

Analog Systems & Lags

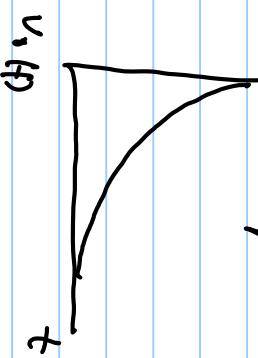
Stability

Stability of First order system.

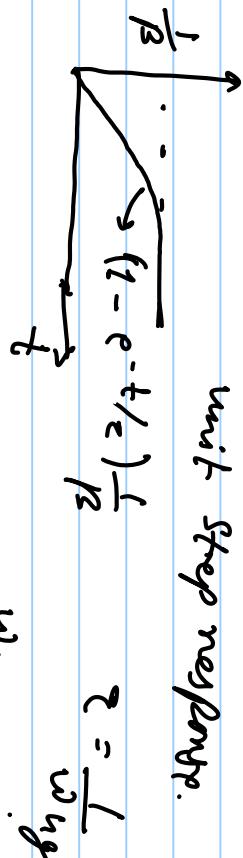
→ First order system is inherently stable for $\beta > 0$

→ min phase margin is 90°

$v_o(t)$ impulse response



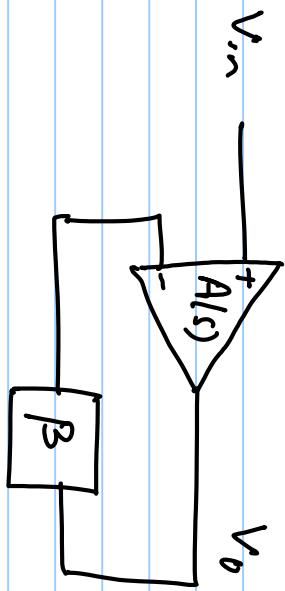
unit step response.



$$\omega_{nig} = \beta A_0 \omega_p$$

$\tau = \frac{1}{\omega_{nig}}$

Stability of a second order system



$$A(s) = \frac{A_0}{(1 + \delta/\omega_p)(1 + \delta/\omega_n)}$$

2 - stage op-amp

Need of 2 - stage op-amp

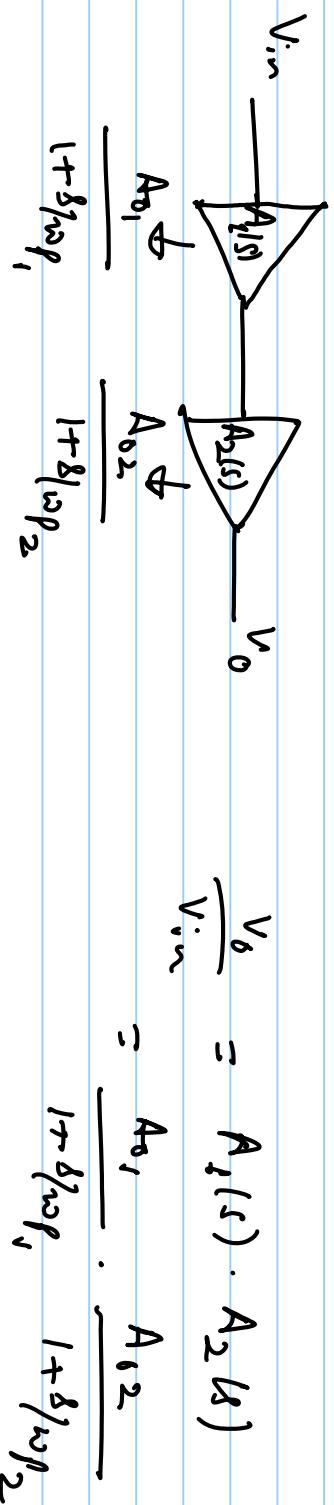
$D \downarrow R_o$
1st

$$I_{out} = g_m \cdot V_o$$

$$g_m = g_m \cdot R_o$$

→ Gain of single stage op-amp is limited by the transistor.
 → Usually this gain is limited to < 100 (40 dB).

→ In order to achieve higher gain, we need to cascade multiple single stages.

