

EE5120 Linear Algebra: Tutorial 3, July-Dec 2017-18

1. Let \mathcal{S}_1 and \mathcal{S}_2 be two subsets of a vector space V such that $\mathcal{S}_1 \subset \mathcal{S}_2$. Say True/False for each of the following. If True, prove it. If False, justify it.
- (a) If \mathcal{S}_1 is linearly independent, then \mathcal{S}_2 is so.
 - (b) If \mathcal{S}_1 is linearly dependent, then \mathcal{S}_2 is so.
 - (c) If \mathcal{S}_2 is linearly independent, then \mathcal{S}_1 is so.
 - (d) If \mathcal{S}_2 is linearly dependent, then \mathcal{S}_1 is so.

Solution:

- (a) False. Need not be the case always. If \mathcal{S}_2 contains a linear combination of elements of \mathcal{S}_1 , then it will not be linearly independent. For example, let $\mathcal{S}_1 = \{1\}$ and $\mathcal{S}_2 = \{1, 2\}$ both subsets of \mathcal{R} . Here \mathcal{S}_1 is linearly independent, while \mathcal{S}_2 is not.
- (b) True. Since \mathcal{S}_1 is linearly dependent we have finite vectors x_1, x_2, \dots, x_n in \mathcal{S}_1 and so in \mathcal{S}_2 such that $a_1x_1 + a_2x_2 + \dots + a_nx_n = 0$ is a nontrivial representation. But this nontrivial representation is also a nontrivial representation of \mathcal{S}_2 . Therefore \mathcal{S}_2 is also linearly dependent.
- (c) True. Proof by contradiction: Assume \mathcal{S}_1 is linearly dependent. Then we can find a non-trivial representation for \mathcal{S}_1 , which will also be a non-trivial representation for \mathcal{S}_2 and contradicts the fact that \mathcal{S}_2 is linearly independent.
- (d) False. Need not be the case always. Refer example for (a)

2. Let P_2 be the set of all second degree polynomials. Clearly, it is a vector space. Which of the following sets are the bases for P_2 ? Justify your answer.
- (a) $\{-1 - x + 2x^2, 2 + x - 2x^2, 1 - 2x + 4x^2\}$.
 - (b) $\{1 + 2x + x^2, 3 + x^2, x + x^2\}$.
 - (c) $\{1 - 2x - 2x^2, -2 + 3x - x^2, 1 - x + 6x^2\}$.
 - (d) $\{-1 + 2x + 4x^2, 3 - 4x - 10x^2, -2 - 5x - 6x^2\}$.
 - (e) $\{1 + 2x - x^2, 4 - 2x + x^2, -1 + 18x - 9x^2\}$.

Solution:

Each of the given sets has three polynomials. Since dimension of P_2 is 3, it is sufficient to test linear independency for the sets to be a basis for P_2 (Note that dimension of a vector space is the total number of basis vectors present in a basis set of that vector space). Test procedure is as follows: Let the polynomials in each set be $\{p_1(x), p_2(x), p_3(x)\}$. Solve $ap_1(x) + bp_2(x) + cp_3(x) = 0$ for constants a, b and c . If these constants are all zero, then the set is linearly independent. Else, it is not. According to this, we obtain that the sets in (b), (c) and (d) are the bases for P_2 .

3. Consider a vector $\mathbf{x} = (x_1, x_2, x_3, x_4)$ in \mathbb{R}^4 . It has 24 rearrangements like (x_2, x_1, x_3, x_4) , (x_4, x_3, x_1, x_2) , and so on. Those 24 vectors, including \mathbf{x} itself, span a subspace S . Find specific vectors \mathbf{x} so that the dimension of S is: (a) 0, (b) 1, (c) 3, (d) 4.

Solution:

- (a) A subspace of dimension 0 in \mathbb{R}^4 is the origin. So the vector that spans it is $(0,0,0,0)$.
- (b) A subspace of dimension 1 implies it has only one vector in its basis. This is possible only if the vector does not change on rearrangement. One such vector is $(1,1,1,1)$.
- (c) Consider a non-zero vector (x_1, x_2, x_3, x_4) such that $x_1 + x_2 + x_3 + x_4 = 0$, i.e., its dot product with $(1,1,1,1)$ is 0. This vector along with its permutations will span a 3-dimensional subspace that is perpendicular to the line through $(1,1,1,1)$ and origin.
- (d) Take the standard basis for \mathbb{R}^4 , i.e., $(1,0,0,0)$ and its permutations since any vector space is a subspace of itself.

