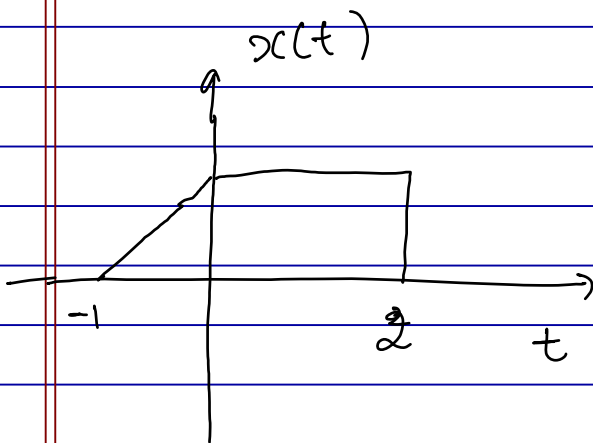
Consider $\alpha = -1$



$x(-t)$ is time reversed version
of $x(t)$

* Combination of time scaling and time shifting

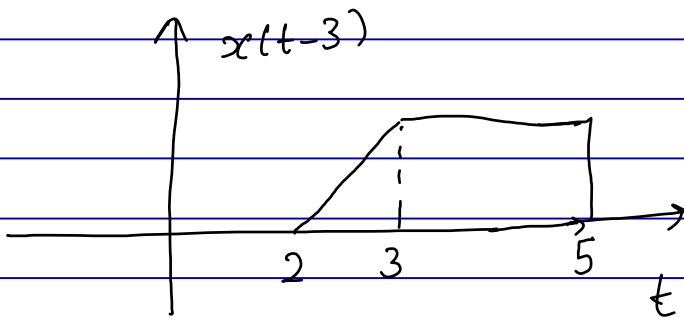
$x(at - b)$ → how is it related to $x(t)$



