

# Graduate admission test for EE4 - Control stream

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Table 1: Marks

1	2	3	4	5	6	7	8	9	10
11	12	13	14	15	16	17	18	19	20

## Instructions:

1. *Time duration : 2 hours Max marks: 75*
2. *Marks for each question along with the part marking is given at the right side of each question*
3. *Read the entire question paper to choose questions that you are most familiar with*
4. *Attempt maximum number of questions*

1. Consider the following sets of linear equations: (2+2)

$$Ax_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, Ax_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, Ax_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

- (a) On what conditions on  $A$  are the solutions  $x_1$ ,  $x_2$  and  $x_3$  unique?
  - (b) Let  $X \in \mathbb{R}^{3 \times 3}$  be a matrix whose columns are  $x_1$ ,  $x_2$  and  $x_3$ . What can you say about  $X$  with respect to  $A$ ?
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2. Check if the following statements are true or false. If true give reasons/proof and if false give a counter example. (2+2)
    - (a) If  $A$  and  $B$  are invertible, then  $A + B$  is also invertible.
    - (b) Determinant of  $(AB - BA)$  is 0

3.  $A \in \mathbb{R}^{3 \times 3}$  has 3 eigenvalues 0,1,2. (1+1+2)

- (a) What is the determinant of  $A$ ?
- (b) What is the rank of  $A$ ?
- (c) What are the eigenvalues of  $(A + I)^{-1}$  and  $A^2$ ?

4. A random variable  $X$  has a probability density function  $f(x)$  as given below (3)

$$f(x) = \begin{cases} a + bx & 0 \leq x \leq 1 \\ 0 & \text{other wise} \end{cases}$$

If the mean of  $X$  is  $\frac{2}{3}$ , then find the variance of  $X$ .

5. A function  $f(x, y)$  is defined as  $f(x, y) = x + y$ . Find the maximum value of  $f(x, y)$  such that  $x^2 + y^2 = 1$ . (2)

6. A function  $f(x)$  is defined as  $f(x) = -2x^3 + 3x^2$ . Find the greatest value of  $f(x)$  for  $x \in (-\frac{1}{2}, 3)$ . (2)

7. The Newton Raphson's iterative formula to find the roots of  $f(x) = 0$  is given as  $2x_{n+1} = \frac{(x_n^2+2)}{(x_n+1)}$ . Find  $f(x)$ . (2)

8. Find the coefficient of  $(x-2)^4$  in the Taylor series expansion of  $f(x) = 3 \log x - \log x^2$  about  $x = 2$ . (2)

9. Consider the following second order systems with their specifications. For each system find the location of poles and state the nature of their step response. (overdamped, critically damped etc.) (2+2)

(a) Transfer function :  $\frac{10(s+7)}{(s+10)(s+20)}$

(b) Settling time: 7 seconds, Peak time: 2 seconds

10. Consider the circuit shown in the Figure 1. (2+2+1)

- (a) Find the transfer function of the above system.  
(b) Find a state space representation for the same.

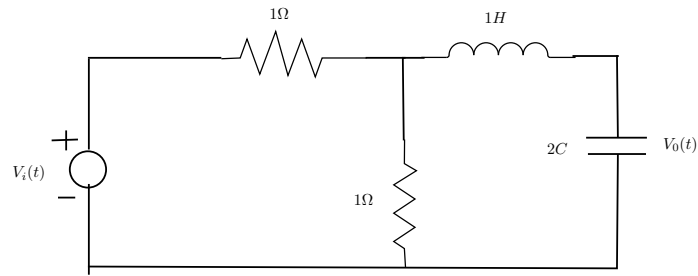


Figure 1: RLC circuit

(c) Is the state space representation unique?

11. Consider the following system:

(2+3)

$$\dot{x} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 1 & -1 \end{bmatrix} x + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} u$$

- (a) Analyze the stability of the system
- (b) Design a state feedback controller to stabilize the system

12. Linearize the following non-linear system around its equilibrium point (0,0) and analyze its stability.

(2+2)

$$\begin{aligned}\dot{x}_1 &= x_2(1 - x_1^2) \\ \dot{x}_2 &= -(x_1 + x_2)(1 - x_1^2)\end{aligned}$$

13. Check if the following (see Figure 2) can be a root locus plot. Justify.

(2+2)