4. Find the basis for the following subspaces of \mathbb{R}^5

- (a) $W_1 = \{(a_1, a_2, a_3, a_4, a_5) \in \mathbb{R}^5 : a_1 - a_3 - a_4 = 0\}$
 (b) $W_2 = \{(a_1, a_2, a_3, a_4, a_5) \in \mathbb{R}^5 : a_2 = a_3 = a_4, a_1 + a_5 = 0\}$

Solution:

- (a) $\{(0,1,0,0,0), (1,0,1,0,0), (1,0,0,1,0), (0,0,0,0,1)\}$
 (b) $\{(0,1,1,1,0), (-1,0,0,0,1)\}$

5. Do the polynomials $x^3 - 2x^2 + 1$, $4x^2 - x + 3$, $3x - 2$ generate $P_3(\mathbb{R})$? where $P_3(\mathbb{R})$ is the set of all polynomials having degree ≤ 3

Solution: None of the linear combinations of the given the polynomials produce $x \in P_3(\mathbb{R}) \therefore$ they can't generate $P_3(\mathbb{R})$

6. Prove that any rank 1 matrix has the form $\mathbf{A} = \mathbf{uv}^T = \text{column times row}$.

Solution: In rank 1 matrix, every row is a multiple of the first row, so the row space is one-dimensional. In fact, we can write as the whole matrix as *the product of a column vector and a row vector*.

Example:
$$\begin{bmatrix} 2 & 1 & 1 \\ 4 & 2 & 2 \\ 8 & 4 & 4 \\ -2 & -1 & -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 4 \\ -1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 1 \end{bmatrix}$$

7. Let V be a finite dimensional vector space and let S be a spanning subset of V . Prove that there exists a subset of S that is the basis for V .

Solution:

Here, we also provide a procedure to construct the basis \mathcal{B} from S . The procedure is as follows:

- (a) Let $\mathcal{B} = \emptyset$ initially.
- (b) If an element $\mathbf{u} \in S$ is s.t $\{\mathbf{u}\} \cup \mathcal{B}$ is linearly independent, then add \mathbf{u} into \mathcal{B} .
- (c) Repeat (b) till linear independence of \mathcal{B} fails.

Hence, by construction \mathcal{B} is a linearly independent subset of S . Now it suffices to show that \mathcal{B} spans V , i.e., $\text{span}(\mathcal{B}) = V$. It is given that $\text{span}(S) = V$.

Let $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ and $\mathcal{B} = \{\mathbf{v}_1, \dots, \mathbf{v}_m\}$ ($m \leq n$). This implies $\mathbf{v}_j = \sum_{i=1}^m a_i^{(j)} \mathbf{v}_i, \forall j = m+1, \dots, n$ and for some constants $a_1^{(j)}, \dots, a_m^{(j)}$. By construction of \mathcal{B} , $\text{span}(\mathcal{B}) \subset \text{span}(S)$. Now let $\mathbf{w} \in \text{span}(S) \Rightarrow \mathbf{w} = \sum_{k=1}^n b_k \mathbf{v}_k = \sum_{k=1}^m b_k \mathbf{v}_k + \sum_{k=m+1}^n b_k \left(\sum_{i=1}^m a_i^{(k)} \mathbf{v}_i \right) \Rightarrow \mathbf{w} \in \text{span}(\mathcal{B})$. Thus, $\text{span}(\mathcal{B}) = \text{span}(S) = V$. Hence, proved.

8. Prove that number of basis vectors of a vector space is unique.

Solution: Let $\mathbf{v}_1, \dots, \mathbf{v}_m$ and $\mathbf{w}_1, \dots, \mathbf{w}_n$ are both bases for the same vector space.