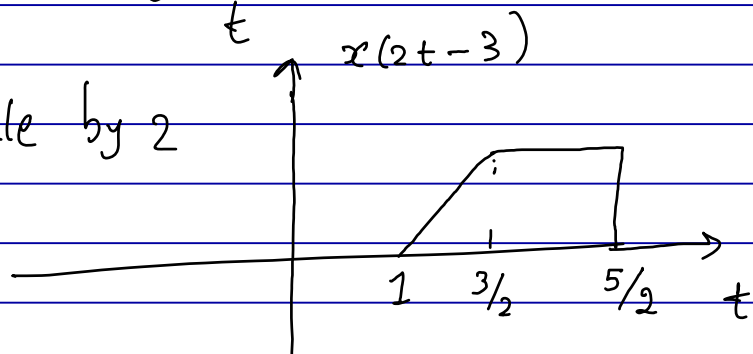
Want to find

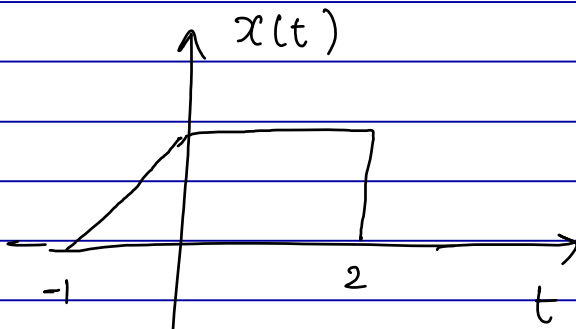
$$x(2t-3) = y(t)$$

shift by 3
 $x(t-3)$

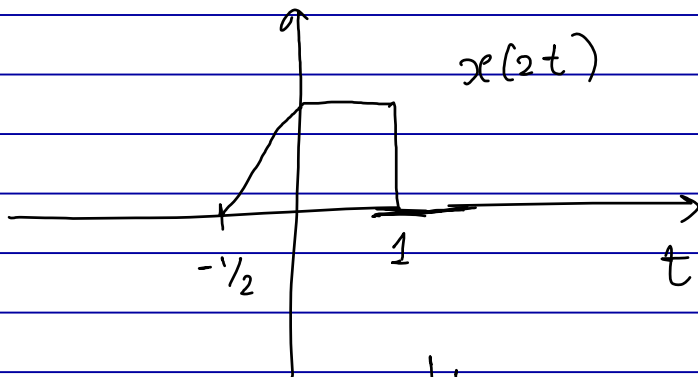


scale by 2

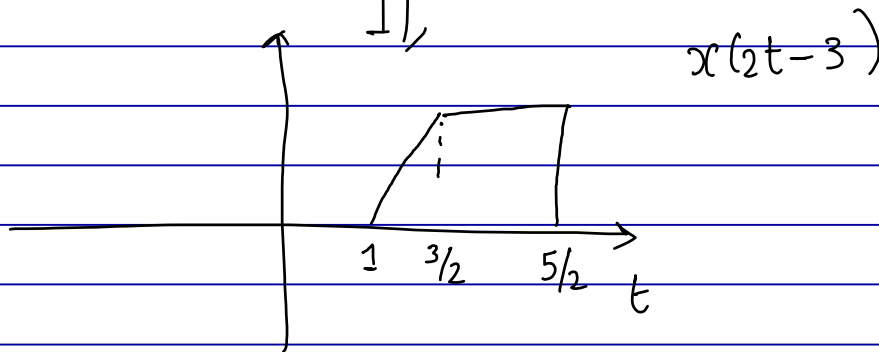




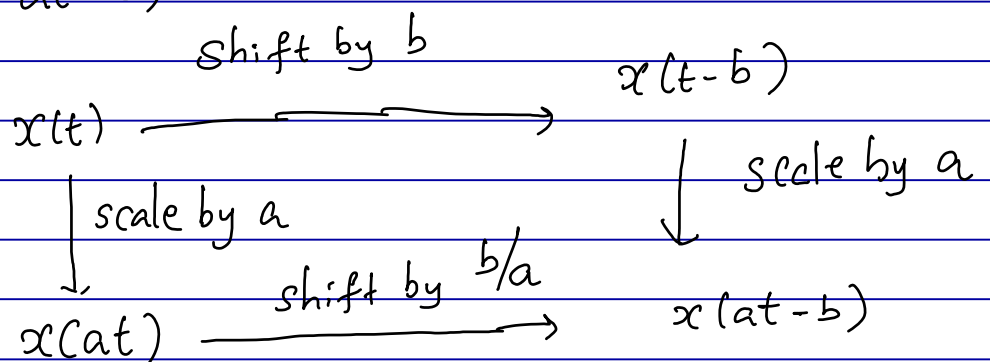
|| scale by factor of 2



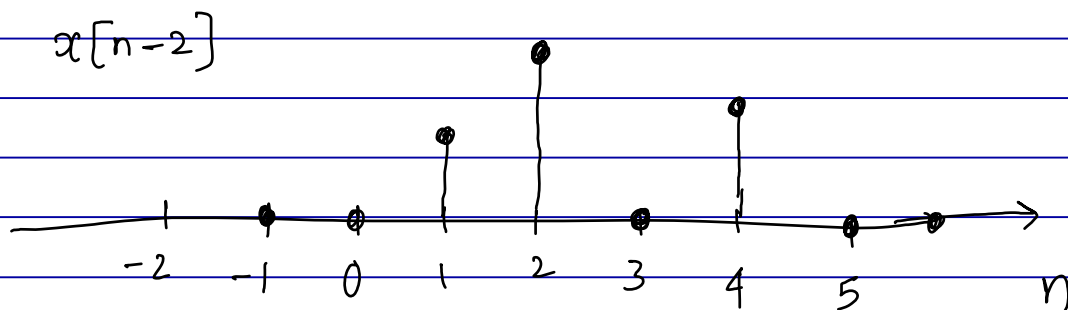
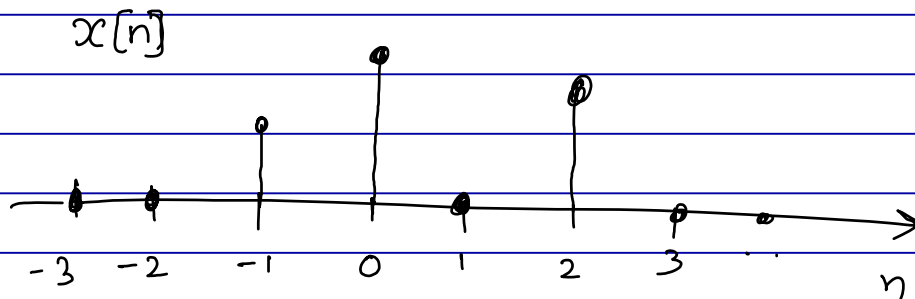
|| shift



$$y(t) = x(at - b)$$



Time Shifting & Scaling for DT Signals



DT time shifting is very similar
to CT time shifting

- Time scaling

$$y[n] = x[\alpha n]$$

If α is an integer, $y[n]$ is
well defined.

- $\alpha = 2$ $y[n] = x[2n]$

↓

contains the even time
samples of $x[n]$

- $\alpha = \frac{1}{2}$ $y[n] = x[n/2]$

↓

$y[n]$ is not defined for odd
values of n

- $\alpha = -1$ $y[n] = x[-n]$

||,

$y[n]$ is time reversed version of $x[n]$

1) Periodic and Aperiodic Signals

Signal $x(t)$ is called periodic if

there exist a non-zero constant T

such that

$$(*) \rightarrow x(t) = x(t+T) \quad (\text{for all } t)$$

\downarrow
original signal

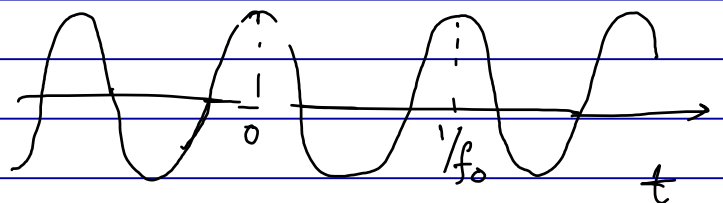
\downarrow
time shifted signal

The smallest value of T for which above condition (*) holds is called fundamental period T_0

Fundamental frequency is the inverse of the fundamental period.

Example;

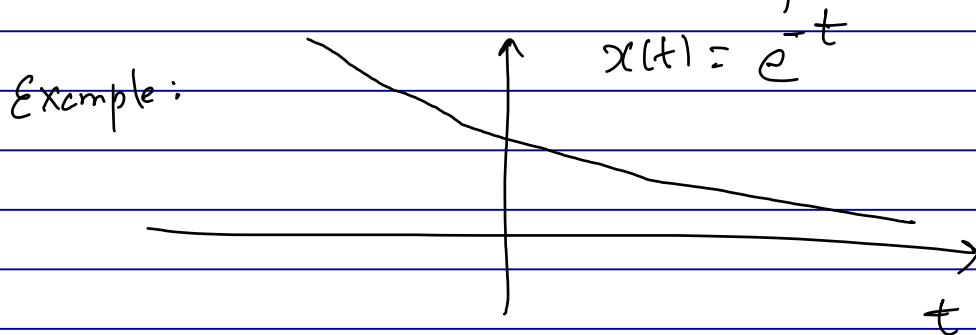
$$x(t) = \cos(2\pi f_0 t)$$



Fundamental period $T_0 = 1/f_0$

$$\begin{aligned}
 x(t+T_0) &= \cos(2\pi f_0(t+T_0)) \\
 &= \cos\left(2\pi f_0 t + 2\pi f_0 \cdot \frac{1}{f_0}\right) \\
 &= \cos(2\pi f_0 t + 2\pi) \\
 &= \cos(2\pi f_0 t) = x(t)
 \end{aligned}$$

Signals which are not periodic
are called aperiodic signals.



Similarly define periodic DT signals:

If there exist non-zero integer N

such that $x[n] = x[n+N]$ then

DT signal/sequence $x[n]$ is periodic.

Even and Odd Signals

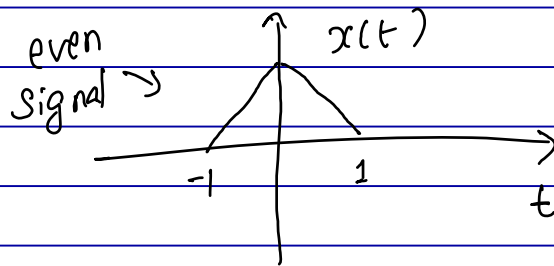
* A signal $x(t)$ is called even signal

$$\text{if } x(t) = x(-t) \quad (\text{for all } t)$$

(original signal is identical to time reversed signal)

Example:

$$\cos(2\pi f_0 t)$$



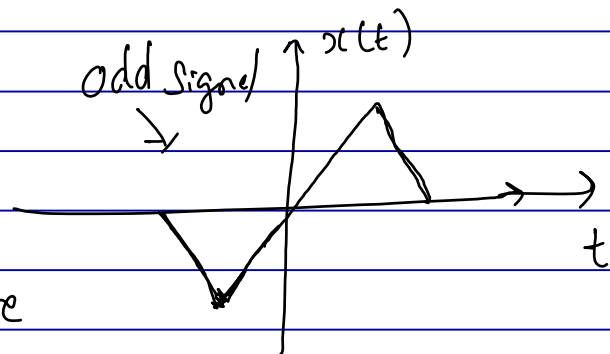
even signals are symmetric about time $t=0$

* A signal $x(t)$ is odd if

$$x(t) = -x(-t) \quad (\text{for all } t)$$

Examples:

$$\sin(2\pi f_0 t)$$



(odd signals are

anti-symmetric about time $t=0$)

Note: Any signal $x(t)$ can be written as a sum of two parts/signal with one of them being an odd signal and other being an even signal

Consider arbitrary signal $x(t)$

$$\text{Define } x_e(t) = \frac{x(t) + x(-t)}{2}$$

$$x_o(t) = \frac{x(t) - x(-t)}{2}$$

Easy to verify that

$x_e(t)$ is an even signal

$x_o(t)$ is odd signal

$$x(t) = x_e(t) + x_o(t)$$

Same definitions apply to DT signals also

$$x[n] = x[-n] \rightarrow \text{even DT signal}$$

$$x[n] = -x[-n] \rightarrow \text{odd}$$

ENERGY & POWER of Signals.

