

2.8.12

### Lec 3

$$\Delta V_S = \Delta I_D \cdot R_S + \Delta V_D$$

$$\Delta I_D = \frac{I_S}{V_t} \exp\left(\frac{V_{D_0}}{V_t}\right) \cdot \Delta V_D$$

$$\approx \frac{I_{D_0}}{V_t} \cdot \Delta V_D$$

$$\Rightarrow \Delta V_D = \frac{V_t}{I_{D_0}} \cdot \Delta I_D$$

$$\Delta V_S = \Delta I_D \cdot R_S + \Delta I_D \cdot \frac{V_t}{I_{D_0}}$$

$\Rightarrow$  Incremental quantities related linearly

+  $I = f(V)$  can be linearised around  $(V_0, I_0)$  - OP

$\rightarrow$  any nonlinearity can be handled this way

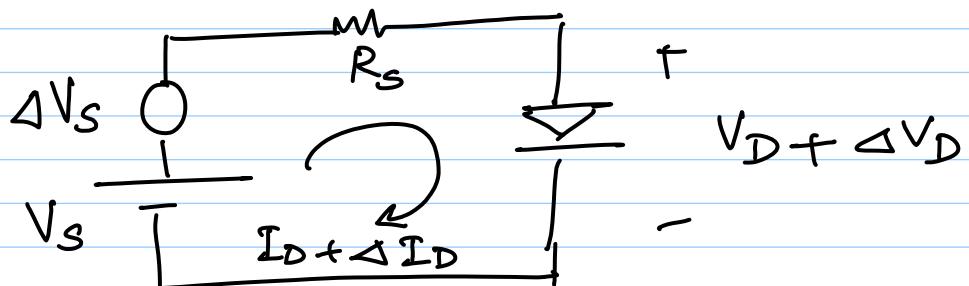
$\rightarrow V = g(I)$  can also be used

$$\text{e.g. } V_D = V_t \ln\left(\frac{I_D}{I_S} + 1\right)$$

$$I_D' = I_{D_0} + \Delta I_D$$

expand  $V_D'$  in a Taylor series

assumptions:  $\Delta V_D$  is "small-signal"



\* If  $V_s$  is changed by a small amount — i.e. the "signal" is small — the loop currents and node voltages also change by a small amount

$$I_D \leftrightarrow V_D \leftrightarrow V_s \Rightarrow \text{non-linear relation}$$

$$I'_D \leftrightarrow V'_D \leftrightarrow V'_s \Rightarrow \text{"}$$

$$\Delta I_D \leftrightarrow \Delta V_D \leftrightarrow \Delta V_s \Rightarrow \text{linear relation}$$

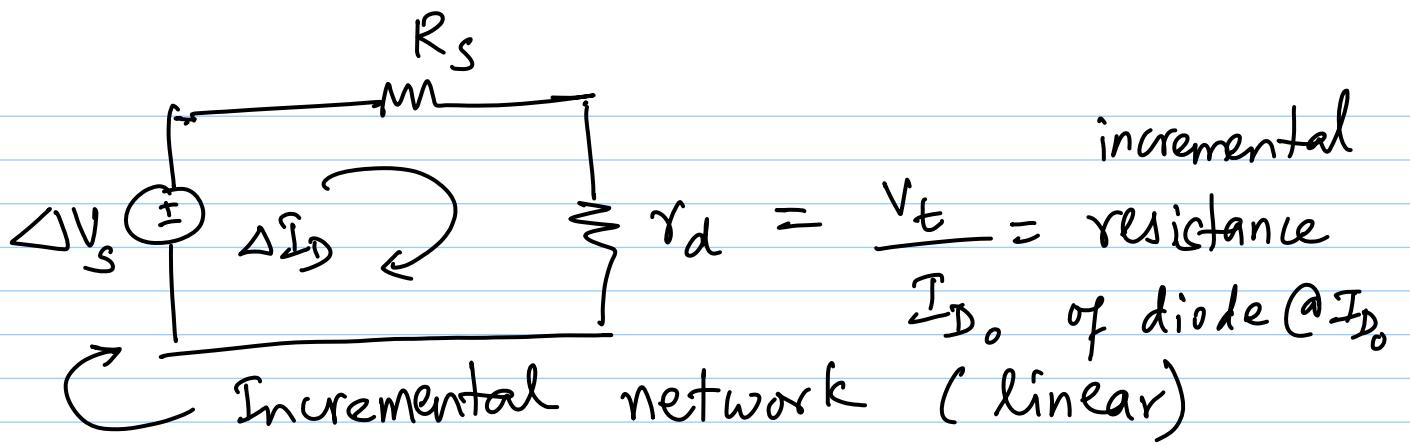
i.e. absolute voltage-current are still related by a NL eqn.