Suppose there are more \mathbf{w}_j 's than \mathbf{v}_i 's ($n > m$). Since \mathbf{v}_i 's form a basis, they must span the space. Every \mathbf{w}_j can be written as a combination of the \mathbf{v}_i 's: If $\mathbf{w}_j = a_{1j}\mathbf{v}_1 + \dots + a_{mj}\mathbf{v}_m$.

$$\mathbf{W} = [\mathbf{w}_1 \quad \mathbf{w}_2 \quad \dots \quad \mathbf{w}_n] = [\mathbf{v}_1 \quad \dots \quad \mathbf{v}_m] \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} = \mathbf{V}\mathbf{A}.$$

We know the shape of \mathbf{A} is m by n . since $n > m$, There is a nonzero solution to $\mathbf{A}\mathbf{x} = \mathbf{0}$. Then $\mathbf{V}\mathbf{A}\mathbf{x} = \mathbf{0} \Rightarrow \mathbf{W}\mathbf{x} = \mathbf{0}$. A combination of the \mathbf{w}_j 's gives zero! The \mathbf{w}_j 's could not be a basis, which is a contradiction. Similarly, ($m > n$) also will fail. Hence, number of basis vectors of a vector space is unique ($m = n$).

9. Let \mathbf{A} be an $m \times n$ matrix. Prove that the sum of dimensions of the column space and null space of \mathbf{A} equals n .

Solution:

Note that \mathbf{A} transforms vectors from \mathbb{R}^n to vectors in \mathbb{R}^m . Null space of $\mathbf{A} = \{\mathbf{x} \in \mathbb{R}^n | \mathbf{A}\mathbf{x} = \mathbf{0}_m\}$ ($\mathbf{0}_m$ is an $m \times 1$ all zero vector). Clearly, null space of $\mathbf{A} \subset \mathbb{R}^n$. Also, it is also a subspace of \mathbb{R}^n . Let $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ ($k \leq n$) be the basis for null space of \mathbf{A} . Then, it can be extended to the basis of \mathbb{R}^n as $\{\mathbf{v}_1, \dots, \mathbf{v}_k, \mathbf{v}_{k+1}, \dots, \mathbf{v}_n\}$. If we prove that

$\{\mathbf{A}\mathbf{v}_{k+1}, \dots, \mathbf{A}\mathbf{v}_n\}$, which are all $m \times 1$ vectors, is the basis for column space of \mathbf{A} , then the final result follows as,

$$\dim(\text{column space of } \mathbf{A}) + \dim(\text{null space of } \mathbf{A}) = n - k + k = n.$$

To prove: $\mathcal{S} = \{\mathbf{A}\mathbf{v}_{k+1}, \dots, \mathbf{A}\mathbf{v}_n\}$ is the basis of the column space of \mathbf{A} .

(i) **Linear Independence:**

Let \mathcal{S} be linearly dependent. Then, there exists constants a_1, \dots, a_{n-k} such that $\sum_{i=1}^{n-k} a_i \mathbf{A}\mathbf{v}_{k+i} = \mathbf{0}_m$ with not all a_i 's equal to zero. Now, $\mathbf{A} \left(\sum_{i=1}^{n-k} a_i \mathbf{v}_{k+i} \right) = \mathbf{0}_m \Rightarrow \sum_{i=1}^{n-k} a_i \mathbf{v}_{k+i} \in \text{null space of } \mathbf{A}$. Then, $\exists b_1, \dots, b_k$ s.t., $\sum_{i=1}^{n-k} a_i \mathbf{v}_{k+i} = \sum_{j=1}^k b_j \mathbf{v}_j$. This contradicts the fact that $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ are linearly independent. Thus, the assumption that \mathcal{S} is linearly dependent is incorrect $\Rightarrow \mathcal{S}$ is linearly independent.

(b) **\mathcal{S} spans column space of "A":**

Let $\mathbf{x} \in \text{column space of } \mathbf{A}$. Then, $\exists \mathbf{y} \in \mathbb{R}^n$ s.t. $\mathbf{A}\mathbf{y} = \mathbf{x}$. But $\mathbf{y} = \sum_{i=1}^n c_i \mathbf{v}_i$, for some constants c_i 's (basis expansion in \mathbb{R}^n). So, $\mathbf{x} = \mathbf{A}\mathbf{y} = \mathbf{A} \left(\sum_{i=1}^n c_i \mathbf{v}_i \right) = \mathbf{A} \left(\sum_{i=1}^k c_i \mathbf{v}_i \right) + \mathbf{A} \left(\sum_{i=k+1}^n c_i \mathbf{v}_i \right) = \mathbf{0}_m + \mathbf{A} \left(\sum_{i=k+1}^n c_i \mathbf{v}_i \right) = \mathbf{A} \left(\sum_{i=k+1}^n c_i \mathbf{v}_i \right) \Rightarrow \mathbf{x} \in \text{span}(\mathcal{S}) \Rightarrow \text{column space of } \mathbf{A} \subset \text{span}(\mathcal{S})$. But $\text{span}(\mathcal{S}) \subset \text{column space of } \mathbf{A}$. So \mathcal{S} spans the column space of \mathbf{A} .