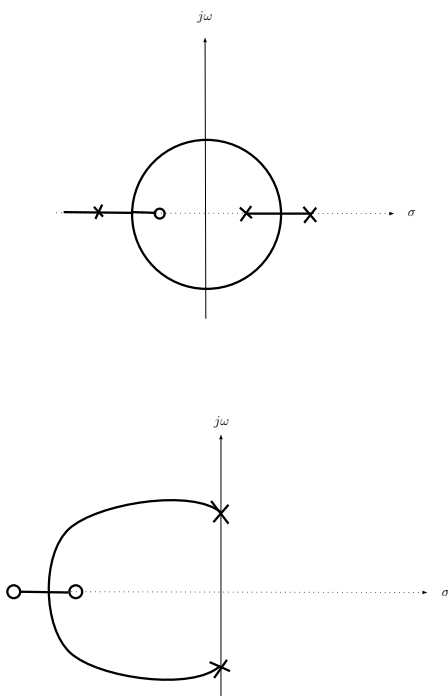


Figure 2: Root locus plot

14. Consider the following linear system in state space representation.

(1+1+1+1)

$$\begin{aligned}\dot{x} &= \begin{bmatrix} -1 & 0 \\ -1 & a \end{bmatrix} x + \begin{bmatrix} 1 \\ 2 \end{bmatrix} u \\ y &= [1 \quad 0] x\end{aligned}$$

Provide a value of  $a$  for the following cases:

- (a) system is controllable
- (b) system is not controllable
- (c) system is observable
- (d) system is not observable

15. Consider a minimum-phase (no zero in RHS plane) system whose asymptotic Bode Magnitude plot is shown in Figure 3. Determine the transfer function  $G(s)$  of the system. (4)

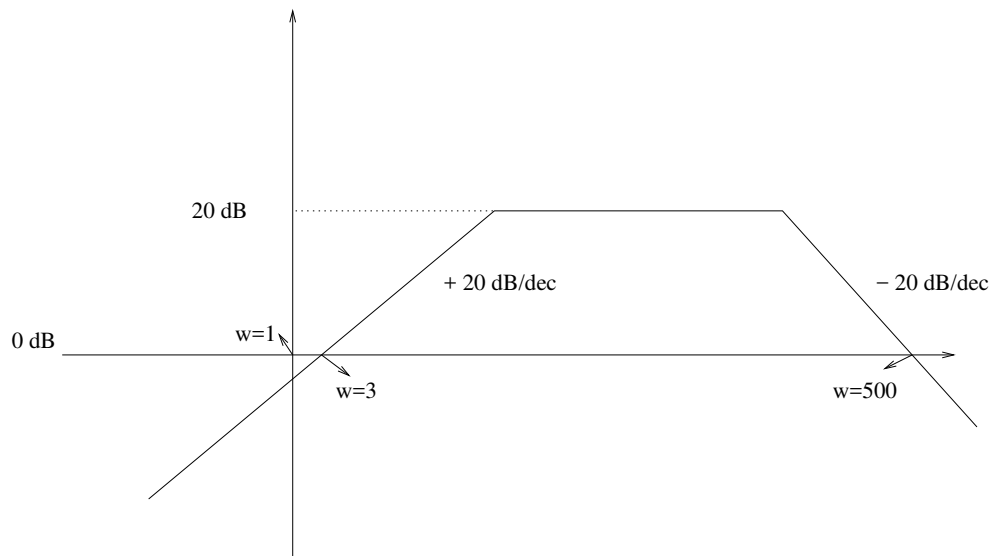


Figure 3: Bode magnitude plot

16. The signal flow graph of a system is shown below: (3+1+1)

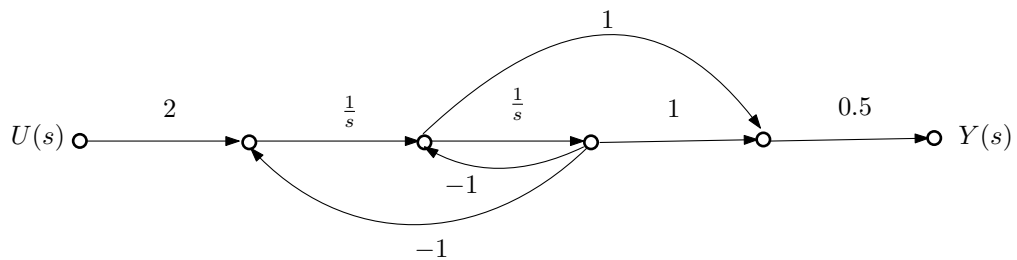


Figure 4: Signal flow graph

Provide the state variable representation of the system. Verify if the system is (a) controllable and (b) observable.

17. Solve the following differential equation:

(5)