BVT: incremental  $V$  &  $I$  are related linearly

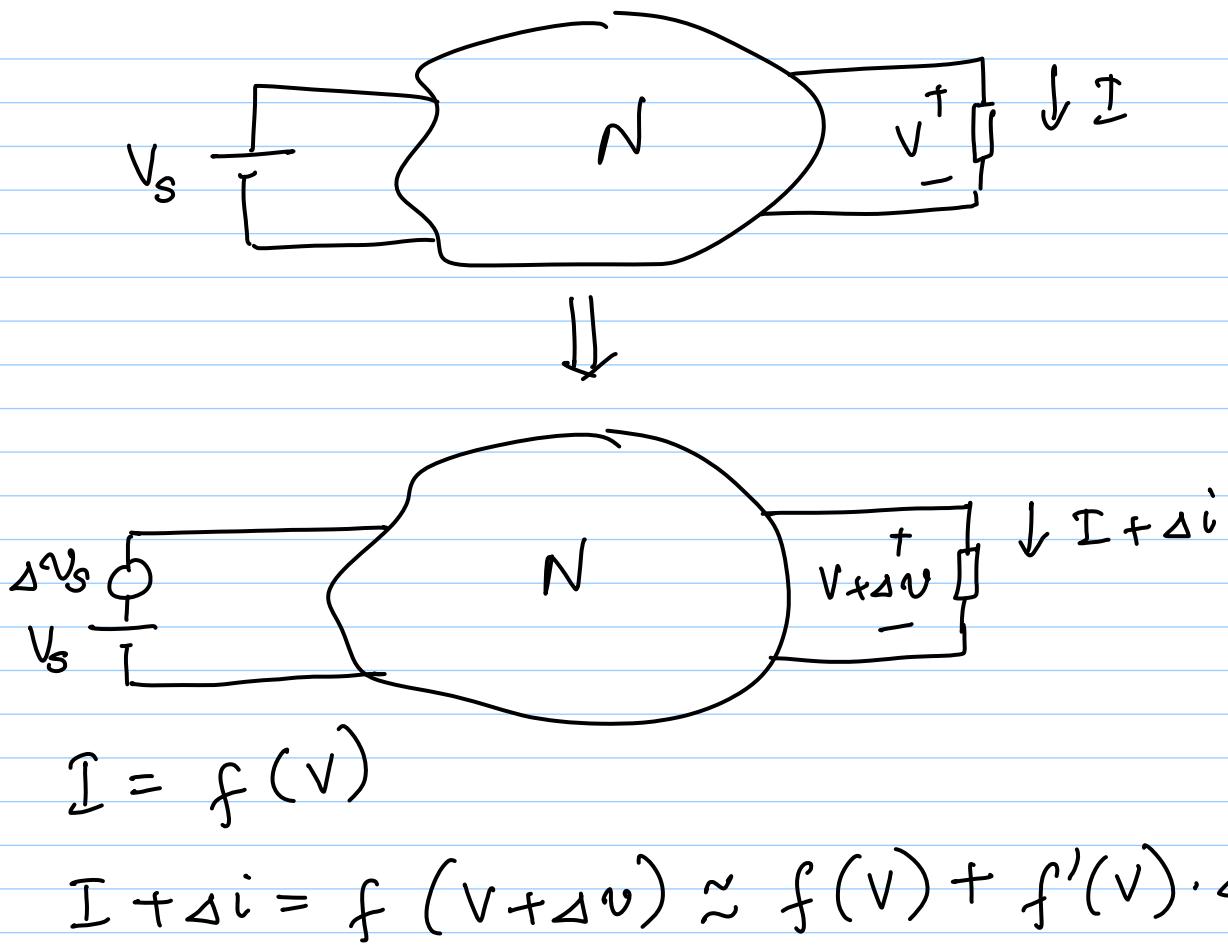
Going back to diode network:

$$\Delta I_D = \frac{\Delta V_s}{R_s + \frac{V_t}{I_{D0}}}$$

What kind of network has this loop eqn?



