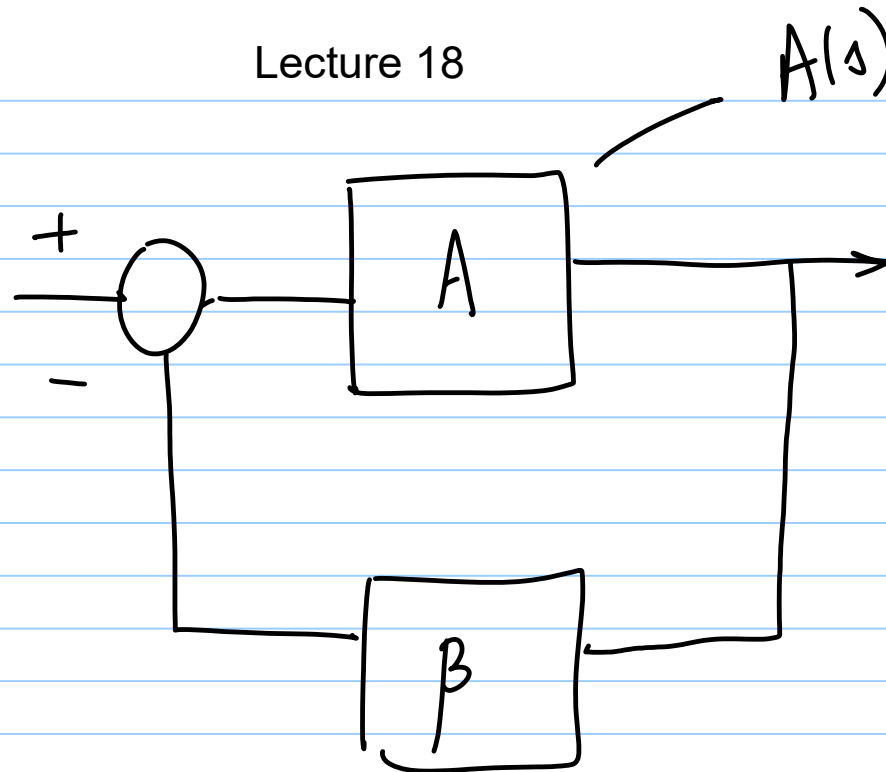


20/02/2019

Lecture 18



$$\text{loop gain} = A\beta$$

$$CLG = \frac{1}{\beta} \cdot \frac{A\beta}{1+A\beta}$$

$$LG(s) = \beta A(s) = \frac{\beta \cdot A_0}{\left(1 + \frac{s}{\omega_p}\right)^3} \leftarrow$$

$$CLG(s) = \frac{1}{\beta} \cdot \frac{A_0 \beta}{1 + A_0 \beta} \cdot \frac{1}{1 + \left[\frac{3s}{\omega_p} + \frac{3s^2}{\omega_p^2} + \frac{s^3}{\omega_p^3} \right]}.$$

$$D(s) = 1 + \frac{3s}{\omega_p(1 + A_0 \beta)} + \frac{3s^2}{\omega_p^2(1 + A_0 \beta)} + \frac{\left(\frac{1}{1 + \beta A_0} \right) s^3}{\omega_p^3(1 + \beta A_0)}$$

roots of $D(s) = 0$

Roots of $D(s/\omega_p)$

$$(1 + A_0\beta) + 3s + 3s^2 + s^3 = 0$$

$$(1+s)^3 + A_0\beta = 0$$

$$s = -1 + (-A_0\beta)^{1/3}$$

e.g. $A_0\beta = 8$

$$s_1 = -1 - 2 = -3;$$

$$s_2 = -1 - 2e^{-j2\pi/3}; \quad s_3 = -1 - 2e^{+j2\pi/3}$$

$$\begin{array}{l}
 s_1 = -3\omega_p \\
 s_2 = +j\sqrt{3}\omega_p \\
 s_3 = -j\sqrt{3}\omega_p
 \end{array}
 \left. \vphantom{\begin{array}{l} s_1 \\ s_2 \\ s_3 \end{array}} \right\} \begin{array}{l} \text{If } A_{op} > 8 \\ \Downarrow \\ \text{poles in RHP} \end{array}$$

We wanted large A_{op}

Solutions:

1) Pole-zero cancellation:

$$\frac{A_0}{\left(1 + s/\omega_p\right)^3} \times \frac{\left(1 + s/\omega_z\right)}{\left(1 + s/\omega_p'\right)}$$