$$\frac{d^2x}{dt^2} + 2\frac{dx}{dt} + x = 5e^{-2t} + t$$

$$x(0) = 4, \frac{dx}{dt}(0) = 1$$

18. Match the unit-step responses, plotted in Figures 5, 6, 7 and 8 with their respective transfer-functions (1+1+1+1)

$$G_1(s) = \frac{(50\pi)^2}{(s^2 + 2 \times 0.1 \times 50\pi s + (50\pi)^2)}$$

$$G_2(s) = \frac{(50\pi)^2}{(s^2 + 2 \times 0.3 \times 50\pi s + (50\pi)^2)}$$

$$G_3(s) = \frac{(50\pi)^2(s - 100)}{-100(s^2 + 100\pi s + (50\pi)^2)}$$

$$G_4(s) = \frac{2 \times (50\pi)^2}{(s + (50\pi)^2)}$$

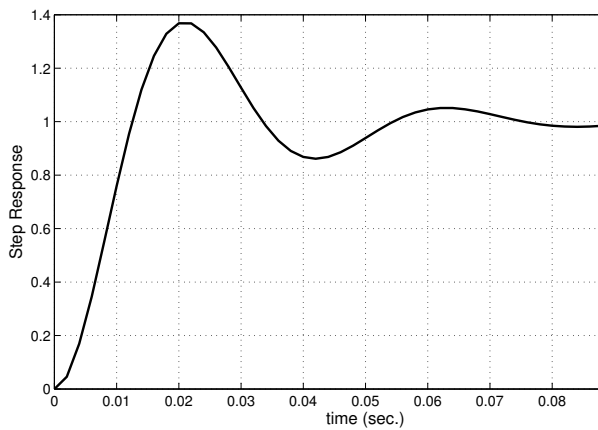


Figure 5: Unit-step response

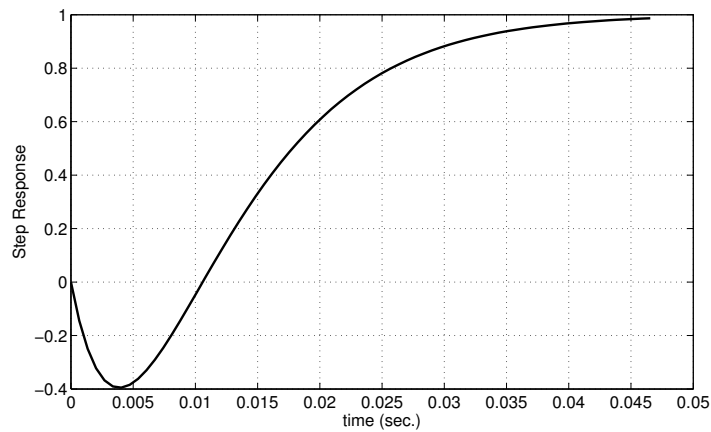


Figure 6: Unit-step response

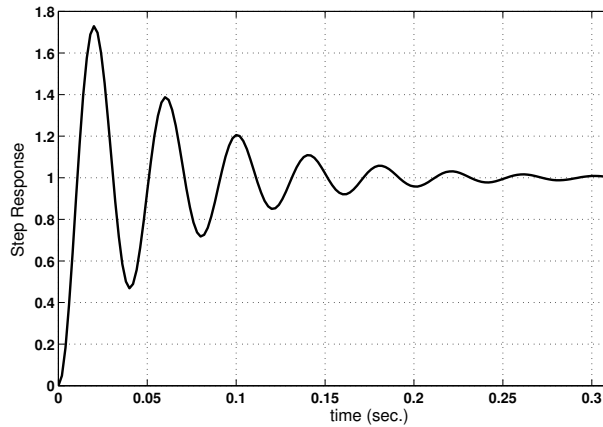


Figure 7: Unit-step response

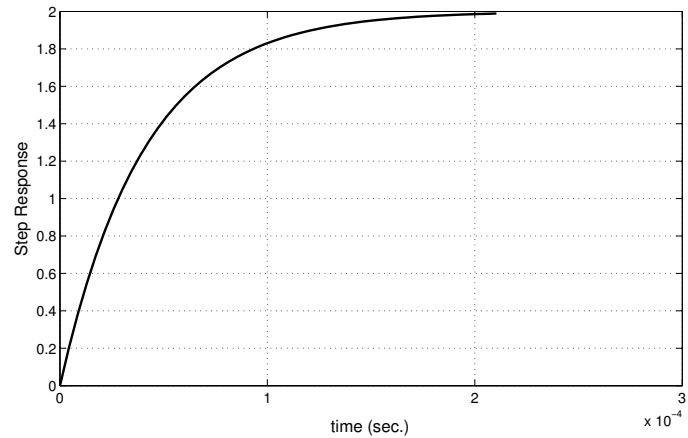


Figure 8: Unit-step response

19. Certain small scale ICs contain a single two-input gate. The ICs are manufactured in three varieties: NAND, OR and EXCLUSIVE-OR as indicated by a printed label on the IC's package. By mistake, a batch of all the three varieties is manufactured without their labels. Devise an efficient test that a technician can apply to any IC from this batch to determine which gate type it contains. (4)

20. It is proposed to determine if a point  $P$  given by  $(x,y)$  lies on a line  $L$  joining  $(x_1, y_1)$  and  $(x_2, y_2)$  by substituting the coordinates of  $P$  into the equation for  $L$ . Suppose all the coordinates are 8-bit two's complement numbers, the digital logic elements required for the task would be
- (a) 4 8-bit subtractors and 1 comparator.
  - (b) 4 8-bit subtractors, 2 8-bit multipliers, 1 16-bit subtractor and 1 comparator.
  - (c) 7 8-bit subtractors, 1 16-bit subtractor and 1 8-bit multiplier.
  - (d) None of the above.

Choose one of (a), (b), (c), (d) and establish your solution. (4)