Note Title

06-08-2015

- Let $x(t)$ be a voltage signal across a resistor R in an electrical network.

$$\begin{aligned}\text{power} &= \text{current} \times \text{Voltage} \\ &= \frac{\text{Voltage}}{R} \times \text{Voltage} \\ &= \frac{x^2(t)}{R}\end{aligned}$$

$$\begin{aligned}\text{Energy dissipated in interval } [T_1, T_2] \\ &= \int_{T_1}^{T_2} \frac{x^2(t)}{R} dt\end{aligned}$$

Let us generalize the notion of power and energy for arbitrary signals

- Let $x(t)$ be a general complex-valued signal

defined in interval $-\infty < t < \infty$

Energy of signal $x(t)$ is defined as

$$E_{\infty} = \lim_{T \rightarrow \infty} \int_{-T}^T |x(t)|^2 dt$$

$$E_{\infty} = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

Power of signal $x(t)$ is defined as

$$P_{\infty} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$$

From these definitions, it follows that

If E_{∞} is finite then $P_{\infty} = 0$

If $P_{\infty} > 0$ then $E_{\infty} = \infty$

Example : $x(t) = \cos(t)$

Here $E_{\infty} = \infty$

$P_{\infty} = ?$

x _____ x

- CT & DT {
- ① Complex Exponentials
 - ② Unit impulse & Unit Step

Continuous-time Complex Exponentials

In the most general form

$$x(t) = A e^{st}$$

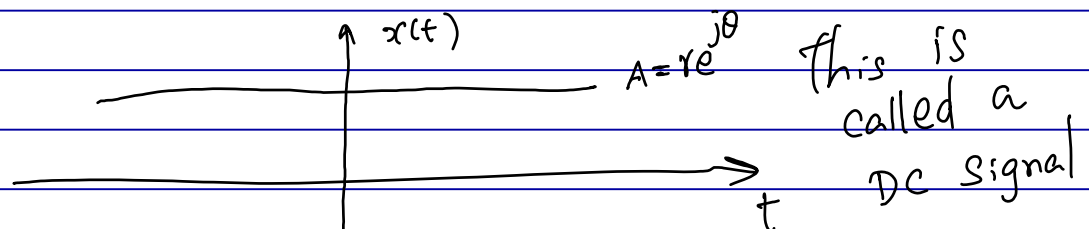
A and s are complex numbers
(in general)

• s is called complex frequency

Suppose $s = \sigma + j\omega$ $A = r e^{j\theta}$

Consider the following special cases

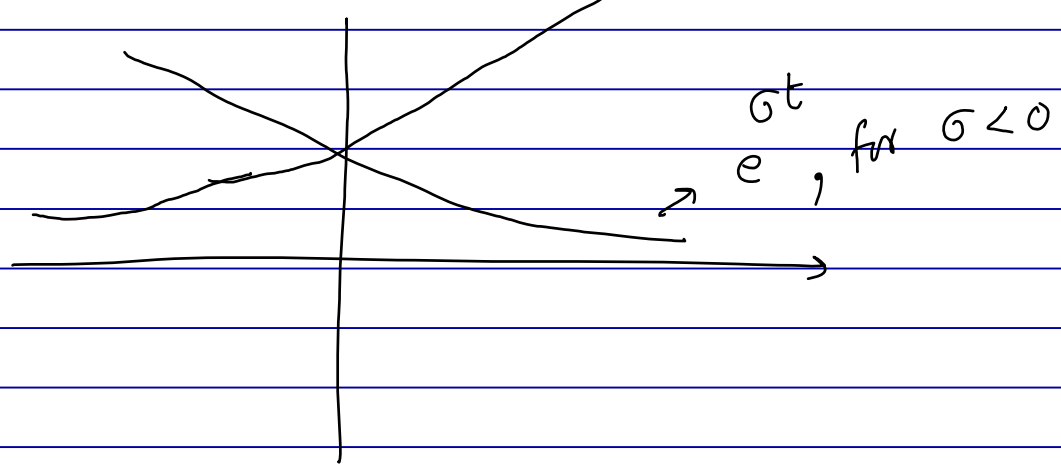
① $s = 0$ $x(t) = A e^{0 \cdot t} = A$



② $s = \sigma + j\omega$

Consider $\omega = 0$ and A is real

$x(t) = A e^{\sigma t} + e^{\sigma t}, \sigma > 0$



10/8

③ Consider $A e^{st} + A^* e^{s^*t}$

$()^* \rightarrow$ denotes conjugation $= r e^{j\theta} \cdot e^{(\sigma + j\omega)t} + r e^{-j\theta} \cdot e^{(\sigma - j\omega)t}$

$= r e^{\sigma t} (e^{j(\omega t + \theta)} + e^{-j(\omega t + \theta)})$

$2 \cos(\omega t + \theta)$

$= 2 r (e^{\sigma t}) \cos(\omega t + \theta)$

Annotations: σt is the real part of complex frequency; ω is the imaginary part of complex frequency.