From above discussions, we proved the desired result.

10. Let \mathbf{A} be an $n \times n$ invertible conjugate symmetric matrix, i.e., $\mathbf{A}^H = (\mathbf{A}^*)^T = \mathbf{A}$ (* - denotes conjugation) and \mathbf{x} be an $n \times 1$ vector. The following procedure guides you to find the inverse of $\mathbf{A} + \mathbf{x}\mathbf{x}^H$.

(a) For an arbitrary \mathbf{y} , consider the equation,

$$(\mathbf{A} + \mathbf{x}\mathbf{x}^H)\mathbf{z} = \mathbf{y}. \quad (1)$$

Now finding inverse of $\mathbf{A} + \mathbf{x}\mathbf{x}^H$ is equivalent to finding a \mathbf{B} such that $\mathbf{z} = \mathbf{B}\mathbf{y}$. Pre-multiply both sides of equation (1) by \mathbf{A}^{-1} and obtain

$$\mathbf{z} = \mathbf{A}^{-1}\mathbf{y} - \mathbf{A}^{-1}\mathbf{x}\mathbf{x}^H\mathbf{z}. \quad (2)$$

(b) Pre-multiply both sides of equation (2) by \mathbf{x}^H and then solve for $\mathbf{x}^H\mathbf{z}$ in terms of $\mathbf{x}, \mathbf{A}, \mathbf{y}$.

(c) Substitute into equation (1) and manipulate to bring into the desired form $\mathbf{z} = \mathbf{B}\mathbf{y}$. Observe what \mathbf{B} is.

Solution: Consider equation (2). Now, on pre-multiply both sides of this equation by \mathbf{x}^H , we get, $\mathbf{x}^H \mathbf{z} = \mathbf{x}^H \mathbf{A}^{-1} \mathbf{y} - \mathbf{x}^H \mathbf{A}^{-1} \mathbf{x} \mathbf{x}^H \mathbf{z} \Rightarrow \mathbf{x}^H \mathbf{z} = \mathbf{x}^H \mathbf{A}^{-1} \mathbf{y} / (1 + \mathbf{x}^H \mathbf{A}^{-1} \mathbf{x})$. Let $\tilde{\mathbf{x}} = \mathbf{A}^{-1} \mathbf{x}$. Substitute this in equation (1). We get,

$$\begin{aligned} \mathbf{A} \mathbf{z} + \mathbf{x} \mathbf{x}^H \mathbf{z} &= \mathbf{y} \\ \Rightarrow \mathbf{A} \mathbf{z} + \mathbf{x} \tilde{\mathbf{x}}^H \mathbf{y} / (1 + \mathbf{x}^H \tilde{\mathbf{x}}) &= \mathbf{y} \\ \Rightarrow \mathbf{A} \mathbf{z} &= \left(\mathbf{I} - \frac{\mathbf{x} \tilde{\mathbf{x}}^H}{1 + \mathbf{x}^H \tilde{\mathbf{x}}} \right) \mathbf{y} \\ \Rightarrow \mathbf{z} &= \left(\mathbf{A}^{-1} - \frac{\tilde{\mathbf{x}} \tilde{\mathbf{x}}^H}{1 + \mathbf{x}^H \tilde{\mathbf{x}}} \right) \mathbf{y}. \end{aligned}$$

Thus, inverse of $\mathbf{A} + \mathbf{x} \mathbf{x}^H$ is $\mathbf{A}^{-1} - \frac{\tilde{\mathbf{x}} \tilde{\mathbf{x}}^H}{1 + \mathbf{x}^H \tilde{\mathbf{x}}}$, with $\tilde{\mathbf{x}} = \mathbf{A}^{-1} \mathbf{x}$.