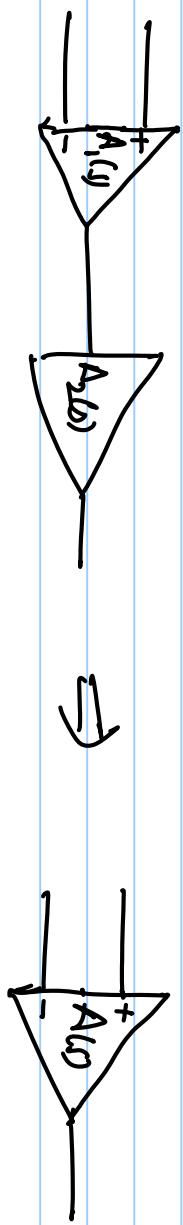


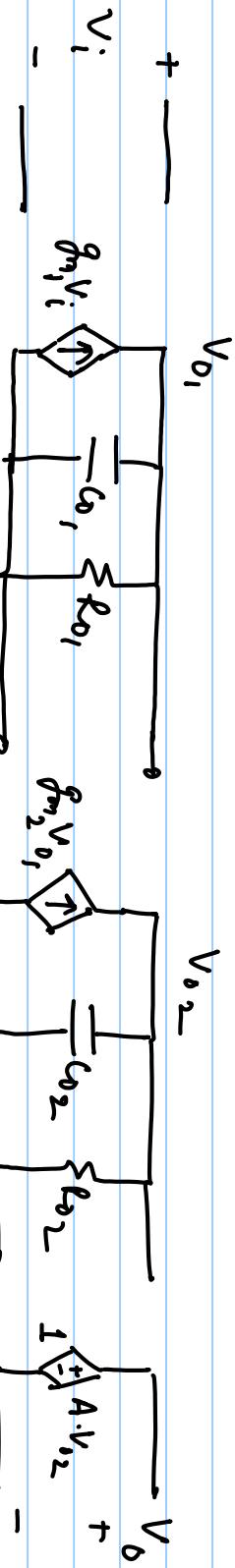
$$= \frac{A_0}{(1 + \frac{\delta}{\omega \rho_1})(1 + \frac{\delta}{\omega \rho_2})}$$

$$A_0 = A_{01} \cdot A_{02}$$

Assume $A_{01} = A_{02} \approx 100$ (nodes)

$$A_0 = 10^4 \text{ (80 deg)}$$





$$\frac{V_{o1}(s)}{V_i(s)} = \frac{g_{m1} R_o1}{1 + R_o1 C_o1 s} \quad ; \quad \frac{V_{o2}(s)}{V_i(s)} = \frac{g_{m2} R_o2}{1 + R_o2 C_o2 s}$$

$$A_o = \frac{(1 + g_{m1} R_o1)(1 + g_{m2} R_o2)}{\left(1 + \frac{R_o1 C_o1 s}{1}\right) \left(1 + \frac{R_o2 C_o2 s}{1}\right)}$$

$A_o = g_{m1} R_o1 \cdot g_{m2} R_o2$

$\omega_p_1 = \frac{1}{R_o1 C_o1}$

$\omega_p_2 = \frac{1}{R_o2 C_o2}$

Assume, $A_0 = 1000$; $f_{m_1} = 100\text{Hz/V}$, $R_{01} = 1M\Omega$, $f_{m_2} = 100\text{Hz/V}$, $R_{02} = 10k\Omega$

$$f_{m_1} R_{01} = 100 \cdot 10^6 \rightarrow A_0 = 1000$$

$$c_{01} = 10PF \quad \& \quad c_{02} = 10PF$$

$$\omega_{p1} = \frac{1}{R_{01} c_{01}} = \frac{1}{10^6 \times 10^{-11}} = 10^5 \text{ rad/sec}$$

$$\omega_{p2} = \frac{1}{R_{02} c_{02}} = \frac{1}{10^5 \times 10^{-11}} = 10^6 \text{ rad/sec}$$

$|A(s)|$

60dB

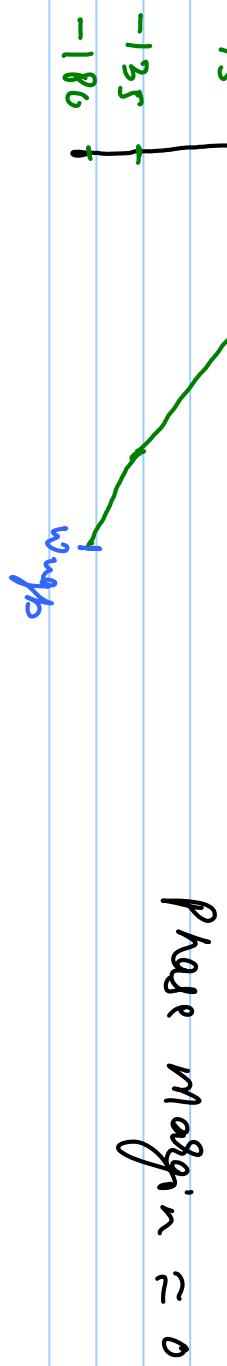
30dB

0dB

$\text{Arg}(s)$ (deg)

ω

$$\omega_{mp} = 10^7 \text{ rad/sec}$$



Phase margin ≈ 0

Total phase shift due to poles = -180°

-180° comes from -ve feedback

so if -ve of. amp is connected in -ve feedback then

Total loop phase shift = $-360^\circ \Rightarrow$ +ve feedback \rightarrow instability.