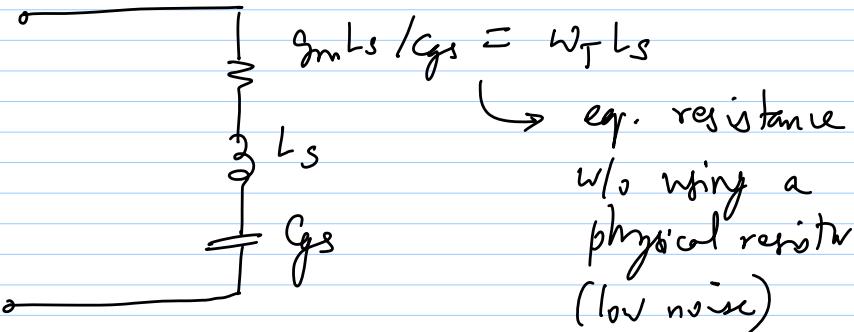


6-9-13

## Lec 16

b)  $Z_s = sL_s$

$$Z_{in} = sL_s + \frac{1}{sC_{gs}} + \frac{g_m L_s}{C_{gs}}$$



Set  $f_o$ ,  $I_{bias}$ ,  $\omega_T L_s$  independently  
- add another degree of freedom

(1) add cap  $C_x$  in ||<sup>t</sup> to  $C_{gs}$

$$\omega_T' = \frac{g_m}{C_g + C_x} \quad \text{changes } \times \text{Re}(Z_{in})$$

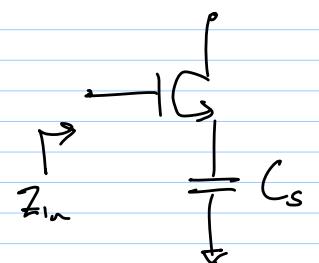
(2) add  $L_g$  in series with the gate

$$f_o = \frac{1}{2\pi \sqrt{C_{gs}(L_g + L_s)}} \quad \checkmark$$

- \* Low noise (no physical resistor)
- \* small  $S_{11} \Rightarrow \omega_T L_s = 50 \text{ n}$
- \* Make  $L_s$  &  $C_{gs}$  resonate @ desired freq.  $f_o$   
constraint:

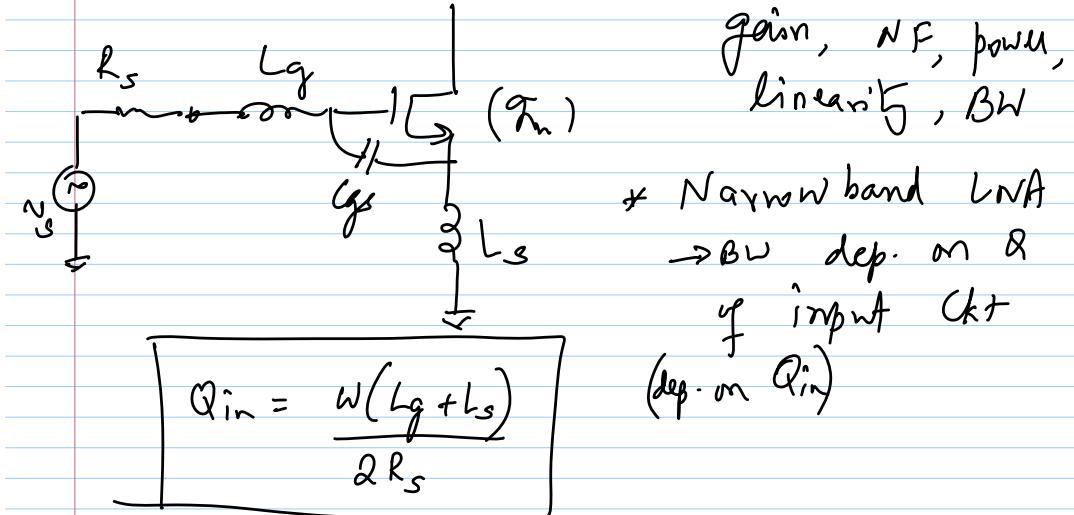
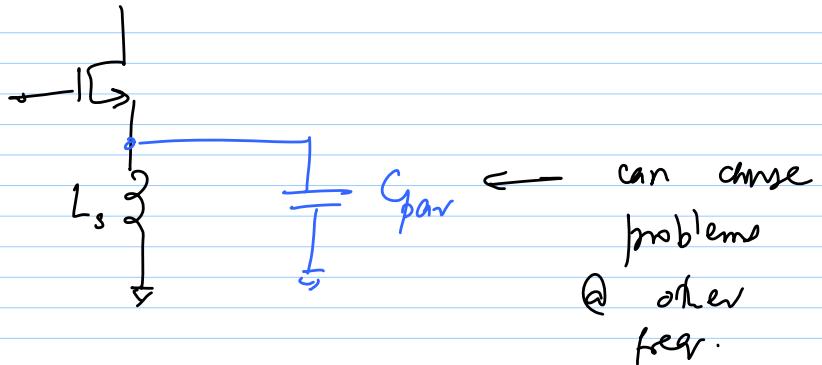
$C_{in}$ ,  
 $C_{gs}$ ,  
 $I_{bias}$