$V$        $I = f(V)$        $\Delta V$        $\Delta I = f'(V_0) \cdot \Delta V$   
 $r = \frac{1}{f'(V_0)}$



$$\therefore \Delta i = f'(v) \cdot \Delta v$$

$$\frac{\Delta v}{\Delta i} = \text{resistance} = \frac{1}{f'(v)}$$

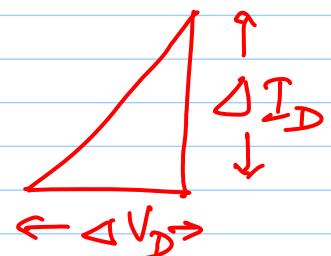
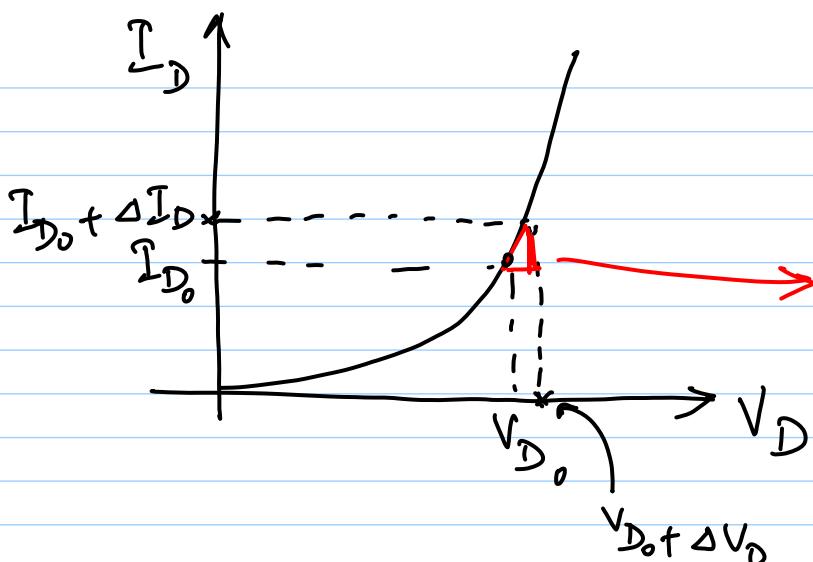
\*  $\frac{\Delta v}{\Delta i}$  depends on  $v, I$  etc.