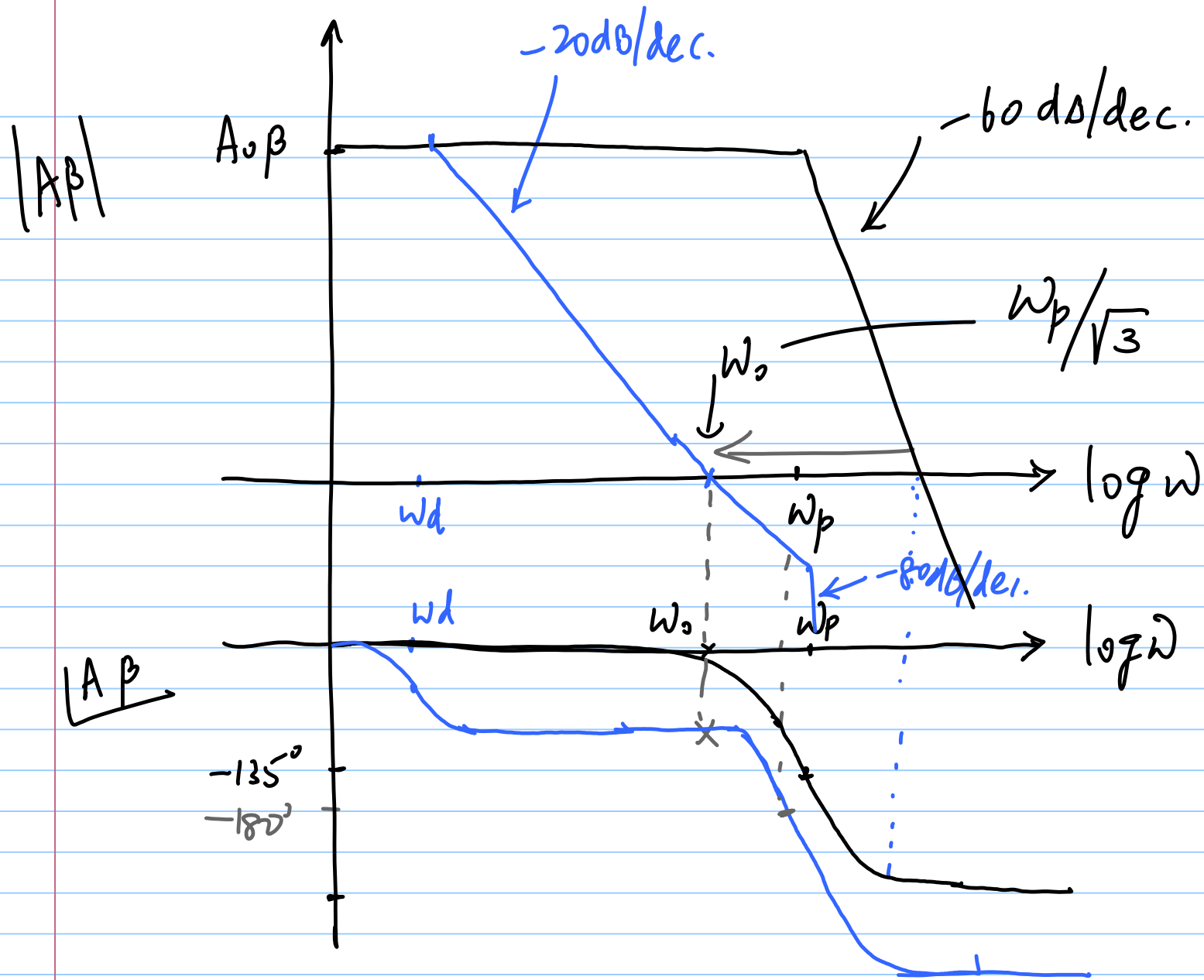
$\omega_z = \omega_p$
 $\omega_p' > \omega_p$

2) Make 3rd order system look like 1st order system

e.g. add pole @ ω_d

$$A(s) = \frac{A_0}{(1 + s/\omega_d) (1 + s/\omega_p)^3}$$

$$\omega_d = \frac{\omega_p}{1000}$$



disadvantage ;
 * lower BW
advantage.
 * unconditionally
 stable
 * Very low
 steady state
 error.

$$\omega_d = \frac{\omega_p}{1000}$$

$$\omega_o \gg \omega_d$$

$$|L_G(j\omega_o)| = 1$$

$$\begin{aligned} \angle L_G(j\omega_o) &= -180^\circ \\ \Rightarrow 0 - 3 \tan^{-1}\left(\frac{\omega_o}{\omega_p}\right) - \underbrace{\tan^{-1}\left(\frac{1000\omega_o}{\omega_p}\right)}_{-\pi/2} &= -\pi \end{aligned}$$

$$-3 \tan^{-1} \left(\frac{\omega}{\omega_p} \right) = -\pi/2$$

$$\tan^{-1} \left(\frac{\omega}{\omega_p} \right) = +\pi/6$$

$$\frac{\omega}{\omega_p} = \frac{+1}{\sqrt{3}}$$

$$|L_4(j\omega_0)| = 1$$

$$\left| \frac{A_0 \beta}{\left(1 + \frac{j}{\sqrt{3}}\right)^3 \cdot \left(1 + \frac{1000j}{\sqrt{3}}\right)} \right| = 1$$

$$\frac{A_0 \beta}{\left(\sqrt{1 + 1/3}\right)^3 \left(\frac{1000}{\sqrt{3}}\right)} = 1 \Rightarrow A_0 \beta = 888.88$$

much larger original
limit of $A_0 \beta = 8$

$\omega_d \equiv$ "Dominant Pole"

Technique $\equiv$ "Dominant pole compensation"