

# Computational Electromagnetics : Introduction to Green's functions

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## Topics in this module

- ① Motivations for Green's functions
- ② A one-dimensional example
- ③ Some general properties of Green's functions
- ④ A two-dimensional example
- ⑤ A three-dimensional example

# Table of Contents

- 1 Motivations for Green's functions
- 2 A one-dimensional example
- 3 Some general properties of Green's functions
- 4 A two-dimensional example
- 5 A three-dimensional example

## Green's function: the motivation

Electrical Engineers are familiar with the concept of a impulse response of a system:

$$x(t) \rightarrow \boxed{\overset{\text{LTI}}{h(t)}} \rightarrow y(t)$$

Domain:  $\leftarrow$  time

$$y(t) = h(t) * x(t) \quad \longleftrightarrow$$

freq  $\rightsquigarrow$

$$Y(\omega) = H(\omega) X(\omega)$$

Fourier transform defn:

$$X(\omega) = \int_{-\infty}^{\infty} x(t) \exp(j\omega t) dt$$

$$\text{eg } X(\omega) = 1, \quad \underline{Y(\omega) = H(\omega)}$$

$\updownarrow$   
 $x(t) ? \quad \delta(t)$

How do we calculate  $h(t)$ ?

1) Calc  $\left( \frac{Y(\omega)}{X(\omega)} \right) \leftarrow$

2) IFT  $H(\omega) \rightarrow h(t)$

## Green's function: the motivation

Make the idea of impulse response more general  $\rightarrow$  also called Green's function

Now  $\mathbb{L}$  is an operator:  $\mathbb{L} \phi(r) = f(r)$  — (1)  $\mathbb{L}$  acts on unprimed only. Compare (3) & (1)

$\rightarrow \nabla^2, \nabla^2 + k^2$   $\left( \frac{\partial}{\partial z} \right)$   $\left( \frac{\partial}{\partial r} \right)$

$\phi(r)$  — unknown

$\mathbb{L}^{-1} f(r)$

Define impulse response as:

Given  $g$ , what is  $\phi$ ?

$$f(r) \times (2)$$

How to solve:

Integrate  
over a region incl  $r=r'$   
over primed coordinates

$$f(r) \mathbb{L} g(r, r') = f(r') \delta(r, r')$$

$$\Rightarrow \mathbb{L} f(r') g(r, r') = f(r) \delta(r, r')$$

$$\mathbb{L} \int f(r') g(r, r') dr' = f(r) \text{ — (3)}$$

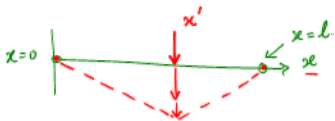
(this is the equivalent of convolution)

$$\mathbb{L} g(r, r') = \delta(r, r') \text{ — (2)} \Rightarrow \phi(r) = \int f(r') g(r, r') dr'$$

# Table of Contents

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## 1-D example: string tied at both ends



Differential equation is  $\frac{d^2 u(x)}{dx^2} = F(x)$

$u(x)$ : String displacement at  $x$ .

$F(x)$ : Applied force.  $L \equiv \frac{d^2}{dx^2}$

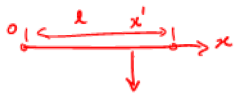
Boundary conditions are: At both ends  $u(0) = 0$   
 $u(l) = 0$

$\phi \equiv u$   
 $f \equiv F$

Green's function defn:

$$\boxed{\begin{aligned} \frac{d^2 G(x, x')}{dx^2} &= \delta(x, x') \\ \bar{d}x^2 &= \delta(x - x') \end{aligned}}$$

s.t.  $G(x=0, x') = G(0, x') = 0$   
 $G(x=l, x') = G(l, x') = 0$   
 $x \neq x'$



## 1-D example: solving with boundary conditions

Let's solve when  $x \neq x' \Rightarrow \frac{d^2 g(x, x')}{dx^2} = 0 \Rightarrow \underline{Ax + B = G(x, x')}$

Consider two cases:

- 1)  $x < x'$   
 $G'' = 0$   
 2)  $x > x'$

$$G(x, x') = \begin{cases} A_1 x + B_1 & \text{--- (1)} \\ A_2 x + B_2 & \text{--- (2)} \end{cases}$$

How many variables?

