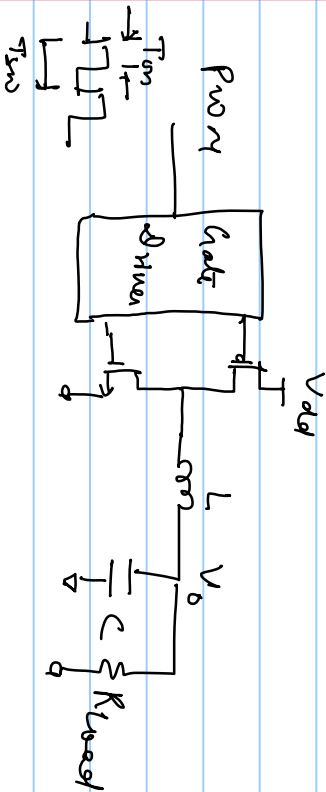


Linear Vs. Switching Regulators

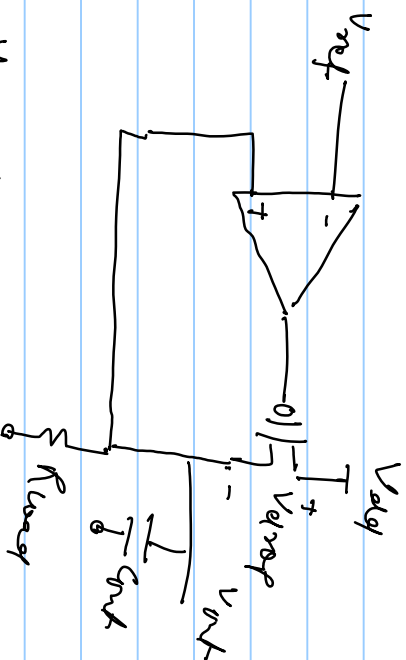
Switching Regulator



$$V_o = D \cdot V_{in}$$

$$D = \frac{T_{on}}{T_{sw}}$$

Linear Regulator



$$V_{out} = V_{in} - V_{drop}$$

Switching

Linear

① More efficient
above V_0/V_{in}

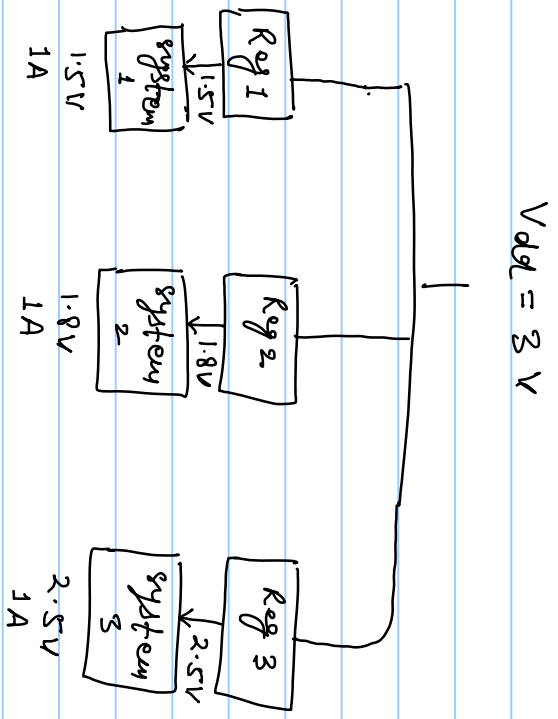
Less efficient
if $V_{in} \gg V_0$
 $V_{drop} \gg$

② Expensive due to
inductors

Cheaper

③ Switching is noisy
not preferred for
noise sensitive
applications - Analog & RF

Quiet-



Case-1 Reg 1, 2 & 3 are switching

$\eta = 90\%$

$\eta_{total} = 90\%$

Case-2 Reg 1, 2 & 3 are linear

$\eta_{total} = \frac{P_{out-total}}{P_{in}}$

$= \frac{P_{out-total}}{P_{out-total} + P_{loss}}$

$$P_{out_total} = 1.5 \text{ W} + 1.8 \text{ W} + 2.5 \text{ W} = 5.8 \text{ W}$$