\*  $I \Rightarrow$  Quiescent Current

$\Delta i \Rightarrow$  incremental current

$v \Rightarrow$  Quiescent Voltage

$\Delta v \Rightarrow$  incremental voltage



$$\frac{\Delta I_D}{\Delta V_D} = \frac{d I_D}{d V_D} \Big|_{V_D_0}$$

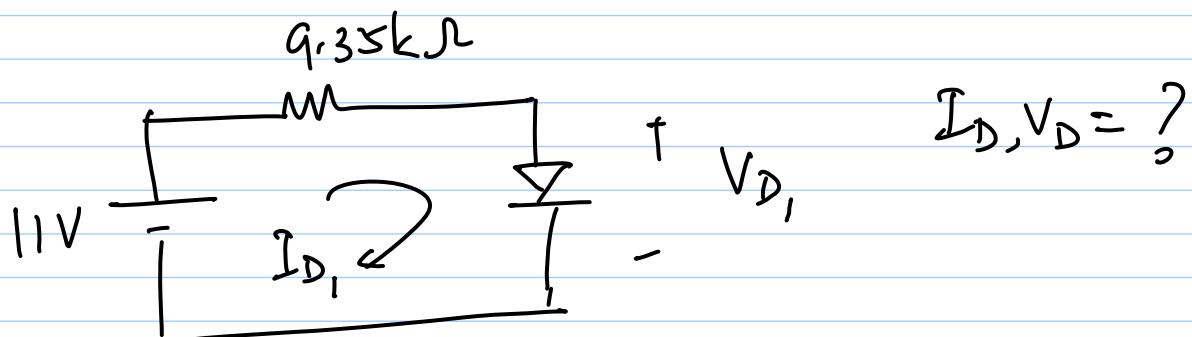
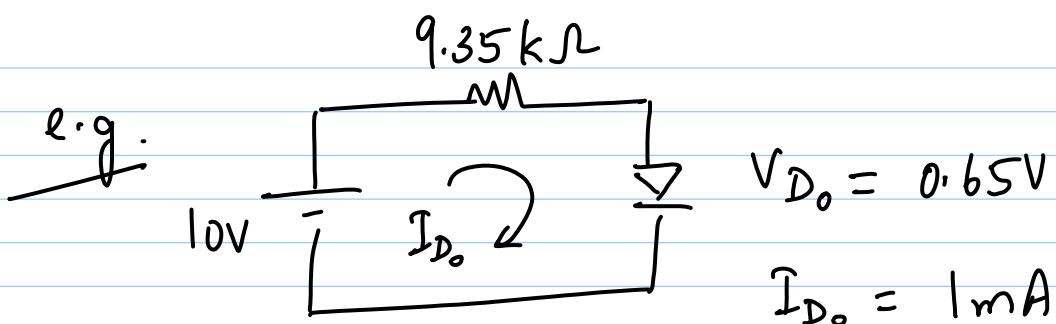
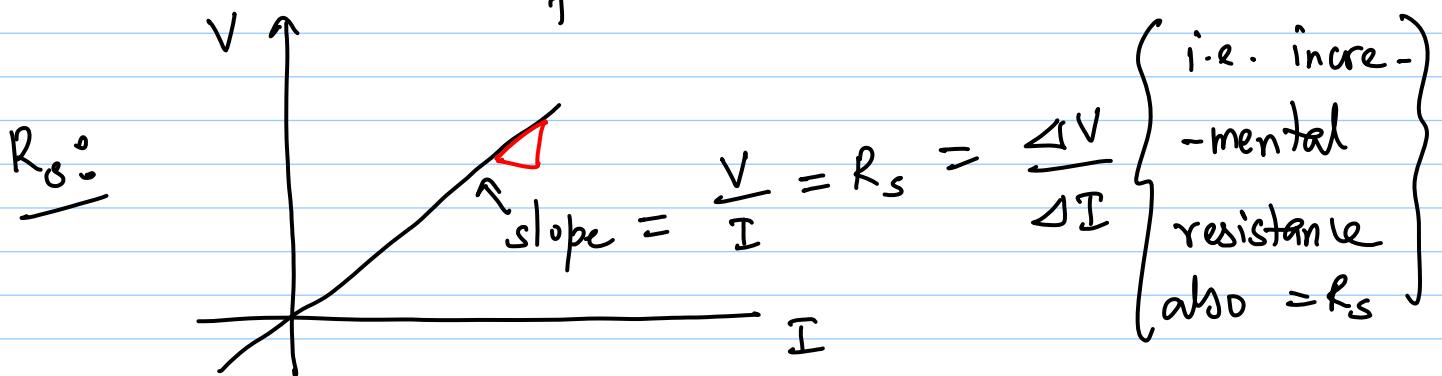
$\frac{\Delta V_D}{\Delta I_D} =$  incremental resistance  
(or dynamic)

$$\frac{\Delta I_D}{\Delta V_D} = "$$

conductance  
both depend  
on  $V_{D_0}, I_{D_0}$

$(V_{D_0}, I_{D_0})$  is called the operating point of the nonlinear device

alternatively, if you want to find incremental resistance/conductance of a NL device, you need to find the O.P. of the device



## Incremental Equivalent Ckt

$\Delta V_s = 1V$        $r_d = \frac{V_t}{I_{D_0}} = \frac{25mV}{1mA} = 25\Omega$

$$\Delta I = \frac{1}{9.35k\Omega + 25} \approx 107\mu A$$

$$I_{D_1} = 1.107 mA$$

If  $V_s = 9V$ ,  $I_{D_2} = ?$

$$\Delta V_s = -1V \Rightarrow \Delta I_D = -107\mu A$$

$$\Rightarrow I_{D_2} = 0.893 mA$$

Next : Is linear approx. valid?

$$\Delta V_D = \Delta I_D \cdot r_d = 107\mu A \times 25$$

$$\approx 2.7mV$$

$$f''(V_{D_0}) = ?$$

$$I_D = I_s \exp\left(\frac{V_D}{V_t}\right)$$

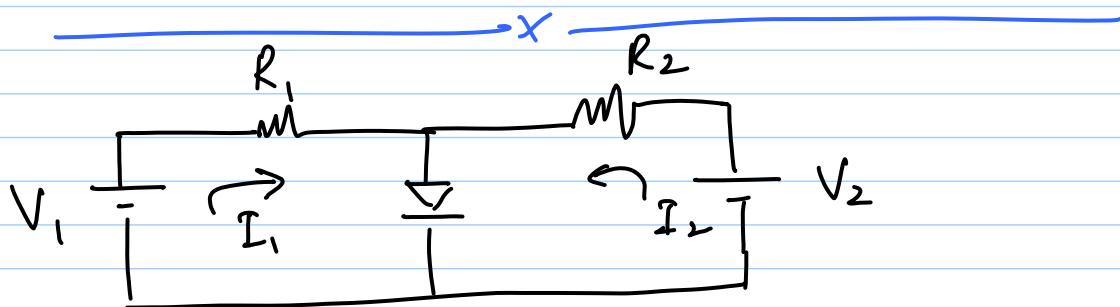
$$f''(V_{D_0}) = \frac{I_s}{V_t^2} \exp\left(\frac{V_{D_0}}{V_t}\right) \approx \frac{I_{D_0}}{V_t^2}$$