4

3 conds so far.

$$A_2 x + B_2 = A_2 (x - l)$$

Apply boundary condns

$$\underline{x=0} \rightarrow A_1 \cdot 0 + B_1 = 0 \Rightarrow \underline{B_1 = 0} \quad \text{--- (a)}$$

$$\underline{x=l} \rightarrow A_2 l + B_2 = 0 \Rightarrow \underline{B_2 = -A_2 l} \quad \text{--- (b)}$$

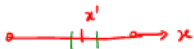
String continuity

$$x = x' \Rightarrow A_1 x' = A_2 (x' - l)$$

↓  
case 1

$$\Rightarrow \underline{A_2 = \frac{A_1 x'}{x' - l}} \quad \text{--- (c)}$$





## 1-D example: final solution

We have 4 variables, and 3 relations. Final trick?

$$G'' = \delta(x-x') \leftarrow$$

Is  $G'$  continuous?

Integrate.  $\int_{x'-\epsilon}^{x'+\epsilon} G''(x, x') dx = \int_{x'-\epsilon}^{x'+\epsilon} \delta(x-x') dx \leftarrow$

Final solution is:

$$u(x) = \int_0^l G(x, x') F(x') dx'$$

$$G'(x, x') \Big|_{x'-\epsilon}^{x'+\epsilon} = 1 = A_2 - A_1 \quad - (d)$$

$$A_1 = \frac{x'-l}{l}, \quad A_2 = \frac{x'}{l}$$

$$G' = \begin{cases} A_1 & x < x' \\ A_2 & x > x' \end{cases}$$

Wrapping it all up:

$$G(x, x') =$$

$$\begin{cases} \left(\frac{x'-l}{l}\right)x, & x < x' \\ \left(\frac{x-l}{l}\right)x', & x > x' \end{cases}$$



## 1-D example: alternate representation

We derived a closed form solution, but alternatives possible

$G(x, x')$  has finite energy  $\implies$  square integrable

Write as:  $G(x, x') = \sum_{n=1}^{\infty} a_n(x') \sin\left(\frac{n\pi x}{l}\right)$   $\sum_{n=1}^{\infty} -\frac{n^2 \pi^2}{l^2} a_n(x') \sin\left(\frac{n\pi x}{l}\right) = \delta(x, x')$

Substitute into eqn:  $G''(x, x') = \delta(x, x')$

How to get  $a_n$ ? Orthogonality?  $\int_0^l \sin\left(\frac{m\pi x}{l}\right) \sin\left(\frac{n\pi x}{l}\right) dx = \begin{cases} l/2, & m=n \\ 0, & m \neq n \end{cases}$

$$-\frac{m^2 \pi^2}{l^2} a_m(x') \cdot \frac{l}{2} = \sin\left(\frac{m\pi x'}{l}\right)$$



Finally we get  $G(x, x') = -\frac{2l}{\pi^2} \sum_{n=1}^{\infty} \frac{1}{n^2} \sin\left(\frac{n\pi x'}{l}\right) \sin\left(\frac{n\pi x}{l}\right)$

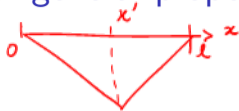
Series

# Table of Contents

- ① Motivations for Green's functions
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## Green's functions: general properties

Keep as template:  $G(x, x') = \left\{ \begin{array}{ll} \frac{(x'-l)}{l} x & x < x' \\ \frac{(x-l)}{l} x' & x > x' \end{array} \right\}$



Following properties are true of Green's functions in general:

- 1) Homogeneous diffn eqn  $\rightarrow$  Satisfies it. ✓
- 2) Symmetric w.r.t.  $x, x'$  ✓
- 3) Satisfies homogeneous boundary cond. ✓
- 4) It is continuous at  $x = x'$
- 5)  $G'$  has a discontinuity at  $x = x'$ .

# Table of Contents

- ① Motivations for Green's functions
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## 2-D example: the wave equation

Already seen this wave equation:

$$\nabla^2 \phi(r) + k^2 \phi(r) = f(r) \quad (1)$$

$$\left[ \phi(r) = \int_{V'} f(r') G(r, r') dr' \right]$$

To solve, start with  $r' = 0$  and consider  $r > 0$ .

w.l.o.g

we have angular symmetry.