$$P_{loss 1} = 1.5 \text{ W}$$

$$P_{loss 2} = 1.2 \text{ W}$$

$$P_{loss 3} = 0.5 \text{ W}$$

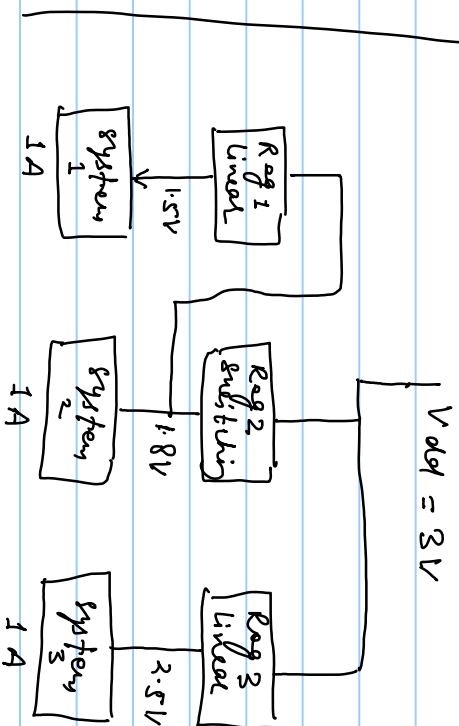
$$P_{loss} = 3.2 \text{ W}$$

$$P_{in} = P_{out_total} + P_{loss} = 9 \text{ W}$$

$$\eta_{total} = \frac{5.8}{9} = 64\%$$

Case-3

Reg 1 & Reg 3 are linear
Reg 2 is switching



$$P_{\text{loss } 1} = 0.3 \text{ W}$$

$$P_{\text{loss } 2} \approx 0.4 \text{ W}$$

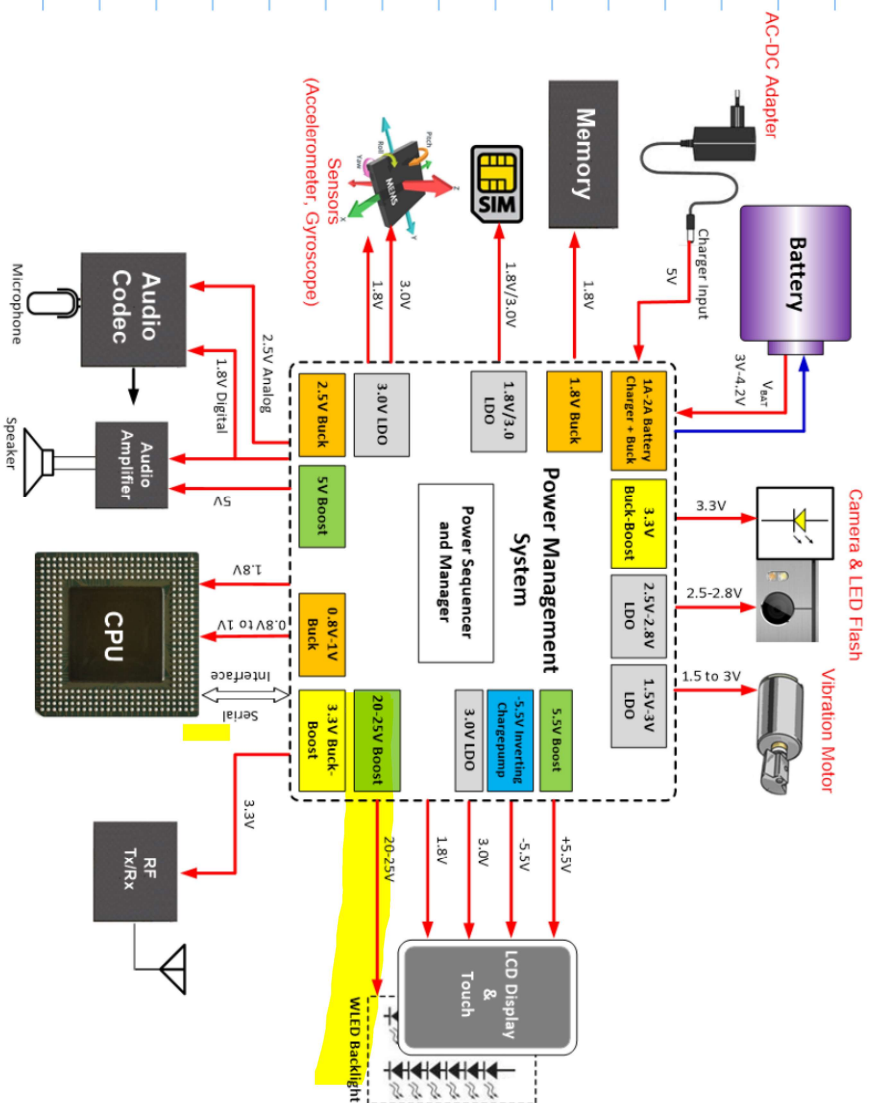
$$P_{\text{loss } 3} = 0.5 \text{ W}$$

$$P_{\text{loss}} = 1.2 \text{ W}$$

$$P_{\text{in}} = 7 \text{ W}$$

$$\eta = \frac{5.8}{7} \approx 82.8\%$$

Power Management in a Smartphone



Switching Regulator \rightarrow 4-5%

Linear Regulators \rightarrow 25-30%

Switching supplies \approx 96% of the power

Performance Parameters of a Regulator

① Efficiency = $\frac{P_{out}}{P_{in}}$

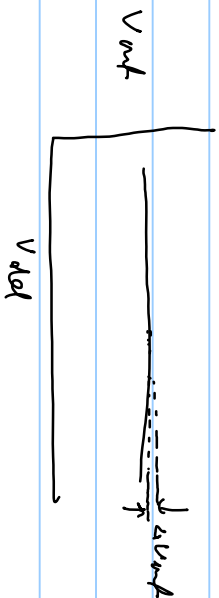
$$P_{in} = P_{out} + P_{loss}$$

$$\eta = \frac{P_{out}}{P_{out} + P_{loss}}$$

- ② Accuracy. drift in V_{out} w.r.t. varying conditions.
 \downarrow dynamic
 static accuracy is mostly caused by offset

③ Line Regulation

$$\text{Line Regulation} = \frac{\Delta V_{out}(\%) }{\Delta V_{in}(\%)}$$



4)

Load Regulation

$$= \frac{\Delta V_{out} (\text{load})}{\Delta I_{load} (\text{load})} = 0.0003$$

5)

Line Transient

Drift in V_{out} w.r.t. step change in V_{dd} .

