

Computational Electromagnetics : Summary of Integral Equation Methods

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Topics in this module

- ① Surface v/s Volume Integral Approach
- ② Finding the Radar Cross-Section (RCS)
- ③ Computational Considerations

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Quick aside: Surface Integral Equations and PECs


How do we deal with scatters that are made of perfect electric conductors?

Recall boundary conditions for PEC

$\hookrightarrow E_z = 0 = \phi$

$\text{TM}_{\text{pol}}: \left. \begin{array}{l} \phi \rightarrow E_z \\ \nabla \phi \cdot \hat{n} \rightarrow H_{\text{tan}} \end{array} \right\}$

If we have a PMC $\rightarrow H_{\text{tan}} = 0, E_z \neq 0$.



A diagram shows a scatterer with two regions, V_1 and V_2 , separated by a boundary. The boundary is divided into N_{seg} segments. A red circle highlights a segment on the boundary.

The original system of equations:

$$\left\{ \begin{array}{l} \oint [g_1(r, r') \nabla \phi(r) \cdot \hat{n} - \phi(r) \nabla g_1(r, r') \cdot \hat{n}] dl = \phi_i(r'), \quad r' \in V_2 \\ \oint [g_2(r, r') \nabla \phi(r) \cdot \hat{n} - \phi(r) \nabla g_2(r, r') \cdot \hat{n}] dl = 0, \quad r' \in V_1 \end{array} \right\} 2N \times 2N$$

$\rightarrow \left\{ \begin{array}{l} \oint (g_1(r, r') \nabla \phi \cdot \hat{n}) dl = \phi_i(r') \\ \oint g_2(r, r') \nabla \phi(r) \cdot \hat{n} dl = 0 \end{array} \right\} N \times N \text{ system.}$

Surface v/s Volume Integral Equations

Surface approach:

For each region:

$$\left. \begin{aligned} \nabla^2 \phi_n + k_n^2 \phi &= Q_n \\ \nabla^2 g_n + k_n^2 g_n &= -\delta(r, r') \end{aligned} \right\}$$

Each eqn solved separately for each region.

variables: $\bar{E}_{tan}, \bar{H}_{tan}$ on S.

Huygen's principle.

$k_1, k_2 \rightarrow$ constants

Homogeneous



Volume approach:

$$\begin{cases} \nabla^2 \phi + k_n^2 \phi = Q_n \\ \nabla^2 \phi_i + k_0^2 \phi = Q_n \end{cases}$$

with & without object.

Eqn in terms of $(\phi - \phi_i)$

$$\rightarrow \nabla^2 (\phi - \phi_i) + \underline{k_0^2} (\phi - \phi_i) = \dots$$

$$\rightarrow \nabla^2 g + \underline{k_0^2} g = -\delta$$

$$\boxed{k_n^2 = k_0^2 \epsilon_r(r)} \cdot \text{Heterogeneous.}$$

Surface v/s Volume Integral Equations

Surface approach: *(Huygen's)*

$$\phi(r') = \phi_i(r') + \left[\oint_S [\phi(r) \nabla g_1(r, r') - g_1(r, r') \nabla \phi(r)] \cdot \hat{n} dl \right]$$

surface equivalence.



Volume approach:

$$\phi(r') = \phi_i(r') + k_0^2 \int_{V_2} g_1(r, r') [\epsilon_r(r) - 1] \phi(r) dr$$

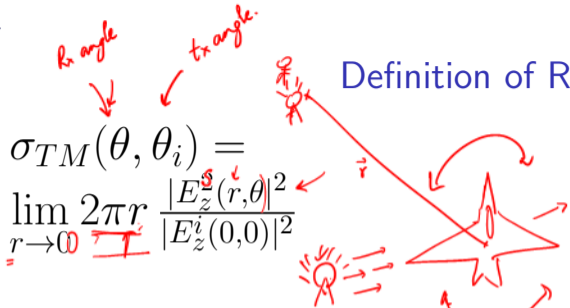
Volume equivalence principle.

Surf faster volume.

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Definition of Radar Cross-Section (RCS): σ



$$\sigma_{TM}(\theta, \theta_i) = \lim_{r \rightarrow \infty} \frac{2\pi r^2 |E_z^s(r, \theta)|^2}{|E_z^i(0, 0)|^2}$$

$$\sigma_{TM}(\theta, \phi, \theta_i, \phi_i) = \lim_{r \rightarrow \infty} \frac{4\pi r^2 |E_z^s(r, \theta, \phi)|^2}{|E_z^i(0, 0, 0)|^2}$$

far field.

Mono-static and Bi-static

Tx and Rx are different.

Tx and Rx same pos.



$$\sigma = \lim_{r \rightarrow \infty} \frac{2\pi |r'| |E_z^s(r', \theta)|^2}{|E_z^i(0, \theta)|^2}$$

$e^{j\omega t}$

$r \rightarrow \infty$

Approximations in the RCS

An integral involving Green's function: $\phi(r') = \phi_i(r') + k_0^2 \int_{V_2} g_1(r, r') \chi(r) \phi(r) dr$

Volume

In 2D: $g(r, r') = \frac{-j}{4} H_0^{(2)}(k|r - r'|)$

In 3D: $g(r, r') = \frac{1}{4\pi|r - r'|} \exp(-jk|r - r'|)$

for $x \gg 1$, $H_0^{(2)}(k\rho) \approx \sqrt{\frac{2j}{\pi k\rho}} \exp(-jk\rho)$

For amp $\rho \approx R$

For phase $\rho \approx R \left[1 - \frac{(xx' + yy')}{R^2} \right]$

$|r - r'| = \sqrt{(x - x')^2 + (y - y')^2} = \sqrt{x'^2 + y'^2 - 2xx' - 2yy' + x^2 + y^2}$



$$= R \sqrt{1 - \frac{2xx' - 2yy'}{R^2} + \frac{x^2 + y^2}{R^2}}$$

small

$$\approx R \left[1 - \frac{(2xx' + 2yy')}{R^2} \right]^{1/2}$$

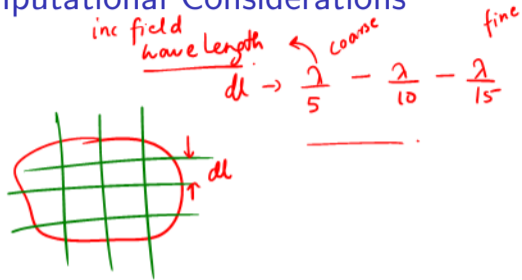
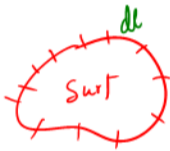
Note: RCS independent of r

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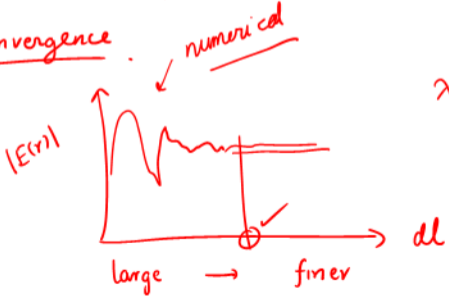
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Computational Considerations

- How fine do you discretize?



Numerical Convergence



$\lambda = \frac{\lambda_0}{n}$, refractive index of obj

Topics that were covered in this module

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Reference: Ch 1 of Peterson's book on CEM