$\Rightarrow$  No  $\theta$  dep<sub>n</sub>.

$$\rightarrow \frac{\partial^2}{\partial r^2} G(r) + \frac{1}{r} \frac{\partial}{\partial r} G(r) + k^2 G(r) = 0$$

implicit  $\rightarrow G(r, 0)$ .

And the corresponding Green's fn defn:

$$\nabla^2 G(r, r') + k^2 G(r, r') = -\delta(r, r') \quad (2)$$

$\int_V f(r')$

Intg

$$\nabla^2 \int_V f(r') G(r, r') + k^2 \int_V f(r') G(r, r') = - \int_V f(r') \delta(r, r')$$

In <sup>2D</sup> polar coordinates:  $\nabla^2 =$

$$\frac{1}{r} \frac{\partial}{\partial r} + \frac{\partial^2}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2}$$



Mult by  $r^2$

## 2-D example: polar coordinates soln <sup>Const.</sup> <sup>(2)</sup>

Our eqn:  $r^2 \frac{d^2 G(r)}{dr^2} + r \frac{dG(r)}{dr} + k^2 r^2 G(r) = 0$

Bessel's eqn:  $x^2 \frac{d^2 y}{dx^2} + x \frac{dy}{dx} + (x^2 - \alpha^2) y = 0$

$\alpha = 0, kr = x$

$\frac{d\psi}{dr} = \frac{d\psi}{dx} \frac{dx}{dr} = k \frac{d\psi}{dx}$

$\frac{x^2}{k^2} k^2 \frac{d^2 G(\frac{x}{k})}{dx^2} + \frac{x}{k} \cdot k \cdot \frac{dG(\frac{x}{k})}{dx} + x^2 G(\frac{x}{k}) = 0$

$x^2 \frac{d^2 G(\frac{x}{k})}{dx^2} + x \frac{dG(\frac{x}{k})}{dx} + x^2 G(\frac{x}{k}) = 0$

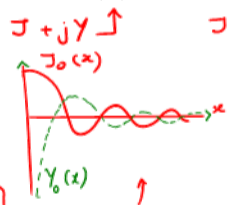
General soln:

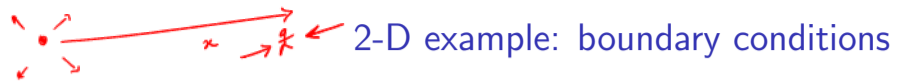
$G(\frac{x}{k}) = a H_0^{(1)}(x) + b H_0^{(2)}(x)$   
 $G(r) = a H_0^{(1)}(kr) + b H_0^{(2)}(kr)$   
 $J_0, Y_0$

First kind  $J_\alpha(x)$  Second kind  $Y_\alpha(x)$

Hankel fn  $\rightarrow$

Also:  $H_\alpha^{(1)}(x)$   $H_\alpha^{(2)}(x)$   
 $J + jY$   $J - jY$





2-D example: boundary conditions

Which form of the solution to take, and why? What have we not considered so far?

$G(r) = aH_0^{(1)}(kr) + bH_0^{(2)}(kr)$  ← *general.* But at large r?

$H_0^{(1)}(x) \approx \sqrt{\frac{2}{\pi x}} \exp(j(x - \frac{\pi}{4})) e^{j\omega t}$   
 ↓ *incoming*  $j(x + \omega t)$

$H_0^{(2)}(x) \approx \sqrt{\frac{2}{\pi x}} \exp(-j(x - \frac{\pi}{4})) e^{j\omega t}$   
 ✓ *outgoing*  $-j(x - \omega t)$

*The observer only sees outgoing wave*

$\Rightarrow a = 0$

Finally,  $G(r) = b H_0^{(2)}(kr)$




## 2-D example: evaluating constants

How do we evaluate  $b$ ?