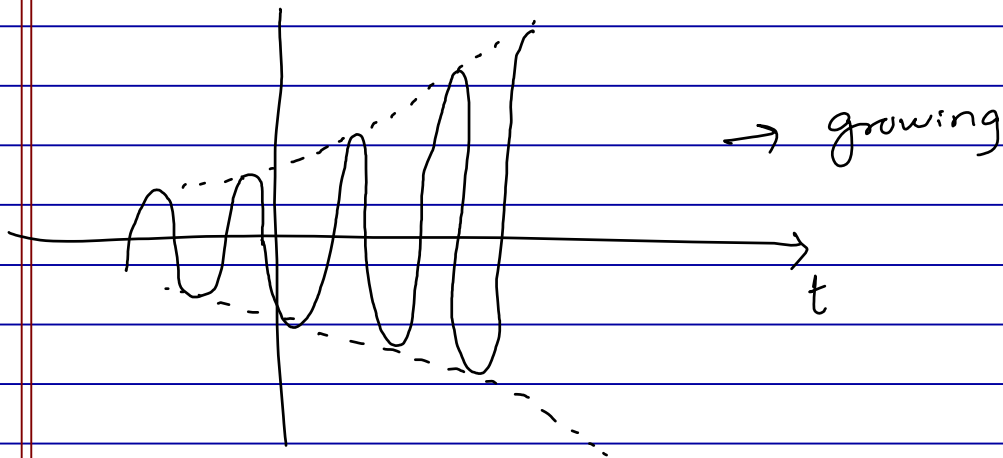
Complex frequencies

$\sigma + j\omega$

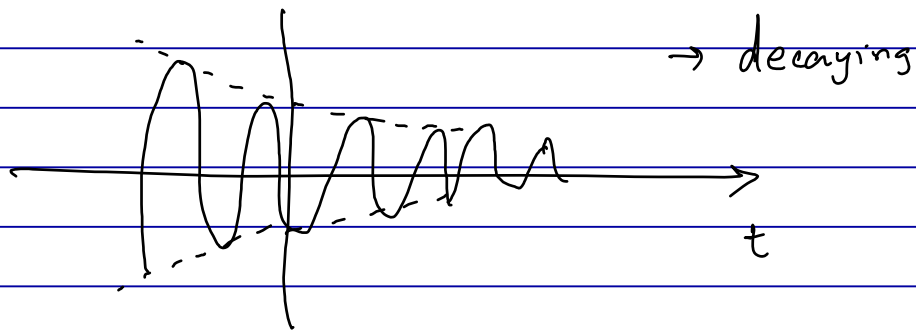
imaginary part of complex freq.

Plots of complex exponentials

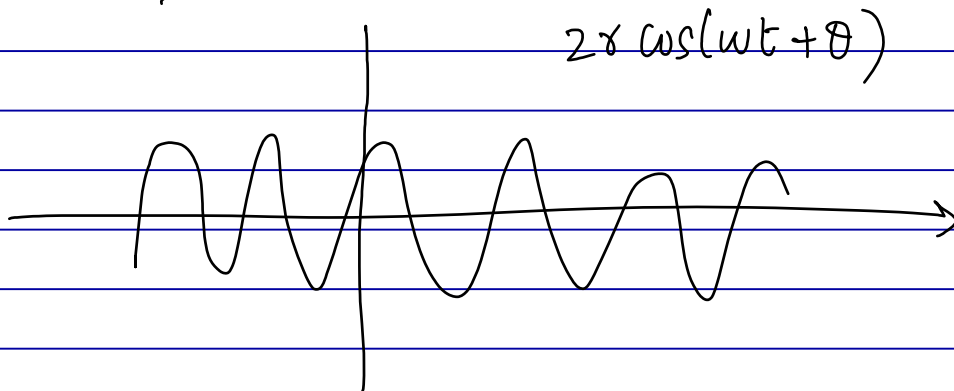
$$(1) \sigma \pm j\omega ; \sigma > 0 \quad 2r e^{\sigma t} \cos(\omega t + \theta)$$



$$(2) \sigma \pm j\omega ; \sigma < 0$$



$$(3) \pm j\omega ; \sigma = 0$$



Signal

Complex frequencies

$$(1) \quad \cos(2t+1)$$

$$\pm 2j$$

$$(2) \quad \sin(3t+5)$$

$$\pm 3j$$

$$\sin(3t+5) = \frac{e^{j(3t+5)} - e^{-j(3t+5)}}{2j}$$

$$= \frac{e^{j5} e^{j3t}}{2j} - \frac{e^{-j5} e^{-j3t}}{2j}$$

$$(3) \quad 4 + 3e^{2t} \sin(5t-1)$$

Complex frequencies

$$0, 2 \pm 5j$$

$$(4) \quad e^{2jt} + e^{-4t} \cos(5t+1) - \sin(3t+2)$$

$$+2j, -4 \pm 5j,$$

$$\pm 3j$$

x ————— x

When $s = j\omega$ ($\sigma = 0$)

$$\begin{aligned} Ae^{st} &= Ae^{j\omega t} \\ &= re^{j\theta} e^{j\omega t} \\ &= r e^{j(\omega t + \theta)} \end{aligned}$$

Say $x(t) = r e^{j(\omega t + \theta)}$

• $x(t)$ is periodic with fundamental

$$\text{period} = \frac{2\pi}{\omega}$$

• Power of $x(t)$ $P_{\infty} = r^2$

• Energy of $x(t)$ $E_{\infty} = \infty$

x ————— x

DT Complex exponential

$$x[n] = e^{j\omega_0 n}, \quad n \in \mathbb{Z}$$

ω_0 is a constant

- For $\omega_0 \neq \omega_0 + 2\pi k$ the DT complex exponential is identical for any integer k .

$$e^{j(\omega_0 + 2\pi k)n} = e^{j\omega_0 n} \cdot \underbrace{e^{j2\pi kn}}_1 = e^{j\omega_0 n}$$

- $x[n] = e^{j\omega_0 n}$ is periodic only if it

satisfies certain condition

$$\text{Suppose } x[n] = x[n+N]$$

N is an integer

$$e^{j\omega_0 n} = e^{j\omega_0(n+N)} = e^{j\omega_0 n} \cdot \underbrace{e^{j\omega_0 N}}_1$$

from original signal

Note Title

10-08-2015

$$\Rightarrow e^{j\omega_0 N} = 1$$

$$\Rightarrow \omega_0 N = 2\pi m \quad \text{for some integer } m$$

$$\Rightarrow \left[\omega_0 = 2\pi \frac{m}{N} \right] \quad \text{for some integers } m \neq N$$

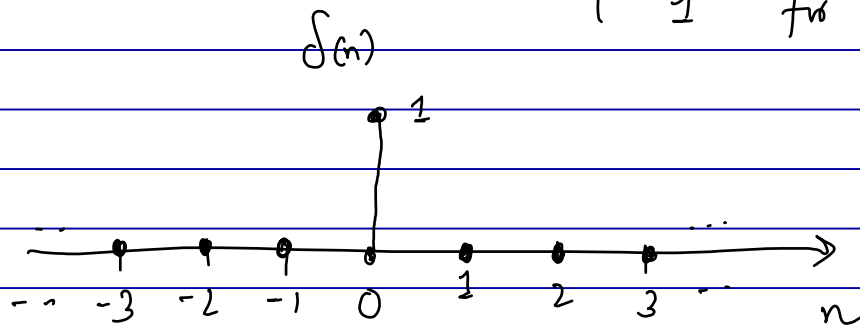
Condition when DT complex exponential is periodic.