$$\text{second term} = \underbrace{\frac{f''(V_{D_0}) \cdot (\Delta V_D)^2}{2}}$$

$$= \frac{I_{D_0}}{2V_t} \cdot (\Delta V_D)^2$$

$$I_D = I_{D_0} + \frac{I_{D_0}}{V_t} \cdot (\Delta V_D) + \frac{I_{D_0}}{2V_t^2} (\Delta V_D)^2 + \dots$$

$\Rightarrow$  we need  $\Delta V_D \ll 2V_t \sim 50 \text{ mV}$  quite valid



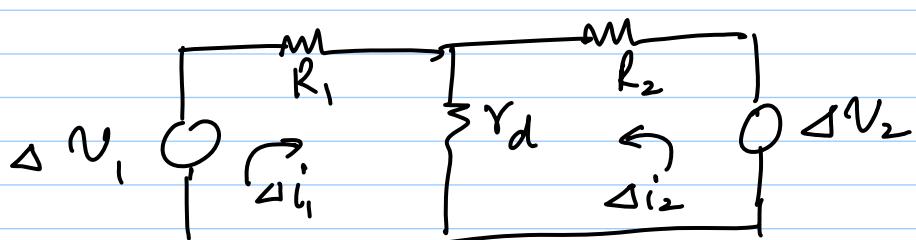
Use NL eqns to find out O.P.

e.g.  $\frac{V_1 - 0.65}{R_1} = I_1$  &  $\frac{V_2 - 0.65}{R_2} = I_2$

$$I_{D_0} = I_1 + I_2$$

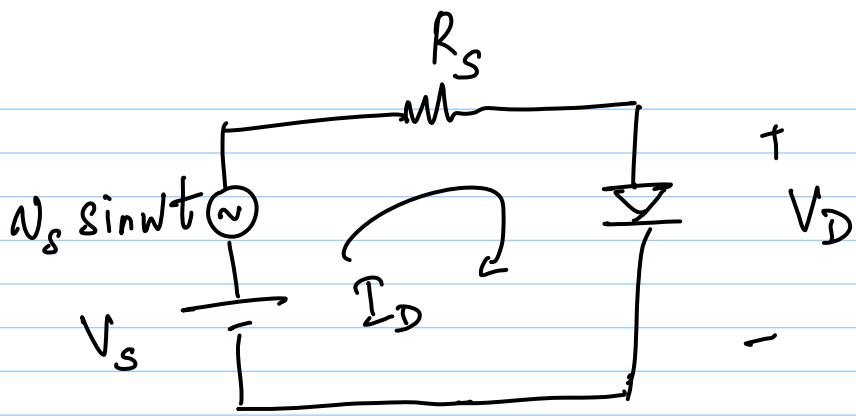
If  $V_1 \rightarrow V_1 + \Delta V_1$  &  $V_2 \rightarrow V_2 + \Delta V_2$

Incremental picture:



$$\Delta i_d = \Delta i_1 + \Delta i_2 \dots$$

$$r_d = \frac{V_t}{I_{D_0}}$$

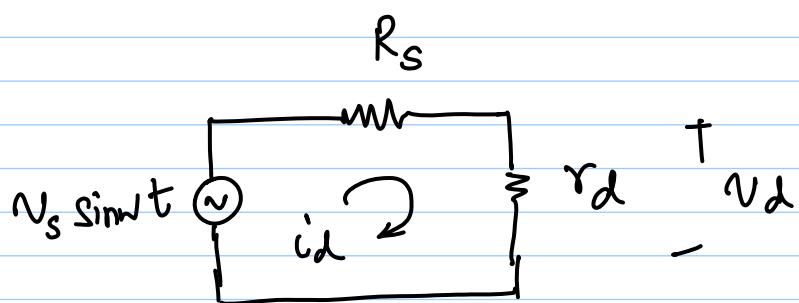


If  $V_s$  is very

small,

$$I_D = I_{D_0} + i_d$$

$$V_D = V_{D_0} + v_d$$



Incremental

(or "small-signal")

picture

$\Rightarrow$  can determine  $i_d$  &  $v_d$  (also  
sinusoids)