Recall:  $\iint_{S_\epsilon} \nabla^2 G(r) + k^2 G(r) ds = \iint_{S_\epsilon} -\delta(r) ds$   $\lim_{\epsilon \rightarrow 0} \frac{\dots}{\epsilon \ll 1}$

(a)      (b)      (c)



Term (a):  $\iint_S \nabla^2 G(r) ds = 2\pi \int_0^\epsilon \nabla^2 G(r) r dr d\theta$

$H_0^{(2)}(x) \rightarrow J_0(x) \approx 1, x \ll 1$   
 $Y_0(x) \approx \frac{2}{\pi} \ln x, x \ll 1$

$\nabla G = \frac{\partial G}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial G}{\partial \theta} \hat{\theta}$

$\nabla^2 G = \nabla \cdot \nabla G$

$\iint \nabla \cdot \nabla G ds = \oint \nabla G \cdot \hat{n} dl = \oint \left( \frac{\partial G}{\partial r} \right) dl$

$= \oint \frac{2}{2r} \left[ 1 - j \frac{2}{\pi} \ln kr \right] b dl = \oint \frac{-2jk \times 1}{\pi} \frac{dl}{kr} = \frac{-2jk \times 1 \times 2\pi r}{\pi} \Big|_{r=\epsilon} b$

Term (b):

$k^2 \iint G(r) r dr d\theta = 2\pi k^2 \int_0^\epsilon G(r) r dr = 2\pi k^2 \int_0^\epsilon r \left( 1 - j \frac{2}{\pi} \ln kr \right) b dr = -4jb \leftarrow (a)$

$= 2\pi k^2 b \left[ \int_0^\epsilon r dr - j \frac{2}{\pi} \int_0^\epsilon r \ln kr dr \right]$

$\int_0^\epsilon r dr = \frac{r^2}{2} \Big|_0^\epsilon = \frac{\epsilon^2}{2}$

$\int_0^\epsilon r \ln kr dr = \ln kr \cdot \frac{r^2}{2} \Big|_0^\epsilon - \int_0^\epsilon \frac{1}{r} \cdot \frac{r^2}{2} dr$

$\lim_{r \rightarrow 0} \frac{\ln kr}{1/r^2} = \frac{1/r}{-2/r^3} = -\frac{r^2}{2}$

$\lim_{\epsilon \rightarrow 0} \frac{\epsilon^2}{2} = 0$

$\lim_{r \rightarrow 0} \frac{r^2 \ln kr}{1/r^2} = \frac{r^2 \ln kr}{1/r^2} = \frac{r^4 \ln kr}{1} = -\frac{r^2}{2}$

$r=0 \rightarrow 0$   
 $\epsilon \rightarrow -\frac{\epsilon^2}{2}$

term (b) = 0

## 2-D example: evaluating constants

How do we evaluate  $b$ ?

Recall:  $\int_{S_\epsilon} [\nabla^2 G(r) + k^2 G(r)] dS = \int_{S_\epsilon} -\delta(r) dS$

Term (c):  $= -1$

$$-4jb + 0 = -1$$

$$b = \frac{1}{4j} = -\frac{j}{4}$$

$$G(r) = -\frac{j}{4} H_0^{(2)}(kr)$$

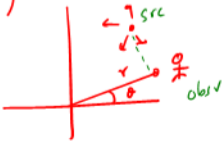
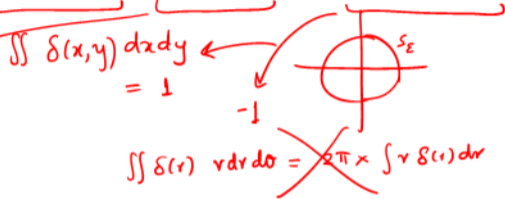
$$G(\vec{r}) = \frac{j}{4} H_0^{(2)}(k|\vec{r}|)$$

Putting it all together:

$$G(r) =$$

Finally,  $G(r, r') =$

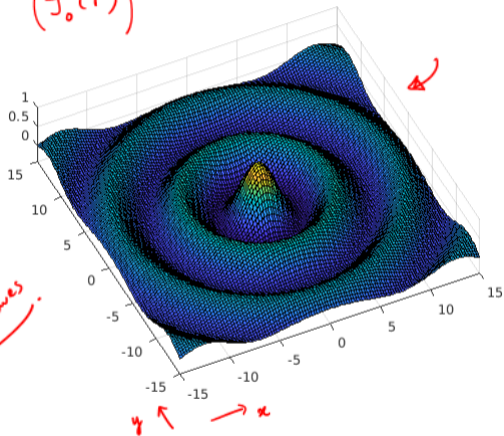
$$\frac{-j}{4} H_0^{(2)}(k|\vec{r} - \vec{r}'|)$$