$\omega_0 = 1$ will not be periodic.

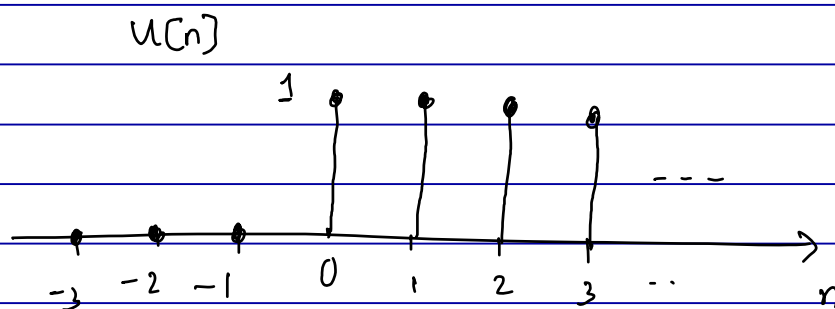
Start with DT case.

DT unit impulse signal $\delta(n)$ is

defined as

$$\delta(n) = \begin{cases} 0 & \text{for } n \neq 0, n \in \mathbb{Z} \\ 1 & \text{for } n = 0 \end{cases}$$


DT unit step signal $u[n]$ is

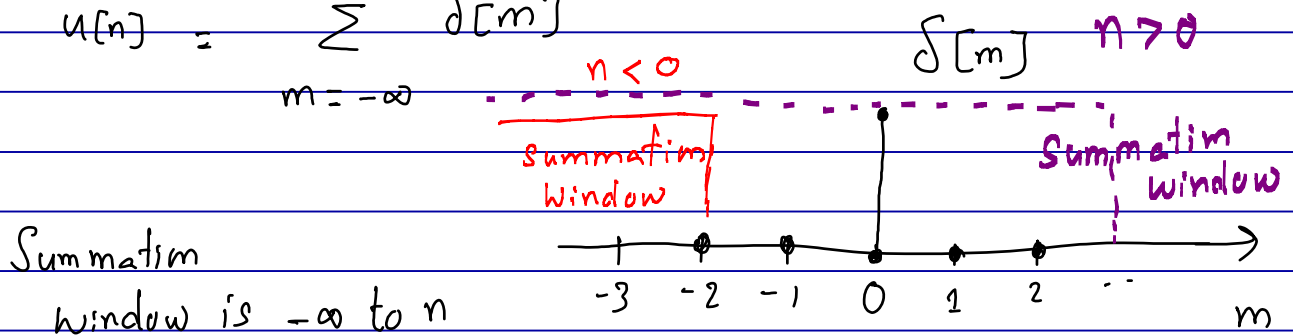
$$u[n] = \begin{cases} 0 & \text{for } n < 0 \\ 1 & \text{for } n \geq 0, n \in \mathbb{Z} \end{cases}$$


Note that $\delta(n) = u[n] - u[n-1]$

↓
can be thought as subtracting
time shifted signal

Writing step function $u[n]$ using
delayed copies of $\delta[n]$
(Summation)

$$u[n] = \sum_{m=-\infty}^n \delta[m]$$



$$u[n] = \sum_{m=-\infty}^n \delta[m]$$

change of variable $k = n - m$

$$u[n] = \sum_{k=0}^{\infty} \delta[n-k]$$

$$= \delta[n] + \delta[n-1] + \delta[n-2] + \dots$$

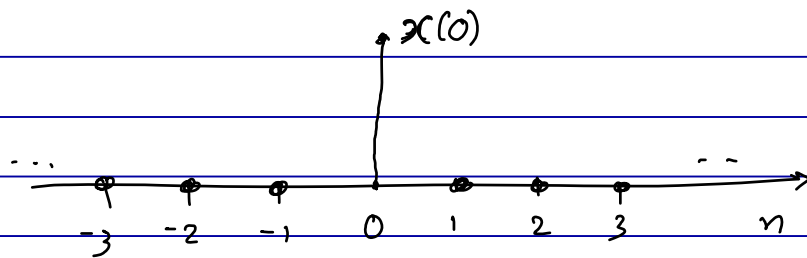
↓

(infinite) summation of delayed copies of $\delta[n]$

Sampling Property of $\delta(n)$

Let $x(n)$ be an arbitrary DT signal

Consider $x(n) \delta(n) \rightarrow$ product of $x(n)$ and $\delta(n)$



$$x(n) \delta(n) = x(0) \delta(n)$$

$$x(n) \delta(n-N) = x(N) \delta(n-N)$$

$r \xrightarrow{\hspace{2cm}} x$

CT unit step function

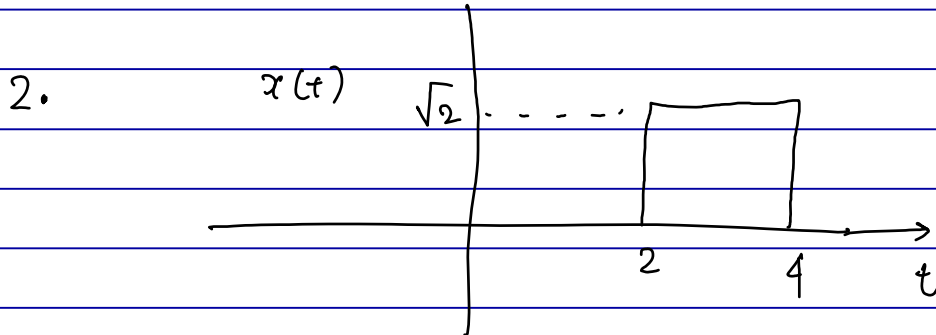
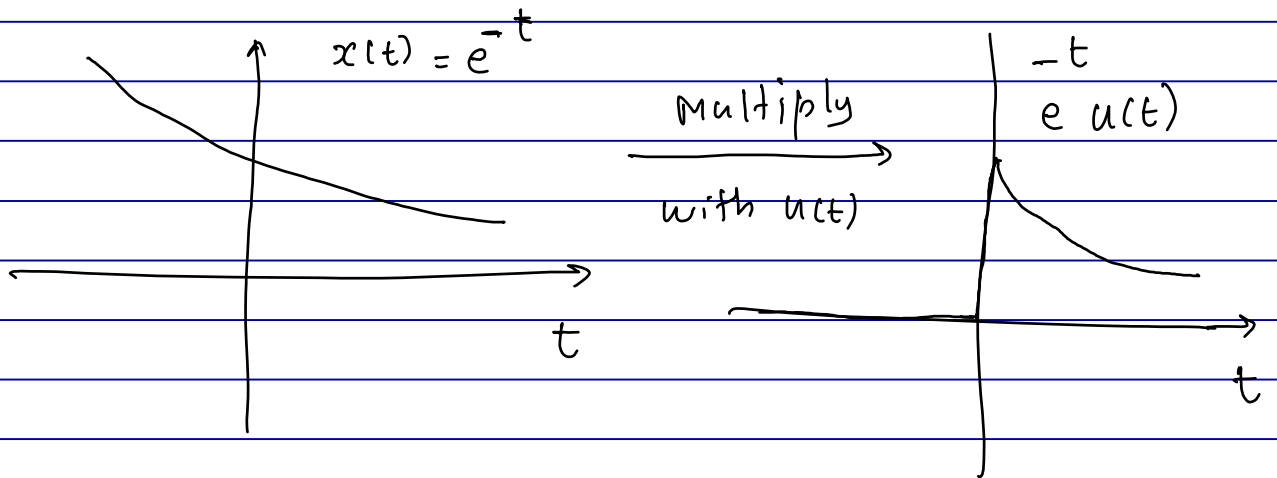
$u(t) \rightarrow$ CT unit step function is