III  $C_s$  @ source of c-s.

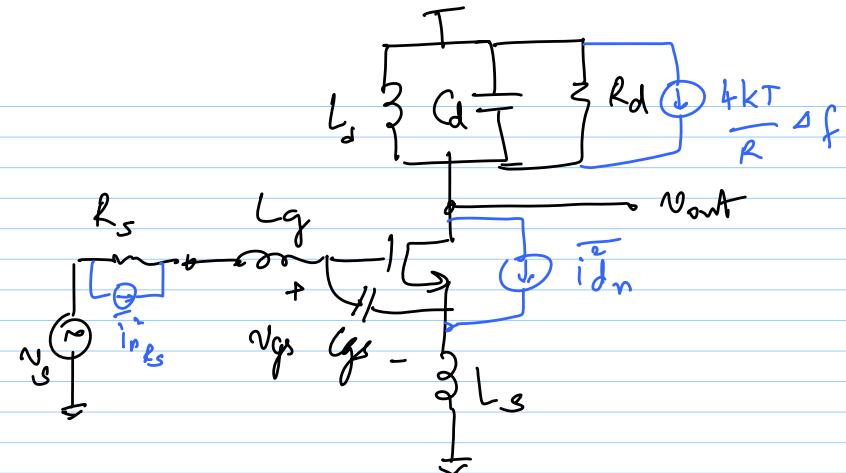


$$Z_{in} = \frac{1}{sC_s} + \frac{1}{sC_{gs}} + \frac{g_m}{s^2 C_g C_s}$$

→ -ve resistance  
→ freq. dependent

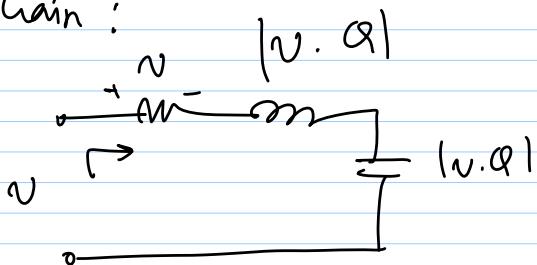


\* ↑ BW  $\Rightarrow$  ↓ Q<sub>in</sub>  $\Rightarrow$  ↓ (L<sub>g</sub> + L<sub>s</sub>)  
 $\Rightarrow$  ↑ C<sub>gs</sub> (keep w<sub>o</sub> constant)  $\Rightarrow$  w<sub>T</sub> ↓  
 $\Rightarrow$  R<sub>in</sub> ↓  $\Rightarrow$  ↑ L<sub>s</sub>  $\dots$  X  
 $\hookrightarrow \Rightarrow \uparrow g_m \Rightarrow \uparrow I_{bias}$



\* L<sub>d</sub> - C<sub>d</sub>  $\Rightarrow$  swings are better  
- oob filtering better  
- BW limitation (R<sub>c</sub>)

\* Gain:



$$v_{gs} = Q_{in} \cdot v_s$$

$$i_d = g_m \cdot Q_{in} \cdot v_s$$

$$v_{out} = g_m \cdot R_L \cdot Q_{in} \cdot v_s$$

$$\text{gain} = \frac{v_o}{v_s} = g_m \cdot R_L \cdot Q_{in}$$

a) more gain than normal C-S-A.  
dep. on  $Q_{in}$

b) NF better than normal C-S-A.  
dep. on  $Q_{in}$

c) Linearity worse than normal C-S-A