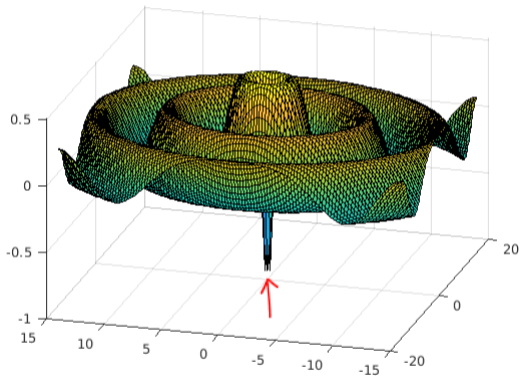
$$e^{j(kx - \omega t)}$$

## 2-D example: visualizing the wave

$$(J_0(\bar{r}))$$



$$Y_0(\bar{r})$$



```
[X,Y] = meshgrid(-15:0.25:15,-15:0.25:15);
R = sqrt(X.^2+Y.^2); BJ = besselj(0,R);
surf(X,Y,BJ)
```

# Table of Contents

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### 3-D example: the wave equation

Same (wave) equation:  $\nabla^2 G(r) + k^2 G(r) = -\delta(r)$       Set  $r' = 0$

In spherical polar coordinates,  $r$ -depn terms are:  $\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial}{\partial r} \right)$

Simplifying for  $r > 0$ :  $\nabla^2 G + k^2 G = 0$

$e^{j\omega t}$

$\Rightarrow a = 0 \rightarrow G(r) = \frac{b e^{-jkr}}{r}$

Solving:

Boundary conditions?

$$\frac{1}{r^2} \frac{d}{dr} \left( r^2 \frac{dG}{dr} \right) + k^2 G = 0$$

$$\frac{1}{r} \frac{d}{dr} \left( r^2 \frac{dG}{dr} \right) + k^2 r G = 0 = \frac{2 dG}{dr} + r \frac{d^2 G}{dr^2} + k^2 r G = 0$$

Final form:

$$\frac{d^2}{dr^2} (rG) + k^2 r G = 0$$

$$r G(r) = a e^{jkr} + b e^{-jkr}$$

$$\hookrightarrow G(r) = a \frac{e^{jkr}}{r} + b \frac{e^{-jkr}}{r} \quad \left. \vphantom{G(r)} \right\} \text{spherical plane waves.}$$

$$G = b \frac{e^{-jkr}}{r}$$

### 3-D example: evaluating the constant

Integrate both sides:  $\int_V (\nabla^2 G(r) + k^2 G(r)) dv = \int_V -\delta(r) dv = -1$



First term:

$$\begin{aligned} \nabla^2 G &= \nabla \cdot \nabla G \\ \int_V \nabla \cdot \nabla G dv &= \oint_V \nabla G \cdot \hat{n} ds \\ \nabla G &= \frac{\partial G}{\partial r} \hat{r} \end{aligned}$$

$$= b \oint \left[ \frac{-jk e^{-jkr}}{r} - \frac{e^{-jkr}}{r^2} \right] r^2 \sin\theta d\theta d\phi = -1$$

$$= -4\pi b \left[ jk \frac{e^{-jkr}}{r} + \frac{e^{-jkr}}{r^2} \right]_{r=\epsilon}$$

$$= -4\pi b \quad \epsilon \rightarrow 0$$

Second term:

$$\int_0^\epsilon k^2 b \frac{e^{-jkr}}{r} r^2 4\pi dv = 4\pi k^2 b \int_0^\epsilon r e^{-jkr} dr$$

as  $\epsilon \rightarrow 0 = 0$

$$-4\pi b = -1, \quad b = \frac{1}{4\pi}$$

Final expression:

$$G(r) = \frac{1}{4\pi r} e^{-jkr}$$

$$G(\bar{r}, \bar{r}') = \frac{1}{4\pi} \frac{e^{-jk|\bar{r}-\bar{r}'|}}{|\bar{r}-\bar{r}'|} \quad \left. \vphantom{G(\bar{r}, \bar{r}')} \right\} 3D$$

$R = |\bar{r} - \bar{r}'|$

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Reference: Ch 14 of Advanced Engineering Electromagnetics, Balanis