$$\text{defined as } u(t) = \begin{cases} 0 & ; \text{ for } t < 0 \\ 1 & ; \text{ for } t \geq 0 \end{cases}$$

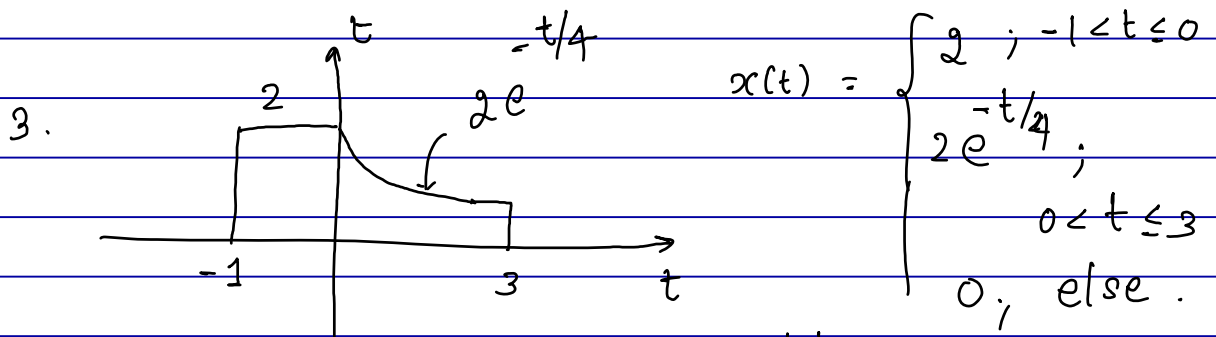
Using $u(t)$, we can compactly represent some types of signals.

Example

1. Suppose we want to nullify signal for negative values of t , we can simply multiply by $u(t)$



$$x(t) = \sqrt{2} [u(t-2) - u(t-4)]$$



$$x(t) = \begin{cases} 2 & -1 < t \leq 0 \\ 2e^{-t/4} & 0 < t \leq 3 \\ 0 & \text{else.} \end{cases}$$

$$x(t) = 2 [u(t+1) - u(t)] + 2e^{-t/4} [u(t) - u(t-3)]$$

CT Impulse function

- Need to be careful in defining CT impulse
- We will understand it from its properties

CT impulse function $\delta(t)$ satisfies

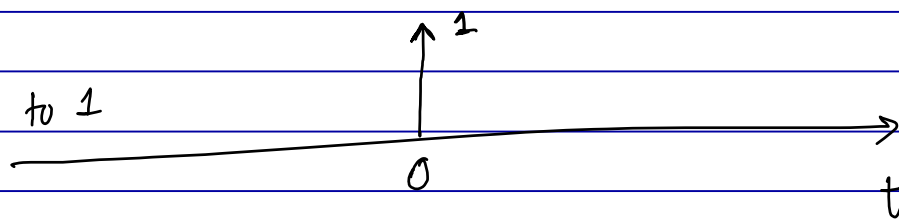
1. $\delta(t) = 0$ for $t \neq 0$

2. $\int_{-\infty}^{\infty} \delta(t) dt = 1$

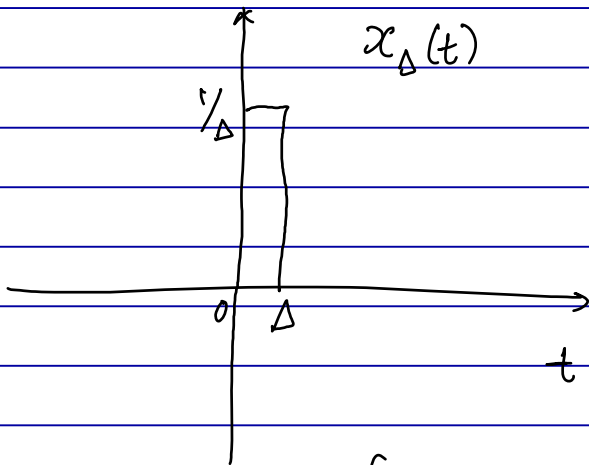
Pictorially

At $t=0$,

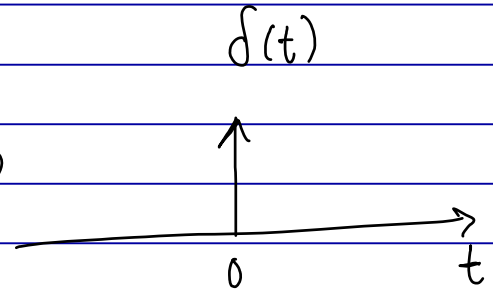
$\delta(t)$ is
not equal to 1



- We can think $\delta(t)$ as a limit of a sequence of functions.



lim
 $\Delta \rightarrow 0$



$$x_{\Delta}(t) = \begin{cases} 1/\Delta & \text{for } 0 \leq t \leq \Delta \\ 0 & \text{else} \end{cases}$$

$$\int_{-\infty}^{\infty} x_{\Delta}(t) dt = 1$$

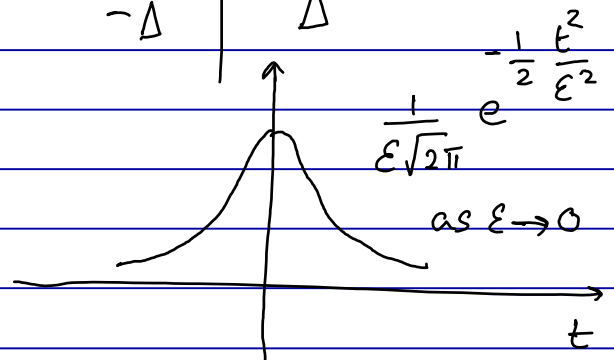
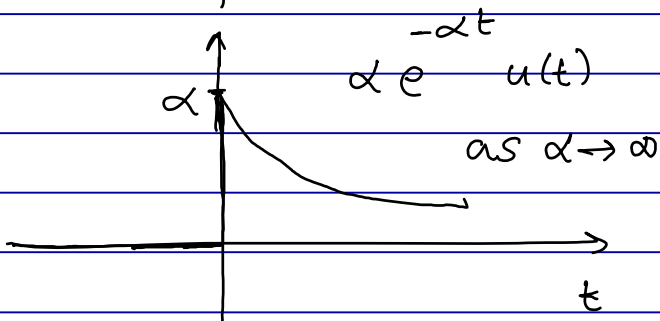
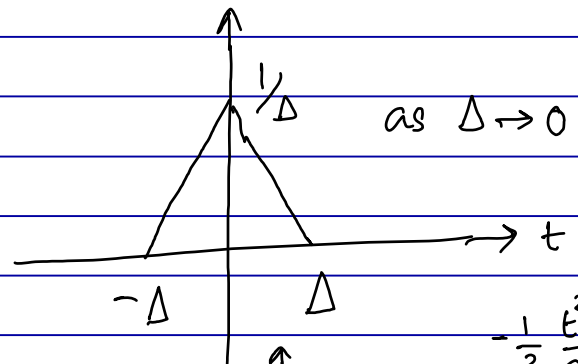
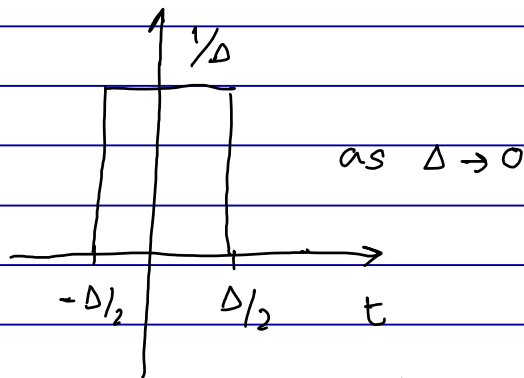
$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

$$\delta(t) = 0 \text{ for } t \neq 0$$

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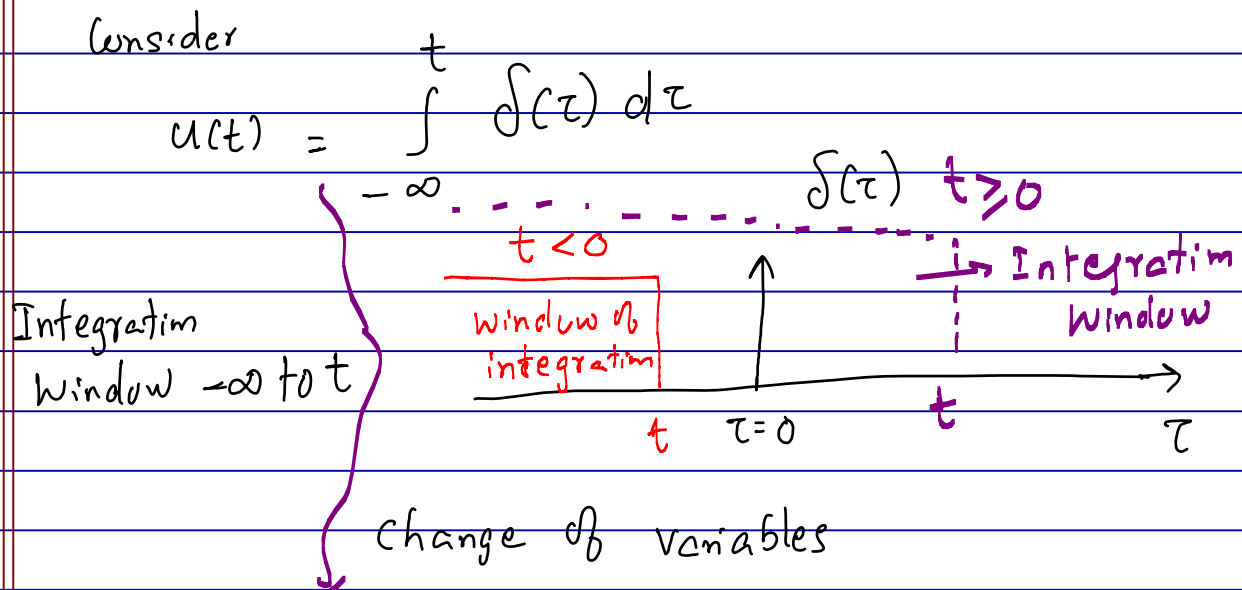
$\delta(t)$ can be obtained thru other limits

also



CT step function can be got
from CT impulse using integration.

$$u(t) = \begin{cases} 1 & \text{for } t \geq 0 \\ 0 & \text{for } t < 0 \end{cases}$$



$$\sigma = t - \tau$$

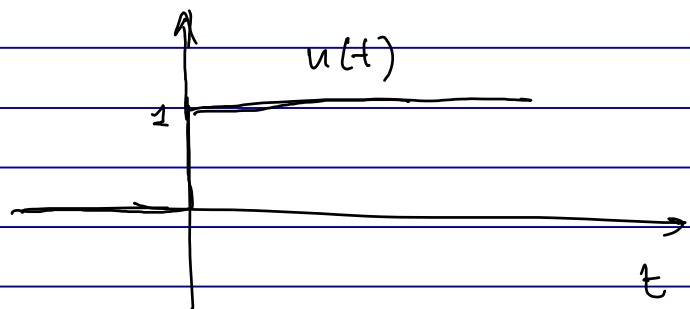
$$u(t) = \int_{\sigma=0}^{\infty} \delta(t - \sigma) d\sigma$$

interpreted as "Sum" of delayed
copies of impulse function.

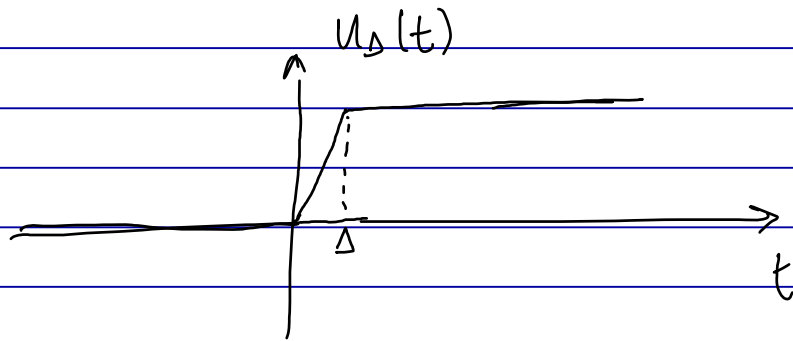
Getting $f(t)$ from $u(t)$ can
be done thru differentiation

But we need to be careful

Since $u(t)$ is discontinuous at $t=0$



Consider $u_{\Delta}(t)$

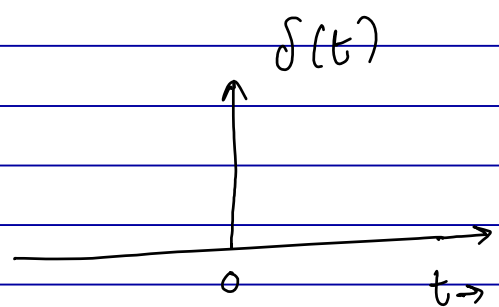
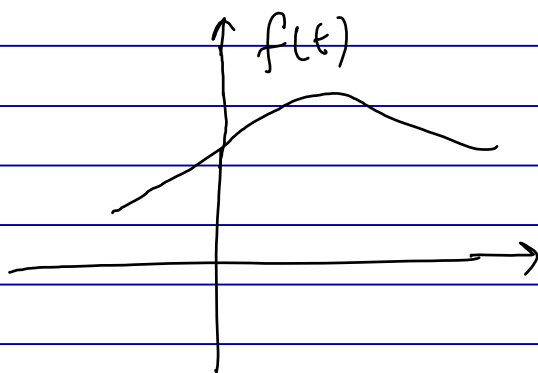


$$\delta(t) = \lim_{\Delta \rightarrow 0} \frac{d}{dt} u_{\Delta}(t)$$

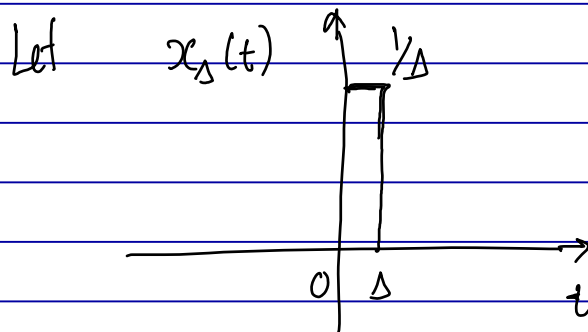
Sampling Property of $\delta(t)$

Let $f(t)$ be some arbitrary function

$f(t)$ be continuous at $t=0$.



Consider $f(t) \delta(t) = ?$



Consider $f(t) \cdot x_\Delta(t)$ and then take
limit as $\Delta \rightarrow 0$

$$f(t) \chi_{\Delta}(t) = \begin{cases} f(t) \cdot \frac{1}{\Delta} & \text{for } 0 \leq t \leq \Delta \\ 0 & \text{otherwise} \end{cases}$$

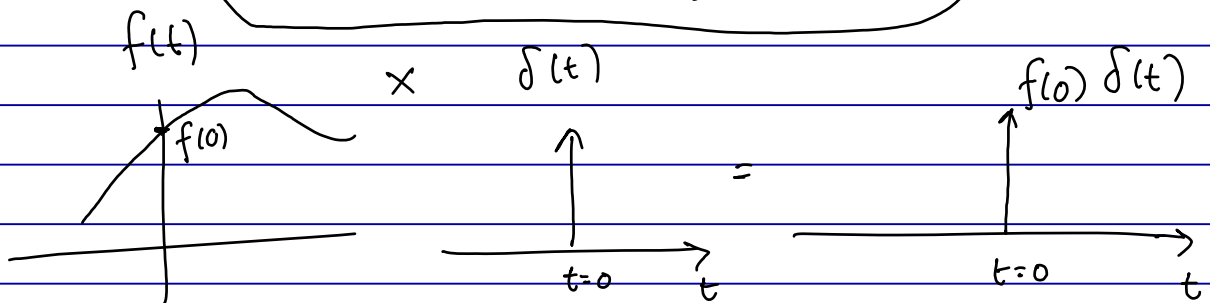
if Δ is very small $\approx \begin{cases} f(0) \cdot \frac{1}{\Delta} & \text{for } 0 \leq t \leq \Delta \\ 0 & \text{otherwise} \end{cases}$

$f(t) \approx f(0)$
for $0 \leq t \leq \Delta$

$f(t) \chi_{\Delta}(t) \approx f(0) \chi_{\Delta}(t)$ for very small Δ

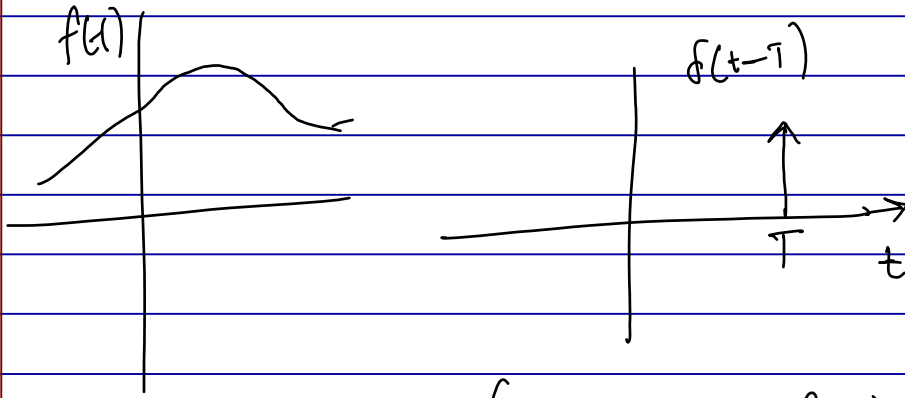
$$\lim_{\Delta \rightarrow 0} f(t) \chi_{\Delta}(t) = \lim_{\Delta \rightarrow 0} f(0) \chi_{\Delta}(t)$$

$$f(t) \delta(t) = f(0) \delta(t)$$



Similarly;

$$f(t) \delta(t-T) = f(T) \delta(t-T)$$



(assuming $f(t)$ is continuous at time $t=T$)

Sifting Property of Impulse function.

$$\int_{-\infty}^{\infty} f(t) \delta(t-T) dt = \int_{-\infty}^{\infty} f(T) \delta(t-T) dt$$

$$= f(T) \int_{-\infty}^{\infty} \delta(t-T) dt$$

$$\left(\int_{-\infty}^{\infty} f(t) \delta(t-T) dt = f(T) \right)$$

$\underbrace{\int_{-\infty}^{\infty} \delta(t-T) dt}_{= 1}$
 Sifting property.